## Soundness in negotiations.

J. Esparza<sup>1</sup> D. Kuperberg<sup>1,2,3</sup> A. Muscholl<sup>1,2,4</sup> I. Walukiewicz<sup>1,4</sup>

<sup>1</sup>TU Munich, <sup>2</sup>IAS, <sup>3</sup>ENS Lyon, <sup>4</sup>LaBRI,CNRS

Séminaire 68NQRT, IRISA, Rennes 12/01/2017

## Introduction

### Negotiations [Desel, Esparza '13] CONCUR

- model multiparty distributed cooperation,
- better complexity than alternative models (Petri Nets),
- embeds natural concepts: soundness, race properties,...

### This paper [EKMW '16] CONCUR:

- study of different restrictions on the model,
- complexity of deciding soundness, concurrency relationships
- application to workflow analysis for programs

 An atomic negotiation or node involves a set of processes (participants) and has a set of possible outcomes.

- An atomic negotiation or node involves a set of processes (participants) and has a set of possible outcomes.
- If all participants are ready to engage in the node (synchronization), then the node can be fired: the processes agree on one of the outcomes (choice) and move on.

- An atomic negotiation or node involves a set of processes (participants) and has a set of possible outcomes.
- If all participants are ready to engage in the node (synchronization), then the node can be fired: the processes agree on one of the outcomes (choice) and move on.
- A negotiation  $\mathcal{N}$  consists of

- An atomic negotiation or node involves a set of processes (participants) and has a set of possible outcomes.
- If all participants are ready to engage in the node (synchronization), then the node can be fired: the processes agree on one of the outcomes (choice) and move on.
- A negotiation  $\mathcal{N}$  consists of
  - a set of processes *Proc*,

- An atomic negotiation or node involves a set of processes (participants) and has a set of possible outcomes.
- If all participants are ready to engage in the node (synchronization), then the node can be fired: the processes agree on one of the outcomes (choice) and move on.
- A negotiation  $\mathcal{N}$  consists of
  - a set of processes *Proc*,
  - a set of outcomes R,

- An atomic negotiation or node involves a set of processes (participants) and has a set of possible outcomes.
- If all participants are ready to engage in the node (synchronization), then the node can be fired: the processes agree on one of the outcomes (choice) and move on.
- A negotiation  $\mathcal{N}$  consists of
  - a set of processes *Proc*,
  - a set of outcomes *R*,
  - a set of nodes N

with two distinguished initial and final nodes,

- An atomic negotiation or node involves a set of processes (participants) and has a set of possible outcomes.
- If all participants are ready to engage in the node (synchronization), then the node can be fired: the processes agree on one of the outcomes (choice) and move on.
- A negotiation  $\mathcal{N}$  consists of
  - a set of processes *Proc*,
  - a set of outcomes *R*,
  - a set of nodes N
    - with two distinguished initial and final nodes,
  - a domain function  $dom : N \rightarrow \mathcal{P}(Proc)$ assigning to each node a set of participants,

- An atomic negotiation or node involves a set of processes (participants) and has a set of possible outcomes.
- If all participants are ready to engage in the node (synchronization), then the node can be fired: the processes agree on one of the outcomes (choice) and move on.
- A negotiation  $\mathcal{N}$  consists of
  - a set of processes *Proc*,
  - a set of outcomes *R*,
  - a set of nodes N
    - with two distinguished initial and final nodes,
  - a domain function  $dom : N \rightarrow \mathcal{P}(Proc)$ assigning to each node a set of participants,
  - a transition table δ : N × R × Proc → P(N)
    δ(n, a, p) = {n', n''} means: if the participants of n choose a, then p is ready to engage in n' or n''.



$$\delta(n_{init}, a, p_2) = \{n_1, n_3\}$$



$$\delta(n_{init}, a, p_2) = \{n_1, n_3\}$$

$$\delta(n_1, a, p_2) = \{n_2, n_{fin}\}$$



 $n_{init}$  initial node,  $n_{fin}$  final node. Here: 3 processes  $p_1, p_2, p_3$  and only one action a.

$$\delta(n_{init}, a, p_2) = \{n_1, n_3\}$$

$$\delta(n_1, a, p_2) = \{n_2, n_{fin}\}$$

 $\delta(n_2, a, p_2) = \{n_1, n_3\}$ 



$$\delta(n_{init}, a, p_2) = \{n_1, n_3\} \qquad n_{init} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_1, a, p_2) = \{n_2, n_{fin}\} \qquad n_1 \xrightarrow{p_2 p_2 p_3} \\ \delta(n_2, a, p_2) = \{n_1, n_3\} \qquad n_1 \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_2, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_2, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_2, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_2, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_2, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_2, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, p_3) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, p_3) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, p_3) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, p_3) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, p_3) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, p_3) = \{n_3, n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, p_3) = \{n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, p_3) = \{n_3, n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_3, p_3) = \{n_3, n_3, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_3} \\ \delta(n_3$$

