

# Optimization – Algorithms

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Nelly Pustelnik

CNRS, Laboratoire de Physique de l'ENS de Lyon, France



## Fixed point algorithm



## Fixed point algorithm: zeros and fixed points

$2^{\mathcal{H}}$  is the power set of  $\mathcal{H}$ , i.e. the family of all subsets of  $\mathcal{H}$ .

Let  $\mathcal{H}$  be a Hilbert space. Let  $\Phi: \mathcal{H} \rightarrow 2^{\mathcal{H}}$ .

The set of **fixed points** of  $\Phi$  is :  $\text{Fix}\Phi = \{x \in \mathcal{H} \mid x \in \Phi x\}$ .

The set of **zeros** of  $\Phi$  is :  $\text{zer}\Phi = \{x \in \mathcal{H} \mid 0 \in \Phi x\}$ .

## Fixed point algorithm: convergence

Let  $\mathcal{H}$  be a Hilbert space.

Let  $(x_k)_{k \in \mathbb{N}}$  be a sequence in  $\mathcal{H}$  and  $\hat{x} \in \mathcal{H}$ .

- $(x_k)_{k \in \mathbb{N}}$  **converges strongly** to  $\hat{x}$  if

$$\lim_{k \rightarrow +\infty} \|x_k - \hat{x}\| = 0.$$

It is denoted by  $x_k \rightarrow \hat{x}$ .

- $(x_k)_{k \in \mathbb{N}}$  **converges weakly** to  $\hat{x}$  if

$$(\forall y \in \mathcal{H}) \quad \lim_{n \rightarrow +\infty} \langle y \mid x_k - \hat{x} \rangle = 0.$$

It is denoted by  $x_k \rightharpoonup \hat{x}$ .

Remark: In a finite dimensional Hilbert space, strong and weak convergences are equivalent.

## Banach-Picard theorem

An operator  $\Phi: \mathcal{H} \rightarrow \mathcal{H}$  is  **$\omega$ -Lipschitz continuous** for some  $\omega \in [0, +\infty[$  if

$$(\forall x \in \mathcal{H})(\forall y \in \mathcal{H}) \quad \|\Phi x - \Phi y\| \leq \omega \|x - y\|.$$

$\Phi$  is **nonexpansive** if it is 1-Lipschitz continuous.

**Banach-Picard theorem** Let  $\omega \in [0, 1[,$  let  $\Phi: \mathcal{H} \rightarrow \mathcal{H}$  be a  $\omega$ -Lipschitz continuous operator, and let  $x_0 \in \mathcal{H}$ . Set

$$(\forall k \in \mathbb{N}) \quad x_{k+1} = \Phi x_k.$$

Then,  $\text{Fix}\Phi = \{\hat{x}\}$  for some  $\hat{x} \in \mathcal{H}$  and we have

$$(\forall k \in \mathbb{N}) \quad \|x_k - \hat{x}\| \leq \omega^k \|x_0 - \hat{x}\|.$$

Moreover,  $(x_k)_{k \in \mathbb{N}}$  converges strongly to  $\hat{x}$  with linear convergence rate  $\omega.$

## Averaged nonexpansive operator

An operator  $\Phi: \mathcal{H} \rightarrow \mathcal{H}$  is  **$\mu$ -averaged nonexpansive** for some  $\mu \in ]0, 1]$  if, for every  $x \in \mathcal{H}$  and  $y \in \mathcal{H}$ ,

$$\|\Phi x - \Phi y\|^2 \leq \|x - y\|^2 - \left( \frac{1 - \mu}{\mu} \right) \|(\text{Id} - \Phi)x - (\text{Id} - \Phi)y\|^2,$$

$\Phi$  is **firmly nonexpansive** if it is  $1/2$ -averaged.

$\Phi$  is **nonexpansive** if and only if  $\Phi$  is  $1$ -averaged.

**Theorem** Let  $\mu \in ]0, 1[$ , let  $\Phi: \mathcal{H} \rightarrow \mathcal{H}$  be a  $\mu$ -averaged nonexpansive operator such that  $\text{Fix}\Phi \neq \emptyset$ , and let  $x_0 \in \mathcal{H}$ . Set

$$(\forall k \in \mathbb{N}) \quad x_{k+1} = \Phi x_k.$$

Then  $(x_k)_{k \in \mathbb{N}}$  converges weakly to a point in  $\text{Fix}\Phi$ .

# Nonlinear operators

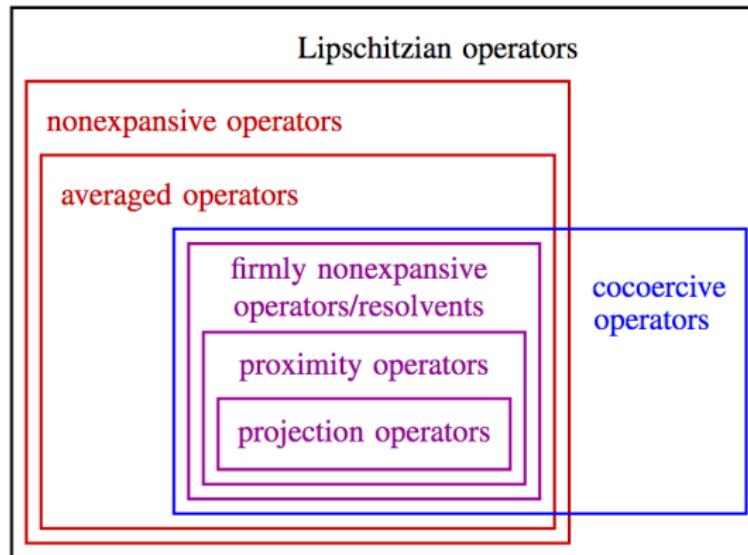


Fig. 3: Classes of nonlinear operators.

