## Online scheduling

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#### Outline

- Introduction
- 2 Studying an algorithm: the FIFO case
- 3 Lower bound on the competitive ratio of any algorithm: the clair-voyant max-stretch case
- 4 The non-clairvoyant case
- 5 How to derive a lower bound: the max-flow case with communications

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Nature of the problem Known

Objective function Known

Characteristics of the instance

Known beforehand

Offline

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When the job is released When the job completes

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(Clairvoyant) Online

Non-clairvoyant online

#### Notation and hypotheses

#### Notation

- ▶ Jobs  $J_1$ , ...,  $J_n$ Job  $J_j$  arrives in the system at date  $r_j$ Job  $J_j$  has a weight (or a priority)  $w_j$ Job  $J_j$  has an execution time  $p_j$  $\Delta$  is the ratio of the largest to the shortest execution time
- ► Completion time of job  $J_j$ :  $C_j$ Flow of job  $J_j$ :  $F_j = C_j - r_j$  (time spent in the system)

#### Hypotheses

- ▶ Job may be preempted
- ▶ One machine (1 | *pmtn* | ???)

### Evaluating the quality of an online schedule

An online algorithm has a competitive factor  $\rho$  if and only if

Whatever the set of jobs  $T_1$ , ...,  $T_n$ 

 $\begin{array}{l} \text{Online schedule } \operatorname{cost}(T_1,...,T_N) \leq \\ \rho \times \operatorname{Optimal off-line schedule } \operatorname{cost}(T_1,...,T_N) \end{array}$ 

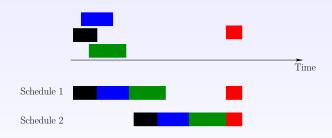
## What should we optimize?

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## What should we optimize?

- ▶ Makespan: max<sub>j</sub> C<sub>j</sub> Arrival dates are not taken into account
- Average flow or response time:  $\sum_{j} (C_j r_j)$ Inconvenient: starvation
- Maximum flow or maximum response time:  $\max_j (C_j r_j)$ No starvation. Favor long jobs. Worst-case optimization.
- Maximum weighted flow: max<sub>j</sub> w<sub>j</sub>(C<sub>j</sub> r<sub>j</sub>)
   Gives back some importance to short jobs.
   Particular case of the *stretch* or *slowdown*:
   w<sub>i</sub>=1/running time of the job on empty platform.

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#### FIFO competitiveness

#### **Theorem**

First come, first served is:

- optimal for the online minimization of max-flow
- $ightharpoonup \Delta$ -competitive for the online minimization of sum-flow
- lacktriangle  $\Delta$ -competitive for the online minimization of max-stretch
- lacktriangledown  $\Delta^2$ -competitive for the online minimization of sum-stretch

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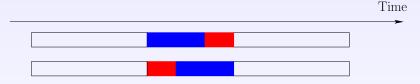
#### FIFO is optimal for max-flow

Consider any instance and a schedule  $\Theta$  s.t. there exists two jobs executed consecutively:  $J_i$  and  $J_j$  with  $r_i < r_j$  and  $C_i \geq C_j$ 

Time

#### FIFO is optimal for max-flow

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In schedule  $\Theta'$  we exchange the execution order of  $J_i$  and  $J_j$ 

$$\begin{aligned} \max_{1 \leq k \leq n} C_k' - r_k &= \max\{ \max_{\substack{1 \leq k \leq n \\ k \notin \{i,j\}}} C_k - r_k, \frac{C_i'}{r_i} - r_i, C_j' - r_j \} \\ C_i' - r_i &< C_i - r_i \quad \text{and} \quad C_j' - r_j = C_i - r_j < C_i - r_i \\ \Rightarrow \quad \max_{1 \leq k \leq n} C_k' - r_k \leq \max_{1 \leq k \leq n} C_k - r_k \end{aligned}$$

## FIFO competitiveness for max-stretch

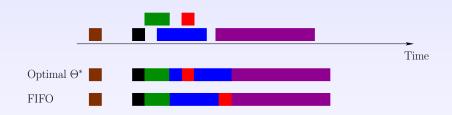
#### Theorem

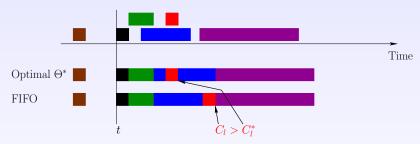
FIFO is  $\Delta$  competitive for maximum stretch minimization

