

How much does exactness cost?*

On polynomial and integer matrix computations

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*SIAM Conference on Applied Linear Algebra, July 16, 2003, Williamsburg.

Problem:

Study of the **complexity** of fundamental problems in **exact** linear algebra over $K[x]$ and \mathbb{Z} .

- ▷ Worst case complexity;
- ▷ Time complexity *i.e.* fastest algorithms;
- ▷ Up to logarithmic factors, soft “ O ” notation: $\tilde{O}(f) = f^{1+o(1)}$;
- ▷ Deterministic or randomized algorithms.

Models of computation/matrix domains.

Algebraic complexity,

matrices in $K^{n \times n}$ with K a commutative field,

arithmetic operations $+$, \times , $/$ in K .

versus

$\hookrightarrow K[x]^{n \times n}$, arithmetic operations $+$, \times , $/$ in K .

\hookrightarrow Bit complexity,

$\mathbb{Z}^{n \times n}$, bit operations.

Motivations.

- Complexity estimates with “concrete” entry domains,
- Better understanding of linear algebra under bit complexity models,
- Improved algorithms for exact (or accurate) results.

Organization of the talk

I - Algebraic *versus* bit complexity.

II - Reductions between problems and target complexity.

III - Polynomial matrix computations.

IV - Integer matrix computations.

Conclusion

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Algebraic complexity over K

Equivalence to **matrix multiplication** (*straight-line*)

Matrix multiplication $n \times n$
 $A \times B$

n^ω , n^3 ou $n^{2.376}$

Determinant, inversion,
rank, characteristic polynomial,
Frobenius form, QR decomposition...

RAM algorithms in $O^\sim(n^\omega)$

- [Strassen 69, Bunch & Hopcroft 74] $\text{Det} \preceq \text{MM}$
- [Strassen 73, Baur & Strassen 83] $\text{MM} \preceq \text{Det}$

$\hookrightarrow \text{MM} \preceq \text{Det} \preceq \text{MM}$

$K[x]$ or **Bit complexity**

Inputs and outputs have a **size** or a **precision**.

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$\|A\| = \max_{i,j} |a_{i,j}|$ (or d).

◦ $A \in \mathbb{Z}^{n \times n}$: $\text{size}(\det A) = O(n \log \|A\|)$.

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◦ $A \in \mathbb{Z}^{n \times n}$: $O(\log \text{cond}(A)) = O(n \log \|A\|)$ bits for accuracy.

Impact of data size?

Ex. Determinant computation/Output size: nd or $O^\sim(n \log \|A\|)$,

Evaluation/interpolation scheme or Chinese remaindering
or $O^\sim(n \log \|A\|)$ bits *a priori*:

↑
 n^ω
↓



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Complexity estimates:

$$O^\sim(n^\omega \times nd) = O^\sim(n^{\omega+1}d),$$
$$O^\sim(n^{\omega+1} \log \|A\|).$$

Fundamentals of symbolic dense linear algebra over $K[x]$ or \mathbb{Z} :

System solution

[Moenck & Carter 79, Dixon 82] Hensel lifting

$\tilde{O}(n^\omega \log \|A\|)$

Las Vegas

Determinant, inversion, nullspace. . .

[Edmonds 67, Bareiss 69, Moenck & Carter 79]

Fraction-free, Chinese remaindering, Newton-Hensel lifting

$\tilde{O}(n \cdot n^\omega \log \|A\|)$

Deterministic

Frobenius form (minimum, characteristic polynomial)

[Giesbrecht 93, Giesbrecht & Storjohann 02]

Danilevsky elimination, Keller-Gehrig, Chinese remaindering

$\tilde{O}(n \cdot n^\omega \log \|A\|)$

Las Vegas

Hermite and Smith forms, (diophantine systems)

[Kannan & Bachem 79, Domich 85, Giesbrecht 95, Storjohann 96-00]

Unimodular eliminations

$\tilde{O}(n \cdot n^\omega \log \|A\|)$

Deterministic

Bit complexity \preceq algebraic complexity \times output size

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Is this bound pessimistic?

$$\text{Bit complexity} \preceq \text{algebraic complexity} \times \text{output size}$$

Is this bound pessimistic?

Clue. The output length may not be necessary *a priori*, i.e. at the beginning of the computation, but only at its very end.

Change of the situation: **reduced overhead or no overhead**

Theorem. The determinant and the Smith normal form of $A \in \mathbb{Z}^{n \times n}$ can be computed by a Monte Carlo algorithm in $O(\sqrt{n} \cdot n^3 \log^{1.5} \|A\|)$ bit operations.

- Search and structured rank- k perturbations for the characteristic polynomial of a sparse matrix;
- Search and dense integer rank- k perturbations for the Smith form of an integer matrix.

[Eberly, Giesbrecht & Villard 00, Kaltofen 92/00, Villard 00]

Theorem. The determinant and the Hermite normal form of $A \in \mathbb{K}[x]^{n \times n}$ can be computed in $O(n^3 d^2)$ operations in \mathbb{K} .

- Column reduction [Mulders & Storjohann 00].

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$A \in \mathbf{K}[x]^{n \times n}$ or $A \in \mathbf{Z}^{n \times n}$

Target problems: determinant, characteristic polynomial, nullspace, rank, inversion, Frobenius, Hermite, Smith normal form and associated transform, minimal bases, matrix gcd . . .

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Target complexity estimate?

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Target complexity estimate?

Nota. Known algebraic complexity **reduction techniques** between problems may not be preserved in bit complexity.

Example.

▷ Over K , **Determinant in n^ω** \implies **Inversion in n^ω**

Derivative inequality [Linnainmaa 76, Baur et Strassen 83, Morgenstern 85].

$$a_{j,i}^* = \frac{\partial \det A}{\partial a_{i,j}}.$$

Example.

▷ Over \mathbf{K} , **Determinant** in $n^\omega \implies$ **Inversion** in n^ω

Derivative inequality [Linnainmaa 76, Baur et Strassen 83, Morgenstern 85].

$$a_{j,i}^* = \frac{\partial \det A}{\partial a_{i,j}}.$$

▷ Over \mathbf{Z} , x and y vectors with constant entries, c a large constant,

$\phi = c \cdot x^t \cdot y$ takes $O(n + \log |c|)$ bit operations,

$[\partial \phi / \partial x_i] = c \cdot y$ takes $O(n \log |c|)$ bit operations.

~> Link with polynomial or integer matrix multiplication?

