

Lattice algorithms

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Some slides courtesy of X. Pujol & D. Stehlé

LIP / ENSL, CNRS, INRIA, U Lyon, UCBL

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Goals of the course

- Give some important ideas about lattice algorithms;
- Strong focus on lattice basis reduction;
- Some (sketches of) proofs;
- but primarily ideas.
- Please interrupt for any question.

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Outline

- Introduction
- Lattice basis reduction – general issues
- Lattice basis reduction – “optimal” algorithms
- Lattice basis reduction – “blockwise” algorithms
- Approximate and exact algorithms for SVP / CVP
- Application : Coppersmith’s method

Introduction

- A lattice is $L(b_1, \dots, b_n) : \mathbb{Z}b_1 \oplus \dots \oplus \mathbb{Z}b_n$;
- Main algorithmic problems: given (b_1, \dots, b_n) , $L = L(b_1, \dots, b_n)$,
 - SVP: find $\lambda_1(L) := \min_{x \in L - \{0\}} \|x\|$ (and x)
 - CVP: given $t \in \mathbb{R}^n$, find $d(t, L)$ and $x \in L$ st. $\|x - t\| = d(t, L)$;
 - BDD: given $t \in \mathbb{R}^n$ and $r \in \mathbb{R}^+$, find $x \in L$ st. $d(x, t) \leq r$.
 - ... plus variants (gap variants, preprocessing...)

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Natural problems (linear problems in integers). Eg. Knapsack application:

- $x_1, \dots, x_n \in \mathbb{N}^n$, $M = \sum_{i=1}^n \varepsilon_i x_i$, find $(\varepsilon_i) \in \{0, 1\}^n$;
- NP-complete ;

L generated by the columns of

$$M = \begin{pmatrix} 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & & \ddots & \vdots & \\ 0 & 0 & \dots & 1 & 0 \\ x_1 & x_2 & \dots & x_n & -S \end{pmatrix}.$$

- If $\eta \in \mathbb{Z}^{n+1}$, $M\eta = (\eta_1, \dots, \eta_{n-1}, \eta_n, \sum_{i=1}^n \eta_i x_i - \eta_{n+1} S)^t$.
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- Lattice basis reduction.

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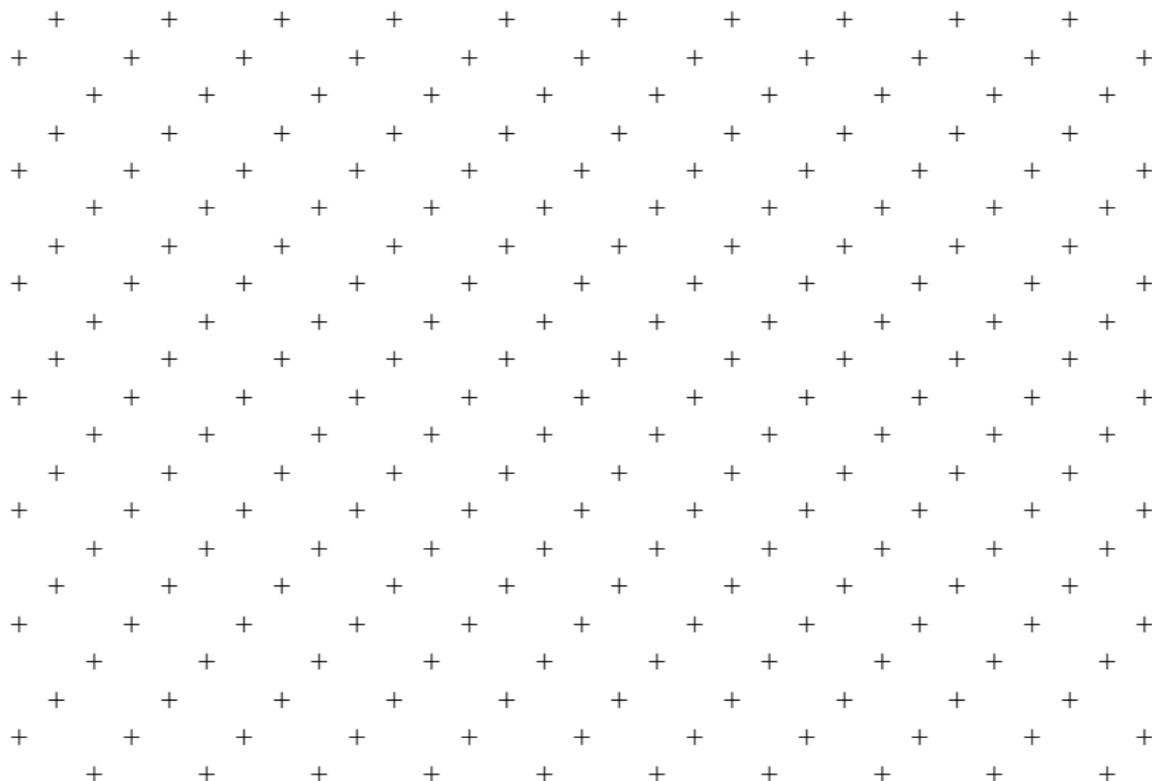
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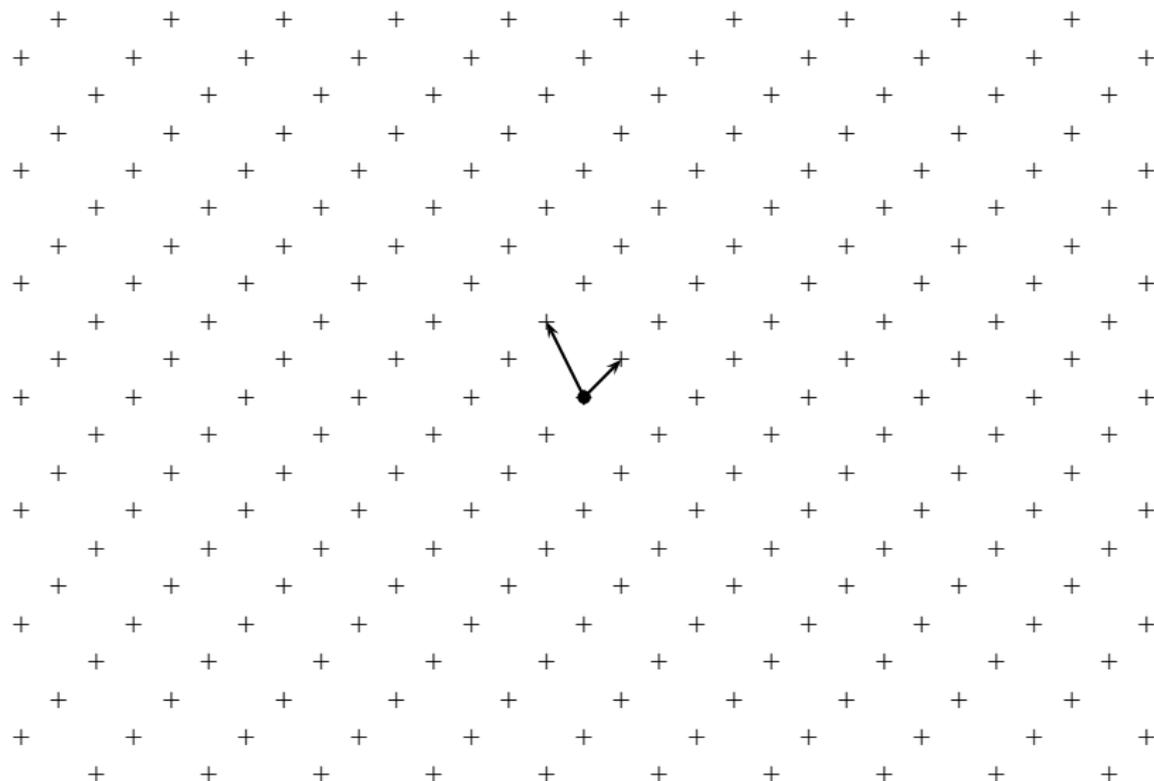
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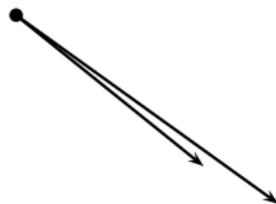
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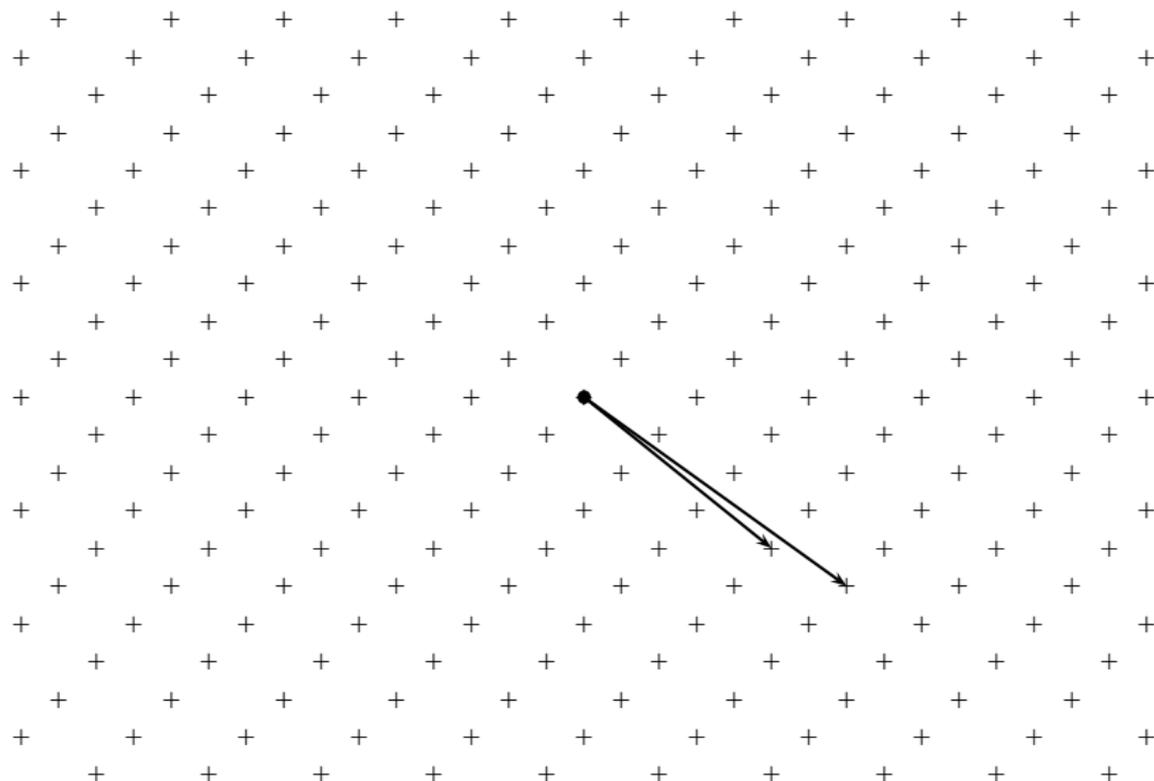
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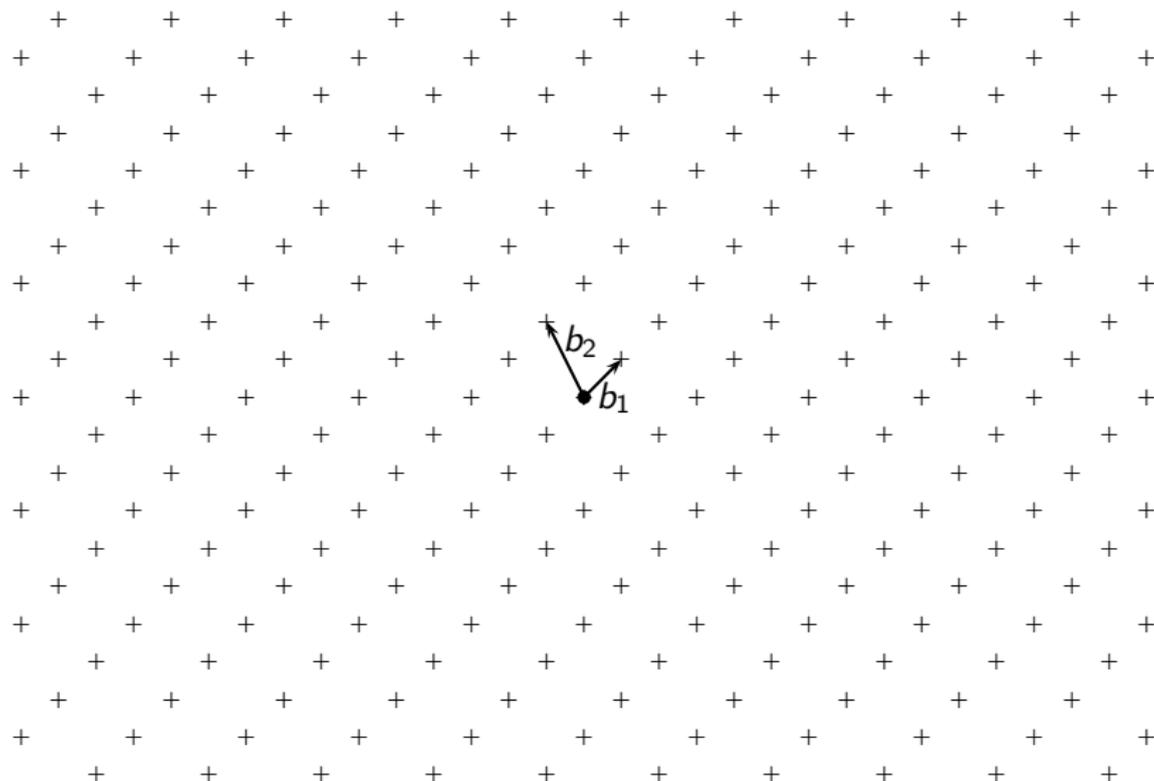
Reseaux euclidiens – bonnes et mauvaises bases



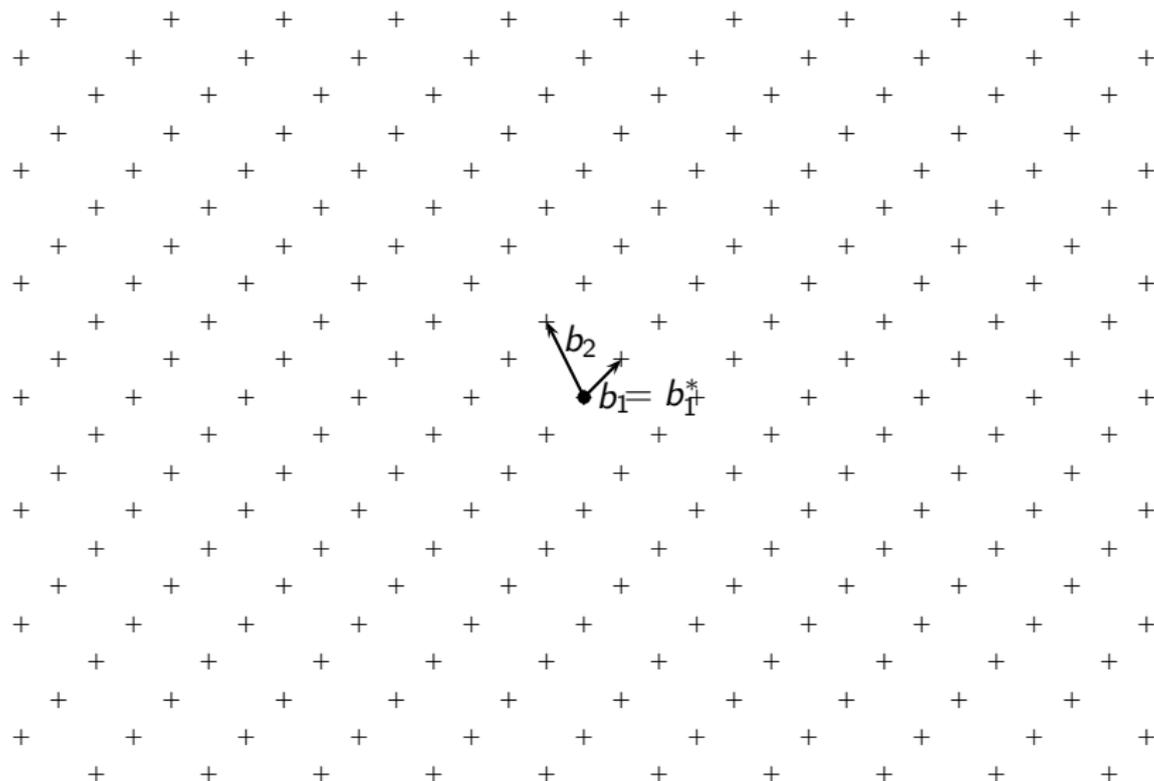
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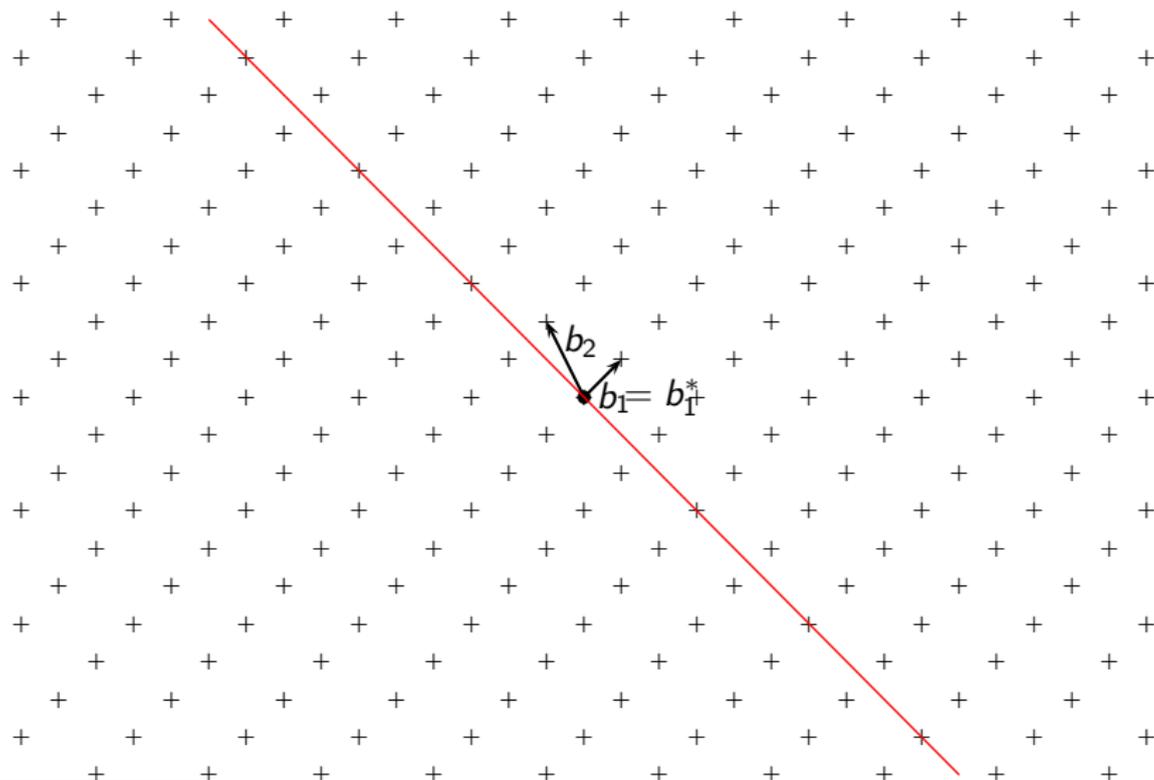
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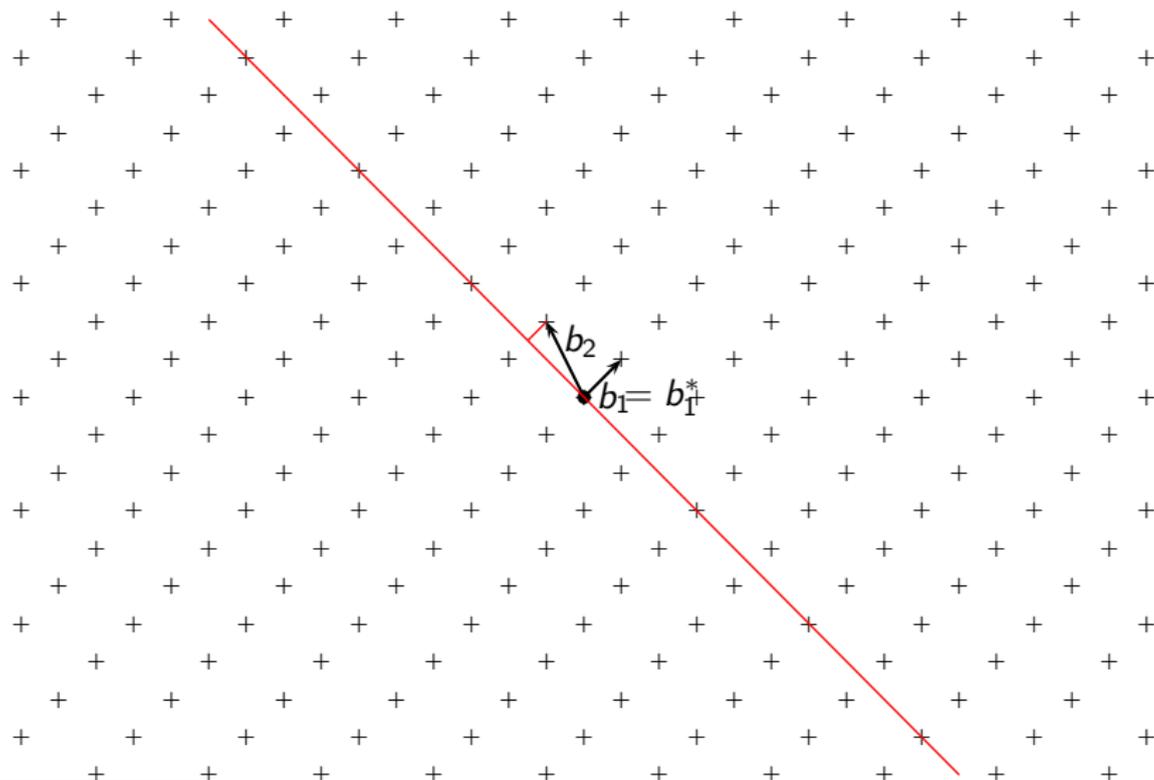
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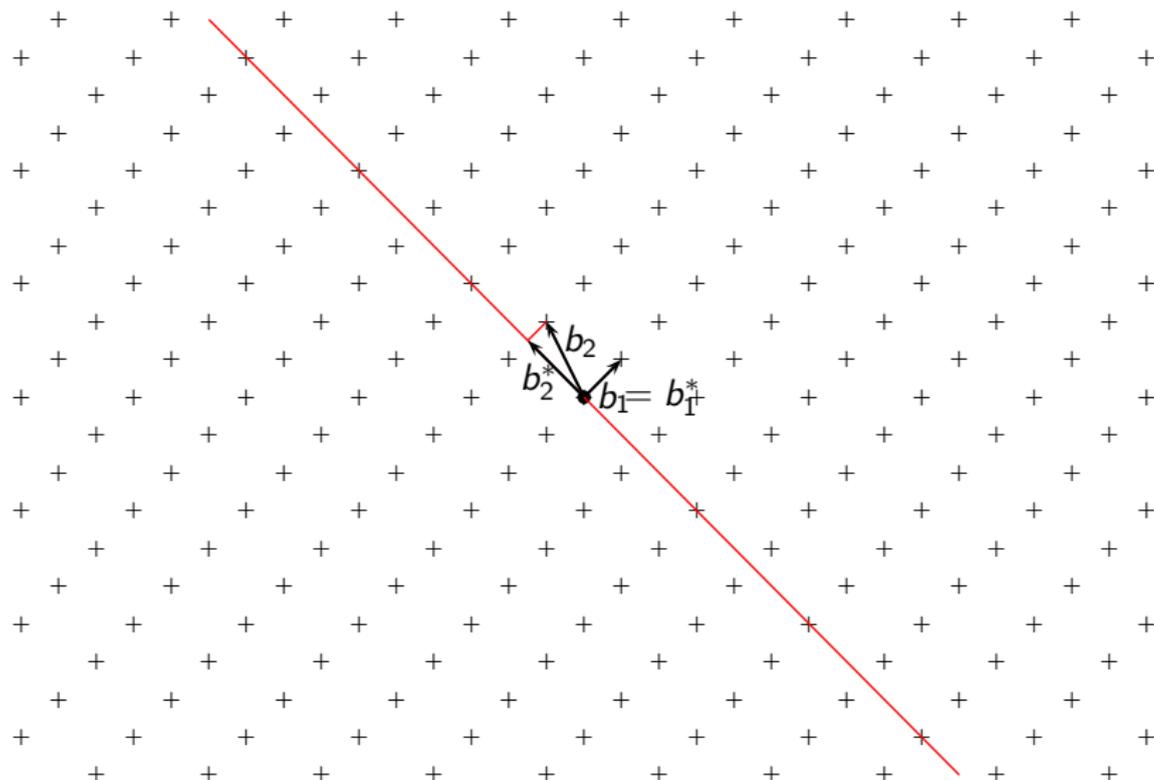
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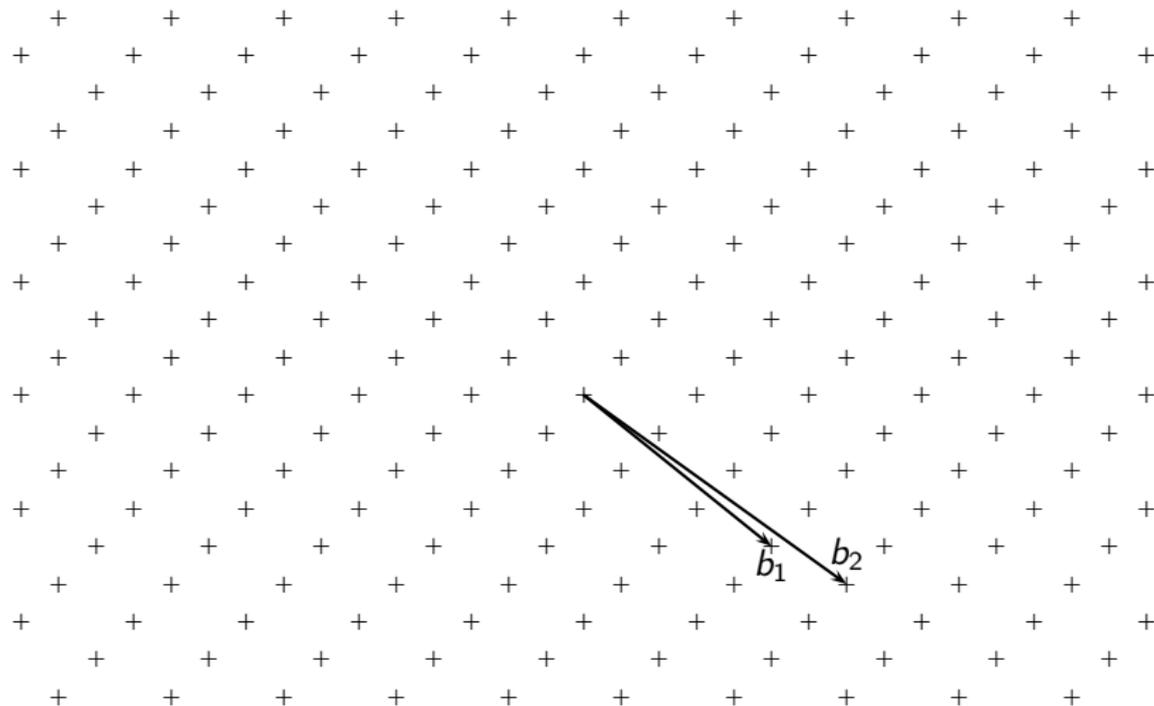


