Online Learning & Game Theory A quick overview with recent results

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Starting Examples



Starting Examples

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- First, in a stochastic environment (i.i.d. processes)
- 2 Then, in an adversarial environment (or individual sequences)
- Finally, some links with game theory

Extensions



Stochastic environment



Estimation of Means

K = 2 discrete-time proc.: $X_n^{(1)}, X_n^{(2)}$ in [0, 1] "The payoff of the ad 1/2 on query *n*"

Estimate the means $\mu^{(1)}, \mu^{(2)}$

Hoeffding inequality: exponential decay

$$\left|\overline{X}_{n}^{(k)}-\mu^{k}\right|>\varepsilon$$
 with proba at most $2\exp\left(-2n\varepsilon^{2}\right)$.

Finite number of mistakes:

$$\mathbb{E}\sum_{n\in\mathbb{N}}\mathbb{1}\left\{\left|\overline{X}_{n}^{(k)}-\mu^{k}\right|>\varepsilon\right\}\leq\frac{1}{\varepsilon^{2}}$$



Regret Minimization

- Choose **one** ad to display k_n . Reward: $X_n^{(k_n)}$

Maximize cumulative reward $\sum_{m=1}^{n} X_m^{(k_m)}$ or $\sum_{m=1}^{n} \mu^{(k_m)}$

Minimize Regret [Hannan'56]

$$R_n = n\mu^* - \sum_{m=1}^n \mu^{(k_m)}, \text{ with } \mu^* = \max\{\mu^{(1)}, \mu^{(2)}\}$$

- Equivalent formulation with $\Delta = \mu^* - \mu^k$:

$$R_n = \Delta \sum_{m=1}^n \mathbb{1}\{k_m \neq \star\}$$

Stochastic & Full Monitoring

- Full Monitoring: all values $X_n^{(1)}, X_n^{(2)}$ observed.
- Optimal algorithm: $k_n = \arg \max \overline{X}_n^{(k)}$:

$$\mathbb{E} R_n \leq rac{1}{\Delta}$$
 and for small $n, \ \mathbb{E} R_N \leq n \Delta$

Bounded regret, uniformly in n!

- **Given** *n*, worst Δ is $1/\sqrt{n}$ and $\mathbb{E}R_n \leq \sqrt{n}$
- But in the examples, **only** $X_n^{(k_n)}$ is observed (bandit monitoring)!

(1.)

Stochastic & Bandit Monitoring

$$- \overline{X}_n^{(k)} = \frac{1}{n} \sum_{m=1}^n X_m^{(k)} \text{ not available, only } \widehat{X}_n^{(k)} = \frac{\sum_{m:k_m=k} X_m^{(k)}}{\#\{m:k_m=k\}}$$

- with $k_n = \arg \max \widehat{X}_n^{(k)}, \mathbb{E}R_n = \Theta(n).$
- Balance exploitation (play arg max) and exploration (play arg min) to get information

Upper Confidence Bound [Auer,Cesa-Bianchi,Fischer'02]

$$k_n = rg \max \widehat{X}_n^{(k)} + \sqrt{rac{2\log(n)}{\sharp\{m:k_m=k\}}}$$

$$\mathbb{E} \boldsymbol{R}_n \leq \Box \frac{\log(n)}{\Delta}$$

New policy: Explore Then Commit [P,Rigollet '13]

- Finite horizon $N \in \mathbb{N}$ given.
- 1) Play alternatively arm 1 and 2 as long as

$$\left|\widehat{X}_{n}^{(1)}-\widehat{X}_{n}^{(2)}\right|\leq 2\sqrt{2rac{\log(4N/n)}{n}}$$

2) Then play for ever the best arm.

$$ightarrow \mathbb{E}\mathbb{R}_{N} \leq \Box rac{\log(N\Delta^{2})}{\Delta}$$
 vs $rac{1}{\Delta}$ with Full Info

→ Worst case $\Delta \simeq \frac{1}{\sqrt{N}}$ Full Monit & ETC: \sqrt{N} vs UCB: $\sqrt{N} \log(N)$

Bandit vs Full Monitoring

Logarithmic vs bounded regret;

same worst case

Bounded Regret ? [Lai,Robbins'84],[Bubeck,P,Rigollet '13]

- Without additional assumption, No: lower bound in $log(n)/\Delta$
- With any given intermediate value $\mu^{\sharp} \in (\mu^{(1)}, \mu^{(2)})$, yes:
- If $\widehat{X}_n^{(1)}$ or $\widehat{X}_n^{(2)}$ above μ^{\sharp} , then $k_n = rg \max \widehat{X}_n^{(k)}$
- Otherwise play alternatively both arms.