Theorem. If there is a straight-line program of length $D(n, d)$ over K which computes the $(d+1)$ **st coefficient of the determinant** of an $n \times n$ matrix of degree d , then there is a straight-line program of length no more than $8D(n, d)$ which **multiplies two $n \times n$ matrices of degree d** [Giorgi, Jeannerod & Villard 03].

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C.f. the relation between estimating error bounds (condition estimation) and testing matrix multiplication

[Demmel, Diament & Malajovich 01].

Candidate target complexity estimate:

$$\text{MM}(n, \log \|A\|) + \text{input/output size}$$

Which integer (resp. polynomial) exact matrix problems can be solved with roughly the same number of arithmetic operations than integer (resp. polynomial) matrix multiplication plus the input/output size?

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$A \in \mathbf{K}[x]^{n \times n}$ of degree d , $\text{MM}(n, d) = \tilde{O}(n^{\omega+1}d)$ or $O(n^3d^2)$.

▷ **Inversion**

(generic inputs) [Jeannerod & Villard 02]

▷ **Determinant**

[Storjohann 02]

▷ **Column reduction**

[Giorgi, Jeannerod & Villard 03]

III-1/ Matrix inversion

Size of the output: $n^2 \times n(d + 1) = O(n^3d)$ elements in K .

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Rich literature on the subject,

[Gauss, Hensel, Hermite/Lagrange, Le Verrier . . .]

\rightsquigarrow Algorithms in $O(\mathit{nd} \times n^3)$ or $O(\mathit{nd} \times n^\omega)$.

Essentially optimal computation of the inverse

[Jeannerod & Villard 02]

Theorem. Except on a subvariety, the inverse of $A \in \mathbb{K}[x]^{n \times n}$ of degree d can be computed in $\tilde{O}(n^3 d)$ operations in \mathbb{K} .

Diagonalization in $\log_2(n)$ steps

$$A = \begin{bmatrix} * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \end{bmatrix}$$

Diagonalization in $\log_2(n)$ steps

$$BA = \begin{bmatrix} * & * & * & * & & & & \\ * & * & * & * & & & & \\ * & * & * & * & & & & \\ * & * & * & * & & & & \\ & & & & * & * & * & * \\ & & & & * & * & * & * \\ & & & & * & * & * & * \\ & & & & * & * & * & * \end{bmatrix}$$

Diagonalization in $\log_2(n)$ steps

$$B'BA = \begin{bmatrix} * & * & & & & & & & & \\ * & * & & & & & & & & \\ & & * & * & & & & & & \\ & & * & * & & & & & & \\ & & & & * & * & & & & \\ & & & & * & * & & & & \\ & & & & & & * & * & & \\ & & & & & & * & * & & \\ & & & & & & & & * & * \\ & & & & & & & & * & * \end{bmatrix}$$

Diagonalization in $\log_2(n)$ steps

$$B''B'BA = \begin{bmatrix} * & & & & & & & \\ & * & & & & & & \\ & & * & & & & & \\ & & & * & & & & \\ & & & & * & & & \\ & & & & & * & & \\ & & & & & & * & \\ & & & & & & & * \end{bmatrix} = D$$

$$\begin{bmatrix} \times & \times \\ ? & ? \end{bmatrix} \begin{bmatrix} A_1 & \times \\ A_2 & \times \end{bmatrix} = \begin{bmatrix} \times & \times \\ 0 & \times \end{bmatrix}$$

$$\begin{bmatrix} \times & \times \\ -A_2 A_1^{-1} & I_n \end{bmatrix} \begin{bmatrix} A_1 & \times \\ A_2 & \times \end{bmatrix} = \begin{bmatrix} \times & \times \\ 0 & \times \end{bmatrix}$$

Schur complement: too fast increase of the degrees,
the first step already uses $O(n^\omega \times nd)$ operations in K ,
 $\implies O(n^{\omega+1} \times d)$.

Minimal kernel bases over $K[x]$ [Forney 75]

$$A = \begin{bmatrix} * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \\ * & * & * & * & * & * & * & * \end{bmatrix} \rightarrow BA = \begin{bmatrix} * & * & * & * & & & & \\ * & * & * & * & & & & \\ * & * & * & * & & & & \\ * & * & * & * & & & & \\ & & & & * & * & * & * \\ & & & & * & * & * & * \\ & & & & * & * & * & * \\ & & & & * & * & * & * \end{bmatrix}$$

$$\begin{bmatrix} \overline{B} \\ \underline{B} \end{bmatrix} \begin{bmatrix} A_L & A_R \end{bmatrix} = \begin{bmatrix} A'_L & 0 \\ 0 & A'_R \end{bmatrix}$$

with \underline{B} (and \overline{B}) **minimal basis** of $\ker A_L$ as a $K[x]$ -submodule.

The row degrees of \underline{B} and of \overline{B} are the smallest possible ones.

Example.

$$\underline{B}A_L = \begin{bmatrix} 0 & 0 & 0 & 0 & 1 \\ -1 & x & -x^2 & x^3 & 0 \end{bmatrix} \begin{bmatrix} x & 0 & 0 \\ 1 & x & 0 \\ 0 & 1 & x \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = 0.$$

The degree may be as large as $nd/2$ for $\ker A_L$ in the worst case.

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Lemma. For a generic A_L the degree is d exactly.

Inversion: operation count

Generic minimal basis computation: $O\tilde{~}(n^3d)$ or $O\tilde{~}(n^\omega d)$

[e.g. matrix Padé approximation, Beckermann & Labahn 94]

[or Knuth/Schönhage/Moenck Euclidean algorithm for matrix polynomials]

Determinant - Computation of the minimal kernels and of D :

$$\sum_{i=0}^{\log n - 1} 2^{i+1} \times O\tilde{~}\left(\left(\frac{n}{2^i}\right)^\omega \times 2^i d\right) = O\tilde{~}(n^\omega d).$$

Inversion - Product of the $\log n$ transformations:

$$\sum_{i=0}^{\log n - 1} 2^i \times 2^i \times O\tilde{~}\left(\left(\frac{n}{2^i}\right)^\omega \times 2^i d\right) = O\tilde{~}(n^3 d).$$

III-2/ Matrix determinant

$$O\tilde{(n^{\omega+1}d)} \leq n^{3.38}d^{1+\epsilon} \text{ [Classical approaches]}$$

