



Aeroacoustic computations with a new CFD solver based on the Lattice Boltzmann Method

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LaBS project

LaBS Consortium

Three industrial companies and two scientific laboratories, software's co-owner and developers, leading, supporting and validating LaBS.



A collaborative project with strong partnerships

« LaBS Consortium » collaborates with partners whose scientific expertise enables building mathematical models and establishing simulation best-practices for several application domains.

With the support of competitiveness clusters :



Financial support from FUI8 :



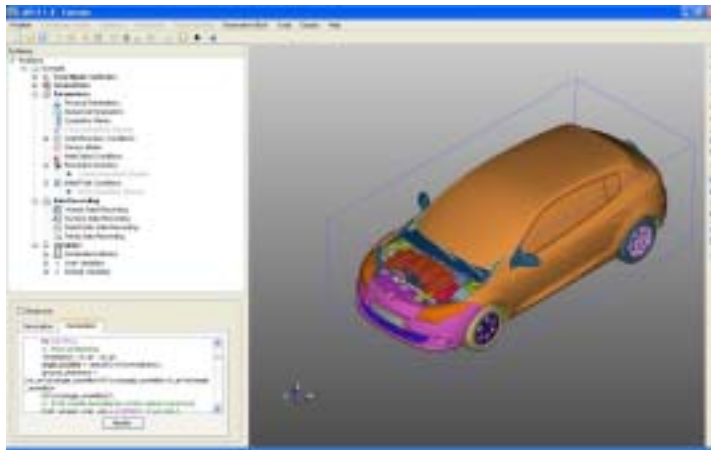
Period : 2009-2013



LaBS software

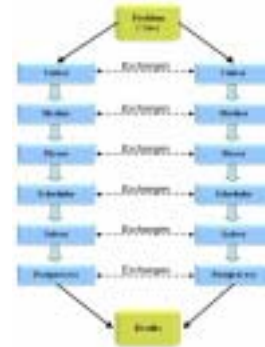
- Developed from scratch
 - a GUI for simulation setup
 - a parallel solver, including the volumetric mesher

Surface meshes
(e.g. : stl files)



GUI

Problem file :
*.labs



Parallel solver

Results files
- Paraview format
- Ensight format

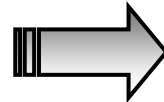
LaBS software



Lattice Boltzmann Method

Statistical mechanics

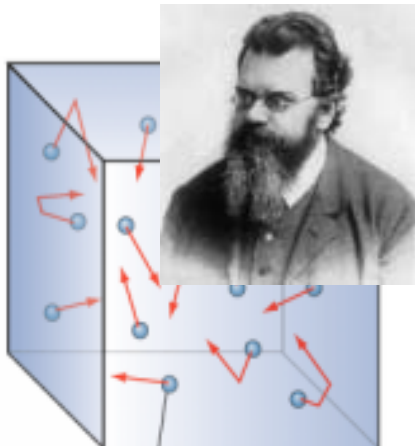
- Boltzmann equation
- Particles
 - Kinetic energy
 - Momentum
 - Shocks
 - Mean free path



Chapman-Enskog
theoretical
expansion

Continuum mechanics

- Navier-Stokes equations
- Continuous media
 - Temperature
 - Pressure
 - Density
 - Viscosity



Lattice Boltzmann method



- Particle velocity discretization (finite discrete velocity set for particles instead of continuous particle velocity)
- Space and time discretizations of the discrete velocity Boltzmann equation

Chapman-Enskog theoretical expansion →
Navier-Stokes equations





Main numerical issues

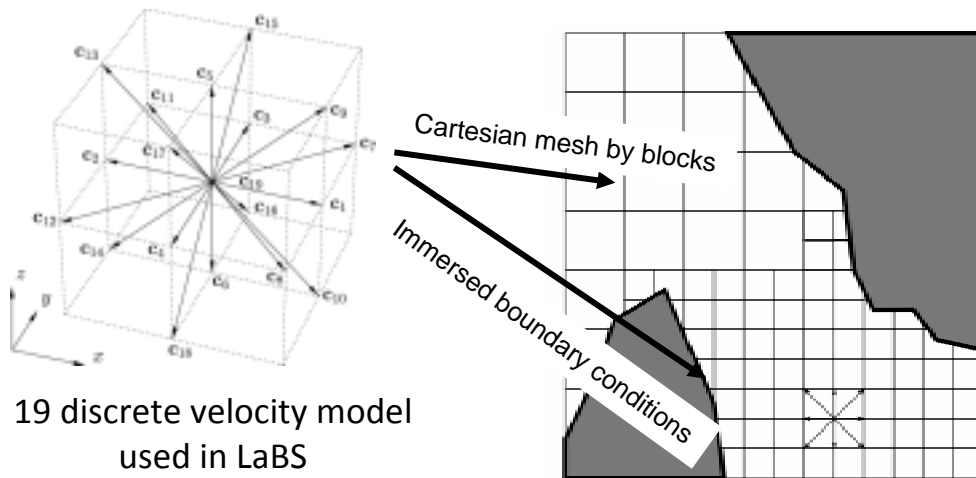
Calculation of distribution functions on a cartesian mesh

$$f_\alpha(\vec{x} + \vec{c}_\alpha \Delta t, t + \Delta t) = \left(1 - \frac{1}{\tau}\right) f_\alpha(\vec{x}, t) + \frac{1}{\tau} f_\alpha^{eq}(\rho(\vec{x}, t), u(\vec{x}, t))$$

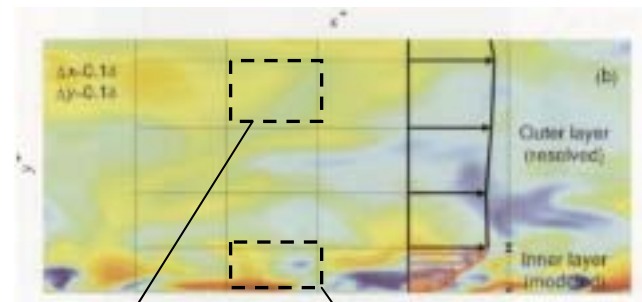
Standard fluid mechanics variables on the same mesh

$$\begin{cases} \rho(\vec{x}, t) = \sum_\alpha f_\alpha(\vec{x}, t) \\ \rho(\vec{x}, t) \vec{u}(\vec{x}, t) = \sum_\alpha \vec{c}_\alpha f_\alpha(\vec{x}, t) \\ p(\vec{x}, t) = c_s^2 \rho(\vec{x}, t) \end{cases}$$

$$c_s = \frac{1}{\sqrt{3}} \frac{\Delta x}{\Delta t} \quad v = c_s^2 \left(\tau - \frac{\Delta t}{2} \right)$$



