

Universality in assembly models

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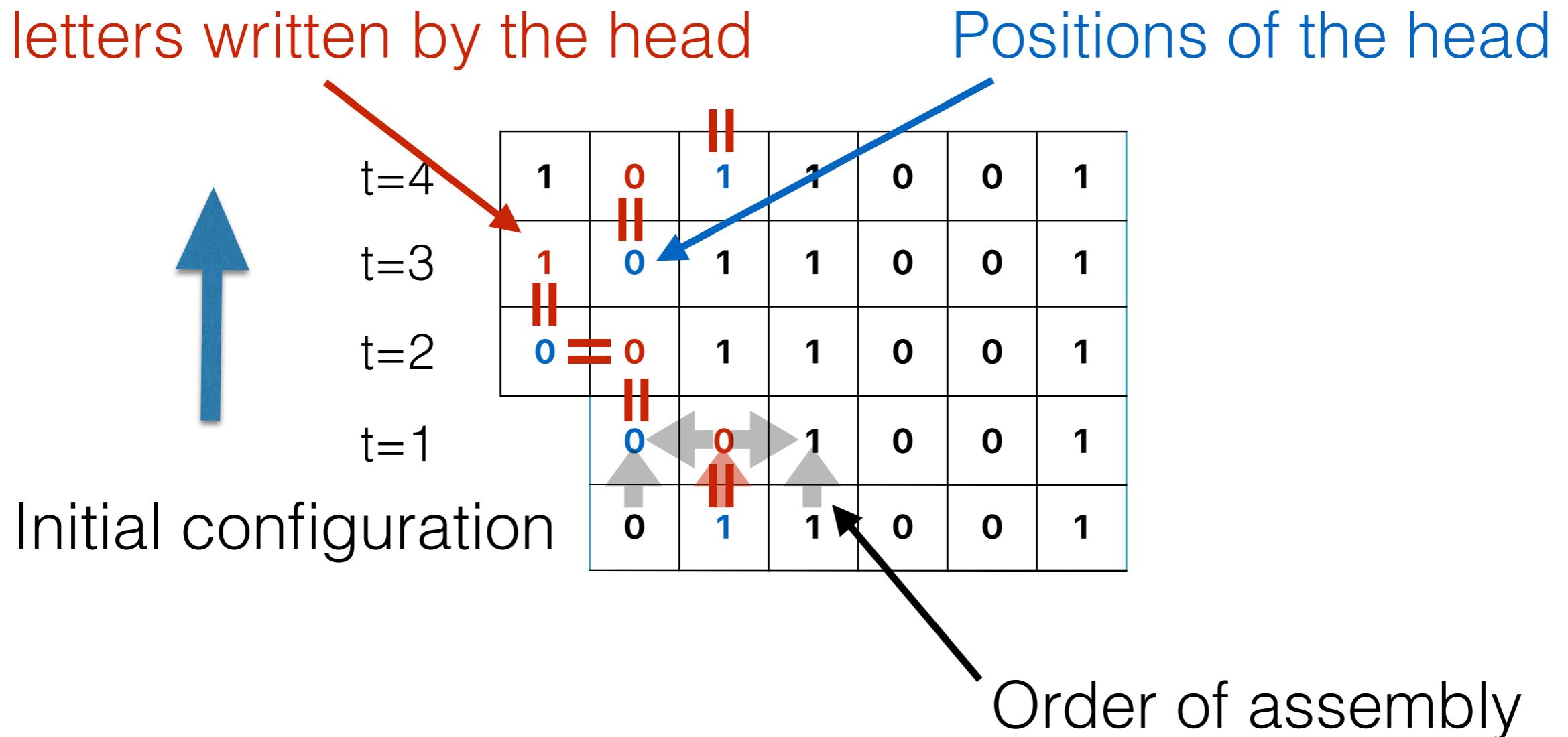
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Universality in algorithmic self-assembly

- Can we decide if an assembly terminates?
- Can we design a tile system for a given shape?
- Do I need more than one tilesset?
- Do I need more than one tile?
- Do I need more than one molecule?

Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D



Algorithmic self-assembly simulates any Turing machine at T°2 in 2D

Position and state of the head

t=4	0	0	1,Halt	1	★
t=3	0	0	0,q'''	1	★
t=2	0	0	0	0,q''	★
t=1	0	0	1,q'	★	
t=0	0	1,q	1	★	

Current tape right end

Transitions:

$$(0,q''') \rightarrow (1,Halt, \bullet)$$

$$(0,q'') \rightarrow (1,q''', \leftarrow)$$

$$(1,q') \rightarrow (0,q'', \rightarrow)$$

$$(1,q) \rightarrow (0,q', \rightarrow)$$

Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

$t+1$	a_{-L}	\dots	a_{-2}	a_{-1}, q'	b	a_1	\dots	a_R	0	\star
t	a_{-L}	\dots	a_{-2}	a_{-1}	a, q	a_1	\dots	a_R	\star	

Tiles for $(a, q) \mapsto (b, q', \leftarrow)$

Algorithmic self-assembly simulates any Turing machine at T°2 in 2D

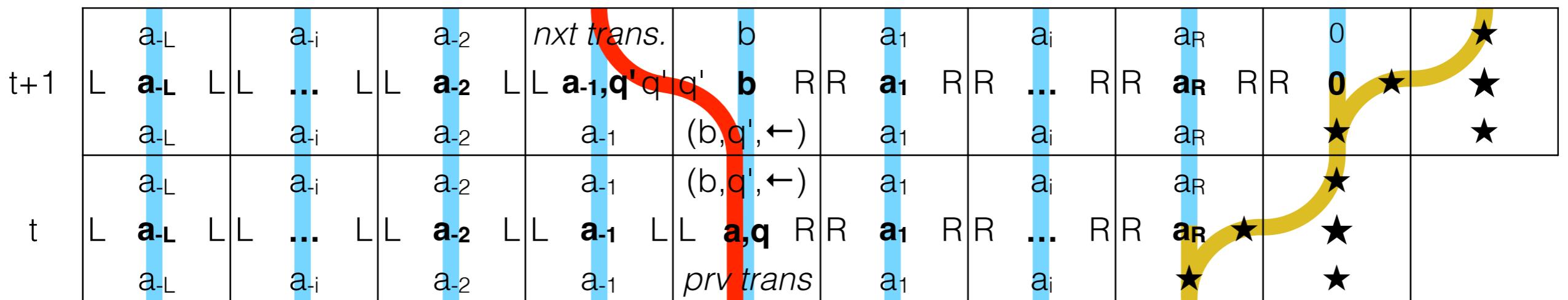
- 1) Organize the information flow passing through the glues on the sides

	a _{-L}	a _{-i}	a ₋₂	nxt trans.	b	a ₁	a _i	a _R	0	★
t+1	L a_{-L} L L ... L L a₋₂ L L a_{-1,q'q'} q' b R R a₁ R R ... R R a_R R R 0 ★ ★	a _{-L}	a _{-i}	a ₋₂	a ₋₁	(b,q',←)	a ₁	a _i	a _R	★
t	L a_{-L} L L ... L L a₋₂ L L a₋₁ L L a,q R R a₁ R R ... R R a_R ★ ★	a _{-L}	a _{-i}	a ₋₂	a ₋₁	(b,q',←)	a ₁	a _i	a _R	★
	prv trans									

