

Versions simplifiées du tenseur de courbure

- **Tenseur de Ricci**

$$\text{Ric}(X, Y) := \text{tr} (g(R(\cdot, X)Y, \cdot))$$

$\begin{pmatrix} 2 \\ 9 \end{pmatrix}$ -tenseur

$$= \sum_{i=1}^m g(R(e_i, X)Y, e_i)$$

où e_1, \dots, e_m base orthonormale de $T_q M$

Rmq $\text{Ric}(X, Y) = \text{Ric}(Y, X)$

- Courbure scalaire $S = t_n(Ric) = \sum_{i=1}^m Ric(e_i, e_i)$
 $S \in C^\infty(M)$

Excuses

(M, g) est une variété Einstein quand

$$Ric = f g, \quad \text{où } f \in C^\infty(M)$$

$$\begin{cases} t_n(g) = m = \dim(M) \\ f = \frac{1}{m} t_n(Ric) = \frac{S}{m} \end{cases}$$

Thm $\hat{S}(g) := \text{Vol}(M, g)^{\frac{2-m}{m}} \int_M S_g \text{vol}_g$

$\boxed{\text{Crit}(\hat{S}) = \{\text{métriques Einstein}\}}$

- Courbure sectionnelle

$$K(\Pi) := \frac{R(X, Y, Y, X)}{\|X\|^2 \|Y\|^2 - g(X, Y)^2}$$

où $\Pi = \text{span}\{X, Y\} \subset T_q M$

$$\dim \Pi = 2$$

Rmq K est bien définie

$$K(\pi) = \frac{g(R(X, Y)Y, X)}{\|X\|_g^2 \|Y\|_g^2 - g(X, Y)^2} = g(R(E_1, E_2)E_2, E_1)$$

ssi $T\Gamma = \text{span}\{X, Y\} = \text{span}\{E_1, E_2\}$, $\|E_i\|_g = 1$
 $g(E_1, E_2) = 0$

$$\left. \begin{aligned} & A \in \text{End}(T_q M), \quad AE_1 = X, \quad AE_2 = Y \\ & g(R(X, Y)Y, X) = g(R(AE_1, AE_2)AE_2, AE_1) = \underbrace{(\det A)^2}_{\|X\|_g^2 \|Y\|_g^2 - g(X, Y)^2} g(R(E_1, E_2)E_2, E_1) \end{aligned} \right\}$$

Rappel.

V espace vectoriel, $\dim(V) = n$

$$\omega \in \bigwedge^n V$$

$$\omega : \underbrace{V \times \dots \times V}_m \rightarrow \mathbb{R}$$

$$\omega(v_1, \dots, v_m) = (-1)^{\sigma} \omega(v_{\sigma(1)}, \dots, v_{\sigma(m)})$$

$\forall \sigma$ permutation
de $\{1, \dots, n\}$

$\forall A : V \rightarrow V$ linéaire

$$\omega(Av_1, \dots, Av_m) = \det(A) \omega(v_1, \dots, v_m)$$

Rmq La courbure sectionnelle K détermine le tenseur de Riemann

Preuve

$$Q(X, Y) = g(R(X, Y)Y, X) = K(\text{span}\{X, Y\}) \left(\|X\|^2 \|Y\|^2 - g(X, Y)^2 \right)$$

(bien déf. $\forall X, Y \in T_q M$; $Q(X, X) = 0$)

$$g(R(X, Z)Z, Y) = \frac{1}{2} \left(Q(X+Y, Z) - Q(X, Z) - Q(Y, Z) \right)$$

$$g(R(X, Z+W)(Z+W), Y)$$

$$\begin{aligned} &= g(R(X, Z)Z, Y) + g(R(X, W)W, Y) \\ &\quad + g(R(X, Z)W, Y) + g(R(X, W)Z, Y) \end{aligned}$$

$$K \rightsquigarrow Q \rightsquigarrow R(X, Z)W + R(X, W)Z$$

si R' ($\frac{3}{1}$)-tenseur avec les symétries du tenseur de Riemann, $Q'(X, Y) := R'(X, Y, Y, X)$

$$Q = Q' \Rightarrow R(X, Z)W - R'(X, Z)W = R'(X, W)Z - R(X, W)Z$$

$$\Rightarrow R = R'$$

(Bianchi)