#### This means that

- FIFO has a competitive factor of  $\Delta$  (i.e., on no instance is FIFO's max-stretch more than  $\Delta$  that of the optimal solution)
- 2 This bound is tight (=cannot be improved)



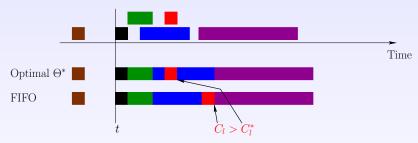




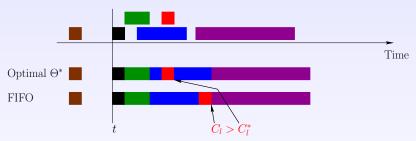
Any job  $J_l$  s.t.  $S_l > S_l^* \ (\Leftrightarrow C_l > C_l^*)$ 

t last time before  $\mathcal{C}_l$  s.t. the processor was idle under FIFO.

t is the release date  $r_i$  of some job  $J_i$ .

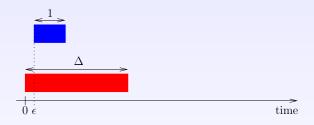


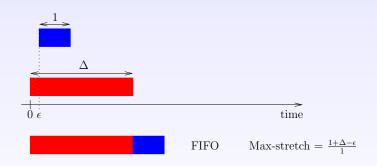
Any job  $J_l$  s.t.  $S_l > S_l^*$  ( $\Leftrightarrow C_l > C_l^*$ ) During  $[r_i, C_l]$ , FIFO exactly executes  $J_i$ ,  $J_{i+1}$ , ...,  $J_{l-1}$ ,  $J_l$ .

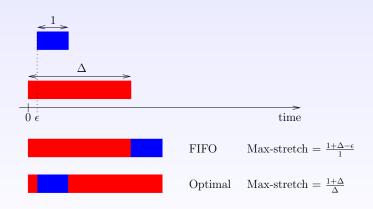


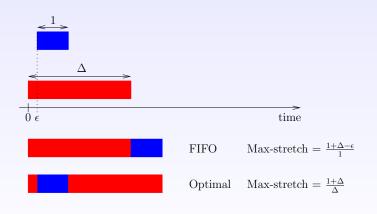
Any job  $J_l$  s.t.  $\mathcal{S}_l > \mathcal{S}_l^*$  ( $\Leftrightarrow C_l > C_l^*$ ) During  $[r_i, C_l]$ , FIFO exactly executes  $J_i$ ,  $J_{i+1}$ , ...,  $J_{l-1}$ ,  $J_l$ . As  $C_l^* < C_l$ , there is a job  $J_k$ ,  $i \leq k \leq l-1$  s.t.  $C_k^* \geq C_l$ . Then:

$$S^* = \max_{j} S_j^* \ge S_k^* = \frac{C_k^* - r_k}{p_k} \ge \frac{C_l - r_l}{p_k} = \frac{C_l - r_l}{p_l} \frac{p_l}{p_k} \ge S_l \times \frac{1}{\Delta}$$
$$\forall l, S_l > S_l^* \quad \Rightarrow \quad \Delta \times S^* \ge S_l$$









Competitive ratio: 
$$\frac{1+\Delta-\epsilon}{\frac{1+\Delta}{\Delta}} = \Delta \frac{1+\Delta-\epsilon}{1+\Delta} = \Delta - \epsilon \ \frac{\Delta}{1+\Delta} \geq \Delta - \epsilon$$

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### Bound on the competitive ratio

#### Theorem

On one processor, any online scheduling algorithm with preemption minimizing the max-stretch has a competitive ratio greater than  $\frac{1}{2}\Delta^{\sqrt{2}-1}$ , if the system receives at least jobs of three different sizes, and if  $\Delta$  is the ratio between the size of the largest and the smallest job.

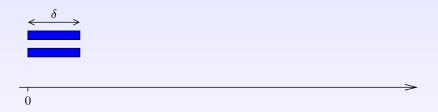
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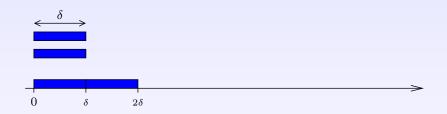
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**Proof principle**: by contradiction we assume that there exists an algorithm and we build a sequence of jobs and a scenario to make the algorithm fail.