## Averaged operator: example

Let  $\mathcal{H}$  be a Hilbert space,  $f \in \Gamma_0(\mathcal{H})$ ,  $\nu \in ]0, 2[$ .

If  $f$  is  $\nu$ -smooth then,  $\text{Id} - \nabla f$  is a  $\nu/2$ -averaged operator.

Remark :  $\text{Id} - \nabla f$  denotes the gradient descent operator.

## Averaged operator: example

Proof : 1) Descent lemma

For every  $(x, y) \in \mathcal{H}^2$  and  $t \in \mathbb{R}$ , let  $\varphi(t) = f(x + t(y - x))$ .  
 $\varphi$  is differentiable and  $\varphi'(t) = \langle y - x \mid \nabla f(x + t(y - x)) \rangle$ . We have then

$$\varphi(1) - \varphi(0) = \int_0^1 \varphi'(t) dt$$

$$\Leftrightarrow f(y) - f(x) - \langle y - x \mid \nabla f(x) \rangle = \int_0^1 \langle y - x \mid \nabla f(x + t(y - x)) - \nabla f(x) \rangle dt.$$

But, according to the Cauchy-Schwarz inequality,

$$\begin{aligned} & \langle y - x \mid \nabla f(x + t(y - x)) - \nabla f(x) \rangle \\ & \leq \|y - x\| \|\nabla f(x + t(y - x)) - \nabla f(x)\| \leq t\nu \|y - x\|^2. \end{aligned}$$

This leads to

$$(\forall (x, y) \in \mathcal{H}^2) \quad f(y) \leq f(x) + \langle y - x \mid \nabla f(x) \rangle + \frac{\nu}{2} \|y - x\|^2.$$

## Averaged operator: example

Proof : 2)  $\text{Id} - \nabla f$  is  $\alpha$ -averaged

From the descent lemma, for every  $(x, y, z) \in \mathcal{H}^3$ ,

$$\begin{aligned} f^*(\nabla f(y)) &\geq \langle z \mid \nabla f(y) \rangle - f(z) \\ &\geq \langle z \mid \nabla f(y) - \nabla f(x) \rangle + \langle x \mid \nabla f(x) \rangle - f(x) - \frac{\nu}{2} \|z - x\|^2. \end{aligned}$$

Moreover, according to the Fenchel-Young inequality,

$$\langle x \mid \nabla f(x) \rangle - f(x) = f^*(\nabla f(x)).$$

Thus,

$$f^*(\nabla f(y)) \geq \langle z \mid \nabla f(y) - \nabla f(x) \rangle + f^*(\nabla f(x)) - \frac{\nu}{2} \|z - x\|^2$$

## Averaged operator: example

Proof : 2)  $\text{Id} - \nabla f$  is  $\mu$ -averaged

Thus,

$$\begin{aligned}f^*(\nabla f(y)) &\geq \langle z \mid \nabla f(y) - \nabla f(x) \rangle + f^*(\nabla f(x)) - \frac{\nu}{2} \|z - x\|^2 \\&= f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle + \langle z - x \mid \nabla f(y) - \nabla f(x) \rangle - \frac{\nu}{2} \|z - x\|^2.\end{aligned}$$

This yields

$$\begin{aligned}f^*(\nabla f(y)) &\geq f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle \\&\quad + (\nu \|\cdot\|^2 / 2)^* (\nabla f(y) - \nabla f(x)) \\&\geq f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle + \frac{1}{2\nu} \|\nabla f(y) - \nabla f(x)\|^2.\end{aligned}$$

Consequently,

$$f^*(\nabla f(y)) \geq f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle + \frac{1}{2\nu} \|\nabla f(y) - \nabla f(x)\|^2.$$

## Averaged operator: example

Proof : 2)  $\text{Id} - \nabla f$  is  $\mu$ -averaged

For every  $(x, y) \in \mathcal{H}^2$ ,

$$f^*(\nabla f(y)) \geq f^*(\nabla f(x)) + \langle x \mid \nabla f(y) - \nabla f(x) \rangle + \frac{1}{2\nu} \|\nabla f(y) - \nabla f(x)\|^2$$

and symmetrically

$$f^*(\nabla f(x)) \geq f^*(\nabla f(y)) + \langle y \mid \nabla f(x) - \nabla f(y) \rangle + \frac{1}{2\nu} \|\nabla f(x) - \nabla f(y)\|^2.$$

By summing

$$-\langle y - x \mid \nabla f(y) - \nabla f(x) \rangle + \frac{1}{\nu} \|\nabla f(x) - \nabla f(y)\|^2 \leq 0.$$

It results that

$$\|(\text{Id} - \nabla f)x - (\text{Id} - \nabla f)y\|^2 + \frac{1 - \nu/2}{\nu/2} \|\nabla f(x) - \nabla f(y)\|^2 \leq \|x - y\|^2.$$

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- We recall that :  $\partial f(x) = \{u \in \mathcal{H} \mid (\forall y \in \mathcal{H}) \langle y - x | u \rangle + f(x) \leq f(y)\}$

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- Let  $u_1 \in \partial f(x_1)$  and  $u_2 \in \partial f(x_2)$ .

By definition:

$$\langle x_2 - x_1 | u_1 \rangle + f(x_1) \leq f(x_2)$$

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it results that  $\boxed{\langle x_1 - x_2 | u_1 - u_2 \rangle \geq 0}$ .

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it results that  $\boxed{\langle x_1 - x_2 | u_1 - u_2 \rangle \geq 0}$ .

- *Remark :*  $\partial f$  is a monotone operator.