III-2/ Matrix determinant

$$O\sim(n^{\omega+1}d) \leq \begin{array}{l} n^{3.38}d^{1+\epsilon} \text{ [Classical approaches]} \\ n^{3.19}d^{1+\epsilon} \text{ [Eberly, Giesbrecht, Villard 2000]} \end{array}$$

III-2/ Matrix determinant

$$\begin{aligned} O_{\sim}(n^{\omega+1}d) &\leq n^{3.38}d^{1+\epsilon} \quad [\text{Classical approaches}] \\ &\quad n^{3.19}d^{1+\epsilon} \quad [\text{Eberly, Giesbrecht, Villard 2000}] \\ &\quad n^{3.03}d^{1+\epsilon} \quad [\text{Kaltofen 1992/2000}] \end{aligned}$$

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$$\begin{aligned} \tilde{O}(n^{\omega+1}d) &\leq n^{3.38}d^{1+\epsilon} \quad [\text{Classical approaches}] \\ &n^{3.19}d^{1+\epsilon} \quad [\text{Eberly, Giesbrecht, Villard 2000}] \\ &n^{3.03}d^{1+\epsilon} \quad [\text{Kaltofen 1992/2000}] \\ &n^{2.7}d^{1+\epsilon} \quad [\text{Kaltofen, Villard 2001}] \end{aligned}$$

III-2/ Matrix determinant

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One of the ingredients: **high-order lifting**
(quadratic iterative refinement for computing the error)

III-3/ Column reduction

Matrix pencils and Kronecker indices,

[Van Dooren 79-81, Beelen, Van den Hurk & Praagman 88, Praagman *et al.* 88-98].

Basis reduction,

[Wolovitch 78, Kailath 80, Paulus 98, Mulders & Storjohann 00].

\rightsquigarrow Algorithms in $O(n^3 d^2)$.

Definition

$$A(x) = \begin{bmatrix} x + 1 & x^2 \\ x^2 & x^3 + x^2 + 1 \end{bmatrix}$$

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↓

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↓

$$\begin{bmatrix} x + 1 & x \\ x^2 & x^2 + 1 \end{bmatrix} \rightarrow C(x) = \begin{bmatrix} x + 1 & 1 \\ x^2 & 1 \end{bmatrix}$$

The column leading matrix $[C]_l$ of $C = AU$ has **maximal rank**.

Consequence. The columns of C provide a **minimal degree** basis of the corresponding $K[x]$ -module.

~> Link with polynomial matrix multiplication?

“Easier” than polynomial matrix multiplication

[Giorgi, Jeannerod & Villard 03]

Theorem. A column reduced form of a non singular matrix A of degree d in $K[x]^{n \times n}$ can be computed by a Las Vegas (certified) algorithms in $MM'(n, d) + O(n^2d)$ or $O(n^\omega d)$ operations in K .

NB. $MM'(n, d) = O(MM(n, d) + \sum_{i=0}^{\log d} 2^i MM(n, 2^{-i}d) + \sum_{i=0}^{\log d} 4^i MM(2^{-i}n, d))$.

Difficulty

Small degrees in the matrix but large degrees in the transformation
(possibly long chain of cancellations)

Example.

$$\begin{bmatrix} 1 & x & 0 & 0 \\ 0 & 1 & x & 0 \\ 0 & 0 & 1 & x \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & x & 0 & 0 \\ 0 & 1 & x & 0 \\ 0 & 0 & 1 & x \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & x & 0 & 0 \\ 0 & 1 & x & 0 \\ 0 & 0 & 1 & x \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & -x & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & x & 0 \\ 0 & 0 & 1 & x \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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Column reduction: the approach

Minimal basis or matrix approximation,

[Beelen, van den Hurk & Praagman 88]

[Villard 96] [Beckermann, Labahn & Villard 99]

$$A(x)U(x) = C(x) \iff \begin{bmatrix} A^{-1}(x) & I \end{bmatrix} \cdot \begin{bmatrix} C(x) \\ U(x) \end{bmatrix} = 0$$

Column reduction: the approach

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Not enough: **too big degrees** (nd) in the transformation U .

High-order lifting and fraction reconstruction

$$A^{-1} = (A^{-1} \bmod x^h) + x^h RA^{-1}.$$

Left fraction \longleftrightarrow Right fraction

Non proper \longleftrightarrow Proper

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Degree d everywhere.

Column reduction

Input : $A \in \mathbb{K}[x]^{n \times n}$ of degree d

Output : $C = AU$ column reduced

|

Column reduction

Input : $A \in \mathbb{K}[x]^{n \times n}$ of degree d

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| $2d$ terms of the expansion of A^{-1} of order higher than $(n - 1)d$

Column reduction

Input : $A \in \mathbb{K}[x]^{n \times n}$ of degree d

Output : $C = AU$ column reduced

2d terms of the expansion of A^{-1} of order higher than $(n - 1)d$
Reconstruction of the fraction description $U'C^{-1}$

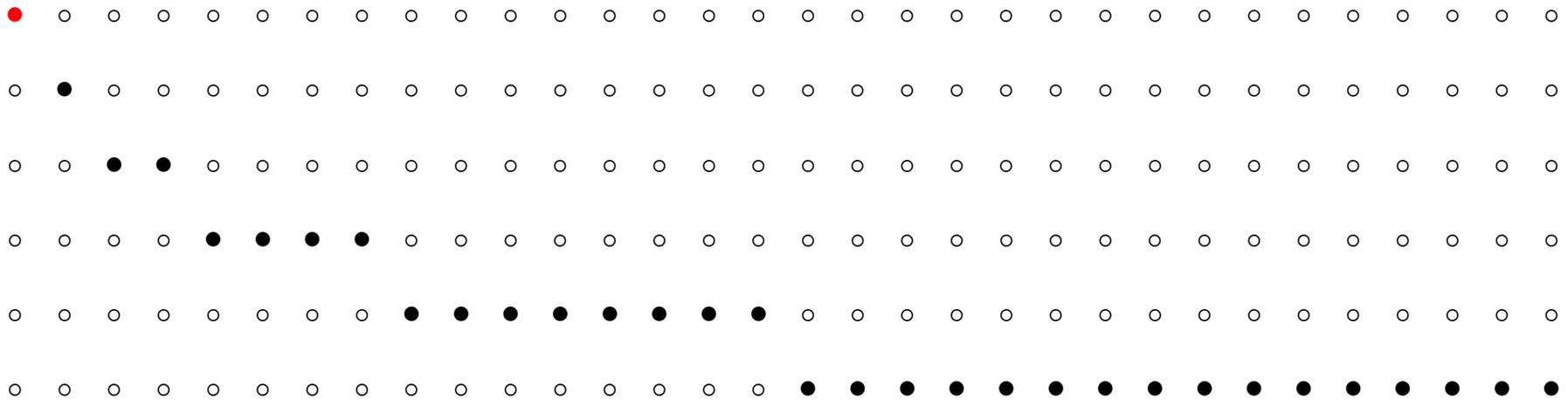
Second step: Knuth/Schönhage/Moenck fast recursive algorithm extended to matrix polynomials.

