Adaptive one-bit matrix completion

Joseph Salmon

Télécom Paristech, Institut Mines-Télécom

Joint work with Jean Lafond (Télécom Paristech) Olga Klopp (Crest / MODAL'X, Université Paris Ouest) Éric Moulines (Télécom Paristech)



songs (Pandora, Itunes)







. . .

In all those cases matrix completion is **a** crucial ingredient (not the only one) for improving recommender systems Koren *et al.* [2009]

Recommendation systems : movie example



Medhi	★★★★★	*	?	*	★★★★★
Lorne	★	★★★★	?	★★★	★★★
Raquel	?	?	?	★★★★	★
Maria	?	★★	★★★★	★★★★★	★★★
Robert	★★	★★★★	?	?	?

Recommendation systems : movie example



Medhi	★★★★★	★	****	*	★★★★★
Lorne	★	★★★★★	**	★★★	★★★
Raquel	*	****	**	★★★★	★
Maria	****	★★	★★★★	★★★★★	★★★
Robert	★★	★★★★	*	****	****

Quantum physics

- Quantum physics
- Image/signal processing with missing pixels

- Quantum physics
- Image/signal processing with missing pixels
- Communications

- Quantum physics
- Image/signal processing with missing pixels
- Communications
- Analysis of survey data

- Quantum physics
- Image/signal processing with missing pixels
- Communications
- Analysis of survey data
- ▶ ...

Classical theoretical model : partial observation and Gaussian noise

Observation model

- Matrix of true ratings : $X^* \in \mathbb{R}^{m_1 \times m_2}$ (to recover)
- ► Indexes observed : $(\omega_i)_{1 \le i \le n} \stackrel{i.i.d.}{\sim}$ Unif over $[m_1] \times [m_2]$,
- Noisy observations : $Y_{\omega_i} = X^*_{\omega_i} + \sigma \varepsilon_{\omega_i}$ for $1 \le i \le n$
- σ : noise level, ε : centered standard Gaussian random vector



<u>Rem</u>: potentially $n \ll m_1 m_2$

<u>Rem</u>: randomness sources : 1) index picking 2) degraded answer

Some dataset sizes

Parameter Size	m_1	m_2	n
MovieLens	$70 \cdot 10^3$	$10 \cdot 10^{3}$	$10 \cdot 10^{6}$
NetFlix	$2.5 \cdot 10^{6}$	$17 \cdot 10^{3}$	$100 \cdot 10^{6}$
Yahoo	$1 \cdot 10^{6}$	$600 \cdot 10^3$	$250 \cdot 10^6$

Low rank and matrix factorization

Underlying simplifying assumption : $r^* = \operatorname{rank}(X^*)$ is small Consequence :

▶ pass from m_1m_2 to $r^*(m_1 + m_2)$ degrees of freedom Interpretation :

- a combination of few items can represent all of them
- a combination of few users can represent all of them



 $X^* = L \cdot R^\top$

Popular estimator

Least square penalized by trace/nuclear norm

$$\hat{X} = \underset{X \in \mathbb{R}^{m_1 \times m_2}}{\arg\min} \frac{1}{2} \sum_{i=1}^n (Y_{\omega_i} - X_{\omega_i})^2 + \lambda \|X\|_{\sigma,1}$$

- $||X||_{\sigma,1}$: trace/nuclear norm (ℓ_1 norm of the singular values)
- $\lambda > 0$: regularization parameter controlling data-fitting / low rank trade-off

Rem:

- ▶ vector case : $\| \cdot \|_1$ regularization \Rightarrow sparsity (LASSO)
- matrix case : $\|\cdot\|_{\sigma,1}$ regularization \Rightarrow low rank

Previous theoretical work on matrix completion with

- noise-free scenario : Recht, Fazel and Parrilo [2010] Candès and Recht [2009] Candès and Tao [2010]
- additive noise scenario : Candès and Plan [2010] Koltchinskii, Tsybakov and Lounici [2011] Negahban and Wainwrigh [2012] Klopp [2014]

Typical results :

Klopp [2014]

