

Dynamic list scheduling of threads on clusters

*G. G. H. Cavalheiro, E. D. Benitez,
D. S. Peranconi, E. Moschetta*



Universidade do Vale do Rio dos Sinos
Programa Interdisciplinar de Pós Graduação em Computação Aplicada



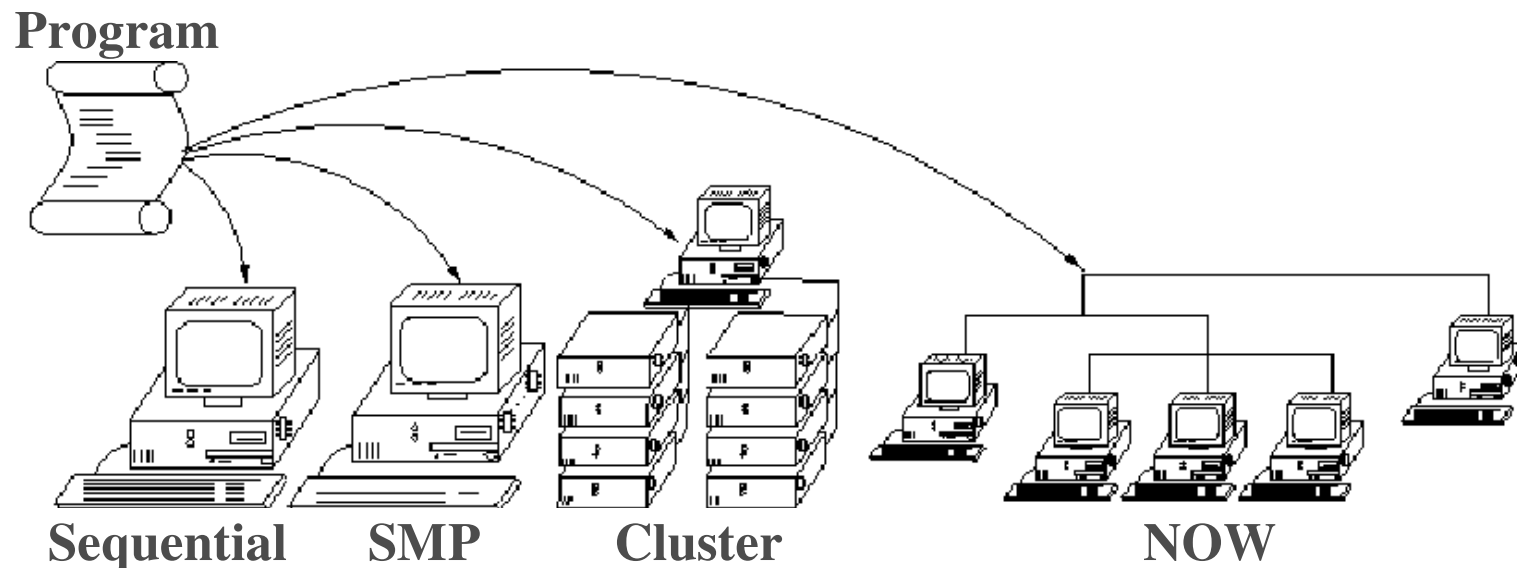
Overview

- **Introduction**
- **Anahy**
 - Task and synchronizations
 - Programming interface
 - Scheduling strategy
- **Handling a Graph of Tasks**
 - Visualizing an execution
- **Some Performances**
- **The Future of Anahy**



Introduction

- Performance portability



- The concurrency of an application can be described regardless of hardware resources


Introduction

- **Performance portability**
- **Concurrency**
 - Depends on application characteristics
 - Can be identified by a specialist on the application
- **Parallelism**
 - Depends on hardware
 - A specialist on applications is not necessarily an specialist in parallel programming

