Low-Power Approximations of Convolutional Neural Networks

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Outline



- 2 Deep Neural Network Models
- 3 Neural Network Compression



Weight quantisation with dyadic rationals

Outline



Deep Neural Network Models

3 Neural Network Compression



Weight quantisation with dyadic rationals

Context

- Machine Learning has become a powerful tool for various applications
- Modelling of complex functions for processing/analysing/interpreting data
- State-of-the-art models: Deep Neural Network (DNN)
- Requires huge computational and memory resources
- Especially for training but also for the deployed systems
- Common solution: cloud computing

Introduction

DNN models for image classification (ImageNet)



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Low-Power Approximations of CNN

Context

• Can DNNs be integrated in embedded systems, mobile and low-power devices?



Motivation

- Reducing server maintenance costs,
- Scalability,
- Reducing network transfer and lag,
- Privacy
- Reducing environmental impact

Outline



2 Deep Neural Network Models

3 Neural Network Compression



Weight quantisation with dyadic rationals

Model overview



Basic operations:

Model overview

Convolutions:

- high computational complexity
- low memory requirements
- Pooling: no memory and very fast
- Fully connected layers:
 - low computational complexity
 - high memory requirements
- Implementations heavily rely on parallelisation (using GPU)
 - \rightarrow high power consumption

Outline



Deep Neural Network Models



Neural Network Compression



Weight quantisation with dyadic rationals

Neural Network Compression

- Very large redundancy in trained DNN models (i.e. the weights)
- Some approaches try to avoid this during the design or training of a model (AutoML)
- Most current approaches:
 - Train a (highly redundant) DNN
 - 2 Compress the model
 - Retrain/refine the model (to compensate for errors)
- Recent DNN models: $\sim 10^6 10^7$ parameters, $\sim 10^2$ MB
- Compression rates: $\sim 1: 10 1: 200$
- Very little or no loss in classification performance!

Compression Approaches



Existing code and solutions

- Many implementations on-line (github etc.)
- Tensorflow Lite
- Core ML (Apple)
- CNTK netopt module (Microsoft)
- MXNet quantisation API (Apache) (BMXnet)
- PyTorch pruning/quantization package
- Deep Learning framework N2D2 (CEA LIST) (https://github.com/CEA-LIST/N2D2)
- Apache TVM
- Alibaba MNN
- Hardware-oriented: NVIDIA, Xilinx VITIS

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Weight quantisation with dyadic rationals

Our approach

- Post-training quantisation method
- We focus on <u>low-power</u> approximations
- Approximate weights by dyadic rationals
 →all multiplications replaced by bit-shifts and additions
- We approximate each convolution matrix M individually by:

$$\hat{\mathbf{M}} = \alpha^* \mathbf{T}^* . \tag{1}$$

• Each element of \mathbf{T}^* is a dyadic rational $m/2^n$ from a set \mathcal{D}

Examples of ${\mathcal D}$

$$\begin{aligned} \mathcal{D}_{1} &= \{-1, 0, 1\}, \\ \mathcal{D}_{2} &= \{-2, -1, 0, 1, 2\}, \\ \mathcal{D}_{3} &= \{-4, -3, -2, -1, 0, 1, 2, 3, 4\}, \\ \mathcal{D}_{4} &= \left\{-4, -3, -2, -1, -\frac{3}{4}, -\frac{1}{2}, -\frac{1}{4}, 0, \frac{1}{4}, \frac{1}{2}, \frac{3}{4}, 1, 2, 3, 4\right\}, \\ \mathcal{D}_{5} &= \left\{-7, -6, -5, -4, -3, -2, -1, -\frac{3}{4}, -\frac{1}{2}, -\frac{1}{4}, 0, \\ &\qquad \frac{1}{4}, \frac{1}{2}, \frac{3}{4}, 1, 2, 3, 4, 5, 6, 7\right\}, \\ \mathcal{D}_{6} &= \left\{-4, -\frac{15}{4}, -\frac{7}{2}, -\frac{13}{4}, \dots, \frac{13}{4}, \frac{7}{2}, \frac{15}{4}, 4\right\}, \\ \mathcal{D}_{7} &= \left\{-5, -\frac{19}{4}, -\frac{9}{2}, -\frac{17}{4}, \dots, \frac{17}{4}, \frac{9}{2}, \frac{19}{4}, 5\right\}\end{aligned}$$

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Low-Power Approximations of CNN

CSD representation

• $\alpha^* > 0 \in \mathbb{R}$ is a expansion factor approximated by the closest CSD representation (Canonical Signed Digit encoding)

• CSD:

- CSD presentation of a number consists of numbers 0, 1 and -1.
- The CSD presentation of a number is unique.
- The number of nonzero digits is minimal.
- There cannot be two consecutive non-zero digits.
- Example: 1 0010 000-1 = 256 + 32 -1 = 287

Optimisation

• We formulate this as an optimisation problem:

$$(\alpha^*, \mathbf{T}^*) = \arg\min_{\alpha, \mathbf{T}} \|\mathbf{M} - \alpha \cdot \mathbf{T}\|^2,$$

- Frobenius norm $\|\mathbf{M}\| = \sqrt{\sum_{i=1}^{m} \sum_{j=1}^{n} |m_{i,j}|}$
- Mixed integer non-linear programming (INLP)

(2)