Spatial discretization \rightarrow unresolved turbulent scales



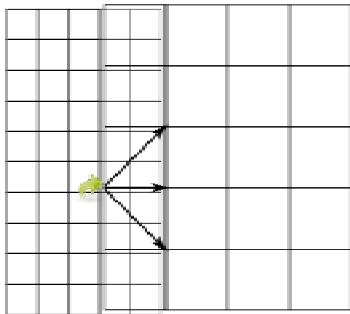
Sub-grid turbulence model

Wall model if too coarse mesh near walls

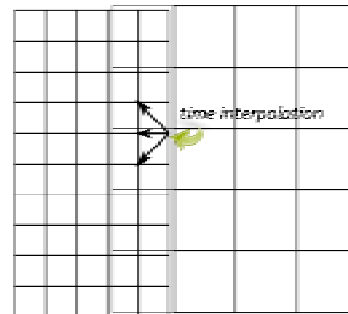


Mesh refinement

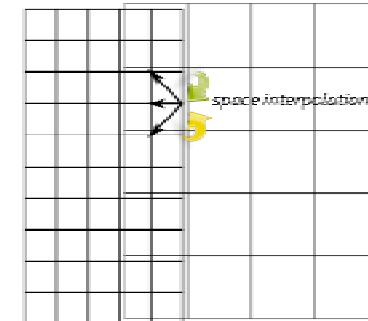
- ❑ AMR-like mesh : successive refinement of the volume mesh (M. J. Berger and P. Colella, "Local adaptive mesh refinement for shock hydrodynamics," J. Comp. Phys, 82:64-84, 1989)
- ❑ In LaBS : vertex-centered formulation → coarse mesh nodes are coincident with fine mesh nodes
- ❑ Partial mesh overlapping approach for data exchanges between refinement blocks
- ❑ Need for rescaling of distribution functions (O. Fillipova and D. Hänel. Grid refinement for lattice-BGK models. J. Comput. Phys., 147(1):219–228, 1998)



Fine to coarse mesh transfer

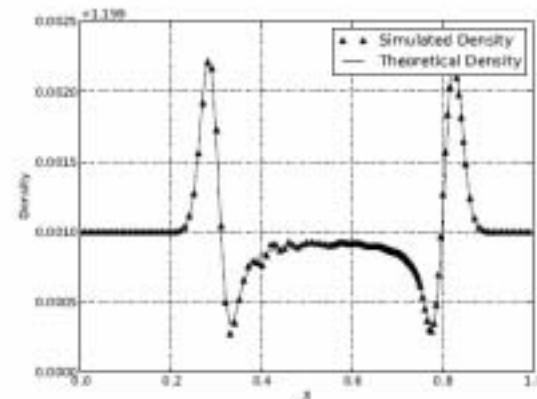
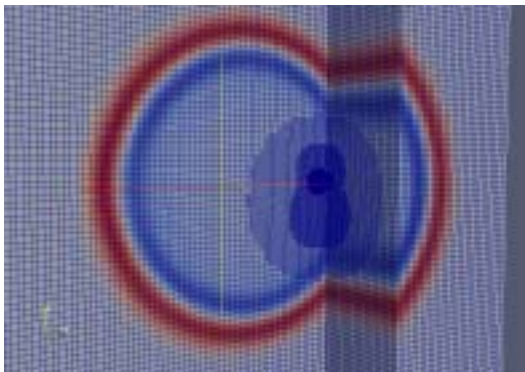


Coarse to fine mesh transfer for coincident fine nodes



Coarse to fine mesh transfer for non-coincident fine nodes

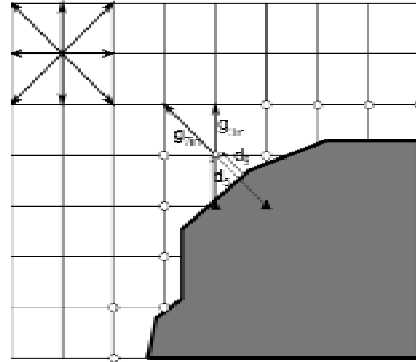
- ❑ Example of validation for an acoustic pulse propagation in a multi-resolution grid





Immersed boundary condition

- ❑ Full separation between the octree volumetric mesh and the surface mesh (triangles)
- ❑ Immersed boundary algorithm must be developed. Several available approaches in literature deduced from the original Navier-Stokes techniques (Peskin, 1977). See for example : Z.-G. Feng and E.E. Michaelides. *The Immersed Boundary-Lattice Boltzmann Method for Solving Fluid-Particles Interaction Problems. J. Comput. Phys., 195(2):602-628, 2004*



Distribution functions associated with velocity #7 and velocity #3 in its example can not calculated by the collision / propagation LBM algorithm because neighbor nodes are inside the solid

- ❑ In LaBS : vertex-based formulation based on the reconstruction of the distribution functions from the macroscopic data (pressure, velocity and velocity gradients) :

$$f_{\alpha}(\vec{x}, t) = f_{\alpha}^{eq}(\vec{x}, t) + f_{\alpha}^{neq}(\vec{x}, t) = \underbrace{\omega_{\alpha} \rho \left(1 + \frac{c_{\alpha,i} u_i}{c_s^2} + \frac{u_i u_j (c_{\alpha,i} c_{\alpha,j} - c_s^2 \delta_{ij})}{2c_s^4} \right)}_{\rho, u_i \text{ Spatial interpolation}} + \underbrace{\tau \frac{\omega_{\alpha} \rho}{c_s^2} \sum_{ij} (c_{\alpha,i} c_{\alpha,j} - c_s^2 \delta_{ij}) S_{ij}}_{\text{Calculation of velocity gradients by off-centered finite difference scheme}} \quad (\text{Chapman-Enskog expansion})$$

$$S_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

Similar to the model described in : J.C.G. Verschaeve and B. Müller, "A curved no-slip boundary condition for the lattice Boltzmann method", J. Comput. Physics, 2010, 229(19), pp.6781-6803