Concurrency >> Parallelism



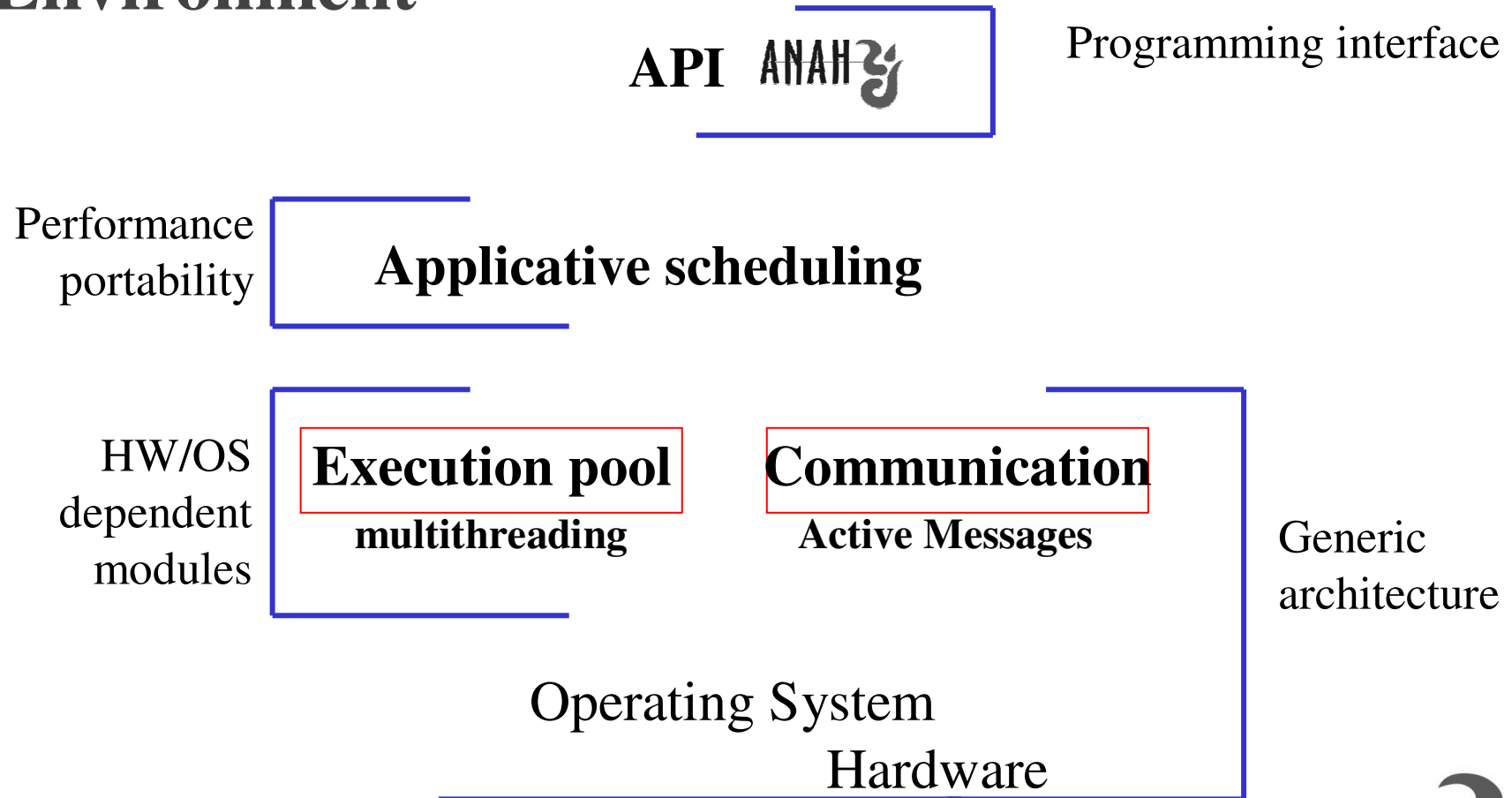
Introduction

- **Performance portability**
- **Our approach:**
 - Dissociate programming of execution
- **Our proposal:**
 - ANAH 
- **Our mechanisms:**
 - Scheduling and dataflow control achieved at run time



Anahy

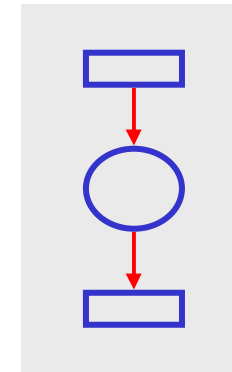
- **Environment**



Anahy

Task and Synchronization

- A *task* defines a sequence of instructions and two set of data: input and output data;
- The synchronization between tasks are guaranteed by accesses to the data



