

Convex optimization

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Optimization: what ?

Whatever people do, at some point they get a craving to organize things in a best possible way. This intention, converted in a mathematical form, turns out to be an optimization problem of certain type.

(Yurii Nesterov)



Optimization: minimization problem

► Minimization problems

f : cost function

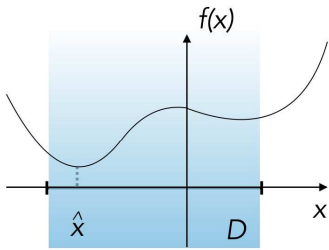
We want to

Find $\hat{x} \in D$ such that $(\forall x \in D) f(\hat{x}) \leq f(x)$

\Leftrightarrow Find $\hat{x} \in D$ such that $f(\hat{x}) = \inf_{x \in D} f(x)$

that is

Find $\hat{x} \in \underset{x \in D}{\text{Argmin}} f(x)$.



Optimization: minimization problem

► Maximization problems

f : reward function

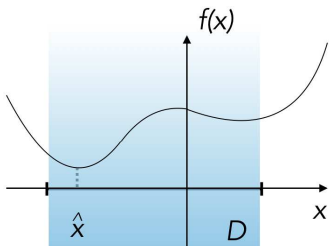
We want to

Find $\hat{x} \in D$ such that $(\forall x \in D) f(\hat{x}) \geq f(x)$

\Leftrightarrow Find $\hat{x} \in D$ such that $(\forall x \in D) -f(\hat{x}) \leq -f(x)$

\Leftrightarrow Find $\hat{x} \in \underset{x \in D}{\text{Argmin}} (-f(x))$.

Without loss of generality, we can focus on minimization problems with $f: D \rightarrow]-\infty, +\infty]$.



Various types of minimization problems

- ▶ D uncountable: continuous optimization problem
- ▶ Optimization problem with P equality constraints and Q inequality constraints:

$$D = \{x \in \mathbb{R}^N \mid (\forall i \in \{1, \dots, P\}) \varphi_i(x) = \delta_i \\ \text{and } (\forall j \in \{1, \dots, Q\}) \psi_j(x) \leq \eta_j\}$$

where $(\forall i \in \{1, \dots, P\}) \delta_i \in \mathbb{R}$ and $\varphi_i: \mathbb{R}^N \rightarrow]-\infty, +\infty]$,
 $(\forall j \in \{1, \dots, Q\}) \eta_j \in \mathbb{R}$ and $\psi_j: \mathbb{R}^N \rightarrow]-\infty, +\infty]$.

If $\varphi_i: x \mapsto \langle x \mid u_i \rangle$ with $i \in \{1, \dots, P\}$ and $u_i \in \mathbb{R}^N$, then *linear* (or affine) equality constraint.

If $\psi_j: x \mapsto \langle x \mid u_j \rangle$ with $j \in \{1, \dots, Q\}$ and $u_j \in \mathbb{R}^N$, then *linear* (or affine) inequality constraint.

Various types of minimization problems

Remark:

$$\begin{aligned}
 & \text{Find } \hat{x} \in \underset{x \in D}{\text{Argmin}} f(x) \\
 \Leftrightarrow & \text{Find } \hat{x} \in \underset{x \in \mathbb{R}^N}{\text{Argmin}} \tilde{f}(x)
 \end{aligned}$$

where

$$(\forall x \in \mathbb{R}^N) \quad \tilde{f}(x) = \begin{cases} f(x) & \text{if } x \in D \\ +\infty & \text{otherwise.} \end{cases}$$

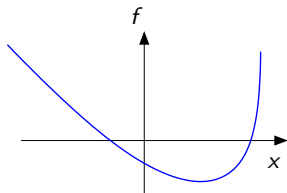
Allowing non finite valued functions leads to a unifying view of constrained and unconstrained minimization problems.

Convex/non-convex

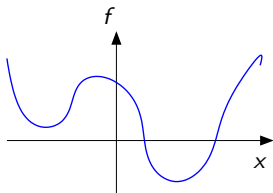
Let $f: \mathbb{R}^N \rightarrow]-\infty, +\infty]$. An unconstrained minimization problem aims to solve:

$$\hat{x} \in \operatorname{Argmin}_{x \in \mathbb{R}^N} f(x)$$

- Convex optimization and non-convex optimization



Fonction convexe



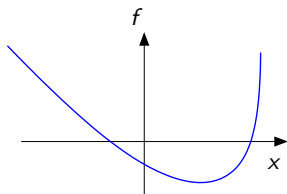
Fonction non-convexe

Convex/non-convex

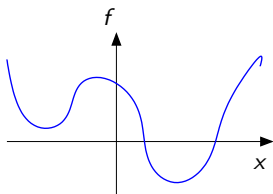
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- **Convex optimization** and non-convex optimization



Fonction convexe



Fonction non-convexe

Main questions to be addressed

1. Existence/uniqueness of a solution \hat{x} ?
2. Characterization of solutions: necessary/sufficient conditions for \hat{x} to be a solution.
3. Designing an algorithm to approximate a solution in the frequent case when no closed form solution is available, i.e. building a sequence $(x_n)_{n \in \mathbb{N}}$ of \mathbb{R}^N such that

$$\lim_{n \rightarrow +\infty} x_n = \hat{x}.$$

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1. **Existence/uniqueness** of a solution \hat{x} ?
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4. Evaluation of the performance of the optimization algorithm:

- ▶ **Convergence speed**

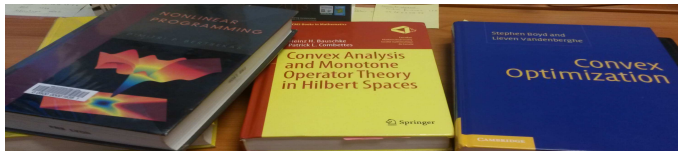
Example: If there exists $\rho \in]0, 1[$ and $n^* \in \mathbb{N}$ such that $(\forall n \geq n^*)$

$\|x_{n+1} - \hat{x}\| \leq \rho \|x_n - \hat{x}\|$, then *Q-linear* convergence rate.

If $\lim_{n \rightarrow +\infty} \frac{\|x_{n+1} - \hat{x}\|}{\|x_n - \hat{x}\|} = 0$, then *Q-superlinear* convergence rate.

- ▶ **Robustness** to numerical errors
- ▶ Amenability to **parallel/distributed implementations**.

Reference books



- ▶ **D. Bertsekas**, Nonlinear programming, Athena Scientific, Belmont, Massachussets, 1995.
- ▶ **Y. Nesterov**, Introductory Lectures on Convex Optimization: A Basic Course, Springer, 2004.
- ▶ **S. Boyd and L. Vandenberghe**, Convex optimization, Cambridge University Press, 2004.
- ▶ **H. H. Bauschke and P. L. Combettes**, Convex Analysis and Monotone Operator Theory in Hilbert Spaces, Springer, New York, 2011.

Hilbert spaces

Let \mathcal{H} and \mathcal{G} be two Hilbert spaces.

A linear operator $L: \mathcal{H} \rightarrow \mathcal{G}$ is **bounded** (or continuous) if

$$\|L\| = \sup_{\|x\|_{\mathcal{H}} \leq 1} \|Lx\|_{\mathcal{G}} < +\infty$$

Hilbert spaces

Let \mathcal{H} and \mathcal{G} be two Hilbert spaces.

Let $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$. Its **adjoint L^*** is the operator in $\mathcal{B}(\mathcal{G}, \mathcal{H})$ defined as

$$(\forall (x, y) \in \mathcal{H} \times \mathcal{G}) \quad \langle y \mid Lx \rangle = \langle L^*y \mid x \rangle.$$

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Example:

$$\text{If} \quad L: \mathcal{H} \rightarrow \mathcal{H}^n: x \mapsto (x, \dots, x)$$

$$\text{then} \quad L^*: \mathcal{H}^n \rightarrow \mathcal{H}: y = (y_1, \dots, y_n) \mapsto \sum_{i=1}^n y_i$$

Proof:

$$\langle Lx \mid y \rangle = \langle (x, \dots, x) \mid (y_1, \dots, y_n) \rangle = \sum_{i=1}^n \langle x \mid y_i \rangle = \left\langle x \mid \sum_{i=1}^n y_i \right\rangle$$

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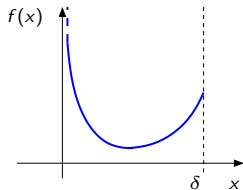
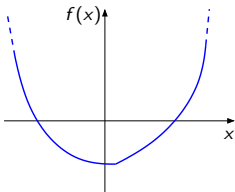
- ▶ We have $\|L^*\| = \|L\|$.
- ▶ If L is bijective (i.e. an **isomorphism**) then $L^{-1} \in \mathcal{B}(\mathcal{G}, \mathcal{H})$ and $(L^{-1})^* = (L^*)^{-1}$.
- ▶ If $\mathcal{H} = \mathbb{R}^N$ and $\mathcal{G} = \mathbb{R}^M$ then $L^* = L^\top$.

Functional analysis: definitions

Let $f : \mathcal{H} \rightarrow]-\infty, +\infty]$ where \mathcal{H} is a Hilbert space.

- ▶ The **domain** of f is $\text{dom } f = \{x \in \mathcal{H} \mid f(x) < +\infty\}$.
- ▶ The function f is **proper** if $\text{dom } f \neq \emptyset$.

Domains of the functions ?

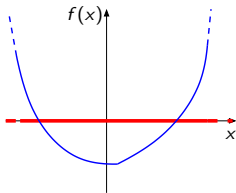


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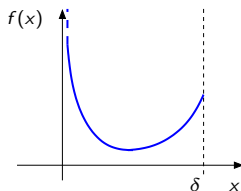
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Domains of the functions ?



$$\text{dom } f = \mathbb{R}$$

(proper)

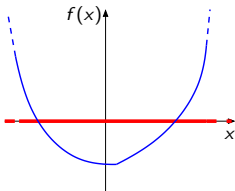


Functional analysis: definitions

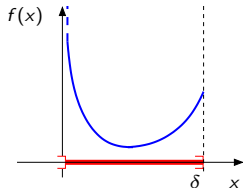
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Domains of the functions ?



$\text{dom } f = \mathbb{R}$
(proper)



$\text{dom } f =]0, \delta]$
(proper)

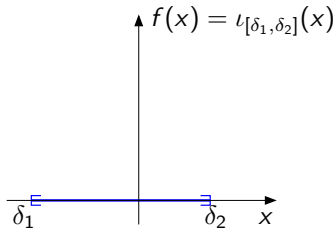
Functional analysis: definitions

Let $C \subset \mathcal{H}$.

The indicator function of C is

$$(\forall x \in \mathcal{H}) \quad \iota_C(x) = \begin{cases} 0 & \text{if } x \in C \\ +\infty & \text{otherwise.} \end{cases}$$

Example : $C = [\delta_1, \delta_2]$



Epigraph

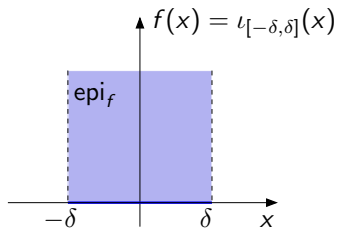
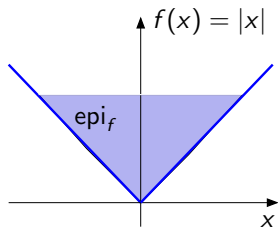
Let $f : \mathcal{H} \rightarrow]-\infty, +\infty]$. The **epigraph** of f is

$$\text{epi } f = \{(x, \zeta) \in \text{dom } f \times \mathbb{R} \mid f(x) \leq \zeta\}$$

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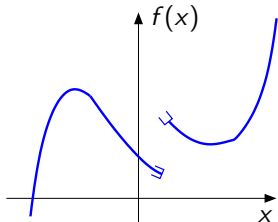
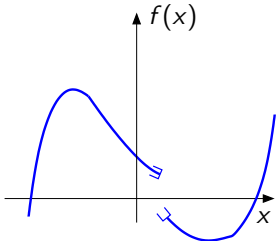


Lower semi-continuity

Let $f : \mathcal{H} \rightarrow]-\infty, +\infty]$.

f is a lower semi-continuous function on \mathcal{H} if and only if $\text{epi } f$ is closed

- ▶ l.s.c. functions ?

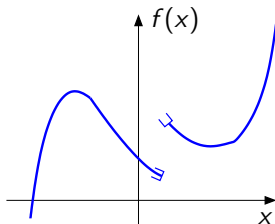
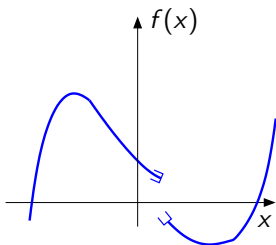


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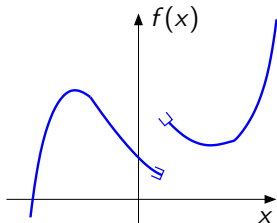
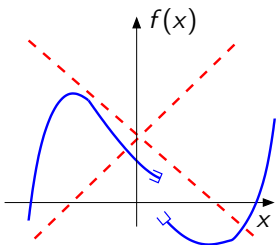


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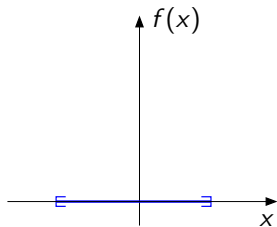
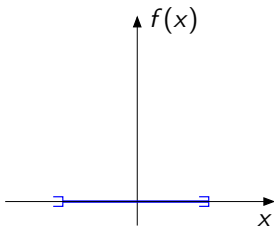


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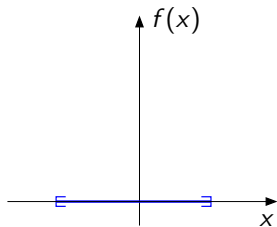
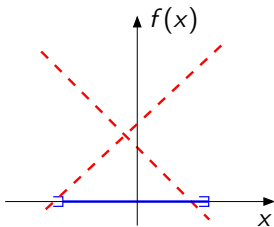


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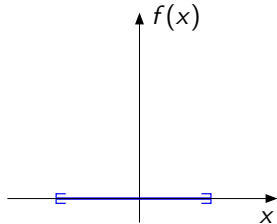
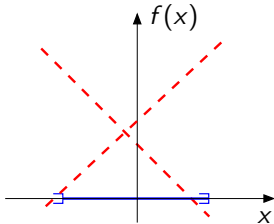


Lower semi-continuity

Let $f : \mathcal{H} \rightarrow]-\infty, +\infty]$.

f is a lower semi-continuous function on \mathcal{H} if and only if $\text{epi } f$ is closed

- ▶ l.s.c. functions ?



Lower semi-continuity

- ▶ Every continuous function on \mathcal{H} is l.s.c.
- ▶ Every finite sum of l.s.c. functions is l.s.c.
- ▶ Let $(f_i)_{i \in I}$ be a family of l.s.c functions.
Then, $\sup_{i \in I} f_i$ is l.s.c.

Existence of a minimizer

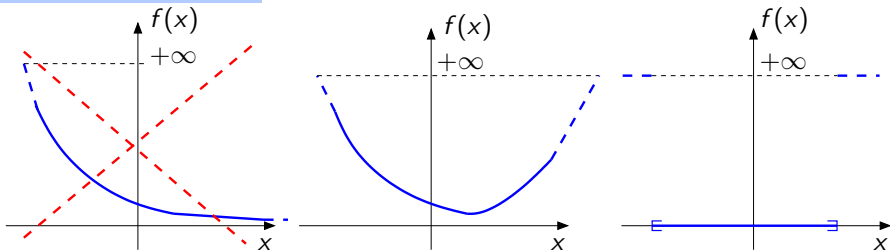
Let \mathcal{H} be a Hilbert space. Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$.

f is **coercive** if $\lim_{\|x\| \rightarrow +\infty} f(x) = +\infty$.

Existence of a minimizer

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Coercive functions ?

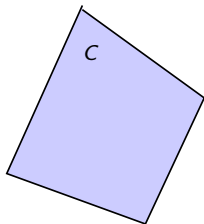
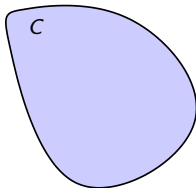
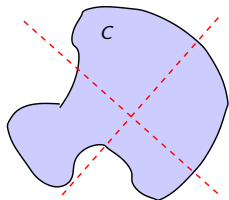


Convex set

$C \subset \mathcal{H}$ is a **convex set** if

$$(\forall (x, y) \in C^2)(\forall \alpha \in]0, 1[) \quad \alpha x + (1 - \alpha)y \in C$$

Convex sets ?