## Averaged operator: example

Proof :

Let  $u_1 \in \partial f(x_1)$  and  $u_2 \in \partial f(x_2)$

$$\langle x_1 - x_2 | u_1 - u_2 \rangle \geq 0 \Leftrightarrow \langle x_1 - x_2 | x_1 - x_2 + u_1 - u_2 \rangle \geq \|x_1 - x_2\|^2$$

We consider  $u'_1 \in (\text{Id} + \partial f)x_1$  et  $u'_2 \in (\text{Id} + \partial f)x_2$ , it results that

$$\langle x_1 - x_2 | u'_1 - u'_2 \rangle \geq \|x_1 - x_2\|^2$$

Then, from the definition of the proximity operator,

$$\langle \text{prox}_f u'_1 - \text{prox}_f u'_2 | u'_1 - u'_2 \rangle \geq \|\text{prox}_f u'_1 - \text{prox}_f u'_2\|^2$$

We can deduce that  $\text{prox}_f$  is a 1/2-averaged operator, i.e,

$$\|u'_1 - u'_2\|^2 \geq \|\text{prox}_f u'_1 - \text{prox}_f u'_2\|^2 + \|(\text{Id} - \text{prox}_f)u'_1 - (\text{Id} - \text{prox}_f)u'_2\|^2$$

## Composition of averaged operator

**Theorem** Let  $D$  be a nonempty subset of  $\mathcal{H}$ . Let  $\alpha_1 \in ]0, 1[$  and  $\alpha_2 \in ]0, 1[$ . Let  $\Phi_1 : D \rightarrow D$  be  $\alpha_1$ -averaged and  $\Phi_2 : D \rightarrow D$  be  $\alpha_2$ -averaged. Then  $\Phi = \Phi_1 \Phi_2$  is  $\alpha$ -averaged with

$$\alpha = \frac{\alpha_1 + \alpha_2 - 2\alpha_1\alpha_2}{1 - \alpha_1\alpha_2} \in ]0, 1[.$$

Proof: Extracted from Theorem 26.14 [Bauschke-Combettes, 2017]

## Gradient method

Let  $f \in \Gamma_0(\mathcal{H})$  and  $f$  is  $\nu$ -smooth. We set, for some  $\tau > 0$ ,

$$\Phi := \text{Id} - \tau \nabla f$$

- **Iterations:**  $(\forall k \in \mathbb{N}) \quad x_{k+1} = x_k - \tau \nabla f(x_k).$

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→ cf. s.7 or Proposition 4.39 in [Bauschke–Combettes, 2017]

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- For every  $\tau \in ]0, 2\nu^{-1}[$ , the gradient method **converges** to a point in  $\text{zer } \nabla f$ .  
→ cf. s.5

## Proximal Point Algorithm (PPA)

Let  $f \in \Gamma_0(\mathcal{H})$ . We set, for some  $\tau > 0$ ,

$$\Phi := \text{prox}_{\tau f} = (\text{Id} + \tau \partial f)^{-1}.$$

- **Iterations:**  $(\forall k \in \mathbb{N}) \quad x_{k+1} = \text{prox}_{\gamma f}(x_k).$

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- For every  $\tau > 0$ ,  $\text{Fix } \Phi = \text{zer } \partial f$ .

Proof:

$$\begin{aligned} x = \text{prox}_{\tau f} x &\Leftrightarrow x \in (\text{I} + \tau \partial f)x \\ &\Leftrightarrow x \in x + \tau \partial f(x) \\ &\Leftrightarrow 0 \in \partial f \end{aligned}$$

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- For every  $\tau > 0$ ,  $\text{Fix } \Phi = \text{zer } \partial f$ .
- For every  $\tau > 0$  and any  $f \in \Gamma_0(\mathcal{H})$ ,  $\text{prox}_{\tau f}$  is  $1/2$ -averaged.  
→ cf. s.10 or Proposition 23.8 in [Bauschke-Combettes, 2017]

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- The **PPA method converges** to a point in  $\text{zer } \partial f$ .  
→ cf. p.6

## Forward-backward splitting

Let  $f \in \Gamma_0(\mathcal{H})$  and  $\nu$ -smooth and  $g \in \Gamma_0(\mathcal{H})$ . We set, for some  $\tau > 0$ ,

$$\Phi := \text{prox}_{\tau g}(\text{Id} - \tau \nabla f) = (\text{Id} + \tau \partial g)^{-1}(\text{Id} - \tau \nabla f)$$

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- **Iterations:**  $(\forall k \in \mathbb{N}) \quad x_{k+1} = \text{prox}_{\tau g}(x_k - \tau \nabla f(x_k))$ .
- Roots in projected gradient method [Levitin 1966] when  $g = \iota_C$  for some closed convex set  $C$

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- **Iterations:**  $(\forall k \in \mathbb{N}) \quad x_{k+1} = \text{prox}_{\tau g}(x_k - \tau \nabla f(x_k)).$
- For every  $\tau > 0$ ,  $\text{zer}(\nabla f + \partial g) = \text{Fix}\Phi$ .