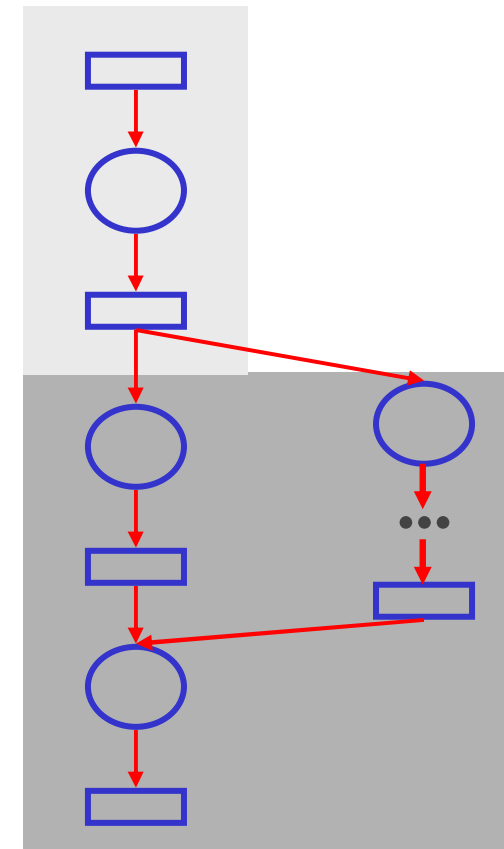
Anahy

Task and Synchronization

- A *task* defines a sequence of instructions and two set of data: input and output data;
- The *synchronization* between tasks are guaranteed by accesses to the data

Large amount of concurrency

↳ large amount of synchronizations



Anahy

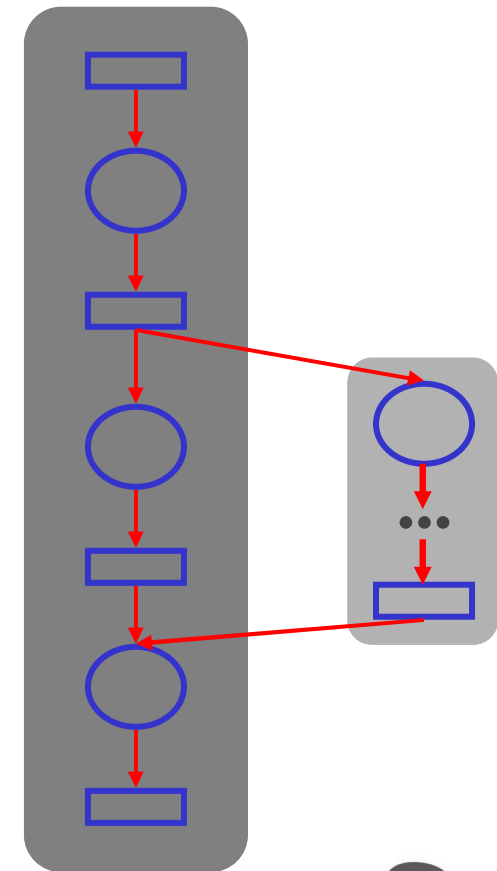
Task and Synchronization

- A *task* defines a sequence of instructions and two set of data: input and output data;
- The *synchronization* between tasks are guaranteed by accesses to the data