 $\widehat{X}_n^{\star} < \mu^{\sharp}$ on $rac{1}{(\mu^{\star} - \mu^{\sharp})^2}$ stages (same argument for other arm).

- If μ^* and Δ known: $\mathbb{E}R_n \leq \Box \frac{1}{\Lambda}$ as with Full Monit.
- If only μ^* known: $\mathbb{E}R_n \leq \Box \frac{\log(1/\Delta^2)}{\Delta}$

More General Frameworks & Results

Results in worst case ("distribution independent bounds")

- Multi-armed bandit. [Auer,Cesa-Bianchi,Freund,Schapire'02],[Audibert,Bubeck'09] $K > 2 \text{ arms}, \mathbb{E}R_n \leq \Box \sqrt{Kn}$
- Continuous bandit. [Kleinberg'08],[Bubeck,Munos,Stoltz,Szepesvari'11] Infinite set of arms, $x \in [0, 1]^d$ and $\mu(\cdot)$ Lipschitz. $\mathbb{E}R_n \leq \Box n^{\frac{d+1}{d+2}}$
- Linear bandit[Dani,Hayes,Kakade'08],[Zinkevich'02],[Abernethy,Hazan,Rakhlin'08] $x \in [0, 1]^d$ and $\mu(\cdot)$ Linear. $\mathbb{E}R_n \leq \Box \sqrt{n}$
- Bandit with covariates (cf Google Example) [P.Rigollet 13],[Bull'14] Covariates $\omega \in [0, 1]^d$, $\mathbb{E}[X^{(k)}|\omega] = \mu^{(k)}(\omega)$ 1-Lip. $\mathbb{E}R_n \leq \Box n^{\frac{d+1}{d+2}}$
- Higher order bounds/small losses/sparsity[Hazan,Kale'10], [Gershinovitz'13], [Cappé,Garivier,Maillard,Munos,Stoltz'13], [Gaillard,Stoltz,van Erven'14]

$$\sqrt{n} \operatorname{vs} \sqrt{\sum_{m=1}^{n} \left(X_m^{(k_m)} - \mu^{(k_m)}\right)^2}, \sqrt{\sum_{m=1}^{n} \sum_{k=1}^{K} p_n^{(k)} \left(X_n^{(k)}\right)^2}$$

An Algorithm

Internal Regret



Adversarial environment

What we have learned so far:

- In worst case analysis

- Regret minimization in $\Box \sqrt{\log(K)n}$ with full monit
- Up to \sqrt{K} , learning as fast with bandit monit. than with full monit.
- In distribution dependent (not worst case)
 - Bounded regret in $\Box \sum \frac{1}{\Delta r}$
 - Additional assumption required to learn as fast in bandit monit

Adversarial World

 In the examples, data are not i.i.d.. Spam senders can even adapt to spam filters, that is:

The law of $X_{n+1}^{(k)}$ can depend on $X_1^{(1)}, \ldots, X_n^{(1)}, X_1^{(K)}, \ldots, X_n^{(K)}$ but **even** on the previous choices k_1, \ldots, k_n .

The environment can adapt and choose rewards strategically.

- Same def of regret (except argmax changes with time)

$$R_n = \max_k \sum_{m=1}^n X_m^{(k)} - \sum_{m=1}^n X_m^{(k_m)}$$

- Goal: a policy with sublinear regret o(n) against **ANY** possible strategy of the environment (in particular any sequences $X_n^{(k)}$)

A Popular Algorithm with Full Monitoring

- With $k_n = \operatorname{argmax} \overline{X}_n^{(k)}, \mathbb{E}R_n = \Theta(n)$.
- With any **deterministic** policy, $\mathbb{E}R_n = \Theta(n)$. '

k with proba
$$\frac{\exp\left(\eta \sum_{m=1}^{n} X_{m}^{(k)}\right)}{\sum_{j=1}^{K} \exp\left(\eta \sum_{m=1}^{n} X_{m}^{(j)}\right)}; \text{temperature } \eta \simeq \sqrt{\log(K)n}$$

- Regret of "exponential weights" [Auer,Cesa-Bianchi,Freund,Schapire'02]

$$\mathbb{E}\boldsymbol{R}_{\boldsymbol{n}} \leq \Box \sqrt{\log(K)\boldsymbol{n}}, \qquad \forall \boldsymbol{n} \in \mathbb{N}$$

- Same dependency in *n* as worst case i.i.d., optimal in *K*.