 $m_1 m_2$

For
$$\lambda = C\sigma \sqrt{\frac{\log(m_1 + m_2)}{\min(m_1, m_2)n}}$$
, w.h.p.
$$\frac{\|\hat{X} - X^*\|_F^2}{m_1 m_2} \le c \max(\sigma^2, \|X^*\|_\infty^2) \frac{r^* \max(m_1, m_2) \log(m_1 + m_2)}{n}$$

<u>Rem</u>: can be extended to non uniform sampling provided each coefficient is sampled sufficiently often

n

Limits of the previous model

- ► Generally ratings are discrete (0-1, 1-5 stars, etc.)
- In surveys, answers are naturally discrete (yes/no, classes, etc.)
- Variance of the noise model (implicitly) assumed identical for all entries. Cases with picky distribution *e.g.*, movies with agreement (only 5's) / disagreement among the audience (lots of 1's and lots of 5's).

Binary model

Observation model Davenport et al. [2012]

- Matrix of true ratings to recover : $X^* \in \mathbb{R}^{m_1 \times m_2}$
- ► Indexes observed : $(\omega_i)_{1 \le i \le n} \stackrel{i.i.d.}{\sim}$ Unif over $[m_1] \times [m_2]$,
- Indirect observations :

$$\mathbb{P}(Y_{\omega_i} = 1) = f(X_{\omega_i}^*) \text{ and } \mathbb{P}(Y_{\omega_i} = -1) = 1 - f(X_{\omega_i}^*)$$

where f is a link function taking value in [0, 1].

<u>Rem</u>: Uniform sampling only for the sake of simplicity <u>Rem</u>: To obtain theoretical guarantees $\log(f(\cdot))$ and $\log(1 - f(\cdot))$ need to be concave (*e.g.*, logit, probit)

The estimator

The log-likelihood of the observations $X \to L(X)$:

$$\mathcal{L}(X) = \sum_{i=1}^{n} \left[\mathbb{1}_{\{Y_{\omega_i}=1\}} \log(f(X_{\omega_i})) + \mathbb{1}_{\{Y_{\omega_i}=-1\}} \log(1 - f(X_{\omega_i})) \right] .$$

Penalized log-likelihood estimator

$$\hat{X} = \underset{X \in \mathbb{R}^{m_1 \times m_2}}{\operatorname{arg\,min}} \operatorname{F}(X) , \quad \text{where} \quad \operatorname{F}(X) = -\frac{1}{n} \operatorname{L}(X) + \lambda \|X\|_{\sigma,1} ,$$

with $\lambda > 0$ a regularization parameter.

Results

Proposed result
For
$$\lambda = C\sqrt{\frac{\log(m_1+m_2)}{\min(m_1,m_2)n}}$$
 w.h.p.
 $\operatorname{KL}\left(f(X^*), f(\hat{X})\right) \leq c^* \frac{r^* \max(m_1, m_2) \log(m_1 + m_2)}{n}$

where we define the Kullback-Liebler divergence :

$$\mathrm{KL}(P,Q) := \frac{1}{m_1 m_2} \sum_{\substack{1 \le i \le m_1 \\ 1 \le j \le m_2}} \left[P_{i,j} \log \frac{P_{i,j}}{Q_{i,j}} + (1 - P_{i,j}) \log \frac{1 - P_{i,j}}{1 - Q_{i,j}} \right].$$

```
Multinomial Coordinate Lifted Gradient Desc. : Dudik et al. [2012]
Data: Observations : Y
ini. param. : \theta_0 \in \Theta_+; tolerance : \epsilon; maximum iterations : K
Result: \theta \in \Theta_+
Initialization : \theta \leftarrow \theta_0, conv \leftarrow 0, k \leftarrow 0
while k \leq K and conv = 0 do
       Compute top singular vectors pair of (-\nabla F(W_{\theta})) : u, v Let
       g = \lambda + \left\langle \nabla \mathbf{L}, uv^{\top} \right\rangle
       if g \leq -\epsilon/2 then
         \begin{bmatrix} \beta = \arg \min_{b \in \mathbb{R}} F\left(\theta + (b\delta_{uv^{\top}})\right) \\ \theta \leftarrow \theta + \beta \delta_{uv^{\top}} ; k \leftarrow k + 1 \end{bmatrix} 
       end
       else
               if q \leq \epsilon then
               | \operatorname{conv} \leftarrow 1
               end
               else
                      \theta \leftarrow \arg \min_{\theta' \in \mathbb{R}^{+\mathbb{K}}, \operatorname{supp}(\theta') \subset \operatorname{supp}(\theta)} F(\theta'); k \leftarrow k+1
               end
       end
end
```

