Solutions for Exercise sheet 1 : Gaussian vectors, random walks.

- **Solution 1** Gaussian vectors. (1) The parameters are the mean $\mu \in \mathbb{R}$ and the variance $\sigma^2 \geq 0$. When $\sigma^2 = 0$, the distribution is just the Dirac in μ , and when $\sigma^2 > 0$, it has pdf $f(t) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-t^2/(2\sigma^2)}$. In both cases the characteristic function is $\phi(t) = e^{i\mu t \sigma^2/2t^2}$.
 - (2) This is immediate to check. By decomposing on the standard Euclidean basis it turns out that $m_i = \mathbb{E}[X_i]$ and $\Sigma_{i,j} = \text{Cov}(X_i, X_j)$. We call those the mean vector and the covariance matrix of X.
 - (3) We have that $\langle t, X \rangle$ is a Gaussian of mean $\langle t, m \rangle$ and variance $\langle t, \Sigma t \rangle$. So by taking the characteristic function of $\langle t, X \rangle$ at point 1 we get $\mathbb{E}[e^{i\langle t, X \rangle}] = \exp(i\langle t, m \rangle - \frac{1}{2}\langle t, \Sigma t \rangle)$. So the distribution of X is completely characterized by the parameters m and Σ .
 - (4) Compute $\mathbb{E}[e^{i\langle t,Ax\rangle}] = \mathbb{E}[e^{i\langle \mathsf{T}At,x\rangle}] = \exp(i\langle \mathsf{T}At,m\rangle \frac{1}{2}\langle \mathsf{T}At,\Sigma^{\mathsf{T}}At\rangle) = \exp(i\langle t,Am\rangle \frac{1}{2}\langle t,A\Sigma^{\mathsf{T}}At\rangle)$. Gaussianity and identification of the parameters follows.
 - (5) If we have the independence condition, then for $t \in V_1$ and $s \in V_2$, we have $\operatorname{Cov}[\langle t, X \rangle, \langle s, X \rangle] = 0$ by Fubini's theorem (justified since everybody is in L^2). But the converse is also true: Suppose that for every $t \in V_1$ and $s \in V_2$, we have $\operatorname{Cov}[\langle t, X \rangle, \langle s, X \rangle] = 0$. Let f_1, \ldots, f_m be a finite family in V_1 followed by a finite family in V_2 . Set $Y = (\langle f_1, X \rangle, \ldots, \langle f_m, X \rangle) = (Y_1, Y_2)$. Then, by computing covariances, we see that the covariance matrix of Y is block-diagonal. This means that we have a product decomposition $\mathbb{E}[e^{i\langle \langle t_1, Y^1 \rangle + \langle t_2, Y_2 \rangle}] = \mathbb{E}[e^{i\langle t_1, Y_1 \rangle}] \mathbb{E}[e^{i\langle t_2, Y_2 \rangle}]$. By injectivity of the characteristic distribution, we have identified the distribution of (Y_1, Y_2) as one of an independent couple of two Gaussian vectors. Now because by definition the σ -algebra spanned by a family of variables is generated by the finite subfamilies, we get the independence of the two σ -algebras.
 - (6) The classic example : set (X, A) to be an independent couple of a standard Gaussian and a Rademacher variable (uniform on $\{\pm 1\}$). Set Y = AX. Then Y is not independent of X ($\mathbb{P}(X > 0, Y > 0) = 0 \neq 1/4$). Yet $Cov(X, Y) = \mathbb{E}[AX^2] = \mathbb{E}[A]\mathbb{E}[X^2] = 0 \times 1 = 0$.
 - (7) If $X = (X_1, \ldots, X_n)$ then we compute $\mathbb{E}[e^{i\langle t, X \rangle}] = e^{-\frac{1}{2}\langle t, t \rangle}$. So it's Gaussian. For m a vector and Σ a semi-definite positive matrix, use the spectral theorem to write $\Sigma = {}^{\mathsf{T}}ODO$, and consider $Y = m + {}^{\mathsf{T}}O\sqrt{D}X$. It should have the prescribed parameters.

Solution 2 — Limit in distribution of Gaussian vectors.

