

From Equivalences to Metrics

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PACE meeting
(BOLOGNA)

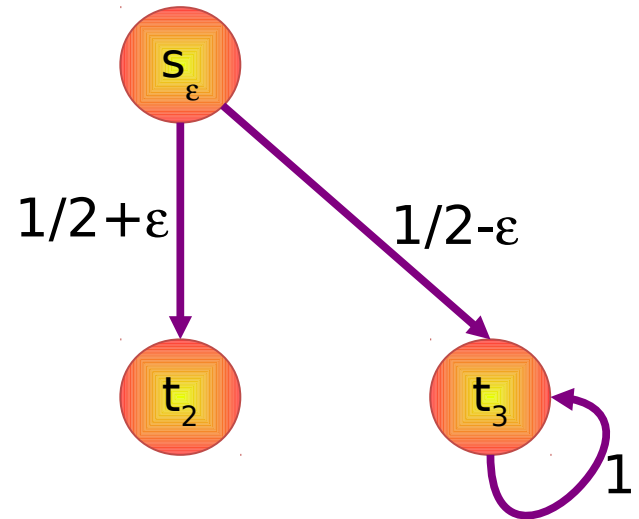
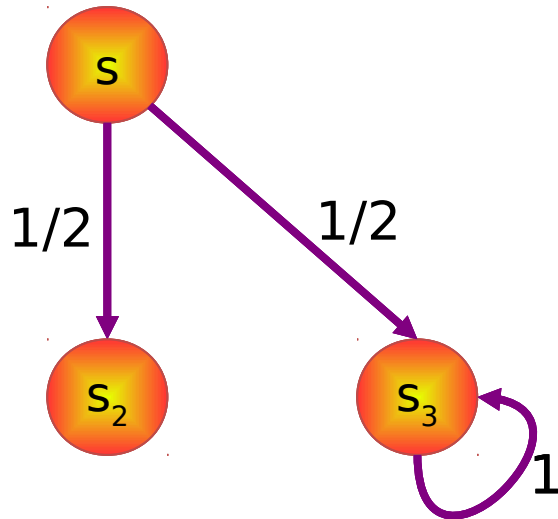
From Equivalences to Metrics

F. van Breugel, J. Worrell: A behavioural pseudometric for probabilistic transition systems. TCS 2005

F. van Breugel, James Worrell: Approximating and computing behavioural distances in probabilistic transition systems. TCS 2006

F. van Breugel, B. Sharma, J. Worrell: Approximating a Behavioural Pseudometric Without Discount for Probabilistic Systems. LMCS 2008

Motivations



s and s_ϵ are NOT behaviorally equivalent ...

... but for small ϵ , they almost behave the same

From Equivalences to Distances

- Behavioural Equivalences are the foundations of qualitative reasoning
- Behavioural Distances are the foundations of quantitative reasoning
- A Behavioural Distance is a pseudo-Metric

$$d:S \times S \rightarrow [0,1]$$

that assigns to two systems the distance of their behaviours

- $d(p,q) = 0$ iff p is behaviourally equivalent to q

From Equivalences to Distances

- Behavioural Equivalences are the foundations of qualitative reasoning
- Behavioural Distance for
- A property

Does these systems behave the same?

Does a system satisfy a certain property?

How far apart is the behaviour of these systems?

How much closely does a system come to satisfy a certain property?

equivalent to q

Plan of the Talk

1. Coalgebras in a nutshell
2. Probabilistic Systems
3. Behavioural (Pseudo-)Metrics
 - Coalgebras
 - Coinduction
 - Refinement Algorithm
 - Modal Logic

Coalgebras in a nutshell

At the blackboard

A functor F induces:

- 1) Behavioural equivalence \cong_F
- 2) Coinduction Proof Principle:
 $x \cong_F y$ iff xRy for some F -bisimulation R
- 3) Partition F -Refinement Algorithm
- 4) An Hennessy-Milner Logic:
 $x \cong_F y$ iff $f(x) = f(y)$ for all F -formulas f

Functors

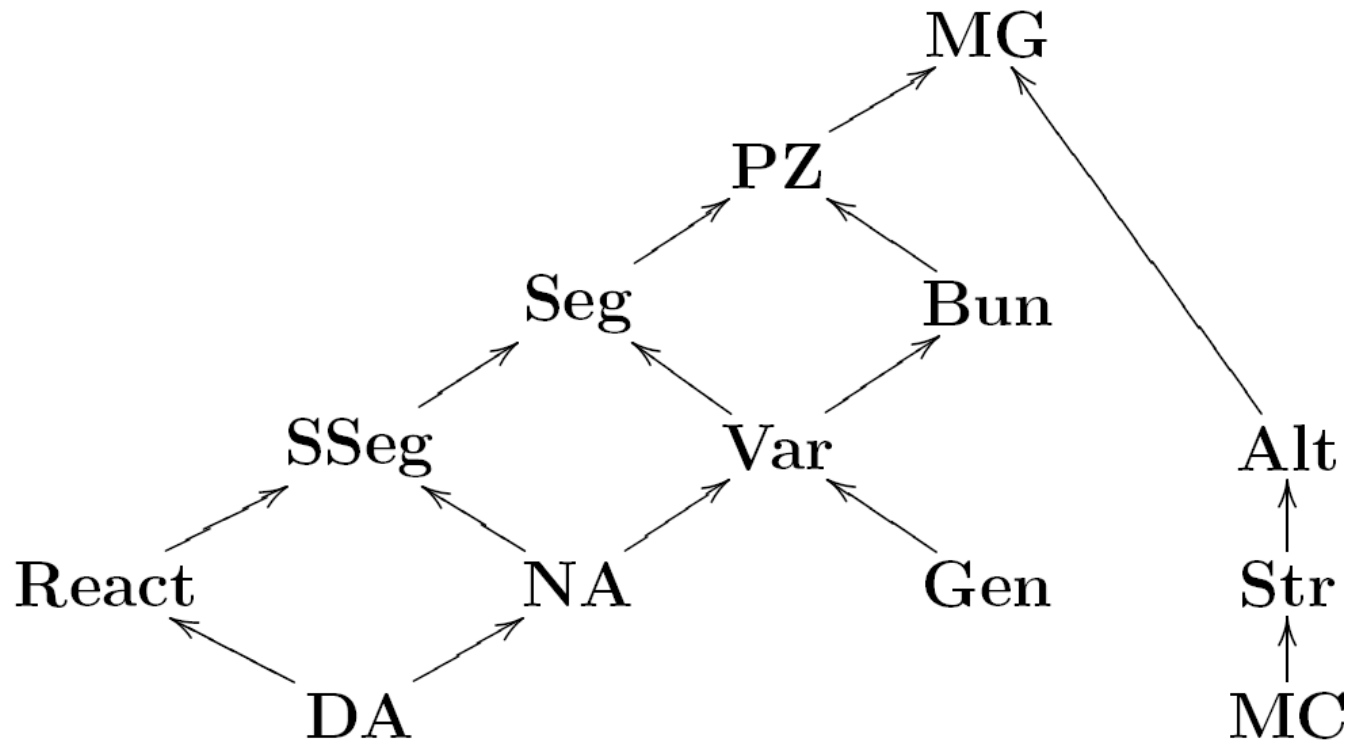
Set is the category of sets and functions

