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Synthetic schlieren—application to the visualization and characterization of air convection

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Abstract

Synthetic schlieren is a digital image processing optical method relying on the variation of optical index to visualize the flow of a transparent fluid. In this article, we present a step-by-step, easy-to-implement and affordable experimental realization of this technique. The method is applied to air convection caused by a warm surface. We show that the velocity of rising convection plumes can be linked to the temperature of the warm surface and propose a simple physical argument to explain this dependence. Moreover, using this method, one can reveal the tenuous convection plumes rising from one's hand, a phenomenon invisible to the naked eye. This spectacular result may help students to realize the power of careful data acquisition combined with astute image processing techniques. This spectacular result may help students to realize the power of careful data acquisition combined with astute image processing techniques (refer to the video abstract).

Supplementary material for this article is available online

Keywords: synthetic schlieren, air convection, optics

(Some figures may appear in colour only in the online journal)

1. Introduction

Optical methods such as shadowgraphy [1-3], Mach–Zehnder interferometry [4] or schlieren methods [5, 6] provide a dynamic and non-intrusive method to visualize small variations in the optical index of refraction n of a transparent media [7]. The schlieren technique is

particularly spectacular and simple/low cost to implement, and as such makes a good candidate for student lab classes. Schlieren experiments are widely used in fluid dynamics to study physical phenomena where the index of refraction of the media is affected, as in shock waves [8–10], heat emanating from a system [11–13] or internal waves [14, 15].

The physical basis for schlieren imaging emerges from geometrical optics principles. In an homogeneous transparent media the light rays propagate uniformly at a constant velocity. However, in the presence of spatial variations of the index of refraction, light rays are refracted and deflected from their continuous path according to Snell's law of refraction. Schlieren experiments take advantage of the rays' deflection to create contrasted images that map the variations of the index of refraction.

The name 'schlieren experiments' groups a large variety of setups [7, 16–18]. The first use of the schlieren technique dates back to the end of the nineteenth century by Toepler and led, for instance, to the first observation of shock waves. It is based on imaging the variations of the index of refraction using a knife edge blocking part of the light rays (which can be understood as a Fourier optical filtering system) [19]. Here we focus on 'synthetic schlieren', a variation of the schlieren methods which was originally developed by Sutherland, Dalziel, Hughes and Linden in 1999 [14, 20] and applied, for instance, to natural convection problems [21]. This method relies on imaging a pattern through a media with a varying index of refraction. Digital image processing then allows one to infer the variations of the index of refraction of a slab of fluid are described in section 2. This technique is then applied to the visualization and characterization of air convection induced by a heat source in section 3. In particular, we show that it is possible to visualize and measure the heat of hands being rubbed together.

The pedagogical interest of the synthetic schlieren method is manifold. It is a direct illustration of the principles of geometrical optics and thermal convection. Indeed, the method makes use of slight differences (whose typical size is only a fraction of the probing wavelength) in images to reveal fine details of otherwise invisible phenomena (as demonstrated by the convection plumes rising from a hand; see figure 5). Moreover, this paper constitutes an interesting introduction to setting up a simple optics experiment as well as to data analysis and image processing, which are now widely used in undergraduate lab projects thanks to the spread of affordable high-speed digital cameras. Using a user-friendly, free software, one is able to visualize a seemingly invisible flow in a few simple steps, and can extract the velocity of rising convection plumes using an insightful built-in space-time tool.

2. Synthetic schlieren experiment

2.1. Experimental setup

The experimental setup to perform synthetic schlieren is shown in figure 1. A camera (Ximea xiQ model MQ013MG-ON) with an objective with a zoom of 12.5-75 mm is mounted on a tripod at y = 0 cm and z = 30 cm. The camera focuses on a checkerboard at $y = d_1 + d_2 = 200$ cm. We use the zoom to image the full checkerboard. The checkerboard is printed on a transparent plastic A4 sheet and composed of black squares and transparent squares of equal dimensions L = 0.9 mm. Backlighting of the sheet is provided by a LED panel to allow for fast acquisition rates, f, typically in a range of 25 to 200 Hz.