Tiles for $(a,q) \rightarrow (b,q',\leftarrow)$

Algorithmic self-assembly simulates any Turing machine at T°2 in 2D

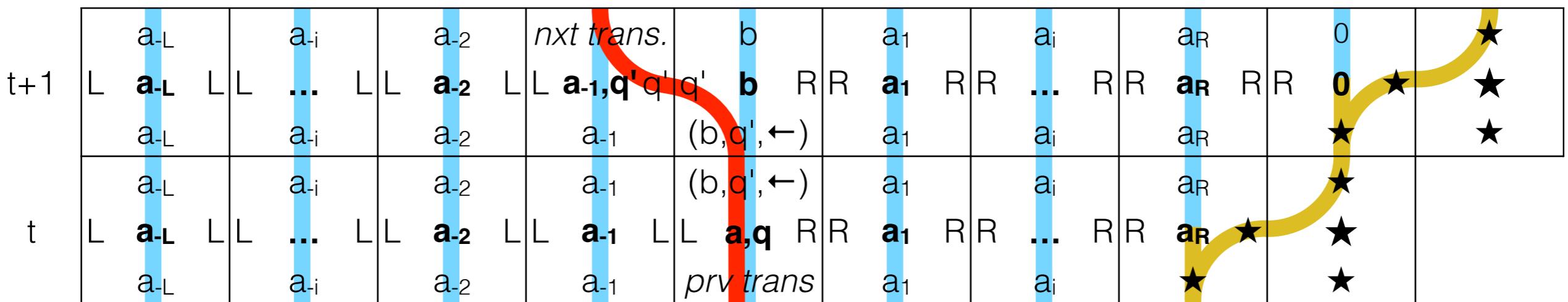
- 1) Organize the information flow passing through the glues on the sides



Tiles for $(a, q) \rightarrow (b, q', \leftarrow)$

Algorithmic self-assembly simulates any Turing machine at T°2 in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles

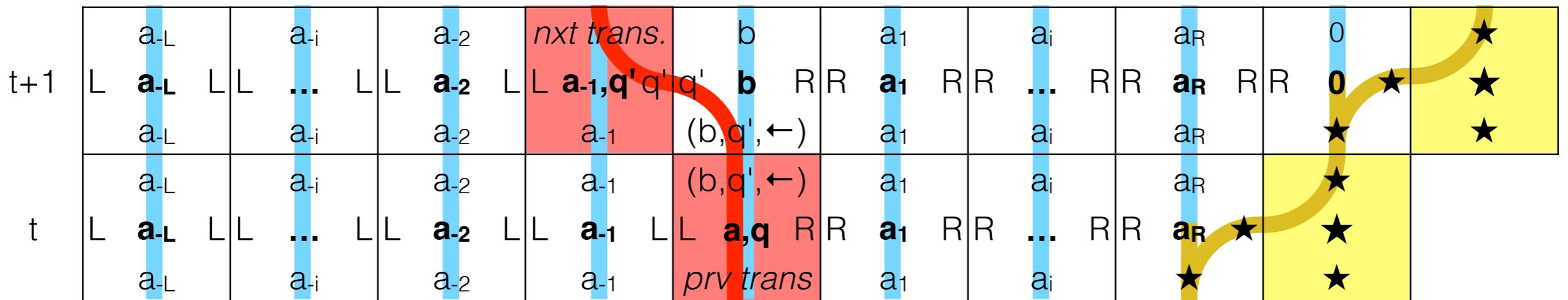


Tiles for $(a, q) \rightarrow (b, q', \leftarrow)$

Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles

The skeleton

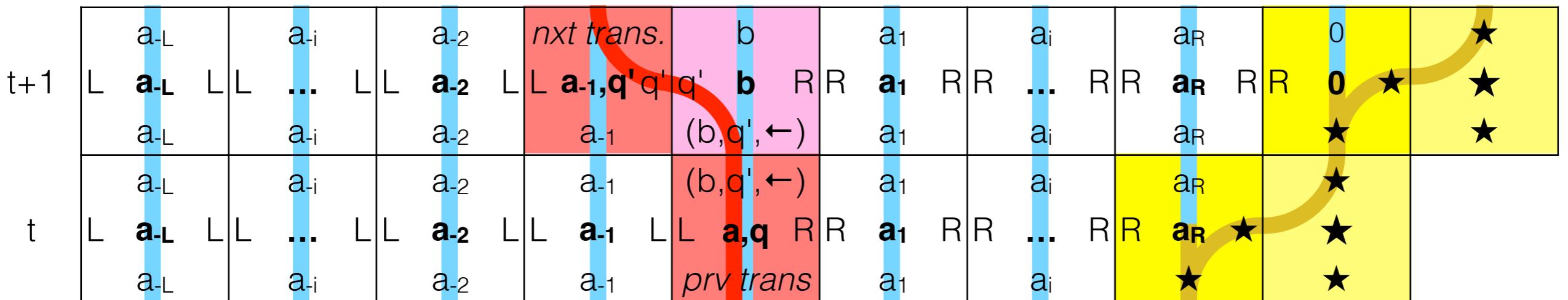


Tiles for $(a,q) \rightarrow (b,q',\leftarrow)$

Algorithmic self-assembly simulates any Turing machine at T°2 in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles

The carriers

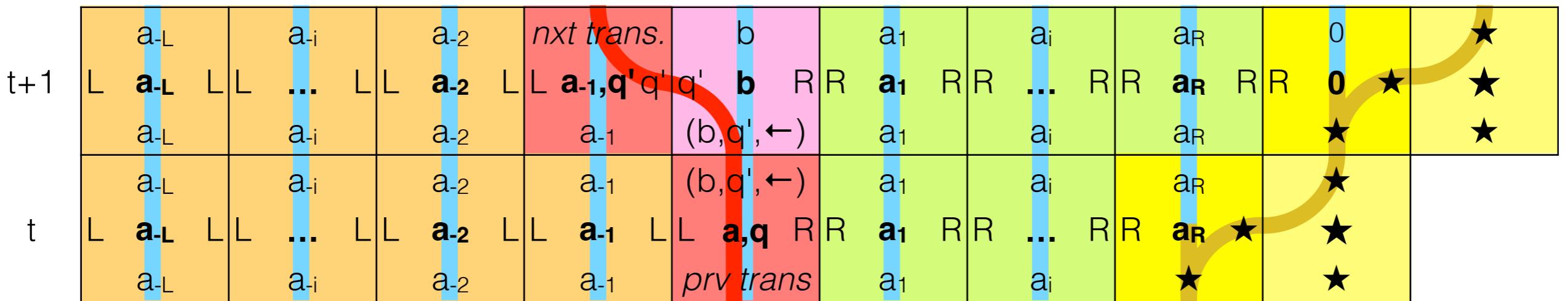


Tiles for $(a,q) \rightarrow (b,q',\leftarrow)$

Algorithmic self-assembly simulates any Turing machine at T°2 in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles

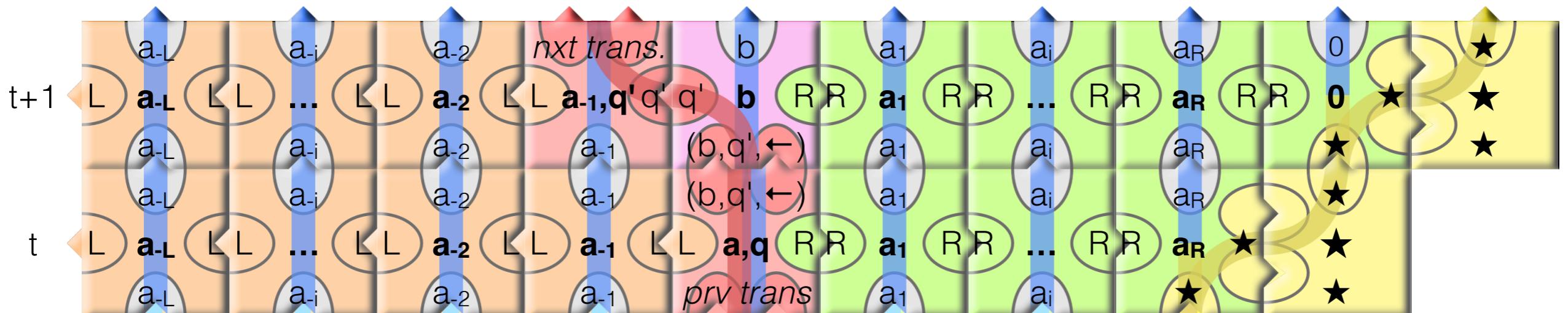
The filling tiles



Tiles for $(a, q) \rightarrow (b, q', \leftarrow)$

Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles
- 3) Set the order, glue strength & colors to match the flow

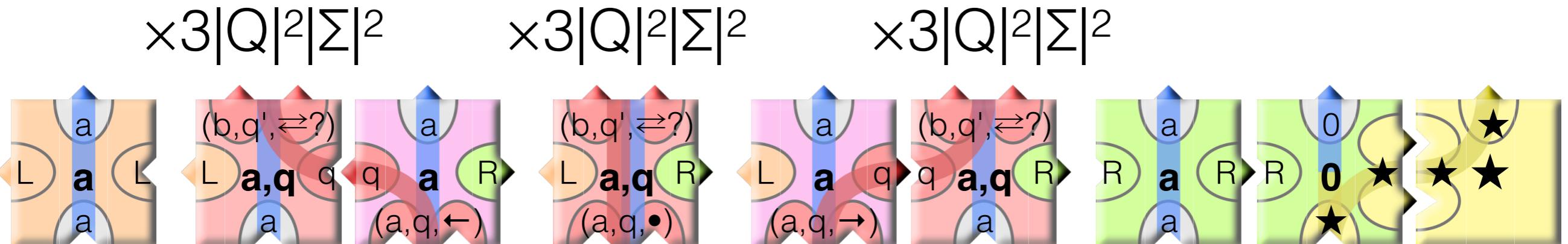


Tiles for $(a, q) \rightarrow (b, q', \leftarrow)$

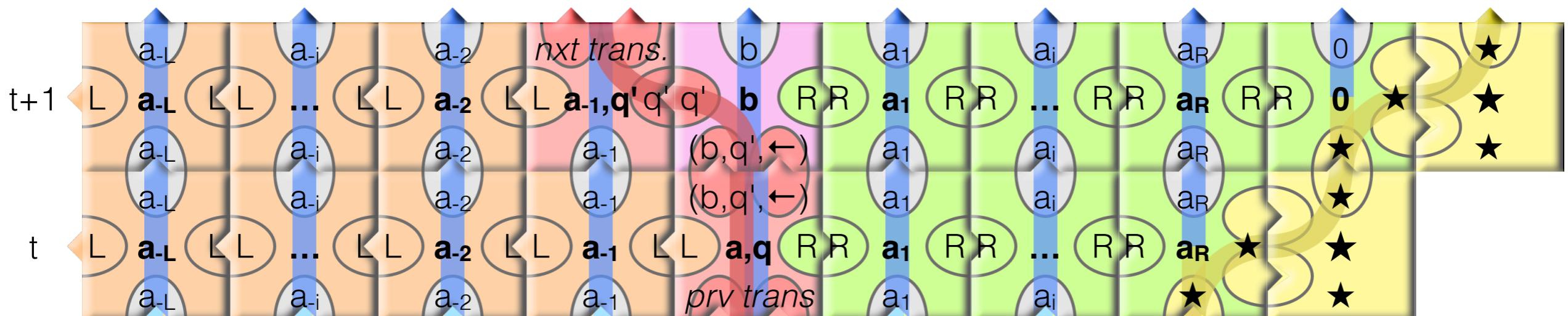
The tileset

with size $O(|Q|^2|\Sigma|^2)$

The tiles for each transition $(a,q) \rightarrow (b,q',\xrightarrow{?})$



$\times |\Sigma|$ $\times 3|Q||\Sigma|$ $\times 3|Q||\Sigma|$ $\times |\Sigma|$ $\times 1$ $\times 1$



Encoding the input as a seed

- **Solution 1: hardcoded**
 - Uses **n** tiles for n bits

A	0	B	B	0	C	C	1	C	C	1	D	D	0	E	E	1	F	F	1	G	G	1	H	H	0	I	I	0	J	J	1	K	K	1	★
---	----------	---	---	----------	---	---	----------	---	---	----------	---	---	----------	---	---	----------	---	---	----------	---	---	----------	---	---	----------	---	---	----------	---	---	----------	---	---	----------	---

- Each tile requires **4 log n bits** to encode its glues, thus this encoding uses **4n log n bits** in total
- Can we do better, with less tiles ?