First step: High-order lifting [Storjohann 02]

(quadratic iterative refinement for computing the error)

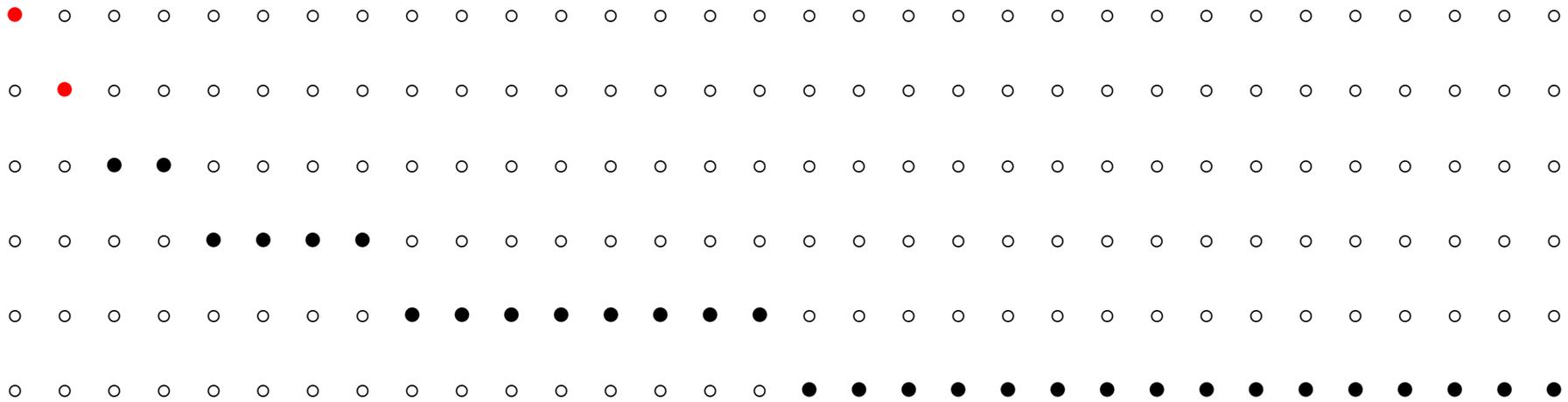
Computing the expansion of A^{-1}

Quadratic approximation



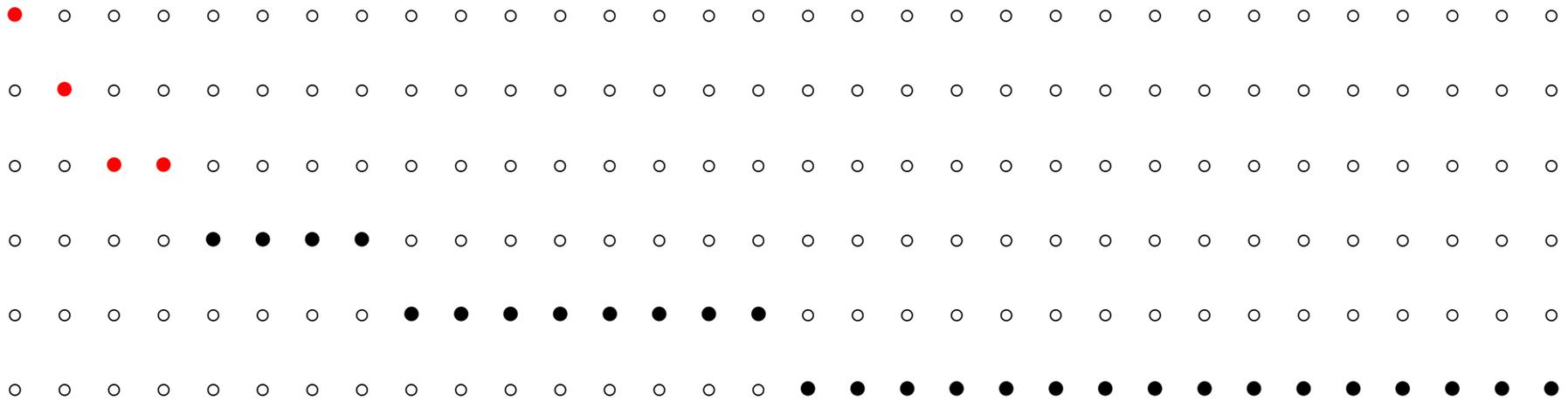
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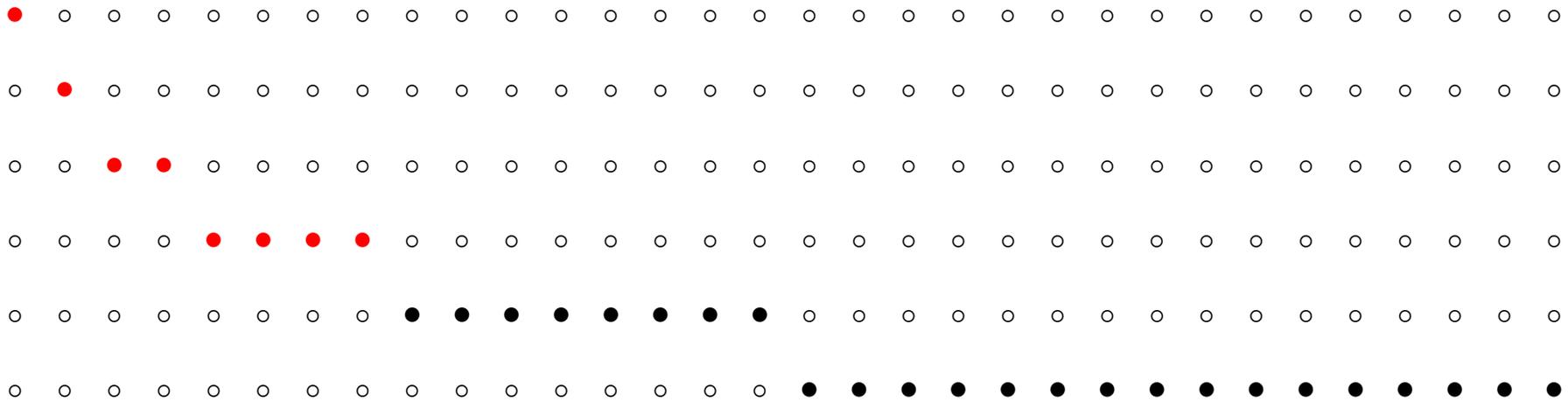