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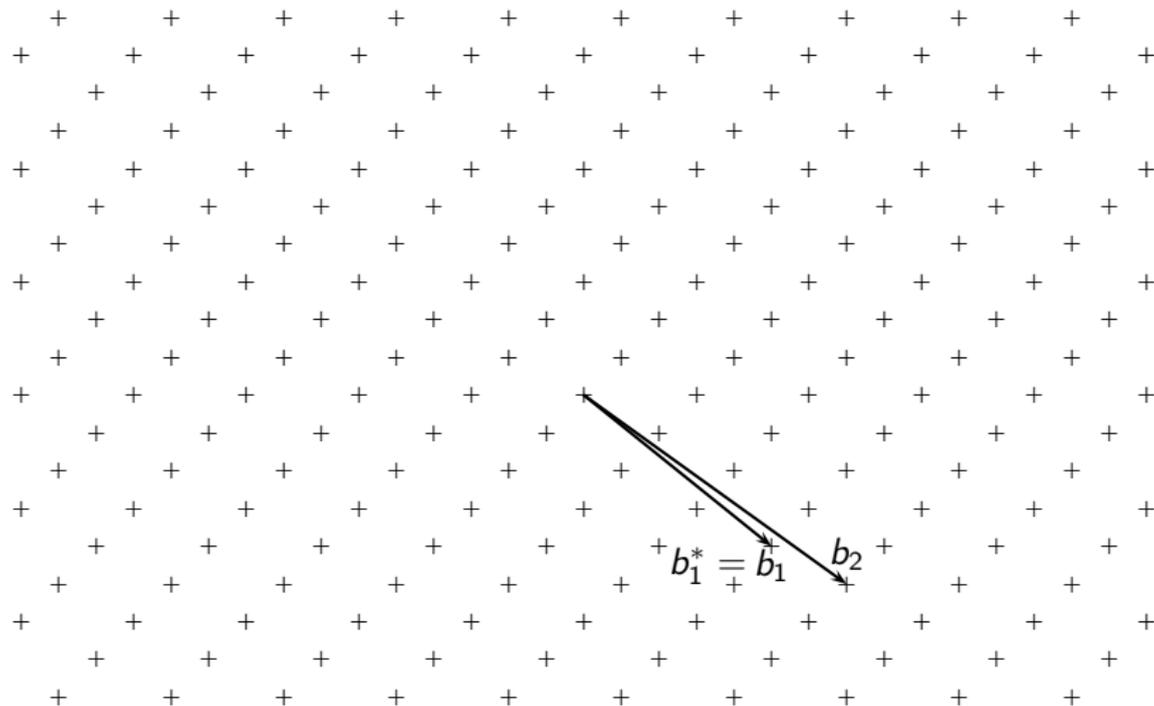
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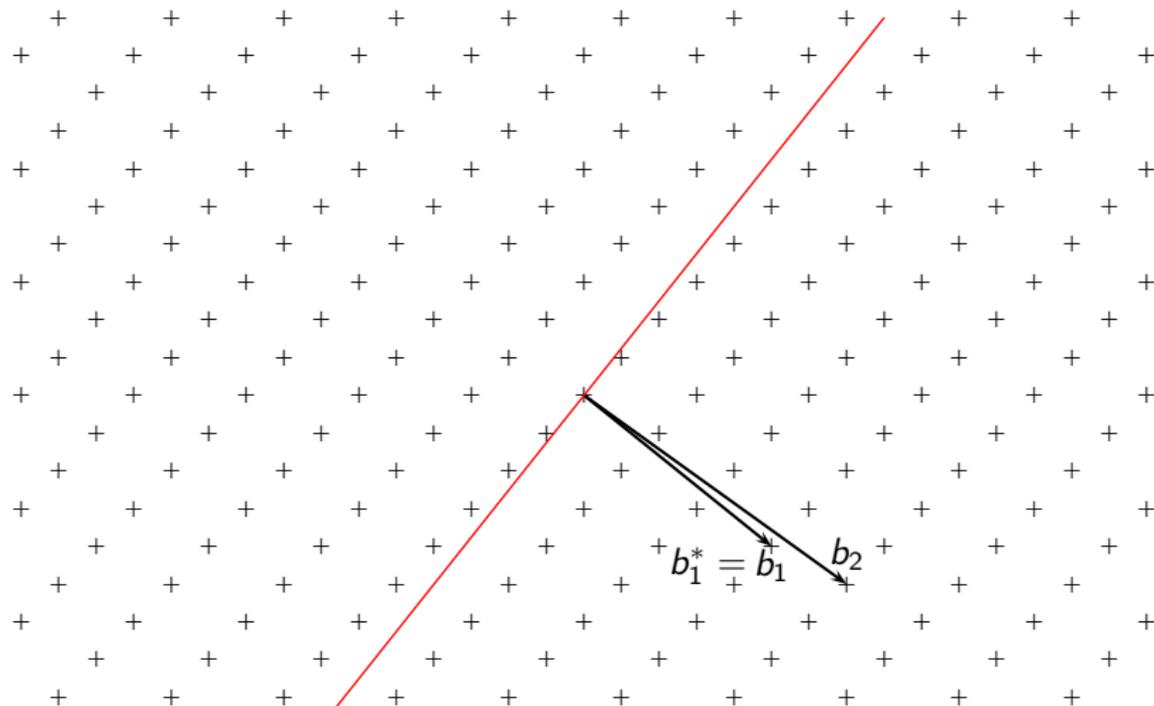
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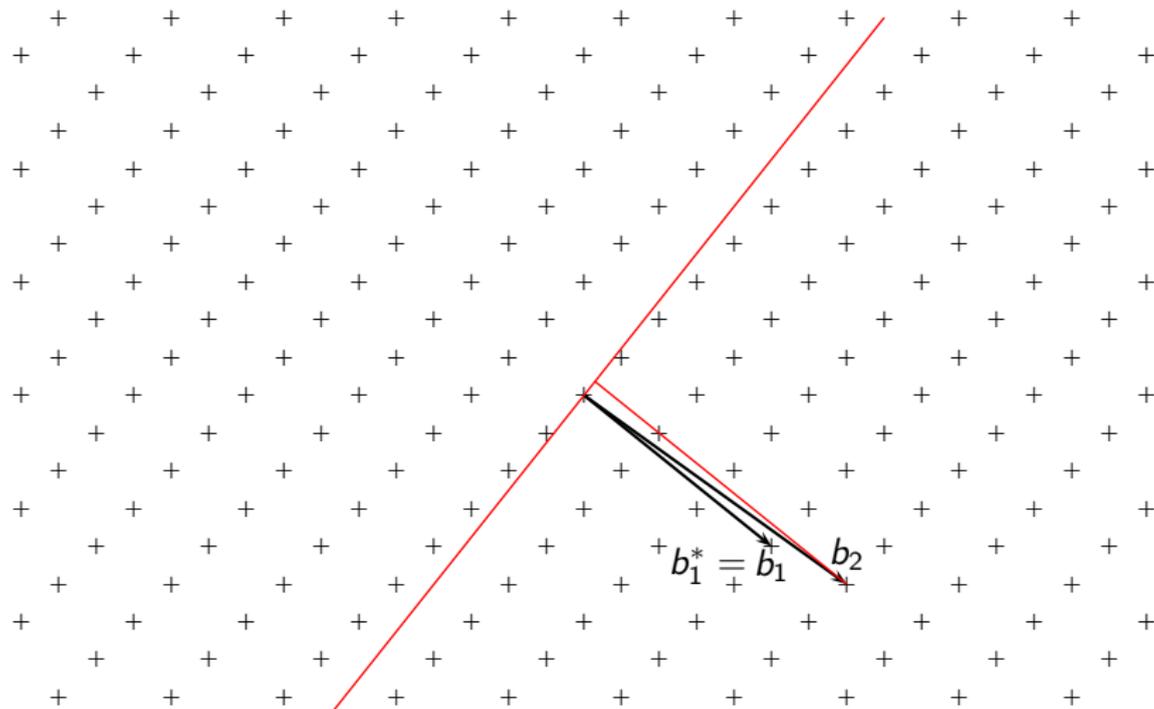
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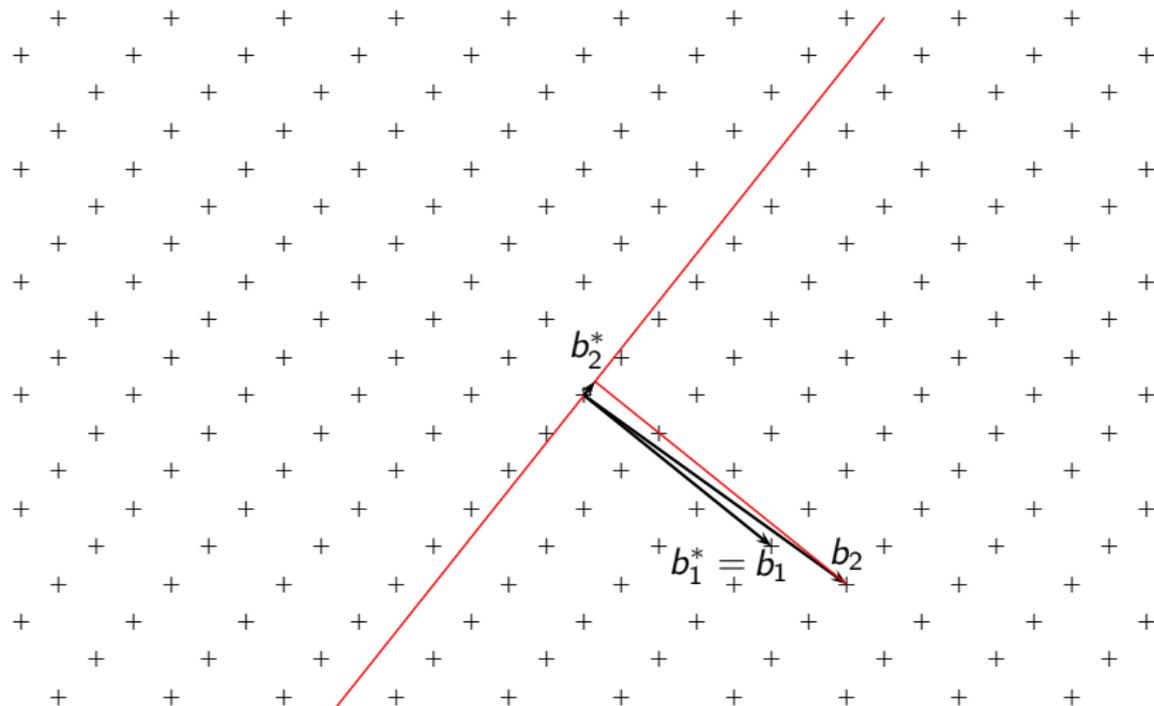
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I. Lattice basis reduction

I. 1. Generalities on lattice basis reduction

Lattice basis reduction - Gram-Schmidt process

- $E_i := \langle b_1, \dots, b_{i-1} \rangle$, $\pi_{E_i^\perp}$.
- Put $b_i^* = b_i - \sum_{j < i} \mu_{ij} b_j^* =: \pi_{E_i^\perp}(b_i)$.
- $\mu_{ij} := (b_i, b_j^*) / \|b_j^*\|^2$.

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Lattice basis reduction

- What is a good basis?
- Geometrically: almost orthogonal;
 - Small orthogonality defect:

$$OD := \frac{\prod_{i=1}^n \|b_i\|}{\prod_{i=1}^n \|b_i^*\|} = \frac{\prod_{i=1}^n \|b_i\|}{\det L} \geq 1.$$

- $\|b_i^*\|$ decreases slowly with i .
- Algorithmically: short vectors;
 - Length defect: $LD_i := \frac{\|b_i\|}{\lambda_i(L)}$.
 - Hermite factor: $HF := \|b_1\| / (\det L)^{1/n}$;
 - SVP approximation factor: $\|b_1\| / \lambda_1(L)$
- Algebraically, $U \in GL_n(\mathbb{Z})$ st. MU is “small”.
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Lattice basis reduction – Example

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 7038304916 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 6175729875 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 9983710959 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 9161878375 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 9322349340 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 9870475629 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 6280159867 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 2020850175 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 893775148 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 37842496080 \end{pmatrix}^T$$

Lattice basis reduction – Example

After LLL reduction

$$\begin{pmatrix} 2 & -1 & 1 & 5 & 1 & 2 & 3 & 1 & 0 & 5 \\ -3 & 6 & 0 & 0 & 8 & 5 & -3 & 1 & 3 & -3 \\ 1 & 2 & 0 & 1 & -4 & -5 & -7 & 5 & 4 & 6 \\ 2 & -6 & 4 & 3 & 0 & 0 & 1 & 3 & 5 & -3 \\ -4 & -1 & -5 & 2 & 2 & -2 & 5 & -2 & 0 & -3 \\ 7 & -3 & -4 & 1 & 1 & -2 & -4 & 1 & 4 & 3 \\ 0 & 3 & -4 & -3 & -3 & 7 & 1 & 4 & -4 & 0 \\ 0 & -4 & 4 & 1 & 4 & 3 & 0 & -7 & 2 & 2 \\ -3 & -1 & 3 & 3 & 4 & 1 & -5 & 2 & -6 & -2 \\ 3 & 0 & -4 & 7 & 0 & 0 & 0 & -1 & -2 & -7 \end{pmatrix}$$

Lattice basis reduction

Relationship “orthogonal \Leftrightarrow short” through

- Minkowski’s second thm :

$$\det L \leq \prod_{i=1}^n \lambda_i(L) \leq \sqrt{n}^n \det L,$$

since $OD / \prod LD_i = \prod_{i=1}^n \lambda_i(L) / \det L$.

- Recall $\lambda_1(L) \geq \min_i \|b_i^*\|$;
- $HF^n = \prod_{i=1}^n \|b_1\| / \|b_i^*\|$.

Reduction notion: quantitative version of all these.

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Lattice basis reduction – notations

Notations :

- L a n -dim. lattice of \mathbb{R}^n , basis (b_1, \dots, b_n) ;
- $(u, v) := \sum_{1 \leq i \leq n} u_i v_i$;
- $\text{vol} L := \sqrt{\det((b_i, b_j))} = |\det(b_i)|$;
- $\|\cdot\|$ is the Euclidean norm, $\|x\| = (x, x)^{1/2}$;
- size of the basis = $\beta := \log \max_{1 \leq i \leq n} \|b_i\|$

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Lattice basis reduction – general strategy

To make b_i small and orthogonal :

- $\|b_i\|^2 = \|b_i^*\|^2 + \|b_i - b_i^*\|^2$;
- Work on $\pi_{L_i^\perp}(b_i, \dots, b_n)$ to improve $\|b_i^*\|$.
- Make second term small \Rightarrow size reduction :
 - Find $x \in L_i := \mathbb{Z}b_1 + \dots + \mathbb{Z}b_{i-1}$ close to $b_i - b_i^*$, $b_i \leftarrow b_i - x$.
- \approx (approx-)CVP.

General philosophy:

- size-reduction + reduce projected sublattices;
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Lattice basis reduction – size reduction

Common feature to all lattice basis reduction algorithms.

- Find $x \in L_i := \mathbb{Z}b_1 + \cdots + \mathbb{Z}b_{i-1}$ close to $t := b_i - b_i^*$;
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- and $t - t_{i-1}b_{i-1}$ close to $\mathbb{Z}b_1 + \cdots + \mathbb{Z}b_{i-2}$
 - Repeat with $t - t_{i-1}b_{i-1}$ until $i = 0$.

Algorithm:

- For j from $i - 1$ downto 1 do
 - $b_i \leftarrow b_i - \lfloor \mu_{ij} \rfloor b_j$
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Lattice basis reduction – a panorama

Strong notions

- Minkowski: b_i shortest possible;
- HKZ (Hermite-Korkine-Zolotarev):
 - b_1 shortest possible = $\lambda_1(L)$
 - size-reduced
 - $\pi_{L_1}(b_2, \dots, b_n)$ HKZ reduced

(Very) costly notions, $2^{O(n)}$ for HKZ.

Lattice basis reduction – a panorama (2)

Weaker / cheaper : blockwise algorithms :

- Use k -dim. HKZ to reduce projections of sublattices;
- size-reduced;
- $\|b_i^*\| \geq \alpha_k^{1-i} \|b_1^*\|$.

Main examples:

- LLL: $\alpha_2 \approx 2/\sqrt{3}$;
- slide, BKZ: $\alpha_k \approx k^{1/k}$;
- Hermite factor $HF = \sqrt{\alpha_k^{n-1}}$;
- Approx-SVP = α_k^{n-1} .

Polynomial time up to $k = O(\log n)$.