Kolmogorov complexity

- Given a universal Turing machine U :

$$K_U(x) = \min \{ |p| : U(p, \varepsilon) = x \}$$

is the size of the smallest program in U that outputs x

- Fact.** $\forall U, \exists A$ s.t. $\forall x, K_U(x) \leq |x| + A$

Proof. A is the size of the program "print" in U .

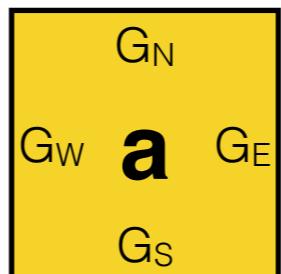
- Theorem.** $K_U(x)$ is independent of U , indeed:

$$\forall U, U' \exists A, B \text{ s.t. } \forall x, K_{U'}(x) - A \leq K_U(x) \leq K_{U'}(x) + B$$

Proof. A and B are the sizes of the programs that execute U and U' respectively in U' and U .

Lower bounding the required number of tiles to encode the seed

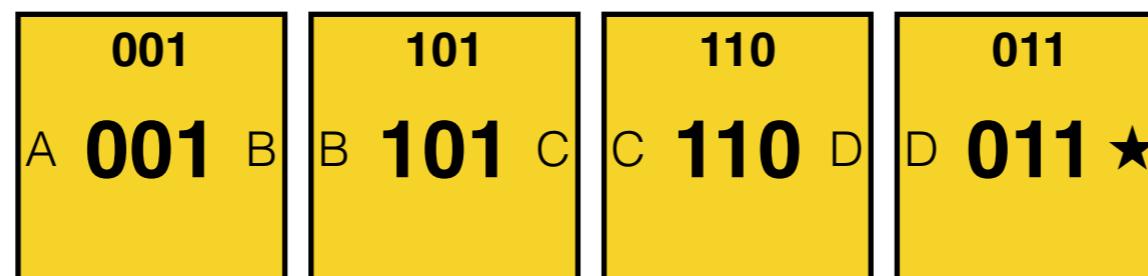
- The Kolmogorov complexity $\mathbf{K}(\mathbf{x})$ is the size of the smallest program that outputs \mathbf{x}
- Bit size of the encoding with T tiles is $\leq 4 T \log_2 T$



- A tileset that self-assembles x is a program that outputs x ,
Thus: $4T \log T \geq K(x)$, i.e. $T \geq K(x) / 4 \log K(x)$

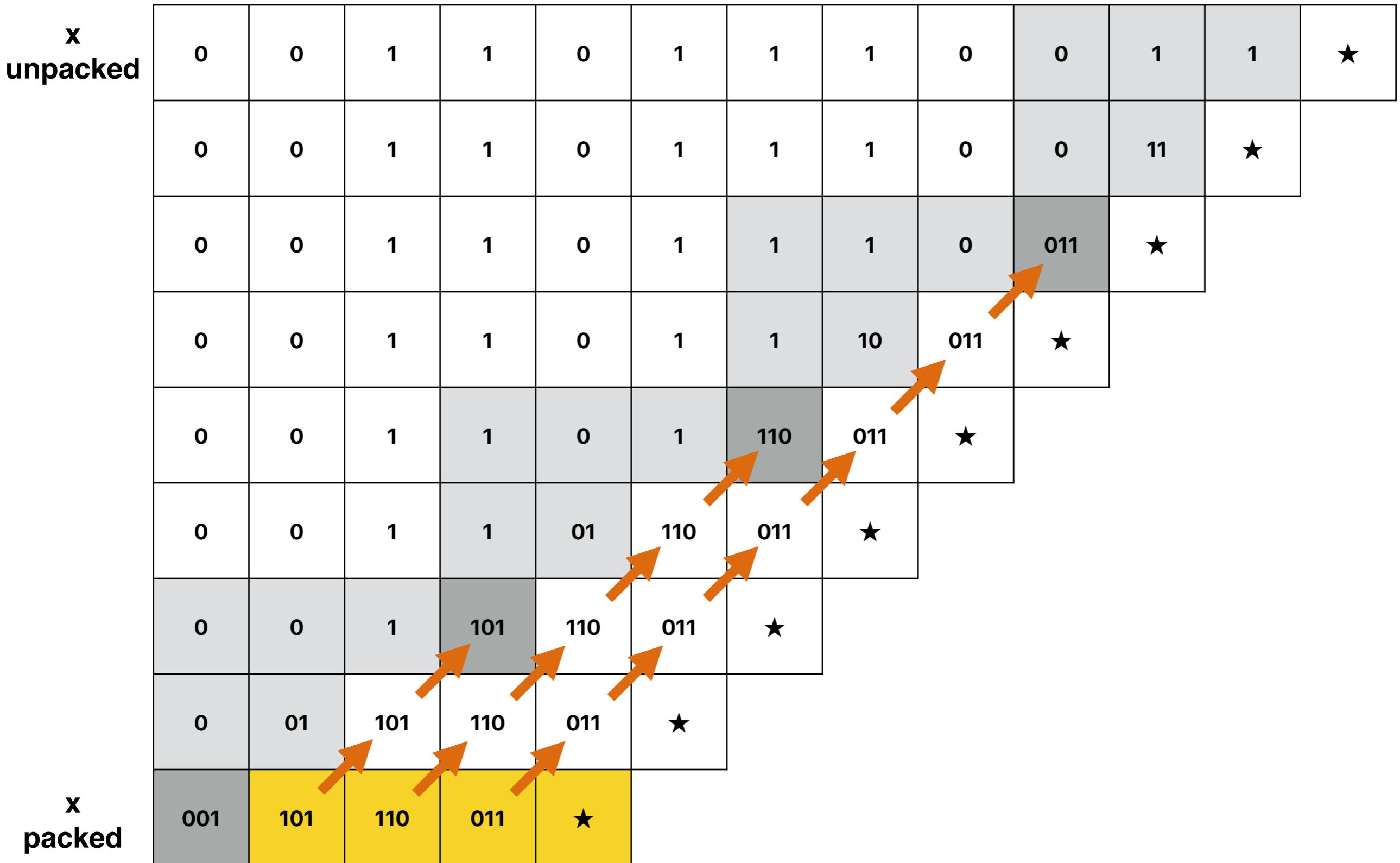
Unpacking a binary string

- Cut string **x** in n / b chunks of **b** bits and uncompress it
- Example: **x = 001 101 110 011** and **b = 3**