Calculation of velocity gradients by off-centered finite difference scheme



Turbulence model

- ❑ Sub-grid turbulent vortices must be modeled by a turbulence model
- ❑ Lattice Boltzmann is a native unsteady algorithm with very low numerical dissipation : it is well adapted to Large Eddy Simulation approach
- ❑ Large scales that ensure turbulent mixing are directly calculated, only the dissipative effect of small turbulent scales must be added.
- ❑ Two sub-grid models are implemented in LaBS :
 - ❑ Shear-Improved Smagorinsky Model (SISM)
 - ❑ The Approximate Deconvolution Model (ADM)
- ❑ The shear-improved Smagorinsky model is a sub-grid turbulent viscosity model :
 - ❑ *E. Leveque, F. Toschi, L. Shao and J.-P. Bertoglio, Shear-Improved Smagorinsky Model for Large-Eddy Simulation of Wall-Bounded Turbulent Flows, [Journal of Fluid Mechanics](#) 2007, vol. 570, pp. 491-502*

$$f_\alpha(\vec{x} + \vec{c}_\alpha \Delta t, t + \Delta t) = \left(1 - \frac{1}{\tau}\right) f_\alpha(\vec{x}, t) + \frac{1}{\tau} f_\alpha^{eq}(\rho(\vec{x}, t), u(\vec{x}, t)) \quad \longrightarrow \quad \nu = c_s^2 \left(\tau - \frac{\Delta t}{2}\right)$$

$$\nu_{eff} = \nu + \nu_T \quad \longrightarrow \quad \tau_{eff}$$

$$\nu_T = (C_s \Delta)^2 \cdot (|\mathbb{S}| - |\langle \mathbb{S} \rangle|)$$

$$\mathbb{S}_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

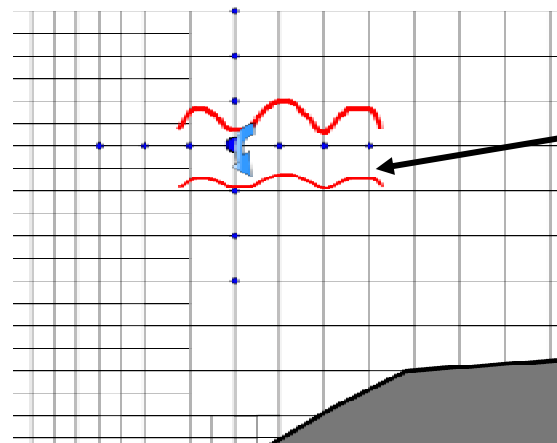
$$|\mathbb{S}| \equiv \sqrt{2 \sum_{i,j} \mathbb{S}_{ij} \mathbb{S}_{ij}}$$

“< >” is low-pass filtering based on an exponentially-weighted moving time average



Turbulence model

- ❑ The Approximate Deconvolution Model (ADM) is not a turbulent viscosity model : dissipation is added through selective spatial filtering
 - ❑ *Navier-Stokes* : Stolz S, Adams NA, Kleiser L. An approximate deconvolution model for large-eddy simulation with application to incompressible wall-bounded flows. *Phys Fluids* 2001;13:997–1015
- ❑ Validation of ADM for LES simulations have been done with Navier-Stokes solver (Bogey, C. & Bailly, C., 2006, Computation of a high Reynolds number jet and its radiated noise using large eddy simulation based on explicit filtering, *Computer & Fluids*, 35(10), 1344-1358) and LBM solver (Lattice Boltzmann : O. Malaspinas and P.Sagaut, Advanced large-eddy simulation for lattice Boltzmann methods: The approximate deconvolution model *Phys. Fluids* 23, 105103, 2011)
- ❑ LBM algorithm is unchanged compared to the DNS case : only an explicit filtering step is added



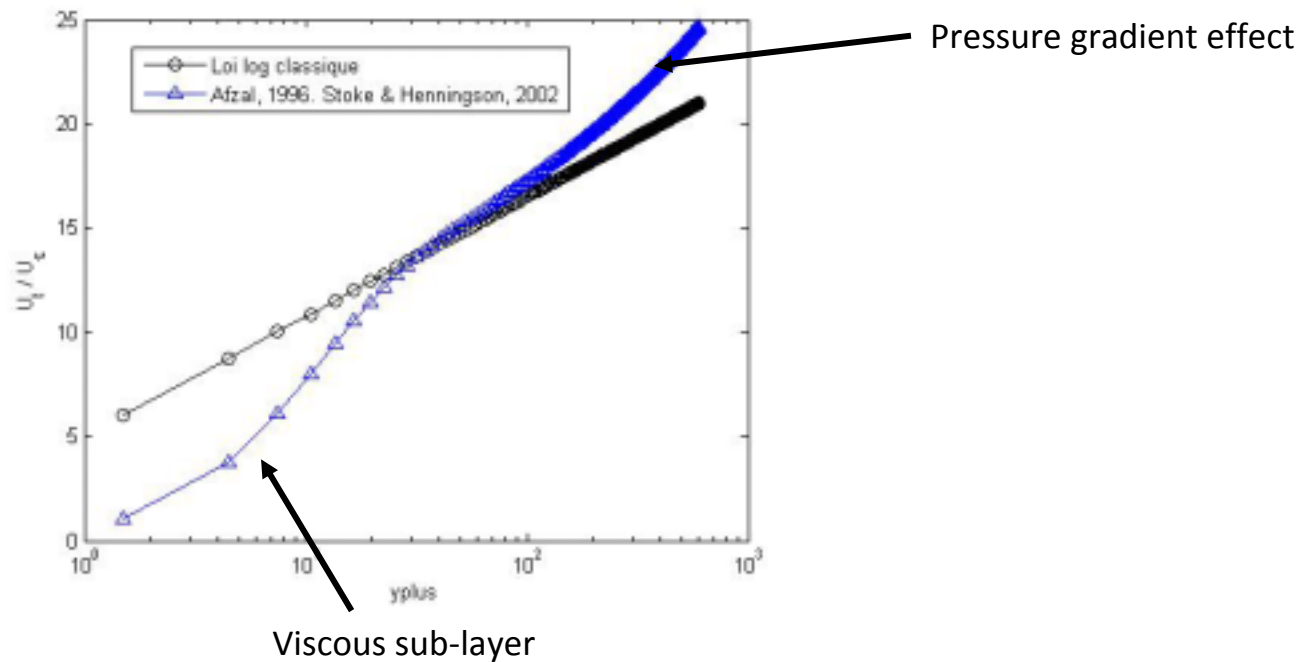
Small scales are damped without affecting the largest scales

- ❑ In LaBS : 7 point stencil is used : D. Ricot, S. Marié, P. Sagaut, C. Bailly Lattice Boltzmann method with selective viscosity filter, *Journal of Computational Physics* 228 (2009) 4478–4490



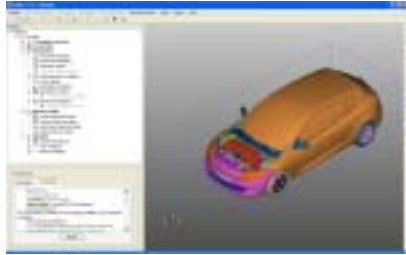
Turbulence model

- Both Shear-Improved Smagorinsky model and Approximate deconvolution model can be associated with a wall law model
- The wall law is a lag-law with adverse pressure gradient effects proposed by Afzal : N. Afzal. Wake layer in a turbulent boundary layer with pressure gradient: a new approach. In IUTAM Symposium on Asymptotic Methods for Turbulent Shear flows at High Reynolds Numbers. K., G., ed., Kluwer Academic Publishers, 1996, 95-118