Proof:

$$\begin{aligned} x \in \text{Fix}\Phi &\Leftrightarrow (\text{Id} - \gamma \nabla f)x \in (\text{Id} + \gamma \partial g)x \\ &\Leftrightarrow 0 \in \nabla f(x) + \partial g(x). \end{aligned}$$

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- For every  $\tau > 0$ ,  $\text{zer}(\nabla f + \partial g) = \text{Fix } \Phi$ .
- $f \in \Gamma_0(\mathcal{H})$ ,  $\nabla f$  is  $\nu^{-1}$ -cocoercive and  $\tau \in ]0, 2\nu^{-1}[$ ,  $\text{prox}_{\tau g}(\text{Id} - \tau \nabla f)$  is  $\alpha$ -averaged nonexpansive where

$$\alpha = \frac{\alpha_1 + \alpha_2 - 2\alpha_1\alpha_2}{1 - \alpha_1\alpha_2}.$$

where  $\alpha_2 = \tau\nu/2$  and  $\alpha_1 = 1/2$  leading to

$$\alpha = \frac{1}{2 - \tau\nu/2} \in ]0, 1[.$$

Leading to

$$\gamma < 2/\nu.$$

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- For every  $\tau \in ]0, 2\nu^{-1}[$ , the **FBS method converges** to a point in  $\text{zer}(\nabla f + \partial g)$ .

## Peaceman-Rachford splitting

Let  $f \in \Gamma_0(\mathcal{H})$  and  $g \in \Gamma_0(\mathcal{H})$ . We set, for some  $\tau > 0$ ,

$$\Phi := (2\text{prox}_{\tau g} - \text{Id}) \circ (2\text{prox}_{\tau f} - \text{Id})$$

- **Iterations:**  $(\forall k \in \mathbb{N}) \quad x_{k+1} = 2\text{prox}_{\tau g}(2\text{prox}_{\tau f}x_k - x_k) - 2\text{prox}_{\tau f}x_k + x_k.$

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- For every  $\tau > 0$ ,  $\text{zer}(\nabla f + \partial g) = \text{prox}_{\tau f}(\text{Fix}\Phi)$ .  
→ cf. Proposition 26.1(iii)(b)[Bauschke-Combettes, 2017]

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→ cf. Proposition 26.1(iii)(b)[Bauschke-Combettes, 2017]
- Weak **convergence not guaranteed in this general setting**.
- Weak **convergence guaranteed if  $f$  is  $\nu$ -smooth**.  
→ cf. Corollary 1& Remark 2(2) [Lions-Mercier, 1979]

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→ cf. Proposition 26.1(iii)(b)[Bauschke-Combettes, 2017]

## Douglas-Rachford splitting

Let  $f \in \Gamma_0(\mathcal{H})$  and  $g \in \Gamma_0(\mathcal{H})$ . We set, for some  $\tau > 0$ ,

$$\Phi := \text{prox}_{\tau g} \circ (2\text{prox}_{\tau f} - \text{Id}) + \text{Id} - \text{prox}_{\tau f}$$

- **Iterations:**  $(\forall k \in \mathbb{N}) \quad x_{k+1} = \text{prox}_{\tau g}(2\text{prox}_{\tau f}x_k - x_k) + x_k - \text{prox}_{\tau f}x_k.$
- For every  $\tau > 0$ ,  $\text{zer}(\nabla f + \partial g) = \text{prox}_{\tau f}(\text{Fix}\Phi).$   
→ cf. Proposition 26.1(iii)(b)[Bauschke-Combettes, 2017]
- **Weak convergence** insured as  
→ cf. Corollary 1& Remark 2(2) [Lions-Mercier, 1979]

## Additional properties of smooth functions

Let  $f \in \Gamma_0(\mathcal{H})$  and  $\nu$ -smooth. Then

$$(\forall x, y \in \mathcal{H}) \quad \langle \nabla f(x) - \nabla f(y) | x - y \rangle \leq \nu \|x - y\|^2$$

Proof: From Cauchy-Schwarz inequality

$$\begin{aligned} & \langle \nabla f(x) - \nabla f(y) | x - y \rangle \\ & \leq \|x - y\| \|\nabla f(x) - \nabla f(y)\| \\ & \leq \nu \|x - y\|^2. \end{aligned}$$

## Additional properties of smooth functions

Let  $f \in \Gamma_0(\mathcal{H})$  and  $\nu$ -smooth. Then

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Proof: From Cauchy-Schwarz inequality

$$\begin{aligned} & \langle \nabla f(x) - \nabla f(y) | x - y \rangle \\ & \leq \|x - y\| \|\nabla f(x) - \nabla f(y)\| \\ & \leq \nu \|x - y\|^2. \end{aligned}$$

Let  $f \in \Gamma_0(\mathcal{H})$  and  $\nu$ -smooth. Then

$$(\forall x, y \in \mathcal{H}) \quad \|\nabla f(x) - \nabla f(y)\|^2 \leq \nu \langle \nabla f(x) - \nabla f(y) | x - y \rangle$$

Proof: cf. s. 8.

## Strong convexity

Let  $f \in \Gamma_0(\mathcal{H})$ .  $f$  is  **$\rho$ -strongly convex** with  $\rho > 0$  if

$$f - \frac{\rho}{2} \|\cdot\|_2^2$$

is convex.

### Properties:

- If  $f$  is  $\rho$ -strongly convex then

$$(\forall x, y \in \mathcal{H}) \quad \langle \nabla f(x) - \nabla f(y) | x - y \rangle \geq \rho \|x - y\|^2$$

- If  $f$  is twice differentiable, then  $f$  is  $\rho$ -strongly convex if and only if all the eigenvalues of the Hessian matrix of  $f$  are at most equal to  $\rho$ .

## Gradient method: linear convergence

Let  $f \in \Gamma_0(\mathcal{H})$  and  $f$  is  $\nu$ -smooth and  $\rho$  strongly convex.  
We set, for some  $\tau \in ]0, 2/\nu[$ ,

$$\Phi := \text{Id} - \tau \nabla f$$

Then,

$$(\forall k \in \mathbb{N}) \quad \|x_k - \hat{x}\| \leq \omega^k \|x_0 - \hat{x}\|.$$

with

$$\omega = \max\{|1 - \tau\rho|, |1 - \tau\nu|\}$$

Moreover,  $(x_k)_{k \in \mathbb{N}}$  converges strongly to  $\hat{x}$  with linear convergence rate  $\omega$ .