Large amount of concurrency

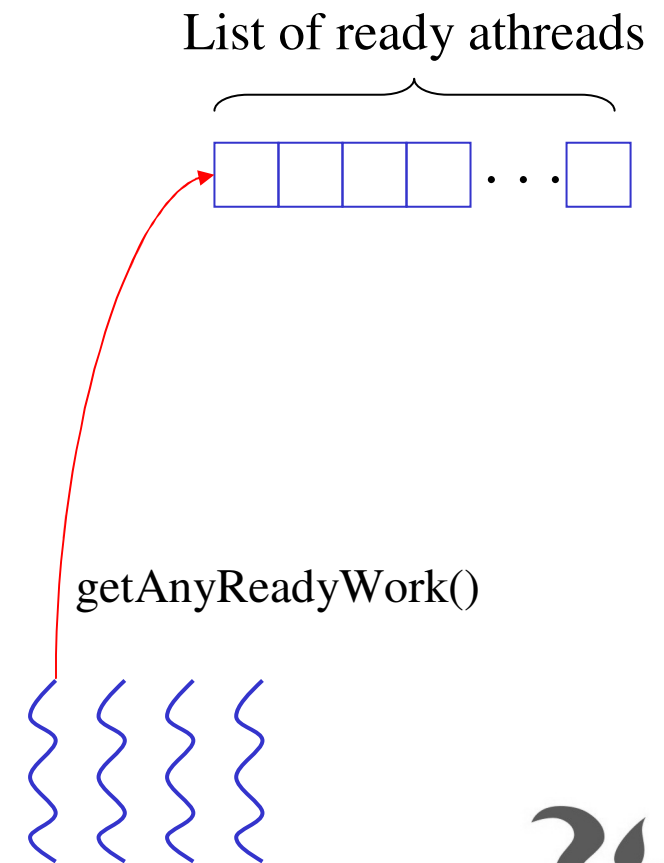
↳ large amount of synchronizations

Coarse scheduling unity: athread



Anahy

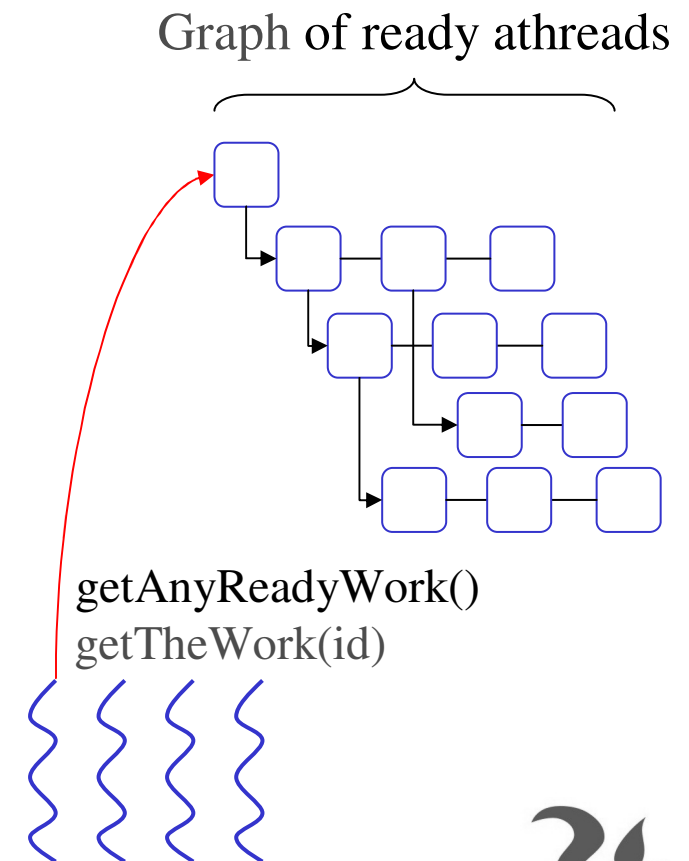
- Execution pool
 - A set of *system* threads is responsible for executing the athreads
 - Each system thread is called VP
 - Strategy:
 - A VP can chose a specific athread to execute



Anahy

- Execution pool
 - A set of *system* threads is responsible for executing the athreads
 - Each system thread is called VP
 - Strategy:
 - A VP can chose a specific athread to execute
 - The list of ready works is organized as a graph of dependencies

...



Anahy

- Programming Interface
- Creation

```
int pthread_create( pthread_t *th,
                  pthread_attr_t *attrib,
                  void *(*func) (void *),
                  void *in );
```