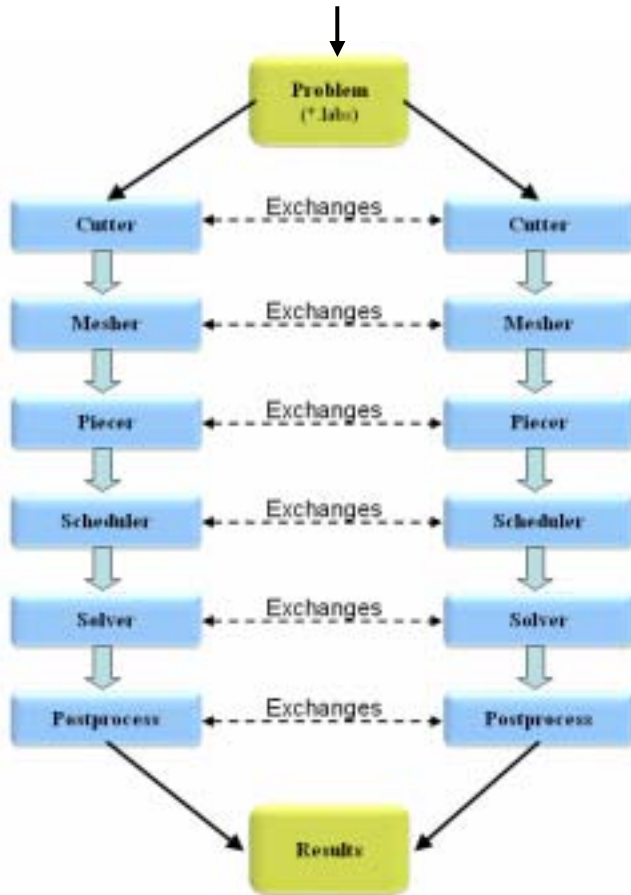




Solver architecture



Simulation setup : dedicated GUI, with script capacities



Load balancing optimization

Mesh and data structure generation

Computation scheduling

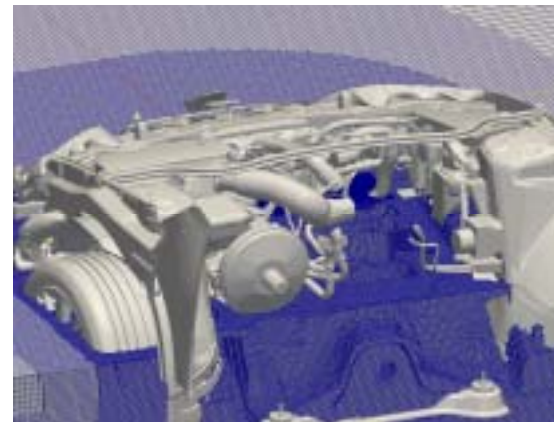
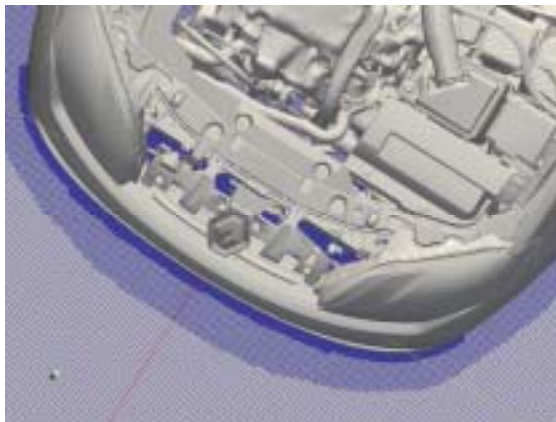
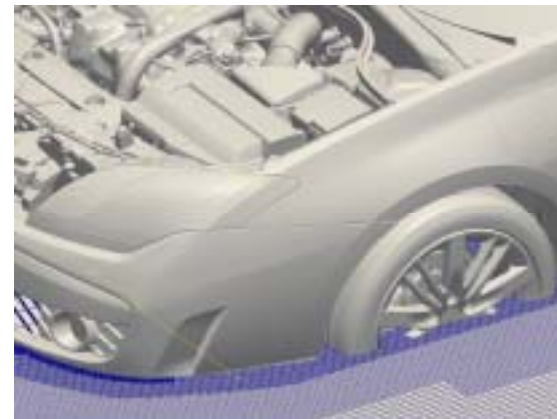
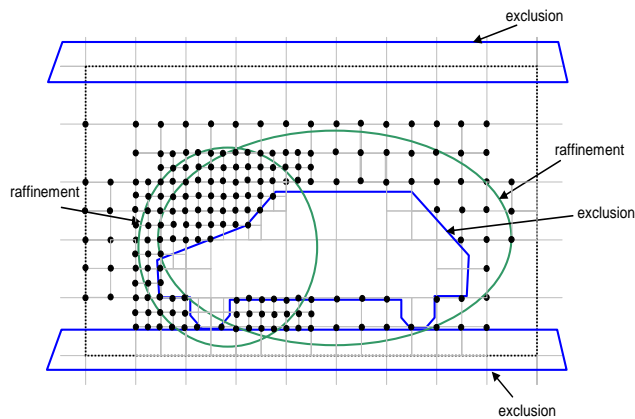
Time-step loop

Merge / convert results files



Volumetric mesh

- ❑ Based on efficient octree mesher
- ❑ Interior of surface meshes are excluded, without limitation in term of shape, number of surfaces, and overlapping regions





