

## TD1 - Modelization and Linear Programming

Indication of hardness: from (\*) to (\*\*\*\*).

### 1 Modelization (again)

#### Exercise 1 - Computers production (\*)

Pear© produces notebook computers and desktop computers. Pear© would like to know how many of each product to produce in order to maximize profit for the quarter. The major constraints are as follows:

1. Each computer (either notebook or desktop) requires a Processing Chip. Due to tightness in the market, the supplier has allocated 10,000 such chips to the company.
2. Each computer requires memory. Memory comes in 8GB chip sets. A notebook computer has 8GB memory installed (so needs 1 chip set) while a desktop computer has 16MB (so requires 2 chip sets). Pear© received a great deal on chip sets, so have a stock of 15,000 chip sets to use over the next quarter.
3. Each computer requires assembly time. Due to tight tolerances, a notebook computer takes more time to assemble: 4 minutes versus 3 minutes for a desktop. There are 38,000 minutes of assembly time available in the next quarter.

Given current market conditions, material cost, and our production system, each notebook computer produced generates \$750 profit, and each desktop produces \$1000 profit.

- (a) Formulate the problem as a Linear Program.
- (b) Solve it geometrically and with the Simplex Algorithm.

#### Exercise 2 - The world is (still) linear... (\*\*\*)

(a) We want to maximize the following fraction  $\frac{3+2x_1+3x_2+x_3}{1+3x_1+x_2+4x_3}$  subject to the constraints  $5x_1 + x_2 + 6x_3 \leq 10$  and  $x_1 + 2x_2 + x_3 \leq 2$  and non negative  $x_i$  for every  $i$ . Show that this problem can be modeled with the following linear program:

$$\begin{aligned} \max & 3t + 2y_1 + 3y_2 + y_3 \\ \text{subject to} & \\ & t = 1 - 3y_1 - y_2 - 4y_3 \\ & 5y_1 + y_2 + 6y_3 - 10t \leq 0 \\ & y_1 + 2y_2 + y_3 \leq 0 \\ & t, y_1, y_2, y_3 \geq 0 \end{aligned}$$

*Hint:*  $t = \frac{1}{1+3x_1+x_2+4x_3}$ .

(b) Explain how you can generalize it to any fraction.

## 2 Convex sets

### Exercise 3 - Alternative definition of convex sets. (\*)

Prove that: a set  $X$  is convex if and only if any convex combination of a finite number of points of  $X$  is in  $X$ .

### Exercise 4 - Applications of the definition (\*)

Show that:

- A hyperplane is a convex set.
- A polyhedron is a convex set.
- A cone is a convex set.

### Exercise 5 - Convex hull is convex. (\*)

Let  $X$  be a set of points of  $\mathbb{R}^n$ . Show that the set  $Conv(X)$  is convex.

### Exercise 6 - Convex hull of the extreme points (\*\*)

Prove that if  $P$  is a polytope, then  $P = Conv(V(P))$ .

### Exercise 7 - Operations on convex sets. (\*)

- (a) Show that the intersection of any collection (not necessarily finite) of convex sets is convex. What about the union of convex sets?
- (b) Show that for any  $X \subseteq \mathbb{R}^n$ , the set  $Conv(X)$  is the intersection of all convex sets that contain  $X$ .

*Hint:* If  $x, y$  are in the intersection, show that the "segment"  $[x, y]$  also is. 2) Why it is included in  $Conv(X)$ ? Since the convex set contains  $X$ , why does it contain  $Conv(X)$ ?

### Exercise 8 - Convex functions. (\*)

- (a) Show that the sum of convex functions is convex.
- (b) Is it also true for the product of convex functions? For their multiplication by a scalar?
- (c) Let  $c \in \mathbb{R}^n$  and  $\alpha \in \mathbb{R}$ . Show that  $f(x) = c^T x + \alpha$  is convex and concave.

### 3 Polytopes

**Exercise 9 - Optimal solution and faces. (\*)**

Prove that any optimal solution of a LP on a polyhedron  $P$  has either an infinite optimal value or all every optimal solution is on a face  $F$  of  $P$  (strictly contained in  $P$ ).

**Exercise 10 - Alternative definition of polytope. (\*\*)**

- (a) Prove that any minimal face of a polytope  $P$  is reduced to a single point.
- (b) Consider the linear programming problem of minimizing  $c^t x$  over a non-empty, polytope  $P$ . Prove that there exists an optimal solution which is an extreme point of  $P$ .