$F ::= \text{Id}, A, F + F, F \times F, F^A, P(F), D(F)$

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A Hierarchy of Probabilistic Systems Types

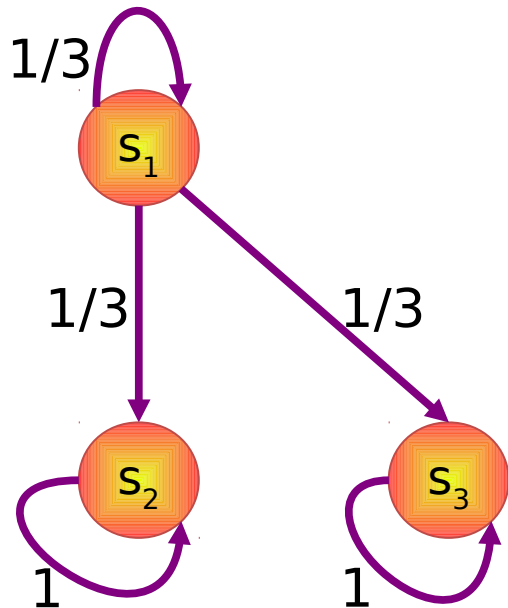


Markov Chains

$\mathbf{D}(\text{Id})$: Set \rightarrow Set

$\mathbf{D}(S) = \{\mu: S \rightarrow [0,1] \mid \mu[X]=1, \text{spt}(\mu) \text{ finite}\}$

$\langle S, \alpha: S \rightarrow \mathbf{D}(S) \rangle$

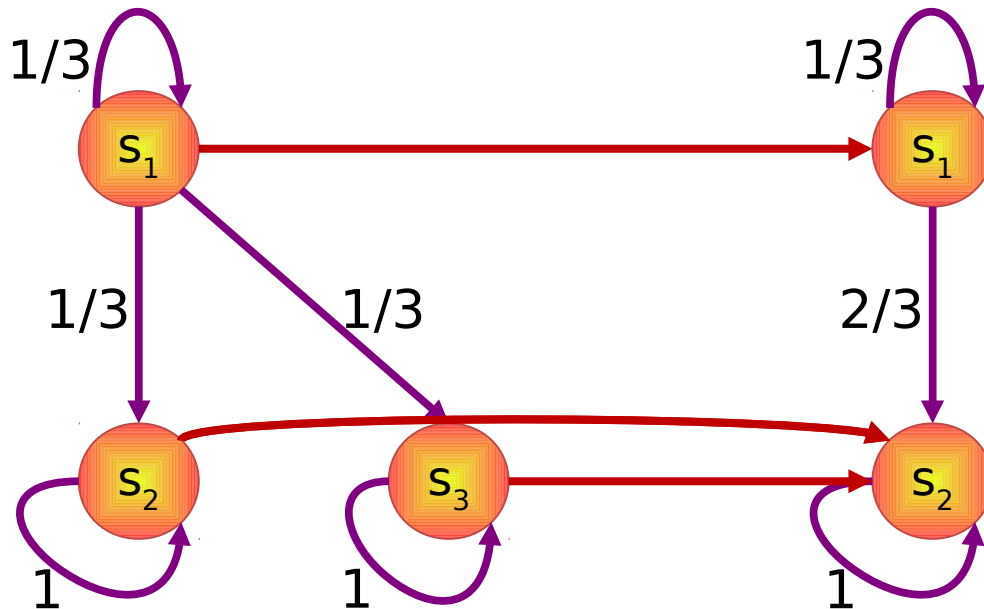


Markov Chains

$\mathbf{D}(\text{Id}): \underline{\text{Set}} \rightarrow \underline{\text{Set}}$

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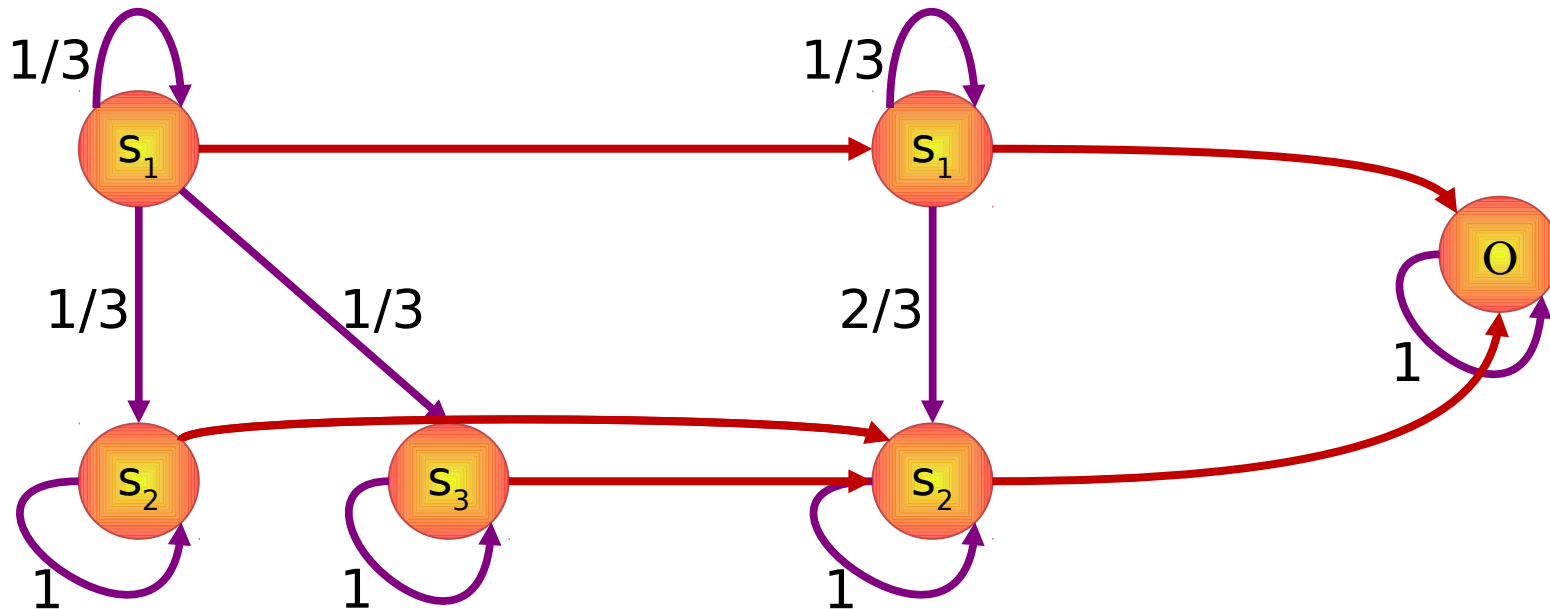