I. 2. Lattice basis reduction – algorithms

Lattice basis reduction – outline

- Case $d = 2$, Gauss' algorithm.
- HKZ
- Blockwise algorithms

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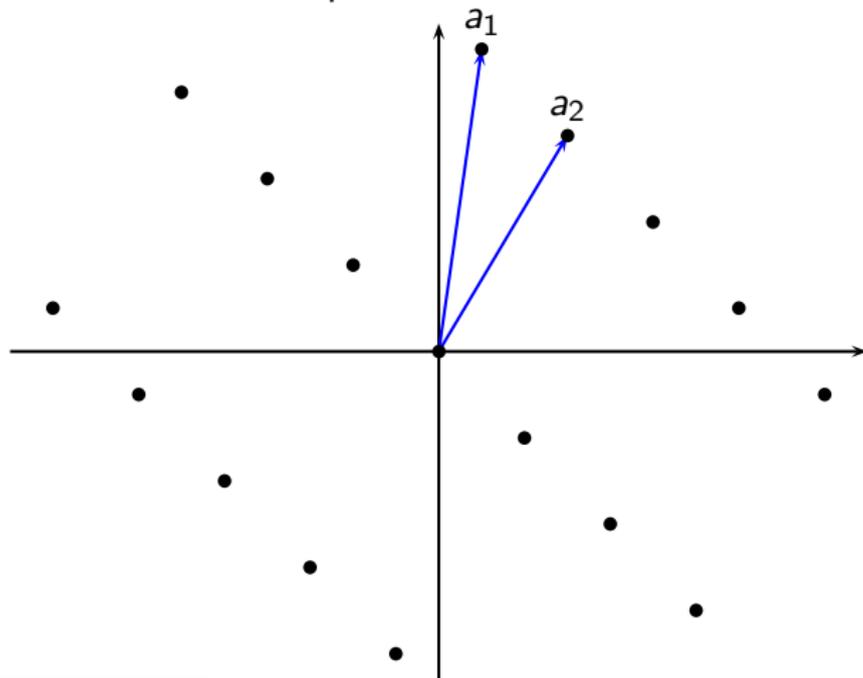
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Lattice basis reduction – “optimal” algorithms

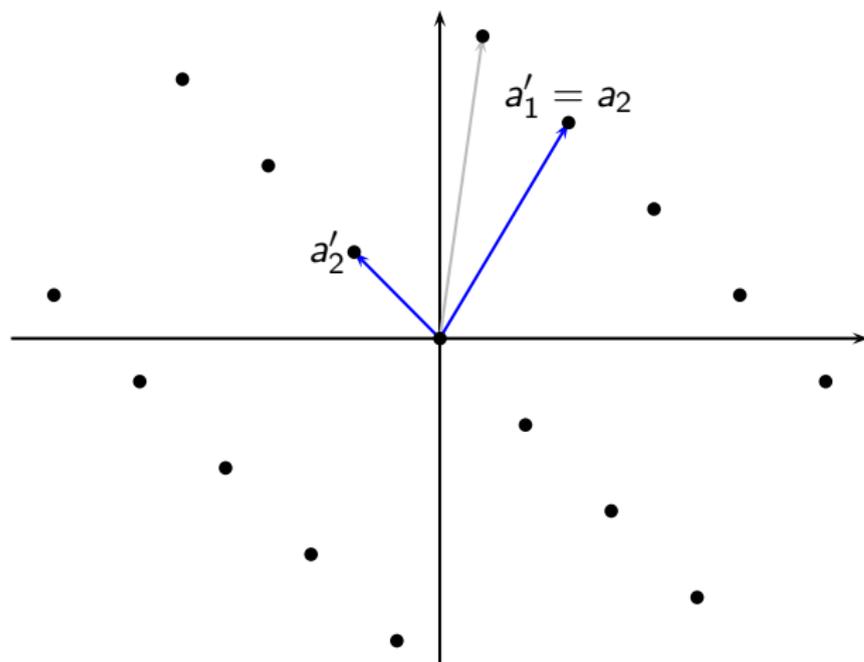
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Lattice basis reduction – “optimal” algorithms

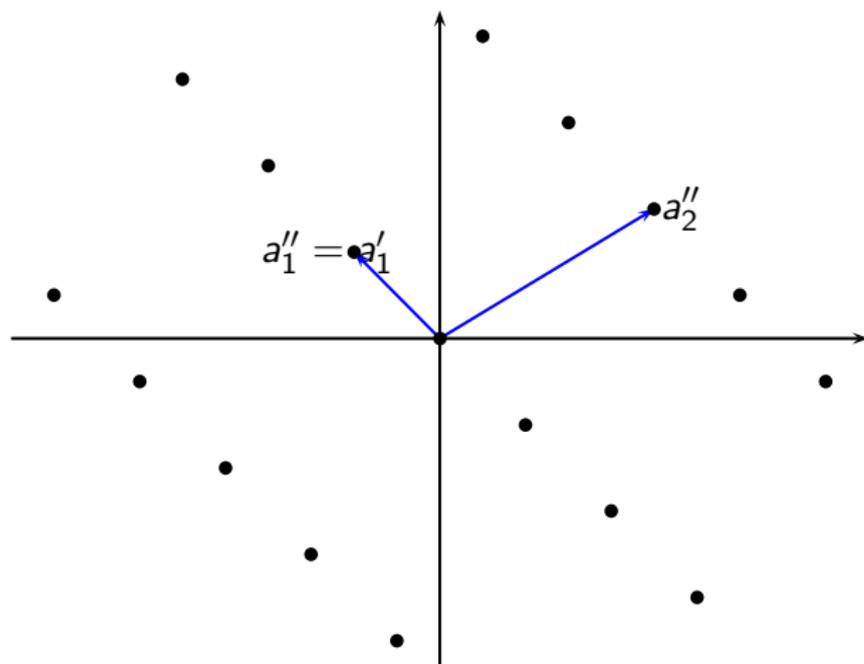
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Lattice basis reduction – “optimal” algorithms

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Lattice basis reduction – “optimal” algorithms

Analysis:

Theorem. Starting with (u, v) , Gauss algorithm returns (b_1, b_2) st.

- 1 $\mathbb{Z}u + \mathbb{Z}v = \mathbb{Z}b_1 + \mathbb{Z}b_2$,
- 2 $\|b_1\| = \lambda_1(L)$, $\|b_2\| = \lambda_2(L)$
- 3 $\|b_2^*\| \geq \sqrt{3}/2 \|b_1^*\|$
- 4 in time $O(\max(\|u\|, \|v\|)^2)$.

Proof (sketch).

- $\|u \pm v\|^2 \geq \|v\|^2 \Rightarrow |(u, v)| \leq \|u\|^2/2$.
- If $\|\alpha u + \beta v\|^2 < \|u\|^2$, we get

$$(\alpha^2 - |\alpha\beta| - 1)\|u\|^2 + \beta^2\|v\|^2 < 0$$

hence $(\alpha - \beta)^2 + |\alpha\beta| - 1 < 0$.

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Complexity of Gauss' algorithm (sketch):

- Current step $\neq (u', v') \leftarrow (v \pm u, u)$;
- Otherwise, $\|u'\|^2 \leq \|v\|^2/3$
- \Rightarrow logarithmic number of steps
- Cost of one step $O(\log \|v_i\|(\log \|u_i\| \|v_i\| - \log \|u_i\|^2 + 1))$
- Overall cost

$$\sum_i O(\log \|v_i\|(\log \|v_i\| - \log \|u_i\| + 1))$$

A quasi-linear time variant (similar to fast gcd) exist.

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- 1 Start with any (u, v) linearly independent;
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NB. (2) is a worst case profile.

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- (b_1, \dots, b_n) HKZ reduced :
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Remarks:

- Need SVP oracle;
- Recursive definition \Rightarrow Recursive algorithm;
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- $d = 1$ is trivial.

Lattice basis reduction – HKZ reduction

- (b_1, \dots, b_n) HKZ reduced :
 - $\|b_1\| = \lambda_1(L)$;
 - size-reduced;
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- Return product of transformation matrices of step 2, 3, 4.

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Lattice basis reduction – “optimal” algorithms

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Theorem. Starting with (e_1, \dots, e_n) , HKZ algorithm returns (b_1, \dots, b_n) st.

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- 2 $\|b_1\| = \lambda_1(L)$
- 3 $\|b_1\|/\|b_n^*\| = O(n^{(\log n)/4+1/2})$
- 4 in time $2^{O(n)}$.

More generally, (3) implies:

$$\|b_i^*\| \approx \exp(\log^2(n-i+1)/4)\|b_n^*\|.$$

Proof: tedious manipulation of Minkowski's inequalities.

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General strategy :

- Use a “dim k ”-oracle : Gauss ($k = 2$), or HKZ (bounded k , or $k \approx \log n$);
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Lattice basis reduction – blockwise algorithms, history

- LLL (1982) : $k = 2$, Gauss, adaptive ($j =$ smallest useful position);
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Lattice basis reduction – LLL reduction

[LLL82] A basis (b_1, \dots, b_n) is δ -LLL reduced ($\delta < 1$) iff.

- ① (b_1, \dots, b_n) is size-reduced
- ② $\pi_{L_i^\perp}(b_i, b_{i+1})$ is almost Gauss-reduced.

(2) (with (1)) \Leftrightarrow Lovasz' condition

$$\begin{aligned} \delta \|b_i^*\|^2 &\leq \|\pi_{L_{i-1}^\perp}(b_{i+1})\|^2 \\ &= \|b_{i+1}^* + \mu_{(i+1)i} b_i^*\|^2 \\ &= \|b_{i+1}^*\|^2 + \mu_{(i+1)i}^2 \|b_i^*\|^2, \end{aligned}$$

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$$(\delta - 1/4) \|b_i^*\|^2 \leq \|b_{i+1}^*\|^2.$$

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Adaptive, oracle = Gauss.

- ① $j \leftarrow 1$
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- ⑥ Size-reduce the basis.

Actual LLL :

- Reduce \rightarrow one Gauss step, i.e. size-reduce + swap
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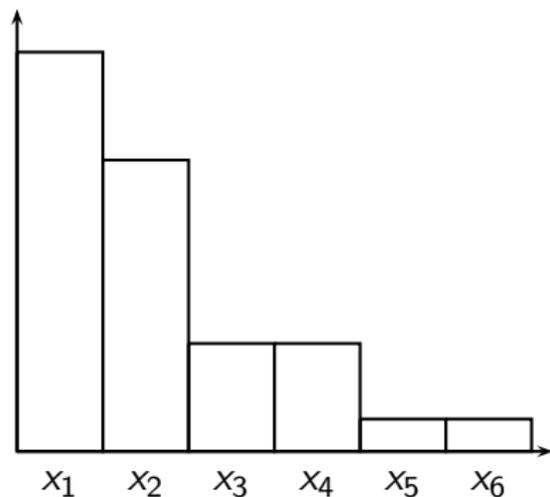
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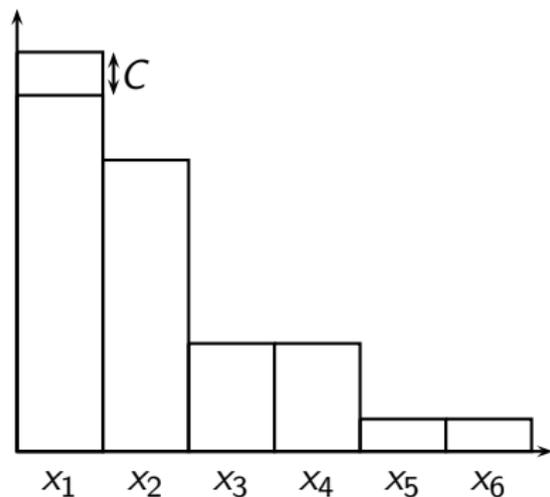
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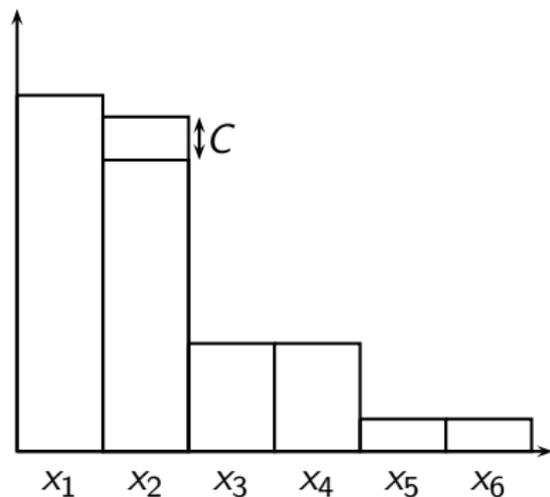
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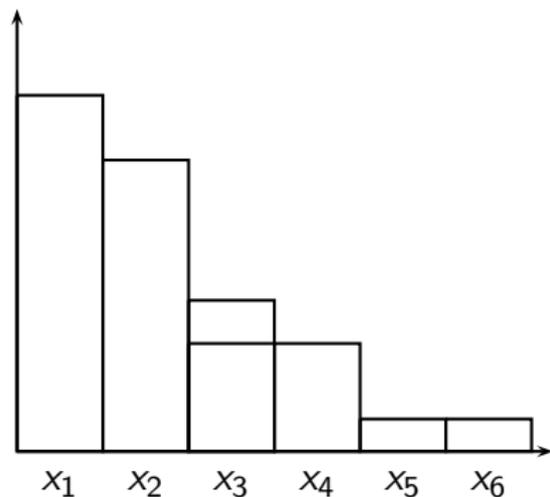
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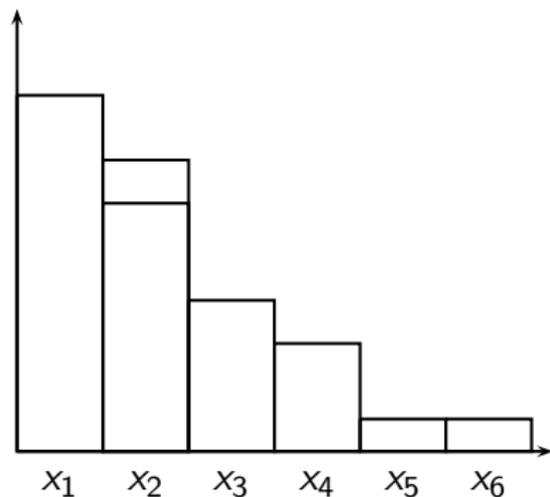
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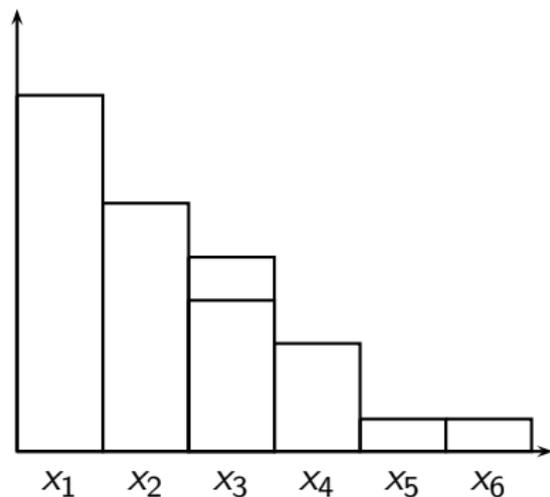
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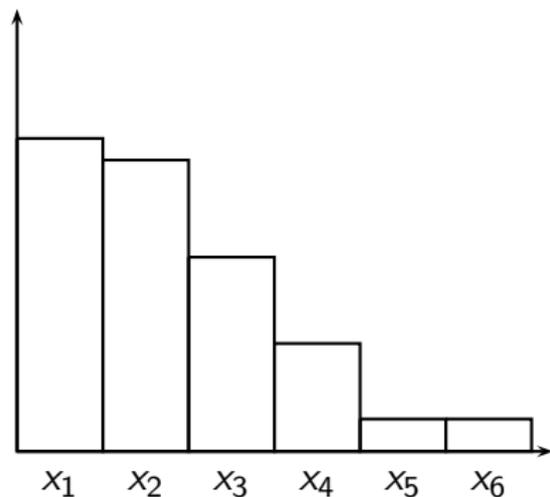
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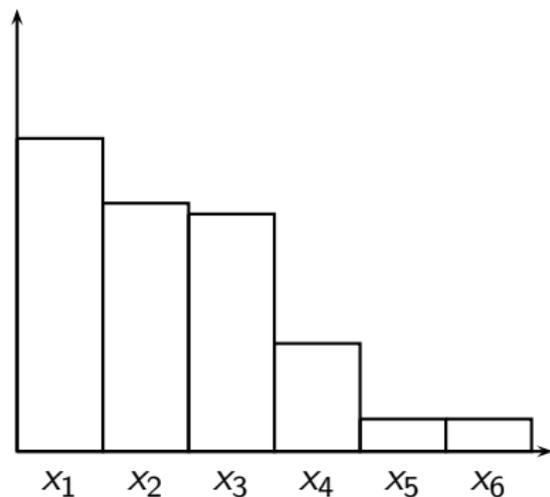
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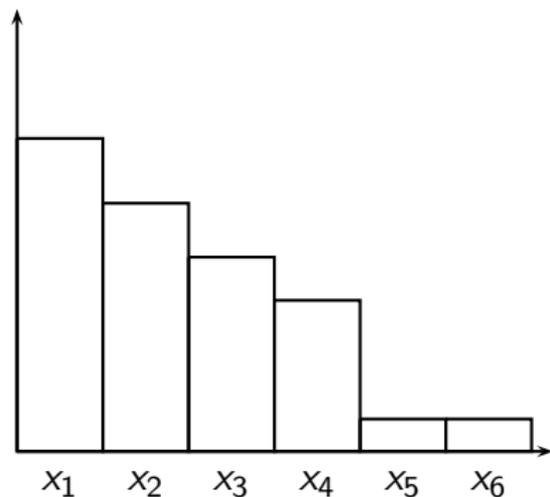
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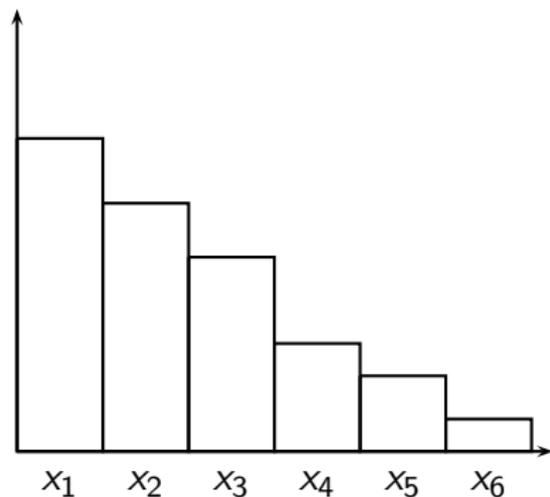
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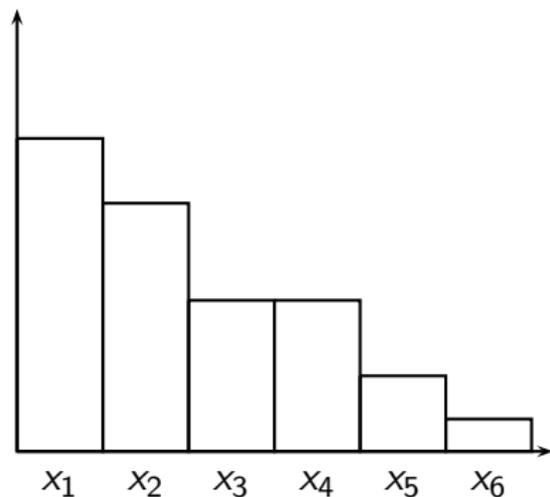
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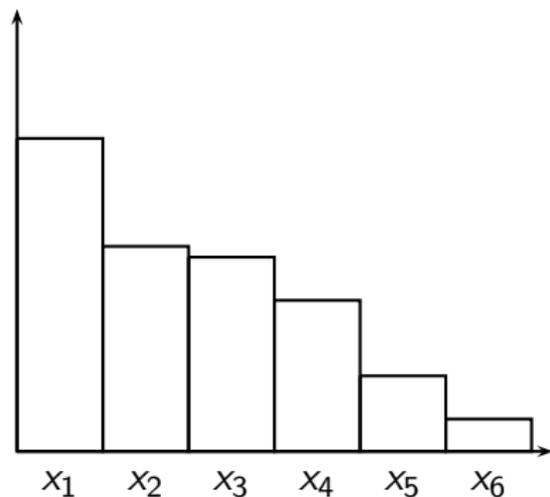
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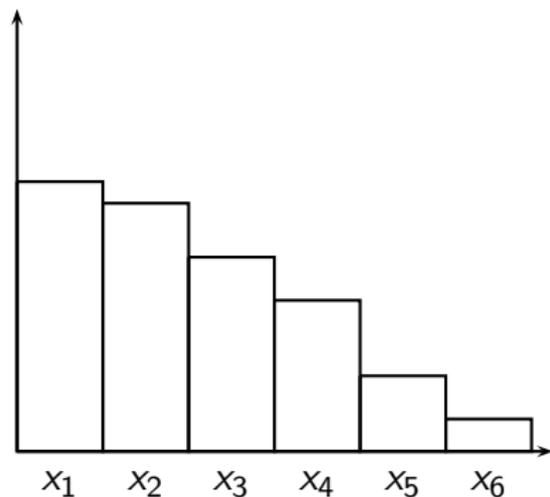
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Lattice basis reduction – LLL theorem

Theorem. On input $E = (e_1, \dots, e_n)$ of size β , the δ -LLL algorithm computes a δ -LLL reduced basis (b_1, \dots, b_n) in time $O(n^2\beta)$ steps of cost $O(n^4(\beta + \log n)^2)$ such that

- $\|b_i^*\| \geq \sqrt{\delta - 1/4} \|b_{i-1}^*\|,$
- (approx-SVP) $\|b_1\| \leq (\delta - 1/4)^{(n-1)/2} \lambda_1(L),$
- (Hermite factor) $HF \leq (\delta - 1/4)^{(n-1)/4}.$

\Rightarrow Can solve gap-SVP with gap $2^{O(n)}.$

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\Rightarrow Can solve gap-SVP with gap $2^{O(n)}.$

Lattice basis reduction – LLL theorem

Theorem. On input $E = (e_1, \dots, e_n)$ of size β , the δ -LLL algorithm computes a δ -LLL reduced basis (b_1, \dots, b_n) in time $O(n^2\beta)$ steps of cost $O(n^4(\beta + \log n)^2)$ such that

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 - First one follows by algorithm;
 - 2. : $\lambda_1(L) \geq \min_{1 \leq i \leq n} \|b_i^*\|$;
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Cost : $O(n^3)$ steps; cost of one step – close to GSO cost?