Convex function: definitions

$f : \mathcal{H} \rightarrow]-\infty, +\infty]$ is a **convex function** if

$$(\forall (x, y) \in \mathcal{H}^2) (\forall \alpha \in]0, 1[) \\ f(\alpha x + (1 - \alpha)y) \leq \alpha f(x) + (1 - \alpha)f(y)$$

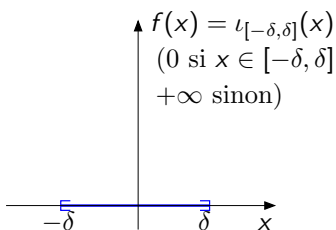
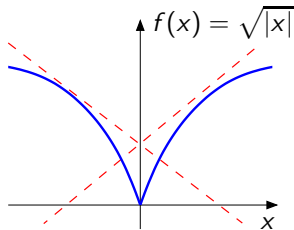
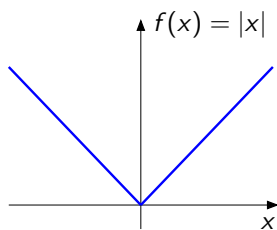
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Convex functions ?

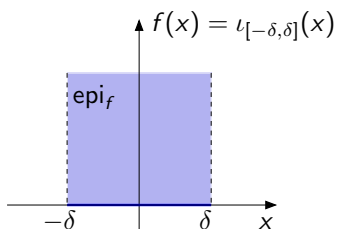
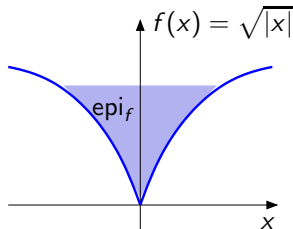
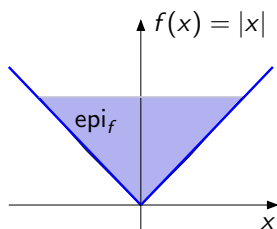


Convex functions: definition

$f : \mathcal{H} \rightarrow]-\infty, +\infty]$ is convex \Leftrightarrow its epigraph is convex.

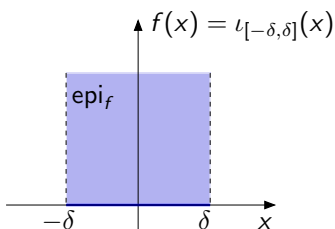
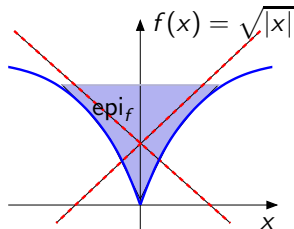
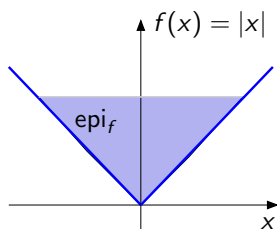
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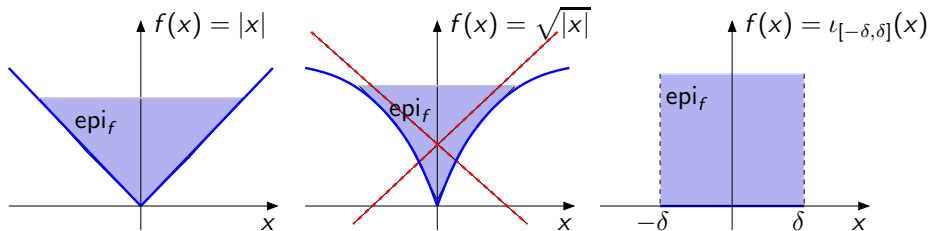
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Convex functions: definition

$f : \mathcal{H} \rightarrow]-\infty, +\infty]$ is convex \Leftrightarrow its epigraph is convex.



- ▶ If $f : \mathcal{H} \rightarrow]-\infty, +\infty]$ is convex, then $\text{dom } f$ is convex.
- ▶ $f : \mathcal{H} \rightarrow [-\infty, +\infty[$ is concave if $-f$ is convex.

Convex functions: properties

- ▶ Every finite sum of convex functions is convex.
- ▶ Let $(f_i)_{i \in I}$ be a family of convex functions. Then, $\sup_{i \in I} f_i$ is convex.
- ▶ $\Gamma_0(\mathcal{H})$: class of convex, l.s.c., and proper functions from \mathcal{H} to $] -\infty, +\infty]$.
- ▶ $\iota_C \in \Gamma_0(\mathcal{H}) \Leftrightarrow C$ is a nonempty closed convex set.
Proof: $\text{epi}_{\iota_C} = C \times [0, +\infty[$.

Strictly convex functions

Let \mathcal{H} be a Hilbert space. Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$.

f is **strictly convex** if

$$(\forall x \in \text{dom } f)(\forall y \in \text{dom } f)(\forall \alpha \in]0, 1[)$$

$$x \neq y \quad \Rightarrow \quad f(\alpha x + (1 - \alpha)y) < \alpha f(x) + (1 - \alpha)f(y).$$

Strictly convex functions

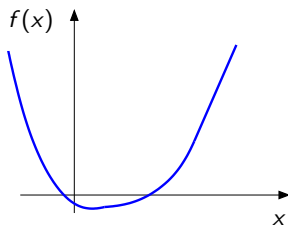
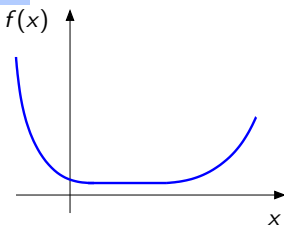
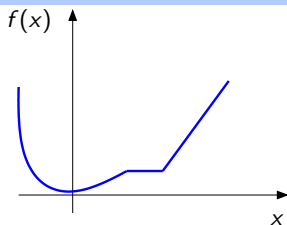
Let \mathcal{H} be a Hilbert space. Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$.

f is **strictly convex** if

$$(\forall x \in \text{dom } f)(\forall y \in \text{dom } f)(\forall \alpha \in]0, 1[)$$

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Strictly convex functions ?



Strictly convex functions

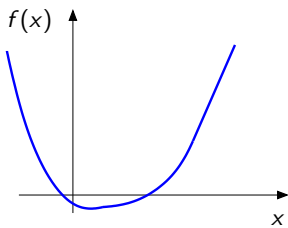
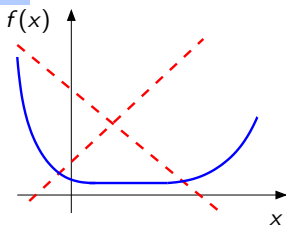
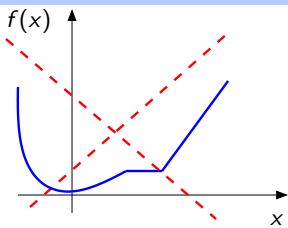
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Strictly convex functions ?



Minimizers of a convex function

Theorem

Let \mathcal{H} be a Hilbert space. Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$ be a proper convex function such that $\mu = \inf f > -\infty$.

- ▶ $\{x \in \mathcal{H} \mid f(x) = \mu\}$ is convex.
- ▶ Every local minimizer of f is a global minimizer.
- ▶ If f is strictly convex, then there exists at most one minimizer.

Existence and uniqueness of a minimizer

Theorem

Let \mathcal{H} be a Hilbert space and C a closed convex subset of \mathcal{H} . Let $f \in \Gamma_0(\mathcal{H})$ such that $\text{dom } f \cap C \neq \emptyset$.

If f is coercive or C is bounded, then there exists $\hat{x} \in C$ such that

$$f(\hat{x}) = \inf_{x \in C} f(x).$$

If, moreover, f is strictly convex, this minimizer \hat{x} is unique.

Optimality condition

1st order necessary and sufficient condition (P. Fermat, 160X-1665)

Let $f \in \Gamma_0(\mathbb{R}^N)$ be continuously differentiable function on \mathbb{R}^N . \hat{x} is a global minimizer of f , i.e., $\hat{x} \in \text{Argmin}_{x \in \mathbb{R}^N} f(x)$, iff

$$\nabla f(\hat{x}) = 0.$$

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Proof (\Rightarrow) : Let $\epsilon \in \mathbb{R}^N$. We set, for every $\alpha \in \mathbb{R}$, $g(\alpha) = f(\hat{x} + \alpha\epsilon)$

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$$\frac{dg(\alpha)}{d\alpha} = \epsilon' \nabla f(\hat{x} + \alpha\epsilon)$$

$$\frac{dg(0)}{d\alpha} = \epsilon' \nabla f(\hat{x})$$

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$$\begin{aligned} \frac{dg(0)}{d\alpha} &= \epsilon^\top \nabla f(\hat{x}) \\ &= \lim_{\alpha \rightarrow 0} \frac{f(\hat{x} + \alpha\epsilon) - f(\hat{x})}{\alpha} \geq 0 \end{aligned}$$

\rightarrow Because \hat{x} is a minimizer of f

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$$\begin{aligned} \frac{dg(0)}{d\alpha} &= -\epsilon^\top \nabla f(\hat{x}) \\ &= \lim_{\alpha \rightarrow 0} \frac{f(\hat{x} - \alpha\epsilon) - f(\hat{x})}{\alpha} \geq 0 \end{aligned}$$

Thus

$$\epsilon^\top \nabla f(\hat{x}) \leq 0$$

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Proof (\Leftarrow) : f being a convex function, this yields to

$$(\forall (x, z) \in \mathbb{R}^N \times \mathbb{R}^N)(\forall \alpha \in [0, 1]) \quad f(\alpha z + (1 - \alpha)x) \leq \alpha f(z) + (1 - \alpha)f(x)$$

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Thus

$$\lim_{\alpha \rightarrow 0} \frac{f(x + \alpha(z - x)) - f(x)}{\alpha} = (z - x)^\top \nabla f(x) \leq f(z) - f(x)$$

If $\nabla f(\hat{x}) = 0$, then

$$(\forall z \in \mathbb{R}^N) \quad f(z) \geq f(\hat{x})$$

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$$\nabla f(\hat{x}) = 0.$$

- ▶ Lead to a N equations - N unknown problem.
- ▶ Closed form expression for only few cases.
- ▶ If no closed form expression exists, an iterative procedure is required.
- ▶ Solve the optimization problem $\hat{x} \in \text{Argmin}_x f(x)$ equivalent to find a solution to $\nabla f(\hat{x}) = 0$.

Optimality condition

► Solving mean squares

$$\text{Find } \hat{x} \in \text{Argmin}_{x \in \mathbb{R}^N} \|Ax - y\|_2^2 \quad \text{with} \quad \begin{cases} A \in \mathbb{R}^{M \times N} \\ y \in \mathbb{R}^M \end{cases}$$

→ Optimality condition:

$$\nabla f(\hat{x}) = 0 \quad \Leftrightarrow \quad A^\top (A\hat{x} - y) = 0$$

$$\boxed{\hat{x} = (A^\top A)^{-1} (A^\top y)}$$

→ Sometimes difficult to invert $A^\top A$. **Closed form expression** known if A models a circulant matrix.

Optimality condition

- ▶ Logistic based criterion:

Find $\hat{x} \in \operatorname{Argmin}_{x \in \mathbb{R}} \log(1 + \exp(-yx))$ with $y \in \mathbb{R}$

→ Optimality condition:

$$\nabla f(\hat{x}) = 0 \quad \Leftrightarrow \quad \boxed{\frac{-y \exp(-y\hat{x})}{1 + \exp(-y\hat{x})} = 0}$$

→ **No closed form expression.** An iterative procedure is required.

Gradient descent

Gradient descent

Let $f \in \Gamma_0(\mathbb{R}^N)$ be continuously differentiable on \mathbb{R}^N and with a β -Lipschitz gradient. Let $x_0 \in \mathbb{R}^N$ and $\gamma_n \in]0, 2/\beta[$

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = x_n - \gamma_n \nabla f(x_n)$$

thus, the sequence $(x_n)_{n \in \mathbb{N}}$ converges to a minimizer of f .

Gradient β -Lipschitz

Let $f \in \Gamma_0(\mathbb{R}^N)$ be continuously differentiable on \mathbb{R}^N . f is gradient β -Lipschitz with $\beta > 0$ if

$$(\forall (u, v) \in \mathbb{R}^N \times \mathbb{R}^N) \quad \|\nabla f(u) - \nabla f(v)\| \leq \beta \|u - v\|$$

Gradient descent

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thus, the sequence $(x_n)_{n \in \mathbb{N}}$ converges to a minimizer of f .

- ▶ An iterative method consists to build a sequence $(x_n)_{n \in \mathbb{N}}$ such that, at each iteration k

$$f(x_{n+1}) < f(x_n)$$

- ▶ Choose γ_n for fast convergence :
→ Steepest descent, methode de Newton, ...

- ▶ Convergence proof: detailed later.

Optimality condition

1st order necessary and sufficient condition

Let C be a non-empty closed convex subset of \mathbb{R}^N . Let $f \in \Gamma_0(\mathbb{R}^N)$ be a continuously differentiable function on C .

\hat{x} is a minimizer of f on C , i.e, $\hat{x} \in \text{Argmin}_{x \in C} f(x)$ iff

$$(\forall x \in C) \quad \nabla f(\hat{x})^\top (x - \hat{x}) \geq 0.$$

- ▶ We are here interested in:

$$\hat{x} \in \text{Argmin}_{x \in C} f(x) \quad \Leftrightarrow \quad (\forall x \in C) \quad f(\hat{x}) \leq f(x)$$

- ▶ **Feasible** x when x satisfies the constraints.

Projected gradient descent

Projected gradient descent

Let C be a non-empty closed convex subset of \mathbb{R}^N . Let $f \in \Gamma_0(\mathbb{R}^N)$ be a continuously differentiable function on C with β -Lipschitz gradient.

Let $x_0 \in C$ and $\gamma_n \in]0, 2/\beta[$

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = P_C(x_n - \gamma_n \nabla f(x_n))$$

then, the sequence $(x_n)_{n \in \mathbb{N}}$ converges to a minimizer of f on C .

- ▶ P_C : projection onto C

$$(\forall x \in \mathbb{R}^N) \quad P_C(x) = \arg \min_{z \in C} \|z - x\|_2^2$$

- ▶ Let $C = \{x = (x^{(i)})_{1 \leq i \leq N} \in \mathbb{R}^N \mid (\forall i \in \{1, \dots, N\}) \ x^{(i)} \geq 0\}$, then

$$P_C(x) = (\max(0, x^{(i)}))_{1 \leq i \leq N}$$

Optimality conditions

Optimization problem under equality and inequality constraints:

$$\hat{x} \in \operatorname{Argmin}_{x \in \mathbb{R}^N} f(x) \quad \text{s.t.} \quad \begin{cases} (\forall i \in \{1, \dots, m\}) \psi_i(x) \leq 0 \\ (\forall j \in \{1, \dots, p\}) \varphi_j(x) = 0 \end{cases}$$

where,

- ▶ for every $i \in \{0, \dots, m\}$, $\psi_i \in \Gamma_0(\mathbb{R}^N)$,
- ▶ for every $j \in \{0, \dots, p\}$, $\varphi_j \in \Gamma_0(\mathbb{R}^N)$,
- ▶ $\mathcal{D} = \bigcap_{i=0}^m \operatorname{dom} \psi_i \cap \bigcap_{j=1}^p \operatorname{dom} \varphi_j \neq \emptyset$.