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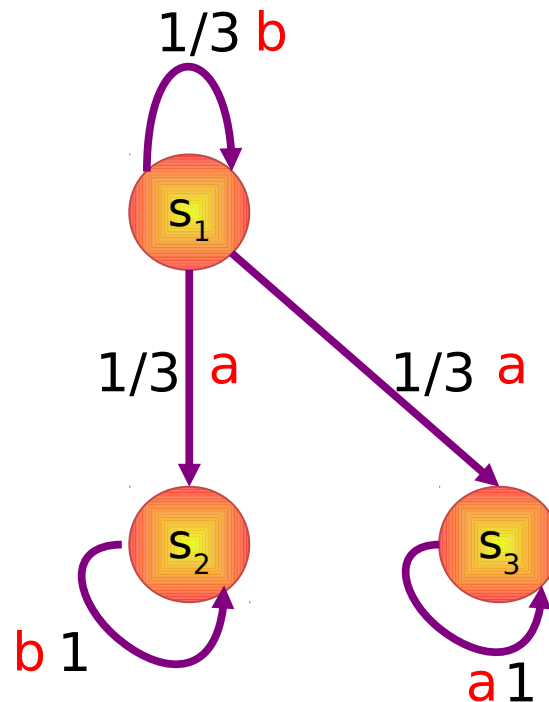


Generative Systems

$D(\text{AxId})$: Set \rightarrow Set

$A = \{a, b\}$

$\langle S, \alpha: S \rightarrow D(\text{Ax}S) \rangle$

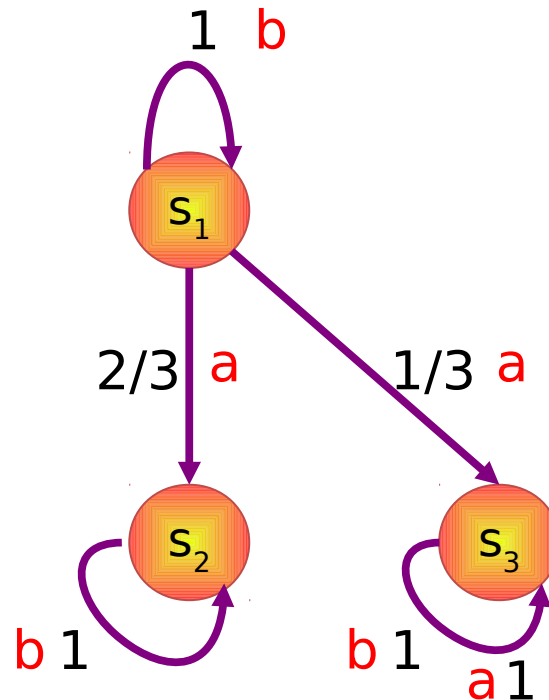


Reactive Systems

$\mathbf{D(Id)^A: \underline{Set} \rightarrow \underline{Set}}$

$A = \{a, b\}$

$\langle S, \alpha: S \rightarrow \mathbf{D}(S)^A \rangle$

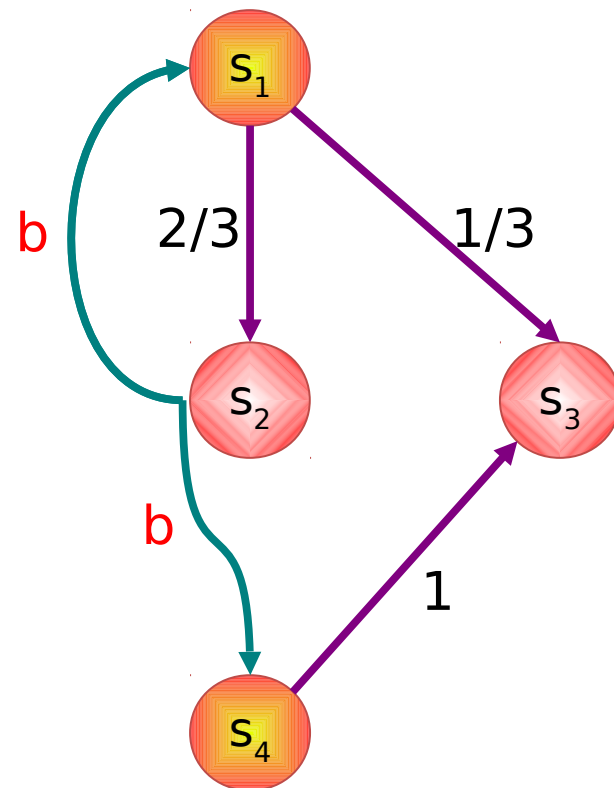


Alternating Systems

$D(\text{Id}) + P(\mathbf{A} \times \text{Id})$: Set \rightarrow Set

$\mathbf{A} = \{a, b\}$

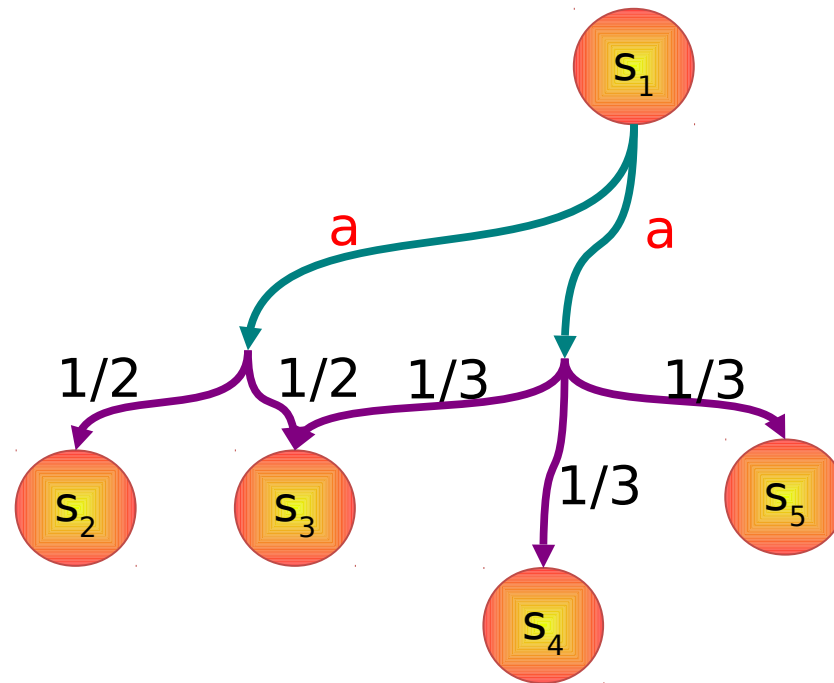
$\langle S, \alpha: S \rightarrow \mathbf{D}(S) + P(\mathbf{A} \times S) \rangle$