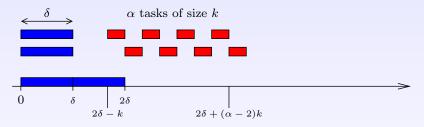




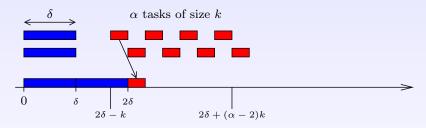


 $\mbox{Achievable stretch: } \frac{2\delta-0}{\delta}=2.$ 

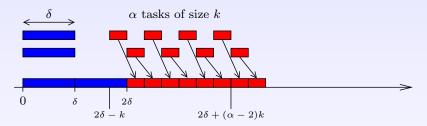




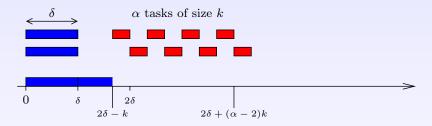
The job  $T_{2+j}$  arrives at time  $2\delta + (j-2)k$ .



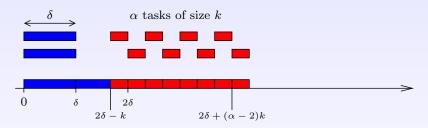
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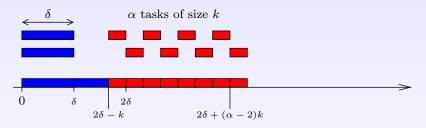
The job  $T_{2+j}$  arrives at time  $2\delta + (j-2)k$ .



In practice: we do not know what happens after  $2\delta-k$ .

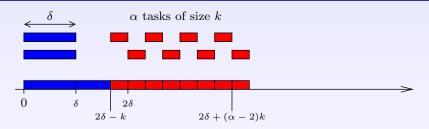


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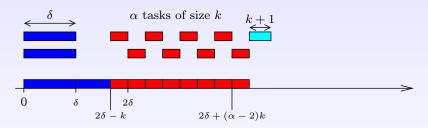
The algorithm being  $\frac{1}{2}\Delta^{\sqrt{2}-1}$ -competitive,  $T_1$  and  $T_2$  must be completed at the latest at time:  $2\cdot\frac{1}{2}\Delta^{\sqrt{2}-1}\cdot\delta=2\cdot\frac{1}{2}\left(\frac{\delta}{k}\right)^{\sqrt{2}-1}\cdot\delta$ 



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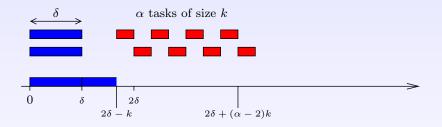
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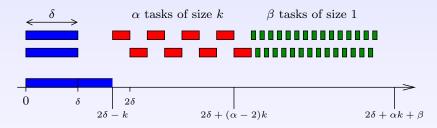
We let 
$$\alpha = \lceil 1 + k - \frac{2\delta}{k} \rceil$$
 and then  $2\delta + (\alpha - 1)k \ge 2 \cdot \frac{1}{2} \left( \frac{\delta}{k} \right)^{\sqrt{2} - 1} \cdot \delta$ .



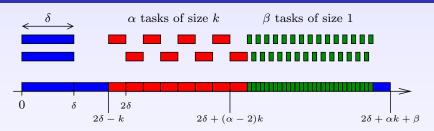
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The job  $T_{2+\alpha+j}$  arrives at time  $2\delta+(\alpha-1)k+(j-1)$ .



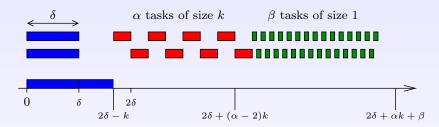
#### Achievable stretch (off-line)

Stretch of each job of size k or 1:1.

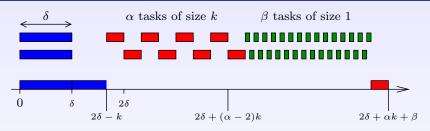
Stretch of 
$$T_1$$
 or  $T_2$ :  $\frac{2\delta + \alpha k + \beta}{\delta}$ 

$$\text{Optimal stretch} \leq \frac{2\delta + \alpha k + \beta}{\delta}$$





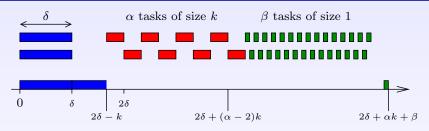
#### Achievable stretch (online)



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The last completed job is of size k.