Lagrangian

$$(\forall (x, \lambda, \nu) \in \mathbb{R}^N \times \mathbb{R}^m \times \mathbb{R}^p) \quad L(x, \lambda, \nu) = f(x) + \sum_{i=1}^m \lambda_i \psi_i(x) + \sum_{j=1}^p \nu_j \varphi_j(x)$$

Optimality condition

Lagrangian

$$(\forall (x, \lambda, \nu) \in \mathbb{R}^N \times \mathbb{R}^m \times \mathbb{R}^p) \quad L(x, \lambda, \nu) = f(x) + \sum_{i=1}^m \lambda_i \psi_i(x) + \sum_{j=1}^p \nu_j \varphi_j(x)$$

- ▶ $\text{dom } L = \mathcal{D} \times \mathbb{R}^m \times \mathbb{R}^p$.
- ▶ $\lambda = (\lambda_i)_{1 \leq i \leq m}$: Lagrange multiplier associated with $\psi_i(x) \leq 0$.
- ▶ $\nu = (\nu_j)_{1 \leq j \leq p}$: Lagrange multiplier associated with $\varphi_j(x) = 0$.
- ▶ λ and ν are *Lagrange multiplier vectors* or *dual variables*.
- ▶ *Lagrange dual function* :

$$(\forall (\lambda, \nu) \in \mathbb{R}^m \times \mathbb{R}^p) \quad d(\lambda, \nu) = \inf_{x \in \mathcal{D}} L(x, \lambda, \nu)$$

Optimality condition

Necessary and sufficient condition: Karush Kuhn Tucker (KKT)

Let $(\psi_i)_{0 \leq i \leq m}$ and $(\varphi_j)_{1 \leq j \leq p}$ be continuously differentiable.
 \hat{x} and $(\hat{\lambda}, \hat{\nu})$ are primal and dual solutions iff

$$(\forall i \in \{1, \dots, m\}) \quad \psi_i(\hat{x}) \leq 0$$

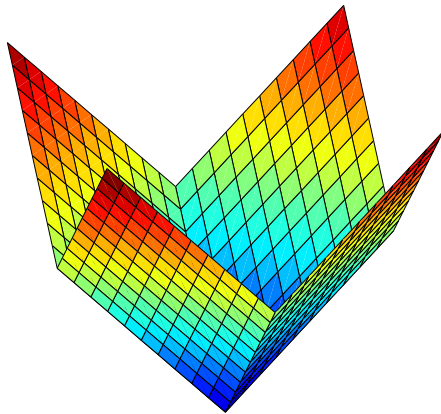
$$(\forall j \in \{1, \dots, p\}) \quad \varphi_j(\hat{x}) = 0$$

$$(\forall i \in \{1, \dots, m\}) \quad \hat{\lambda}_i \geq 0$$

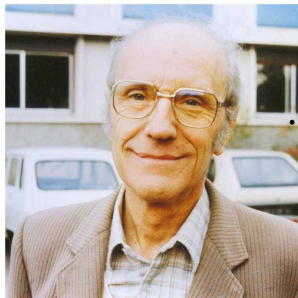
$$(\forall i \in \{1, \dots, m\}) \quad \hat{\lambda}_i \psi_i(\hat{x}) = 0$$

$$\nabla f_0(\hat{x}) + \sum_{i=1}^m \hat{\lambda}_i \nabla \psi_i(\hat{x}) + \sum_{j=1}^p \hat{\nu}_j \nabla \varphi_j(\hat{x}) = 0$$

Non-smooth convex optimization



A pioneer

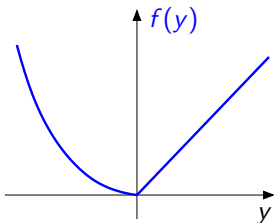


Jean-Jacques Moreau
(1923–2014)

Subdifferential of function: definition

Let $f : \mathcal{H} \rightarrow]-\infty, +\infty]$ be a proper function.

The (Moreau) **subdifferential of f** , denoted by ∂f ,



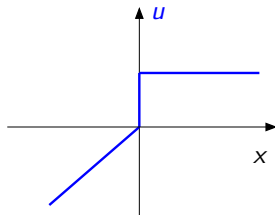
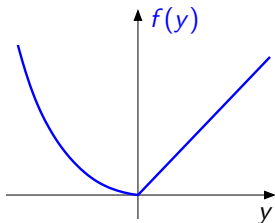
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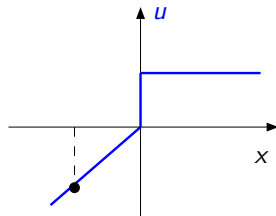
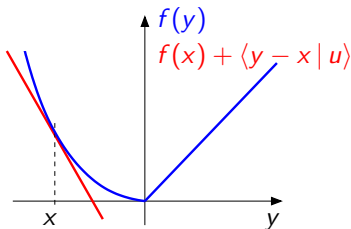
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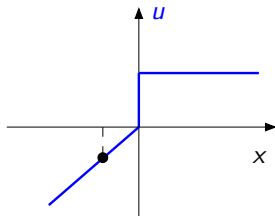
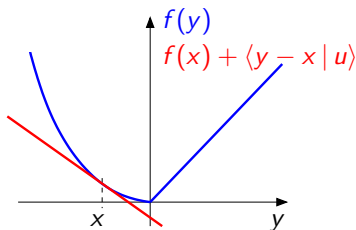
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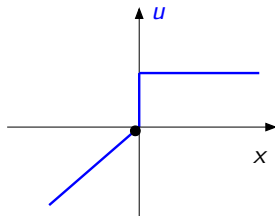
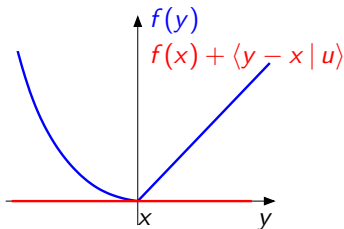
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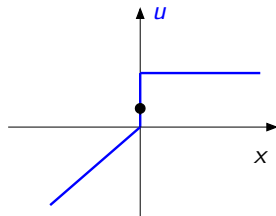
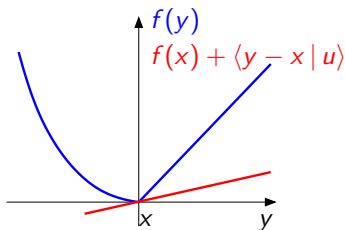
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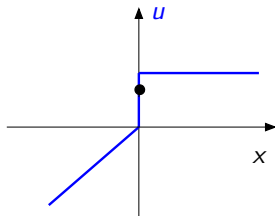
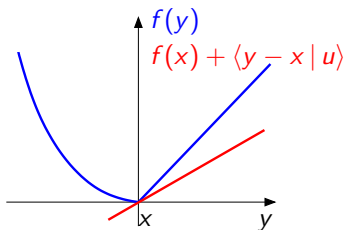
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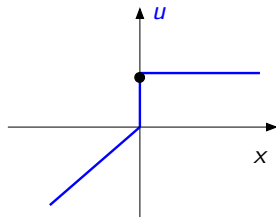
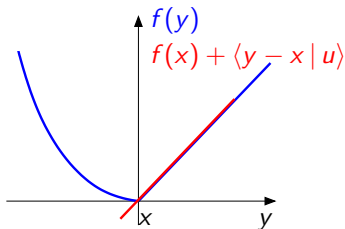
Subdifferential of function: definition

Let $f : \mathcal{H} \rightarrow]-\infty, +\infty]$ be a proper function.

The (Moreau) **subdifferential of f** , denoted by ∂f , is such that

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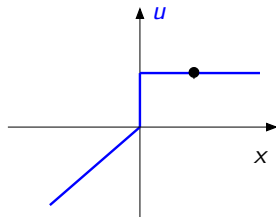
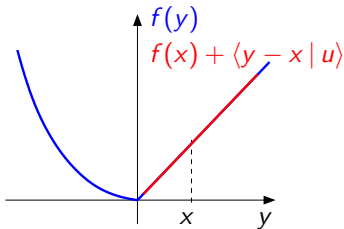
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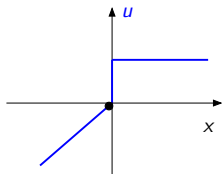
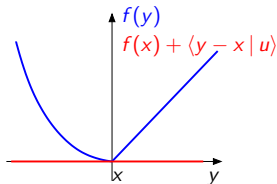
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Fermat's rule: $0 \in \partial f(x) \Leftrightarrow x \in \text{Argmin} f$

Subdifferential of a convex function: properties

If $f: \mathcal{H} \rightarrow]-\infty, +\infty]$ is convex and it is Gâteaux differentiable at x , then

$$\partial f(x) = \{\nabla f(x)\}$$

Let \mathcal{H} be a Hilbert space and let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$ be a proper function. f is **Gâteaux differentiable** at $x \in \text{dom } f$ if there exists $\nabla f(x) \in \mathcal{H}$ such that

$$(\forall y \in \mathcal{H}) \quad \langle \nabla f(x) \mid y \rangle = \lim_{\substack{\alpha \rightarrow 0 \\ \alpha \neq 0}} \frac{f(x + \alpha y) - f(x)}{\alpha}.$$

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Proof:

For every $\alpha \in [0, 1]$ and $y \in \mathcal{H}$,

$$\begin{aligned} f(x + \alpha(y - x)) &\leq (1 - \alpha)f(x) + \alpha f(y) \\ \Rightarrow \langle \nabla f(x) \mid y - x \rangle &= \lim_{\substack{\alpha \rightarrow 0 \\ \alpha \neq 0}} \frac{f(x + \alpha(y - x)) - f(x)}{\alpha} \leq f(y) - f(x) \end{aligned}$$

Then $\nabla f(x) \in \partial f(x)$.

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Proof:

Conversely, if $u \in \partial f(x)$, then, for every $\alpha \in [0, +\infty[$ and $y \in \mathcal{H}$,

$$\begin{aligned} f(x + \alpha y) &\geq f(x) + \langle u | x + \alpha y - x \rangle \\ \Rightarrow \langle \nabla f(x) | y \rangle &= \lim_{\substack{\alpha \rightarrow 0 \\ \alpha \neq 0}} \frac{f(x + \alpha y) - f(x)}{\alpha} \geq \langle u | y \rangle \end{aligned}$$

By selecting $y = u - \nabla f(x)$, it results that $\|u - \nabla f(x)\|^2 \leq 0$ and then $u = \nabla f(x)$.

Subdifferential of a convex function: properties

Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$ be Gâteaux differentiable on $\text{dom } f$, which is convex.

Then, f is convex if and only if

$$(\forall (x, y) \in (\text{dom } f)^2) \quad f(y) \geq f(x) + \langle \nabla f(x) \mid y - x \rangle .$$

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Proof:

Conversely, if the gradient inequality is satisfied, we have, for every $(x, y) \in (\text{dom } f)^2$ and $\alpha \in [0, 1]$, $\alpha x + (1 - \alpha)y \in \text{dom } f$, and

$$f(x) \geq f(\alpha x + (1 - \alpha)y) + (1 - \alpha) \langle \nabla f(\alpha x + (1 - \alpha)y) \mid x - y \rangle$$

$$f(y) \geq f(\alpha x + (1 - \alpha)y) + \alpha \langle \nabla f(\alpha x + (1 - \alpha)y) \mid y - x \rangle.$$

By multiplying the first inequality by α and the second one by $1 - \alpha$ and summing them, we get

$$\alpha f(x) + (1 - \alpha)f(y) \geq f(\alpha x + (1 - \alpha)y).$$

Subdifferential calculus

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

- ▶ Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$ be proper, then for every $\lambda \in]0, +\infty[$
 $\partial(\lambda f) = \lambda \partial f$.
- ▶ Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.
 If $\text{dom } g \cap L(\text{dom } f) \neq \emptyset$, then

$$(\forall x \in \mathcal{H}) \quad \partial f(x) + L^* \partial g(Lx) \subset \partial(f + g \circ L)(x).$$

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Proof: Let $x \in \mathcal{H}$, $u \in \partial f(x)$ and $v \in \partial g(Lx)$. We have:
 $u + L^*v \in \partial f(x) + L^* \partial g(Lx)$ and

$$\begin{aligned} (\forall y \in \mathcal{H}) \quad f(y) &\geq f(x) + \langle y - x \mid u \rangle \\ g(Ly) &\geq g(Lx) + \langle L(y - x) \mid v \rangle. \end{aligned}$$

Therefore, by summing,

$$f(y) + g(Ly) \geq f(x) + g(Lx) + \langle y - x \mid u + L^*v \rangle.$$

We deduce that $u + L^*v \in \partial(f + g \circ L)(x)$.

Subdifferential calculus

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

If $\text{int}(\text{dom } g) \cap L(\text{dom } f) \neq \emptyset$ or $\text{dom } g \cap \text{int}(L(\text{dom } f)) \neq \emptyset$, then

$$\partial f + L^* \partial g L = \partial(f + g \circ L).$$

Particular case:

- ▶ If $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and f is finite valued, then $\partial f + \partial g = \partial(f + g)$.
- ▶ If $g \in \Gamma_0(\mathcal{G})$, $L \in \mathcal{B}(\mathcal{G}, \mathcal{H})$, and $\text{int}(\text{dom } g) \cap \text{ran } L \neq \emptyset$, then $L^* \partial g L = \partial(g \circ L)$.

Subdifferential calculus

Let $(\mathcal{H})_{i \in I}$ where $I \subset \mathbb{N}$ be Hilbert spaces and let $\mathcal{H} = \bigoplus_{i \in I} \mathcal{H}_i$.
 For every $i \in I$, let $f_i: \mathcal{H}_i \rightarrow]-\infty, +\infty]$ be a proper function. Let

$$f: \mathcal{H} \rightarrow]-\infty, +\infty] : x = (x_i)_{i \in I} \mapsto \sum_{i \in I} f_i(x_i)$$

Then,

$$(\forall x = (x_i)_{i \in I} \in \mathcal{H}) \quad \partial f(x) = \prod_{i \in I} \partial f_i(x_i).$$

Proof: Let $x = (x_i)_{i \in I} \in \mathcal{H}$. We have

$$\begin{aligned} t &= (t_i)_{i \in I} \in \prod_{i \in I} \partial f_i(x_i) \\ \Leftrightarrow (\forall i \in I)(\forall y_i \in \mathcal{H}_i) \quad f_i(y_i) &\geq f_i(x_i) + \langle t_i \mid y_i - x_i \rangle \\ \Rightarrow (\forall y = (y_i)_{i \in I} \in \mathcal{H}) \quad \sum_{i \in I} f_i(y_i) &\geq \sum_{i \in I} f_i(x_i) + \sum_{i \in I} \langle t_i \mid y_i - x_i \rangle \\ \Leftrightarrow (\forall y \in \mathcal{H}) \quad f(y) &\geq f(x) + \langle t \mid y - x \rangle. \end{aligned}$$

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Proof: Conversely,

$$\begin{aligned} & t = (t_i)_{i \in I} \in \partial f(x) \\ \Leftrightarrow & (\forall y = (y_i)_{i \in I} \in \mathcal{H}) \quad \sum_{i \in I} f_i(y_i) \geq \sum_{i \in I} f_i(x_i) + \sum_{i \in I} \langle t_i | y_i - x_i \rangle. \end{aligned}$$

Let $j \in I$. By setting $(\forall i \in I \setminus \{j\}) y_i = x_i \in \text{dom } f_i$, we get

$$(\forall y_j \in \mathcal{H}_j) \quad f_j(y_j) \geq f_j(x_j) + \langle t_j | y_j - x_j \rangle.$$

Conjugate: definition

Let \mathcal{H} be a Hilbert space and $f: \mathcal{H} \rightarrow]-\infty, +\infty]$.

The **conjugate** of f is the function $f^*: \mathcal{H} \rightarrow [-\infty, +\infty]$ such that

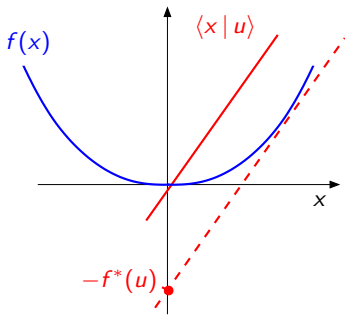
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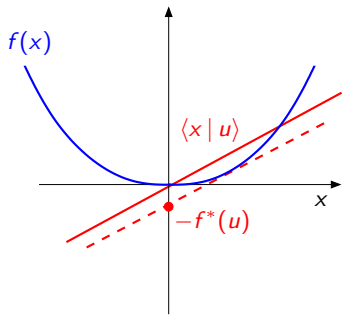


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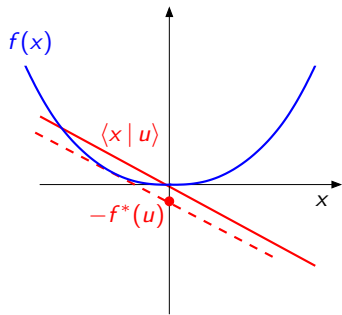


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Examples :

▶ $f = \frac{1}{2} \|\cdot\|^2 \Rightarrow f^* = \frac{1}{2} \|\cdot\|^2$

Proof : For every $(x, u) \in \mathcal{H}^2$, $\langle x | u \rangle - \frac{1}{2} \|x\|^2 = \frac{1}{2} \|u\|^2 - \frac{1}{2} \|u - x\|^2$
is maximum at $x = u$.