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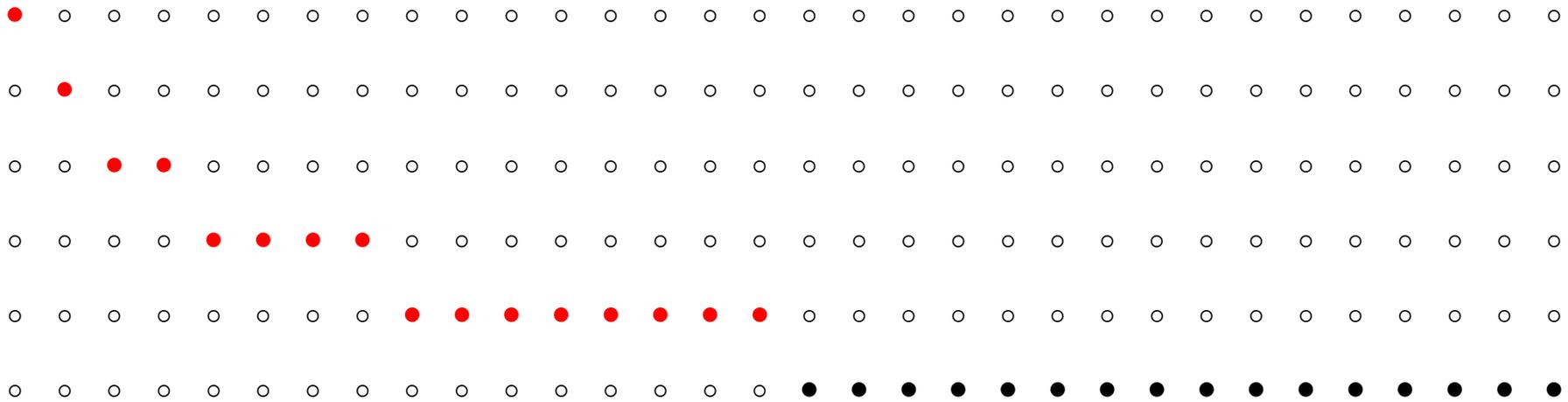
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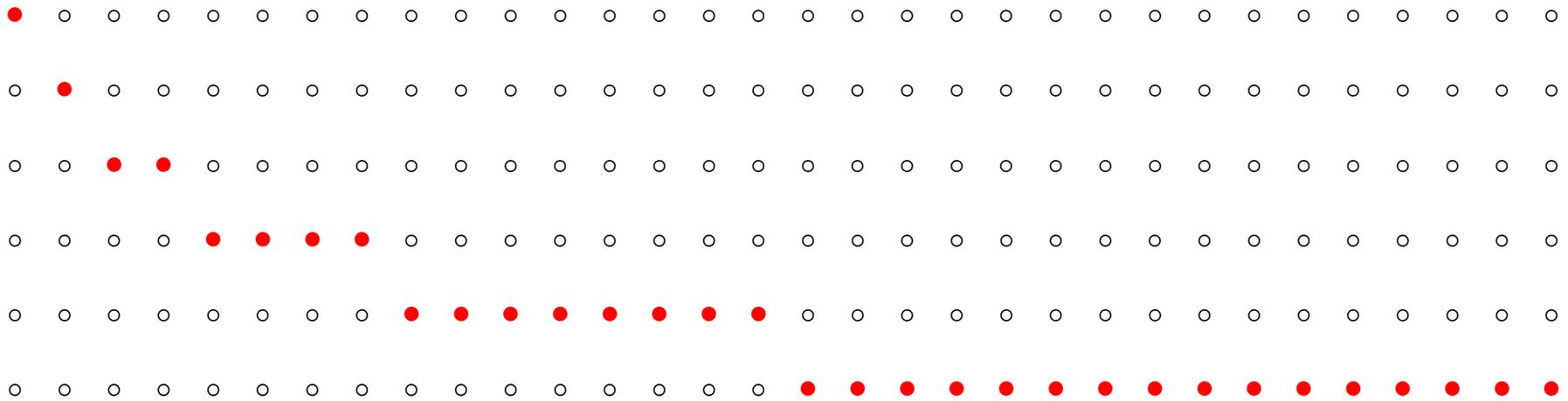
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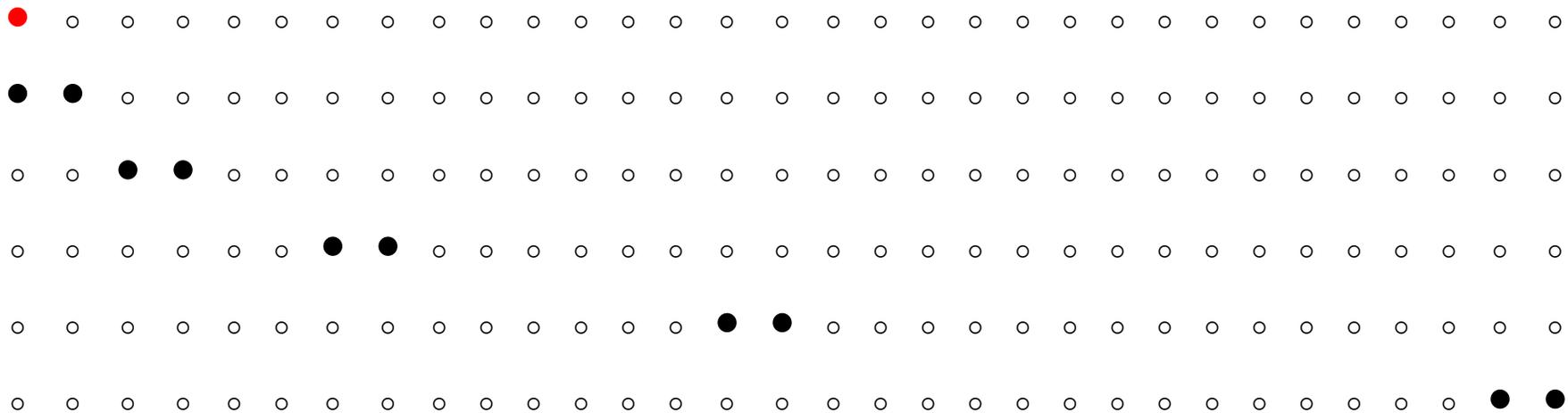
Computing the expansion of A^{-1}