Prop Si K est constante sur toute fibre de TM ,
 i.e. $K(\pi) = K_0(x) \quad \forall \pi \in T_x M$ 2-plan
 alors $R(X, Y)Z = K_0 \cdot (g(Y, Z)X - g(X, Z)Y)$

Preuve $R'(X, Y)Z = K_0(g(Y, Z)X - g(X, Z)Y)$

$R'(X, Y) = -R'(Y, X), \quad g(R'(X, Y)W, Z) = g(R'(W, Z)X, Y)$

$R'(X, Y)W + R'(Y, W)X + R'(W, X)Y = 0$

$Q'(X, Y) = g(R'(X, Y)Y, X) = K_0 (||Y||^2 ||X||^2 - g(X, Y)^2)$
 $= Q(X, Y)$ □

COURBURE DES SOUS-VARIÉTÉS RIEM

$$(M, g) \xrightarrow[\text{incl}]{\iota} (\tilde{M}, \tilde{g}) \quad \begin{matrix} \text{sous-variété riemannienne} \\ (\tilde{g} = \iota^* \tilde{g}) \end{matrix}$$

∇ $\tilde{\nabla}$

Levi-Civita

$$N_x M = \{ v \in T_x \tilde{M} \mid \tilde{g}(v, w) = 0 \quad \forall w \in T_x M \}, \quad x \in M$$

$$x \in M, v \in T_x \tilde{M} \quad \text{et écrit comme} \quad v = \underbrace{v^T}_{\in \tilde{T}_x M} + \underbrace{v^N}_{\in N_x M}$$

On a déjà vu. $\nabla_x Y = (\tilde{\nabla}_x Y)^T$

$\forall X, Y \in \Gamma(TM)$

$$\tilde{\nabla}_X Y \Big|_M = \nabla_X Y + \underbrace{(\tilde{\nabla}_X Y)^N}_{= \cdot \boxed{\Pi(X, Y)}}$$

2-ème
FORME
FONDAMENTALE

Rmq Π est un tenseur. $\Pi \in \Gamma(T^*M \otimes T^*M \otimes NM)$

$$\left(\begin{array}{l} f \in C^\infty(M) \\ \Pi(fX, Y) = f \Pi(X, Y) \\ \Pi(X, fY) = \tilde{\nabla}_X (fY)^N = (Xf) \underbrace{Y^N}_0 + f (\tilde{\nabla}_X Y)^N = f \Pi(X, Y) \end{array} \right)$$

Rmng $\text{II}(X, Y) = \text{II}(Y, X)$

$$\left(\text{II}(X, Y) - \text{II}(Y, X) = \left(\tilde{\nabla}_X Y - \tilde{\nabla}_Y X \right)^N = [X, Y]^N = 0 \right)$$

Equation de Weingarten

$\forall N \in \Gamma(NM), X, Y \in \Gamma(TM)$

$$\tilde{g}(\tilde{\nabla}_X N, Y) = -\tilde{g}(N, \text{II}(X, Y))$$

Preuve $\tilde{g}(\tilde{\nabla}_X N, Y) = X \underbrace{\tilde{g}(N, Y)}_{\equiv 0} - \tilde{g}(N, \underbrace{\tilde{\nabla}_X Y}_{\text{II}(X, Y)})$

□

$$R = \text{tenseur de Riemann de } (M, g) \quad (M, g) \hookrightarrow (\tilde{M}, \tilde{g})$$

$$\tilde{R} = " " " " " (\tilde{M}, \tilde{g})$$

Prop $\forall X, Y, W, Z$ champs de vecteurs sur M

$$\begin{aligned}\tilde{g}(\tilde{R}(X, Y)W, Z) &= g(R(X, Y)W, Z) - \tilde{g}(\Pi(X, Z), \Pi(Y, W)) \\ &\quad + \tilde{g}(\Pi(X, W), \Pi(Y, Z))\end{aligned}$$