Consequently, $f^*(u) = \frac{1}{2} \|u\|^2$.

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Examples :

- ▶ $f = \frac{1}{2} \|\cdot\|^2 \Rightarrow f^* = \frac{1}{2} \|\cdot\|^2$.
- ▶ Let $\phi: \mathbb{R} \rightarrow]-\infty, +\infty]$ be a even function. $(\phi \circ \|\cdot\|)^* = \phi^* \circ \|\cdot\|$.
- ▶ $(\forall x \in \mathbb{R}^N) f(x) = \frac{1}{q} \|x\|_q^q$ with $q \in]1, +\infty[$
 $\Rightarrow (\forall u \in \mathbb{R}^N) f^*(u) = \frac{1}{q^*} \|u\|_{q^*}^{q^*}$ with $\frac{1}{q} + \frac{1}{q^*} = 1$

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Let \mathcal{H} be a Hilbert space and $f: \mathcal{H} \rightarrow]-\infty, +\infty]$.

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$$(\forall u \in \mathcal{H}) \quad f^*(u) = \sup_{x \in \text{dom } f} (\langle x | u \rangle - f(x))$$

► If f is even, then f^* is even.

Proof :

$$\begin{aligned}(\forall u \in \mathcal{H}) \quad f^*(-u) &= \sup_{x \in \mathcal{H}} (\langle x | -u \rangle - f(x)) \\ &= \sup_{x \in \mathcal{H}} (\langle -x | u \rangle - f(-x)) \\ &= \sup_{x \in \mathcal{H}} (\langle x | u \rangle - f(x)) \\ &= f^*(u).\end{aligned}$$

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Moreau-Fenchel theorem

Let \mathcal{H} be a Hilbert space and $f: \mathcal{H} \rightarrow]-\infty, +\infty]$ be a proper function.

$$f \text{ is l.s.c. and convex} \Leftrightarrow f^{**} = f.$$

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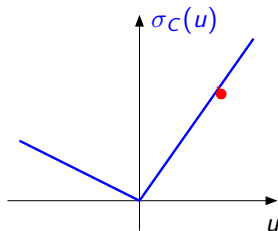
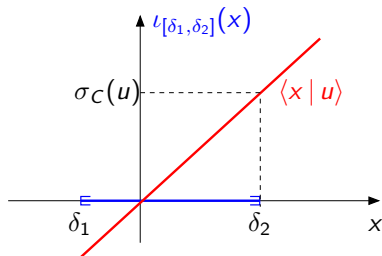
- Consequence: If $f \in \Gamma_0(\mathbb{R})$, then f^* is proper, hence $f^* \in \Gamma_0(\mathbb{R})$.

Conjugate: example

Let \mathcal{H} be a Hilbert space and $C \subset \mathcal{H}$.

σ_C is the **support function** of C if

$$\begin{aligned}
 (\forall u \in \mathcal{H}) \quad \sigma_C(u) &= \sup_{x \in C} \langle x | u \rangle \\
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 \end{aligned}$$

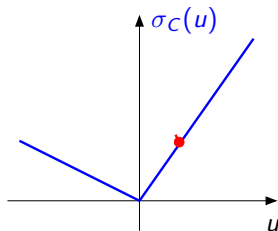
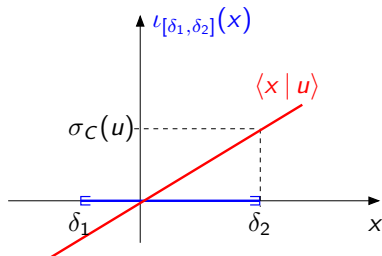


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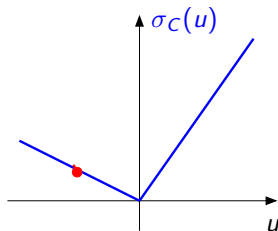
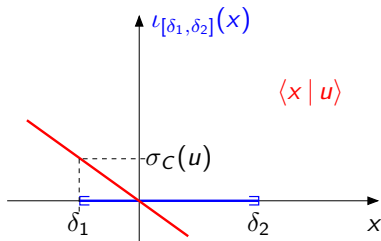


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Let \mathcal{H} be a Hilbert space.

$f: \mathcal{H} \rightarrow]-\infty, +\infty]$ is **positively homogeneous** if

$$(\forall x \in \mathcal{H})(\forall \alpha \in]0, +\infty[) \quad f(\alpha x) = \alpha f(x).$$

f positively homogeneous and belongs to $\Gamma_0(\mathcal{H})$ if and only if $f = \sigma_C$ where C is a nonempty closed convex subset of \mathcal{H} .

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Proof : (\Rightarrow)

Let $y \in \text{dom } f$.

$$f(0) = \lim_{\alpha \rightarrow 0, \alpha \geq 0} f((1 - \alpha)0 + \alpha y) = \lim_{\alpha \rightarrow 0} \alpha f(y) = 0.$$

Let $C = \{u \in \mathcal{H} \mid (\forall x \in \mathcal{H}) \langle x \mid u \rangle \leq f(x)\}$.

We have, for every $u \in C$,

$$f^*(u) = \sup_{x \in \mathcal{H}} \langle x \mid u \rangle - f(x) \leq 0 = \langle 0 \mid u \rangle - f(0) \leq f^*(u).$$

Consequently, $f^*(u) = 0$.

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Proof: (\Rightarrow)

Moreover, for every $u \notin C$, there exists $x \in \mathcal{H}$ such that

$\langle x | u \rangle > f(x)$. We have then, for every $\alpha \in]0, +\infty[$,
 $f^*(u) \geq \langle \alpha x | u \rangle - f(\alpha x) = \alpha(\langle x | u \rangle - f(x))$. By taking $\alpha \rightarrow +\infty$,
 we obtain $f^*(u) = +\infty$.

To conclude, $f^* = \iota_C \in \Gamma_0(\mathcal{H}) \Rightarrow f = \sigma_C$ and C is a nonempty closed convex set.

Conjugate: example

► Let $f: \mathbb{R} \rightarrow]-\infty, +\infty] : x \mapsto \begin{cases} \delta_1 x & \text{if } x < 0 \\ 0 & \text{if } x = 0 \\ \delta_2 x & \text{if } x > 0 \end{cases}$

with $-\infty \leq \delta_1 < \delta_2 \leq +\infty$.

Then, $f = \sigma_C$ where C is the closed real interval such that $\inf C = \delta_1$ et $\sup C = \delta_2$.

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Particular case: ℓ^1 norm of \mathbb{R}^N : $C = [-1, 1]^N$.

Conjugate: properties

Let $(\mathcal{H})_{i \in I}$ where $I \subset \mathbb{N}$ be Hilbert spaces and let $\mathcal{H} = \bigoplus_{i \in I} \mathcal{H}_i$.
 For every $i \in I$, let $f_i: \mathcal{H}_i \rightarrow]-\infty, +\infty]$. Let

$$f: \mathcal{H} \rightarrow]-\infty, +\infty] : x = (x_i)_{i \in I} \mapsto \sum_{i \in I} f_i(x_i)$$

Then,

$$(\forall u = (u_i)_{i \in I} \in \mathcal{H}) \quad f^*(u) = \sum_{i \in I} f_i^*(u_i).$$

Proof: Let $u = (u_i)_{i \in I} \in \mathcal{H}$. We have

$$\begin{aligned} f^*(u) &= \sup_{x \in \mathcal{H}} \langle x \mid u \rangle - f(x) \\ &= \sup_{x=(x_i)_{i \in I} \in \mathcal{H}} \sum_{i \in I} \langle x_i \mid u_i \rangle - f_i(x_i) \\ &= \sum_{i \in I} \sup_{x_i \in \mathcal{H}_i} \langle x_i \mid u_i \rangle - f_i(x_i) \\ &= \sum_{i \in I} f_i^*(u_i). \end{aligned}$$

Fenchel-Rockafellar duality

Primal problem

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$. Let $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

We want to

$$\underset{x \in \mathcal{H}}{\text{minimize}} \quad f(x) + g(Lx).$$

Dual problem

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$. Let $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

We want to

$$\underset{v \in \mathcal{G}}{\text{minimize}} \quad f^*(-L^*v) + g^*(v).$$

Example 1: Linear programming

Let $L \in \mathbb{R}^{K \times N}$, $b \in \mathbb{R}^K$, and $c \in \mathbb{R}^N$.

The primal problem

$$\text{Primal-LP : } \quad \underset{x \in [0, +\infty[^N}{\text{minimize}} \quad \langle c \mid x \rangle \quad \text{s.t.} \quad Lx \geq b$$

is associated with the the dual problem

$$\text{Dual-LP : } \quad y \in [0, +\infty[^K \quad \langle b \mid y \rangle \quad \text{s.t.} \quad L^\top y \leq c.$$

In addition, if the primal problem has a solution, then strong duality holds.

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In addition, if the primal problem has a solution, then strong duality holds.

Proof: Set

$$\begin{cases} (\forall x \in \mathcal{H} = \mathbb{R}^N) & f(x) = \langle c \mid x \rangle + \iota_{[0, +\infty[^N}(x), \\ (\forall z \in \mathcal{G} = \mathbb{R}^K) & g(z) = \iota_{[0, +\infty[^K}(z - b), \\ & y = -v \end{cases}$$

Example 2: Consensus and sharing

Let \mathcal{H} be a real Hilbert space.

For every $i \in \{1, \dots, m\}$, let $g_i: \mathcal{H} \rightarrow]-\infty, +\infty]$ and $h_i: \mathcal{H} \rightarrow]-\infty, +\infty]$.

The **consensus** problem is given by

$$\underset{\substack{(x_1, \dots, x_m) \in \mathcal{H}^m \\ x_1 = \dots = x_m}}{\text{minimize}} \quad \sum_{i=1}^m g_i(x_i).$$

The **sharing problem** is given by

$$\underset{\substack{(u_1, \dots, u_m) \in \mathcal{H}^m \\ u_1 + \dots + u_m = u}}{\text{minimize}} \quad \sum_{i=1}^m h_i(u_i), \quad u \in \mathcal{H}.$$

If, for every $i \in \{1, \dots, m\}$, $h_i = -g_i^*(\cdot - u/m)$, then sharing is the dual problem of consensus.

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If, for every $i \in \{1, \dots, m\}$, $h_i = -g_i^*(\cdot - u/m)$, then sharing is the dual problem of consensus.

Proof: Set $L = \text{Id}$ and $(\forall x = (x_1, \dots, x_m) \in \mathcal{H}^m) \begin{cases} f(x) = \iota_{\Lambda_m}(x), \\ g(x) = \sum_{i=1}^m g_i(x_i) \end{cases}$

where $\Lambda_m = \{(x_1, \dots, x_m) \in \mathcal{H}^m \mid x_1 = \dots = x_m\}$.

Fenchel-Rockafellar duality

Duality theorem (1)

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

$$\text{zer}(\partial f + L\partial g L^*) \neq \emptyset \quad \Leftrightarrow \quad \text{zer}((-L)\partial f^*(-L^*) + \partial g^*) \neq \emptyset$$

Proof:

$$\begin{aligned} (\exists x \in \mathcal{H}) \quad 0 \in \partial f(x) + L^* \partial g(Lx) &\Leftrightarrow (\exists x \in \mathcal{H})(\exists v \in \mathcal{G}) \quad \begin{cases} -L^*v \in \partial f(x) \\ v \in \partial g(Lx) \end{cases} \\ &\Leftrightarrow (\exists x \in \mathcal{H})(\exists v \in \mathcal{G}) \quad \begin{cases} x \in \partial f^*(-L^*v) \\ Lx \in \partial g^*(v) \end{cases} \\ &\Leftrightarrow (\exists v \in \mathcal{G}) \quad 0 \in -L\partial f^*(-L^*v) + \partial g^*(v). \end{aligned}$$

Fenchel-Rockafellar duality

Proof:

$$0 \in \partial f(\hat{x}) + L^* \partial g(L\hat{x}) \subset \partial(f + g \circ L)(\hat{x}).$$

Then, according to Fermat rule, \hat{x} is a solution to the primal problem.
In addition, there exists $\hat{v} \in \mathcal{G}$ such that

$$\begin{cases} 0 \in \partial f(\hat{x}) + L^* \hat{v} \\ \hat{v} \in \partial g(L\hat{x}) \end{cases} \Leftrightarrow \begin{cases} -L^* \hat{v} \in \partial f(\hat{x}) \\ L\hat{x} \in \partial g^*(\hat{v}). \end{cases}$$

We have also $\hat{x} \in \partial f^*(-L^* \hat{v})$, which implies that

$$0 \in -L \partial f^*(-L^* \hat{v}) + \partial g^*(\hat{v}).$$

On the other hand,

$$0 \in -L \partial f^*(-L^* \hat{v}) + \partial g^*(\hat{v}) \subset \partial(f^* \circ (-L^*) + g^*)(\hat{v})$$

$\Rightarrow \hat{v}$ solution to the dual problem.

The second assertion is shown in a similar manner.

Fenchel-Rockafellar duality

Particular case:

If $f = \varphi + \frac{1}{2}\|\cdot - z\|^2$ where $\varphi \in \Gamma_0(\mathcal{H})$ and $z \in \mathcal{H}$, then

$$\begin{aligned}
 -L^*\hat{v} \in \partial f(\hat{x}) &\Leftrightarrow -L^*\hat{v} \in \partial\varphi(\hat{x}) + \hat{x} - z \\
 &\Leftrightarrow 0 \in \hat{x} + L^*\hat{v} - z + \partial\varphi(\hat{x}).
 \end{aligned}$$

Hence,

$$\hat{x} = \text{prox}_{\varphi}(-L^*\hat{v} + z).$$

Link with Lagrange duality

Minimax problem

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

The primal problem is equivalent to finding

$$\mu = \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \sup_{v \in \mathcal{G}} \mathcal{L}(x, y, v)$$

where \mathcal{L} is the **Lagrange function** defined as

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(x, y, v) = f(x) + g(y) + \langle v \mid Lx - y \rangle$$

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Proof:

$$\begin{aligned} \mu &= \inf_{x \in \mathcal{H}} f(x) + g(Lx) = \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} f(x) + g(y) + \iota_{\{0\}}(Lx - y) \\ &= \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} f(x) + g(y) + \sup_{v \in \mathcal{G}} \langle v \mid Lx - y \rangle \\ &= \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \sup_{v \in \mathcal{G}} f(x) + g(y) + \langle v \mid Lx - y \rangle. \end{aligned}$$

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Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

The dual problem is equivalent to finding

$$-\mu^* = \sup_{v \in \mathcal{G}} \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \mathcal{L}(x, y, v)$$

where \mathcal{L} is the **Lagrange function** defined as

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(x, y, v) = f(x) + g(y) + \langle v \mid Lx - y \rangle$$

Proof:

$$\begin{aligned} \mu^* &= \inf_{v \in \mathcal{G}} f^*(-L^*v) + g^*(v) = \inf_{v \in \mathcal{G}} \left(\sup_{x \in \mathcal{H}} \langle x \mid -L^*v \rangle - f(x) \right) + \left(\sup_{y \in \mathcal{G}} \langle y \mid v \rangle - g(y) \right) \\ &= \inf_{v \in \mathcal{G}} - \left(\inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} f(x) + g(y) + \langle v \mid Lx - y \rangle \right) \\ &= - \sup_{v \in \mathcal{G}} \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} f(x) + g(y) + \langle v \mid Lx - y \rangle. \end{aligned}$$

Link with Lagrange duality

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Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

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$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(x, y, v) = f(x) + g(y) + \langle v \mid Lx - y \rangle$$

Remark: v is called the Lagrange multiplier associated with the constraint $Lx = y$.