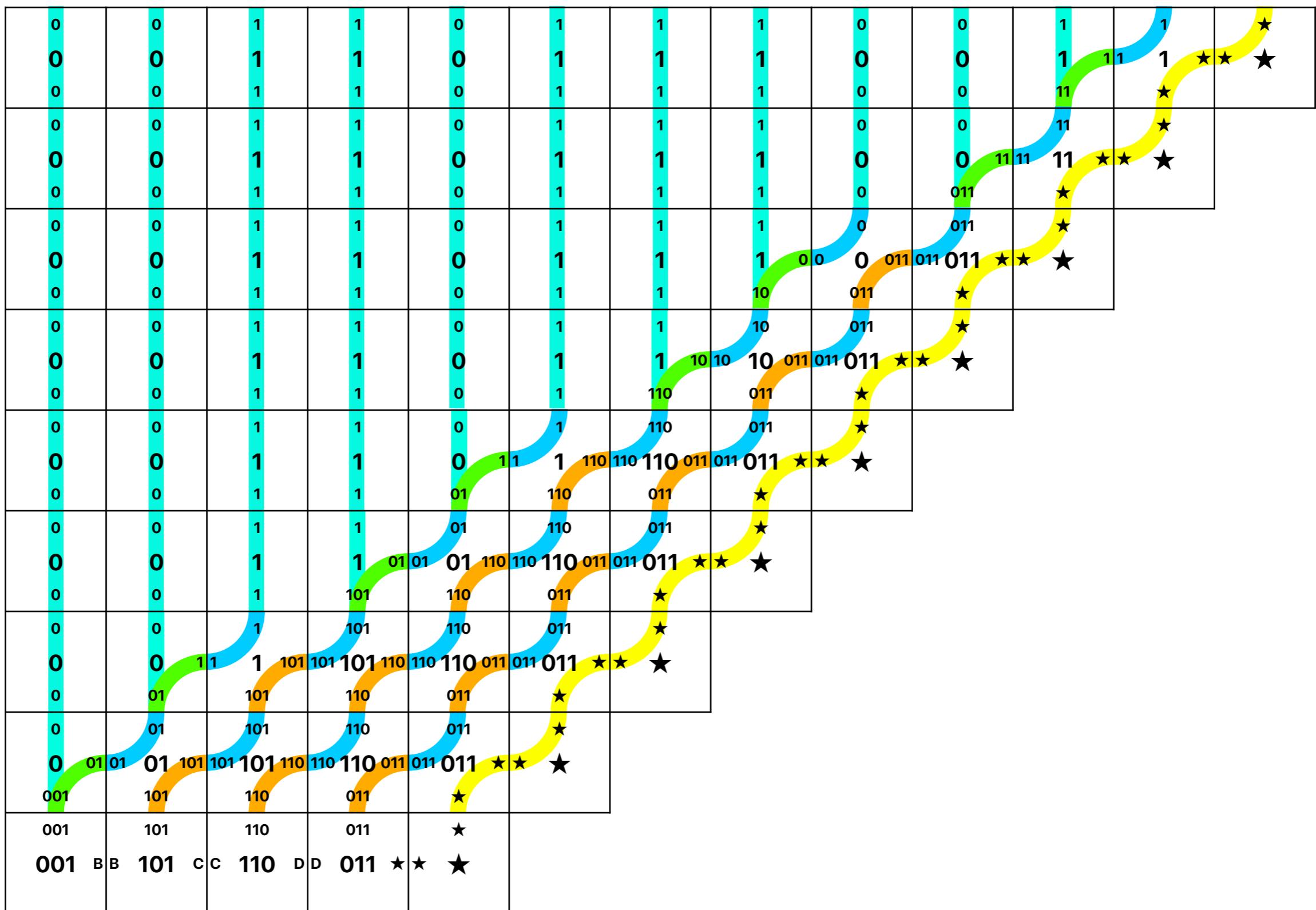


n / b tiles

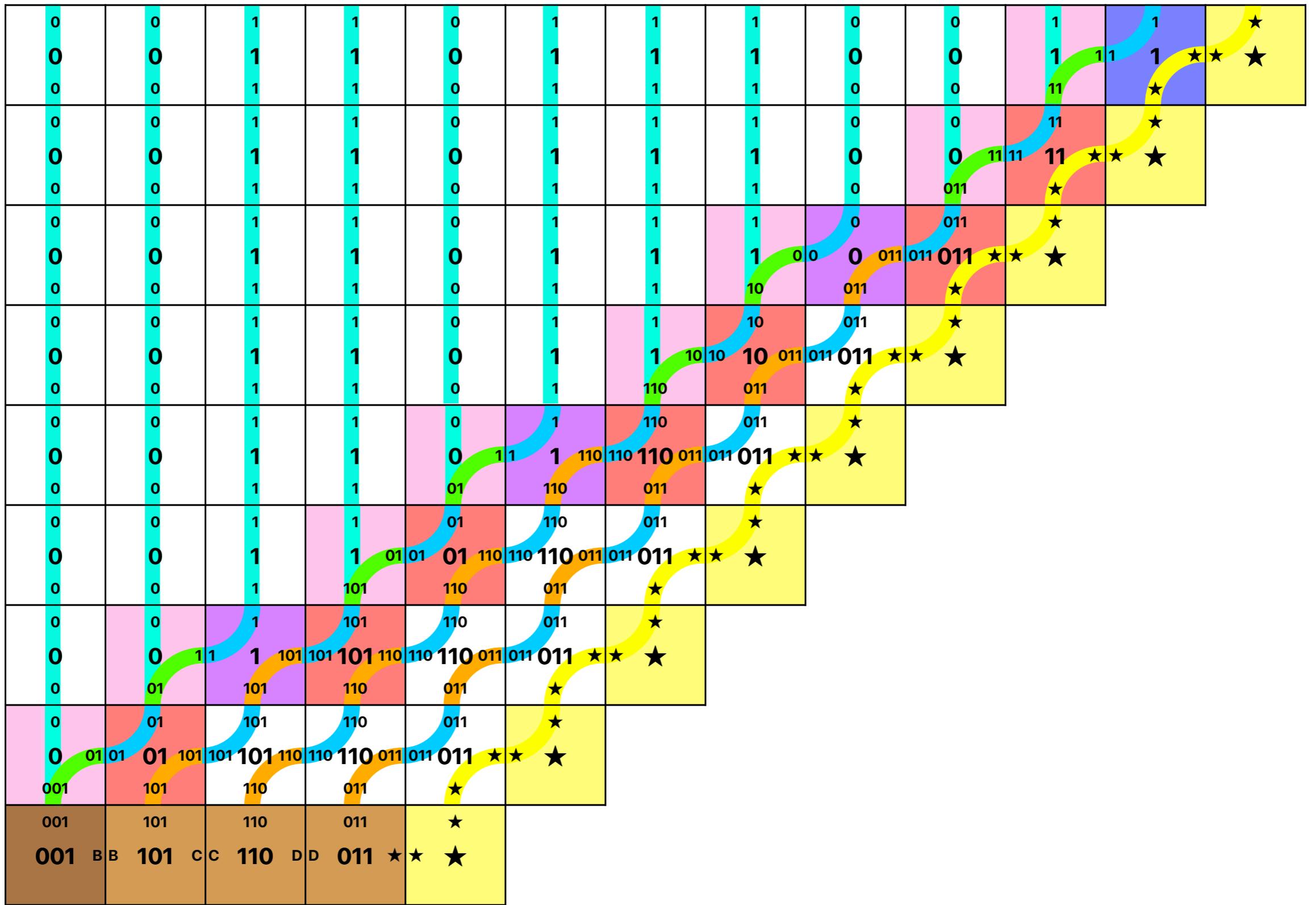