Thanks to the student who found this neat proof of question 1 Let μ_n and σ_n be the parameters of X_n

(1) If we have convergence in distribution, then we have convergence of the characteristic functions to the one of the limit. So there exists a characteristic function $f : \mathbb{R} \to \mathbb{R}$ such that for all $t \in \mathbb{R}$, $f_n(t) = e^{i\mu_n t - \frac{\sigma_n^2}{2}t^2} \to f(t)$. Now taking the modulus then the log yields $\sigma_n^2 \to -\frac{2}{t^2}\log(|f(t)|) = \sigma^2 \ge 0$. We deduce that $|f(t)| = e^{-\frac{\sigma^2}{2}t^2}$. Now

$$e^{i\mu_n t} = e^{\frac{\sigma_n^2}{2}t^2} f_n(t) \to e^{\frac{\sigma^2}{2}t^2} f(t) =: u(t),$$

where u is a continuous function in \mathbb{C} of modulus 1 (with u(0) =: 1). Taking ϵ small enough so that the $\operatorname{Re}(u(t)) > 1/2$ for $t \in (0, \varepsilon)$, we can integrate the previous convergence and get

$$\frac{1}{i\mu_n}(e^{i\mu_n\varepsilon}-1)\to\int_{t=0}^\varepsilon u(t)dt\neq 0$$

Upon inverting then multiplying by $(e^{i\mu_n\varepsilon} - 1) \to u(\varepsilon) - 1$, we obtain that μ_n converges to $\frac{u(\varepsilon)-1}{i\int_{t=0}^{\varepsilon} u(t)dt}$. We then have convergence of the parameters, and $X \sim \mathcal{N}(\mu, \sigma^2)$ with $\mu = \lim \mu_n$ and $\sigma^2 = \lim \sigma_n^2$.

(2) By the first question, if there is convergence in probability, there is convergence in distribution, hence μ_n and σ_n converge. Since moments of Gaussian variables are polynomials in (μ_n, σ_n) , we have convergence of all moments. Hence $(X_n)_n$ is bounded in every L^p , p > 1. Hence $(|X_n|^{p'})$ is uniformly integrable for every p'. By Vitali's theorem, $X_n \to X$ in $L_{p'}$.

Solution 3 — Some estimates.

Let $(X_n)_{n\geq 0}$ be the simple symmetric random walk.

(1) $\mathbb{P}(X_{2n}=0) = {\binom{2n}{n}} 2^{-2n}$. Stirling's formula gives us

$$\mathbb{P}(X_{2n}=0) \sim \frac{1}{\sqrt{\pi n}}$$

(2) Using the ballot theorem for the walk between times 0 and n-1,

$$\mathbb{P}(X_n = 0, X_1 \cdots X_{n-1} \neq 0)$$

$$= \frac{1}{2} \mathbb{P}(X_{n-1} = -1, X_1 \cdots X_{n-2} \neq 0) + \frac{1}{2} \mathbb{P}(X_{n-1} = 1, X_1 \cdots X_{n-2} \neq 0)$$

$$= \frac{1}{n-1} (\frac{1}{2} \mathbb{P}(X_{n-1} = 1) + \frac{1}{2} \mathbb{P}(X_{n-1} = -1))$$

$$= \frac{1}{n-1} \mathbb{P}(X_n = 0)$$

Hence $\mathbb{P}(X_n = 0, X_1 \cdots X_{n-1} \neq 0) \sim \mathbb{1}_n \text{ even } \sqrt{\frac{2}{\pi}n^{-3/2}}.$

(3) By summation of equivalents,

$$\mathbb{P}(\tau_0 \ge k) = \sum_{n=k}^{\infty} \mathbb{P}(X_n = 0, X_1 \cdots X_{n-1} \ne 0) \sim \sqrt{\frac{2}{\pi}} \sum_{2n \ge k} (2n)^{-3/2} \sim \sqrt{\frac{2}{\pi}} 2^{-3/2} \frac{(k/2)^{-1/2}}{1/2} = \sqrt{\frac{2}{\pi k}} \sqrt{\frac{$$

(4) In class, you showed that $\frac{\mathbb{E}[|X_n|]}{n} = \mathbb{P}(\tau_0 > n)$, from which we deduce

$$\mathbb{E}[|X_n|] \sim \sqrt{\frac{2n}{\pi}}.$$

Solution 4 — Maximum and hitting times. Will be completed later.

Solution 5 — Conditioning and independence.

• Set $u(x) = \mathbb{E}[f(x,Y)] = \int f(x,y) d\mathbb{P}_Y(y)$. According to Fubini's theorem, u(x) is defined \mathbb{P}_X -a.e. Let us check that the almost-surely defined random variable u(X) satisfies the universal property required from the conditional expectation $\mathbb{E}[f(X,Y) \mid \mathcal{G}]$.

Let Z be a \mathcal{G} -measurable bounded random variable. Then $Zf(X,Y) \in L^1$, and since Y is independent of (X, Z), which means $\mathbb{P}_{(X,Z,Y)} = \mathbb{P}_{(X,Z)} \otimes \mathbb{P}_Y$.