Link with Lagrange duality

Proof (\Rightarrow): If $(\hat{x}, \hat{y}, \hat{v})$ is a saddle point of \mathcal{L} , then it is a critical point of \mathcal{L} , that is

$$\begin{aligned} & \begin{cases} 0 \in \partial_x \mathcal{L}(\hat{x}, \hat{y}, \hat{v}) = \partial f(\hat{x}) + L^* \hat{v} \\ 0 \in \partial_y \mathcal{L}(\hat{x}, \hat{y}, \hat{v}) = \partial g(\hat{y}) - \hat{v} \\ 0 = \nabla_v \mathcal{L}(\hat{x}, \hat{y}, \hat{v}) = L\hat{x} - \hat{y} \end{cases} \\ \Leftrightarrow & \begin{cases} -L^* \hat{v} \in \partial f(\hat{x}) \\ \hat{v} \in \partial g(\hat{y}) \\ \hat{y} = L\hat{x} \end{cases} \\ \Leftrightarrow & \begin{cases} -L^* \hat{v} \in \partial f(\hat{x}) \\ L\hat{x} \in \partial g^*(\hat{v}) \\ \hat{y} = L\hat{x}. \end{cases} \end{aligned}$$

Link with Lagrange duality

Proof (\Leftarrow): Conversely, assume that (\hat{x}, \hat{v}) is a Kuhn-Tucker point and $\hat{y} = L\hat{x}$. Since \hat{x} (resp. \hat{v}) is a solution to the primal (resp. dual) problem, then

$$\begin{aligned}\mu &= \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \sup_{v \in \mathcal{G}} \mathcal{L}(x, y, v) = \sup_{v \in \mathcal{G}} \mathcal{L}(\hat{x}, \hat{y}, v) \\ -\mu^* &= \sup_{v \in \mathcal{G}} \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \mathcal{L}(x, y, v) = \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \mathcal{L}(x, y, \hat{v}).\end{aligned}$$

By strong duality, $\sup_{v \in \mathcal{G}} \mathcal{L}(\hat{x}, \hat{y}, v) = \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \mathcal{L}(x, y, \hat{v})$, which can be rewritten as

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(\hat{x}, \hat{y}, v) \leq \mathcal{L}(x, y, \hat{v})$$

or equivalently

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(\hat{x}, \hat{y}, v) \leq \mathcal{L}(\hat{x}, \hat{y}, \hat{v}) \leq \mathcal{L}(x, y, \hat{v}).$$

Exercise

We are interested in the estimation of a piecewise estimate x by means of total variation leading to the minimization problem:

$$\hat{x} = \arg \min_{x \in \mathbb{R}^N} \frac{1}{2} \|x - y\|_2^2 + \lambda \|Lx\|_1$$

where $(Lx)^{(i)} = x^{(i+1)} - x^{(i)}$ for every $i \in \{1, \dots, N-1\}$ such that $L \in \mathbb{R}^{(N-1) \times N}$ denoted a finite difference operator.

- Prove that the dual problem can be written as

$$\min_{u \in \mathbb{R}^{N+1}} \frac{1}{2} \|y + L^* u\|_2^2 \quad \text{s.t.} \quad \begin{cases} (\forall i \in \{1, \dots, N-1\}) & |u^{(i)}| \leq \lambda \\ u^{(0)} = u^{(N)} = 0 \end{cases}$$

and that:

$$\hat{x} = y + L^* \hat{u}$$

Proximity operator: definition

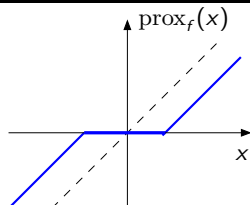
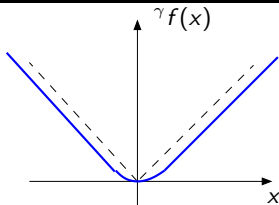
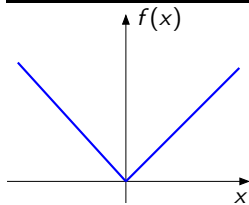
Let \mathcal{H} be a Hilbert space. Let $f \in \Gamma_0(\mathcal{H})$.

- ▶ The **Moreau envelope** of f of parameter $\gamma \in]0, +\infty[$ is

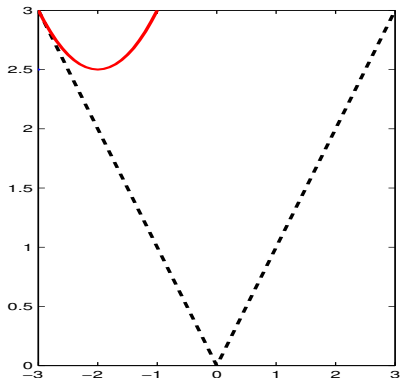
$$\gamma f: \mathcal{H} \rightarrow \mathbb{R}: x \mapsto \inf_{y \in \mathcal{H}} f(y) + \frac{1}{2\gamma} \|y - x\|^2.$$

- ▶ The **proximity operator** of f is

$$\text{prox}_f: \mathcal{H} \rightarrow \mathcal{H}: x \mapsto \underset{y \in \mathcal{H}}{\text{argmin}} f(y) + \frac{1}{2} \|y - x\|^2.$$

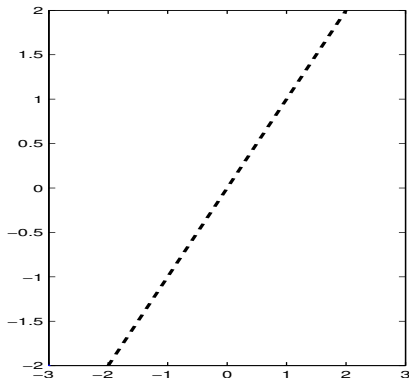


Proximity operator: definition



Moreau envelope

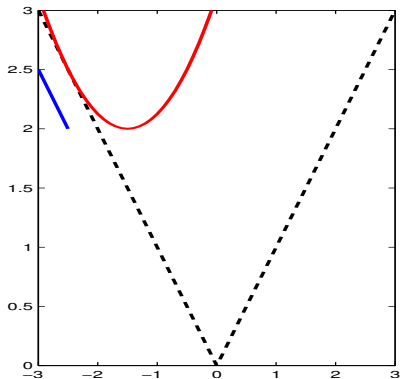
$$\gamma f(x) = \inf_{y \in \mathcal{H}} f(y) + \frac{1}{2\gamma} \|y - x\|^2$$



Proximity operator

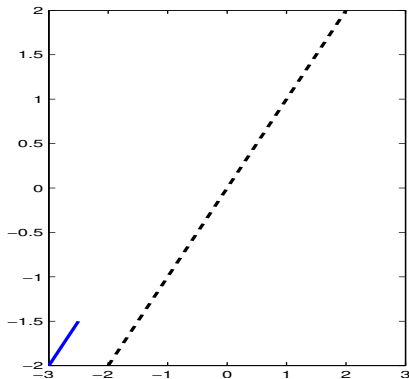
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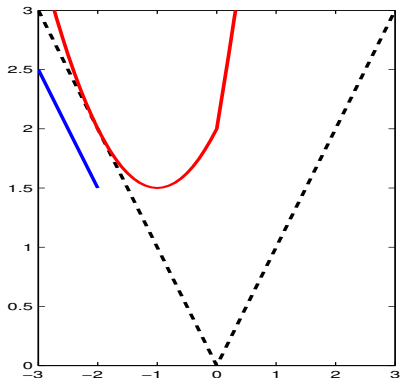
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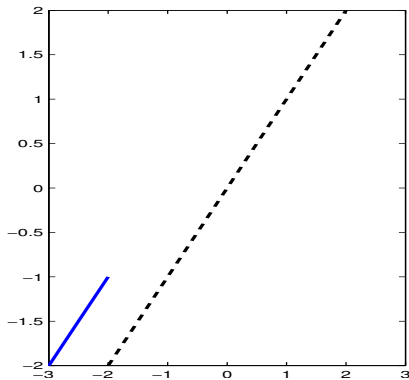
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Moreau envelope

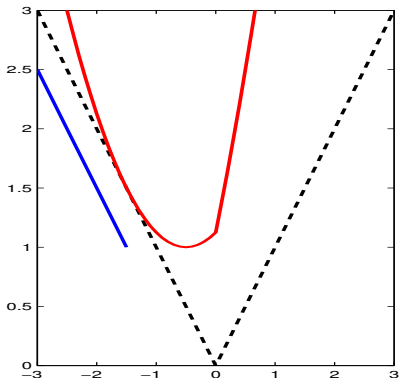
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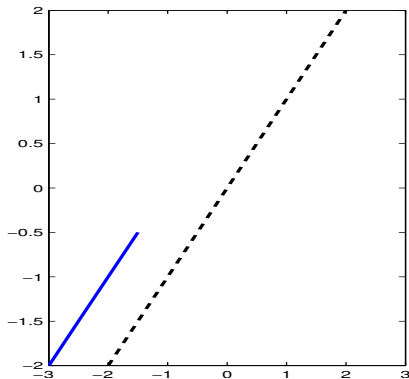
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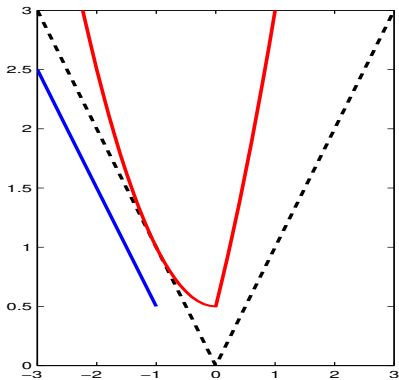
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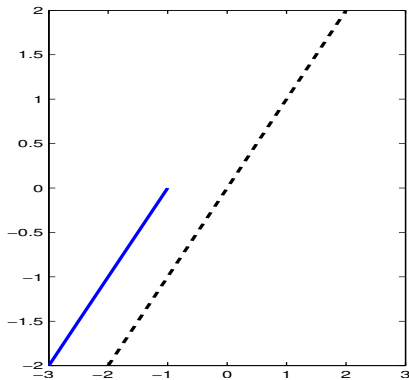
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Proximity operator: definition



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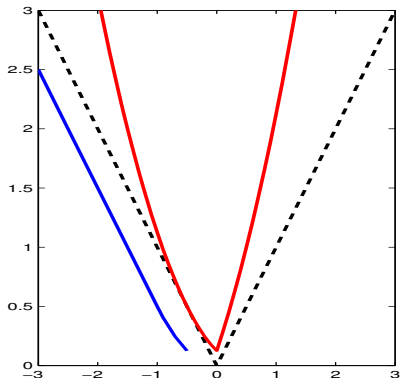
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Proximity operator

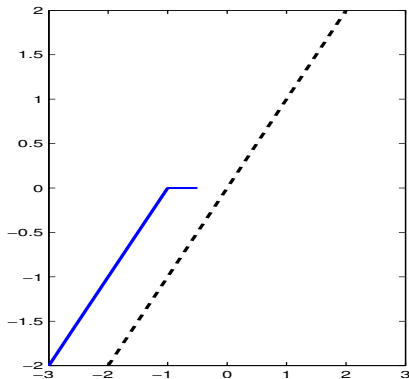
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Moreau envelope

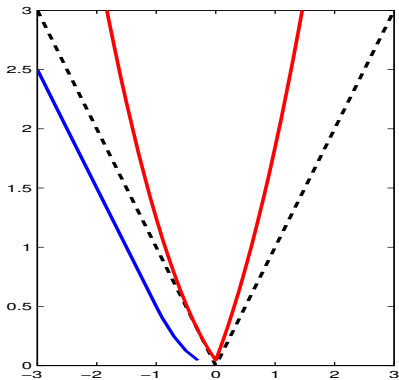
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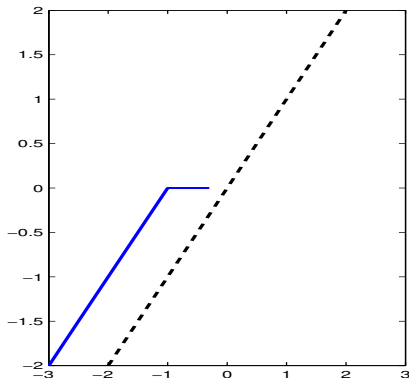
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Moreau envelope

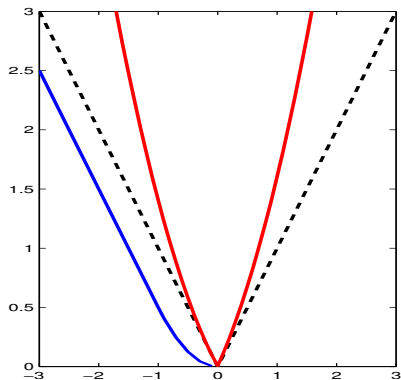
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Proximity operator

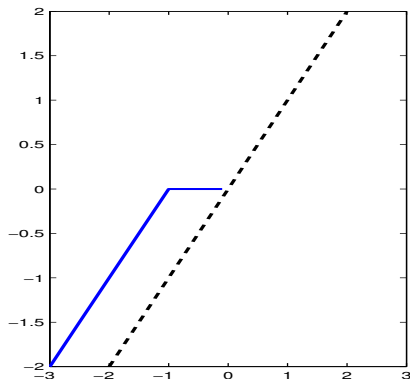
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Proximity operator: definition



Moreau envelope

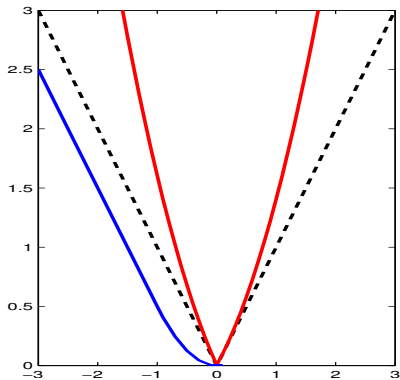
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Proximity operator

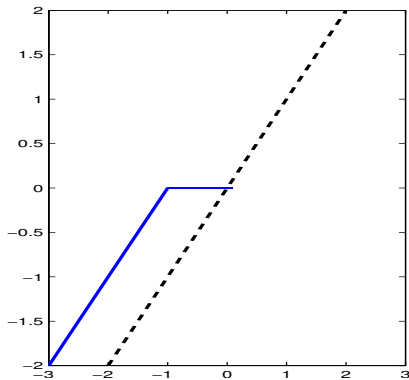
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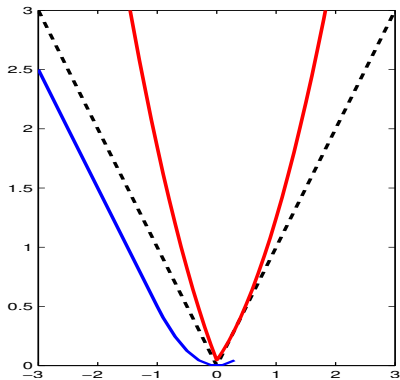
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Proximity operator

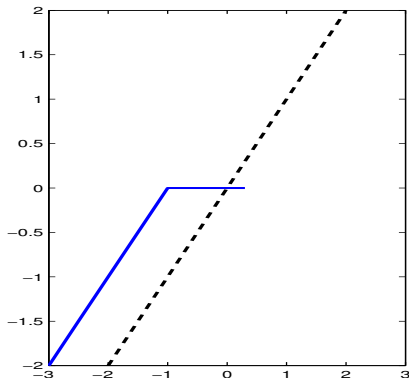
$$\text{prox}_f(x) = \underset{y \in \mathcal{H}}{\text{argmin}} f(y) + \frac{1}{2} \|y - x\|^2$$

Proximity operator: definition



Moreau envelope

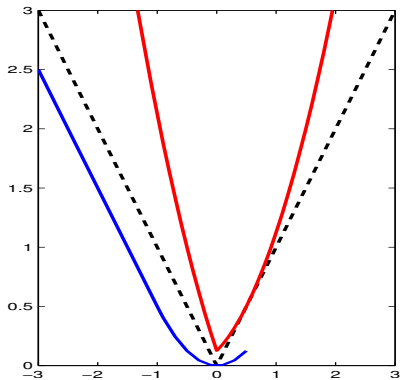
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Proximity operator

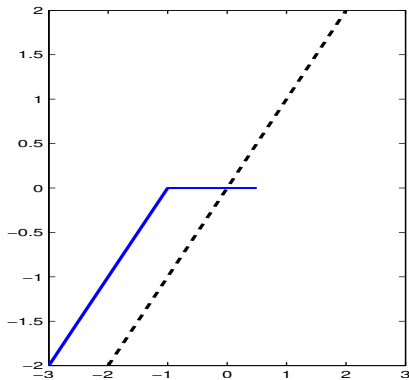
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Proximity operator: definition