Academic validations : turbulent channel flow

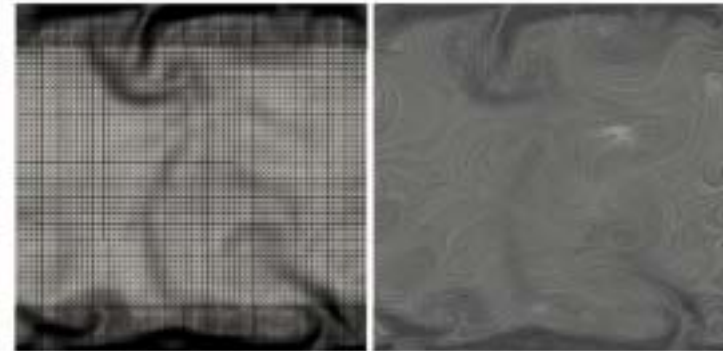
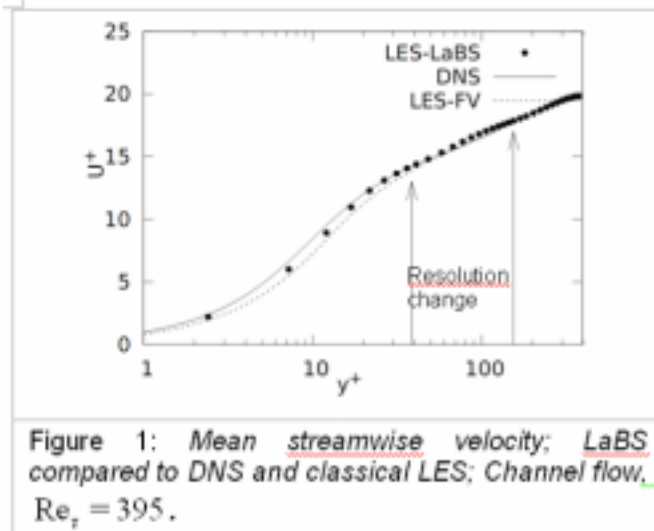
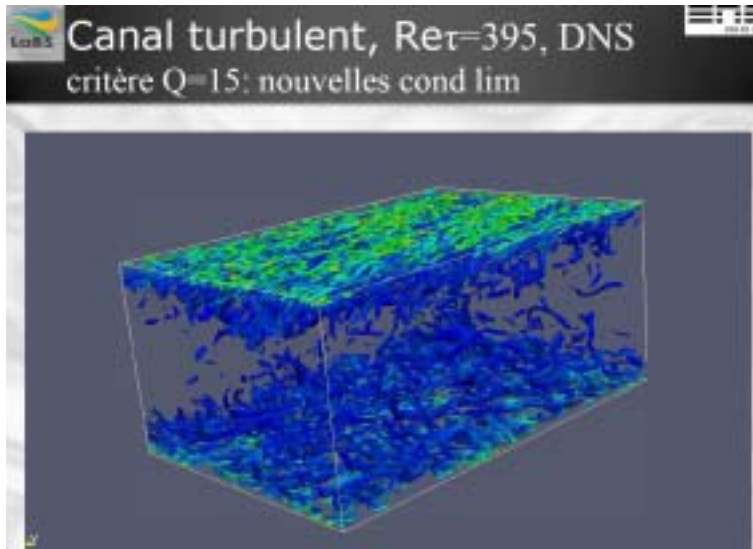
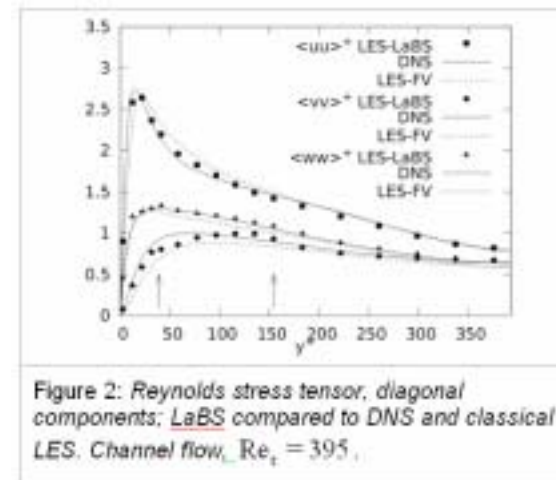


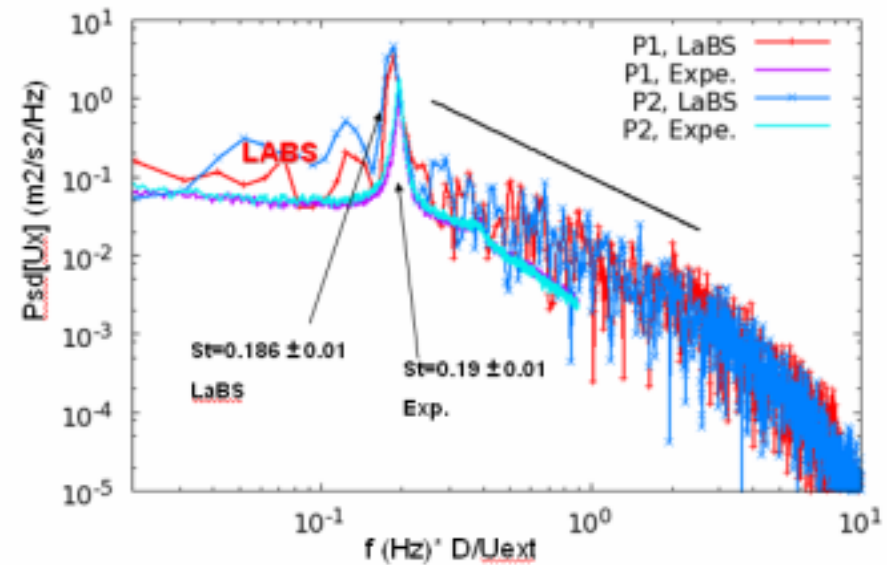
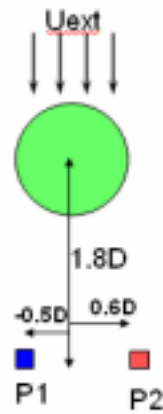
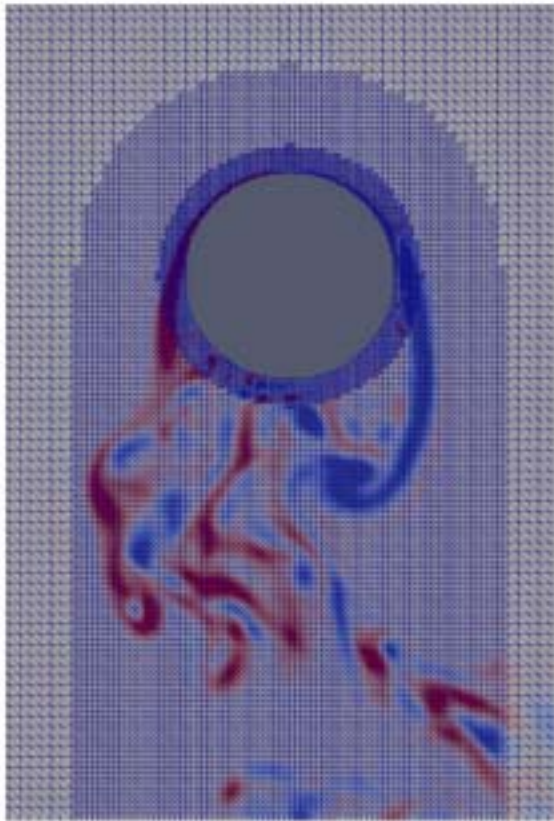
Figure 1: DNS of a turbulent plane-channel flow at $Re_\tau = 180$ by the Lattice-Boltzmann