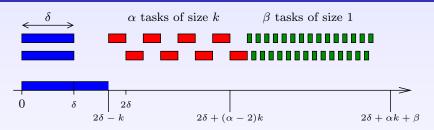
$$\mathsf{Stretch} \geq \frac{(2\delta + \alpha k + \beta) - (2\delta + (\alpha - 2)k)}{k} = 2 + \frac{\beta}{k}.$$



#### Achievable stretch (online)

The last completed job is of size 1.

$$\mathsf{Stretch} \geq \frac{(2\delta + \alpha k + \beta) - (2\delta + (\alpha - 1)k + (\beta - 1))}{1} = k + 1.$$



#### Achievable stretch (online)

$$\mathsf{Stretch} \geq \min \left\{ 2 + \frac{\beta}{k}, k + 1 \right\}$$

We let: 
$$\beta = \lceil k(k-1) \rceil$$

Then: stretch > k + 1.

# The adversary: summing things up

$$\alpha = \left\lceil 1 + k - \frac{2\delta}{k} \right\rceil$$

$$\beta = \lceil k(k-1) \rceil$$

$$\text{Optimal stretch} \leq \frac{2\delta + \alpha k + \beta}{\delta}$$

Achieved stretch  $\geq k + 1$ .

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We let 
$$k = \delta^{2-\sqrt{2}}$$

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Achieved stretch  $\geq k + 1$ .

We let 
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Therefore 
$$k+1 > \left(\frac{1}{2}\delta^{\sqrt{2}-1}\right)\left(\frac{2\delta + \alpha k + \beta}{\delta}\right)$$

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#### **Theorem**

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#### Lower bound as a function of n

#### Theorem

There is no c-competitive preemptive online algorithm minimizing the maximum stretch with c < n

#### Principle of the proof

- We suppose there exists an algorithm whose ratio  $c = n \epsilon$
- n jobs are released at time 0
- ▶ Whatever the scheduler does, no job completes before time n
- Jobs are sorted by non-decreasing cumulative computation time computed at time n: the (i+1)-th job is of size  $\lambda^{i-1}$
- ightharpoonup The maximum stretch is at least n (first job has size 1 and is not completed at n)
- Optimal: execute jobs in Shortest Processing Time first order:

$$\frac{\sum_{j=1}^{i} \lambda^{j-1}}{\lambda^{i-1}} = \frac{\lambda^{i} - 1}{\lambda^{i-1}(\lambda - 1)} \xrightarrow[\lambda \to +\infty]{} 1$$

## **EquiPartition**

#### Theorem

EquiPartition is n-competitive for the minimization of maximum stretch.

However, EquiPartition is at best  $\frac{\Delta+1}{2+\ln(\Delta)}$  competitive (when FIFO is  $\Delta$  competitive)

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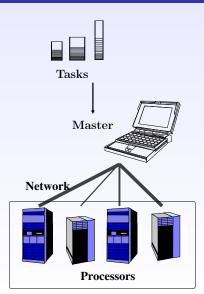
#### The scheduling problem

#### The scheduler

- Gather the tasks
- Send them to the processors

#### The aim

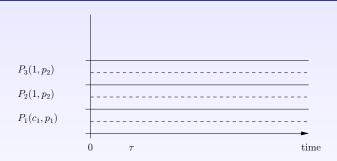
Distribute *identical* tasks to the processors, in order to process these tasks



## The scheduling problem

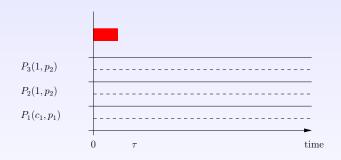
#### Formally

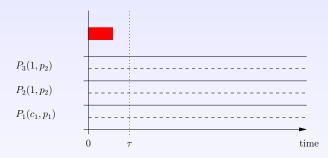
- ightharpoonup n tasks, m processors
- $ightharpoonup p_j$ : processing time of a task on processor j
- $ightharpoonup c_i$ : time to send a task from the master to the worker j
- $ightharpoonup r_i$ : arrival date
- $ightharpoonup C_i$ : completion time
- ▶ The objective function:
  - ightharpoonup maximal flow: max  $C_i r_i$