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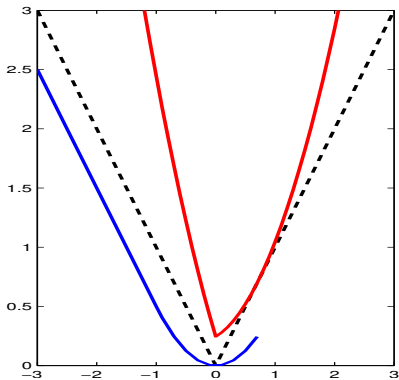
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Proximity operator

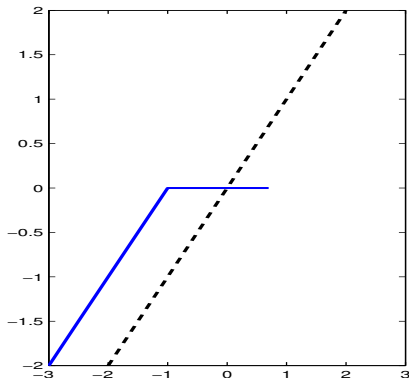
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Proximity operator: definition



Moreau envelope

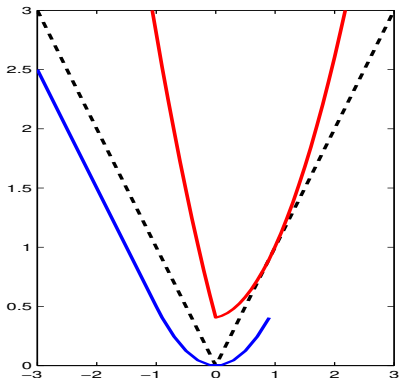
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Proximity operator

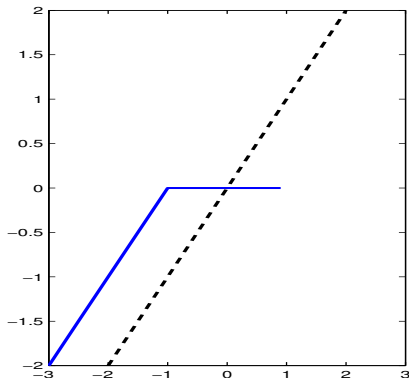
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Proximity operator: definition



Moreau envelope

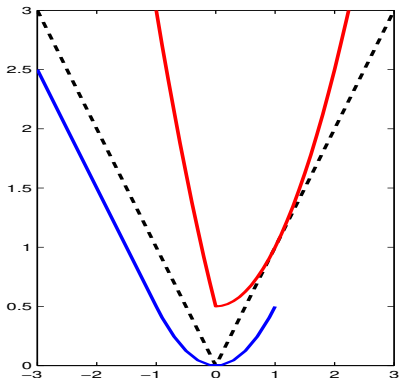
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Proximity operator

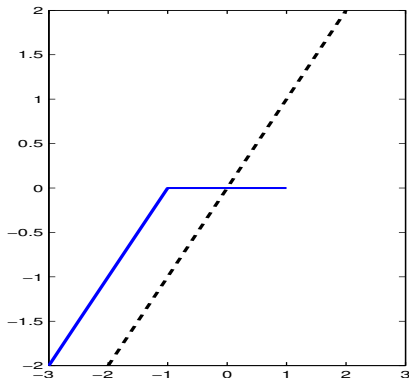
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Proximity operator: definition



Moreau envelope

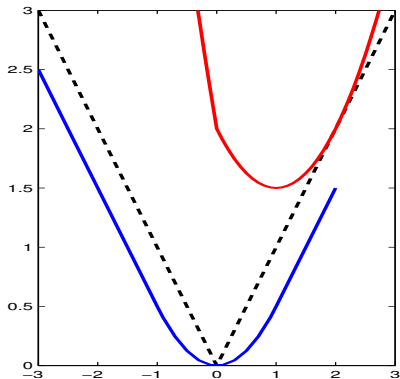
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Proximity operator

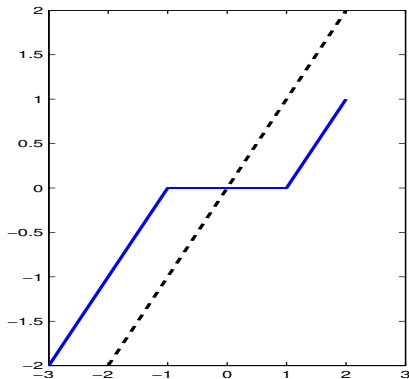
$$\text{prox}_f(x) = \underset{y \in \mathcal{H}}{\text{argmin}} f(y) + \frac{1}{2} \|y - x\|^2$$

Proximity operator: definition



Moreau envelope

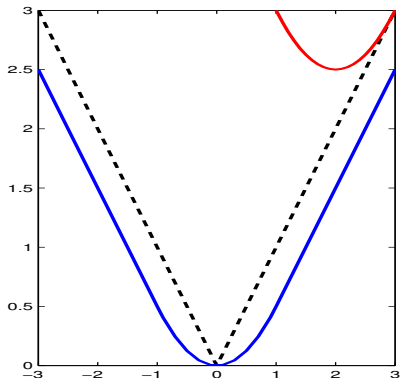
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Proximity operator

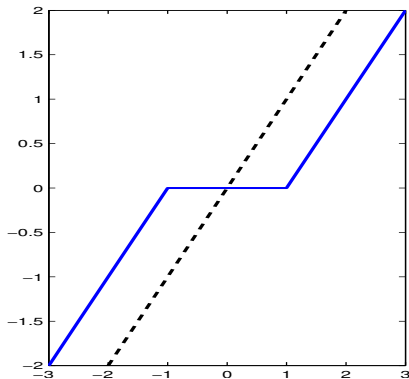
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Proximity operator: definition



Moreau envelope

$$\gamma f(x) = \inf_{y \in \mathcal{H}} f(y) + \frac{1}{2\gamma} \|y - x\|^2$$



Proximity operator

$$\text{prox}_f(x) = \underset{y \in \mathcal{H}}{\text{argmin}} f(y) + \frac{1}{2} \|y - x\|^2$$

Proximity operator: characterization

Let \mathcal{H} be a Hilbert space and $f \in \Gamma_0(\mathcal{H})$.

$$(\forall x \in \mathcal{H}) \quad p = \text{prox}_f(x) \Leftrightarrow x - p \in \partial f(p).$$

Proof: By using Fermat's rule, for every $x \in \mathcal{H}$, $p = \text{prox}_f(x)$ if and only if

$$\begin{aligned} p &= \arg \min_{y \in \mathcal{H}} f(y) + \frac{1}{2} \|y - x\|^2 \\ \Leftrightarrow 0 &\in \partial \left(f + \frac{1}{2} \|\cdot - x\|^2 \right) (p) \\ \Leftrightarrow 0 &\in \partial f(p) + p - x \\ \Leftrightarrow x &\in (\text{Id} + \partial f)(p). \end{aligned}$$

Proximity operator: examples

Projection :

Let \mathcal{H} be a Hilbert space. Let C be a nonempty closed convex subset of \mathcal{H} .

$$(\forall x \in \mathcal{H}) \quad \text{prox}_{\iota_C}(x) = \underset{y \in C}{\text{argmin}} \frac{1}{2} \|y - x\|^2 = P_C(x).$$

Remark :

- ▶ $p = P_C(x) \Leftrightarrow x - p \in \partial \iota_C(p) = N_C(p)$
 $\Leftrightarrow (\forall y \in C) \langle y - p \mid x - p \rangle \leq 0$.

Particular case: if C is a vector space: $p = P_C(x) \Leftrightarrow x - p \in C^\perp$.

- ▶ $\gamma \iota_C = (2\gamma)^{-1} d_C^2$ where d_C distance to the convex set C is defined by $d_C: x \mapsto \inf_{y \in C} \|y - x\| = \|x - P_C x\|$.

Proximity operator: examples

Power q function with $q \geq 1$:

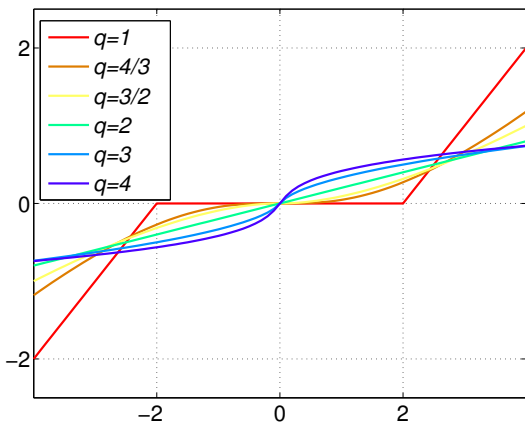
Let $\chi > 0$, $q \in [1, +\infty[$ and $\varphi: \mathbb{R} \rightarrow]-\infty, +\infty]: \xi \mapsto \chi|\xi|^q$.

Then, for every $\xi \in \mathbb{R}$,

$$\text{prox}_{\varphi}\xi = \begin{cases} \text{sign}(\xi) \max\{|\xi| - \chi, 0\} & \text{if } q = 1 \\ \xi + \frac{4\chi}{3 \cdot 2^{1/3}} ((\epsilon - \xi)^{1/3} - (\epsilon + \xi)^{1/3}) \\ \quad \text{where } \epsilon = \sqrt{\xi^2 + 256\chi^3/729} & \text{if } q = \frac{4}{3} \\ \xi + \frac{9\chi^2 \text{sign}(\xi)}{8} \left(1 - \sqrt{1 + \frac{16|\xi|}{9\chi^2}}\right) & \text{if } q = \frac{3}{2} \\ \frac{\xi}{1+2\chi} & \text{if } q = 2 \\ \text{sign}(\xi) \frac{\sqrt{1+12\chi|\xi|}-1}{6\chi} & \text{if } q = 3 \\ \left(\frac{\epsilon+\xi}{8\chi}\right)^{1/3} - \left(\frac{\epsilon-\xi}{8\chi}\right)^{1/3} \quad \text{where } \epsilon = \sqrt{\xi^2 + 1/(27\chi)} & \text{if } q = 4 \end{cases}$$

Proximity operator: examples

Power q function with $q \geq 1$ and $\chi = 2$.



Proximity operator: properties

Let \mathcal{H} be a Hilbert space, $x \in \mathcal{H}$ and $f \in \Gamma_0(\mathcal{H})$.

Properties	$g(x)$	$\text{prox}_{g,x}$
Translation	$f(x - z), z \in \mathcal{H}$	$z + \text{prox}_f(x - z)$
Quadratic perturbation	$f(x) + \alpha \ x\ ^2 / 2 + \langle z x \rangle + \gamma$ $z \in \mathcal{H}, \alpha > 0, \gamma \in \mathbb{R}$	$\text{prox}_{\frac{f}{\alpha+1}}\left(\frac{x-z}{\alpha+1}\right)$
Scaling	$f(\rho x), \rho \in \mathbb{R}^*$	$\frac{1}{\rho} \text{prox}_{\rho^2 f}(\rho x)$
Reflexion	$f(-x)$	$-\text{prox}_f(-x)$
Moreau envelope	$\gamma f(x) = \inf_{y \in \mathcal{H}} f(y) + \frac{1}{2\gamma} \ x - y\ ^2$ $\gamma > 0$	$\frac{1}{1+\gamma} (\gamma x + \text{prox}_{(1+\gamma)f}(x))$

Proximity operator: properties

Let \mathcal{H} be a separable Hilbert space.

Let $(b_i)_{i \in I}$ be an orthonormal basis of \mathcal{H} .

For every $i \in I$, let $\varphi_i \in \Gamma_0(\mathbb{R})$ such that $\varphi_i \geq 0$. For every $x \in \mathcal{H}$, if

$$f(x) = \sum_{i \in I} \varphi_i(\langle x | b_i \rangle)$$

then

$$\text{prox}_f(x) = \sum_{i \in I} \text{prox}_{\varphi_i}(\langle x | b_i \rangle) b_i.$$

Example: $\mathcal{H} = \mathbb{R}^N$, $(b_i)_{1 \leq i \leq N}$ canonical basis of \mathbb{R}^N , $f = \lambda \|\cdot\|_1$ with $\lambda \in [0, +\infty[$.

$$(\forall x = (x^{(i)})_{1 \leq i \leq N}) \in \mathbb{R}^N \quad \text{prox}_{\lambda \|\cdot\|_1}(x) = (\text{prox}_{\lambda|\cdot|}(x^{(i)}))_{1 \leq i \leq N}$$

Proximity operator: properties

Moreau decomposition formula

Let \mathcal{H} be a Hilbert space, $f \in \Gamma_0(\mathcal{H})$ and $\gamma \in]0, +\infty[$.

$$(\forall x \in \mathcal{H}) \quad \text{prox}_{\gamma f^*} x = x - \gamma \text{prox}_{\gamma^{-1} f}(\gamma^{-1} x).$$

Proof:

$$\begin{aligned} p = \text{prox}_{\gamma f^*} x &\Leftrightarrow x - p \in \gamma \partial f^*(p) \\ &\Leftrightarrow p \in \partial f\left(\frac{x - p}{\gamma}\right) \\ &\Leftrightarrow \frac{x}{\gamma} - \frac{x - p}{\gamma} \in \frac{1}{\gamma} \partial f\left(\frac{x - p}{\gamma}\right) \\ &\Leftrightarrow \frac{x - p}{\gamma} = \text{prox}_{\gamma^{-1} f}(\gamma^{-1} x) \\ &\Leftrightarrow p = x - \gamma \text{prox}_{\gamma^{-1} f}(\gamma^{-1} x). \end{aligned}$$

Proximity operator: properties

Moreau decomposition formula

Let \mathcal{H} be a Hilbert space, $f \in \Gamma_0(\mathcal{H})$ and $\gamma \in]0, +\infty[$.

$$(\forall x \in \mathcal{H}) \quad \text{prox}_{\gamma f^*} x = x - \gamma \text{prox}_{\gamma^{-1} f}(\gamma^{-1} x).$$

Example: If $\mathcal{H} = \mathbb{R}^N$, $f = \frac{1}{q} \|\cdot\|_q^q$ with $q \in]1, +\infty[$, then $f^* = \frac{1}{q^*} \|\cdot\|_{q^*}^{q^*}$ with $1/q + 1/q^* = 1$, and

$$(\forall x \in \mathbb{R}^N) \quad \text{prox}_{\frac{\gamma}{q^*} \|\cdot\|_{q^*}^{q^*}} x = x - \gamma \text{prox}_{\frac{1}{\gamma q} \|\cdot\|_q^q}(\gamma^{-1} x).$$

Proximity operator: examples

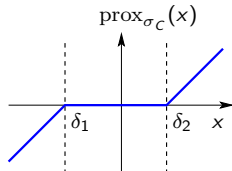
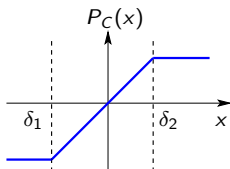
Support function :

Let \mathcal{H} be a Hilbert space and $C \subset \mathcal{H}$ be nonempty closed convex.

$$(\forall x \in \mathcal{H}) \quad \text{prox}_{\sigma_C} = \text{Id} - P_C.$$

Soft-thresholding : $\mathcal{H} = \mathbb{R}$, $\delta_1 = \inf C$ and $\delta_2 = \sup C$. For every $x \in \mathbb{R}$,

$$\sigma_C(x) = \begin{cases} \delta_1 x & \text{if } x < 0 \\ 0 & \text{if } x = 0 \\ \delta_2 x & \text{if } x > 0 \end{cases} \Rightarrow \text{prox}_{\sigma_C}(x) = \text{soft}_C(x) = \begin{cases} x - \delta_1 & \text{if } x < \delta_1 \\ 0 & \text{if } x \in C \\ x - \delta_2 & \text{if } x > \delta_2. \end{cases}$$



Proximity operator: properties

Let \mathcal{H} and \mathcal{G} be two Hilbert spaces. Let $f \in \Gamma_0(\mathcal{H})$ and $L \in \mathcal{B}(\mathcal{G}, \mathcal{H})$ such that $LL^* = \mu \text{Id}$ where $\mu \in]0, +\infty[$. Then

$$\text{prox}_{f \circ L} = \text{Id} - \mu^{-1}L^* \circ (\text{Id} - \text{prox}_{\mu f}) \circ L.$$

Proof: $LL^* = \mu \text{Id} \Rightarrow \text{ran } L = \mathcal{H}$ is closed, hence

$V = \text{ran}(L^*) = (\ker L)^\perp$ is closed. The orthogonal projection onto V is $P_V = L^*(LL^*)^{-1}L = \mu^{-1}L^*L$.