- Rational arithmetic \Rightarrow control denominators;
- $b_i^* = b_i + \sum_{j<i} y_j b_j$.
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Lattice basis reduction – LLL, recent progresses

- Floating-point GSO;
- Quasi-linear LLL.

Lattice basis reduction – LLL, recent results

Floating-point GSO :

- GSO expensive (big rational / integer computations);
- Need little information ($\lfloor \mu_{ij} \rfloor$);
- Use approximation / floating-point computations;
- ... but numerically unstable.
- Recompute GSO when instability is detected;
- Use a precise fpa model.

Theorem (Nguyen-Stehlé). LLL can be done with fpa in precision $O(d)$, giving a cost $O(d^4 \beta(d + \beta))$.

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Lattice basis reduction – LLL, recent results

Quasi-linear LLL :

- Novocin-Stehlé-Villard, inspired of fast gcd – might be practical;
- H.-Pujol-Stehlé, using BKZ analysis and fast Gauss' algorithm;
- Schnorr, choosing best index j for LLL at each step + fast Gauss.

Theorem (Novocin-Stehlé-Villard). almost-LLL can be done in time $\tilde{O}(n^5\beta + n^{\omega+1}\beta)$.

Lattice basis reduction – LLL in practice

- (old) Folklore: LLL performs better than analysis;
- Often finds first minimum.

Thorough experimental studies by Nguyen and Stehlé (2007).

- In small dimensions ≤ 20 , it works more or less;
- Otherwise, SVP approx factor $\approx (1.04)^n$.
- Analysis is sharp.

Lattice basis reduction – BKZ

(b_1, \dots, b_n) is k -BKZ reduced if:

- (b_1, \dots, b_n) size-reduced;
- For all i , $\pi_{L_i^\perp}(b_i, \dots, b_{\min(n, i+k-1)})$ is HKZ-reduced.

Use a k -HKZ oracle.

Theorem(Schnorr, 1994) If (b_1, \dots, b_n) is k -BKZ reduced, then

- $\|b_i\| \leq k^{\frac{n-1}{k-1}} \frac{i+3}{4} \lambda_i(L)$.
- $\|b_i^*\| \leq k^{\frac{n-1}{k-1}} \lambda_i(L)$.
- $HF \leq \sqrt{k^{\frac{n}{k-1}}}$.

Proof. Combine Minkowski inequalities over projected sublattices.

Lattice basis reduction – BKZ, algorithmic aspects

Strategies :

- LLL-like: HKZ-reduce at the smallest possible i ;
- Schnorr-Euchner: reduce at $1, 2, 3, \dots, n-k+1, 1, 2, 3, \dots$

Cost :

- LLL-type arguments do not seem to work;
- hard to control a potential when reduction occurs;
- Does the LLL strategy even terminate?
- Schnorr-Euchner behaves well in practice, can prove $2^{O(n)}$ bound.

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Lattice basis reduction – BKZ, algorithmic aspects

A dual strategy :

- Stop after a polynomial number of steps;
- ... but what is the quality of the basis?

Theorem. After $\mathcal{O}\left(\frac{n^3}{k^2}(\log n + \log \log \beta)\right)$ calls to HKZ_k , BKZ_k returns a basis (b_1, \dots, b_n) of L such that:

$$\|b_1\| \leq 2k^{\frac{n-1}{2(k-1)} + \frac{3}{2}} (\det L)^{1/n}$$

Lattice basis reduction – BKZ, algorithmic aspects

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- Stop after a polynomial number of steps;
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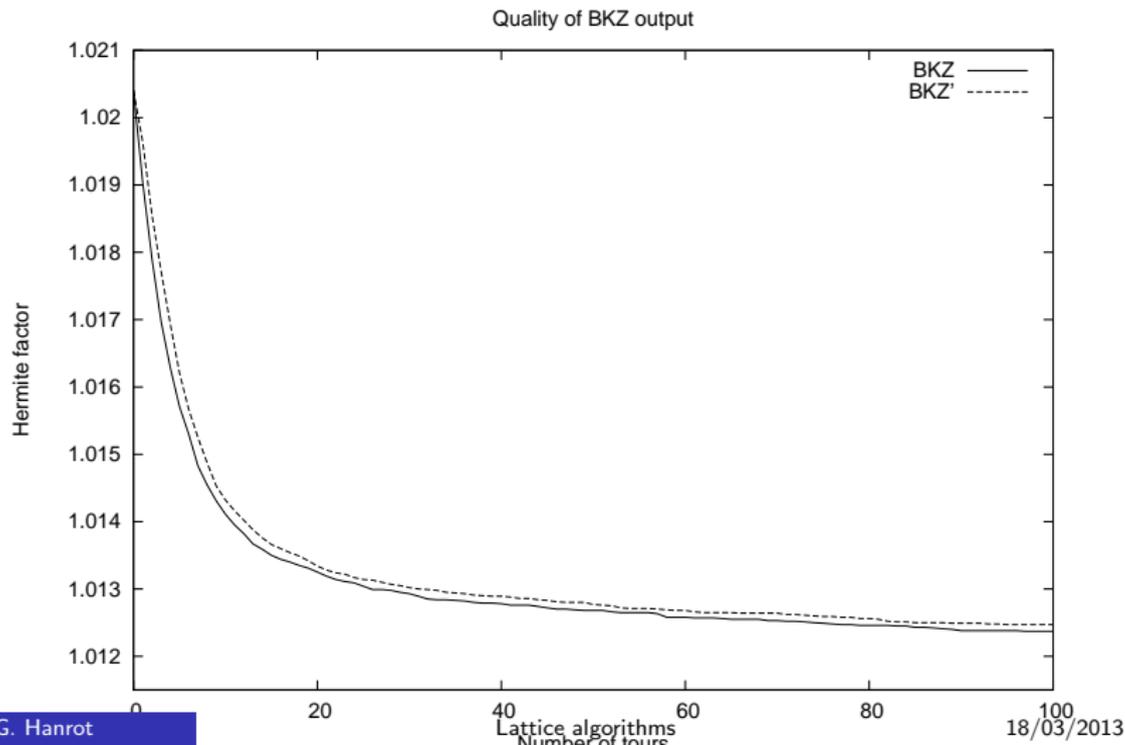
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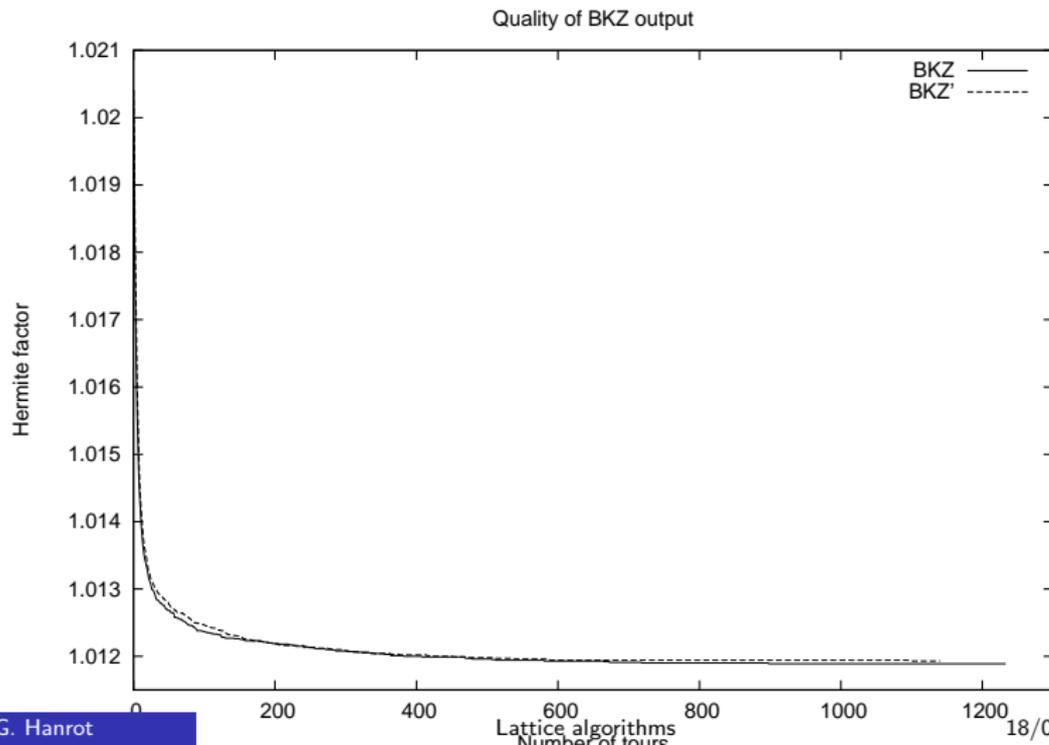
Lattice basis reduction – BKZ, a picture

Progress made during the execution of BKZ



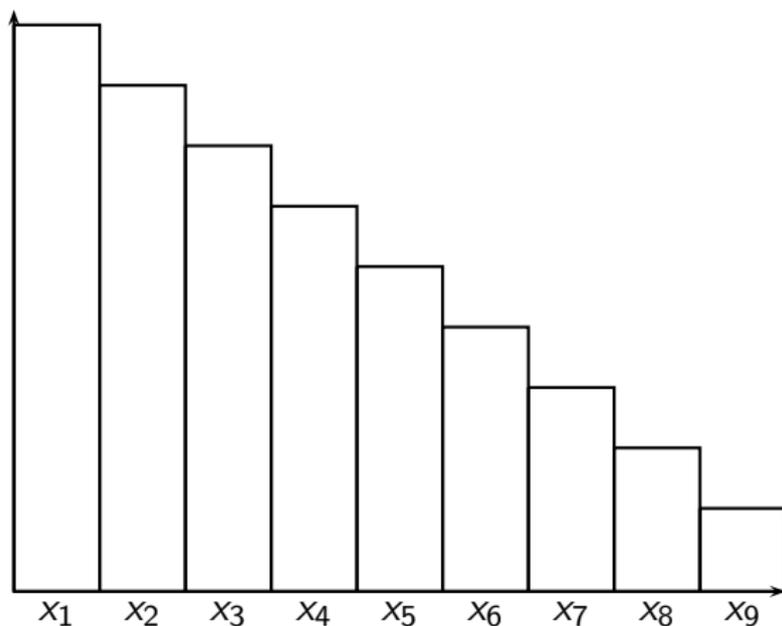
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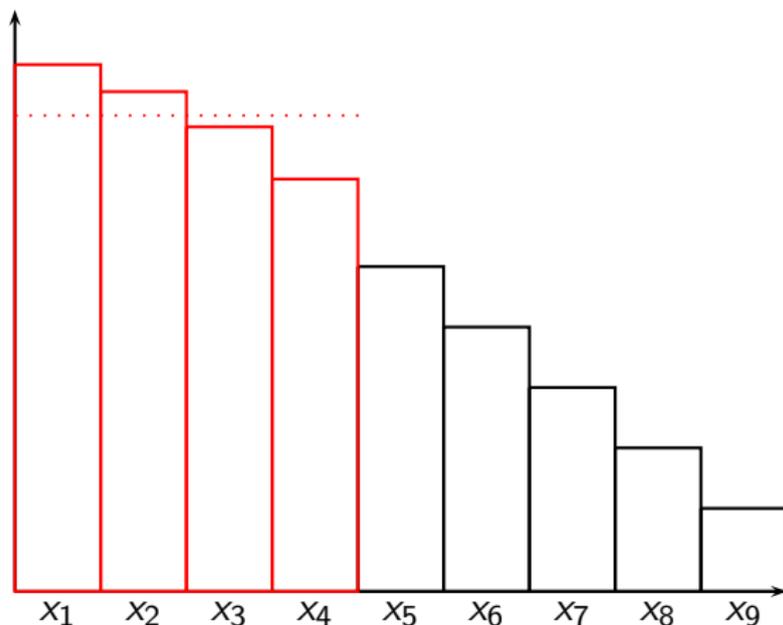
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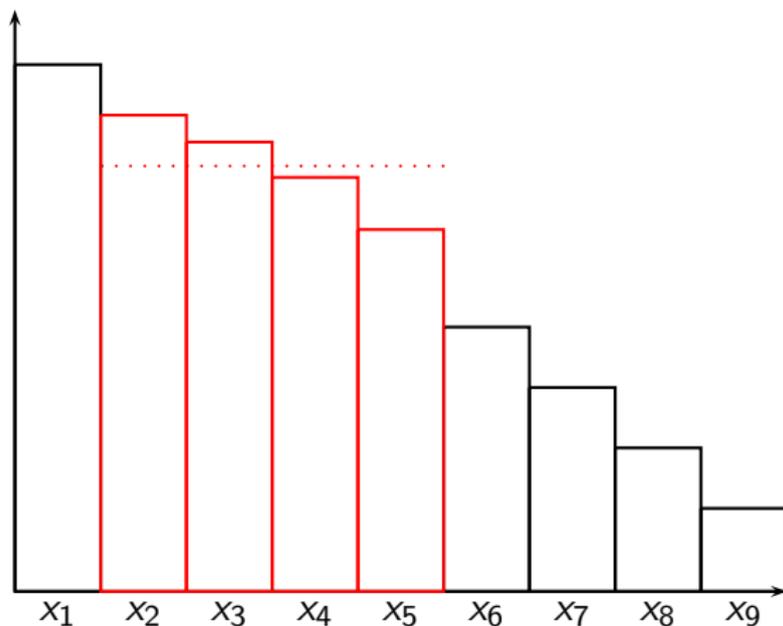
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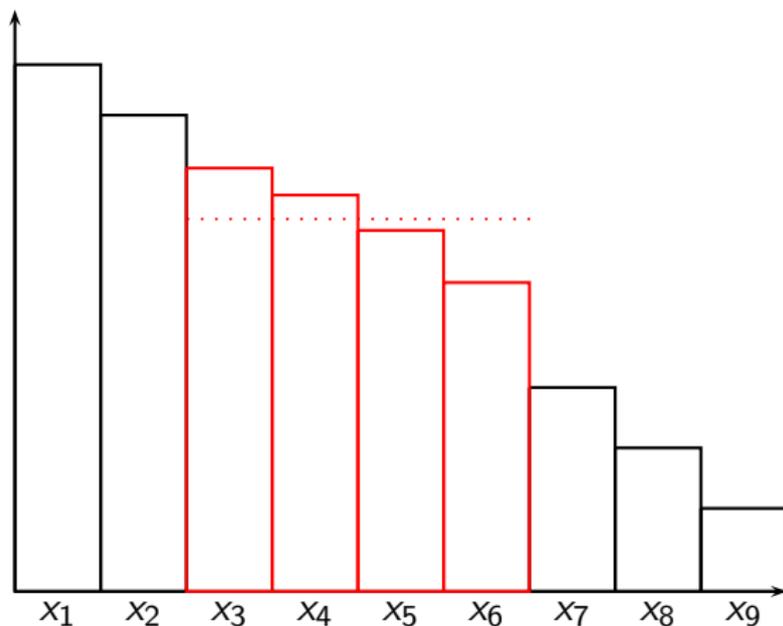
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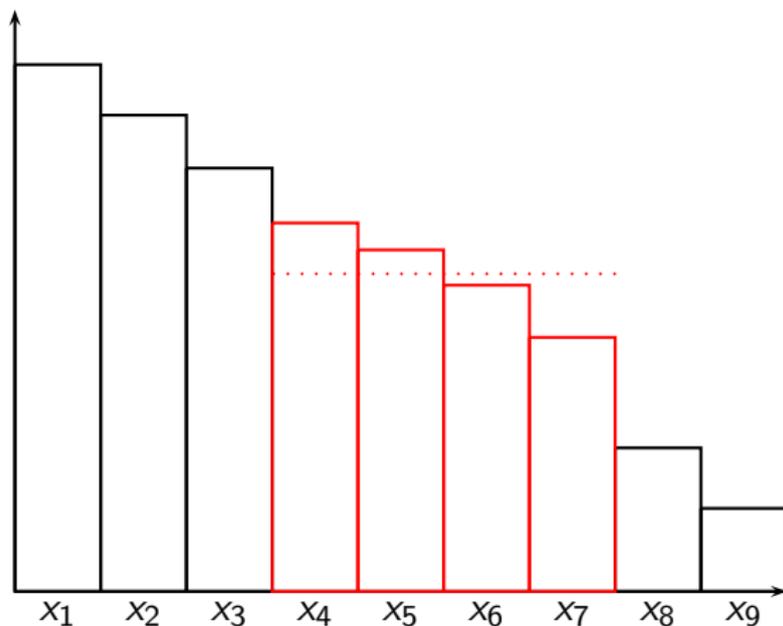
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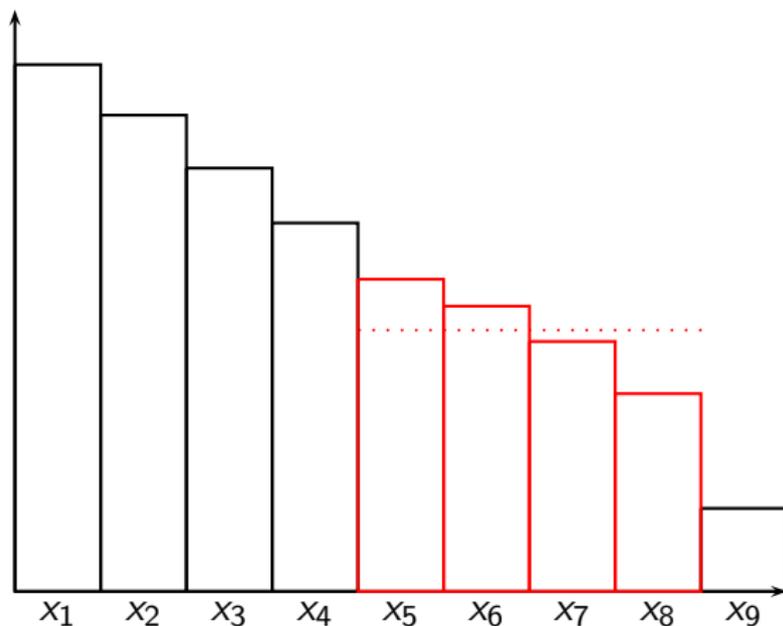
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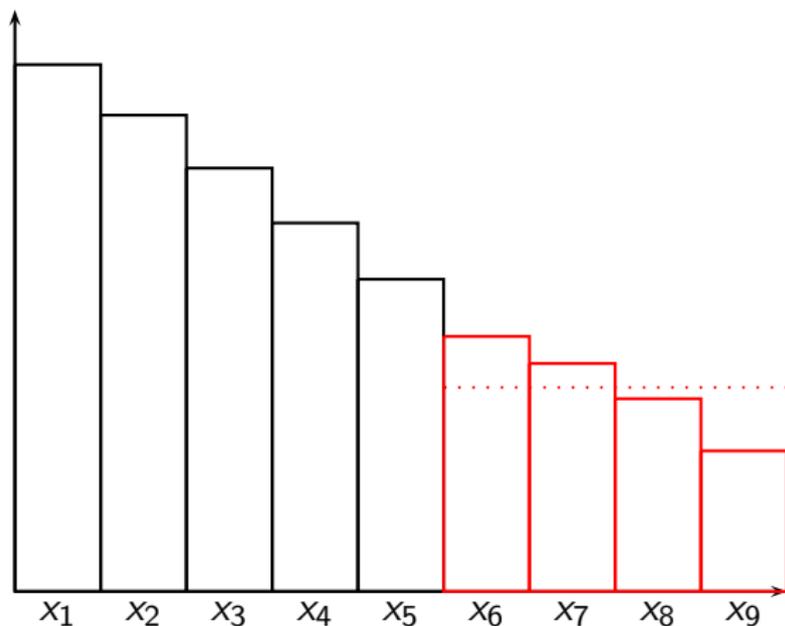
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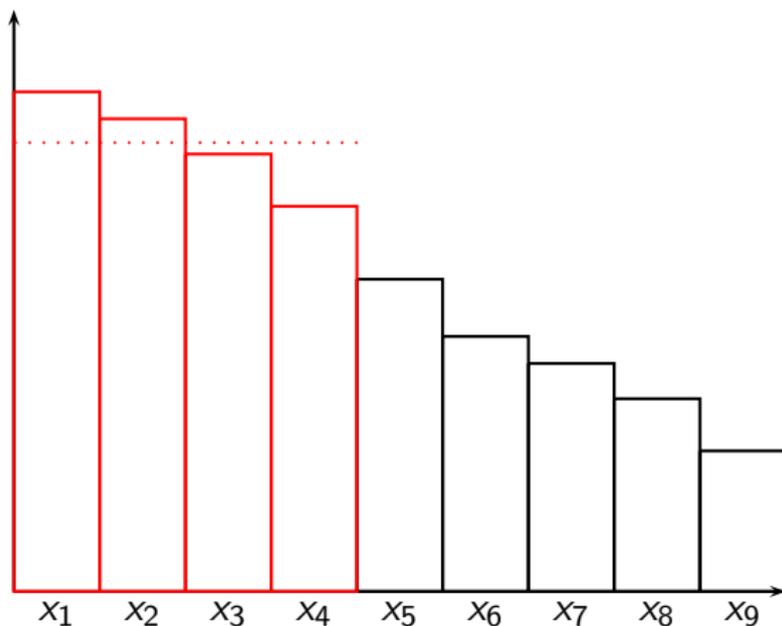
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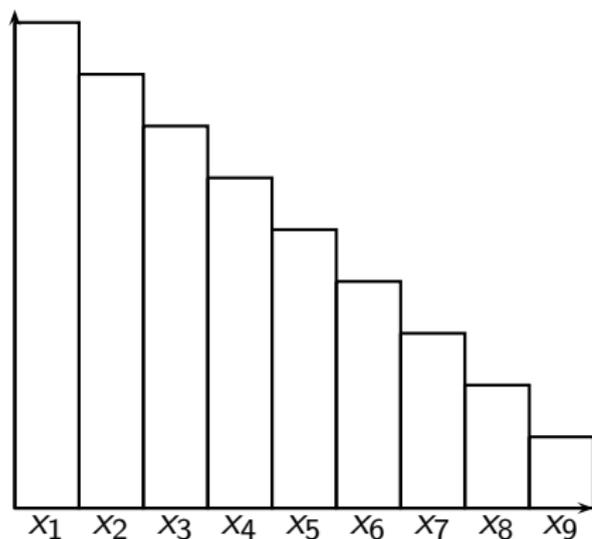
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BKZ_k's sandpile as a dynamic system