Academic validations : cylinder wake

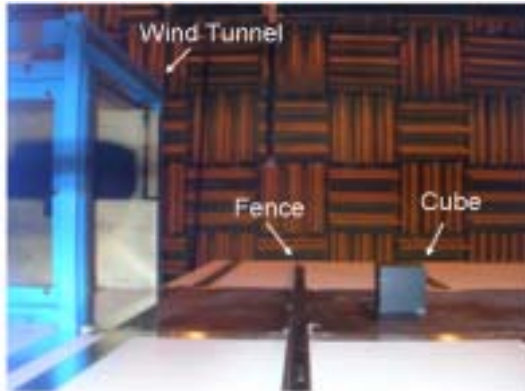
- Turbulent flow behind a circular cylinder, $Re_D = 47000$



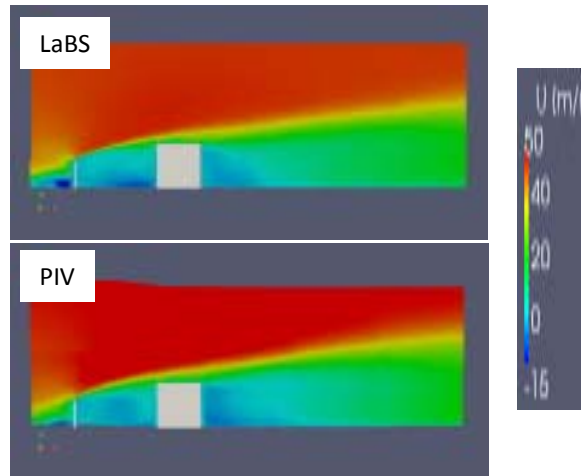


Validation on simple case : Fence-cube configuration

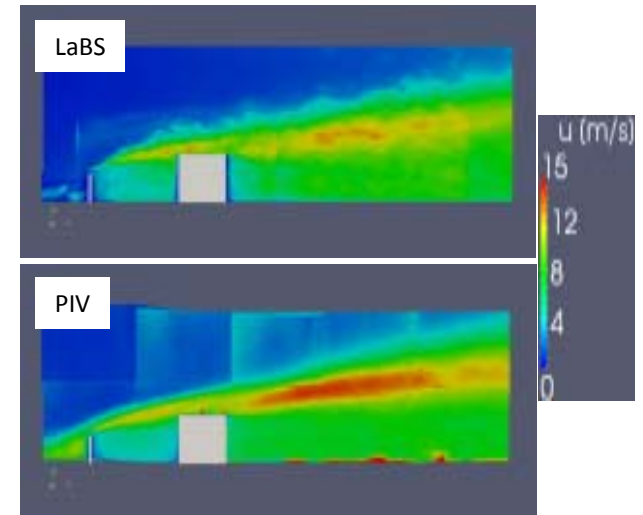
- ❑ Experimental database from a previous Predit project (MIMOSA) : measurements at LMFA / Ecole Centrale Lyon
- ❑ A cube (size 10 cm) mounted on a plane is placed behind a fence : PIV, hot-wire, unsteady wall pressure measurements
- ❑ $U_0=45$ m/s, 20 millions mesh nodes, 350000 time-steps (around 0.78 sec of physical time)



Mean streamwise velocity



Fluctuating streamwise velocity

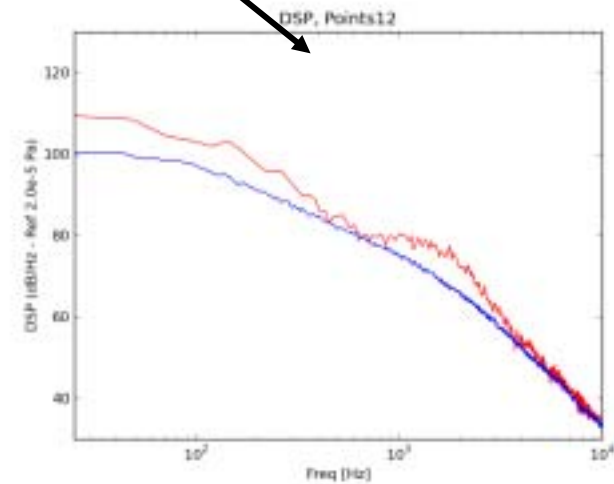
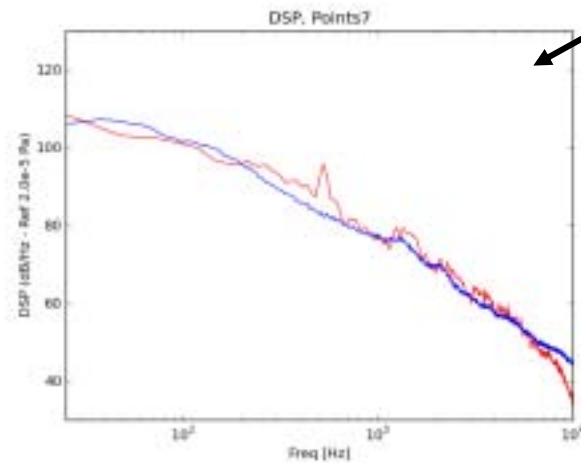
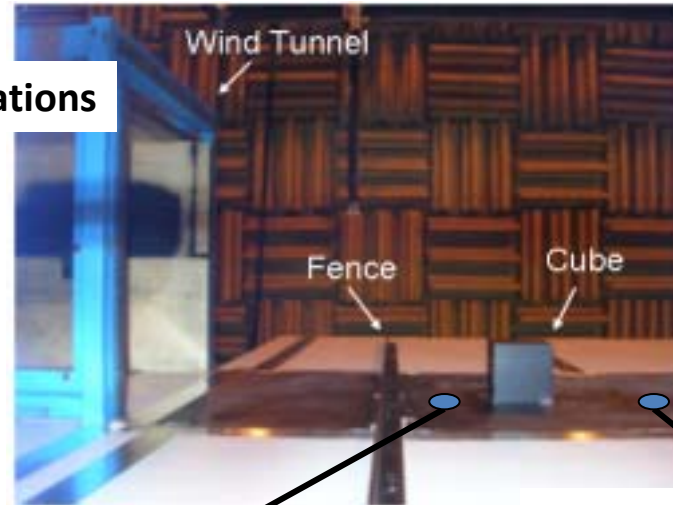