For every $x \in \mathcal{H}$, $p = \text{prox}_{f \circ L} x \Leftrightarrow x - p \in \partial(f \circ L)(p) = L^* \partial f(Lp)$ (since $\text{ran } L = \mathcal{H}$). Thus, $x - p \in V$.

It can be deduced that $P_{V^\perp} p = P_{V^\perp} x = x - P_V x = x - \mu^{-1}L^*Lx$.

Furthermore,

$x - p \in L^* \partial f(Lp) \Rightarrow Lx - Lp \in \mu \partial f(Lp) \Leftrightarrow Lp = \text{prox}_{\mu f}(Lx)$.

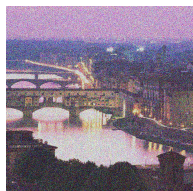
We have thus $P_V p = \mu^{-1}L^*Lp = \mu^{-1}L^* \text{prox}_{\mu f}(Lx)$ and

$p = P_V p + P_{V^\perp} p = x - \mu^{-1}L^*(\text{Id} - \text{prox}_{\mu f})(Lx)$.

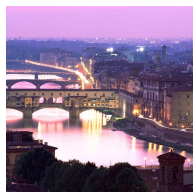
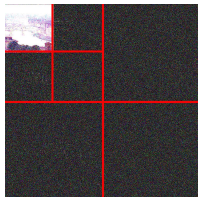
Proximity operator: properties

Particular case : $L \in \mathcal{B}(\mathcal{H}, \mathcal{H})$ unitary, $\text{prox}_{f \circ L} = L^* \text{prox}_f L$.

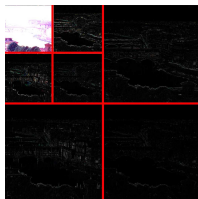
- ▶ Illustration: denoising using an ℓ_1 penalty on the coefficients resulting from an orthogonal wavelet transform L .



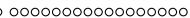
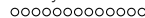
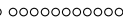
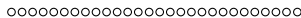
L →



← L^*



↙ $\text{prox}_{\lambda \|\cdot\|_1}$



Fixed point algorithm



Naive answer

Fixed point theorem (E. Picard, 1856-1941)

If

- ▶ \hat{x} is a fixed point of T , i.e. $\hat{x} = T\hat{x}$
- ▶ T is a strict contraction, i.e. there exists $\rho \in [0, 1[$ such that

$$(\forall (x, x') \in \mathbb{R}^N \times \mathbb{R}^N) \quad \|Tx - Tx'\| \leq \rho \|x - x'\|$$

then $(x_n)_{n \in \mathbb{N}}$ converges to \hat{x} .



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then $(x_n)_{n \in \mathbb{N}}$ converges to \hat{x} .



Proof: For all $n \in \mathbb{N}$,

$$\begin{aligned} \|x_{n+1} - \hat{x}\| &= \|Tx_n - T\hat{x}\| \\ &\leq \rho \|x_n - \hat{x}\|. \end{aligned}$$

Consequently, $\|x_n - \hat{x}\| \leq \rho^n \|x_0 - \hat{x}\|$. Hence, we have proved that $(x_n)_{n \in \mathbb{N}}$ converges linearly to \hat{x} .

Objective of this part

- ▶ Extend this theorem to more general operators
 - ▶ not necessarily *strictly* contractive
 - ▶ possibly dependent on the iteration number n
 - ▶ built from **composition of simpler operators** (*splitting techniques*).
- ▶ Apply this to solve minimization problems.
↪ How to relate T to the objective function f ?

Fixed point algorithm: convergence

Let \mathcal{H} be a Hilbert space.

Let $(x_n)_{n \in \mathbb{N}}$ be a sequence in \mathcal{H} and $\hat{x} \in \mathcal{H}$.

- ▶ $(x_n)_{n \in \mathbb{N}}$ converges strongly to \hat{x} if

$$\lim_{n \rightarrow +\infty} \|x_n - \hat{x}\| = 0.$$

It is denoted by $x_n \rightarrow \hat{x}$.

- ▶ $(x_n)_{n \in \mathbb{N}}$ converges weakly to \hat{x} if

$$(\forall y \in \mathcal{H}) \quad \lim_{n \rightarrow +\infty} \langle y | x_n - \hat{x} \rangle = 0.$$

It is denoted by $x_n \rightharpoonup \hat{x}$.

Remark: In a finite dimensional Hilbert space, strong and weak convergences are equivalent.

Fixed point algorithm: convergence

Let \mathcal{H} be a Hilbert space.

Let $(x_n)_{n \in \mathbb{N}}$ be a sequence of \mathcal{H} .

$(x_n)_{n \in \mathbb{N}}$ converges weakly if and only if

▶ $(x_n)_{n \in \mathbb{N}}$ is bounded

and

▶ $(x_n)_{n \in \mathbb{N}}$ possesses at most one sequential cluster point in the weak topology.

▶ \hat{x} is a sequential cluster point of $(x_n)_{n \in \mathbb{N}}$ in the weak topology if there exists a subsequence $(x_{n_k})_{k \in \mathbb{N}}$ of $(x_n)_{n \in \mathbb{N}}$ that converges weakly to \hat{x} .

Fixed point algorithm: convergence

Let \mathcal{H} be a Hilbert space.

Let $(x_n)_{n \in \mathbb{N}}$ be a sequence of \mathcal{H} .

$(x_n)_{n \in \mathbb{N}}$ converges weakly if and only if

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and

▶ $(x_n)_{n \in \mathbb{N}}$ possesses at most one sequential cluster point in the weak topology.

Illustration:

x_0	x_1	x_2	x_3	x_4	x_5	...
1	-1	1	-1	1	-1	...

→ $(x_n)_{n \in \mathbb{N}}$ is bounded but it has 2 sequential cluster points: -1 and 1 .

→ $(x_n)_{n \in \mathbb{N}}$ does not converge.

Fixed point algorithm: convergence

Lemma 1

Let \mathcal{H} be a Hilbert space and $D \subset \mathcal{H}$ nonempty.

Let $(x_n)_{n \in \mathbb{N}}$ be a sequence in D .

$(x_n)_{n \in \mathbb{N}}$ **weakly converges** to a point in D if

- ▶ for every $x \in D$, $(\|x_n - x\|)_{n \in \mathbb{N}}$ converges

and

- ▶ **every** weak sequential cluster point of $(x_n)_{n \in \mathbb{N}}$ lies in D .

Fixed point algorithm: convergence

Proof:

If $(\|x_n - x\|)_{n \in \mathbb{N}}$ converges, then $(\|x_n - x\|)_{n \in \mathbb{N}}$ and thus $(x_n)_{n \in \mathbb{N}}$ are bounded.

We assume that $(x_{n_k})_{k \in \mathbb{N}}$ and $(x_{n_\ell})_{\ell \in \mathbb{N}}$ are such that $x_{n_k} \rightarrow \hat{x}$ and $x_{n_\ell} \rightarrow \hat{x}'$ where $(\hat{x}, \hat{x}') \in D^2$. For every $n \in \mathbb{N}$,

$$2 \langle x_n | \hat{x}' - \hat{x} \rangle = \|x_n - \hat{x}\|^2 - \|x_n - \hat{x}'\|^2 - \|\hat{x}\|^2 + \|\hat{x}'\|^2.$$

Because $(\|x_n - \hat{x}\|)_{n \in \mathbb{N}}$ and $(\|x_n - \hat{x}'\|)_{n \in \mathbb{N}}$ converge, there exists $\alpha \in \mathbb{R}$ such that $\langle x_n | \hat{x}' - \hat{x} \rangle \rightarrow \alpha$ and thus

$\langle x_{n_k} | \hat{x}' - \hat{x} \rangle \rightarrow \langle \hat{x} | \hat{x}' - \hat{x} \rangle = \alpha$. Similarly, $\langle \hat{x}' | \hat{x}' - \hat{x} \rangle = \alpha$.

Consequently, $\|\hat{x}' - \hat{x}\|^2 = 0 \Rightarrow \hat{x} = \hat{x}'$.

Fixed point algorithm: Fejér-monotone sequence

Let \mathcal{H} be a Hilbert space and D be a nonempty subset of \mathcal{H} .

Let $(x_n)_{n \in \mathbb{N}}$ be a sequence in \mathcal{H} .

$(x_n)_{n \in \mathbb{N}}$ is **Fejér-monotone** with respect to D if

$$(\forall x \in D)(\forall n \in \mathbb{N}) \quad \|x_{n+1} - x\| \leq \|x_n - x\|.$$

Let \mathcal{H} be a Hilbert space and D be a nonempty subset of \mathcal{H} .

Let $(x_n)_{n \in \mathbb{N}}$ be Fejér-monotone with respect to D then

- ▶ $(x_n)_{n \in \mathbb{N}}$ is bounded .
- ▶ for every $x \in D$, $(\|x_n - x\|)_{n \in \mathbb{N}}$ converges.

Fixed point algorithm: Fejér-monotone sequence

Fejér-monotone convergence

Let \mathcal{H} be a Hilbert space and let D be a nonempty subset of \mathcal{H} .

Let $(x_n)_{n \in \mathbb{N}}$ be a sequence in \mathcal{H} .

$(x_n)_{n \in \mathbb{N}}$ converges weakly to a point in D if

- ▶ $(x_n)_{n \in \mathbb{N}}$ is Fejér-monotone with respect to D
- and
- ▶ every weak sequential cluster point of $(x_n)_{n \in \mathbb{N}}$ lies in D .

Fixed point algorithm: Fejér-monotone sequence

Lemma 2

Let \mathcal{H} be a Hilbert space and C be a nonempty closed convex subset of \mathcal{H} . If $(x_n)_{n \in \mathbb{N}}$ denotes a sequence in C that weakly converges to \hat{x} then $\hat{x} \in C$.

Fixed point algorithm: Fejér-monotone sequence

Lemma 2

Let \mathcal{H} be a Hilbert space and C be a nonempty closed convex subset of \mathcal{H} . If $(x_n)_{n \in \mathbb{N}}$ denotes a sequence in C that weakly converges to \hat{x} then $\hat{x} \in C$.

Proof:

We have $\hat{x} - P_C \hat{x} \in N_C(P_C \hat{x})$.

Because $(\forall n \in \mathbb{N}) x_n \in C$, we have

$$\langle x_n - P_C \hat{x} \mid \hat{x} - P_C \hat{x} \rangle \leq 0.$$

By using $x_n \rightharpoonup \hat{x}$, it results that $\|\hat{x} - P_C \hat{x}\|^2 = 0$, and thus $\hat{x} = P_C(\hat{x}) \in C$.

Nonexpansive operator: fixed point algorithm

Demiclosedness principle

Let \mathcal{H} be a Hilbert space and C be a nonempty closed convex subset of \mathcal{H} .
Let $T: C \rightarrow \mathcal{H}$ be a nonexpansive operator.

If $(x_n)_{n \in \mathbb{N}}$ is a sequence in C that converges weakly to \hat{x} and if $Tx_n - x_n \rightarrow 0$
then $\hat{x} \in \text{Fix } T$.

Nonexpansive operator: fixed point algorithm

Demiclosedness principle

Let \mathcal{H} be a Hilbert space and C be a nonempty closed convex subset of \mathcal{H} . Let $T: C \rightarrow \mathcal{H}$ be a nonexpansive operator.

If $(x_n)_{n \in \mathbb{N}}$ is a sequence in C that converges weakly to \hat{x} and if $Tx_n - x_n \rightarrow 0$ then $\hat{x} \in \text{Fix } T$.

Proof:

$x_n \rightharpoonup \hat{x} \Rightarrow \hat{x} \in C$ and $T\hat{x}$ defined. For every $n \in \mathbb{N}$,

$$\|x_n - T\hat{x}\|^2 = \|x_n - \hat{x}\|^2 + \|\hat{x} - T\hat{x}\|^2 + 2 \langle x_n - \hat{x} | \hat{x} - T\hat{x} \rangle$$

$$\|x_n - T\hat{x}\|^2 = \|x_n - Tx_n\|^2 + \|Tx_n - T\hat{x}\|^2 + 2 \langle x_n - Tx_n | Tx_n - T\hat{x} \rangle$$

$$\begin{aligned} \Rightarrow \|\hat{x} - T\hat{x}\|^2 &= \|x_n - Tx_n\|^2 + \|Tx_n - T\hat{x}\|^2 - \|x_n - \hat{x}\|^2 \\ &\quad + 2 \langle x_n - Tx_n | Tx_n - T\hat{x} \rangle - 2 \langle x_n - \hat{x} | \hat{x} - T\hat{x} \rangle \end{aligned}$$

Nonexpansive operator: fixed point algorithm

Demiclosedness principle

Let \mathcal{H} be a Hilbert space and C be a nonempty closed convex subset of \mathcal{H} . Let $T: C \rightarrow \mathcal{H}$ be a nonexpansive operator.

If $(x_n)_{n \in \mathbb{N}}$ is a sequence in C that converges weakly to \hat{x} and if $Tx_n - x_n \rightarrow 0$ then $\hat{x} \in \text{Fix } T$.

Proof:

$$\begin{aligned} \|\hat{x} - T\hat{x}\|^2 &= \|x_n - Tx_n\|^2 + \|Tx_n - T\hat{x}\|^2 - \|x_n - \hat{x}\|^2 \\ &\quad + 2\langle x_n - Tx_n \mid Tx_n - T\hat{x} \rangle - 2\langle x_n - \hat{x} \mid \hat{x} - T\hat{x} \rangle. \end{aligned}$$

Since T is nonexpansive, by using the Cauchy-Schwarz inequality,

$$\begin{aligned} \|\hat{x} - T\hat{x}\|^2 &\leq \|x_n - Tx_n\|^2 + 2\|x_n - Tx_n\| \|Tx_n - T\hat{x}\| - 2\langle x_n - \hat{x} \mid \hat{x} - T\hat{x} \rangle \\ &\leq \|x_n - Tx_n\|^2 + 2\|x_n - Tx_n\| \|x_n - \hat{x}\| - 2\langle x_n - \hat{x} \mid \hat{x} - T\hat{x} \rangle. \end{aligned}$$

$x_n \rightharpoonup \hat{x} \Rightarrow (x_n)_{n \in \mathbb{N}}$ bounded. The result follows by taking the limit.

Nonexpansive operator: fixed point algorithm

Let \mathcal{H} be a Hilbert space and C be a nonempty subset of \mathcal{H} .

