Estimation Lasso et interactions poissoniennes sur le cercle

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Motivation

• Estimation in Hawkes model (Reynaud-Bouret and Schbath 2010, Hansen *et al.* 2012, ...) and for Poissonian interactions (Sansonnet 2014) needs the knowledge of an a priori bound on the support of interaction fonctions.

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- Aim: Overcome knowledge of this bound in a high-dimensional discrete setting.
 - A discrete version of the Poissonian interactions model that is in the heart of my PhD thesis.
 - A circular model: to avoid boundary effects and also to reflect a certain biological reality.

Poissonian discrete model

• <u>Parents</u>: *n* i.i.d. uniform random variables U_1, \ldots, U_n on the set $\{0, \ldots, p-1\} \rightarrow \text{points on a circle (we work modulus$ *p* $)}$.

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- Children:
 - Each U_i gives birth independently to some Poisson variables.
 - If $x^* = (x_0^*, \dots, x_{p-1}^*)^H \in \mathbb{R}^p_+$, then $N_{U_i+j}^i \sim \mathcal{P}(x_j^*)$ independent of anything else.
 - The variable $N_{U_i+j}^i$ represents the number of children that a certain individual U_i has at distance *j*.
 - We set $Y_k = \sum_{i=1}^n N_k^i$ the total number of children at position k whose distribution conditioned on the U_i 's is given by

$$Y_k \sim \mathcal{P}\left(\sum_{i=1}^n x_{k-U_i}^*\right).$$

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Aim: Estimate x^* with the observation of the U_i 's and the Y_k 's.

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$$A = \begin{pmatrix} \mathbb{N}(0) & \mathbb{N}(p-1) & \cdots & \mathbb{N}(1) \\ \mathbb{N}(1) & \mathbb{N}(0) & \ddots & \vdots \\ \vdots & \ddots & \ddots & \mathbb{N}(p-1) \\ \mathbb{N}(p-1) & \cdots & \mathbb{N}(1) & \mathbb{N}(0) \end{pmatrix}$$

is a $p \times p$ circulant matrix, with

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Aim: Recover $x^* \Leftrightarrow$ solve an inverse problem (potentially ill-posed) where the operator A is random and depends on the U_i 's.

RIP property I

• The eigenvalues of A are given by $\sigma_k = \sum_{i=1}^n e^{-2\pi i k U_i/p}$, for k in $\{0, ..., p-1\}$. In particular,

$$\mathbb{E}(\sigma_k) = \begin{cases} n & \text{if } k = 0[p] \\ 0 & \text{if } k \neq 0[p] \end{cases}$$

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- We first focus on proving a Restricted Isometry Property (Candès and Tao, 2005): there exist positive constants *r* and *R* such that with high probability, for any *K*-sparse vector *x* (i.e. with at the most *K* non-zero coordinates)

$$r\|x\|^2 \leqslant \|Ax\|^2 \leqslant R\|x\|^2,$$

with R as close to r as possible.

RIP property II

• Under conditions, a RIP is satisfied by $\widetilde{A} = A - \frac{n - \sqrt{n}}{p} \mathbb{1}\mathbb{1}^{H}$:

$$\frac{n}{2}\|x\|_2^2 \leqslant \|\widetilde{A}x\|_2^2 \leqslant \frac{3n}{2}\|x\|_2^2.$$

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 We obtain also a classical Restricted Eigenvalue (RE) type condition (see Bickel 2009) on an event of probability larger than 1 - 5.54 pe^{-θ} s.t. for all d ∈ {0,..., p - 1},

$$|\mathbb{U}(d)| \leqslant \kappa \left(rac{n}{\sqrt{p}} heta + heta^2
ight) =: n\xi(heta),$$

with
$$\mathbb{U}(d) = \sum_{u=0}^{p-1} \sum_{i=1}^{n} \sum_{j \neq i, j=1}^{n} \left(\mathbf{1}_{U_i=u} - \frac{1}{p} \right) \left(\mathbf{1}_{U_j=u+d[p]} - \frac{1}{p} \right)$$
 and for

p and *n* be fixed integers larger than 1 and for all $\theta > 1$.

Lasso estimator by using a weighted penalty I

•
$$\widetilde{A} = A - \frac{n - \sqrt{n}}{p} \mathbb{1}\mathbb{1}^{\mathsf{H}}$$
 and $\widetilde{Y}_k = Y_k - \frac{n - \sqrt{n}}{p}\overline{Y}$, with $\overline{Y} = \frac{1}{n} \sum_{k=0}^{p-1} Y_k$.