Validation on simple case : Fence-cube configuration



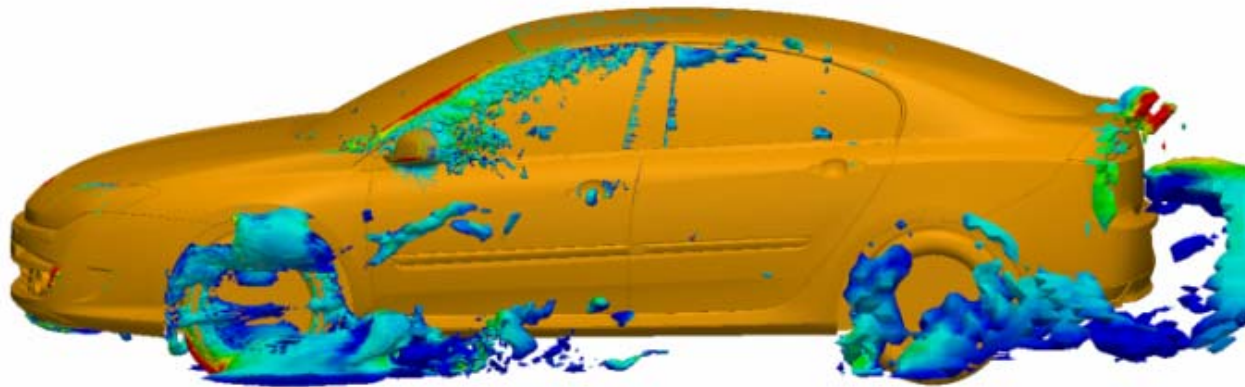
Wall pressure fluctuations



— LaBS
— Measurements



Validation on vehicles



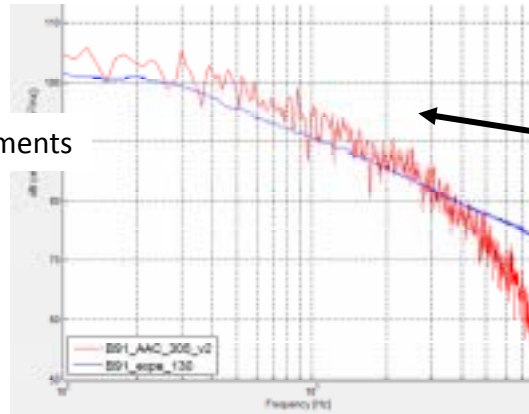
- Full scale vehicle simulation
- 10 levels of refinement, around 30 millions mesh nodes, 300 000 time-steps
- $U_0 = 44.4$ m/s
- Wall Law LES (Approximate Deconvolution Model)



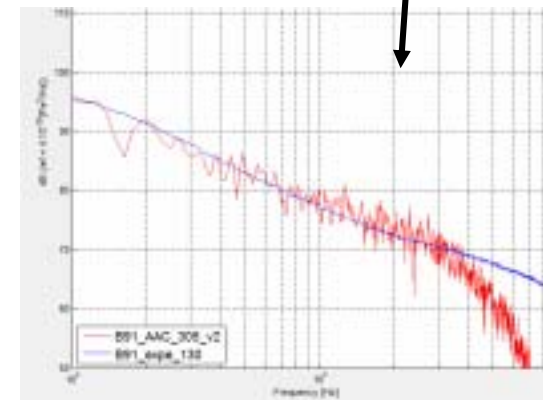
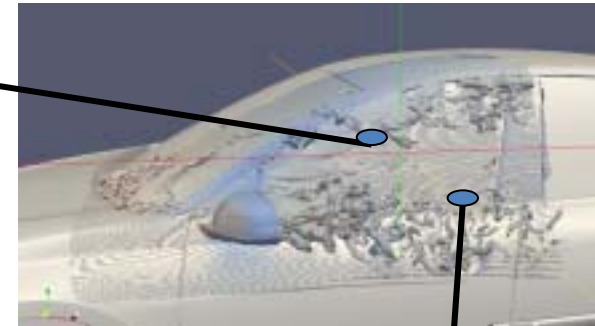
Validation on vehicles



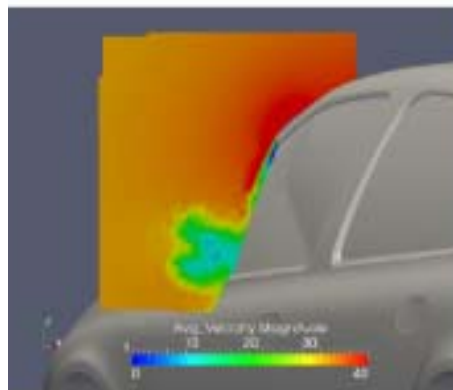
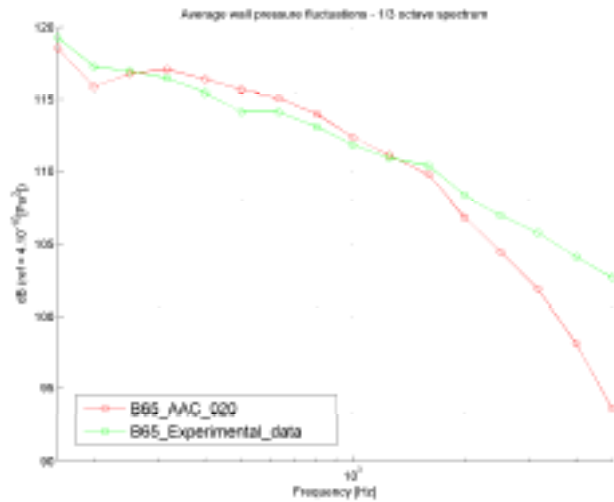
— LaBS
— Measurements



Laguna case : fine band spectra



Clio case : third-octave band spectra, averaged on the whole surface of the side window