Let $T: C \rightarrow C$ be a nonexpansive operator

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = Tx_n.$$

α -averaged operator: example

Proof : 1) **Descent lemma**

For every $(x, y) \in \mathcal{H}^2$ and $t \in \mathbb{R}$, let $\varphi(t) = f(x + t(y - x))$.
 φ is differentiable and $\varphi'(t) = \langle y - x \mid \nabla f(x + t(y - x)) \rangle$. We have then

$$\varphi(1) - \varphi(0) = \int_0^1 \varphi'(t) dt$$

$$\Leftrightarrow f(y) - f(x) - \langle y - x \mid \nabla f(x) \rangle = \int_0^1 \langle y - x \mid \nabla f(x + t(y - x)) - \nabla f(x) \rangle dt.$$

But, according to the Cauchy-Schwarz inequality,

$$\begin{aligned} & \langle y - x \mid \nabla f(x + t(y - x)) - \nabla f(x) \rangle \\ & \leq \|y - x\| \|\nabla f(x + t(y - x)) - \nabla f(x)\| \leq t\nu \|y - x\|^2. \end{aligned}$$

This leads to

$$(\forall (x, y) \in \mathcal{H}^2) \quad f(y) \leq f(x) + \langle y - x \mid \nabla f(x) \rangle + \frac{\nu}{2} \|y - x\|^2.$$

α -averaged operator: example

Proof : 2) $\text{Id} - \nabla f$ is α -averaged

From the descent lemma, for every $(x, y, z) \in \mathcal{H}^3$,

$$\begin{aligned} f^*(\nabla f(y)) &\geq \langle z \mid \nabla f(y) \rangle - f(z) \\ &\geq \langle z \mid \nabla f(y) - \nabla f(x) \rangle + \langle x \mid \nabla f(x) \rangle - f(x) - \frac{\nu}{2} \|z - x\|^2. \end{aligned}$$

Moreover, according to the Fenchel-Young inequality,

$$\langle x \mid \nabla f(x) \rangle - f(x) = f^*(\nabla f(x)).$$

Thus,

$$f^*(\nabla f(y)) \geq \langle z \mid \nabla f(y) - \nabla f(x) \rangle + f^*(\nabla f(x)) - \frac{\nu}{2} \|z - x\|^2$$

α -averaged operator: example

Proof : 2) $\text{Id} - \nabla f$ is α -averaged

Thus,

$$\begin{aligned} f^*(\nabla f(y)) &\geq \langle z \mid \nabla f(y) - \nabla f(x) \rangle + f^*(\nabla f(x)) - \frac{\nu}{2} \|z - x\|^2 \\ &= f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle + \langle z - x \mid \nabla f(y) - \nabla f(x) \rangle - \frac{\nu}{2} \|z - x\|^2. \end{aligned}$$

This yields

$$\begin{aligned} f^*(\nabla f(y)) &\geq f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle \\ &\quad + (\nu \| \cdot \|^2 / 2)^*(\nabla f(y) - \nabla f(x)) \\ &\geq f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle + \frac{1}{2\nu} \|\nabla f(y) - \nabla f(x)\|^2. \end{aligned}$$

Consequently,

$$f^*(\nabla f(y)) \geq f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle + \frac{1}{2\nu} \|\nabla f(y) - \nabla f(x)\|^2.$$

α -averaged operator: example

Proof : 2) $\text{Id} - \nabla f$ is α -averaged

For every $(x, y) \in \mathcal{H}^2$,

$$f^*(\nabla f(y)) \geq f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle + \frac{1}{2\nu} \|\nabla f(y) - \nabla f(x)\|^2$$

and symmetrically

$$f^*(\nabla f(x)) \geq f^*(\nabla f(y)) + \langle y \mid \nabla f(x) - \nabla f(y) \rangle + \frac{1}{2\nu} \|\nabla f(x) - \nabla f(y)\|^2.$$

By summing

$$-\langle y - x \mid \nabla f(y) - \nabla f(x) \rangle + \frac{1}{\nu} \|\nabla f(x) - \nabla f(y)\|^2 \leq 0.$$

It results that

$$\|(\text{Id} - \nabla f)x - (\text{Id} - \nabla f)y\|^2 + \frac{1 - \nu/2}{\nu/2} \|\nabla f(x) - \nabla f(y)\|^2 \leq \|x - y\|^2.$$

α -averaged operator: example

Let \mathcal{H} be a Hilbert space, $f \in \Gamma_0(\mathcal{H})$.
 prox_f is a $1/2$ -averaged operator.

Proof:

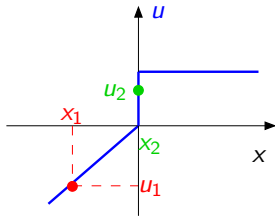
- ▶ We recall that : $\partial f(x) = \{u \in \mathcal{H} \mid (\forall y \in \mathcal{H}) \langle y - x | u \rangle + f(x) \leq f(y)\}$
- ▶ Let $u_1 \in \partial f(x_1)$ and $u_2 \in \partial f(x_2)$.

By definition:

$$\langle x_2 - x_1 | u_1 \rangle + f(x_1) \leq f(x_2)$$

$$\langle x_1 - x_2 | u_2 \rangle + f(x_2) \leq f(x_1)$$

it results that $\langle x_1 - x_2 | u_1 - u_2 \rangle \geq 0$.



α -averaged operator: example

Proof :

Let $u_1 \in \partial f(x_1)$ and $u_2 \in \partial f(x_2)$

$$\langle x_1 - x_2 \mid u_1 - u_2 \rangle \geq 0 \Leftrightarrow \langle x_1 - x_2 \mid x_1 - x_2 + u_1 - u_2 \rangle \geq \|x_1 - x_2\|^2$$

We consider $u'_1 \in (\text{Id} + \partial f)x_1$ et $u'_2 \in (\text{Id} + \partial f)x_2$, it results that

$$\langle x_1 - x_2 \mid u'_1 - u'_2 \rangle \geq \|x_1 - x_2\|^2$$

Then, from the definition of the proximity operator,

$$\langle \text{prox}_f u'_1 - \text{prox}_f u'_2 \mid u'_1 - u'_2 \rangle \geq \|\text{prox}_f u'_1 - \text{prox}_f u'_2\|^2$$

We can deduce that prox_f is a 1/2-averaged operator, i.e.,

$$\|u'_1 - u'_2\|^2 \geq \|\text{prox}_f u'_1 - \text{prox}_f u'_2\|^2 + \|(\text{Id} - \text{prox}_f)u'_1 - (\text{Id} - \text{prox}_f)u'_2\|^2$$

Fixed point algorithm: α -averaged operator

Let \mathcal{H} be a Hilbert space and let $\alpha \in]0, 1[$.

Let $T: \mathcal{H} \rightarrow \mathcal{H}$ be an α -averaged operator with $\alpha \in]0, 1[$ such that $\text{Fix } T \neq \emptyset$.

Let $(\lambda_n)_{n \in \mathbb{N}}$ be a sequence in $[0, 1/\alpha]$ such that

$$\sum_{n \in \mathbb{N}} \lambda_n (1 - \alpha \lambda_n) = +\infty.$$

Let $x_0 \in \mathcal{H}$ and $(\forall n \in \mathbb{N}) x_{n+1} = x_n + \lambda_n (Tx_n - x_n)$. The following properties are satisfied

- ▶ $(x_n)_{n \in \mathbb{N}}$ is Fejér-monotone with respect to $\text{Fix } T$.
- ▶ $(Tx_n - x_n)_{n \in \mathbb{N}}$ converge strongly to 0.
- ▶ $(x_n)_{n \in \mathbb{N}}$ converge weakly to a point in $\text{Fix } T$.

Fixed point algorithm: α -averaged operator

Proof :

Since T is α -average, there exists a non expansive operator R such that $T = (1 - \alpha)\text{Id} + \alpha R$.

Let $(\forall n \in \mathbb{N}) \mu_n = \alpha \lambda_n \in [0, 1]$.

The iterations can be written as

$$\begin{aligned} (\forall n \in \mathbb{N}) \quad x_{n+1} &= x_n + \lambda_n (Tx_n - x_n) \\ &= x_n + \mu_n (Rx_n - x_n). \end{aligned}$$

Moreover, $\text{Fix}R = \text{Fix}T$.

+ Krasnosel'skii-Mann algorithm.

Optimization algorithm: *Forward-Backward*

Let \mathcal{H} be a Hilbert space.

Let $f \in \Gamma_0(\mathcal{H})$.

Let $g \in \Gamma_0(\mathcal{H})$ be differentiable with a ν -Lipschitzian gradient where $\nu \in]0, +\infty[$.

Let $\gamma \in]0, 2/\nu[$ and $\delta = \min\{1, 1/(\nu\gamma)\} + 1/2$.

Let $(\lambda_n)_{n \in \mathbb{N}}$ be a sequence in $[0, \delta[$ such that $\sum_{n \in \mathbb{N}} \lambda_n (\delta - \lambda_n) = +\infty$.

We assume that $\text{Argmin}(f + g) \neq \emptyset$. Let $x_0 \in \mathcal{H}$ and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} y_n = x_n - \gamma \nabla g(x_n) \\ x_{n+1} = x_n + \lambda_n (\text{prox}_{\gamma f} y_n - x_n). \end{cases}$$

Then, $(x_n)_{n \in \mathbb{N}}$ converges weakly to a minimizer of $f + g$.

Optimization algorithm: *Forward-Backward*

Proof: Let $T = \text{prox}_{\gamma f} \circ (\text{Id} - \gamma \nabla g)$. For every $x \in \mathcal{H}$,

$$x \in \text{Fix } T \Leftrightarrow (\text{Id} - \gamma \nabla g)x \in (\text{Id} + \gamma \partial f)x \Leftrightarrow 0 \in \nabla g(x) + \partial f(x).$$

Consequently, $\text{Fix } T = \text{zer}(\nabla g + \partial f) \neq \emptyset$. Moreover, for every $n \in \mathbb{N}$,

$$x_{n+1} = x_n + \lambda_n (Tx_n - x_n).$$

$\text{prox}_{\gamma f}$ is $1/2$ -average and $\text{Id} - \gamma \nabla g$ is $\gamma\nu/2$ -averaged.

It follows that T is α -averaged with

$$\alpha = \frac{2}{1 + \frac{1}{\max\{\frac{1}{2}, \frac{\gamma\nu}{2}\}}} \Leftrightarrow \alpha^{-1} = \delta.$$

Optimization algorithm: projected gradient

Let \mathcal{H} be a Hilbert space.

Let C a nonempty closed convex subset of \mathcal{H} .

Let $g \in \Gamma_0(\mathcal{H})$ be differentiable with a ν -Lipschitzian gradient where $\nu \in]0, +\infty[$.

Let $\gamma \in]0, 2/\nu[$ and $\delta = \min\{1, 1/(\nu\gamma)\} + 1/2$.

Let $(\lambda_n)_{n \in \mathbb{N}}$ be a sequence in $[0, \delta[$ such that $\sum_{n \in \mathbb{N}} \lambda_n(\delta - \lambda_n) = +\infty$.

We assume that $\text{Argmin}_{x \in C} g(x) \neq \emptyset$. Let $x_0 \in \mathcal{H}$ and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} y_n = x_n - \gamma \nabla g(x_n) \\ x_{n+1} = x_n + \lambda_n (P_C y_n - x_n). \end{cases}$$

Then, $(x_n)_{n \in \mathbb{N}}$ converges weakly to a minimizer of g over C .

Optimization algorithm: gradient descent

Let \mathcal{H} be a Hilbert space.

Let $g \in \Gamma_0(\mathcal{H})$ be a differentiable function with a ν -lipschitzian gradient where $\nu \in]0, +\infty[$.

Let $\gamma \in]0, 2/\nu[$.

We assume that $\operatorname{Argmin} g \neq \emptyset$. Let $x_0 \in \mathcal{H}$ and

$$(\forall n \in \mathbb{N}) \quad x_{n+1} = x_n - \gamma \nabla g(x_n)$$

Then, $(x_n)_{n \in \mathbb{N}}$ converges weakly to a minimizer of f .

Optimization algorithm: Douglas-Rachford

Let \mathcal{H} be a Hilbert space.

Let $f \in \Gamma_0(\mathcal{H})$ and $g \in \Gamma_0(\mathcal{H})$.

$$(\forall n \in \mathbb{N}) \quad \begin{cases} y_n = \text{prox}_{\gamma g} x_n \\ z_n = \text{prox}_{\gamma f} (2y_n - x_n) \\ x_{n+1} = x_n + \lambda_n (z_n - y_n). \end{cases}$$

Optimization algorithm: Douglas-Rachford

Let \mathcal{H} be a Hilbert space.

Let $f \in \Gamma_0(\mathcal{H})$ and $g \in \Gamma_0(\mathcal{H})$.

Let $\gamma \in]0, +\infty[$ and let $(\lambda_n)_{n \in \mathbb{N}}$ be a sequence in $[0, 2]$ such that $\sum_{n \in \mathbb{N}} \lambda_n(2 - \lambda_n) = +\infty$.

We assume that $\text{zer}(\partial f + \partial g) \neq \emptyset$. Let $x_0 \in \mathcal{H}$ and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} y_n = \text{prox}_{\gamma g} x_n \\ z_n = \text{prox}_{\gamma f} (2y_n - x_n) \\ x_{n+1} = x_n + \lambda_n(z_n - y_n). \end{cases}$$

The following properties are satisfied:

- ▶ $x_n \rightarrow \hat{x}$
- ▶ $z_n - y_n \rightarrow 0$, $y_n \rightarrow \hat{y}$, $z_n \rightarrow \hat{y}$ where $\hat{y} = \text{prox}_{\gamma g} \hat{x} \in \text{Argmin}(f + g)$.

Optimization algorithm: Douglas-Rachford

Sketch of proof:

$$\underset{v \in \mathcal{G}}{\text{minimize}} \quad g(Lv) \quad \Leftrightarrow \quad \underset{x \in \mathcal{H}}{\text{minimize}} \quad \iota_E(x) + g(x)$$

where $E = \text{ran } L$.

We apply Douglas-Rachford algorithm with

$f = \iota_E \Rightarrow \text{prox}_{\gamma f} = P_E$ by setting

$$(\forall n \in \mathbb{N}) \quad P_E y_n = Lc_n \quad \text{and} \quad P_E x_n = Lv_n$$

where $c_n = \underset{c \in \mathcal{H}}{\text{argmin}} \quad \|y_n - Lc\|^2 = (L^*L)^{-1}L^*y_n$.

Optimization algorithm: Douglas-Rachford

Particular case of Douglas-Rachford algorithm:

$\mathcal{H} = \mathcal{H}_1 \times \cdots \times \mathcal{H}_m$ where $\mathcal{H}_1, \dots, \mathcal{H}_m$ Hilbert spaces

$(\forall x = (x_1, \dots, x_m) \in \mathcal{H}) \quad g(x) = \sum_{i=1}^m g_i(x_i)$

where $(\forall i \in \{1, \dots, m\}) \quad g_i \in \Gamma_0(\mathcal{H}_i)$

$L: v \mapsto (L_1 v, \dots, L_m v)$ where $(\forall i \in \{1, \dots, m\}) \quad L_i \in \mathcal{B}(\mathcal{G}, \mathcal{H}_i)$.

PPXA+ algorithm

Let $(x_{0,i})_{1 \leq i \leq m} \in \mathcal{H}$, $v_0 = (\sum_{i=1}^m L_i^* L_i)^{-1} \sum_{i=1}^m L_i^* x_{0,i}$ and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} y_{n,i} = \text{prox}_{\gamma g_i} x_{n,i}, & i \in \{1, \dots, m\} \\ c_n = (\sum_{i=1}^m L_i^* L_i)^{-1} \sum_{i=1}^m L_i^* y_{n,i} \\ x_{n+1,i} = x_{n,i} + \lambda_n (L_i (2c_n - v_n) - y_{n,i}), & i \in \{1, \dots, m\} \\ v_{n+1} = v_n + \lambda_n (c_n - v_n). \end{cases}$$

We have then $v_n \rightarrow \hat{v} \in \text{Argmin} \sum_{i=1}^m g_i \circ L_i$.

Optimization algorithm: Douglas-Rachford

Particular case of Douglas-Rachford algorithm:

$\mathcal{H} = \mathcal{H}_1 \times \cdots \times \mathcal{H}_m$ where $\mathcal{H}_1 = \cdots = \mathcal{H}_m$ Hilbert spaces

$(\forall x = (x_1, \dots, x_m) \in \mathcal{H}) \quad g(x) = \sum_{i=1}^m g_i(x_i)$

where $(\forall i \in \{1, \dots, m\}) \quad g_i \in \Gamma_0(\mathcal{H}_i)$

$L: v \mapsto (L_1 v, \dots, L_m v)$ where $L_1 = \dots = L_m = \text{Id}$.

PPXA algorithm

Let $(x_{0,i})_{1 \leq i \leq m} \in \mathcal{H}$, $v_0 = \frac{1}{m} \sum_{i=1}^m x_{0,i}$ and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} y_{n,i} = \text{prox}_{\gamma g_i} x_{n,i}, & i \in \{1, \dots, m\} \\ c_n = \frac{1}{m} \sum_{i=1}^m y_{n,i} \\ x_{n+1,i} = x_{n,i} + \lambda_n (2c_n - v_n - y_{n,i}), & i \in \{1, \dots, m\} \\ v_{n+1} = v_n + \lambda_n (c_n - v_n). \end{cases}$$

We have then $v_n \rightarrow \hat{v} \in \text{Argmin} \sum_{i=1}^m g_i$.