Optimisation

- Linearisation of problem
- $\mathbf{M} = [m_{i,j}]$ $i, j = 1, 2, \dots, N$ and $r \in \mathcal{D}$
- binary decision variables:

$$x_{i,j}(r) = egin{cases} 1, & ext{if } m_{i,j} = r, \ 0, & ext{otherwise.} \end{cases}$$

• (2) can be re-written according to the following binary linear programming problem:

$$\min_{x_{i,j}(r)} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{r \in \mathcal{D}} (r - \alpha \cdot m_{i,j})^2 \cdot x_{i,j}(r),$$
(3)

subject to

$$\sum_{r \in \mathcal{D}} x_{i,j}(r) = 1, \qquad i, j = 1, 2, \dots, N.$$

Optimisation

• Each entry of T_{α} can be computed as:

$$t_{i,j}^{(\alpha)} = \sum_{r \in \mathcal{D}} r \cdot x_{i,j}^{(\alpha)}(r).$$
(4)

Resulting approximation error:

$$\operatorname{Error}(\alpha) = \|\mathbf{M} - \alpha \cdot \mathbf{T}_{\alpha}\|^{2}.$$

- Can be solved in $\mathcal{O}(N)$
- Global optimum value α^* :

$$\alpha^* = \arg\min_{\alpha} \operatorname{Error}(\alpha), \tag{5}$$

• Solved by simple minimization over a vector of values.

Example

$$\mathbf{M}_0 = \begin{bmatrix} 1.5200701 & 1.0317051 & 0.7906240 & -0.2153791 & -0.2340538 \\ 1.3982610 & 2.1860176 & 2.0152923 & 1.5620477 & 0.8270900 \\ -0.6848867 & 0.7470516 & 1.6923728 & 1.2537112 & 1.1946758 \\ -1.2387477 & -0.5483563 & 0.1261987 & 0.8677799 & 0.7742613 \\ -1.4691808 & -1.2178997 & -0.2924347 & 0.2172496 & 0.1325074 \end{bmatrix}$$

.

Example

Solving (2) for the above matrix using \mathcal{D}_8 , we obtain:

$$\begin{split} \alpha^* &= 0.30931, \\ \mathbf{T}^* &= \begin{bmatrix} 5 & 3.25 & 2.5 & -0.75 & -0.75 \\ 4.5 & 7 & 6.5 & 5 & 2.75 \\ -2.25 & 2.5 & 5.5 & 4 & 3.75 \\ -4 & -1.75 & 0.5 & 2.75 & 2.5 \\ -4.75 & -4 & -1 & 0.75 & 0.5 \end{bmatrix} \\ &= \frac{1}{4} \cdot \begin{bmatrix} 20 & 13 & 10 & -3 & -3 \\ 18 & 28 & 26 & 20 & 11 \\ -9 & 10 & 22 & 16 & 15 \\ -16 & -7 & 2 & 11 & 10 \\ -19 & -16 & -4 & 3 & 2 \end{bmatrix}. \end{split}$$

Example

- CSD approximation of α^* : $\alpha^* = 0.30931 \approx 2^{-2} + 2^{-4} - 2^{-8} = 0.30859375.$
- Fully multiplierless approximation:

$$\hat{\mathbf{M}} = (2^{-4} + 2^{-6} - 2^{-10}) \cdot \begin{bmatrix} 20 & 13 & 10 & -3 & -3 \\ 18 & 28 & 26 & 20 & 11 \\ -9 & 10 & 22 & 16 & 15 \\ -16 & -7 & 2 & 11 & 10 \\ -19 & -16 & -4 & 3 & 2 \end{bmatrix}$$

Results

• Tested on three different models of different complexity:

- Face detection CNN: 1k parameters, 97% of exact model
- MNIST: 180k parameters, 99% of exact model
- AlexNet/ImageNet: 1.2M convolution matrices, 96% of exact model
- Different approximations for different layers



Low-complexity face detection with our approach

approximate vs. exact



Results

Mean classification rates for the MNIST test set and different approximations relative to the exact model.

	Exact	ASG	PLAN	Linear I	Linear II	Quadratic I	Quadratic I
Exact	1.0000	1.0000	0.9847	0.9680	0.9978	1.0000	1.0000
A_1	0.9684	0.9684	0.9588	0.9260	0.9615	0.9684	0.9684
A_2	0.9643	0.9643	0.9627	0.8805	0.9573	0.9643	0.9643
A_3	0.9961	0.9961	0.9848	0.9655	0.9944	0.9961	0.9961
A_4	0.9973	0.9973	0.9863	0.9700	0.9969	0.9973	0.9973
A_5	0.9976	0.9976	0.9866	0.9666	0.9969	0.9976	0.9976
A_6	0.9991	0.9991	0.9868	0.9701	0.9973	0.9991	0.9991
A_7	0.9992	0.9992	0.9846	0.9680	0.9977	0.9992	0.9992
A_8	0.9994	0.9994	0.9848	0.9675	0.9981	0.9994	0.9994
$A_{3,3,1,1}$	0.9931	0.9931	0.9749	0.9625	0.9924	0.9931	0.9931
$A_{3,1,1,1}$	0.9891	0.9891	0.9684	0.9580	0.9866	0.9891	0.9891
$A_{4,4,1,1}$	0.9937	0.9937	0.9780	0.9618	0.9943	0.9937	0.9937
$A_{4,1,1,1}$	0.9885	0.9885	0.9655	0.9572	0.9872	0.9885	0.9885

Further information

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