- Synchronization

```
int pthread_join( pthread_t th, void **res );
```

- Pthread code

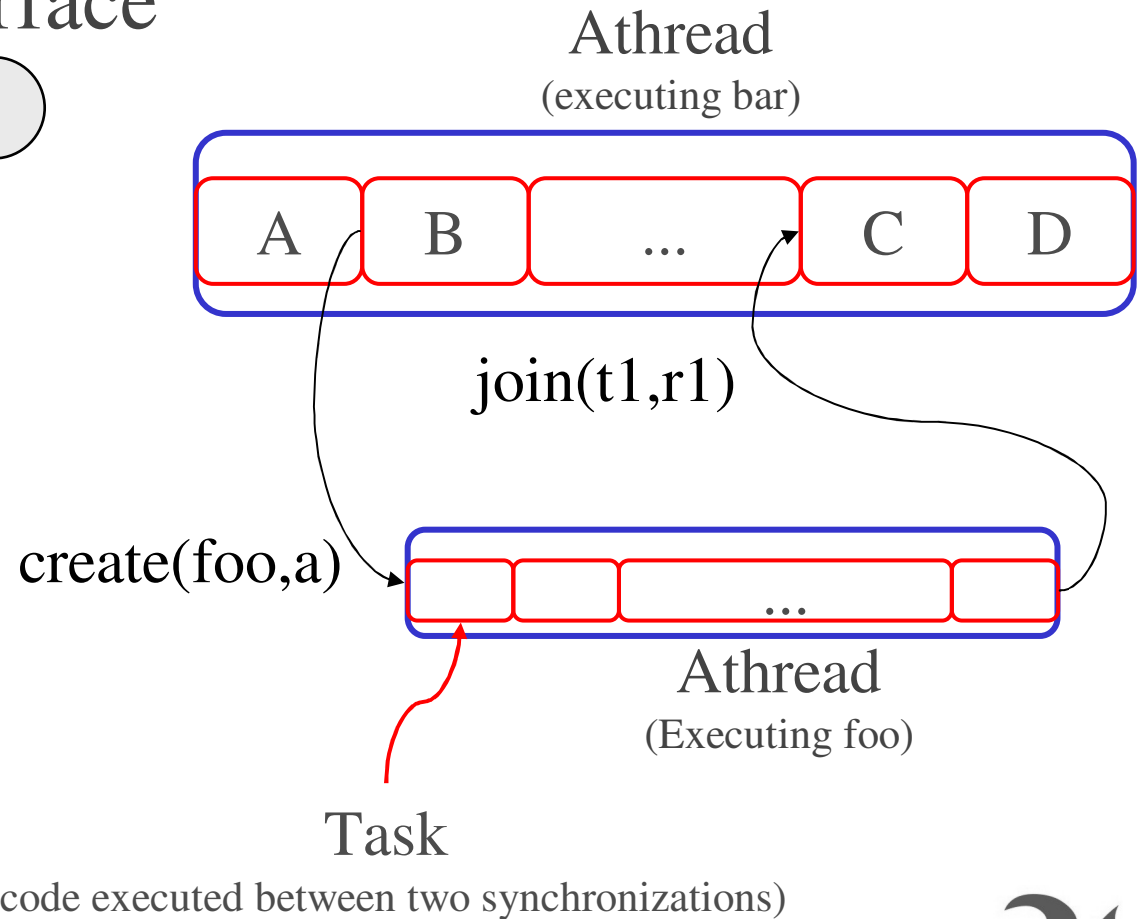
```
void *foo( void *in ) {
    ...
    return out;
}
```



Anahy

- Programming Interface

```
void* foo(void* x) {  
    ...  
}  
void* bar(void* p) {  
    Task_A  
    t1 = create(foo, a);  
    Task_B  
    t2 = create(fuu, b);  
    ...  
    join(t1, r1)  
    Task_C  
    join(t2, r2)  
    Task_D  
    return &something;  
}
```