 $\mathbb{E}(\widetilde{Y}|U_1,\ldots,U_n)=\widetilde{A}x^*.$

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 E(Y) = ||x*||₁ and conditionally on the U_i's, Ỹ is an unbiased estimate of Ãx*:

$$\mathbb{E}(\widetilde{Y}|U_1,\ldots,U_n)=\widetilde{A}x^*.$$

We first introduce the following Lasso estimate for some $\gamma > 0$:

$$\widehat{x} := \operatorname*{argmin}_{x \in \mathbb{R}^{p}} \left\{ \|\widetilde{Y} - \widetilde{A}x\|_{2}^{2} + \gamma \sum_{k=0}^{p-1} d_{k}|x_{k}| \right\},\$$

which is based on random and data-dependent weights d_k .

Lasso estimator by using a weighted penalty II

The Lasso estimate satisfies

$$\begin{cases} (\widetilde{A}^{\mathsf{H}}(\widetilde{Y} - \widetilde{A}\widehat{x}))_{k} = \frac{\gamma d_{k}}{2} \operatorname{sign}(\widehat{x}_{k}) & \text{for } k \text{ s.t. } \widehat{x}_{k} \neq 0\\ |\widetilde{A}^{\mathsf{H}}(\widetilde{Y} - \widetilde{A}\widehat{x})|_{k} \leq \frac{\gamma d_{k}}{2} & \text{for } k \text{ s.t. } \widehat{x}_{k} = 0 \end{cases},$$

and in particular, for any k,

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• Our approach where weights are random is similar to Zou 2006, Bertin *et al.* 2011, Hansen *et al.* 2012, ...: in some sense, the weights play the same role as the thresholds in the estimation procedure proposed in Donoho and Johnstone 1994, Reynaud-Bouret and Rivoirard 2010, Sansonnet 2014, ...

Lasso estimator by using a weighted penalty III

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Remark: If $\gamma \ge 2$, x^* will also satisfy $|\widetilde{A}^{\mathsf{H}}(\widetilde{Y} - \widetilde{A}\widehat{x}^*)|_k \le \frac{\gamma d_k}{2}$. This is a key technical point to prove optimality of our approach.

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• They need to be high enough, so that they work even if A is not invertible enough.

How to choose the d_k 's?

Proposition 1

For any $\theta > 0$, there exists an event $\Omega_{\nu}(\theta)$ of probability larger than $1 - 2pe^{-\theta}$ on which, for all k in $\{0, \dots, p-1\}$,

$$|\widetilde{A}^{\mathsf{H}}(\widetilde{Y}-\widetilde{A}x^*)|_k \leqslant \sqrt{2\nu_k\theta}+\frac{B\theta}{3},$$

where

$$B = \max_{u \in \{0,\dots,p-1\}} \left| \mathbb{N}(u) - \frac{n-1}{p} \right|$$

and

$$w_k = \sum_{u=0}^{p-1} w(k-u) x_u^*,$$

with
$$w(d) = \sum_{u=0}^{p-1} \left(\mathbb{N}(u) - \frac{n-1}{p} \right)^2 \mathbb{N}(u+d)$$
 for all d in $\{0, \ldots, p-1\}$.

Derivation of constant weights

 $v_k \leqslant W \|x^*\|_1,$

where

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$$W := \max_{d} w(d) = \max_{u \in \{0,\dots,p-1\}} \sum_{\ell=0}^{p-1} \left(\mathbb{N}(\ell+u) - \frac{n-1}{p} \right)^2 \mathbb{N}(\ell)$$
 is observable, and

• $||x^*||_1$ is unbiasedly estimated by \overline{Y} .

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• $||x^*||_1$ is unbiasedly estimated by \overline{Y} .

Constant weights

$$d := \sqrt{2W\theta} \left[\sqrt{\bar{Y} + \frac{5\theta}{6n}} + \sqrt{\frac{\theta}{2n}} \right] + \frac{B\theta}{3}$$

satisfies $|\widetilde{A}^{\mathsf{H}}(\widetilde{Y} - \widetilde{A}x^*)|_k \leq d_k = d$ on an event of probability larger than $1 - (2p + 1)e^{-\theta}$.

Derivation of non constant weights

We reestimate the v_k 's:

$$\hat{v}_k = \sum_{\ell=0}^{p-1} \left(\mathbb{N}(\ell-k) - \frac{n-1}{p} \right)^2 Y_{\ell}.$$

Derivation of non constant weights

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Non constant weights

$$\tilde{d}_k = \sqrt{2\theta} \left[\sqrt{\hat{v}_k + \frac{5\theta B^2}{6}} + \sqrt{\frac{\theta B^2}{2}} \right] + \frac{B\theta}{3}$$

satisfies $|\widetilde{A}^{\mathsf{H}}(\widetilde{Y} - \widetilde{A}x^*)|_k \leqslant d_k = \widetilde{d}_k$ on an event of probability larger than $1 - 3pe^{-\theta}$.