The experiment is undertaken in two steps. First, a reference image $I_0(x, z)$ of the checkerboard is acquired. Then a physical phenomenon that disturbs the air index of



Figure 1. Schematic of the synthetic schlieren experiment. A camera is focused on a checkerboard printed on a transparent plastic sheet and back-illuminated by a LED panel. A heat source is placed between the camera and the checkerboard and induces air convection. The air convection is associated to a temperature, density and index of refraction gradient in the air just above the heat source surface. The checkerboard image is altered because the light rays deviate toward the high indexes of refractions. The analysis of this alteration induced by variation of the index of refraction is at the core of the synthetic schlieren experiment. (b) Data acquisition procedure.

refraction in the camera field at $y = d_1 = 100$ cm between the camera and the checkerboard is turned on. In this article, we illustrate the synthetic schlieren technique to visualize plumes, convected columns of hot air produced by a heat source. The air convection is associated in the z-direction to a gradient of temperature ∇T , density $\nabla \rho$ and index of refraction ∇n of the air just above the heat source surface. The checkerboard image I(t, x, z) is recorded as a function of the time t at a rate f by the camera. As light rays deviate toward the higher value index of refractions, the index of refraction variations ∇n modify the image of the checkerboard I as compared to the reference image I_0 . Visualization of the plumes is then achieved from the analysis of this alteration. The heat source temperature may also be determined, providing a calibration procedure.

I is changed compared to I_0 . Indeed, due to the ∇n , the light rays deviate toward the high index of refractions. The analysis of this alteration permits one to visualize the plume and even determine the heat source temperature provided the experiment is calibrated.

2.2. Data analysis

The data reduction used in this article is a three-step process that can be done with ImageJ, a free software dedicated to image analysis [22]. Those steps are described in the supplementary materials, available online at stacks.iop.org/EJP/39/035803/mmedia. For each image, the first two steps provide an image displaying the intensity of the variation of the index of refraction. This series of images can then be either analyzed as a movie or, following the approach described as a third step in this article, using spatio-temporal diagrams.



Figure 2. Typical data processing. The heat source is the flame from a lighter. (a) Image of the checkerboard $I_0(x, z)$ at room temperature $T_0 = 25$ °C. (b) Image of grid I(t, x, z) when the heat source is on. (c) Image resulting from the synthetic schlieren, $I_{s1}(t, x, z)$. (d) Filtered image, $I_{s2}(t, x, z)$. (e) Overall image, I_{s2} . The blue box indicates the region of interest displayed in (a–d). There are two scale bars: the green upper one is related to the grip plan and the lower orange one is related to the heat source plan. Both represent 1 cm. (f) Analysis procedure.

The first two steps are illustrated in figure 2. I_0 is subtracted to each image I(t, x, z) to provide a stack of images $I_{s1}(t, x, z)$. When there is no variation in the index of refraction, the image I(t, x, z) is identical to I_0 and the difference is null, leading to a black I_{s1} image. In the presence of variations of the index of refraction, I(t, x, z) is a distorted image of the checkerboard and the resulting image $I_{s1}(t, x, z)$ shows grey spots of which the spatial extension δr is related to the intensity of the fluctuations of the refractive index in the $y = d_1$ plan. These grey spots in I_{s1} are then low-pass filtered to form a continuum I_{s2} image. Either a low-pass or a Gaussian blur filter are used with a cutoff length l_c of at least twice the checkerboard periodicity ($l_c = 4L = 3.6 \text{ mm}$). Figure 2(e) shows I_{s2} , the resulting schlieren image induced by the flame of a lighter. We observe plumes rising over time. I_{s2} displays two scale bars. The green one corresponds to the scale bar in the checkerboard plan. The orange one corresponds to the scale of objects placed in the heat source plane. Due to the setup geometry there is a perspective effect, and objects' position at $y = d_1$ appear larger than objects placed at $y = d_1 + d_2$.

In this article, we detail a last data reduction step permitting one to visualize the dynamics of the plumes. It consists in computing a spatio-temporal diagram $ST(t, x_0, z)$ of the stack of images I_{s2} , as displayed in figure 3. ST is obtained by choosing a horizontal position x_0 and plotting $I_{s2}(t, x_0, z)$ as a function of t and z. The z-axis is graduated following the orange scale bar related to the heat source plan. In this representation we observe grey inclined lines, which are the trace of the rising plumes. Around 5 cm above the heat source, the line inclination becomes constant over time. In this region their inclination yields a stationary plume rising velocity v. By measuring different line inclinations within the time frame of the experiment, typically a few seconds, and at different x_0 we determine the average velocity v of the plume and its standard deviation dv. We typically find that $dv/v \sim 20\%$.