$$X = (x_1, \dots, x_n)^T$$

$$X_{0.5} \leftarrow A_1 X$$

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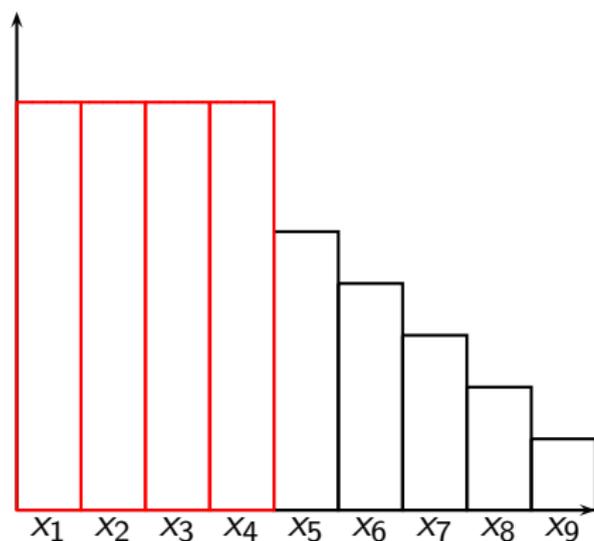
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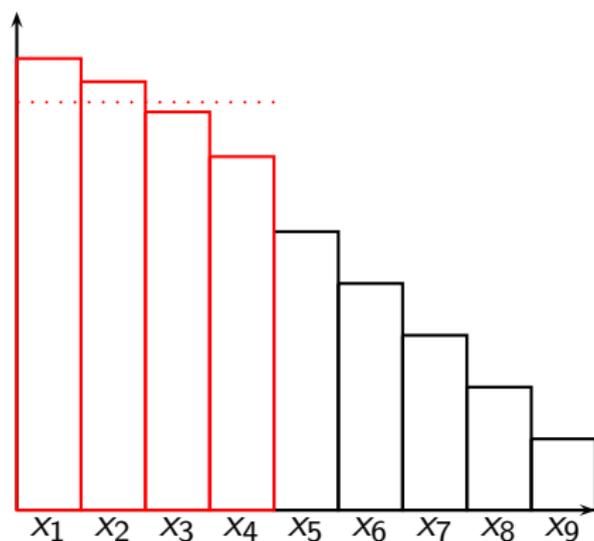
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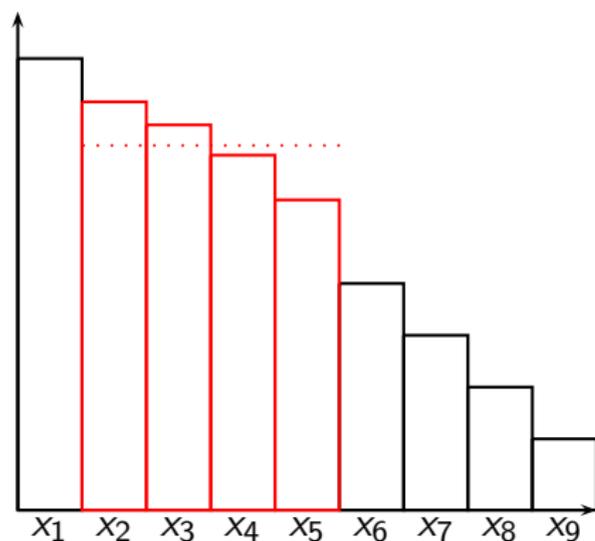
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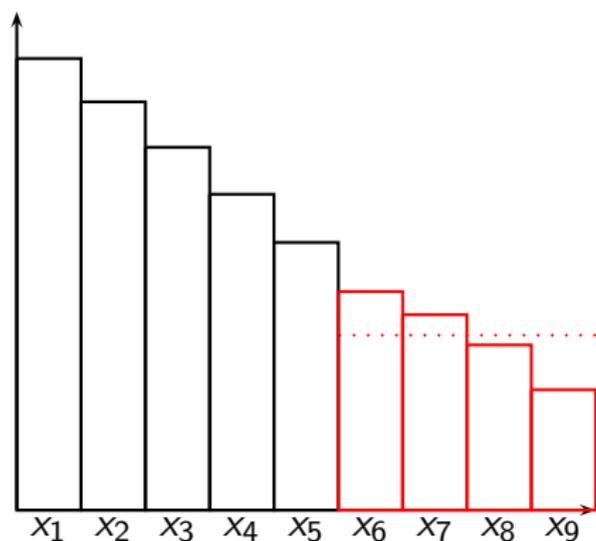
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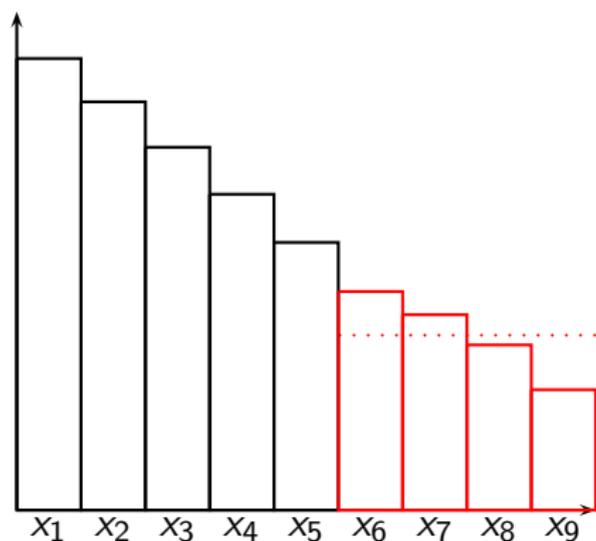
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- Reducedness of the output \Rightarrow fixed points.
- Speed of convergence \Rightarrow eigenvalues of $A^T A$.

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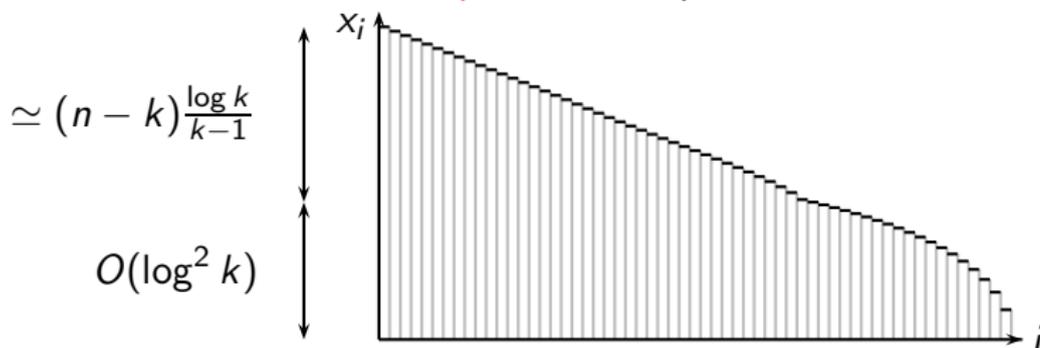
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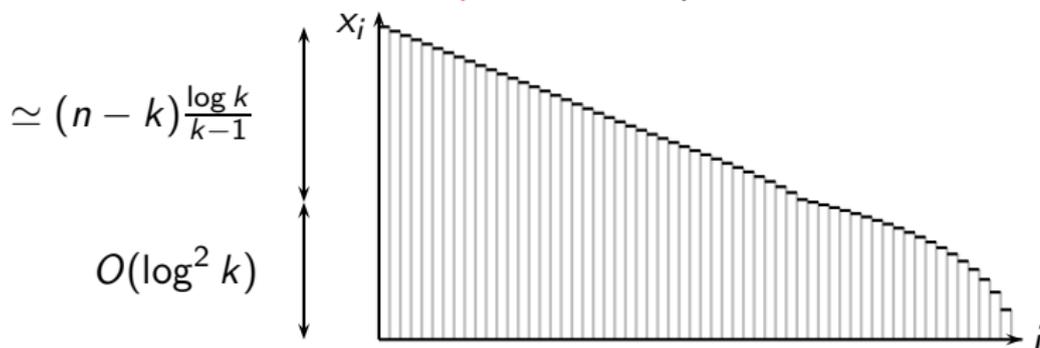


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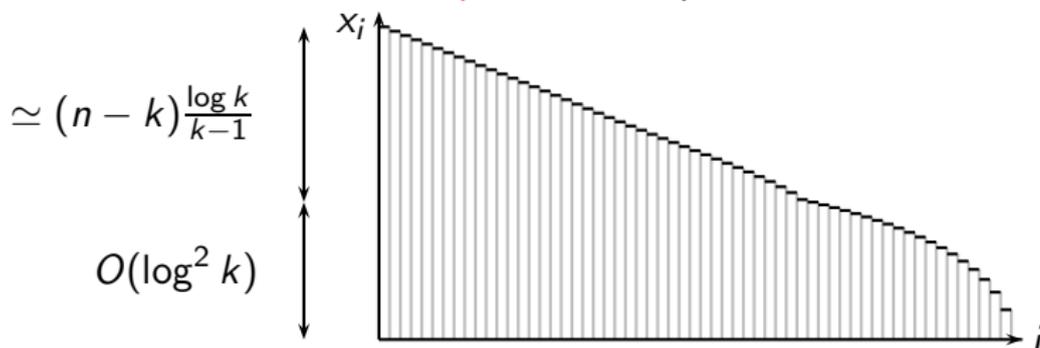
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Lattice basis reduction – Polynomial LLL

$b_1, \dots, b_n \in \mathbb{K}[X]^n$, $L = K[X]b_1 \oplus \dots \oplus K[X]b_n$.

- Orthogonality defect = $\sum_{i=1}^n \deg b_i - \deg \det(b_1, \dots, b_n)$;
- OD = 0 \Leftrightarrow up to row permutation max degrees are on the diagonal.
- also known as Popov normal form.

Theorem. There is a polynomial-time algorithm which returns a basis for which OD = 0, and (up to permutation) b_i is the i -th minimum of the lattice.

Lattice basis reduction – Polynomial LLL

Algorithm (see whiteboard).

II. Algorithms for SVP / CVP

II. 1. Approximate algorithms for SVP / CVP

SVP and CVP algorithms – approximate algorithms

$L = L(b_1, \dots, b_n)$, (b_1, \dots, b_n) reduced;

Approx-SVP(b_1, \dots, b_n):

- Return b_1 ;
- Approx factor : LLL = $2^{O(n)}$, k -BKZ $\approx k^{n/k}$;

Approx-CVP(t, b_1, \dots, b_n):

- Babai algorithms;
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Babai roundoff algorithm :

- Compute t_i such that $t = \sum_{i=1}^n t_i b_i$ (, ie. $B^{-1}t$)
- Return $\tilde{t} := \sum_{i=1}^n \lfloor t_i \rfloor b_i$.

Theorem. If (b_1, \dots, b_n) is LLL-reduced, then
 $\|\tilde{t} - t\| = 2^{O(d)} d(t, L)$.

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"Reduce" CVP to SVP by using

$$L' := \begin{pmatrix} B & -t \\ 0 & C \end{pmatrix},$$

for a large constant C .

- LLL-reduce L' , read \tilde{t} on first vector;
- Short vectors in $L' = (u - x_{n+1}t, x_{n+1}C)$, $u \in L$;
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$$L' := \begin{pmatrix} B & -t \\ 0 & C \end{pmatrix},$$

for a large constant C .

- LLL-reduce L' , read \tilde{t} on first vector;
- Short vectors in $L' = (u - x_{n+1}t, x_{n+1}C)$, $u \in L$;
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- Algorithmic interpretation: further than Babai.

Can be better, somewhat less convenient.

SVP and CVP algorithms – Kannan's embedding technique

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II. 2. Exact algorithms for SVP / CVP

SVP and CVP algorithms – outline

- **The KFP enumeration-based algorithm**
 - R. Kannan: Improved algorithms for integer programming and related lattice problems, STOC'83
 - U. Fincke & M. Pohst: A procedure for determining algebraic integers of given norm, EUROCAL'83
- Saturating the space: The AKS solver and its descendants
- Using the Voronoi cell: the Micciancio-Voulgaris algorithm

The Kannan-Fincke-Pohst enumeration algorithm

Given $(\mathbf{b}_i)_{i \leq n}$ and $\mathbf{t} \in \mathbb{R}^n$, we look for all $(x_i)_i \in \mathbb{Z}^n$ s.t.:

$$\left\| \sum_i x_i \mathbf{b}_i - \mathbf{t} \right\|^2 = \sum_i (x_i - t_i + \sum_{j>i} \mu_{j,i} x_j)^2 \|\mathbf{b}_i^*\|^2 \leq A$$

where $\mathbf{t} = \sum_i t_i \mathbf{b}_i^*$ and A is arbitrary.

By **successive projections**:

$$\begin{aligned} (x_n - t_n)^2 \|\mathbf{b}_n^*\|^2 &\leq A \\ (x_{n-1} - t_{n-1} + \mu_{n,n-1} x_n)^2 \|\mathbf{b}_{n-1}^*\|^2 + (x_n - t_n)^2 \|\mathbf{b}_n^*\|^2 &\leq A \\ &\dots \\ \sum_{j \geq i} (x_j - t_j + \sum_{k>j} \mu_{k,j} x_k)^2 \|\mathbf{b}_j^*\|^2 &\leq A \\ &\dots \end{aligned}$$

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- For each value of (x_k, \dots, x_n) , x_{k-1} belongs to a finite set.
- KFP is a **tree traversal**, where one is interested in the leaves.
- Cost analysis reduces to counting lattice points in balls.

Gaussian heuristic

For any “nice” K , we have $|L \cap K| \approx \frac{\text{vol } K}{\det L}$.

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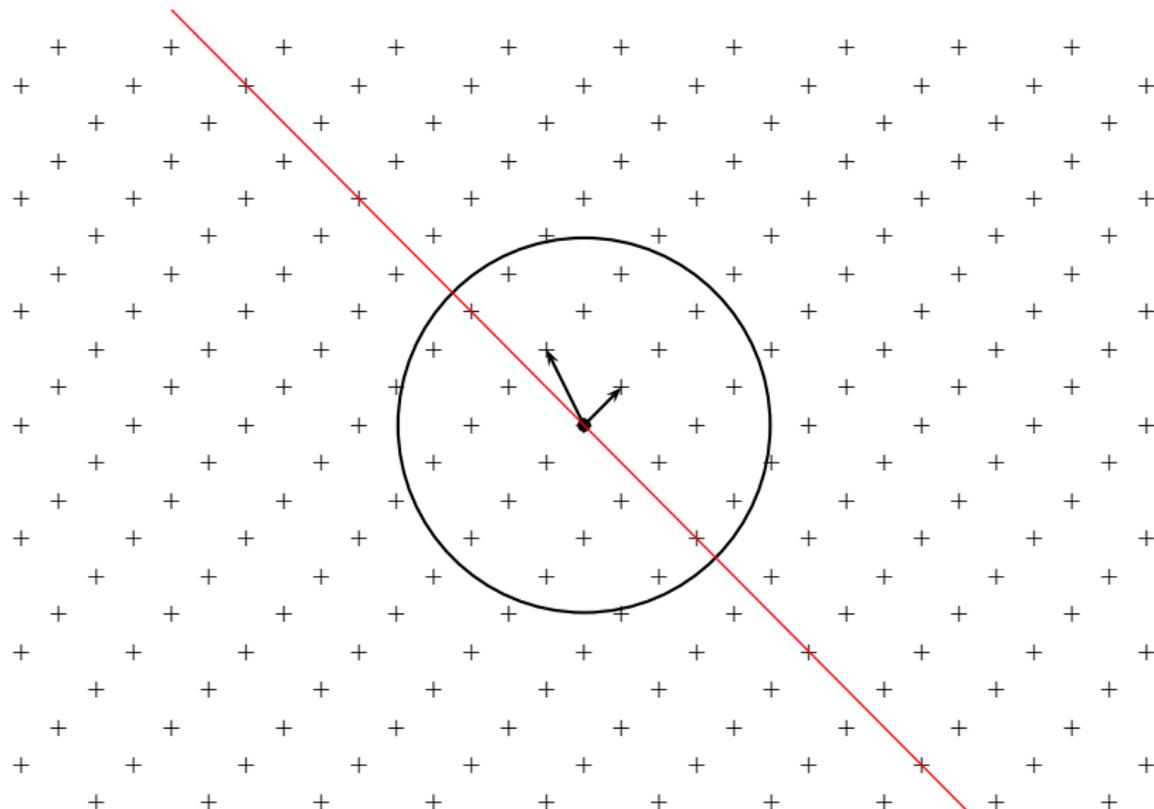
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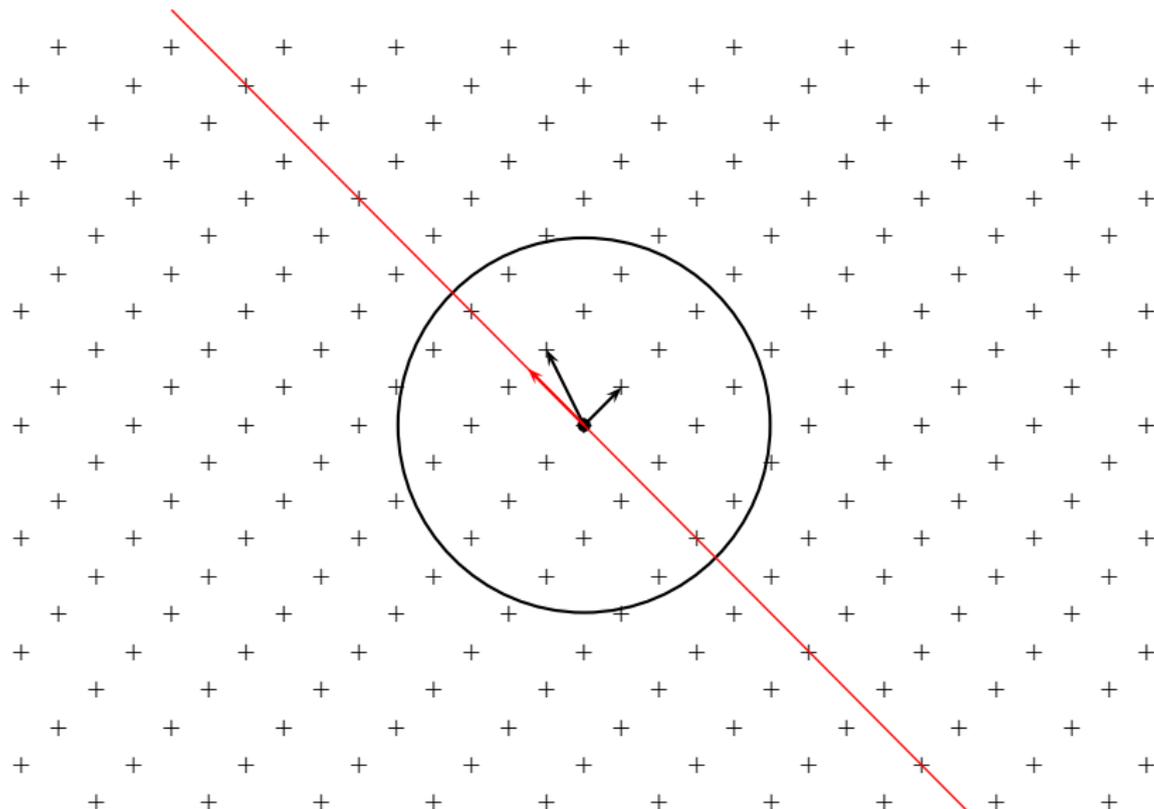
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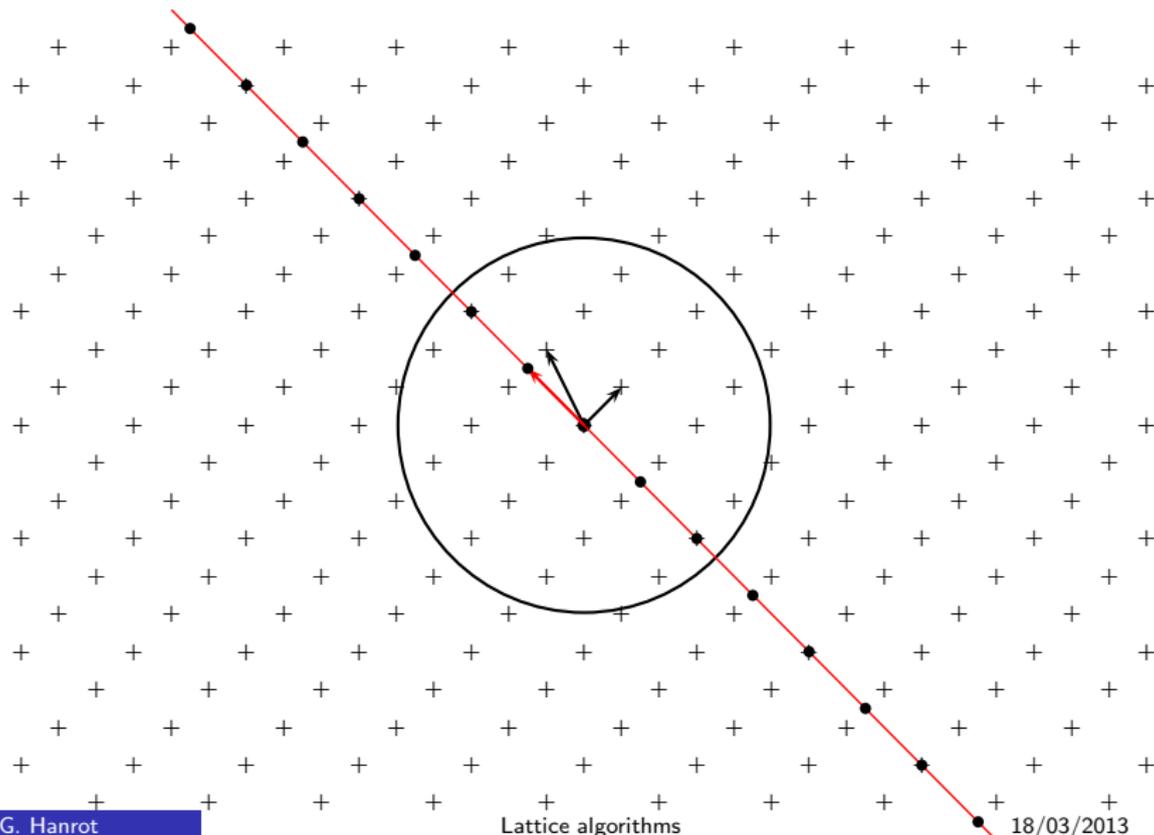
CVP, SVP – the KFP enumeration algorithm