Control of the weights I

We consider the following special relationships between *n*, *p* and θ . For any integers *n*, *p* and for any $\theta > 1$,

 $\kappa'\sqrt{p}\theta \leqslant n \leqslant \kappa''p\theta^{-1},$

where $\kappa' := \max(2\kappa, 1)$ and κ'' is an absolute constant small enough.

• In particular, if we choose θ proportional to $\log p$ (which is natural to have results on events with large probability), then the regime becomes

 $\sqrt{p}\log(p) << n << p\log^{-1}(p).$

Control of the weights II

Theorem

• On a event of probability larger than $1 - (2 + 8.54p)e^{-\theta}$

$$\bar{c}\left(n\theta\|x^*\|_{\ell_{\mathbf{1}}}+\theta^2\right)\leqslant d^2\leqslant c\left(n\theta\|x^*\|_{\ell_{\mathbf{1}}}+\theta^4\right).$$

• On a event of probability larger than $1 - 10.54 p e^{-\theta}$, for any $k \in \{1, \dots, p\}$,

$$c''\left(n\theta x_k^* + n^2\theta p^{-1}\sum_{u\neq k} x_u^* + \theta^2\right)$$
$$\leqslant \tilde{d}_k^2 \leqslant c'\left(n\theta x_k^* + n^2\theta^2 p^{-1}\sum_{u\neq k} x_u^* + \theta^4\right)$$

.

Control of the weights II

For instance, in the asymptotic regime

$$n heta=o(p)$$
 and $heta^2=o(n^2\|x^*\|_1/p),$

then if $x_k^* = 0$,

$$\tilde{d}_k^2 = O(n^2 \theta^2 p^{-1} ||x^*||_1) = o(n\theta ||x^*||_1).$$

Therefore

$$\tilde{d}_k^2 = o(d^2),$$

i.e. \tilde{d}_k can be much more smaller than d.

Oracle inequalities for the lasso estimate with d

Theorem

Let $\gamma > 2$ and $0 < \varepsilon < 1$. Let s a positive integer satisfying

$$rac{3\gamma+2}{\gamma-2}s\xi(heta)\leqslant 1-arepsilon.$$

Then, there exists a constant $C_{\gamma,\varepsilon}$ depending on γ and ε such that on an event of probability larger than $1 - (1 + 7.54p)e^{-\theta}$, the lasso estimate \hat{x} satisfies

$$\|\widetilde{A}\widehat{x} - \widetilde{A}x^*\|_2^2 \leqslant C_{\gamma,\varepsilon} \inf_{x: |\operatorname{supp}(x)| \leqslant s} \left\{ \|\widetilde{A}x - \widetilde{A}x^*\|_2^2 + \frac{sd(\theta)^2}{n} \right\}$$

And if x^* is *s*-sparse, under the same assumptions, we get that

$$\|\widetilde{A}\widehat{x}-\widetilde{A}x^*\|_2^2\leqslant rac{C_{\gamma,arepsilon}sd(heta)^2}{n}.$$

Remark : We also obtain oracle inequalities for the ℓ_1 and ℓ_∞ -losses.

Oracle inequalities for the lasso estimate with \tilde{d}_k

Theorem

Let $\gamma>2$ and 0 $<\varepsilon<1.$ Let s be a positive integer and assume that we are on an event s.t.

$$\frac{\max_{1\leqslant k\leqslant p}\widetilde{d}_k(\theta)}{\min_{1\leqslant k\leqslant p}\widetilde{d}_k(\theta)}\leqslant \frac{\left((1-\varepsilon)s^{-1}\xi(\theta)^{-1}-1\right)(\gamma-2)}{2(\gamma+2)}$$

Then, there exists a constant $C_{\gamma,\varepsilon}$ depending on γ and ε such that on an event of probability larger than $1-8.54pe^{-\theta}$, the lasso estimate \hat{x} satisfies

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And what happens next?

We will consider a second alternative consisting in assuming that x* is supported by S* with |S*| = o(p). We then introduce the pseudo-estimate x^(S*) defined by

$$\widehat{x}^{(S^*)} \in \operatorname*{argmin}_{x \in \mathbb{R}^{p}: \mathrm{supp}(x) \subseteq S^*} \left\{ \|\widetilde{Y} - \widetilde{A}x\|_2^2 + \gamma \sum_{k=0}^{p-1} d_k |x_k| \right\}.$$

In this case, we shall see that under some conditions the support of \hat{x} is included into S^* (support property), enabling us to derive oracle inequalities quite easily.

Model

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Merci pour votre attention !