Simple Probabilistic Automata (Simple Segala Systems)

$P(\mathbf{A} \times \mathbf{D}(\text{Id}))$: Set \rightarrow Set $A = \{a, b\}$

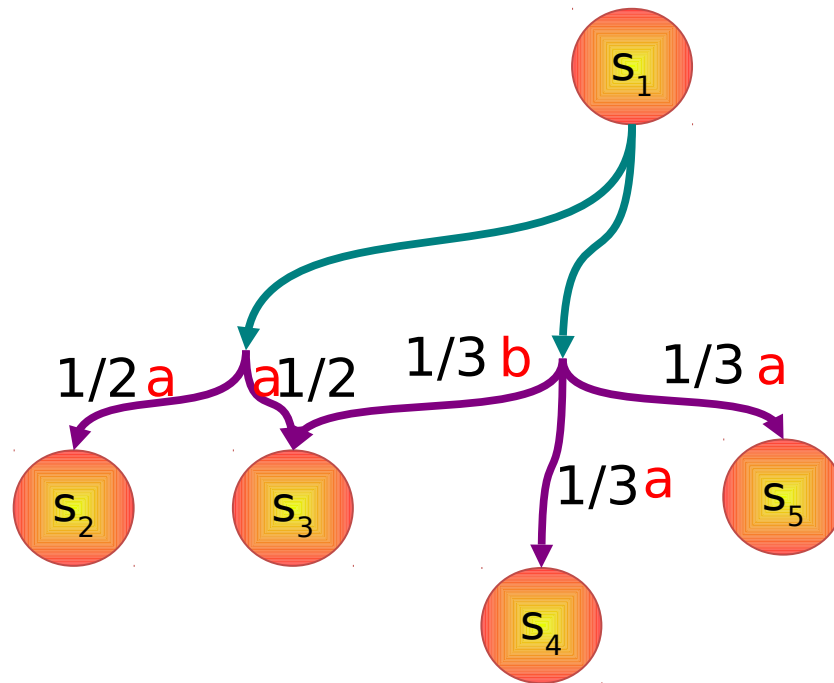
$\langle S, \alpha: S \rightarrow P(\mathbf{A} \times \mathbf{D}(S)) \rangle$



Probabilistic Automata (Segala Systems)

$PD(A \times id): \underline{Set} \rightarrow \underline{Set}$ $A = \{a, b\}$

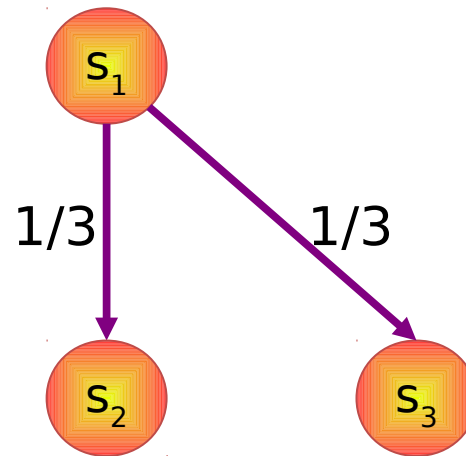
$\langle S, \alpha: S \rightarrow P D(A \times S) \rangle$



(Partial) Markov Chains

$D(\mathbf{1} + \text{Id}) : \underline{\text{Set}} \rightarrow \underline{\text{Set}}$

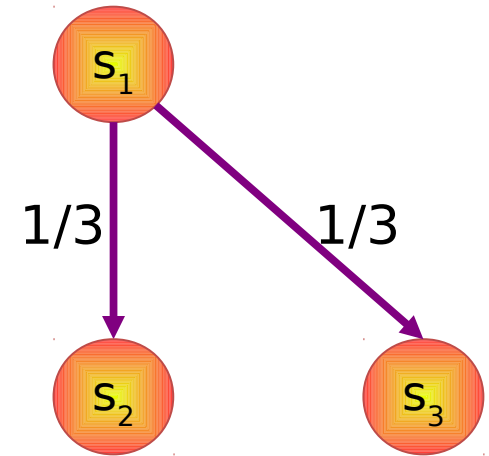
$\langle S, \pi : S \rightarrow D(\mathbf{1} + S) \rangle$



(Partial) Markov Chains Bisimulation

$D(\mathbf{1} + \text{Id}) : \underline{\text{Set}} \rightarrow \underline{\text{Set}}$