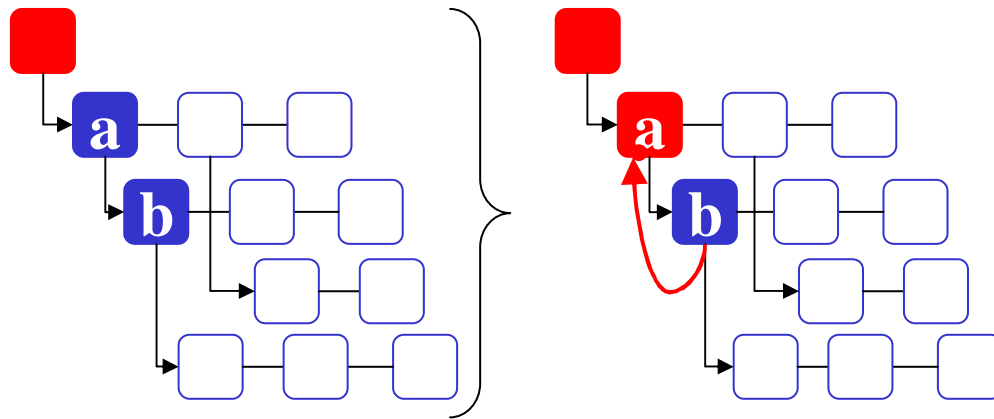
Anahy

- Scheduling
- List scheduling
 - Blind strategy
 - Explosion on concurrency or memory
- Scheduling heuristics
 - Different searches on the graph
- Applied:
 - When a VP becomes idle and request for work
 - When is executed a join operation



Handling graph of tasks

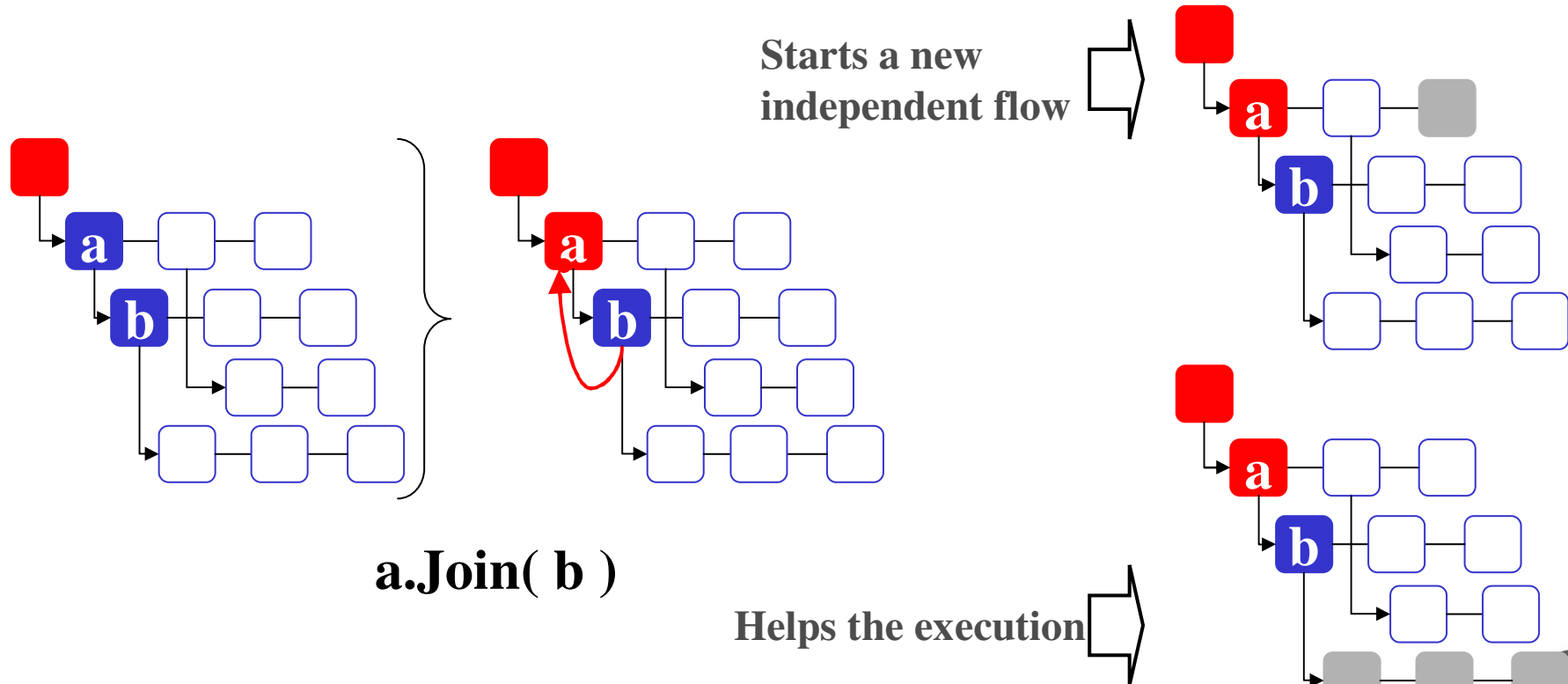
- Search an athread on the graph:
 - `athread_t* SearchFrom(from, direction, orientation, axis)`



a.Join(b)