Figure 3. Spatio-temporal diagram. (a) The synthetic schlieren experiment produces a stack of images $I_{s2}(t, x, z)$ that display the local checkerboard deformation of spatial amplitude δr . The setup is chosen so that δr is about the pixel size but smaller than the grid size *L*. For a hot heat source, these deformations propagate upward. Following these deformations permits one to determine the rising velocity *v* of the plume. (b) *ST*(*t*, x_0 , *z*) is the spatio-temporal diagram of the stack I_{s2} . *ST* is obtained by choosing a horizontal position x_0 and plotting $I_{s2}(t, x_0, z)$ as a function of *t* and *z*. The *z*-axis is graduated following the scale bar relating the heat source plan. The inclination of the pattern indicates the plume velocity *v*. An aluminum block at T = 81 °C yield $v = 70 \pm 8$ cm/s.

2.3. Set-up parameters

Obviously I_0 and I must be acquired in the same conditions. If the checkerboard has moved from one acquisition to the other, a moiré pattern is observed in the background of I_{s1} .

This experiment depends crucially on a few parameters: d_1 , the distance between the camera and the heat source; d_2 , the distance between the heat source and the checkerboard; L, the square size on the checkerboard; and f, the acquisition frequency.

The values of d_1 and d_2 set the orange and green scale bars on I_{s2} . Small d_1 and large d_2 enlarge the orange scale compared to the green scale. It follows that the technique sensitivity to ∇n is increased. We choose $d_1 = d_2$ so that there is roughly a factor of two between the orange and green scale bar.

The length L also sets the upper bound on the variations of index of refraction that can be unambiguously determined. Denoting δr the spatial amplitude of the checkerboard deformation, a given value of L is limited to measure deformation such that 1 pix $< \delta r < L$. If $\delta r < 1$ pix, ∇n is too small and no deformation is measured. If $\delta r > L$, the local image deformation is larger than the checkerboard dimension and leads to aliasing and to erroneous plume velocity measurements.

The length L must not be a multiple of a pixel or moiré effects are observed [23, 24].

The low-pass filter characteristic length defines the spatial resolution with which we observe the plume on I_{s2} . In the present article, it has been chosen as $l_c = 2L$, but larger values are possible.

The acquisition frequency f must be chosen according to the velocity of the phenomena studied. The typical time scale can either be derived from physical modeling or practically from the analysis of the spatio-temporal diagrams. In the case of convection, if f is too high, the inclination of the grey lines in the spatio-temporal diagram (figure 3(b)) are almost vertical and this gives a poor resolution of the velocity v. If f is too low, the plumes travel too great a distance between two frames and the grey inclined lines disappear; it thus becomes impossible to measure v.

Finally, the synthetic schlieren technique is quantitative provided that the variations of index of refraction along the *y*-axis are homogeneous. This is usually the case when the variations of index of refraction are confined to a slab of fluid along the *y*-axis. If the variations of index of refraction are inhomogeneous, the velocity of the plume is underestimated.

3. Application to the air convection induced by a heat source

To benchmark the schlieren experiment, we chose to study the air convection induced by a heat source [25]. This is typically the situation of rising smoke from a fire. In this case, the dust permits one to visualize the plumes. However, in the absence of dust, plumes cannot be seen by the naked eye. Here, as seen in the previous section, the schlieren experiments permit one to visualize the plumes and measure their rising speed. Another common example of natural convection are hot mirages [26–28]. In a hot mirage the sun heats the ground and creates a time-averaged temperature gradient $\langle \nabla T \rangle$ between the ground surface at temperature gradient goes along with a refractive index gradient $\langle \nabla n \rangle$: moving away from the ground $\langle n \rangle$ increases. The light rays coming from above the horizon bend toward high *n*, reach the eyes of an observer and give him the impression that the sky is on the ground. Superposed to this time-averaged description, the hotter and lighter air close to the ground dynamically rises up. These rising plumes dynamically blur the scenery. Our digital schlieren setup is calibrated from the dynamical analysis of the rising plumes induced by a surface of known temperature *T*.