## Gradient method: linear convergence

Proof:

- Since  $f$  is  $\nu$  smooth and  $\rho$  strongly convex with  $\nu > \rho$ :

$$(\forall x, y \in \mathcal{H}) \quad \langle \nabla f(x) - \nabla f(y) | x - y \rangle \leq \nu \|x - y\|^2$$

by subtracting  $-\rho \|x - y\|^2$ :

$$\begin{aligned} \langle \nabla f(x) - \nabla f(y) - \rho x + \rho y | x - y \rangle &\leq \nu \|x - y\|^2 - \rho \|x - y\|^2 \\ &\leq (\nu - \rho) \|x - y\|^2 \end{aligned}$$

$\rightarrow \tilde{f} = f - \frac{\rho}{2} \|\cdot\|^2$  is  $(\nu - \rho)$ -smooth.

- Gradient descent on  $f$ :

$$\begin{aligned} G_{\tau \nabla f} &= \text{Id} - \tau \nabla f \\ &= \text{Id} - \tau \nabla \tilde{f} - \tau \rho \text{Id} \\ &= (1 - \tau \rho) \text{Id} - \tau \nabla \tilde{f} \end{aligned}$$

## Gradient method: linear convergence

Proof:

- Let  $\tau \in ]0, \frac{2}{\nu}[$  and  $\begin{cases} p = G_{\tau \nabla f} x \\ q = G_{\tau \nabla f} y \end{cases}$

$$\begin{aligned}\|p - q\|^2 &= \|(1 - \tau\rho)(x - y) - \tau\nabla\tilde{f}(x) - \nabla\tilde{f}(y)\|^2 \\ &= (1 - \tau\rho)^2\|(x - y)\|^2 + \tau^2\|\nabla\tilde{f}(x) - \nabla\tilde{f}(y)\|^2 \\ &\quad - 2(1 - \tau\rho)\tau\langle(x - y)|\nabla\tilde{f}(x) - \nabla\tilde{f}(y)\rangle \\ &\leq (1 - \tau\rho)^2\|(x - y)\|^2 \\ &\quad + (\tau^2\nu - 2(1 - \tau\rho)\tau)\langle(x - y)|\nabla\tilde{f}(x) - \nabla\tilde{f}(y)\rangle \\ &\leq (1 - \tau\rho)^2\|(x - y)\|^2 \\ &\quad + \max\{0, \tau(\tau(\nu + \rho) - 2)\}(\nu - \rho)\|x - y\|^2 \\ &\leq \max\{(1 - \tau\rho)^2, (1 - \tau\nu)^2\}\|x - y\|^2\end{aligned}$$

## Forward-Backward method: linear convergence

Let  $f \in \Gamma_0(\mathcal{H})$  and  $f$  is  $\nu$ -smooth and  $\rho$  strongly convex and  $g \in \Gamma_0(\mathcal{H})$ . We set, for some  $\tau \in ]0, 2/\nu[$ ,

$$\Phi := \text{prox}_{\tau g}(\text{Id} - \tau \nabla f)$$

Then,

$$(\forall k \in \mathbb{N}) \quad \|x_k - \hat{x}\| \leq \omega^k \|x_0 - \hat{x}\|.$$

with

$$\omega = \max\{|1 - \tau\rho|, |1 - \tau\nu|\}$$

Moreover,  $(x_k)_{k \in \mathbb{N}}$  converges strongly to  $\hat{x}$  with linear convergence rate  $\omega$ .

Remark: Same rate as gradient descent.

## Forward-Backward method: linear convergence

Let  $f \in \Gamma_0(\mathcal{H})$  and  $f$  is  $\nu$ -smooth and  $\rho$  strongly convex and  $g \in \Gamma_0(\mathcal{H})$ . We set, for some  $\tau \in ]0, 2/\nu[$ ,

$$\Phi := \text{prox}_{\tau g}(\text{Id} - \tau \nabla f)$$

Then,

$$(\forall k \in \mathbb{N}) \quad \|x_k - \hat{x}\| \leq \omega^k \|x_0 - \hat{x}\|.$$

with

$$\omega = \max\{|1 - \tau\rho|, |1 - \tau\nu|\}$$

Moreover,  $(x_k)_{k \in \mathbb{N}}$  converges strongly to  $\hat{x}$  with linear convergence rate  $\omega$ .

Proof: The proximity is a non expansive operator, that is for

$$\begin{cases} \tilde{p} = \text{prox}_{\tau g}(G_{\tau \nabla f} x) \\ \tilde{q} = \text{prox}_{\tau g}(G_{\tau \nabla f} y) \end{cases} \quad \text{leading to } \|\tilde{p} - \tilde{q}\| \leq \|p - q\|$$

# Comparisons

Let  $f \in C_{1/\alpha}^{1,1}(\mathcal{H})$  and  $g \in C_{1/\beta}^{1,1}(\mathcal{H})$ , for some  $\alpha > 0$  and  $\beta > 0$ .

The problem is to

$$\underset{x \in \mathcal{H}}{\text{minimize}} \quad f(x) + g(x),$$

under the assumption that solutions exist.

## Example: Smooth TV denoising

$$\underset{x \in \mathbb{R}^N}{\text{minimize}} \quad \frac{1}{2} \|x - z\|_2^2 + \chi h_\mu(Lx),$$

- $L \in \mathbb{R}^{N-1 \times N}$  denotes the first order discrete difference operator
$$(\forall n \in \{1, \dots, N-1\}) \quad (Lx)_n = \frac{1}{2}(x_n - x_{n-1})$$
- $h_\mu$ : Huber loss, the smooth approximation of the  $\ell_1$ -norm parametrized by  $\mu > 0$ .

$$h_\mu \in C_{1/\mu}^{1,1}(\mathbb{R}^{N-1}).$$

Closed form expression of  $\text{prox}_{h_\mu}$ .