(An Algorithm)

Optimality and Bandit Monitoring

- **Optimality:**
$$\mathbb{E}R_n \ge \Box \sqrt{\log(K)n}$$
 if $X_n^{(k)} = \pm 1$ w.p. $1/2$

$$\mathbb{E}\sum_{m=1}^{n} X_{m}^{(k_{m})} = 0 \text{ but } \mathbb{E}\max_{k} \sum_{m=1}^{n} X_{m}^{(k)} = \Box \sqrt{\log(K)n}$$

- Bandit Monit.:
$$\widetilde{X}_n^{(k)} = X_n^{(k)} \frac{\mathbb{1}\{k_n = k\}}{\mathbb{P}_n\{k_n = k\}}$$
 unbiased estim. of $X_n^{(k)}$

"Exponential weights" w.r.t. $\widetilde{X}_n^{(k)}$: $\mathbb{E}R_n \leq \Box \sqrt{K \log(K) n}$

Remark: Optimal bounds are $\Box \sqrt{Kn}$

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Discrete/Continuous Time

$$-\frac{\exp\left(\eta \sum_{m=1}^{n} X_{m}^{(k)}\right)}{\sum_{j=1}^{K} \exp\left(\eta \sum_{m=1}^{n} X_{m}^{(j)}\right)} = \nabla \Phi(V_{n}) := \frac{1}{\eta} \log\left(\sum_{k=1}^{K} \exp(\eta V_{n}^{(k)})\right)$$

with $V_{n}^{(k)} = \sum_{m=1}^{n} X_{n}^{(k)} - X_{m}^{(k_{m})}$

Deterministic continuous approx. of stochastic discrete proc.

[Benaïm,Hofbauer,Sorin'06],[Benaïm,Faure'13]

$$- \mathbb{E}[V_{n+1}] - V_n = \left(X_{n+1}^{(k)} - \langle \nabla \Phi(V_n), X_{n+1} \rangle\right)_{k=1,\dots,K}$$

Stochastic Approx of $\dot{V} \in F(V) := \left\{ U - \langle \nabla \Phi(V), U \rangle \vec{\mathbf{1}}; \ U \in R^{\kappa} \right\}$

- Differential inclusion with Lyapounov function $\Phi(V)$: $\Phi(V)' = \langle \dot{V}, \Phi(V) \rangle = \langle U - \langle U, \nabla \Phi(V) \rangle \vec{1}, \nabla \Phi(V) \rangle = 0$

 $- \lim R_n \leq \lim V_n = V(+\infty) = V(0) = \log(d)/\eta$

Refined Regret: Internal-Swap-

- Regret: "As well as the best constant strategy"
- Internal: "On the stages where $k_n = k$, k was the best choice" [Foster, Vohra'99]

$$\boldsymbol{R}_{n}^{\text{int}} = \max_{k} \left\{ \max_{j} \sum_{m:k_{m}=k} \boldsymbol{X}_{m}^{(j)} - \boldsymbol{X}_{m}^{(k)} \right\}$$

- Swap: "As well as $\phi(k)$ instead of $k, \phi : [K] \to [K]$ " [Blum,Mansour'07]

$$m{R}^{ ext{swap}}_n = \max_{\phi[k] o [k]} \sum_{m=1}^n X^{(\phi(k_m))}_m - X^{(k_m)}_m$$

General regret

- Regret: "As well as the best constant strategy"
- General: "As well as $\xi(k_1, \ldots, k_n)$ instead of $k_n, \xi \in \Xi$ " [Lehrer'02]

$$R_{n}^{\text{gen}} = \max_{\xi \in \Xi} \left\{ \max_{j} \sum_{m=1}^{n} X_{m}^{(\xi(k_{1},...,k_{m}))} - X_{m}^{(k_{m})} \right\}$$

- Generalized version of "exponential weights" [P'14]

$$\mathbb{E}R_n^{gen} \leq \Box \sqrt{\log(|\Xi|)n}$$

− Internal regret $\leq \Box \sqrt{\log(K)n}$, Swap regret $\leq \Box \sqrt{K \log(K)n}$

Third Part

Links with Game Theory

What we have learned in the previous section:

- In worst case analysis
 - Learning is as fast in adversarial than stochastic environment
- In the adversarial framework
 - Refined notions of regret can be minimized

Against Opponents - Game Theory

 $X_n^{(k)}$ **not** arbitrary, but induced by choices of another player

- **TWO players**, simultaneous actions in $\{1, ..., K\}$ and $\{1, ..., L\}$
- Payoffs are defined by **two matrices** $A \in \mathbb{R}^{K \times L}$ and $B \in \mathbb{R}^{K \times L}$.
 - Player 1 picks row $k \in \{1, ..., K\}$ and Player 2 column $\ell \in \{1, ..., L\}$
 - Player 1 gets A_{k,ℓ} and Player 2 gets B_{k,ℓ}
- Choices can be **random** $p \in \Delta([K])$ and $q \in \Delta([L])$
 - Player 1 gets $\sum_{k,\ell} p_k q_\ell A_{k,\ell} = p^T A q$; P2 gets $p^T B q$
- Online learning: $X_n^{(k)} = A_{k,\ell_n}$ and $Y_n^{(\ell)} = B_{k_n,\ell}$.