3.1. Calibration

First we measured the velocity of plume v of plumes created by the air convection triggered by the presence of a hot aluminum block (radius 6.1 cm, height 3 cm). The aluminum block was heated up in an oven at 200 °C. A small hole in the aluminum block was drilled so that we could monitor its temperature T with a thermocouple thermometer. We then placed the aluminum block in the schlieren experiment and performed image acquisitions as its temperature slowly decreased to T_0 . A similar experiment was conducted using an aluminum block cooled down in a freezer; in this case the plumes moved downward. Figure 4(a) shows the evolution of v as a function of T. We observe that the velocity increases monotonously with T. The plume velocity is characteristic of the block temperature. Figure 4(b) shows that $sign(v)v^2$



Figure 4. Plume velocity *v* with its corresponding standard deviation dv as a function of the heat source temperature *T*. (a) *v* as a function of T. (b) v^2 and its direction as a function of *T*. *circ* corresponds to the calibration experiments and are obtained by measuring the plume velocity induced by a aluminum block with a surface temperature *T*. *T* is measured independently by a thermometer embedded in the block. The line corresponds to the best linear fit, $v^2 = A(T - T_0)$, with $A = 65 \pm 6$ cm²s⁻²K⁻¹ and $T_0 = 25$ °C. Blue and red squares correspond to the plume velocities induced by the surface of a hand and rubbed hands, respectively. In this case, *v* is measured and positioned on the fit line so that one can determine the hand surface temperature using the calibration. We find 35 °C for the unrubbed hand surface and temperatures up to 73 °C for the rubbed hand surface (see figure 4).

increases linearly with temperature. A linear fitting procedure provides a temperature calibration of the surface of the block. This calibration indeed depends on the details of the experimental setup.

3.2. Surface temperature of rubbed hands

Having set up a calibration, we are now in a position to determine any surface temperature between -10 and 150 °C using the synthetic schlieren setup in figure 1. We chose to look at the temperature of hands rubbed against one another. Just after being rubbed, one of the hands is placed in the experimental setup. The hand surface temperature is high enough with respect to T_0 to observe plumes, as displayed in figure 5(a). The spatio-temporal diagram in figure 5(b) shows that the hand temperature decreases from 73 °C to its equilibrium temperature, 35 °C, within ~10 s.

3.3. Discussion

In this subsection, we derive a simple model for the estimation of v and for the scaling $v^2 \sim T$.



Figure 5. Surface temperature of a rubbed hand using synthetic schieren. (a) Synthetic schieren results of a rubbed hand. The green upper one is related to the grip plan and the lower orange one is related to the heat source plan. Both represent 1 cm. (b) Spatio-temporal diagram of image stack corresponding to (a). The plumes' speed decreases with time ($v_1 = 57 v_2 = 43$ and $v_3 = 30 \text{ cm/s}$), which corresponds to decreasing temperatures ($T_1 = 73$, $T_2 = 53$ and $T_3 = 38$ °C).

To model the plume speed v, it is necessary to estimate or measure the air temperature within the plume. The plume temperature is indeed responsible for the plume's lower density and therefore its rise. To do so we used an infra-red camera (Flir) which acquired images where the intensity codes for the temperature. Figure 6 shows the plume temperature measured by an infra-red camera for (a) a flame and (b) the aluminum block experiment described previously (note the difference in temperature scale between both images). The plume temperature is much lower than the source temperature. For a flame, the plume temperature is $\Delta T_{air} \sim 30$ °C above room temperature. For an aluminum block at



Figure 6. Images normalized by the background temperature obtained from an infra-red camera. The normalization is obtained by subtracting the image from the hot source with the image at room temperature. (a) Flame at T = 900 °C. (b) Aluminum block at T = 66 °C. The block intensity is saturated and the temperature scale does not apply on the block.

T = 66 °C, the plume temperature is barely measurable with the infra-red camera, $\Delta T_{air} \sim 0.15$ °C. In this context, the affordable synthetic schlieren setup proposed here proves to be more sensitive and appropriate to visualize hot air plumes than expensive infra-red cameras.