Unpacking a binary string



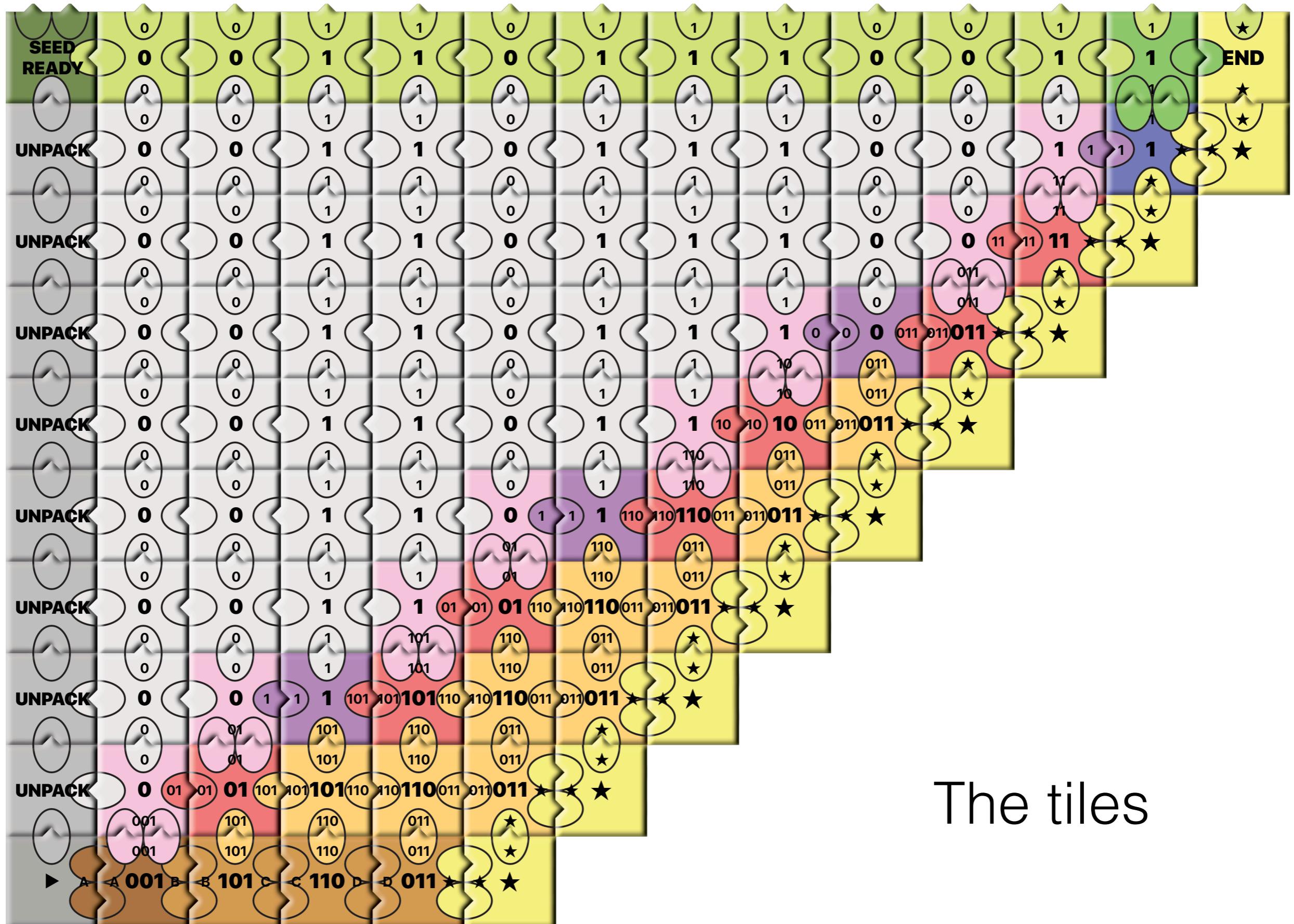
Determine the flow of information