# Comparisons

**Proposition** (see [Briceno-Arias, Pustelnik, 2021] for detailed references)

In the context of Problem p.16, suppose that  $f$  is  $\rho$ -strongly convex, for some  $\rho \in ]0, \alpha^{-1}[$ , and let  $\tau > 0$ . Then, the following holds:

1. **Gradient descent** Suppose that  $\tau \in ]0, 2\beta\alpha/(\beta + \alpha)[$ . Then,  $\text{Id} - \tau(\nabla g + \nabla f)$  is  $r_G(\tau)$ -Lipschitz continuous, where

$$r_G(\tau) := \max \{ |1 - \tau\rho|, |1 - \tau(\beta^{-1} + \alpha^{-1})| \} \in ]0, 1[. \quad (1)$$

In particular, the minimum in (1) is achieved at

$$\tau^* = \frac{2}{\rho + \alpha^{-1} + \beta^{-1}}$$

and

$$r_G(\tau^*) = \frac{\alpha^{-1} + \beta^{-1} - \rho}{\alpha^{-1} + \beta^{-1} + \rho}.$$

## Comparisons

**Proposition** (see [Briceno-Arias, Pustelnik, 2021] for detailed references)

In the context of Problem p.16, suppose that  $f$  is  $\rho$ -strongly convex, for some  $\rho \in ]0, \alpha^{-1}[$ , and let  $\tau > 0$ . Then, the following holds:

1. **FBS** Suppose that  $\tau \in ]0, 2\alpha[$ . Then  $\text{prox}_{\tau g}(\text{Id} - \tau \nabla f)$  is  $r_{T_1}(\tau)$ -Lipschitz continuous, where

$$r_{T_1}(\tau) := \max \{ |1 - \tau\rho|, |1 - \tau\alpha^{-1}| \} \in ]0, 1[. \quad (1)$$

In particular, the minimum in (1) is achieved at

$$\tau^* = \frac{2}{\rho + \alpha^{-1}} \quad \text{and} \quad r_{T_1}(\tau^*) = \frac{\alpha^{-1} - \rho}{\alpha^{-1} + \rho}.$$

## Comparisons

**Proposition** (see [Briceno-Arias, Pustelnik, 2021] for detailed references)

In the context of Problem p.16, suppose that  $f$  is  $\rho$ -strongly convex, for some  $\rho \in ]0, \alpha^{-1}[$ , and let  $\tau > 0$ . Then, the following holds:

1. **FBS** Suppose that  $\tau \in ]0, 2\beta]$ . Then  $\text{prox}_{\tau f}(\text{Id} - \tau \nabla g)$  is  $r_{T_2}(\tau)$ -Lipschitz continuous, where  $r_{T_2}(\tau) := \frac{1}{1 + \tau\rho} \in ]0, 1[$ . In particular, the minimum in (1) is achieved at

$$\tau^* = 2\beta \quad \text{and} \quad r_{T_2}(\tau^*) = \frac{1}{1 + 2\beta\rho}.$$

## Comparisons

**Proposition** (see [Briceno-Arias, Pustelnik, 2021] for detailed references)

In the context of Problem p.16, suppose that  $f$  is  $\rho$ -strongly convex, for some  $\rho \in ]0, \alpha^{-1}[$ , and let  $\tau > 0$ . Then, the following holds:

1. **PRS**  $(2\text{prox}_{\tau g} - \text{Id}) \circ (2\text{prox}_{\tau f} - \text{Id})$  and  $(2\text{prox}_{\tau f} - \text{Id}) \circ (2\text{prox}_{\tau g} - \text{Id})$  are  $r_R(\tau)$ -Lipschitz continuous, where

$$r_R(\tau) = \max \left\{ \frac{1 - \tau\rho}{1 + \tau\rho}, \frac{\tau\alpha^{-1} - 1}{\tau\alpha^{-1} + 1} \right\} \in ]0, 1[. \quad (1)$$

In particular, the minimum in (1) is achieved at

$$\tau^* = \sqrt{\frac{\alpha}{\rho}} \quad \text{and} \quad r_R(\tau^*) = \frac{1 - \sqrt{\alpha\rho}}{1 + \sqrt{\alpha\rho}}.$$

# Comparisons

**Proposition** (see [Briceno-Arias, Pustelnik, 2021] for detailed references)

In the context of Problem p.16, suppose that  $f$  is  $\rho$ -strongly convex, for some  $\rho \in ]0, \alpha^{-1}[$ , and let  $\tau > 0$ . Then, the following holds:

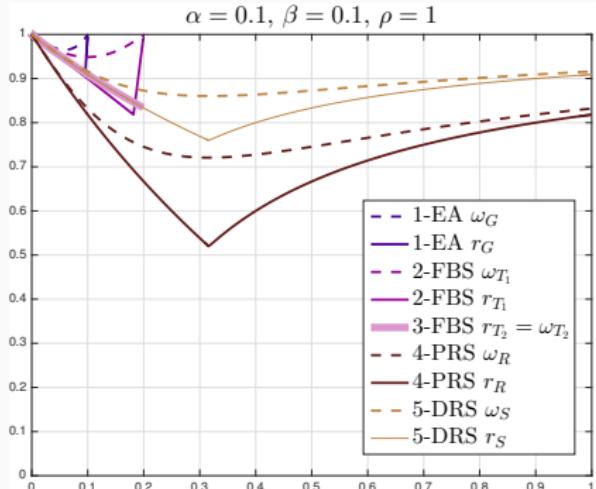
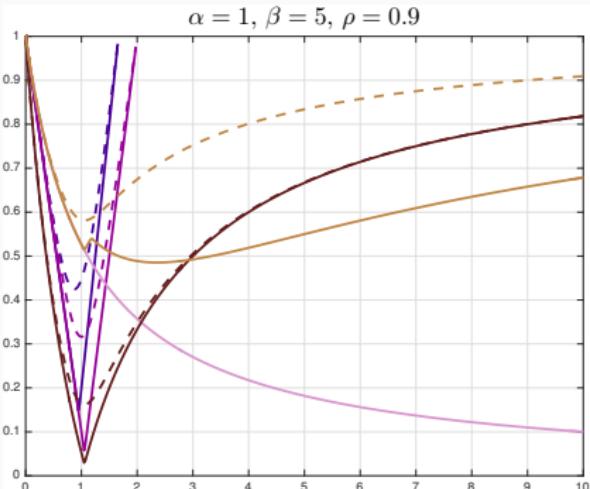
1. **DRS**  $S_{\tau \nabla g, \tau \nabla f}$  and  $S_{\tau \nabla f, \tau \nabla g}$  are  $r_S(\tau)$ -Lipschitz continuous, where

$$r_S(\tau) = \min \left\{ \frac{1 + r_R(\tau)}{2}, \frac{\beta + \tau^2 \rho}{\beta + \tau \beta \rho + \tau^2 \rho} \right\} \in ]0, 1[ \quad (1)$$

and  $r_R$  is defined in p.16. In particular, the optimal step-size and the minimum in (1) are

$$(\tau^*, r_S(\tau^*)) = \begin{cases} \left( \sqrt{\frac{\alpha}{\rho}}, \frac{1}{1 + \sqrt{\alpha \rho}} \right), & \text{if } \beta \leq 4\alpha; \\ \left( \sqrt{\frac{\beta}{\rho}}, \frac{2}{2 + \sqrt{\beta \rho}} \right), & \text{otherwise.} \end{cases}$$

# Theoretical comparisons



Comparison of the convergence rates of EA, FBS, PRS, DRS for two choices of  $\alpha$ ,  $\beta$ , and  $\rho$ . Note that optimization rates are better than cocoercive rates in general.

## Example: Smooth TV denoising

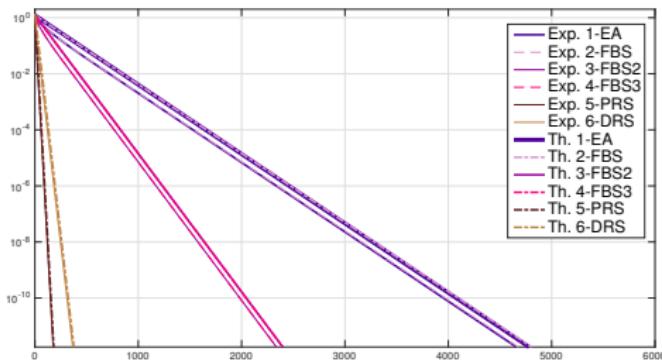
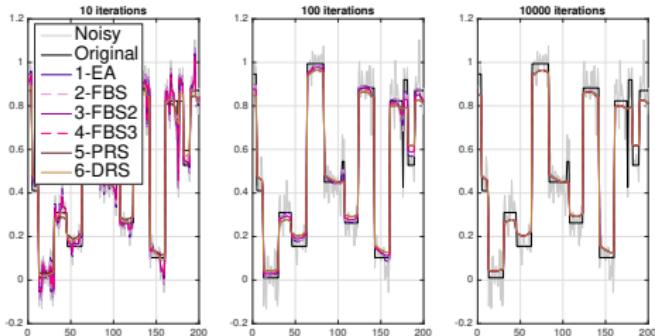
- **First formulation:** minimize  $\underbrace{\frac{1}{2}\|x - z\|_2^2}_{f(x)} + \underbrace{\chi h(Lx)}_{g(x)}$   
 $\rightarrow f$  is  $\rho = 1$  strongly convex,  $\alpha = 1$ , and  $\beta = \frac{\mu}{\chi\|L\|^2}$ .

- 1- **EA:** Use  $G_\tau(\nabla g + \nabla f)$
- 2- **FBS:** Use  $T_{\tau\nabla f, \tau\nabla g}$

- **Second formulation:**  $\min_{x \in \mathcal{H}} \underbrace{\frac{1}{2}\|x - z\|_2^2}_{\tilde{f}(x)} + \underbrace{\chi h_{\mathbb{I}_1}(L_{\mathbb{I}_1}x) + \chi h_{\mathbb{I}_2}(L_{\mathbb{I}_2}x)}_{\tilde{g}(x)}$   
 $\rightarrow \tilde{f}$  is  $\rho = 1$  strongly convex,  $\alpha = \frac{\mu}{\mu + \chi\|L_{\mathbb{I}_2}\|^2}$ , and  $\beta = \frac{\mu}{\chi\|L_{\mathbb{I}_1}\|^2}$ .