$$\begin{aligned}\text{Proof LHS.} &= \tilde{g}(\tilde{\nabla}_X \tilde{\nabla}_Y W - \tilde{\nabla}_Y \tilde{\nabla}_X W - \tilde{\nabla}_{[X, Y]} W, Z) \\ &= \tilde{g}(\tilde{\nabla}_X \nabla_Y W - \tilde{\nabla}_Y \nabla_X W - \nabla_{[X, Y]} W + \tilde{\nabla}_X \Pi(Y, W) - \tilde{\nabla}_Y \Pi(X, W), Z) \\ &= g(R(X, Y)W, Z) + \tilde{g}(\tilde{\nabla}_X \Pi(Y, W) - \tilde{\nabla}_Y \Pi(X, W), Z)\end{aligned}$$

$$\begin{aligned} &= g(R(X, Y)W, Z) - \tilde{g}(II(Y, W), II(X, Z)) \\ &\quad + \tilde{g}(II(X, W), II(Y, Z)) \end{aligned}$$

□

SURFACES EMBEDDED IN \mathbb{R}^3

espace euclidien

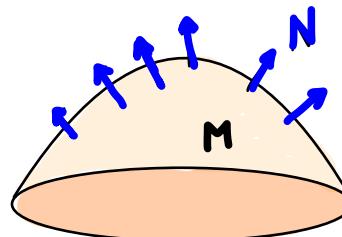
$$(M^2, g) \hookrightarrow (\tilde{M}, \tilde{g}) = (\overbrace{\mathbb{R}^3}^{\text{espace euclidien}}, \langle , \rangle)$$

$$\tilde{R} = 0, \quad \nabla_x (f \partial_{x^j}) = (Xf) \partial_{x^j}$$

Supposons $\exists N \in \Gamma(NM)$

$$\|N\| = 1$$

($\forall n \in \mathbb{N}$, M orientable,
donc $\forall n$ localement)



Application de Gauss

$x \in M$

$$G_x(v) = \tilde{\nabla}_v N$$

G est une endomorphisme (linéaire) $G_x \in \text{End}(T_x M)$

$$\left(\text{car } \langle \tilde{\nabla}_v N, N \rangle = \frac{1}{2} \underbrace{\|N\|^2}_{\equiv 1} \equiv 0 \right)$$

Courbure de Gauss de (M, g)

$$K_{\text{gauss}} : M \rightarrow \mathbb{R}, \quad K_{\text{gauss}}(x) := \det(G_x)$$

("Théorème remarquable")

Theorema egregium (Gauss, 1827)

K_{gauss} est intrinsèque, i.e elle ne dépend que de (M, g) , et pas du plongement $M \hookrightarrow \mathbb{R}^3$

En fait $K_{\text{gauss}}(x) = \underbrace{K(T_x M)}_{\substack{\text{courbure} \\ \text{sectionnelle}}}$

Preuve

Dans un voisinage $U \subset M$ de x on a un repère orthonormé $E_1, E_2 \in \Gamma(TU)$

$$\begin{pmatrix} \|E_1\|_g = \|E_2\|_g = 1 \\ g(E_1, E_2) = 0 \end{pmatrix}$$

On exprime G_x dans la base E_1, E_2 .

$$K_{gauv}(x) \quad G_x = \begin{pmatrix} \langle \tilde{\nabla}_{E_1} N, E_1 \rangle & \langle \tilde{\nabla}_{E_1} N, E_2 \rangle \\ \langle \tilde{\nabla}_{E_2} N, E_1 \rangle & \langle \tilde{\nabla}_{E_2} N, E_2 \rangle \end{pmatrix}$$

$$\begin{aligned} \det(G_x) &= \langle \tilde{\nabla}_{E_1} N, E_1 \rangle \langle \tilde{\nabla}_{E_2} N, E_2 \rangle - \langle \tilde{\nabla}_{E_2} N, E_1 \rangle \langle \tilde{\nabla}_{E_1} N, E_2 \rangle \\ &= \langle N, \text{II}(E_1, E_1) \rangle \langle N, \text{II}(E_2, E_2) \rangle - \langle N, \text{II}(E_2, E_1) \rangle \langle N, \text{II}(E_1, E_2) \rangle \end{aligned}$$

$$= \langle \Pi(E_1, E_1), \Pi(E_2, E_2) \rangle - \|\Pi(E_1, E_2)\|^2$$

$$= g(R(E_1, E_2)E_2, E_1) = K(T_x M)$$

|

$$\tilde{R} = 0$$

□

Rmq La courbure de Gauss est la seule courbure intrinsèque d'une surface riemann.