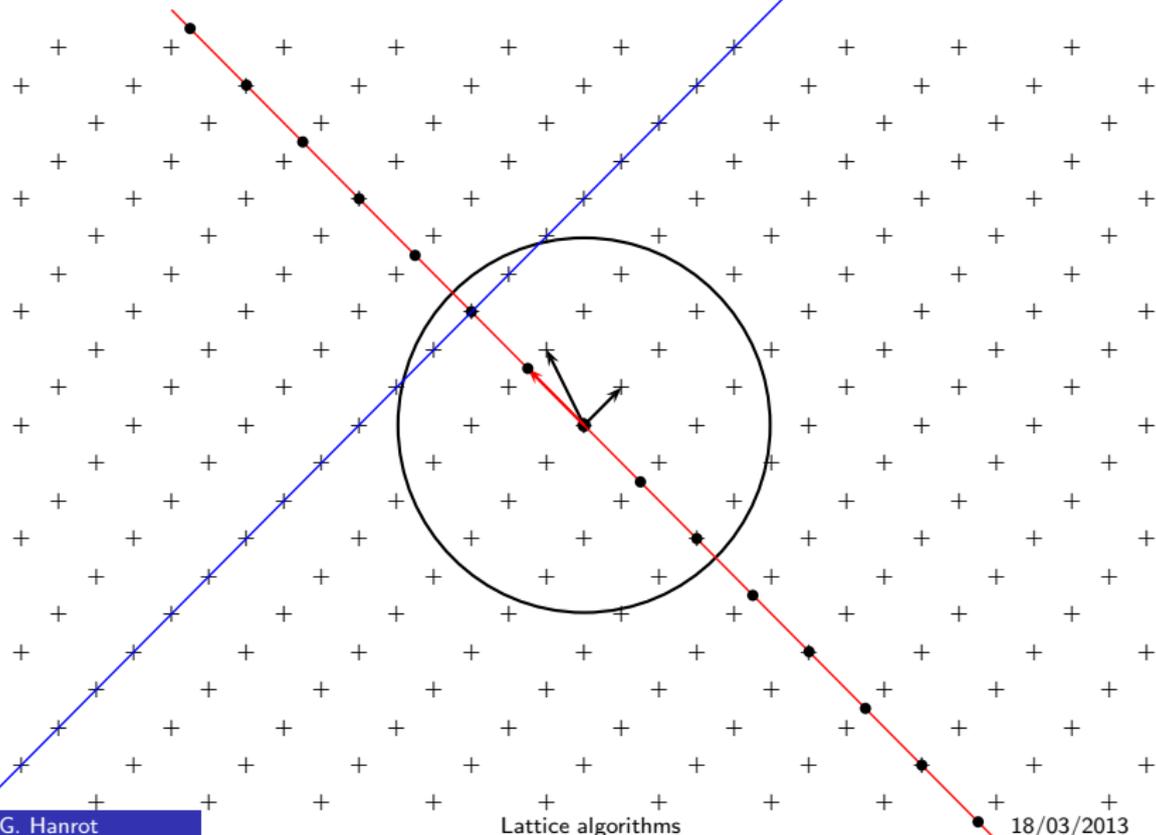
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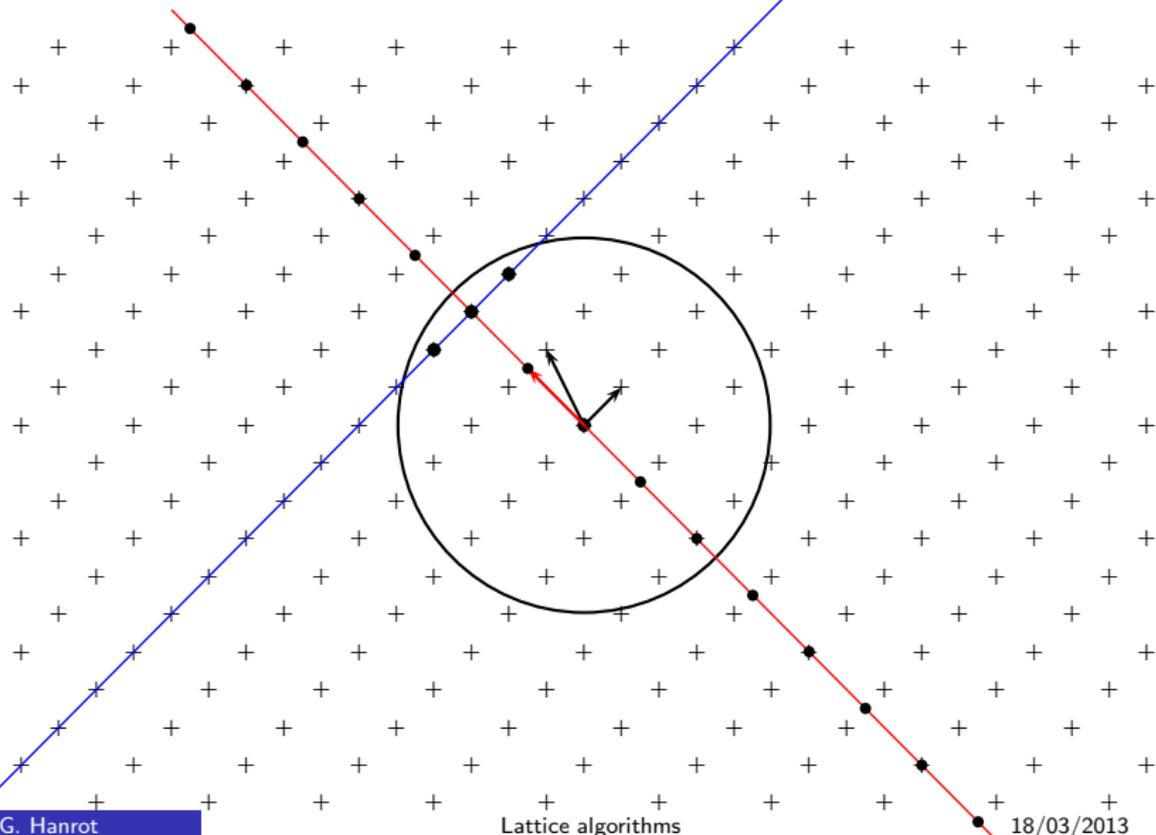
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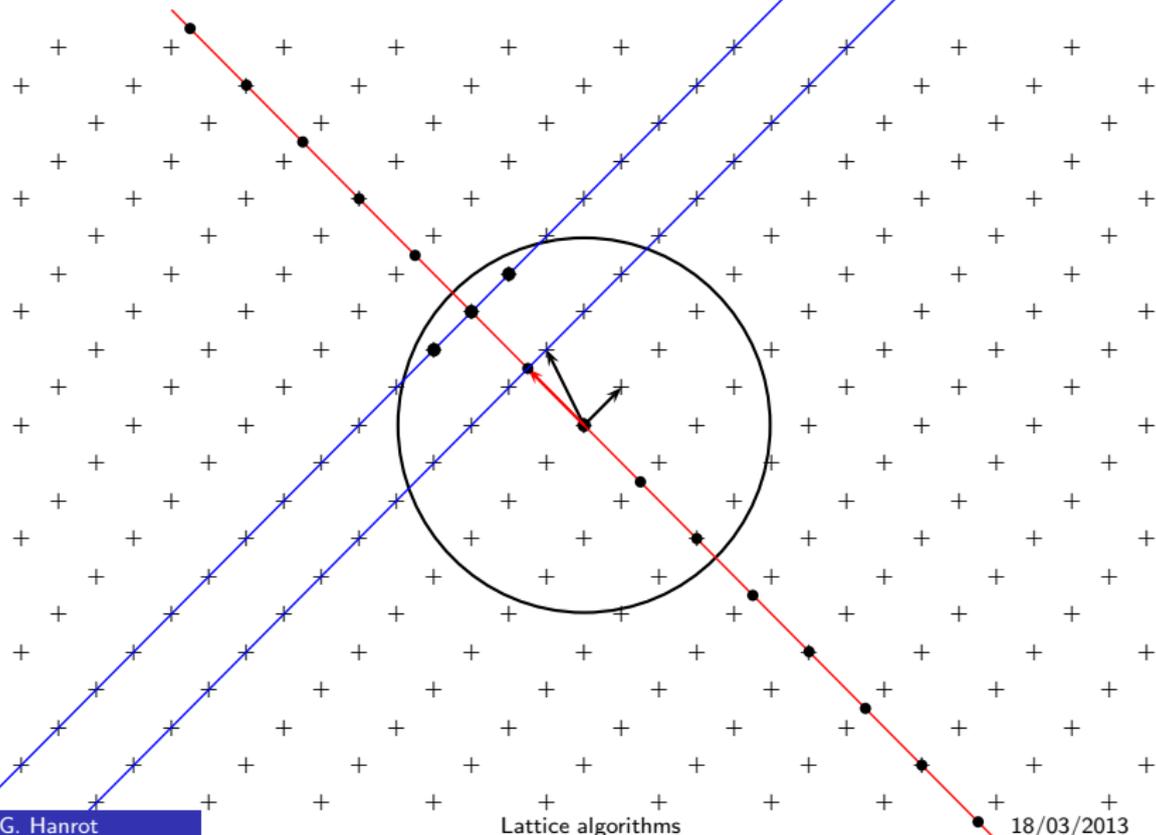
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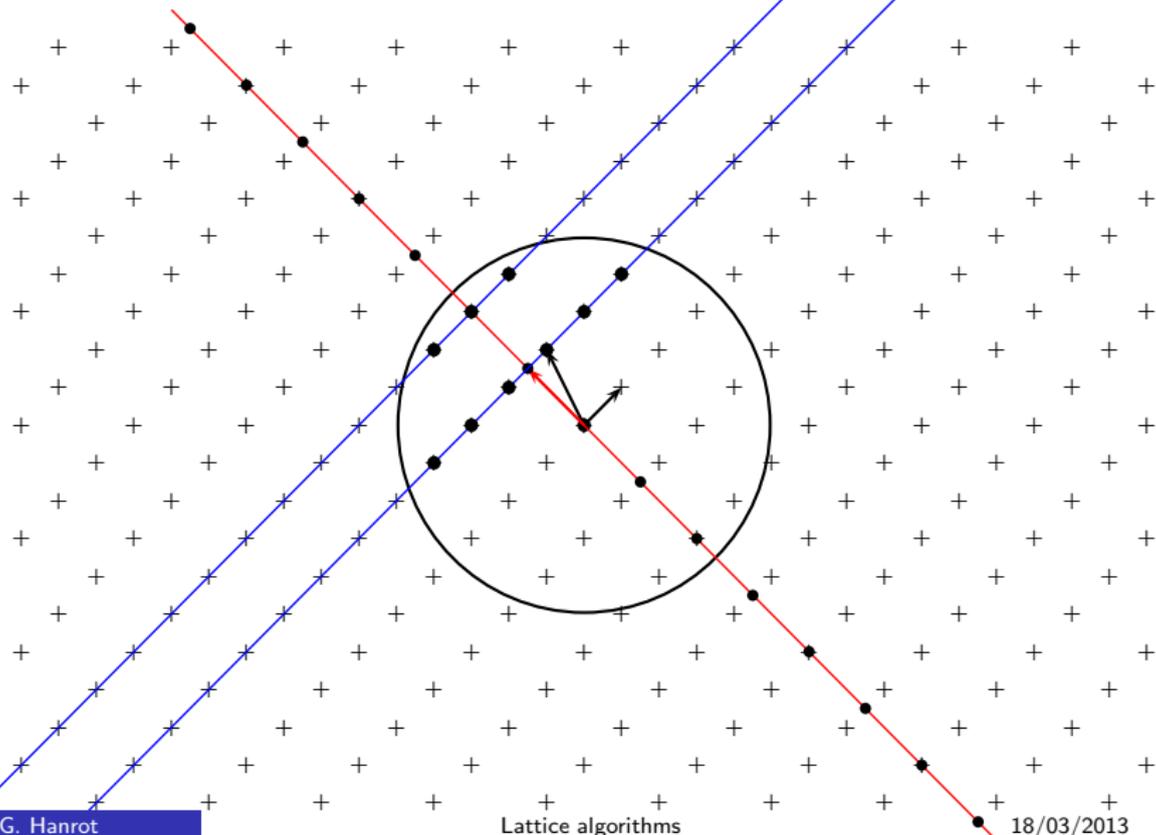
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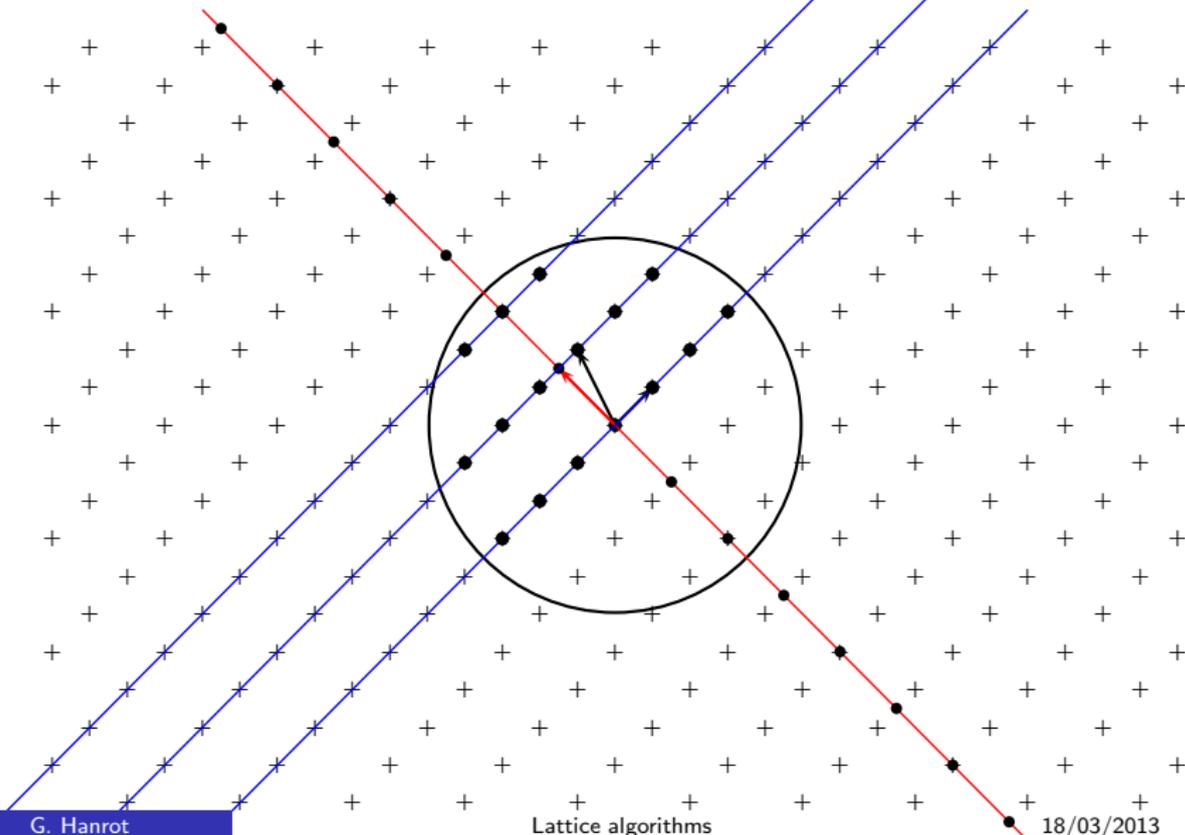
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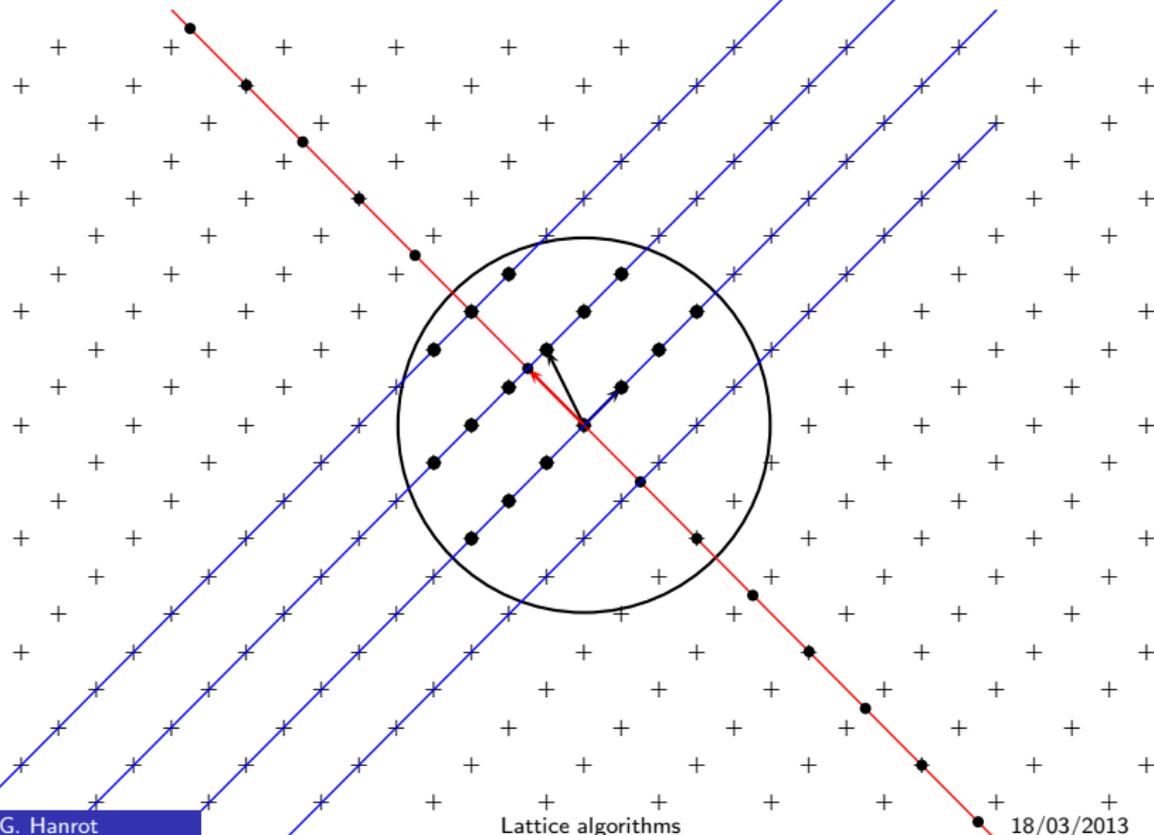
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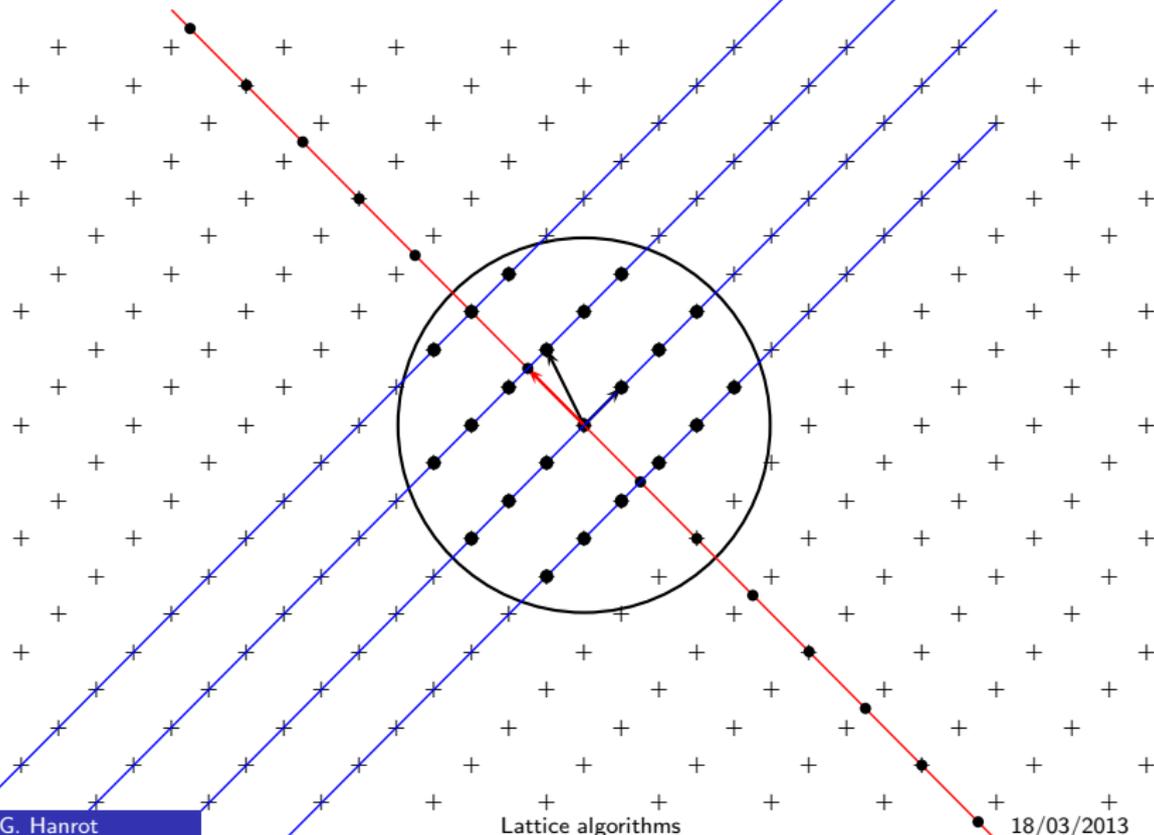
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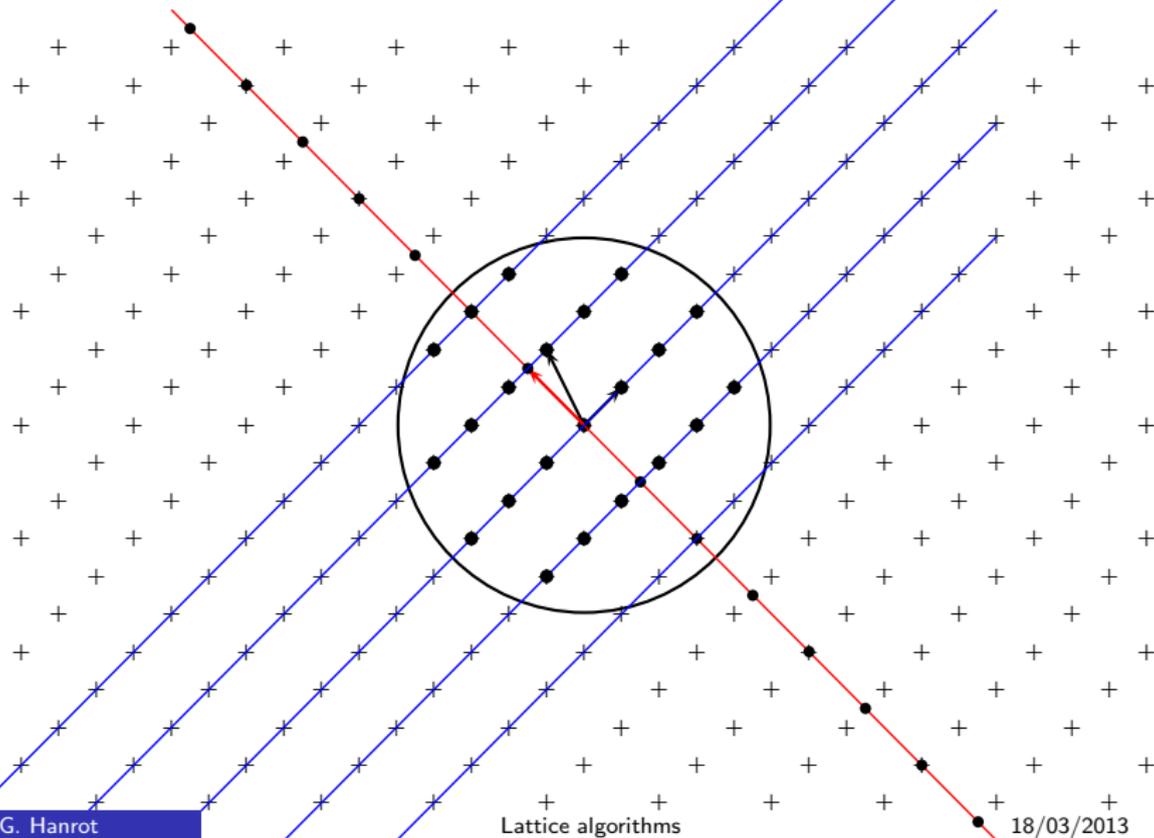
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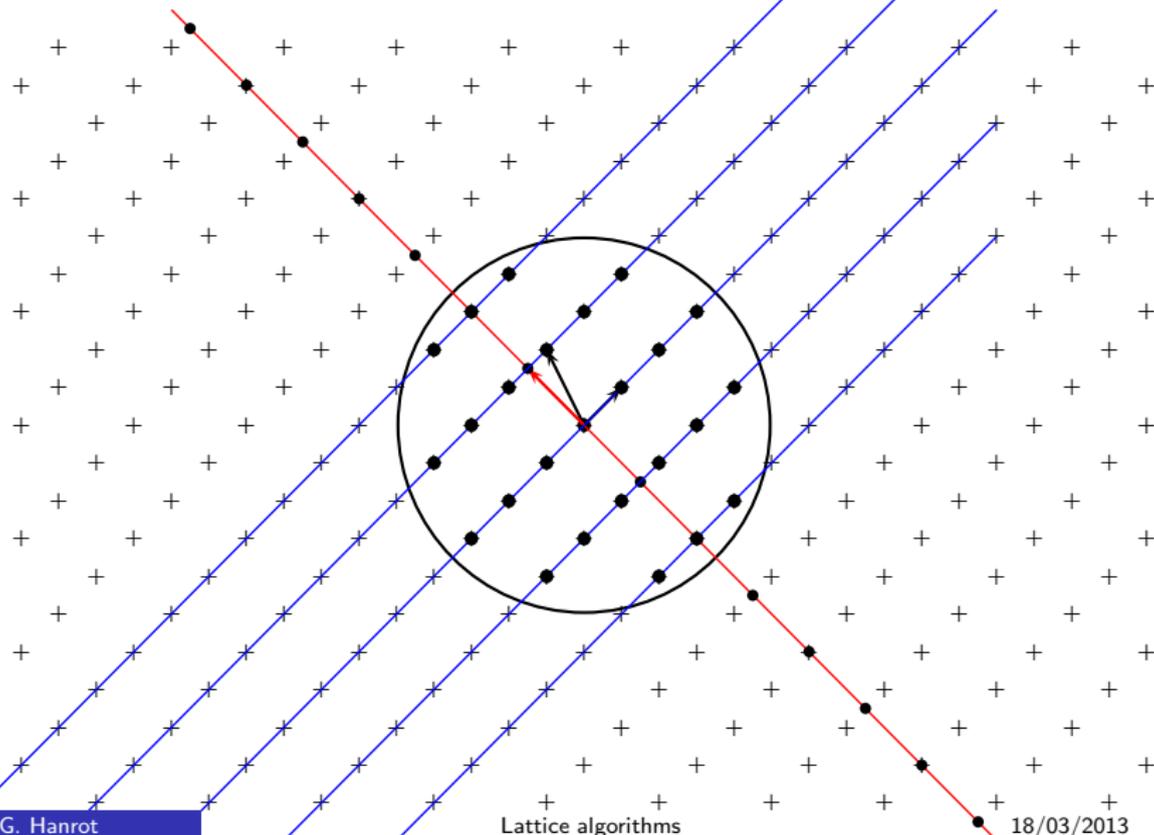
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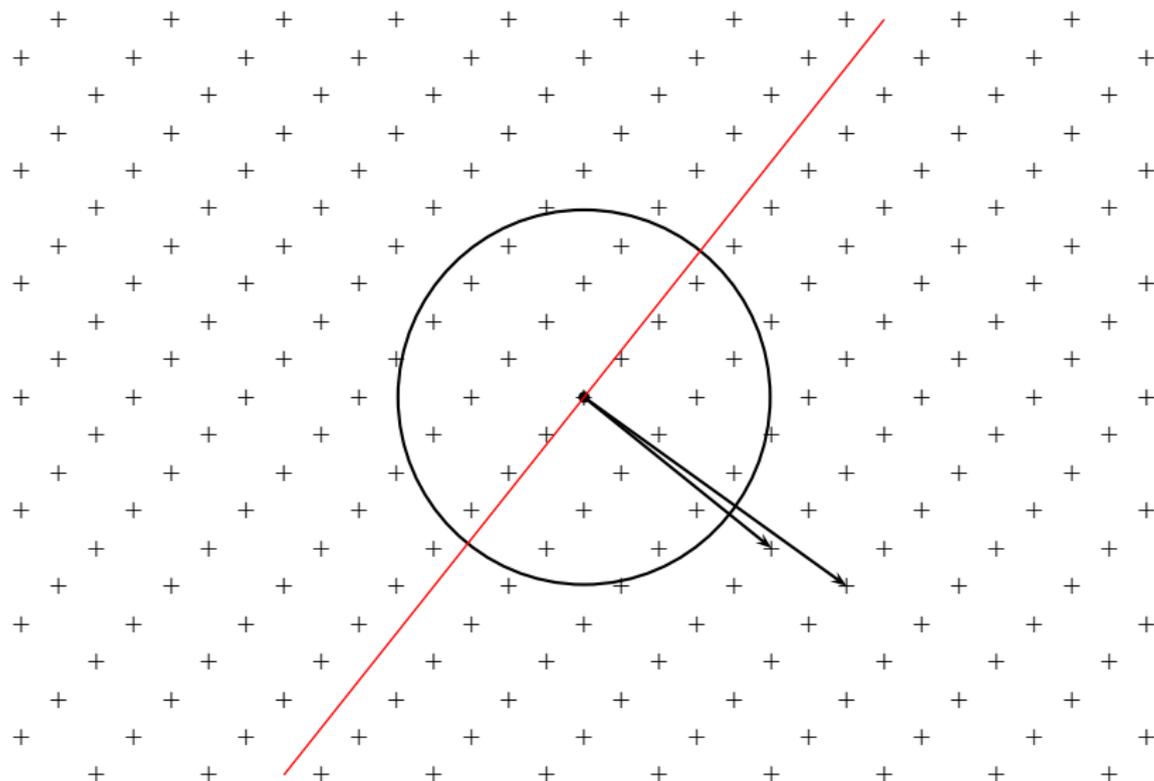
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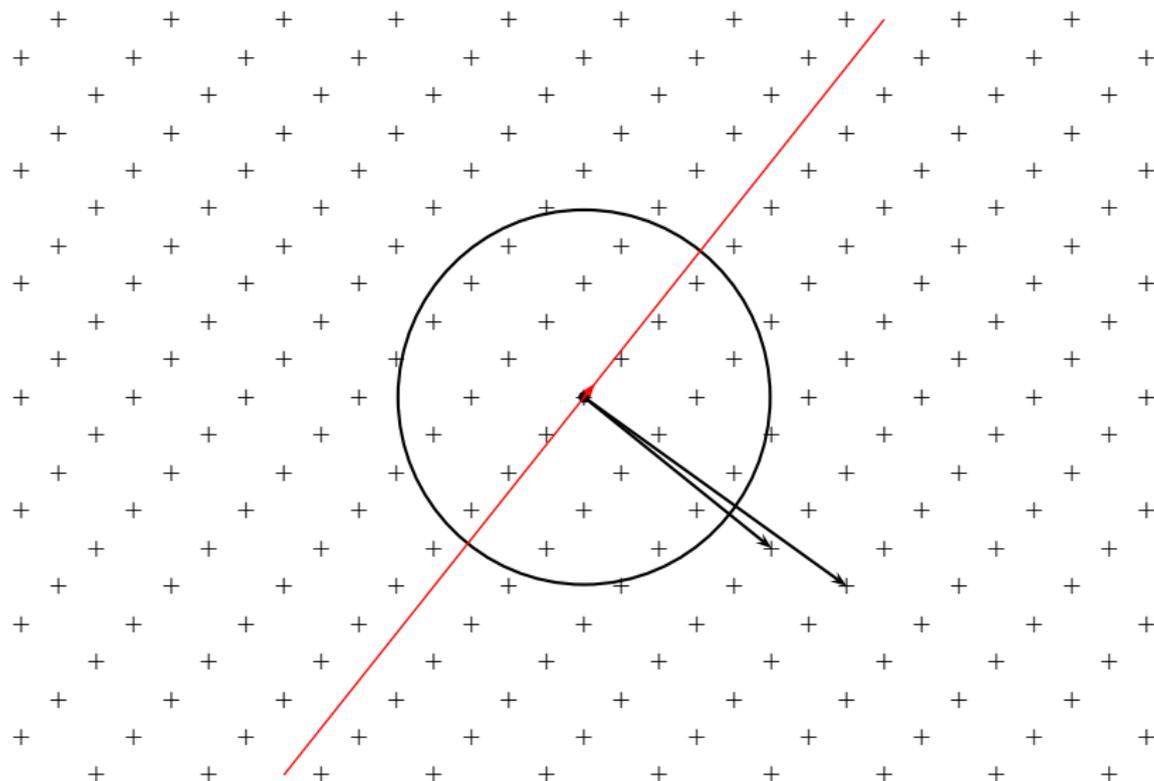
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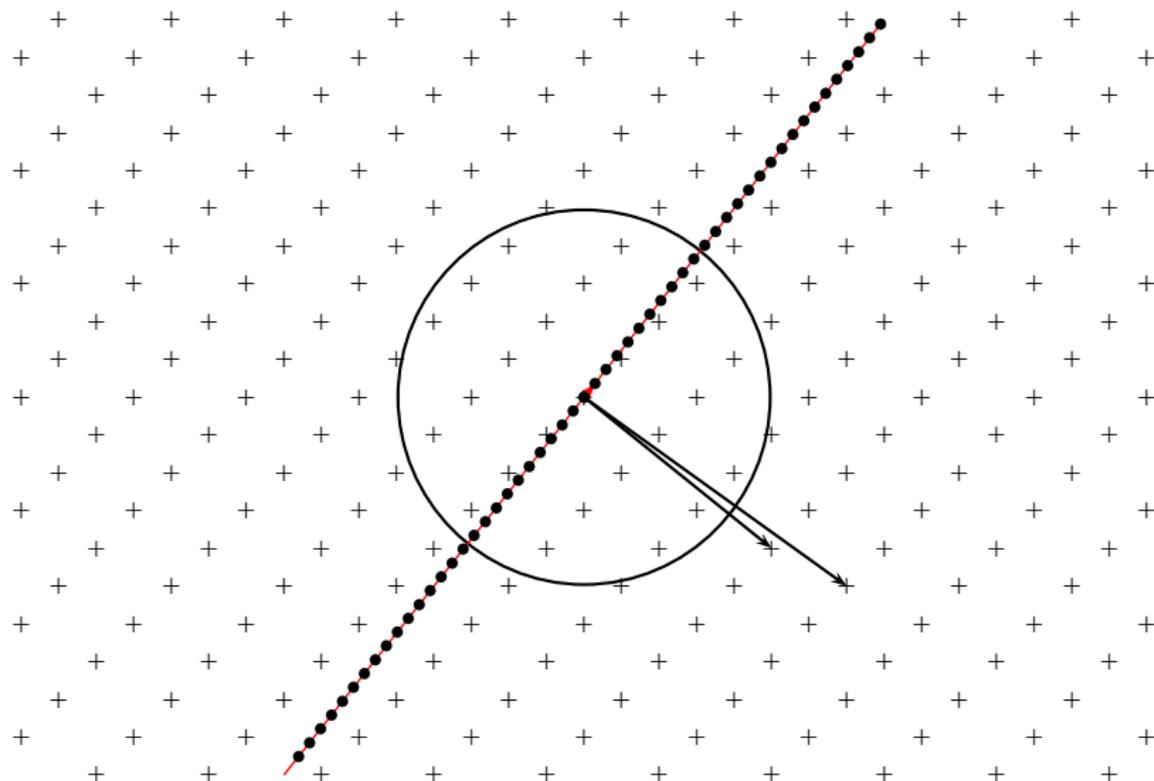
CVP, SVP – The KFP enumeration algorithm (II)