Handling graph of tasks

- Search an athread on the graph:
 - `athread_t* SearchFrom(from, direction, orientation, axis)`



Handling graph of tasks

- Examples
 - SearchFrom(current, ROOT, LEFT, VERT)
 - returns the next athread ready in the sub-graph having current as root (left-to-right, high priority on deep nodes)
 - SearchFrom(NULL, TOP, RIGHT, HORIZ)
 - returns the next athread ready in the graph from the first node of the graph (right-to-left, high priority on high nodes).
 - SearchFrom(jid, ROOT, RIGHT, HORIZ)
 - returns the next athread ready in the sub-graph having jid as root (right-to-left, high priority on the highest athread in the sub-graph).



Handling graph of tasks

- Visual example
 - Recursive program:

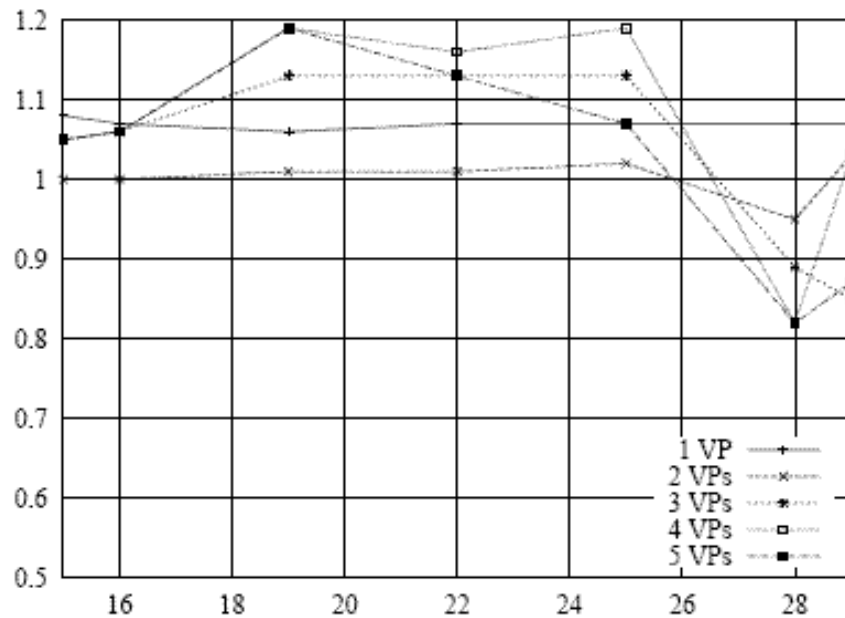
```
void* tree( void* n ) {  
    if( n > 2 ) {  
        t1 = create( tree, *n-1 );  
        t2 = create( tree, *n-2 );  
        doSomething( ... );  
        join(t1,&r1);  
        join(t2,&r2);  
    }  
    else doSomething( ... );  
    return &something;  
}
```

- VP idle:
 - searches the last created in the highest level
SearchFrom(NULL, TOP, RIGHT, HORIZ)
- athread blocked in a join:
 - searches a ready athread from jid
SearchFrom(jid, HERE, RIGHT, HORIZ)