$\langle S, \pi : S \rightarrow D(\mathbf{1} + S) \rangle$

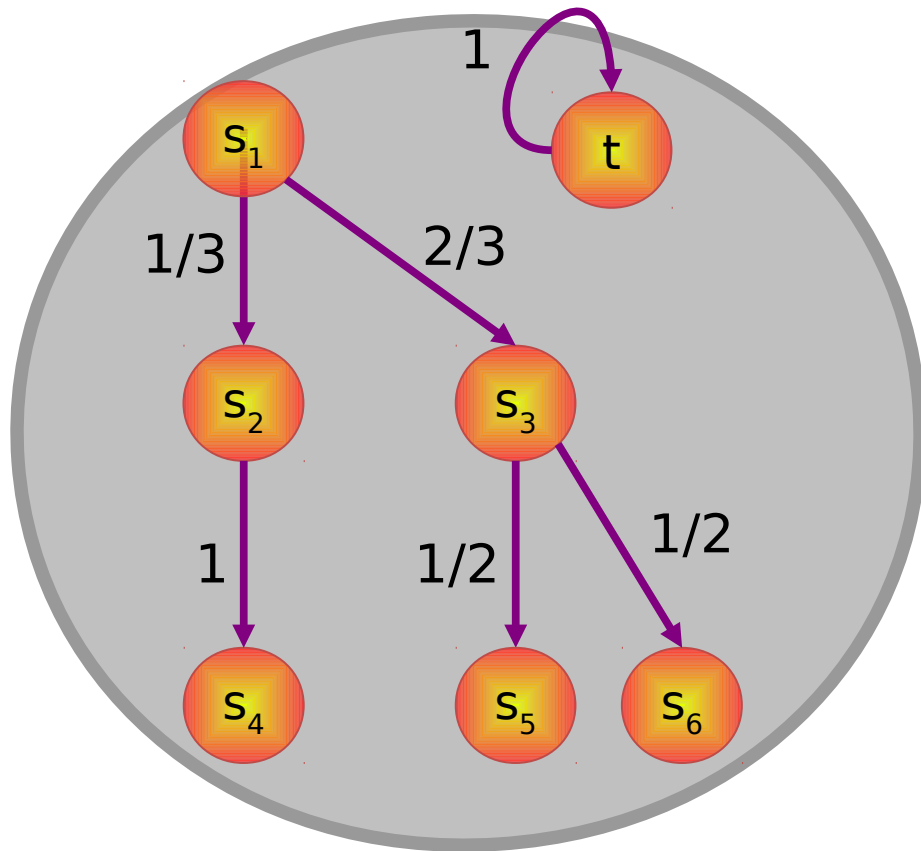


R is a Bisimulation iff whenever $s_1 R s_2$ then

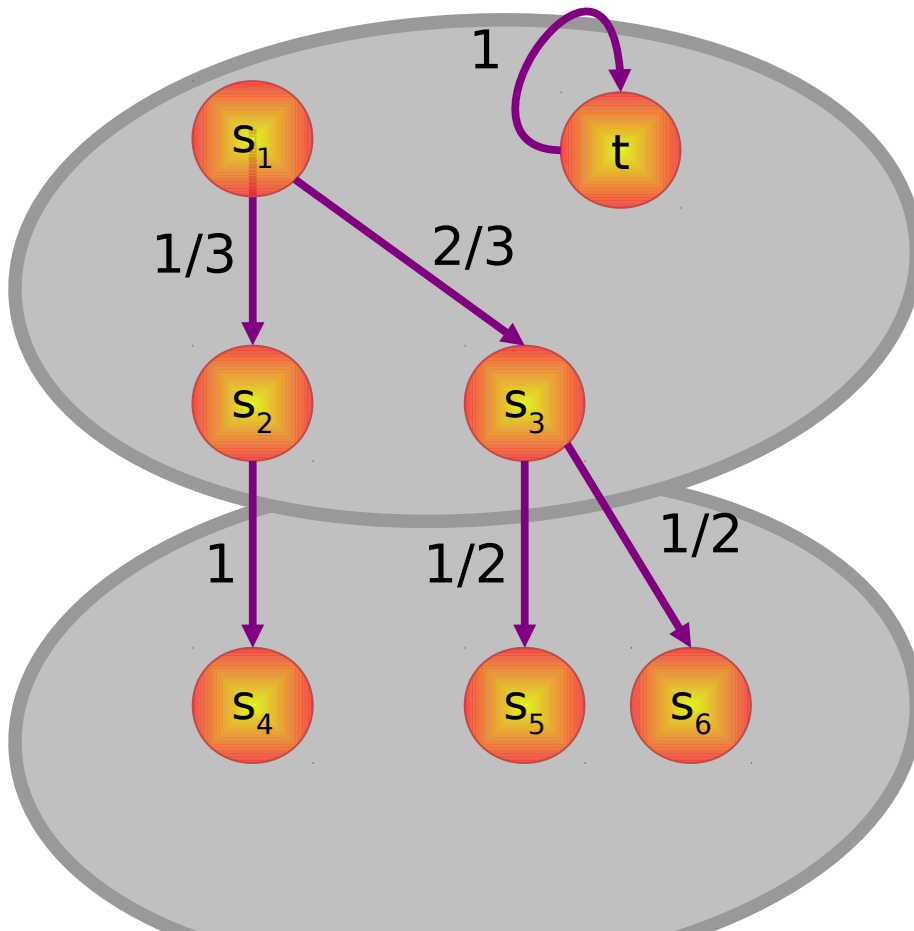
For all equivalence classes E of R

$$\sum_{s \in E} \pi(s_1, s) = \sum_{s \in E} \pi(s_2, s)$$

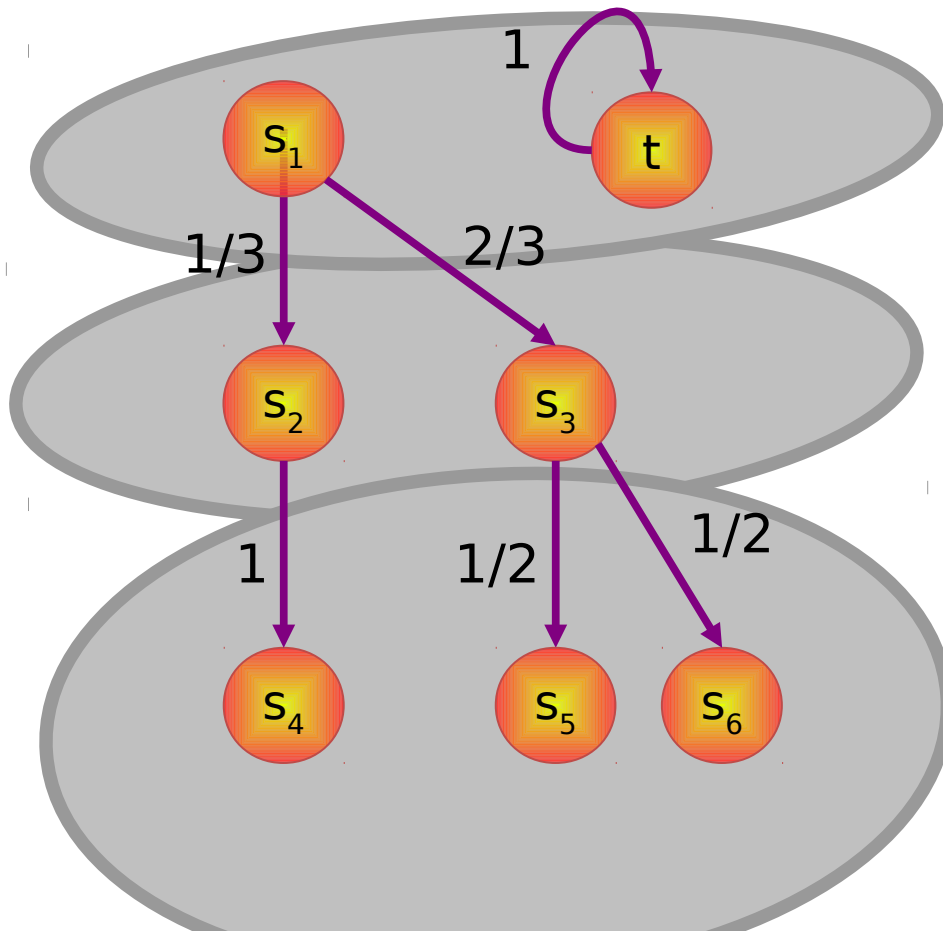
(Partial) Markov Chains Partition Refinement