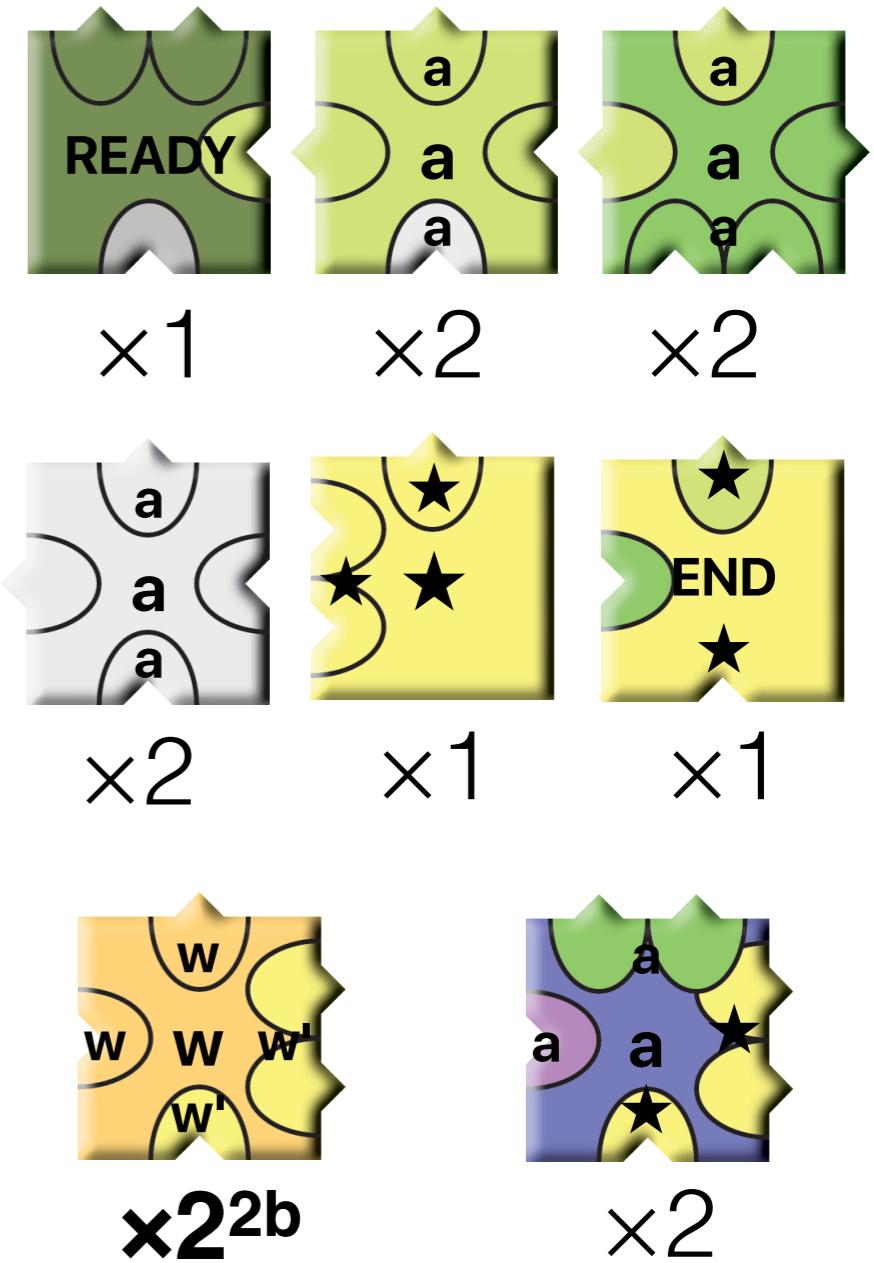
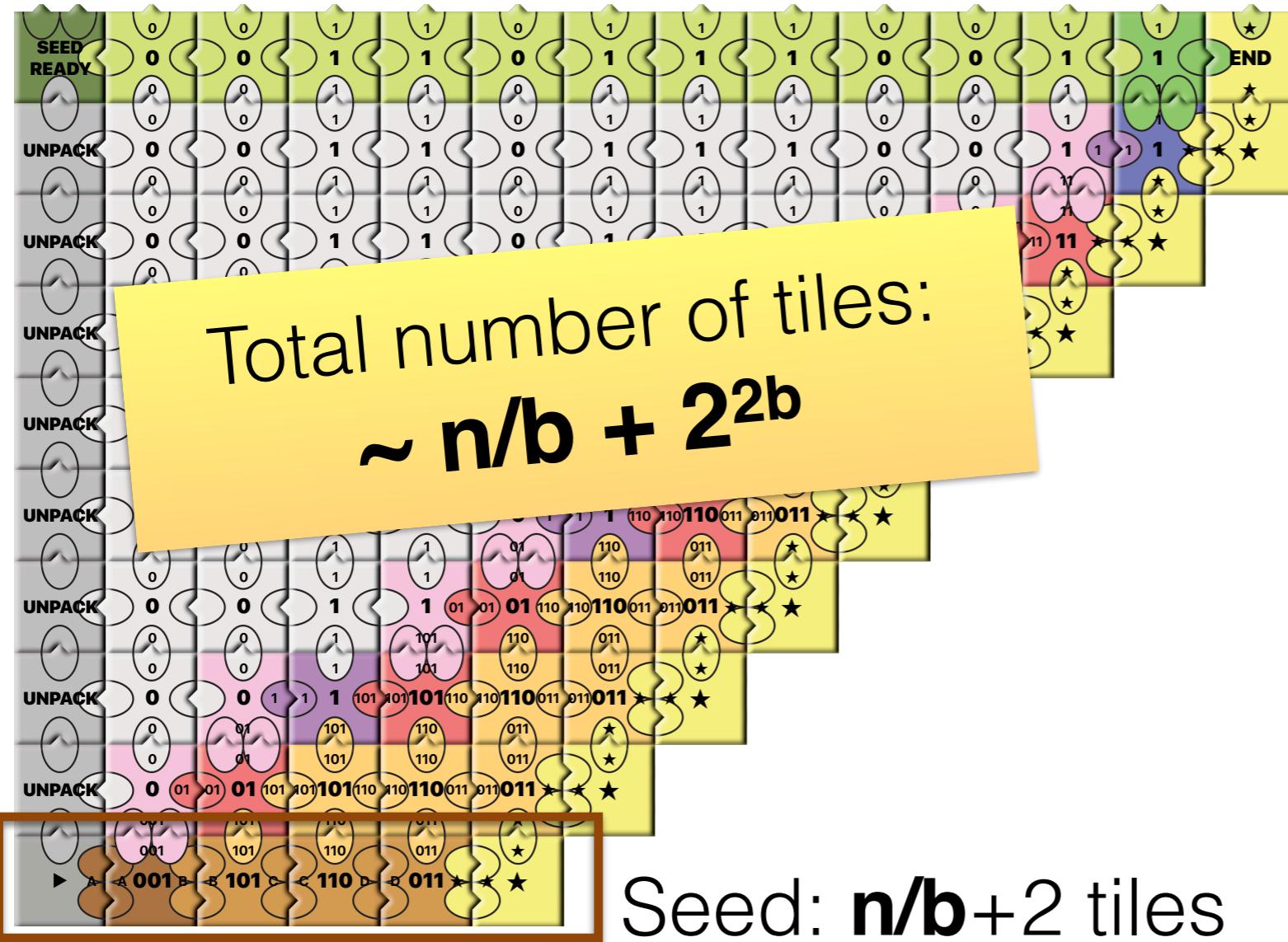
Determine the various tile types