**Exercise 11 - An example (\*)**

Give an example of convex set which is not the convex hull of its extreme points.

**Hint:** It is not a polytope (why?), thus...

**Exercise 12 - Lines and Extreme Points. (\*\*)**

We say that a polyhedron  $P$  contains a line if there exists a point  $x \in P$  and a nonzero vector  $d \in \mathbb{R}^n$  such that  $x + \lambda d \in P$  for all scalars  $\lambda$ .

- (a) Prove the following: Let  $P$  be a non-empty polyhedron. Show that if  $P$  does not contain a line, then  $P$  contains an extreme point.
- (b) Is the converse also true? Proof or counter-example.

### 4 Harder exercises on polytopes

**Exercise 13 - Extremal points of the unit disk (\*\*\*)**

We want to prove formally that the set of extremal points of the unit disk

$$C = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \text{ such that } x^2 + y^2 \leq 1 \right\}$$

is the set of points satisfying  $x^2 + y^2 = 1$ .

- (a) Let  $\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$  be a point satisfying  $x_0^2 + y_0^2 = 1$ . Give an equation of the line tangent to the sphere at point  $\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$  as  $\alpha x + \beta y = c$  (explicit  $\alpha, \beta$  and  $c$ ).
- (b) Maximize  $\alpha x + \beta y$  on  $C$ . What is the optimal value? Show that  $\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$  is the unique point reaching the optimal value.
- (c) Let  $X$  be a subset of  $C$  such that  $\begin{pmatrix} x_0 \\ y_0 \end{pmatrix} \notin X$ . What can you say about the optimal value of the objective function in  $\text{Conv}(X)$ ? Conclude.
- (d) Recall why it implies that  $C$  is not a polytope.
- (e) How can you adapt this proof for higher dimensional spaces?

*Hint for (b):* We denote by  $(u|v) = \sum_i u_i v_i$  the scalar product of two vectors  $u$  and  $v$ . Recall that (Cauchy-Schwarz theorem)

$$|(u|v)| \leq \|u\| \cdot \|v\|$$

And the equality case happens if and only if  $u = \lambda v$  for  $\lambda \geq 0$ .

**Exercise 14 - Extended formulations - The cross polytope (\*\*\*)**

Consider the following polytope:

$$C_d = \{x \text{ such that } \|x\|_1 = 1\} = \{x \in \mathbb{R}^d \text{ such that } \pm x_1 \pm x_2 \dots \pm x_d \leq 1\}$$

- (a) Represent  $C_d$  when  $d = 2$  and  $d = 3$ .
- (b) Show that no constraint of the following polyhedron is useless. In other words, prove that none of the constraints  $\pm x_1 \pm x_2 \dots \pm x_d \leq 1$  can be deleted without modifying the polytope.  
What is the number of facets of this polytope?
- (c) Find an extended formulation  $C_d$  with a linear number of constraints.

*Hint for (c):* How did we transform absolute values into variables in TD1?

## 5 Simplex algorithm

**Exercise 15 - Solve the following LP (\*\*)** Solve the following linear programs using the simplex algorithm:

$$\begin{aligned} \max \quad & 6x_1 + 8x_2 + 5x_3 + 9x_4 \quad \text{subject to:} \\ & 2x_1 + x_2 + x_3 + 3x_4 \leq 5 \\ & x_1 + 3x_2 + x_3 + 2x_4 \leq 3 \\ & x_1, x_2, x_3, x_4 \geq 0. \end{aligned}$$

**Exercise 16 - Solve the following LP (\*\*)**

$$\begin{aligned} \max \quad & 3x_1 + 3x_2 + 4x_3 \quad \text{subject to:} \\ & x_1 + x_2 + 2x_3 \leq 4 \\ & 2x_1 + 3x_3 \leq 5 \\ & 2x_1 + x_2 + 3x_3 \leq 7 \\ & x_1, x_2, x_3 \geq 0. \end{aligned}$$

**Exercise 17 - Solve the following LP (\*\*)**

$$\begin{aligned} \max \quad & 2x_1 + x_2 \quad \text{subject to:} \\ & 2x_1 + x_2 \leq 3 \\ & 2x_1 + x_2 \leq 1 \\ & 2x_1 + x_2 \leq 4 \\ & 2x_1 + x_2 \leq 5 \\ & x_1, x_2 \geq 0 \end{aligned}$$