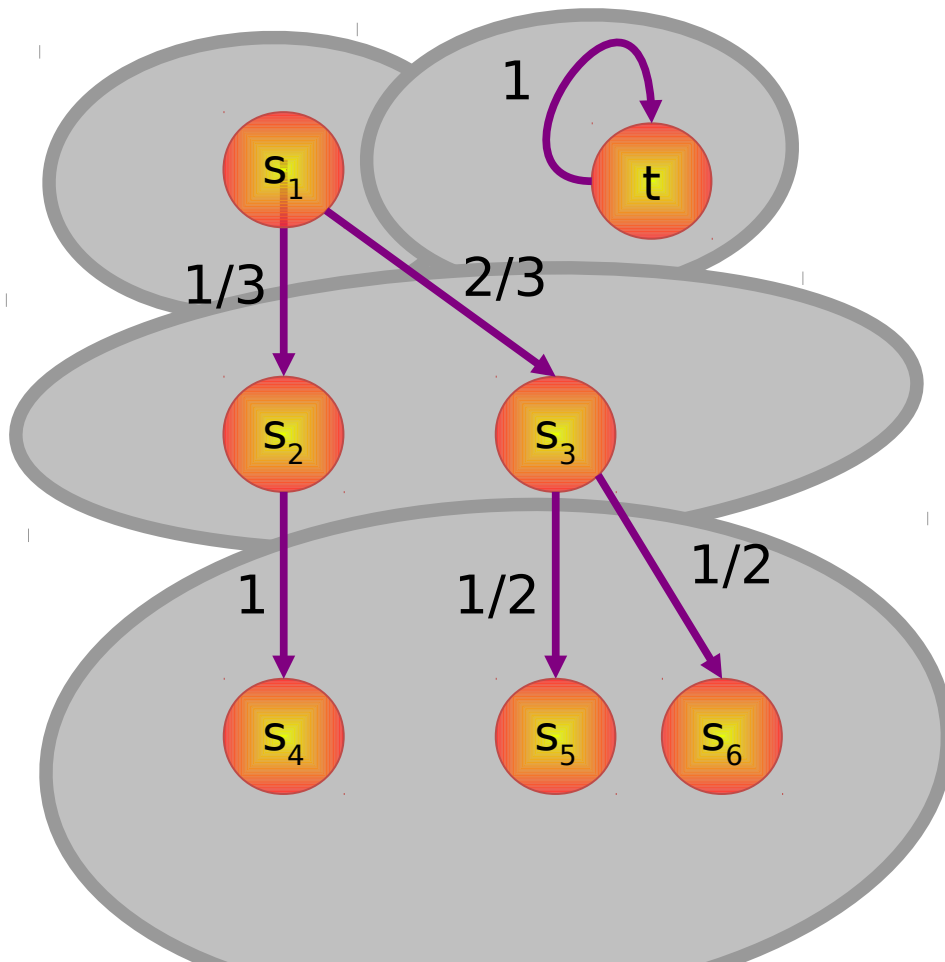
(Partial) Markov Chains Partition Refinement



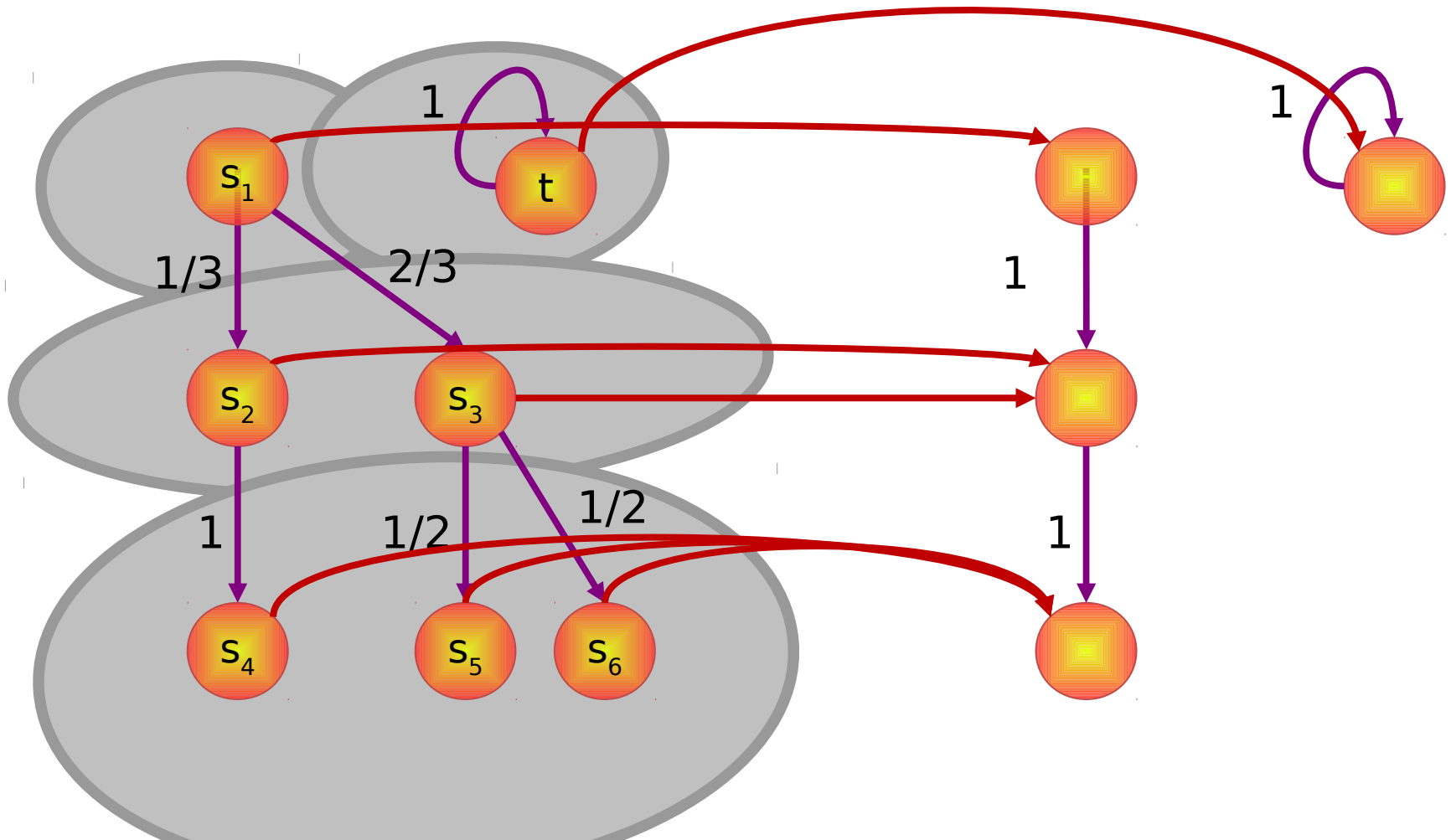
(Partial) Markov Chains Partition Refinement