We deduce

$$\mathbb{E}[Zf(X,Y)] = \int zf(x,y)d\mathbb{P}_{(X,Z,Y)}(x,z,y) = \int zf(x,y)d(\mathbb{P}_{(X,Z)}\otimes\mathbb{P}_Y)(x,z,y)$$
$$= \int z\left(\int f(x,y)d\mathbb{P}_Y(y)\right)d\mathbb{P}_{(X,Z)}(x,z) \text{ (Fubini)}$$
$$= \mathbb{E}[Zu(X)].$$

This proves the claim. I often write this very basic claim about conditional expectations as follows :

$$\mathbb{E}[f(X,Y) \mid \mathcal{G}] = \mathbb{E}[f(x,Y)]_{x=X}.$$

• We may now interpret this as a conditional distribution. Let $\mu(x, \cdot)$ denote the distribution of f(x, Y). Then for every bounded measurable ϕ ,

$$\mathbb{E}[\phi(f(X,Y))|\mathcal{G}] = \mathbb{E}[\phi(f(x,Y))]_{x=X} = \left(\int \phi(u)\mu(x,du)\right)_{x=X} = \int \phi(u)\mu(X,du).$$

This implies that the distribution of f(X, Y) given \mathcal{G} is $\mu(X, \cdot)$. In other words, μ is a conditional probability kernel for f(X, Y) given X.

Solution 6 — Gaussian conditional distribution and Bayesian statistics 101. (1) To do this, we project X on $\sigma(Y)$ to write

$$X = \frac{\operatorname{Cov}(X, Y)}{\operatorname{Var}(Y)}Y + \left(X - \frac{\operatorname{Cov}(X, Y)}{\operatorname{Var}(Y)}Y\right),$$

the two terms of this sum being uncorrelated hence independent, as they themselves form a Gaussian vector. Writing Z the second term, we end up with

$$X = \frac{\rho}{\sigma_Y^2} Y + Z$$

, where Z is independent of Y. We deduce $\operatorname{Var}(X) = \frac{\rho^2}{\sigma_Y^4} \operatorname{Var}(Y) + \operatorname{Var}(Z)$ (Pythagora's !), and hence $\operatorname{Var}(Z) = \sigma_X^2 - \frac{\rho^2}{\sigma_Y^2}$. Using the previous exercise, we deduce that the conditional probability kernel of X given Y is

$$(y,\cdot) \mapsto \mathbb{P}(\frac{\rho}{\sigma_Y^2}y + Z \in \cdot) = \mathcal{N}(\frac{\rho}{\sigma_Y^2}y, \sigma_X^2 - \frac{\rho^2}{\sigma_Y^2})(\cdot).$$

(3) Applying the previous question, we get that

$$\mathbb{P}_{\theta|\overline{X}=\overline{x}} = \mathcal{N}\left(\frac{\overline{x}}{1+\frac{\sigma^2}{n\tau^2}}, \frac{1}{\frac{n}{\sigma^2}+\frac{1}{\tau^2}}\right)$$

- (4) (a) The limit as $\sigma \to \infty$ is $\mathcal{N}(0, \tau^2)$. When the observations are very random, they give no information about θ .
 - (b) The limit as $\sigma \to 0$ is $\mathcal{N}(\overline{x}, 0) = \delta_{\overline{x}}$. When the observations are not random, they equal θ almost surely, hence the distribution of θ given the observations is not random.
 - (c) The limit as $\tau \to \infty$ is $\mathcal{N}(\overline{x}, \sigma^2/n)$. The prior distribution of θ is very random hence contains no information. That is why the conditional distribution given \overline{X} is not biased towards 0 anymore. Note that we recover the point of view of *inferential statistics*: when θ is unknown but deterministic, we indeed have $\theta - \overline{x} \sim \mathcal{N}(0, \sigma^2/n)$.
 - (d) The limit as $\tau \to 0$ is $\mathcal{N}(0,0) = \delta_0$. Indeed since the prior distribution of θ becomes deterministically equal to 0, then the posterior does too.
- (5) We may interpret this as follows: a real-world parameter θ must be measured. Prior (theoretical or based on the past) knowledge gives us its *a priori* distribution $\mathcal{N}(0, \tau^2)$. We are also given noisy measurements X_1, \ldots, X_n of this parameter, and wonder what the distribution of θ becomes after adding this supplementary information.
- (6) It turns out that the conditional distribution of θ given (X_1, \ldots, X_n) is the same as the one given \overline{X} . Indeed if we replay the proof of question 1 and project θ on \overline{X} , we get

$$\theta = \frac{n\tau^2}{n\tau^2 + \sigma^2}\overline{X} + Z,$$

and it turns out that not only $\operatorname{Cov}(\overline{X}, Z) = 0$ but also $\operatorname{Cov}(X_i, Z) = 0, 1 \le i \le n$. Hence we may continue as in question 1.