Quadratic approximation



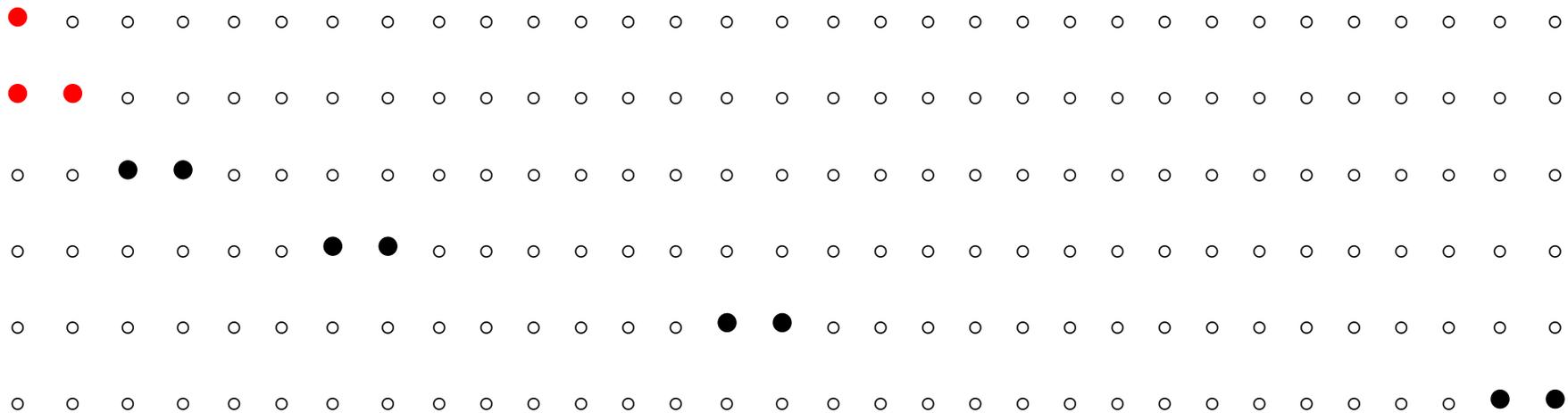
Computing the expansion of A^{-1}

High-order component lifting [Storjohann 02]