(Partial) Markov Chains Partition Refinement



(Partial) Markov Chains Partition Refinement



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Functors

Ms is the category of metric spaces
and non-expansive maps

**$F ::= \text{Id}, \mathbf{A}, \mathbf{F} + \mathbf{F}, \mathbf{F} \times \mathbf{F}, \mathbf{F}^{\mathbf{A}}, \mathbf{P}(\mathbf{F}), \mathbf{D}(\mathbf{F}),$
 $\delta(\mathbf{F})$**

δ is in $[0,1]$

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Example of Coinduction

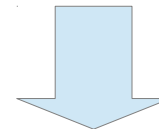
Post-fix point

d	s	s ₂	s ₃	t
s	0	1	1	2ε
s ₂	1	0	1	1
s ₃	1	1	0	1
t	2ε	1	1	0

$$\Delta(d)(s,t) \leq$$

$$\varepsilon + 2\varepsilon/3 \leq$$

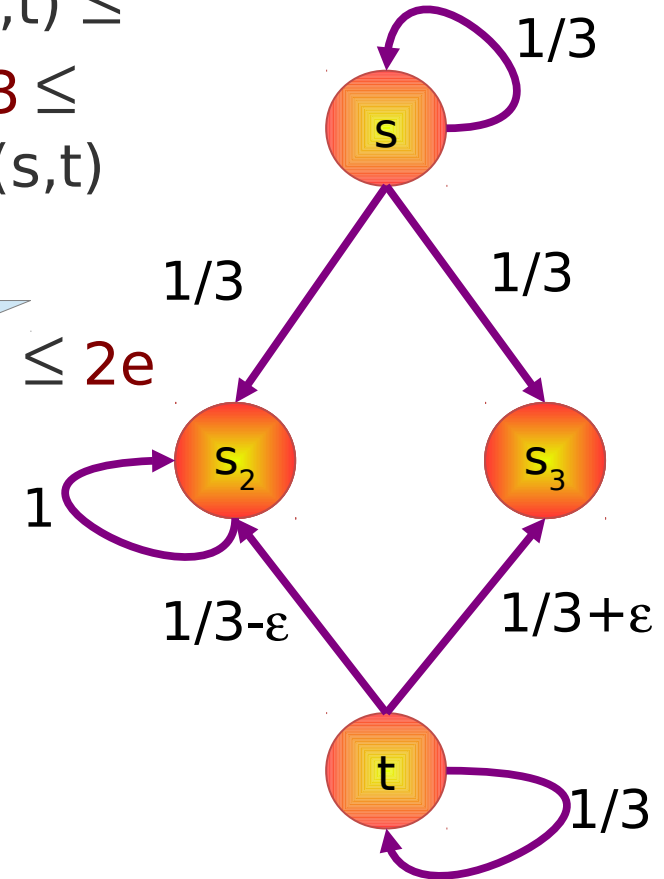
$$2\varepsilon = d(s,t)$$



$$d_F(s,t) \leq 2\varepsilon$$

Coupling of s and t

	s	s ₂	s ₃	t	π(s)
s	0	0	0	1/3	1/3
s ₂	0	1/3-ε	ε	0	1/3
s ₃	0	0	1/3	0	1/3
t	0	0	0	0	0
π(t)	0	1/3-ε	1/3+ε	1/3	

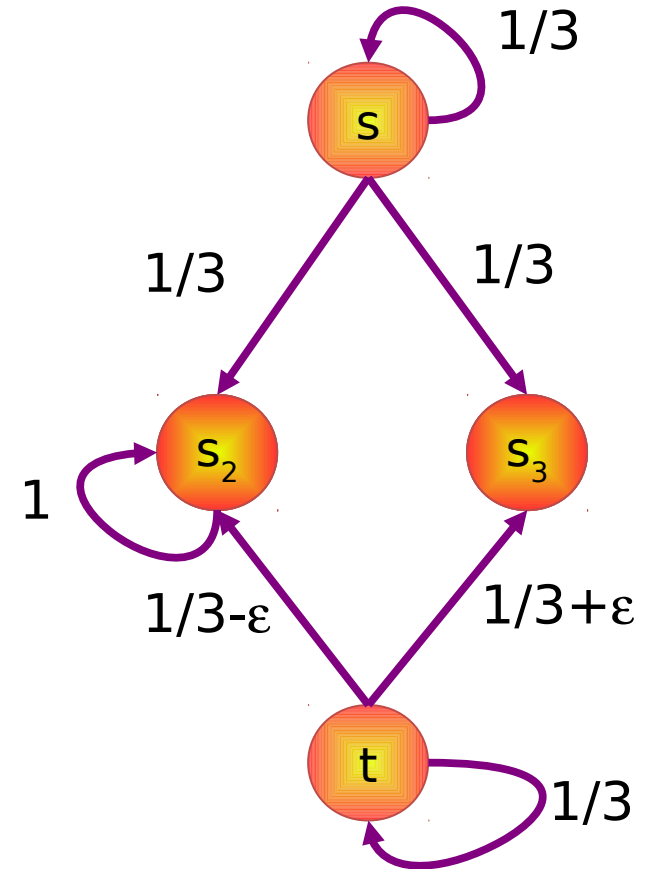


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Metric Refinement

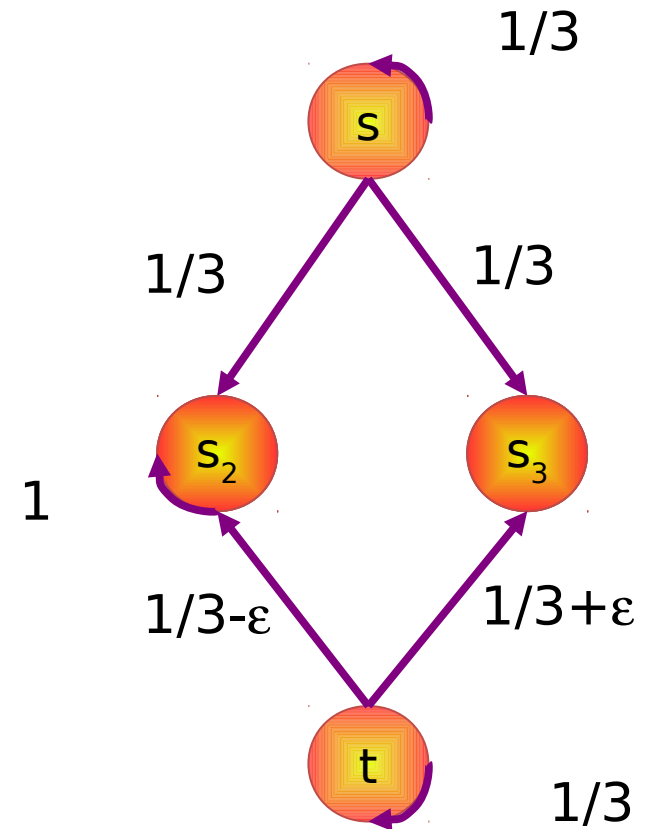
d_0	s	s_2	s_3	t
s	0	0	0	0
s_2	0	0	0	0
s_3	0	0	0	0
t	0	0	0	0