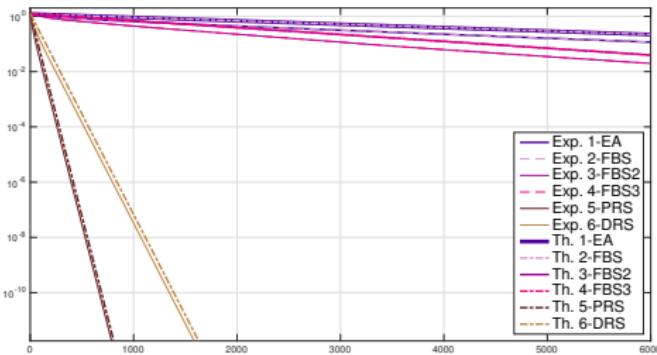
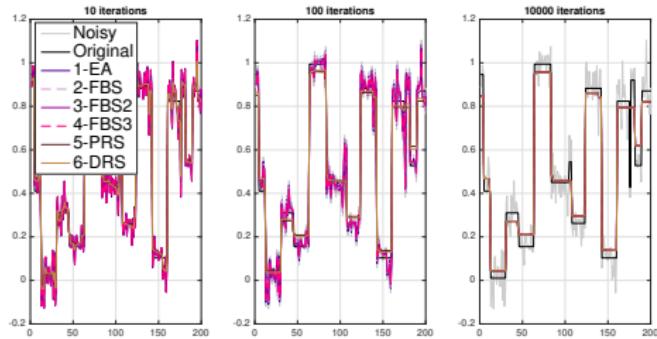
- 3- **FBS 2:** Use  $T_{\tau\nabla \tilde{g}, \tau\nabla \tilde{f}}$
- 4- **FBS 3:** Use  $T_{\tau\nabla \tilde{f}, \tau\nabla \tilde{g}}$
- 5- **PRS:** Use  $R_{\tau\nabla \tilde{f}, \tau\nabla \tilde{g}}$
- 6- **DRS:** Use  $S_{\tau\nabla \tilde{f}, \tau\nabla \tilde{g}}$

# Numerical and theoretical comparisons



Piecewise constant denoising estimates after 10, 100, and 10000 iterations with  $\chi = 0.7$  and  $\mu = 0.002$  when considering gradient descent, FBS, PRS or DRS. Associated theoretical and numerical convergence rates.

# Numerical and theoretical comparisons



Piecewise constant denoising estimates after 10, 100, and 10000 iterations with  $\chi = 0.7$  and  $\mu = 0.0001$  when considering gradient descent, FBS, PRS or DRS. Associated theoretical and numerical convergence rates.

# Optimization algorithms

Forward-Backward	$f + g$	$f$ $\zeta$ -smooth $\text{prox}_g$	[Combettes,Wajs,2005]
ISTA	$f + g$	$f$ $\zeta$ -smooth $g = \lambda \ \cdot\ _1$	[Daubechies et al, 2003]
Projected gradient	$f + g$	$f$ $\zeta$ -smooth $g = \iota_C$	
Gradient descent	$f + g$	$f$ $\zeta$ -smooth $f_2 = 0$	
Douglas-Rachford	$f + g$	$\text{prox}_f$ $\text{prox}_{f_2}$	[Combettes,Pesquet, 2007]
PPXA	$\sum_i f_i$	$\text{prox}_{f_i}$	[Combettes,Pesquet, 2008]

## Forward-Backward method: Worst case complexity

Let  $f \in \Gamma_0(\mathcal{H})$  and  $f$  is  $\zeta$ -smooth and  $g \in \Gamma_0(\mathcal{H})$ .

We set, for some  $\tau \in ]0, 1/\beta]$  where  $\beta \geq \zeta$ ,

$$\Phi := \text{prox}_{\tau g}(\text{Id} - \tau \nabla f)$$

Then,

$$(\forall k \geq 1) \quad f(x_k) - f(\hat{x}) \leq \frac{\beta}{2k} \|x_0 - \hat{x}\|^2.$$

## Make algorithms faster

---

# Acceleration: Nesterov acceleration

## Beck-Teboulle proximal gradient algorithm (FISTA)

[Beck, Teboulle, 2009]:

- **Goal:**  $\min_{x \in \mathcal{H}} f(x) + g(x)$  with  $f$  is  $\nu$ -Lipschitz differentiable.
- **Iterations:** Let  $\gamma \in ]0, 1/\nu[$ ,  $x_0 = z_0 \in \mathcal{H}$ ,  $t_0 = 1$ , and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_{n+1} = \text{prox}_{\gamma g}(z_n - \gamma \nabla f(z_n)) \\ t_{n+1} = \frac{1 + \sqrt{4t_n^2 + 1}}{2} \\ \lambda_n = \frac{t_n - 1}{t_{n+1}} \\ z_{n+1} = x_{n+1} + \lambda_n(x_{n+1} - x_n). \end{cases}$$

- **Guarantees:**

- Convergence of  $(f(x_n) + g(x_n))_{n \in \mathbb{N}}$  with rate  $O(1/n^2)$ .
- Convergence of  $(x_n)_{n \in \mathbb{N}}$  not secured theoretically.

## Acceleration: Nesterov acceleration

### Chambolle-Dossal proximal gradient algorithm

[Chambolle,Dossal,2015]:

- **Goal:**  $\min_{x \in \mathcal{H}} f(x) + g(x)$  with  $f$  is  $\nu$ -Lipschitz differentiable.
- **Iterations:** Let  $\gamma \in ]0, 1/\nu[$ ,  $x_0 = z_0 \in \mathcal{H}$ ,  $a > 2$ , and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_{n+1} = \text{prox}_{\beta^{-1}g}(z_n - \beta^{-1}\nabla f(z_n)) \\ \lambda_n = \frac{n-1}{n+a} \\ z_{n+1} = x_{n+1} + \lambda_n(x_{n+1} - x_n). \end{cases}$$

- **Guarantees:**

- Convergence of  $(f(x_n) + g(x_n))_{n \in \mathbb{N}}$  with rate  $O(1/n^2)$ .
- Convergence of  $(x_n)_{n \in \mathbb{N}}$ .