 $n_{init}$  initial node,  $n_{fin}$  final node. Here: 3 processes  $p_1, p_2, p_3$  and only one action *a*.

$$\delta(n_{init}, a, p_2) = \{n_1, n_3\} \qquad n_{init} \xrightarrow{p_1 p_2 p_3} \\ \delta(n_1, a, p_2) = \{n_2, n_{fin}\} \qquad n_1 \xrightarrow{p_2 p_2 p_3} \\ \delta(n_2, a, p_2) = \{n_1, n_3\} \qquad n_2 \xrightarrow{p_2 p_3} \\ \delta(n_3, a, p_2) = \{n_2, n_{fin}\} \qquad n_{fin} \xrightarrow{p_1 p_2 p_3} \\ n_{fin} \xrightarrow{p_1 p_3} \\ n_{fin} \xrightarrow{p_1 p_3} \\ n_{fin} \xrightarrow{p_1 p_2 p_3} \\ n_{fin} \xrightarrow{p_1 p_$$

 $p_2$  is non-deterministic, while  $p_1$  and  $p_3$  are deterministic.

**Deterministic negotiations**: All processes are deterministic.

- **Deterministic negotiations**: All processes are deterministic.
- Weakly non-deterministic negotiations: Each node involves at least one deterministic process.
- Acyclic: No cycle in the transition graph between nodes.

- **Deterministic negotiations**: All processes are deterministic.
- Weakly non-deterministic negotiations: Each node involves at least one deterministic process.
- Acyclic: No cycle in the transition graph between nodes.

Intuition for weakly non-deterministic negotiations:

The negotiation is guided by the deterministic processes. Non-deterministic processes are "told" where to go by the deterministic ones.

- **Deterministic negotiations**: All processes are deterministic.
- Weakly non-deterministic negotiations: Each node involves at least one deterministic process.
- Acyclic: No cycle in the transition graph between nodes.

Intuition for weakly non-deterministic negotiations:

The negotiation is guided by the deterministic processes. Non-deterministic processes are "told" where to go by the deterministic ones.

**Research program**: investigate the complexity of analysis problems for deterministic and weakly non-deterministic negotiations.

# The Soundness problem

## Soundness property

#### Soundness:

Every partial run can be completed into an accepting run. Non-blocking property, witnessing good design.

**Example**: Previous negotiation is sound.

#### Soundness:

Every partial run can be completed into an accepting run. Non-blocking property, witnessing good design.

**Example**: Previous negotiation is sound.

Aim: Understand the fine-grained complexity of the following problem, depending on restrictions on  $\mathcal{N}$ : INPUT: A negotiation  $\mathcal{N} = (N, Proc, R, \delta)$ . OUTPUT: Is  $\mathcal{N}$  sound ? Soundness problem PSPACE-complete in general [DE '13].

Complexity of the soundness problem for classes of negotiations?

Theorem (DE '14)

Deciding soundness is in PTIME for deterministic negotiations.

This paper [EKMW '16]: explores the room between the two.

#### Theorem (EKMW '16)

Deciding soundness is in PTIME for acyclic weakly non-deterministic negotiations.

Main tool used in the proof: the Omitting Theorem.

### Theorem (EKMW '16)

It can be decided in PTIME if for a given deterministic, acyclic, and sound negotiation  $\mathcal{N}$  and two sets  $P \subseteq \mathbb{N} \times \mathbb{R}$  and  $B \subseteq \mathbb{N}$ , there is a successful run of  $\mathcal{N}$  containing P and omitting B.

General interest: characterize the important parts of a negotiation.

What happens if we drop restrictions in the previous results ? Dropping weak non-determinism:

Theorem (EKMW '16)

The soundness problem for acyclic negotiations is coNP-complete.

What happens if we drop restrictions in the previous results ? Dropping weak non-determinism:

Theorem (EKMW '16)

The soundness problem for acyclic negotiations is coNP-complete.

Dropping acyclicity for a milder constraint:

```
Theorem (EKMW '16)
```

The soundness problem for **det-acyclic** weakly non-deterministic negotiations is coNP-complete.

**Det-acyclicity**: deterministic processes are acyclic. Enough here to prevent cycles in actual runs.

## Det-acyclicity example

**Det-acyclicity** + Weak ND  $\implies$  no cycles in runs, Here not weakly ND.



$$\delta(n_{init}, a, p_2) = \{n_1, n_3\}$$



$$\delta(n_{init}, a, p_2) = \{n_1, n_3\}$$

$$\delta(n_1, a, p_2) = \{n_2, n_{fin}\}$$



$$\delta(n_{init}, a, p_2) = \{n_1, n_3\}$$

$$\delta(n_1, a, p_2) = \{n_2, n_{fin}\}$$

 $\delta(n_2, a, p_2) = \{n_1, n_3\}$ 



$$\delta(n_{init}, a, p_2) = \{n_1, n_3\}$$
$$\delta(n_1, a, p_2) = \{n_2, n_{fin}\}$$

$$o(n_2, a, p_2) = \{n_1, n_3\}$$

 $\delta(n_3, a, p_2) = \{n_2, n_{fin}\}$ 



$$\delta(n_{init}, a, p_2) = \{n_1, n_3\}$$
$$\delta(n_1, a, p_2) = \{n_2, n_{fin}\}$$
$$\delta(n_2, a, p_2) = \{n_1, n_3\}$$