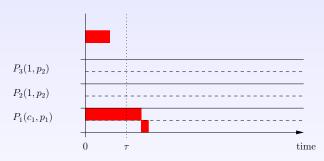
#### Idea:

- lacktriangle a fast processor with slow communications  $(c_1>1)$
- two identical and slow processors, with fast communications
- lacktriangle if only one task, one must choose the fast processor  $(c_1+p_1<1+p_2)$



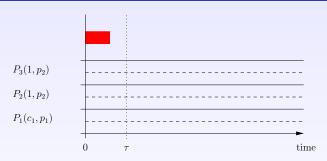


We look at time  $\tau \geq 1$  to see what has happened. Three possibilities:



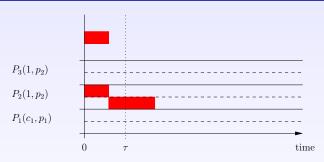
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① Optimal : task on  $P_1$ , max-flow  $\geq c_1 + p_1$ .



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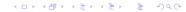
- **①** Optimal : task on  $P_1$ , max-flow  $\geq c_1 + p_1$ .
- **2** Nothing done: max-flow  $\geq \tau + c_1 + p_1$ , ratio  $\geq \frac{\tau + c_1 + p_1}{c_1 + p_1}$ .

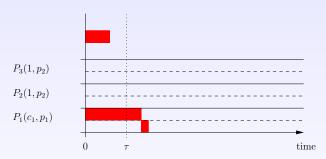


We look at time  $\tau \geq 1$  to see what has happened. Three possibilities:

- **①** Optimal : task on  $P_1$ , max-flow  $\geq c_1 + p_1$ .
- **②** Nothing done: max-flow  $\geq \tau + c_1 + p_1$ , ratio  $\geq \frac{\tau + c_1 + p_1}{c_1 + p_1}$ .
- **3** Task send to  $P_2$ , max-flow  $\geq 1 + p_2$ . Ratio  $\geq \frac{1+p_2}{c_1+p_1}$ .

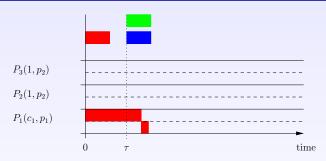
We want to force the algorithm to process the first task on  $P_1$ .



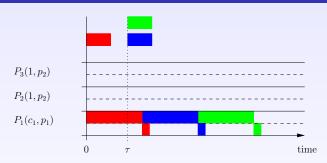


We look at time  $\tau \geq 1$  to see what has happened. We will choose  $\tau$ ,  $c_1$ ,  $p_1$  and  $p_2$  such that:

$$\min\left\{\frac{1+p_2}{c_1+p_1}, \frac{\tau+c_1+p_1}{c_1+p_1}\right\} \ge \rho$$



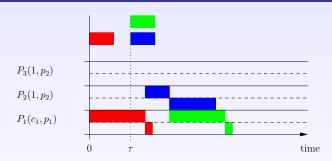
At time  $\tau$  we send two new tasks. We consider all the possible cases.



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The two tasks are executed on  $P_1$ :

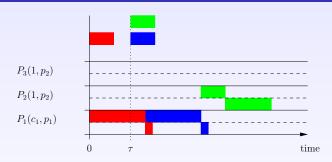
$$\max\{c_1+p_1,\\ \max\{\max\{c_1,\tau\}+c_1+p_1,c_1+2p_1\}-\tau,\\ \max\{\max\{c_1,\tau\}+c_1+p_1+\max\{c_1,p_1\},c_1+3p_1\}-\tau\}$$



At time  $\tau$  we send two new tasks.

The first of the two tasks is executed on  $P_2$  (or  $P_3$ ), and the other one on  $P_1$ .

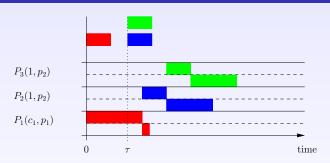
$$\max\{c_1 + p_1, \\ (\max\{c_1, \tau\} + c_2 + p_2) - \tau, \\ \max\{\max\{c_1, \tau\} + c_2 + c_1 + p_1, c_1 + 2p_1\} - \tau\} = 0$$



At time  $\tau$  we send two new tasks.