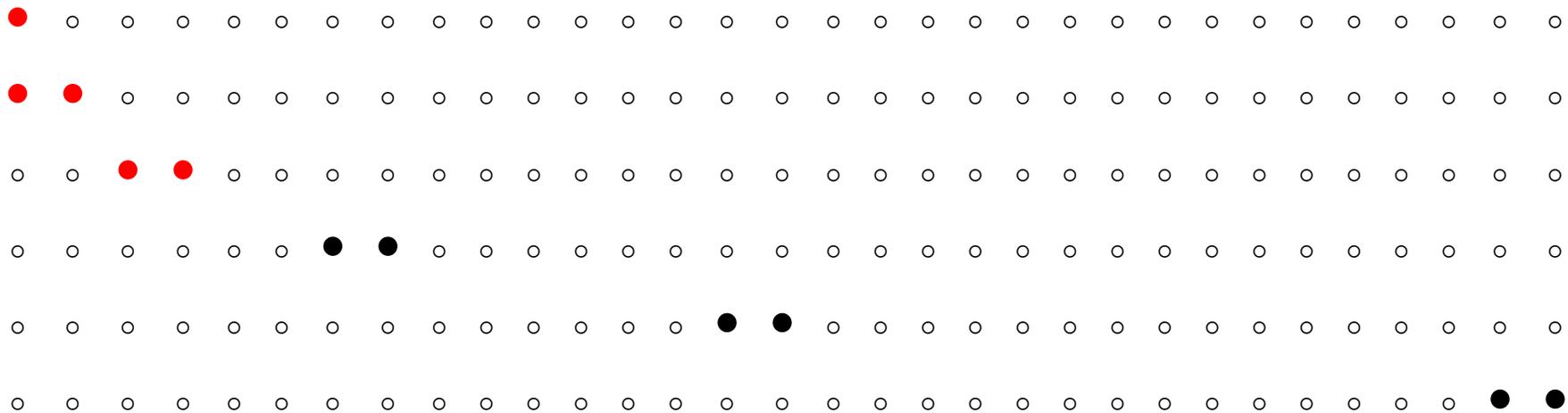
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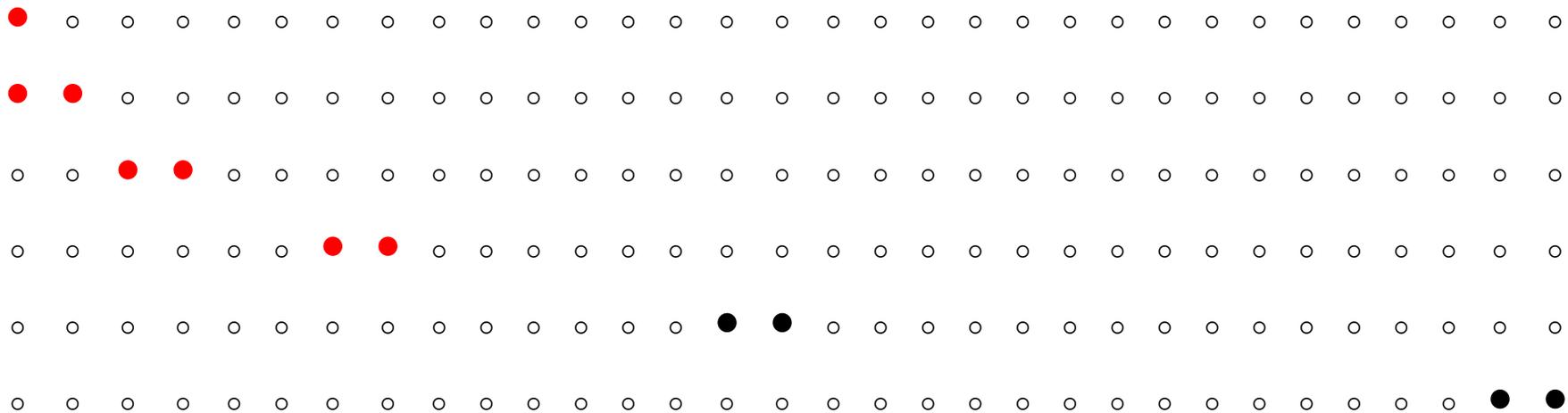
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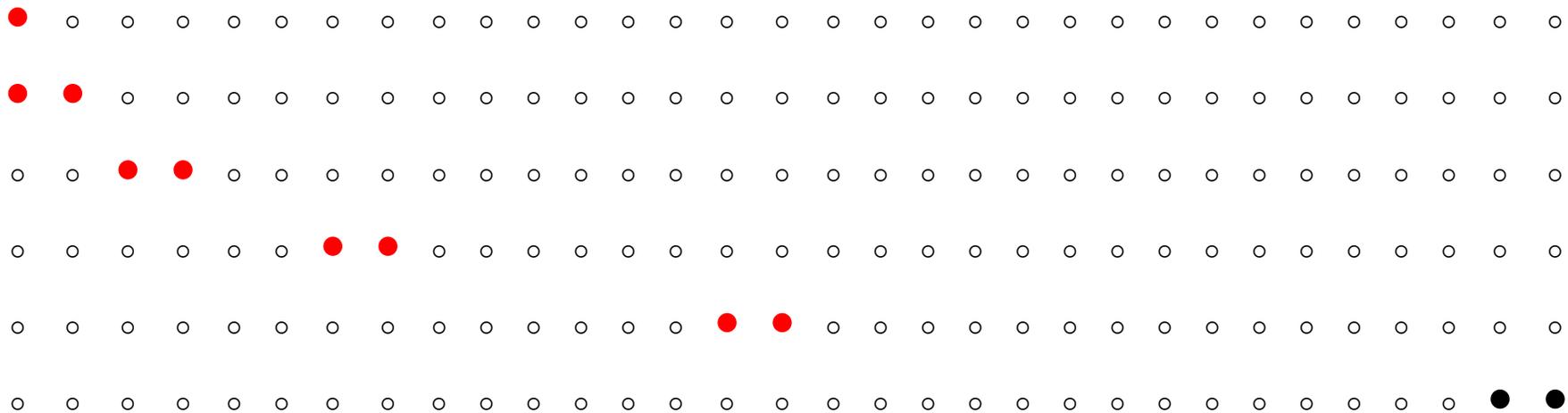
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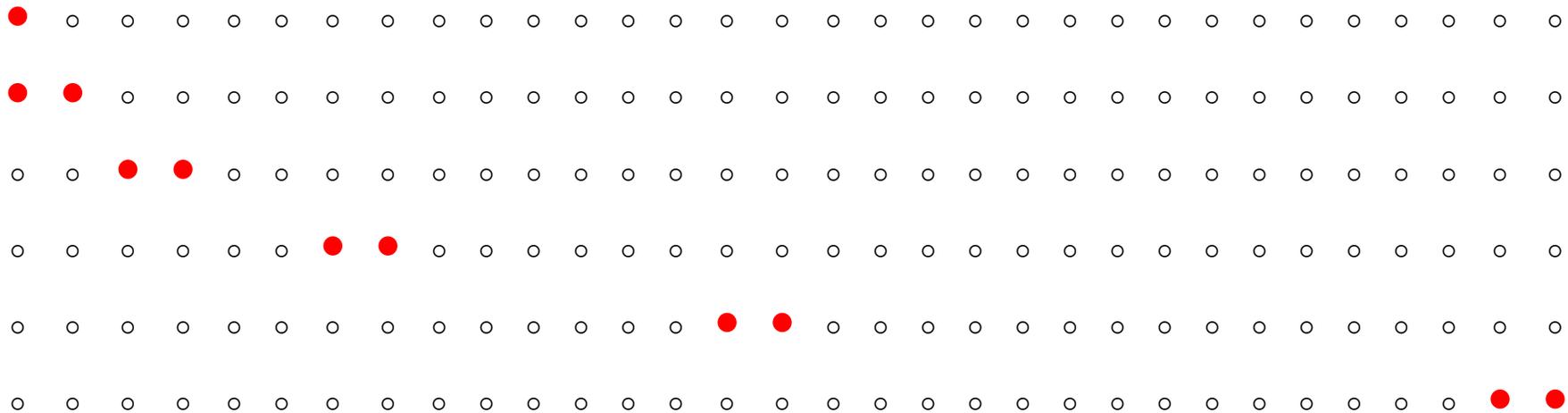
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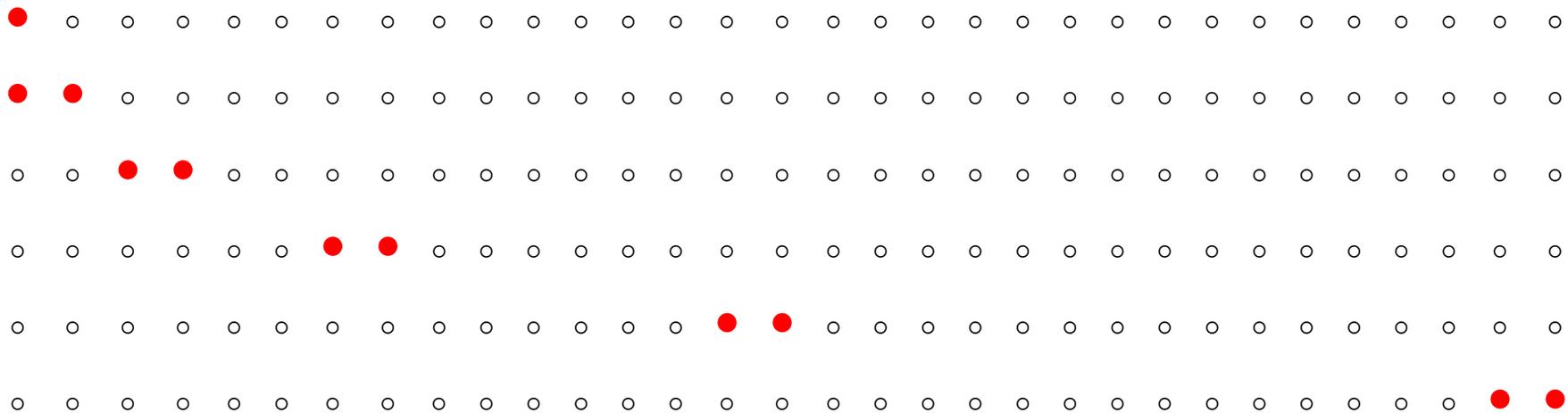
High-order component lifting [Storjohann 02]



$$A^{-1} = (A^{-1}(x) \bmod x^k) + x^{k+1}RA^{-1}$$

Computing the expansion of A^{-1}

High-order component lifting [Storjohann 02]



$$\begin{aligned}
 A^{-1} &= (A^{-1}(x) \bmod x^k) + x^{k+1} R A^{-1} \\
 &= (A^{-1}(x) \bmod x^k) + x^{k+1} R_L (A^{-1})_L + x^{2k-1} R_H (A^{-1})_H
 \end{aligned}$$