 $\delta(n_3, a, p_2) = \{n_2, n_{fin}\}$ 



# Applications of sound negotations



#### Race Problem:

### **GIVEN**: a negotiation $\mathcal{N}$ , and two nodes n, m of $\mathcal{N}$ . **DECIDE**: can n and m be concurrently enabled ?

### **Race Problem: GIVEN**: a negotiation $\mathcal{N}$ , and two nodes n, m of $\mathcal{N}$ . **DECIDE**: can n and m be concurrently enabled ?

- standard question for concurrent systems
- inherently concurrent property, hard to work with linearizations

The race problem is PSPACE-complete in the general case and NP-complete for acyclic negotiations.

Determinism alone does not help:

```
Theorem (EKMW '16)
```

The race problem stays PSPACE-complete and NP-complete for deterministic and acyclic deterministic negotiations.

The race problem is PSPACE-complete in the general case and NP-complete for acyclic negotiations.

Determinism alone does not help:

```
Theorem (EKMW '16)
```

The race problem stays PSPACE-complete and NP-complete for deterministic and acyclic deterministic negotiations.

But determinism and soundness together help:

### Theorem (EKMW '16)

The race problem is

- *in PTIME for sound deterministic negotiations.*
- NLOGSPACE-complete for sound deterministic acyclic negotiations,

Application of negotiations: analyze the workflow of programs.

**Data-flows**: Petri-net-based modeling notation, widely used (Protos) [van der Aalst et al, '09].

Model the behaviour of programs or protocols acting on global variables via operations: alloc(x), read(x), write(x), dealloc(x).

📲 Protos D.' judalcalismi "active_papers", datacorrectness_caite/example.pail - [Main Process] 📃 🗇 🗵	
Ble Edit Algoment Yew Analysis Icols Window 1940	- 0 ×
[]C]웹위슈티아더에# 및 레프슬퍼한디어♥ & O 의분과 O 분경 페인터인 100~ - E 4 # 제15 특	
Process	Data
	• • • • • • • • • • • • • • • • • • •
p1 p3 p6	:::::/ <b>/</b> K b
	/™ <mark>™</mark> C
p2 0 p4 p5 0 p7	
[not pred(b)]	
Activity proporties 11	/ 🖳 g
General Description Instructions Data Applications Involved Extra Simulation	
RECE *R Main Process.a	
nnne 🔭 Main Process.c	r u
nnne 🔭 Main Process.e	
TEER TR Main Process.f	

Sound acyclic deterministic negotiations with variables ~ formalize data-flow problems from [van der Aalst et al, '09]:

- Well-defined behaviour: no concurrent operations on the same variable,
- No redundancy: allocated variables are used,
- Clean memory: allocated variables are deallocated.

Sound acyclic deterministic negotiations with variables ~ formalize data-flow problems from [van der Aalst et al, '09]:

- Well-defined behaviour: no concurrent operations on the same variable,
- No redundancy: allocated variables are used,
- Clean memory: allocated variables are deallocated.

### Theorem (EKMW '16)

All these properties can be checked in PTIME on data-flows.

Proof using the Omitting Theorem.

Exponential improvement on [van der Aalst et al, '09].

**Data-flow result**: Embeds typical specifications into a class of trace properties easy to decide (PTIME).

All these properties can be described by fixed-size automata with simple structure.

Can we generalize this ?

**Data-flow result**: Embeds typical specifications into a class of trace properties easy to decide (PTIME).

All these properties can be described by fixed-size automata with simple structure.

Can we generalize this ?

Theorem (Unpublished)

There is a property P specified by a 6-state automaton such that checking P for a sound acyclic deterministic negotiation is **NP-complete**.

We get a fine-grained description of the difficulty of trace property checking.

## Conclusion

- The negotiation model provides new insights on what makes communicating finite-state processes hard to analyze.
- Soundness is a key property that can decrease the complexity of checking other properties.
- Detailed picture of complexities of property checking.
- Applications to the static analysis of workflow processes.

## Conclusion

- The negotiation model provides new insights on what makes communicating finite-state processes hard to analyze.
- Soundness is a key property that can decrease the complexity of checking other properties.
- Detailed picture of complexities of property checking.
- Applications to the static analysis of workflow processes.

#### Open problem

Soundness for Weakly non-deterministic negotiations: PSPACE-complete ? coNP-complete ?.