Main interests compared to other classical methods

- Does not require full SVD as proximal methods
- Convex formulation which offers strong theoretical guarantees
- Well adapted to sparse structure

• Simulate X^* for $m_1 \times m_2 = 100 \times 150, \ 300 \times 450, \ 900 \times 1350 \text{ and } r^* = 5$

• Simulate X^* for

 $m_1 \times m_2 = 100 \times 150, \, 300 \times 450, \, 900 \times 1350 \text{ and } r^* = 5$

► For each X* simulate with logit distribution n observations, from n = 10000 to 500000

► Simulate X^{*} for

 $m_1 \times m_2 = 100 \times 150, \ 300 \times 450, \ 900 \times 1350 \ \text{and} \ r^* = 5$

- ► For each X* simulate with logit distribution n observations, from n = 10000 to 500000
- For Gaussian and Binomial estimator, choose λ by cross validation

► Simulate X^{*} for

 $m_1 \times m_2 = 100 \times 150, \, 300 \times 450, \, 900 \times 1350$ and $r^* = 5$

- For each X^* simulate with logit distribution n observations, from n = 10000 to 500000
- For Gaussian and Binomial estimator, choose λ by cross validation
- For Gaussian and Binomial estimator, estimate X^*

► Simulate X^{*} for

 $m_1 \times m_2 = 100 \times 150, \, 300 \times 450, \, 900 \times 1350$ and $r^* = 5$

- ► For each X* simulate with logit distribution n observations, from n = 10000 to 500000
- For Gaussian and Binomial estimator, choose λ by cross validation
- For Gaussian and Binomial estimator, estimate X^*
- ► For Gaussian and Binomial estimator, compute KL divergence

Illustration over simulation (with cross-validation choice for λ)



Conclusion

- New results for binary / logit matrix completion
- No need to know a bound on the rank or to make a "spikiness" assumption
- Fast algorithm based on Lifted Coordinate Descent Dudik et al. [2012]
- Extension to multinomial under some separability

Références I

E. J. Candès and Y. Plan.

Matrix completion with noise.

Proceedings of the IEEE, 98(6) :925-936, 2010.

E. J. Candès and B. Recht.

Exact matrix completion via convex optimization. *Found. Comput. Math.*, 9(6) :717–772, 2009.

E. J. Candès and T. Tao.

The power of convex relaxation : Near-optimal matrix completion. *IEEE Trans. Inf. Theory*, 56(5) :2053–2080, 2010.

M. Dudík, Z. Harchaoui, and J. Malick.

Lifted coordinate descent for learning with trace-norm regularization. In *AISTATS*, 2012.

M. A. Davenport, Y. Plan, E. van den Berg, and M. Wootters.
 1-bit matrix completion.
 CoRR, abs/1209.3672, 2012.

Références II

Y. Koren, R. Bell, and C. Volinsky. Matrix factorization techniques for recommender systems.

Computer, 42(8) :30–37, 2009.

► O. Klopp.

Noisy low-rank matrix completion with general sampling distribution. *Bernoulli*, 2(1) :282–303, 02 2014.

► V. Koltchinskii, A. B. Tsybakov, and K. Lounici.

Nuclear-norm penalization and optimal rates for noisy low-rank matrix completion.

Ann. Statist., 39(5) :2302–2329, 2011.

S. Negahban and M. J. Wainwright.

Restricted strong convexity and weighted matrix completion : optimal bounds with noise.

J. Mach. Learn. Res., 13 :1665-1697, 2012.

Références III

► B. Recht, M. Fazel, and P. A. Parrilo.

Guaranteed minimum-rank solutions of linear matrix equations via nuclear norm minimization.

SIAM review, 52(3) :471-501, 2010.