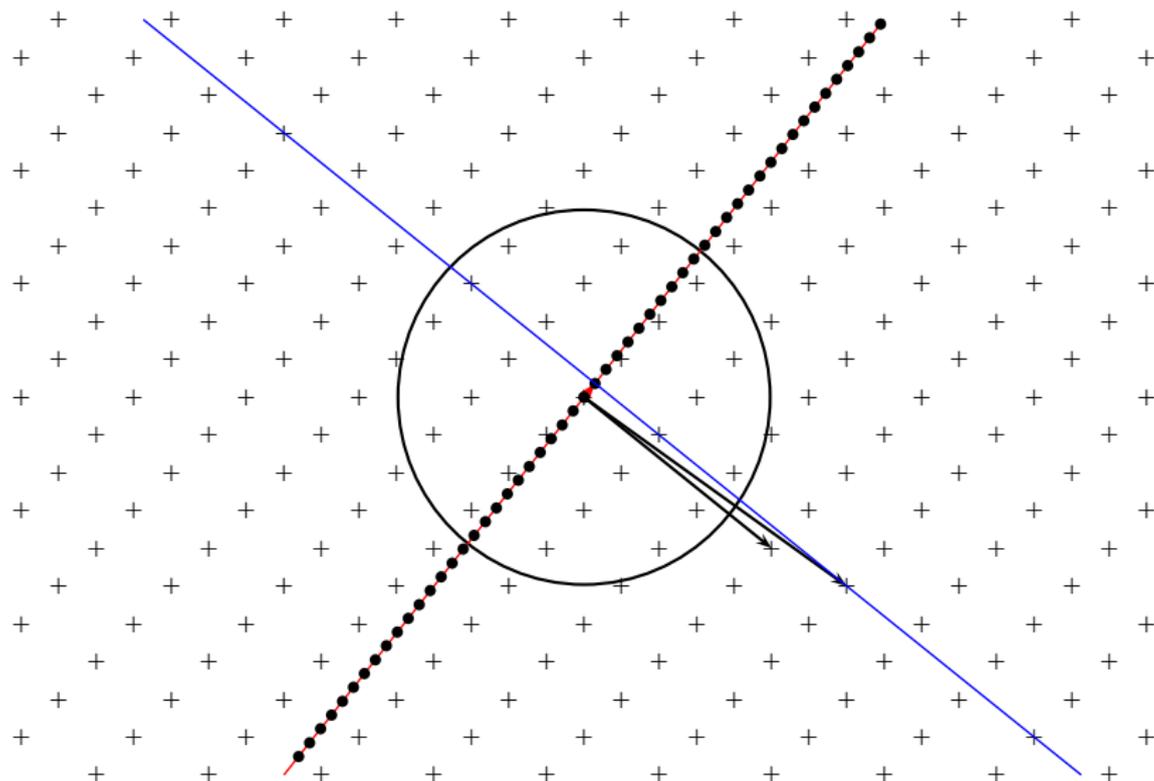
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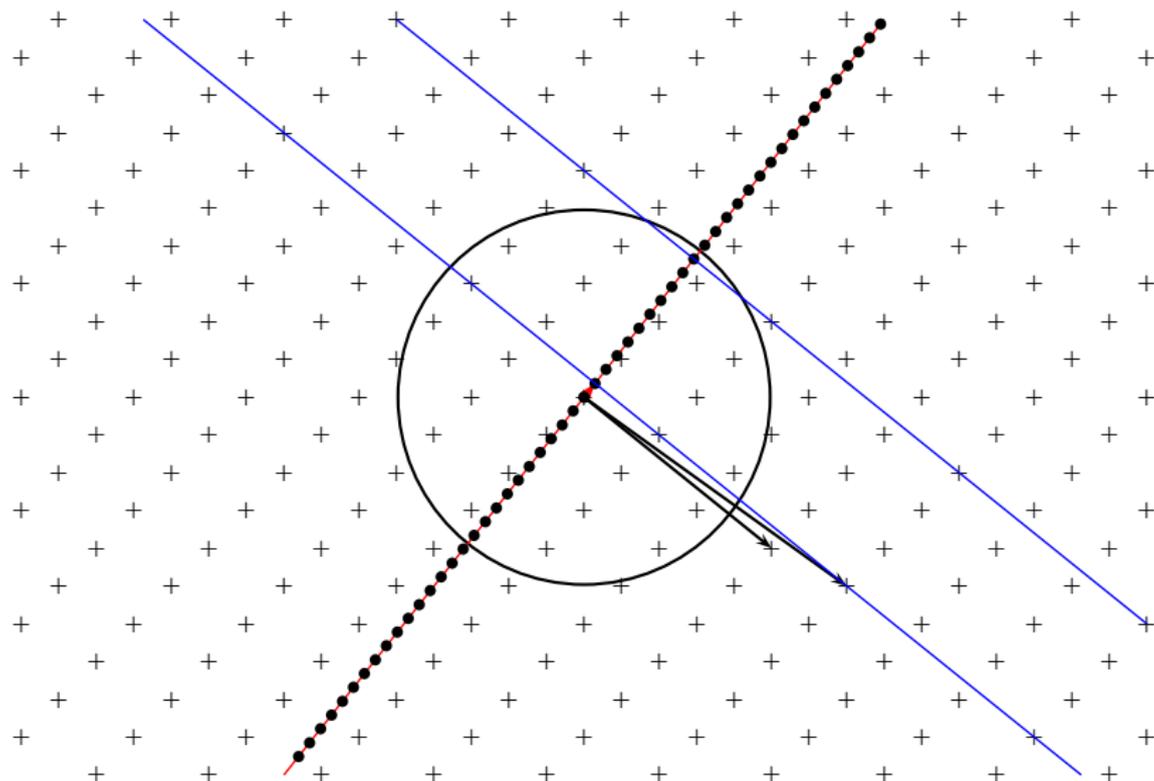
CVP, SVP – The KFP enumeration algorithm (II)



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Kannan's improvement

- The shorter the basis vectors, the faster the enumeration.
 - Kannan pre-processes the basis by performing enumerations in lower dimensions ;
 - quasi-HKZ reduced basis as input to SVP;
- ⇒ Recursive process, using SVP solver in dim $n - 1$.
- Complexity $n^{n/(2e)+o(n)}$ [HaSt07]
(upper and lower worst-case bound).

KFP: the most practical SVP & CVP solver

- Basis is pre-processed before enumeration [Kannan83]
- Computations rely on floating-point arithmetic [PuSt08]
- The tree search can be parallelized [DHPS10]
- The choice of bound A can be optimized
- The tree search can be pruned (heuristic) [ScEu91, GaNgRe10]:

$$\forall i, \sum_{j \geq i} (x_j - t_j + \sum_{k > j} \mu_{k,j} x_k)^2 \| \mathbf{b}_j^* \|^2 \leq p_i \cdot A,$$

where $1 \geq p_1 \geq \dots \geq p_n > 0$.

- Practical limits (a few days on a modern processor)
- No provably guaranteed answer (see [10])
- No heuristic answer (see [10])

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Practical limits (a few days on a modern processor):

- For a guaranteed answer: $n \approx 70$.
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The saturation principle

Kabatyansky & Levenshtein

Let $E \subseteq \mathbb{R}^n \setminus \mathbf{0}$. Assume that for any $\mathbf{u} \neq \mathbf{v}$ in E , the angle between \mathbf{u} and \mathbf{v} is $\geq \phi_0$. Then $|E| \leq 2^{cn+o(n)}$ for some $c(\phi_0)$.