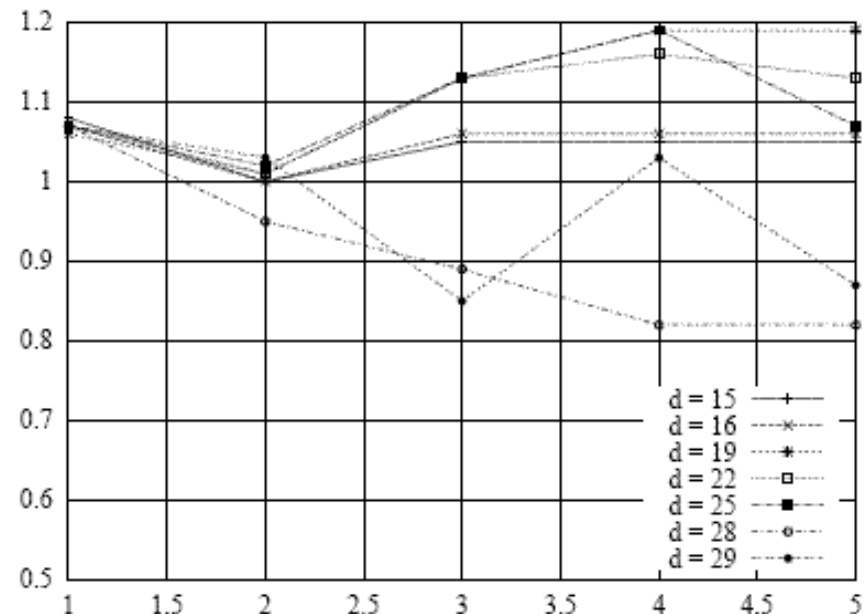


Performance

High Parallel Application
Ratio: Cilk / Anahy on a dual-processor



Depth
Concurrency level on the program



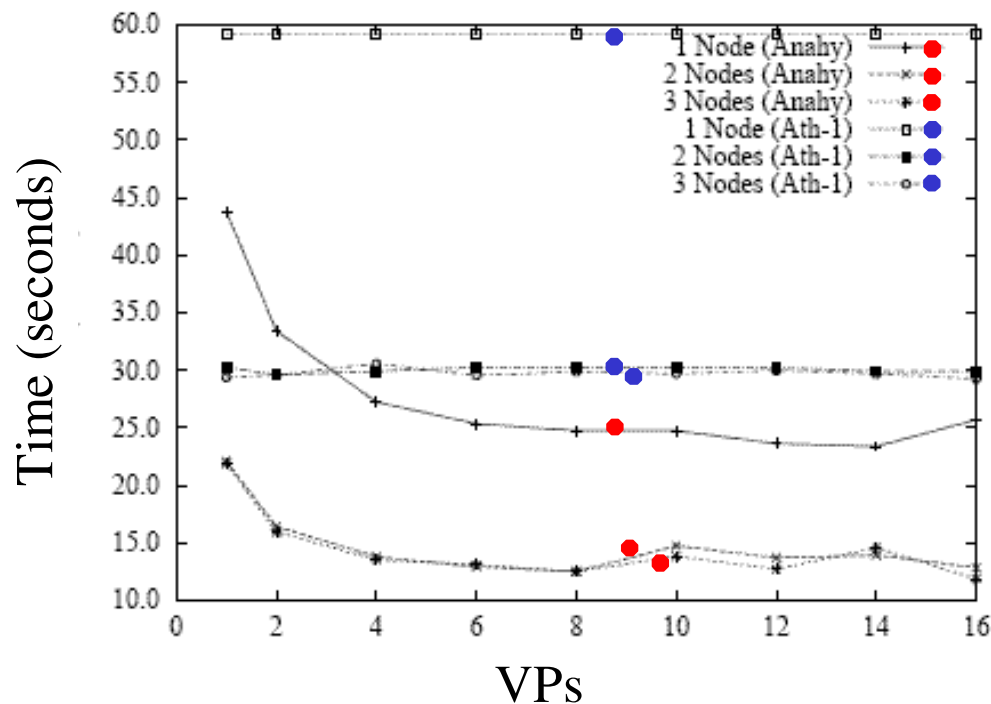
VPs
Parallel execution support



Performance

High Parallel Application

Execution times: Athapascan-1 x Anahy on a cluster



Parallel execution support per node



The future of Anahy

- Current work
 - Distributed version
 - Real applications
 - Dynamic programming
 - Metabolic cellular network
 - Crowd simulation
- Next
 - Scheduling strategies
- Next++
 - Other Pthreads synchronization mechanisms
 - Mutex, condition variables



Dynamic list scheduling of threads on clusters

*G. G. H. Cavalheiro, E. D. Benitez,
D. S. Peranconi, E. Moschetta*

gersonc@anahy.org, anahy@anahy.org