$$g(R(X, Y)Z, W) = \underbrace{K}_{\text{courbure}} \left(g(Y, Z)g(X, W) - g(X, Z)g(Y, W) \right)$$

Gauss

$$Ric(X, W) = K \left(\underbrace{\sum_{i=1,2} g(E_i, E_i)}_2 g(X, W) - \underbrace{\sum_{i=1,2} g(X, E_i) g(W, E_i)}_{g(X, W)} \right)$$

$$= K g(X, W)$$

$$S = t_n(Ric) = 2K$$

Rmq Toute surface riemannienne est une variété Einstein

Curiosité Toute variété einsteinienne (M^n, g)
de dim $n \geq 3$ a courbure scalaire constante

(Faux en dim $n = 2$)

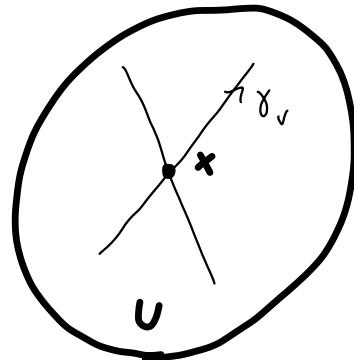
Preuve (M^n, g) Einstein, $Ric = \frac{S}{n} g$

$$\nabla_X Ric = \frac{1}{n} \left((XS)g + S \underbrace{\nabla_X g}_0 \right) = \frac{1}{n} (XS)g$$

E_1, \dots, E_m repère orthonormale, $\nabla E_i|_x = 0$
 $x \in M$ fixé

$E_1(x), \dots, E_m(x)$ base orth de $T_x M$

$$\forall v \in T_x M \quad \|v\|_g = 1$$



$$\gamma_v(t) = \exp_{p_x}(t v)$$

$E_i(\gamma_v(t))$ = transp parallèle
de $E_i(x)$
le long γ_v

$$\nabla_{\dot{\gamma}_v(t)} E_i \equiv 0 \quad \Rightarrow \quad \nabla_v E_i = \nabla_{\dot{\gamma}_v(0)} E_i = 0$$

$\forall t \in (-\varepsilon, \varepsilon)$

$$\forall v \in T_x M, \|v\|_g = 1$$



en x.

$$\sum_i (\nabla_{E_i} R_{1c})(E_j, E_i) = \sum_{i, k} \nabla_{E_i} (g(R(E_k), E_k))(E_j, E_i)$$

$$= \sum_{i, k} g((\nabla_{E_i} R)(E_k, E_j) E_i, E_k)$$

$$= \sum_{i, k} (-g((\nabla_{E_k} R)(E_j, E_i) E_i, E_k))$$

↑
2-eme
Bianchi

$$- g((\nabla_{E_j} R)(E_i, E_k) E_i, E_k)$$

$$= \sum_{i, k} (-E_k g(R(E_j, E_i) E_i, E_k) - E_j g(R(E_i, E_k) E_i, E_k))$$

$$= E_J S - \sum_K E_K (Ric(E_J, E_K))$$

$$\Rightarrow \sum_i \underbrace{E_i (Ric(E_J, E_i))}_{(\nabla_{E_i} Ric)(E_J, E_i)} = \frac{1}{2} E_J S$$

$$\stackrel{\text{"}}{=} (\nabla_{E_i} Ric)(E_J, E_i)$$

$$\frac{1}{m} (E_i S) g(E_J, E_i)$$

$$\Rightarrow \frac{1}{m} E_J S = \frac{1}{2} E_J S \quad \Rightarrow \quad \begin{matrix} \text{if } m \geq 3, \text{ alors} \\ dS \equiv 0 \end{matrix}$$