For $\phi_0 = 60^\circ$, we obtain $|E| \leq 2^{0.401 \cdot n}$.

Consequence: If points belong to a ball and their pairwise distances are bounded from below, then their number is $2^{O(n)}$.

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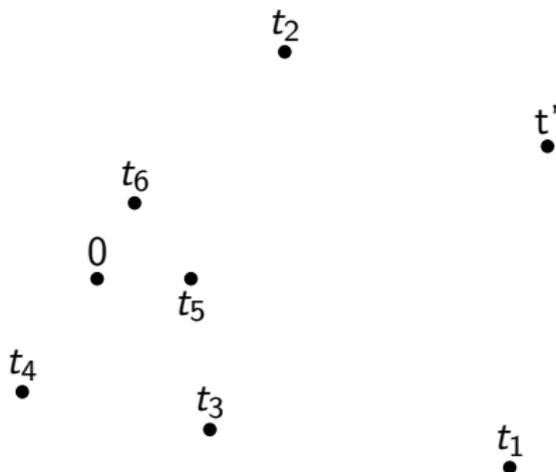
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The ListSieve SVP Algorithm, heuristic version

- 1 Sample $\mathbf{t}_1, \dots, \mathbf{t}_N \in L$.
- 2 For all $i \leq N$, if there is $j < i$ with $\|\mathbf{t}_i - \mathbf{t}_j\| < (1 - \frac{1}{n})\|\mathbf{t}_i\|$, replace \mathbf{t}_i by $\mathbf{t}_i - \mathbf{t}_j$.
- 3 Return a shortest non-zero vector found.

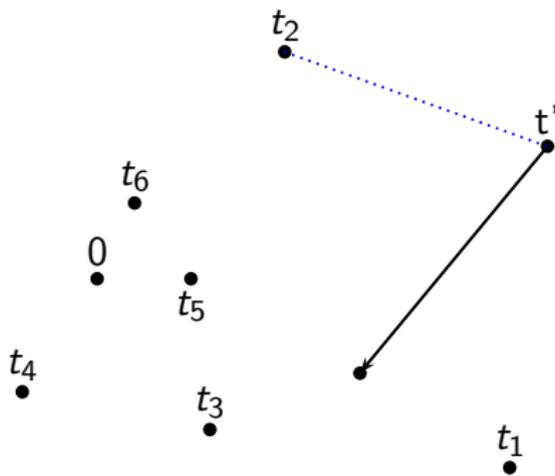
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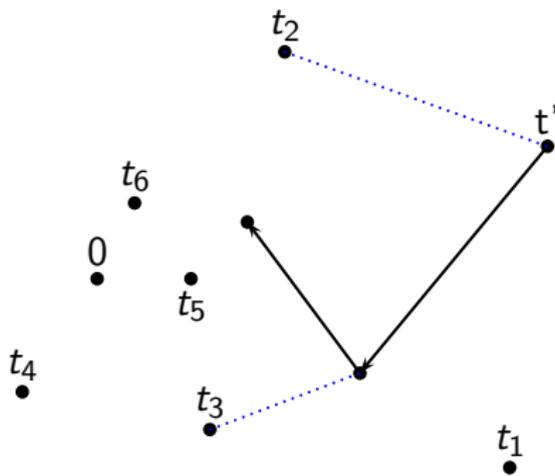
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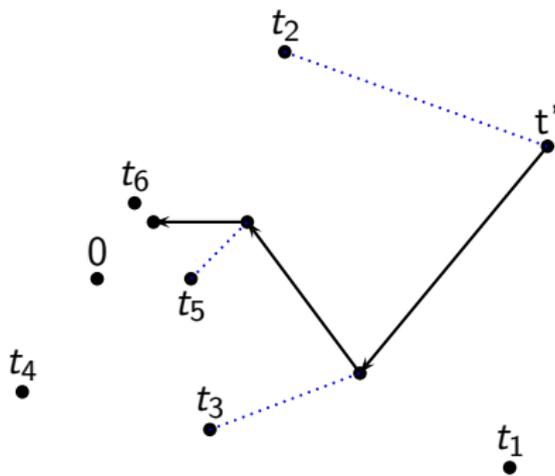
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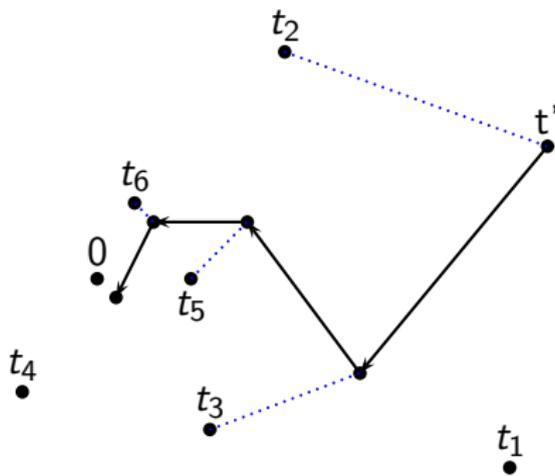
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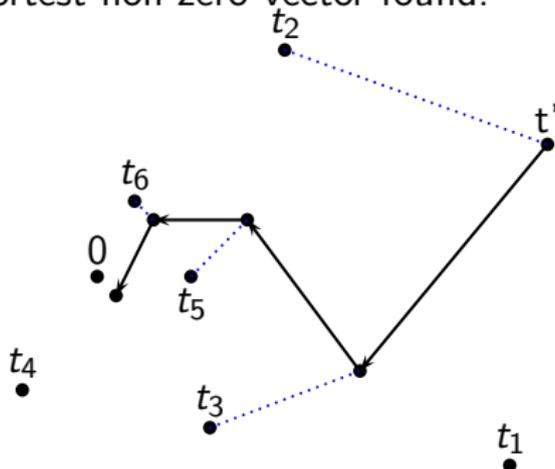
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- Time complexity $\leq N^2$; Space complexity $\leq N^2$.
- Saturation principle \Rightarrow at most $2^{c'n+o(n)}$ points at any time.

Correctness of ListSieve

How to ensure we get a shortest $\mathbf{s} \in L \setminus \mathbf{0}$?

- Principle: **Hide the lattice** to ListSieve by adding noise to the initial vectors: $\mathbf{t}_i \rightarrow \mathbf{t}_i + \mathbf{e}_i$.
- Once the vector has been dealt with: $\mathbf{t}_i^{end} \rightarrow \mathbf{t}_i^{end} - \mathbf{e}_i$.
- If noise $\approx \|\mathbf{s}\|$, then, with probability $\geq 2^{-\Omega(n)}$:

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- N is set large enough s.t. we get the same $\mathbf{t}^{end} \in L$ twice.
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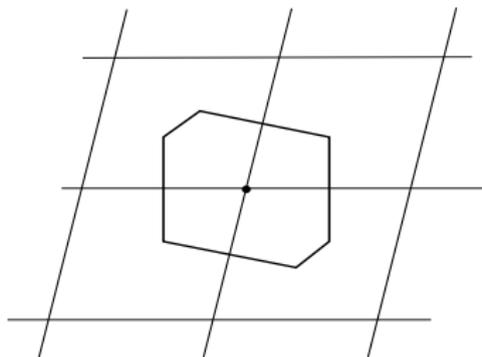
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Plan of the talk

- Reminders and context
- The KFP enumeration-based algorithm
- Saturating the space: The AKS solver and its descendants
- **Using the Voronoi cell: the Micciancio-Voulgaris algorithm.**
 - D. Micciancio & P. Voulgaris: A deterministic single exponential time algorithm for most lattice problems based on Voronoi cell computations, STOC'10

The Voronoi cell of a lattice

$$\mathcal{V}(L) = \{\mathbf{x} \in \mathbb{R}^n : \forall \mathbf{b} \in L \setminus \mathbf{0}, \|\mathbf{x} - \mathbf{b}\| > \|\mathbf{x}\|\}.$$



The relevant vectors

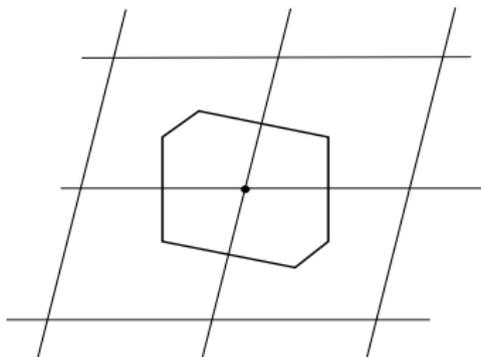
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Furthermore, these \mathbf{v}_i are the smallest such set.

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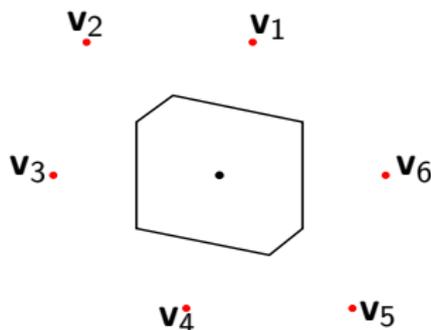
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$$\mathcal{V}(L) = \{\mathbf{x} \in \mathbb{R}^n : \forall \mathbf{b} \in L \setminus \mathbf{0}, \|\mathbf{x} - \mathbf{b}\| > \|\mathbf{x}\|\}.$$



The relevant vectors

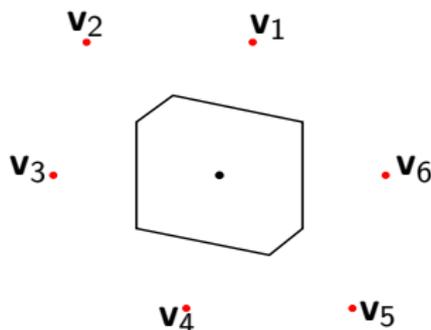
Let $(\mathbf{v}_i)_i$ be s.t. $\pm\mathbf{v}_i$ are the unique minima of a non-zero coset of $L/2L$. Then $\mathcal{V}(L) = \{\mathbf{x} \in \mathbb{R}^n : \forall i, \|\mathbf{v}_i - \mathbf{x}\| > \|\mathbf{x}\|\}$.

Furthermore, these \mathbf{v}_i are the smallest such set.

- A coset of $L/2L$ is of the form $(\sum_i \varepsilon_i \mathbf{b}_i) + 2L$ with $\varepsilon_i \in \{0, 1\}$.
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Solving SVP & CVP with the Voronoi cell

- SVP: A shortest non-zero vector is a relevant vector.
- CVP: translate \mathbf{t} by a $\mathbf{b} \in L$ to map it to $\overline{\mathcal{V}}(L)$.
- It suffices to be able to do it when $\mathbf{t} \in 2\overline{\mathcal{V}}(L)$.

CVP $_{2\overline{\mathcal{V}} \rightarrow \overline{\mathcal{V}}}$:

- $\mathcal{C}(\mathbf{v}_i)$: cone of apex $\mathbf{0}$ and base the corresponding facet of $\overline{\mathcal{V}}$.
- While $\mathbf{t} \notin \overline{\mathcal{V}}$: Find i s.t. $\mathbf{t} \in \mathcal{C}(\mathbf{v}_i)$; Subtract \mathbf{v}_i from \mathbf{t} .

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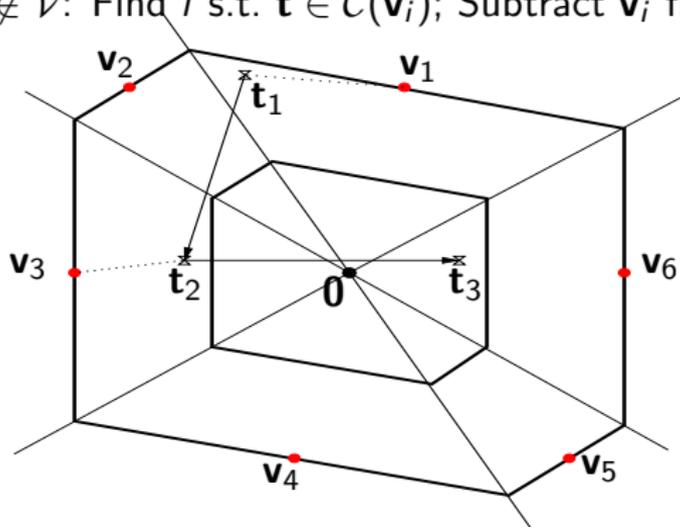
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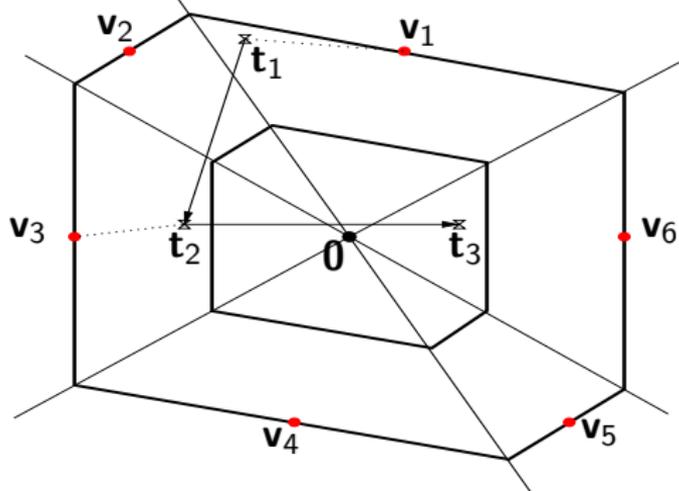


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- A relevant vector $\mathbf{v} \in L$ is a shortest vector in a coset of $L/2L$.
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Trick: CVP in dim n can be solved with $2^{o(n)}$ CVP's in dim $n - 1$.

$$\text{CVP}(\mathbf{t}, 2L) = \min_{\|\cdot\|} \{ \text{CVP}(\mathbf{t} + x_n(2\mathbf{b}_n), L^-) : x_n \in \mathbb{Z} \},$$

- $L^- = 2L \cap \text{Span}(\mathbf{b}_1, \dots, \mathbf{b}_{n-1})$.
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Overall: Intertwined Voronoi/CVP in increasing dimensions.

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III. Application : Coppersmith's method

Lattice algorithms – Coppersmith's method

- $P \in \mathbb{Z}[X]$ of degree d , **monic**;
- N an integer;
- want to solve $P(x) = 0 \pmod{N}$;
- easy
 - if N prime (factoring mod p);
 - or factors of N known (CRT + Hensel lifting);
- hard in general: $\deg P = 2 \Leftrightarrow$ factoring N .
- look for small solutions x .
- Why small? Allow to lift the problem to \mathbb{Z} (easy again).

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Lattice algorithms – Coppersmith's method (outline)

Simple example :

- RSA: $N = pq$, d, e integers such that $d \cdot e = (p - 1)(q - 1)$;
- N, e public;
- Encryption is $x \mapsto x^e$, decryption is $x \mapsto x^d$.

If $|x| < N^{1/e}$, can decrypt from $c := x^e \bmod N$:

- $|x|^e < N \Rightarrow x^e = c$ in \mathbb{Z} ;
- Extract e -th root in \mathbb{Z} (eg. Newton's method).

Key argument: if

- $|x| \leq X$ (X small),
- and $|P|(X) < N$ (P small),

then $P(x) = 0 \bmod N \Rightarrow P(x) = 0$ in \mathbb{Z} .

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First attempt: Girault, Toffin, Vallée / Hastad.

- Try to find small $Q = P + SN$;
- x, Q small $\Rightarrow Q(x) < N$
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Lattice algorithms – Coppersmith's method (outline)

L lattice generated by coefficient vectors of $N, Nx, \dots, Nx^{d-1}, P$.

$$L = \begin{pmatrix} N & & & & p_0 \\ & N & & & p_1 \\ & & N & & p_2 \\ & & & \ddots & \vdots \\ & & & & N & p_{d-1} \\ & & & & & 1 \end{pmatrix}$$

- v short vector in $L \Leftrightarrow Q = P + SN$ with small coefficients;
- Want very small high order coefficients, low order coefficient are less important.
- More precisely, $|x| \leq X \Rightarrow |Q(x)| \leq \sum_{j=0}^d q_j X^j$.
- \Rightarrow want $Q(xX) = P(xX) + S(xX)N$ with small coefficients
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Lattice algorithms – Coppersmith's method (outline)

Analysis.

- $\text{vol}(L) = \prod_{i=0}^{d-1} (NX^i) = N^d X^{d(d+1)/2}$;
- LLL returns a vector v with $\|v\|_2 \leq 2^{O(d)} N^{d/(d+1)} X^{d/2}$
- Hence $\|v\|_1 \leq 2^{O(d)} N^{d/(d+1)} X^{d/2}$
- ok if $2^{O(d)} N^{d/(d+1)} X^{d/2} < N$
- ... $X = O(N^{2/(d(d+1))})$.

Time = $\text{poly}(d, \log N)$.

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Lattice algorithms – Coppersmith's method (outline)

Coppersmith's method.

Key idea: use multiplicities (powers of P)!

- $P(x) = 0 \pmod N \Rightarrow P^i(x)N^{k-i} = 0 \pmod N^k$ for all i ;
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Lattice L

- generated by coefficient vectors of $S_{ij} = (xX)^j P^i(xX)N^{k-i}$;
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- Look for $Q = \sum_{i=0}^k P^i N^{k-i} R_i(X)$, $\deg R_i < d$, $\deg R_k \leq t$;
- s.t. $|Q|(X) < N^k$

Lattice L

- generated by coefficient vectors of $S_{ij} = (xX)^j P^i (xX) N^{k-i}$;
- dimension $\delta = dk + t + 1$;
- $\deg S_{ij} = id + j$;
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Lattice algorithms – Coppersmith's method (outline)

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Coppersmith's method (1996).

$$\begin{aligned} \text{diagonal}(L) = & (N^k, N^k X, \dots, N^k X^{d-1}, \\ & N^{k-1} X^d, N^{k-1} X^{d+1}, \dots, N^{k-1} X^{2d-1} \\ & , \dots, \\ & X^{kd}, X^{kd+1}, \dots, X^{kd+t}) \end{aligned}$$

$$\text{vol} L = X^{\sum_{i=0}^{\delta-1} i} N^{d \sum_{i=0}^k (k-i)}$$

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Lattice algorithms – Coppersmith's method

$$\text{vol}L = X^{\delta(\delta-1)/2} N^{dk(k+1)/2}.$$

- Want

$$2^{O(\delta)} X^{(\delta-1)/2} N^{dk(k+1)/2\delta} \leq N^k,$$

- ie.

$$X = O(N^{k(2\delta - d(k+1))/\delta(\delta-1)}).$$

- $\delta \approx dk, k \rightarrow \infty,$

$$2k(2\delta - d(k+1))/\delta(\delta-1) = 1/d - O(1/k).$$

Take $k = O(\log N),$

- get $X = O(N^{1/d});$
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Lattice algorithms – Coppersmith's method, gcd extension

Solve $|x| \leq X$, $\gcd(P(x), N) > N^\beta$.

- Same strategy;
- If $|x| \leq X$, $\gcd(Q(x), N^k) > N^{k\beta}$ and $|Q|(X) < N^{k\beta}$
- ... then $Q(x) = 0$.

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Lattice algorithms – Coppersmith's method, summary

Theorem. (Coppersmith). There is a polynomial-time algorithm which on input P, N , returns all $x \in [-N^{1/d}, N^{1/d}]$ such that $P(x) = 0 \pmod N$.

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Lattice algorithms – Coppersmith's method, application 1

Factoring with high bits known.

- Assume $N = pq$ RSA modulus, $p = p_h + p_l$, where p_h is known and p_l is “small”;
- Put $R(X) = X + p_h$;
- Have $\gcd(R(p_l), N) \approx N^{1/2}$;
- Coppersmith's method \Rightarrow can find p_l as soon as $|p_l| \leq N^{1/4}$.
- Can factor N in polynomial time from half the high order bits of a factor of N .

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Lattice algorithms – Coppersmith's method, bivariate version

- same game with $Q(x, y) = 0 \pmod N$, $|x| \leq X$, $|y| \leq Y$;
- Build a lattice from $(xX)^\ell (yY)^m Q(xX, yY)^i N^{k-i}$;
- Find **two** small vectors in this lattice \rightarrow

$$P_1(x, y) = 0 \pmod N, P_2(x, y) = 0 \pmod N.$$

- If P_1, P_2 small enough, $P_1(x, y) = P_2(x, y) = 0$;
- May fail if P_1 and P_2 are algebraically dependent...
- Otherwise, use your favorite method to solve (resultant, Hensel lifting, etc.).
- Details are tricky: auxiliary polynomials depend finely on shape of P and X, Y .

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Lattice algorithms – Coppersmith's method, application 2

RSA modulus $N = ed$, d small, e public.

- Wiener's attack with continued fractions \Rightarrow can find d from e, N as soon as $d < N^{1/4}$;
- Boneh-Durfee : $ed + k(N + 1 - p - q) = 1$, hence $k(A + s) = 1 \pmod e$, k, s unknown.
- d small $\Rightarrow e \approx N \Rightarrow |k| \leq e^\delta, |s| \leq e^{0.5}$.
- $f(x, y) := x(A + y) - 1$, use

$$g_{i,l} = x^i f(x, y)^l e^{k-l}, h_{i,j} = y^j f(x, y)^l e^{k-l},$$

- Triangular matrix... find \tilde{g} small enough as soon as $\delta \leq 0.284$.
- Using a better (non full-rank) lattice gives $\delta \leq 0.292$.

Lattice algorithms – Coppersmith's method and RS codes

Let \mathbb{K} be a finite field, n, k given.

- $(x_i)_{1 \leq i \leq n}$ pairwise distinct points in \mathbb{K} ;
- Reed-Solomon code: message is P , $\deg P < k$, send $(P(x_1), \dots, P(x_n))$, receive (y_1, \dots, y_n) ;
- Define $R(x)$ of degree $< k$ st. $R(x_i) = y_i$ for all i ;
- Decoding : Find all $P \in \mathbb{K}[X]$, $\deg P \leq k$, st.
 $\deg \gcd(P(X) - R(X), \prod_{i=1}^n (X - x_i)) > \delta$ (correct $n - \delta$ errors).

This is (list-)decoding of Reed-Solomon codes.

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- $k = 1, u$ arbitrary: $\delta = \sqrt{2kn}$ (Sudan)
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