We have now all the ingredients necessary to estimate with a simple model the plume velocity. Based on the schlieren images I_{s2} , we assume that the plume is shaped like a streamed body of radius r = 1 cm and height h = 10 cm (volume, $V_{sb} \sim \frac{4}{6}\pi r^3 + \frac{1}{3}\pi r^2 h$). This is the first strong hypothesis: the plume is indeed not a solid body as the hot air circulates within the plume. The plume is subject to the buoyancy force Π_a and the drag force f_v . Π_a is due to the mismatch of density between the plume and surrounding air and it drives the plume to rise against the gravity field g. f_v is due to the air resistance and is opposed to the rising motion of the plume. The Reynolds number having a value of $Re = vh/v \sim 3000$ (air dynamic viscosity $v = 15 \ \mu m^2/s$), the drag coefficient for a stream body is C = 0.04. This value is effective for a solid–fluid interface and therefore constitutes the second strong hypothesis: the plume interface is indeed fluid–fluid. In the stationary regime, where the plume velocity is constant, the two forces compensate each other and we obtain the following expression for v:

$$\begin{cases} \Pi_a = V_{sb} \Delta \rho g \\ f_v = \frac{1}{2} C \rho \pi r^2 v^2 \end{cases}$$
$$\Rightarrow v^2 \sim \frac{2V_{sb}g}{C \pi r^2} \frac{\Delta \rho}{\rho}. \tag{1}$$

Using the ideal gas law for the air and differentiating it at constant pressure *P* and particle number *N*, we obtain a relation between ΔT_{air} and $\Delta \rho$:

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$$P = \frac{N}{V} R T_{air} \Rightarrow \frac{\Delta \rho}{\rho} = -\frac{\Delta T_{air}}{T_0}.$$
(2)

Assuming that the pressure remains constant constitutes the third strong hypothesis in this model. Using equations (1) and (2), we obtain an expression for the plume velocity as function of ΔT_{air} :

$$v \sim \sqrt{\frac{2V_{sb}g}{C\pi r^2}} \left| \frac{\Delta T_{air}}{T_0} \right|.$$
 (3)

For the aluminum block at T = 66 °C, the infra-red camera yields a plume temperature difference $\Delta T_{air} = 0.15$ °C with respect to the room temperature $T_0 = 25$ °C. Using equation (3), we find $v \sim 10$ cm/s. This gives the right order of magnitude. The model however underestimates the experimental value of 50 cm/s.

This simple model yields that $v^2 \sim \Delta T_{air}$. Provided that the temperature of the plume is proportional to the surface temperature of the heat source, the model explains the scaling observed empirically in figure 4(b).

The typical velocity of plumes has also been addressed in *Physical Fluid Dynamics* by D. J. Tritton [29]. The scaling of plume velocity in free convection is also found to be proportional to the square root of the temperature difference between the wall and the ambient air. Its derivation is obtained by balancing the kinetic energy $1/2\rho v^2$ with the gravitational potential energy $g\alpha\Delta Tz$, α being the thermal expansion coefficient of air.

4. Conclusion

There are many optical techniques that use the deflection or phase changes in light rays to map variations in the refractive index n. The classical shadowgraph method [1-3] is sensitive to the curvature in the refractive index field which focuses or defocuses nominally parallel light rays. This technique is essentially qualitative because it is difficult to extract quantitative information about the density fluctuations due to boundary conditions at the edges of the field of view. Interferometers such as the Mach–Zehnder interferometer [4] provide direct measurements of variations in the speed of light through the phase change experienced by monochromatic light. However, their application is often limited by cost and the precision required in set-up. Schlieren methods [5, 6] are sensitive to refractive index variations in the plane normal to light rays passing through the medium. While schlieren has been used for many years to visualize flows containing variations in refractive index, its application may be limited by the price of the optical components; indeed, the visualization of large domains requires the use of expensive parabolic mirrors. It also may be difficult to extract quantitative information: for instance, in its simplest form, the intensity of a 'knife edge' schlieren image is polluted by gradients of the refractive index perturbations in the direction of the knife edge.

Synthetic schlieren is an alternative to those techniques. It is simple to setup and cost effective now that fast cameras are cheap. It is sensitive, fast, local and yields qualitative information about the 2D flow without the use of dyes or tracers. In this article, we first have described the experimental setup, shown how to process the data and discussed the experiment parameters. In a second part, we have successfully tested synthetic schlieren to study the convection induced by a heat source. We have visualized the plumes produced by a heat source and measured their velocity v. We came up with an empirical scaling that relates unambiguously v to the temperature of the heat source T. Building on this calibration, we have detected the heat released by rubbed hands. Finally, using a simple model we have estimated v and justified the empirical scaling.

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