Organization of the talk

I - Algebraic *versus* bit complexity.

II - Reductions between problems and target complexity.

III - Polynomial matrix computations.

IV - Integer matrix computations.

Conclusion

$$A \in \mathbb{Z}^{n \times n},$$

$$\text{MM}(n, \log \|A\|) = \tilde{O}(n^{\omega+1} \log \|A\|) \text{ or } O(n^3 \log^2 \|A\|).$$

Nota. More difficult than the polynomial case.

▷ **Integer determinant**

[Storjohann 03]

▷ **Integer characteristic polynomial**

[Kaltofen & Villard 03]

IV-1/ Matrix determinant

$$b = \log^\alpha \|A\|$$

$$\tilde{O}(n^{\omega+1} \log \|A\|) \leq n^{3.38} b \text{ [Classical approaches]}$$

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Nota. Apparently no progress on this side of $O\tilde{\sim}(n^{\omega+1} \log \|A\|)$ bit operations for matrix inversion.

IV-2/ Integer characteristic polynomial

Iterated powers or Krylov approach and Chinese remaindering,

$\leadsto O^{\sim}(n^{\omega+1} \log \|A\|)$ bit operations

Las Vegas randomized

[Giesbrecht & Storjohann 02]

Via algebraic complexity without divisions

[Kaltofen & Villard 01-03]

Theorem. The determinant of any matrix A in $\mathbb{R}^{n \times n}$ can be computed with $O^{\sim}(n^{3+1/5})$ or $n^{2.7}$ ring operations.

Theorem. The characteristic polynomial of any matrix A in $\mathbb{Z}^{n \times n}$ can be computed by a randomized Monte Carlo algorithm with $O^{\sim}(n^{3+1/5} \log \|A\|)$ or $O^{\sim}(n^{2.7 \log \|A\|})$ bit operations.

To postpone the size increase?

Exemple:

x and y two vectors in \mathbb{Z}^n with constant entries,
 c a large constant,

Compute $c \cdot x^t \cdot y$?

→ Solution 1. $c \cdot x^t$ then $(c \cdot x^t) \cdot y$ Cost: $O(\log |c|^2)$.

To postpone the size increase?

Exemple:

x and y two vectors in \mathbb{Z}^n with constant entries,
 c a large constant,

Compute $c \cdot x^t \cdot y$?

→ Solution 1. $c \cdot x^t$ then $(c \cdot x^t) \cdot y$ Cost: $O(\log^2 |c|)$.

→ Solution 2. $x^t \cdot y$ then $c \cdot (x^t \cdot y)$ Cost: $O(\log |c|)$.

Integer determinant and characteristic polynomial,

Ingredients:

- Elimination of divisions [Strassen 73]
- Baby step/giant step [Kaltofen 92]
- Krylov/Lanczos [Wiedemann 86]
- Block Krylov/Lanczos [Coppersmith 86, Villard 97]
- Multifactor Hensel lifting [Sorjohann 00]

1. Computation of $u^t v, u^t A v, u^t A^2 v, \dots, u^t A^{2n} v$
2. Computation of the **minimum polynomial**

From scalar polynomials in $\mathbb{K}[x]$ to **matrix polynomials** in

$$(\mathbb{K}[x])^{m \times m} = (\mathbb{K}^{m \times m})[x].$$

Matrix minimum polynomial,

$$U, V \in \mathbb{K}^{n \times m}, \quad U^t V, U^t A V, U^t A^2 V, \dots, U^t A^{2n/m} V$$

↓

$$F(x) = x^d I + x^{d-1} F_{d-1} + \dots + F_0 \in \mathbb{K}[x]^{m \times m},$$

$$A, n \times n \quad \rightarrow \quad F(x), m \times m \quad \rightarrow \quad \det F(x)$$

▷ **Postpone the size increase:** less powers of A .

Nota. First gain by using baby steps/giant steps, additional gain with the minimum matrix polynomial.

Conclusion.

des resultats de l'expose: dire ce qu'il reste a faire pour les finir

inversion cas general ?

reunifier les complexites

pgcd recursif

without divisions

inverse cas general

MMprime

all problems had the "same" complexity, and now

lien + numerique avec pepier Demmel. Eg complexity calcul du conditionnement?

recapituler le meilleurs exposants connus

certified rank? char poly? transfor matrices ?

revenir au titre (how does cost?)

matrices creuses, structurees

Linbox

floating points / accuracy

Suppression du facteur n / Modle binaire sur \mathbb{Z} (en O^\sim)

	Facteur	Total
Dterminant (LV) Storjohann 2003	$n^{1/5}$ $\log^\alpha n$	$n^{2.7} \log \ A\ $ $n^\omega \log \ A\ ^*$
Forme de Smith (LV)	$\log^\alpha n$	$n^\omega \log \ A\ ^*$
Polynme caractéristique (MC) + Forme normale de Frobenius	$n^{1/5}$	$n^{2.7} \log \ A\ $

Suppression du facteur n / Module algébrique sur $K[x]$ (en \mathcal{O})

	Facteur	Total
Dterminant , Smith (LV) ¹	$\log^\alpha n$	$n^\omega d^*$
Déterminant sans division ²	$n^{1/5}$	$n^{2.7}$
Rduction en colonnes , pgcd (LV) ³	$\log^\beta n$	$n^\omega d^*$
Inversion ⁴ (SLP)	$\log^\gamma n$	$n^3 d^*$

¹_[Sto2002], ²_[KaVi2001-03], ³_[GiJeVi2003], ⁴_[JeVi2002].