Regular Sensing

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• Deterministic automata scanning the environment and checking a specification.

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- Input: S set of signals, $\Sigma = 2^{S}$ alphabet of the automaton.

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- Input: S set of signals, $\Sigma = 2^{S}$ alphabet of the automaton.
- New approach: Reading signals via sensors costs energy.
- Goal: Minimize the energy consumption in an average run.

Deterministic automaton \mathcal{A} on $\{00, 01, 10, 11\}$.



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$$scost(\mathcal{A}) = \lim_{m \to \infty} |\Sigma|^{-m} \sum_{w:|w|=m} scost(w)$$

Computing the cost

Remarks on the definition of sensing cost:

- Initial state plays a role but not acceptance condition.
- Works on finite or infinite words.
- Cost is deduced from the transition structure.
- Signals can be weighted with different probabilities or sensing cost.

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Theorem

Sensing cost of an automaton is computable in polynomial time.

By computing the stationary distribution of the induced Markov chain.

Back to the example



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Limitation of the probabilistic model: Safety or Reachability automata always have cost 0. Only ergodic components matter in the long run.

Sensing cost of a regular language

Sensing cost as a measure of complexity of regular languages.

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On finite words, the optimal sensing cost of a language is always reached by its minimal automaton.

 \rightarrow Sensing as a complexity measure is not interesting on finite words, coincides with size.

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Theorem

The sensing cost of an ω -regular language is the one of its residual automaton.

Corollary

Computing the sensing cost of an ω -regular language is in **PTime**.

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- Idea of the proof of general interest: one can "ignore" the input for arbitrary long periods and still recognize the language.

Conclusion

Future work:

- Precise study of the trade-off between different complexity measures
- Generalize to transducers
- Modify the definition to account for transient states