Assume both players minimize regret independently.

Do they "learn a solution concept" from game theory ?

Nash Equilibria

"A Nash equilibria is a situation where no player has interest to change his action" [Nash'50], [Nash'51]

- A Nash equilibria is a pair $(p^*, q^*) \in \Delta([K]) \times \Delta([L])$ such that
 - Player 1 has no interest to change given q*:

$$(p^*)^T A q^* \ge p^T A q^*, \quad \forall p \in \Delta([K])$$

• Player 2 has no interest to change given p*:

 $(\boldsymbol{p}^*)^T \boldsymbol{A} \boldsymbol{q}^* \geq (\boldsymbol{p}^*)^T \boldsymbol{A} \boldsymbol{q}, \quad \forall \boldsymbol{q} \in \Delta([L])$

 There always exist Nash equilibria; generically an odd number [Nash'50], [Nash'51], [Shapley'74]

Are Nash Equilibria Learnable?

- Both players minimize their regret independently.

$$k_n \sim p_n \in \Delta([K]), \ \ell_n \sim q_n \in \Delta([L])$$

Learning Nash equilibria could mean:

- $(p_n, q_n) \in \Delta([K]) \times \Delta([L])$ cv to a NE, or to set of NE.
- $\left(\frac{1}{n}\sum_{m=1}^{n}\delta_{k_m},\frac{1}{n}\sum_{m=1}^{n}\delta_{\ell_m}\right) \in \Delta([K]) \times \Delta([L])$ cv to a NE, or to set of NE
- $\left(\frac{1}{n}\sum_{m=1}^{n} \delta_{k_m,\ell_m}\right) \in \Delta([K] \times [L])$ cv to a NE, or to set of NE
- Nash equilibria are not learnable (independently): [Hart,Mas-Colell'04]
 There always exists a game s.t. none of the convergence occur
- What is Learnable?

correlated eq, Minmax-Value, Potential eq [Coucheney, Gaujal, Mertikopolous]

Correlated Equilibria

"Players use an external device to correlate (as traffic lights); when they are told to take an action (as stop or go), it is optimal"

- A correlated equilibrium is a distribution π ∈ Δ([K] × [L]).
 (k^{*}, ℓ^{*}) ~ π; P1 is told secretly to play k^{*}, P2 to play ℓ^{*}
 - if P1 plays k^{*} ∈ [K], he gets Σ_{ℓ∈[L]} π_{k^{*},ℓ}A_{k^{*},ℓ}. If he plays j ∈ [K] instead, he would get Σ_{ℓ∈[L]} π_{k^{*},ℓ}A_{j,ℓ}

$$-\sum_{\ell \in [L]} \pi_{k^*,\ell} A_{k^*,\ell} \geq \sum_{\ell \in [L]} \pi_{k^*,\ell} A_{j,\ell}, \quad \text{for all } k^*, j \in [K]$$

• Similar to no internal regret !

If both players minimize internal regret, empirical distribution of actions converge to the set of correlated equilibria. [Foster, Vohra'99]

Nash Equilibria

(Other equilibria)

Minmax Theory

In zero-sum games, players have optimal strategies

- "zero-sum": B = -A; P1 maximizes and P2 minimizes $p^{T}Aq$
- $\text{Value} = \max_{p \in \Delta([K])} \min_{q \in \Delta([L])} p^T A q = \min_{q \in \Delta([L])} \max_{p \in \Delta([K])} p^T A q$
- p^* optimal if $(p^*)^T Aq \ge$ Value for all $q \in \Delta([L])$.
- $R_n \leq 0 \Longrightarrow \frac{1}{n} \sum_{m=1}^n X_m^{(k_m)} \geq \text{Value}$
- $\left(\frac{1}{n}\sum_{m=1}^{n}\delta_{k_m},\frac{1}{n}\sum_{m=1}^{n}\delta_{\ell_m}\right)$ cv to optimal strat, i.e. to NE
- NE are fast learnable in zero-sum game, at $O\left(\frac{1}{n}\right)$ [Harris'98]

conclusion

Conclusion

- In worst case analysis

- With full monitoring, learning is **as fast** in adversarial than stochastic environment
- Up to \sqrt{K} , learning is as fast with bandit monit. than with full monit.
- In distribution dependent (not worst case)
 - Additional assumption required to learn as fast in bandit than in full monitoring

- In game theoretic framework

- Nash equilibria are not learnable in general
- Correlated equilibria are learnable (by minimizing internal regret)
- In zero-sum and potential games, equilibria are learnable.

Fundamental textbook: [Cesa-Bianchi,Lugosi'06]