Metric Refinement

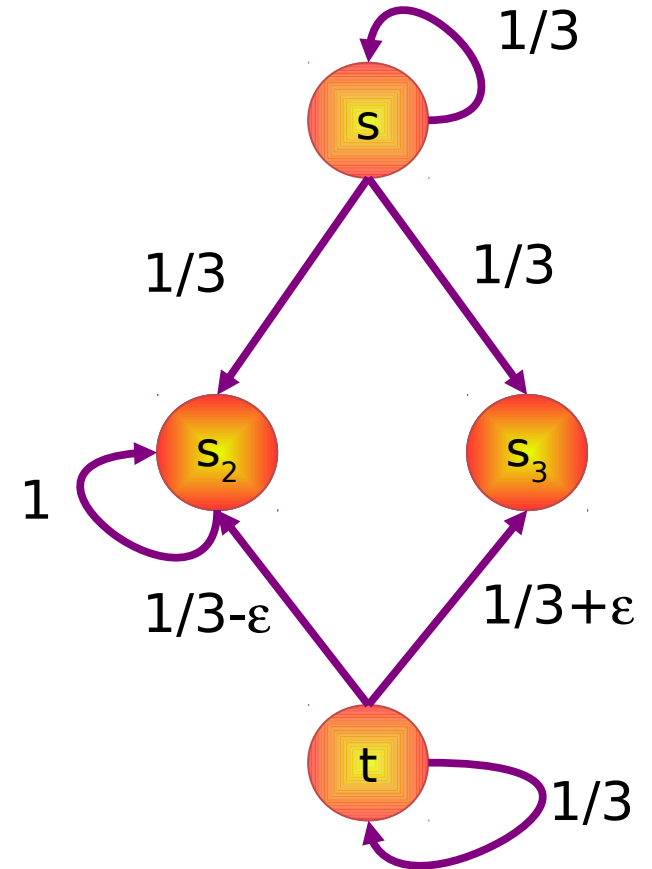
d_0	s	s_2	s_3	t
s	0	0	0	0
s_2	0	0	0	0
s_3	0	0	0	0
t	0	0	0	0

d_1	s	s_2	s_3	t
s	0	0	1	0
s_2	0	0	1	0
s_3	1	1	1	1
t	0	0	1	0



Metric Refinement

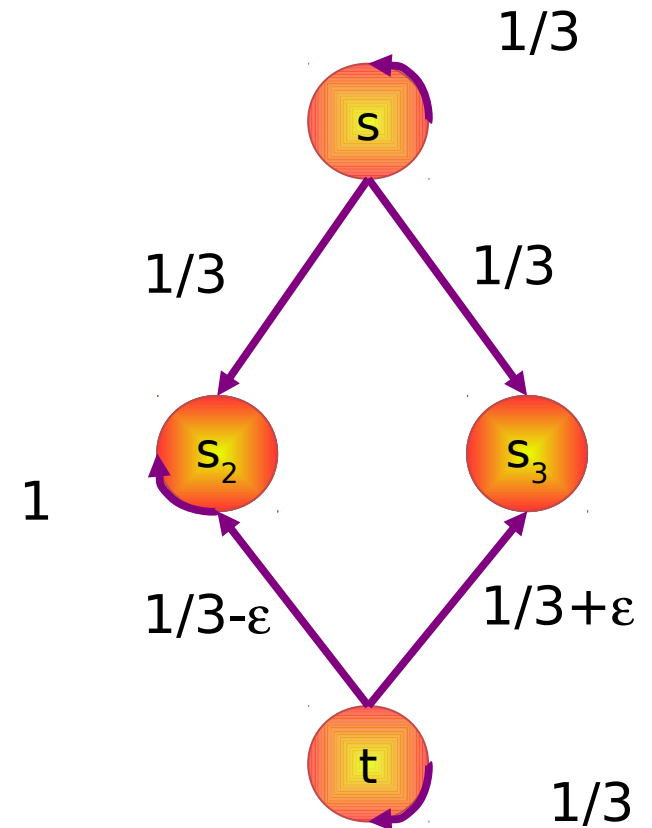
d2	s	s_2	s_3	t
s	0	1/3	1	ϵ
s_2	1/3	0	1	1/3+ ϵ
s_3	1	1	0	1
t	ϵ	1/3+ ϵ	1	0



Metric Refinement

d2	s	s_2	s_3	t
s	0	1/3	1	ϵ
s_2	1/3	0	1	1/3+ ϵ
s_3	1	1	0	1
t	ϵ	1/3+ ϵ	1	0

d3	s	s_2	s_3	t
s	0	1/3+1/9	1	$\epsilon+\epsilon/3$
s_2	1/3+1/9	0	1	1/3+ ϵ +1/9+ $\epsilon/3$
s_3	1	1	0	1
t	$\epsilon+\epsilon/3$	1/3+ ϵ +1/9+ $\epsilon/3$	1	0



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A Logical Characterization

- Modal Formulas f are functions $f:S \rightarrow \{0,1\}$
- Quantitative Formulas $f:S \rightarrow [0,1]$

$$d(s_1, s_2) = \sup_f |f(s_1) - f(s_2)|$$

A quantitative logic

$$\varphi ::= \text{true} \mid \diamond\varphi \mid \varphi \wedge \psi \mid \neg\varphi \mid \varphi \ominus q$$

$D(\mathbf{1} + \text{Id})$: Set \rightarrow Set

$\langle S, \pi: S \rightarrow D(\mathbf{1} + S) \rangle$

$$\begin{aligned} \llbracket \text{true} \rrbracket_{\delta}(s) &= 1 \\ \llbracket \diamond\varphi \rrbracket_{\delta}(s) &= \delta \sum_{s' \in S} \pi(s, s') \llbracket \varphi \rrbracket_{\delta}(s') \\ \llbracket \varphi \wedge \psi \rrbracket_{\delta}(s) &= \min\{\llbracket \varphi \rrbracket_{\delta}(s), \llbracket \psi \rrbracket_{\delta}(s)\} \\ \llbracket \neg\varphi \rrbracket_{\delta}(s) &= 1 - \llbracket \varphi \rrbracket_{\delta}(s) \\ \llbracket \varphi \ominus q \rrbracket_{\delta}(s) &= \max\{\llbracket \varphi \rrbracket_{\delta}(s) - q, 0\} \end{aligned}$$