The first of the two tasks is executed on  $P_1$ , and the other one on  $P_2$  (or  $P_3$ ).

$$\max\{c_1 + p_1, \\ \max\{\max\{c_1, \tau\} + c_1 + p_1, c_1 + 2p_1\} - \tau, \\ (\max\{c_1, \tau\} + c_1 + c_2 + p_2) - \tau\}$$

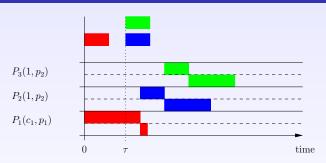


At time  $\tau$  we send two new tasks.

One of the two tasks is executed on  $P_2$  and the other one on  $P_3$ .

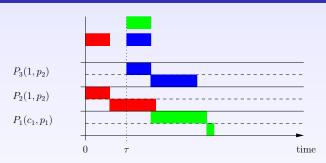
$$\max\{c_1+p_1, (\max\{c_1,\tau\}+c_2+p_2)-\tau, (\max\{c_1,\tau\}+c_2+c_2+p_2)-\tau\}$$





At time  $\tau$  we send two new tasks.

The case where both tasks are executed on  $P_2$  (or both on  $P_3$ ) is worse than the previous one, therefore, we do not need to study it.



At time  $\tau$  we send two new tasks.

The (desired) optimal: the first task on  $P_2$ , the second on  $P_3$ , and the third on  $P_1$ .

$$\max\{c_2+p_2, (\max\{c_2,\tau\}+c_2+p_2)-\tau, (\max\{c_2,\tau\}+c_2+c_1+p_1)-\tau\}$$



Lower bound on the competitiveness of any online algorithm:

```
\min \left\{ \begin{array}{l} \frac{\tau + c_1 + p_1}{c_1 + p_1}, \\ \frac{1 + p_2}{c_1 + p_1}, \\ \\ \min \left\{ \begin{array}{l} \max\{c_1 + p_1, \max\{\max\{c_1, \tau\} + c_1 + p_1, c_1 + 2p_1\} - \tau, \\ \max\{\max\{c_1, \tau\} + c_1 + p_1 + \max\{c_1, p_1\}, c_1 + 3p_1\} - \tau \right\} \\ \max\{c_1 + p_1, (\max\{c_1, \tau\} + c_2 + p_2) - \tau, \max\{\max\{c_1, \tau\} + c_2 + c_1 + p_1, c_1 + 2p_1\} - \tau \right\} \\ \max\{c_1 + p_1, \max\{\max\{c_1, \tau\} + c_1 + p_1, c_1 + 2p_1\} - \tau, (\max\{c_1, \tau\} + c_1 + c_2 + p_2) - \tau \right\} \\ \max\{c_1 + p_1, (\max\{c_1, \tau\} + c_2 + p_2) - \tau, (\max\{c_1, \tau\} + c_2 + c_2 + p_2) - \tau \right\} \\ \max\{c_2 + p_2, (\max\{c_2, \tau\} + c_2 + p_2) - \tau, (\max\{c_2, \tau\} + c_2 + c_1 + p_1) - \tau \right\} \\ \end{array} \right.
```

Constraints :  $c_1 + p_1 < 1 + p_2$ .

Numeric resolution

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- ② Characterization of the shape of the optimal :  $\tau < c_1$ ,  $p_1 = 0$ , etc.

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- New system:

$$\min \left\{ \begin{array}{l} \frac{\tau + c_1}{c_1} \\ \\ \frac{1 + p_2}{c_1} \\ \\ \min \left\{ \begin{array}{l} 3c_1 - \tau \\ c_1 + 1 - \tau + p_2 \\ 2c_1 - \tau + 1 + p_2 \\ c_1 + 2 + p_2 - \tau \\ \hline \end{array} \right. = \min \left\{ \begin{array}{l} \frac{\tau + c_1}{c_1} \\ \\ \frac{1 + p_2}{c_1} \\ \\ \frac{c_1 + 1 - \tau + p_2}{1 + p_2} \\ \\ \frac{c_1 + 2 + p_2 - \tau}{1 + p_2} \end{array} \right.$$

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• Solution:  $c_1=2(1+\sqrt{2}), \ p_2=\sqrt{2}c_1-1, \ \tau=2, \ \rho=\sqrt{2}.$ 