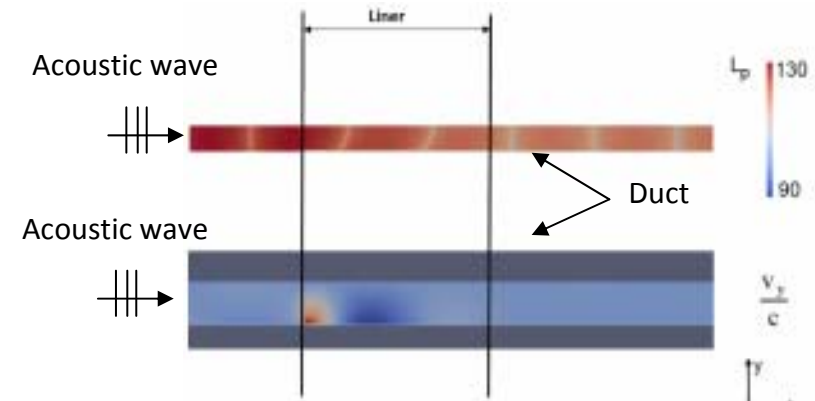




Innovative models : acoustic impedance and porous media

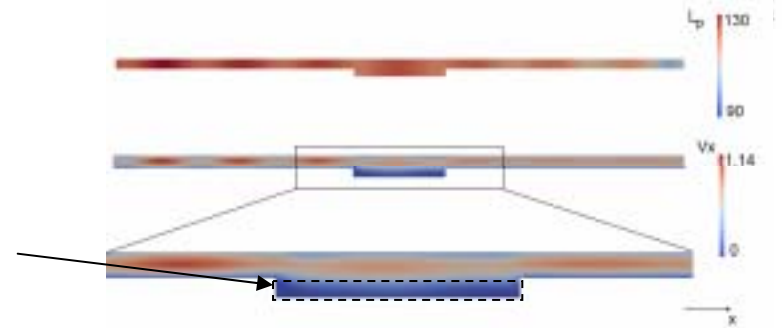


- Development of a time-domain locally reactive impedance

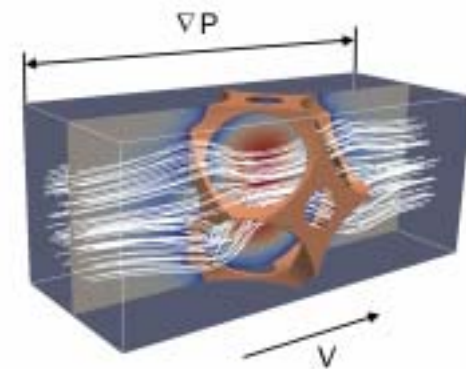


- Development of non-locally reactive porous materials
 - Porous materials is represented by a volumetric mesh
 - Darcy law (resistivity) can be applied on this mesh node to model low-frequency absorbing behavior

Volumetric porous region



- Airflow resistivity characterization
 - Direct « measurement » of the air flow resistivity of a micro-structure of arbitrary complexity



- ❑ Development of a general framework for moving solid models
 - ❑ Moving solid are embedded in a moving mesh
 - ❑ Displacement of mesh / solid is taken into account through the ALE (Arbitrary-Lagrangian Eulerian) model : at each time-step the previous data are interpolated on the mesh at its new position
 - ❑ Fixed / mobile mesh data exchanges are treated with Chimera approach (overlapping grid)
- ❑ Rotating solids are first developed in LaBS

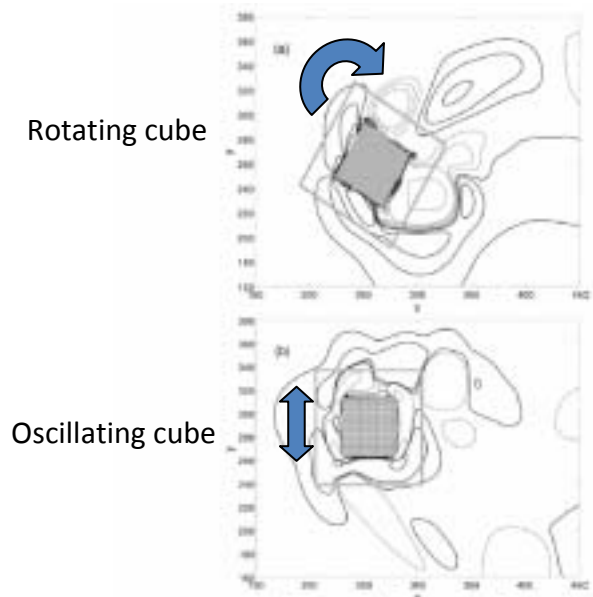
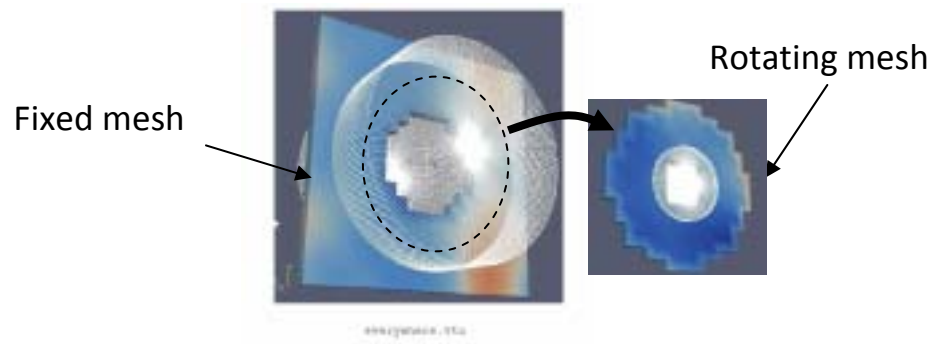
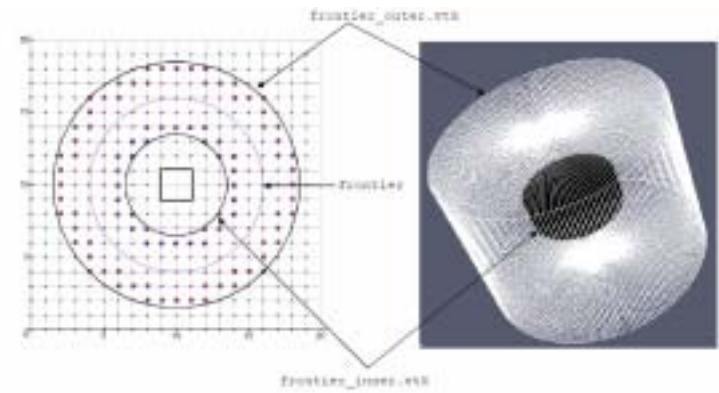


Figure 19: Isocontours of the Weiss criteria (vorticity in dotted lines) of the flow around a moving two-dimensional square cylinder, immersed in a Poiseuille Flow at $Re=70$. The laws of motion considered are (a) uniform rotation and (b) transverse harmonic motion.





Conclusions

- ❑ New CFD solver based on Lattice Boltzmann method
 - ❑ With strong scientific background and careful validation on each application fields
 - ❑ Good results on academic cases
 - ❑ Satisfactory results on aeroacoustic automotive cases
 - ❑ Currently running on several hundreds of CPU
- ❑ General CFD simulations can be done
 - ❑ DNS (academic cases)
 - ❑ LES (with two models : SISM and ADM)
 - ❑ WL-LES (Wall Law LES)
- ❑ Aeroacoustic is the first application target
 - ❑ Wall pressure fluctuation
 - ❑ Duct aeroacoustic (under validation)
 - ❑ High-lift airfoil noise generation (under validation)
 - ❑ Development of advanced acoustic models (time-domain impedance, porous materials,...)
- ❑ LaBS will be commercially available in 2013
 - ❑ Distributed by CS
 - ❑ Offer will comprise GUI / solver license and advanced support
 - ❑ CPU-on-Demand solution
 - ❑ License will include access to the open source scientific module that contains all physical models. Advanced users will be able to integrate their own LBM / turbulence /... models.