Add tiles at the boundary for continuation



The tiles



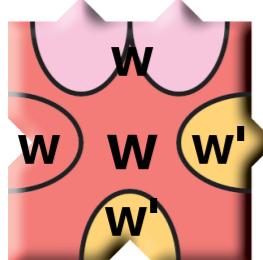
$$2 \leq |w| \leq b$$

$$|w'| = b$$

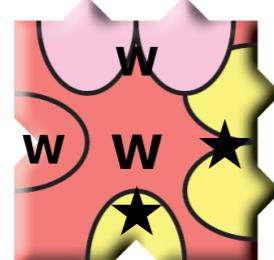
$$2 \leq |w| \leq b$$

$$|w|=b$$

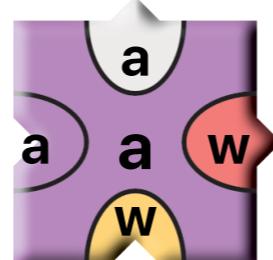
$$2 \leq |w| < b$$



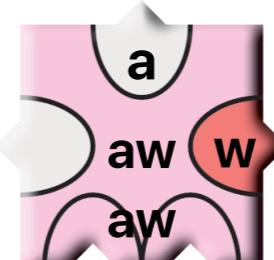
$$\times 2^{2b}$$



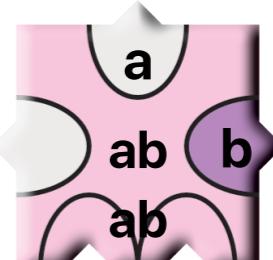
$$\times 2^b$$



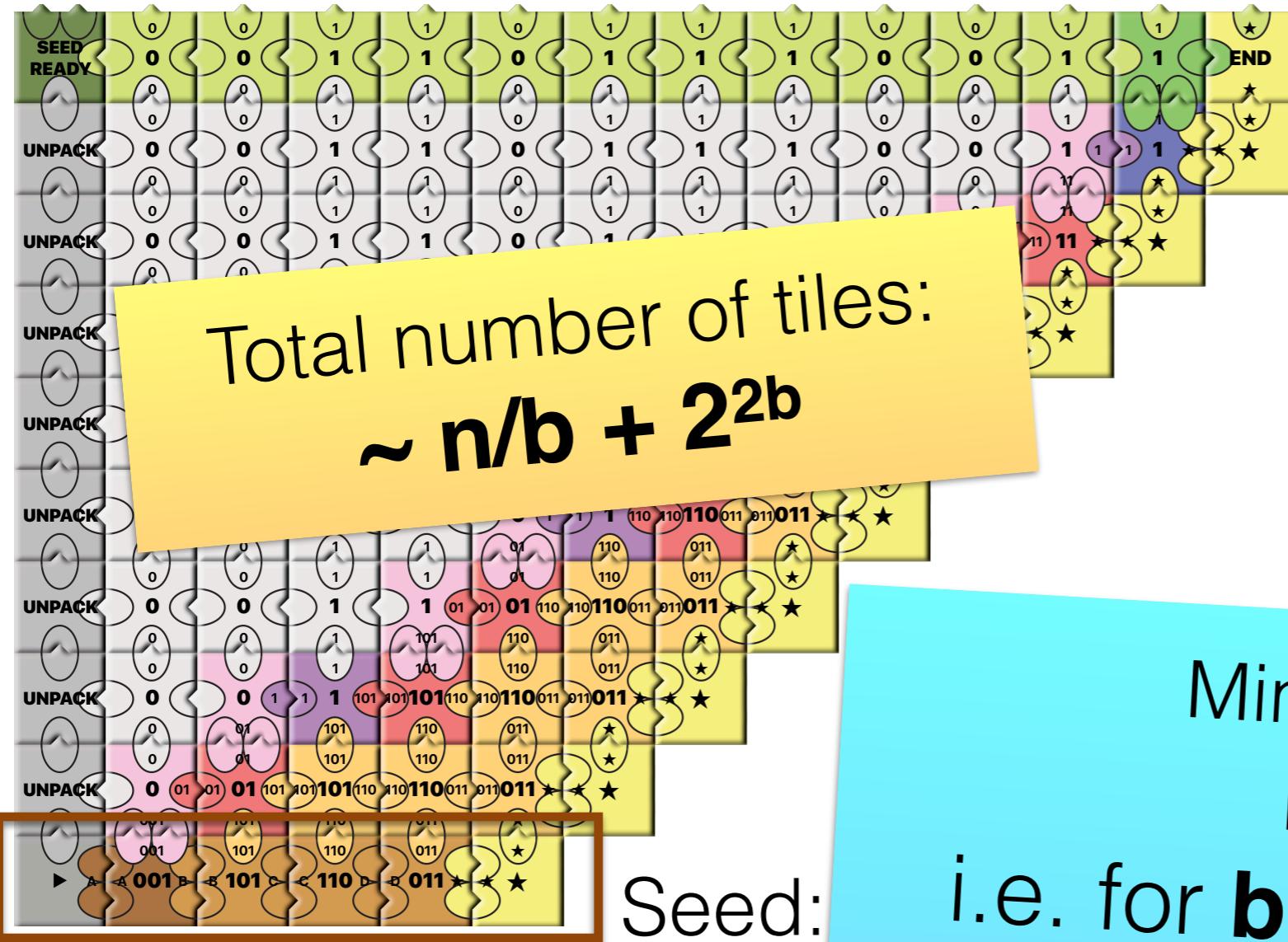
$$\times 2^{b+1}$$



$$\times 2^b$$

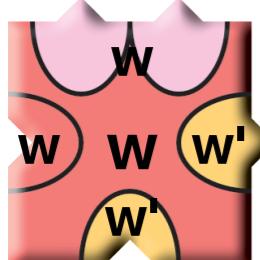


$$\times 4$$



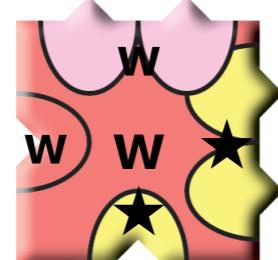
$$2 \leq |w| \leq b$$

$$|w'| = b$$



$\times 2^{2b}$

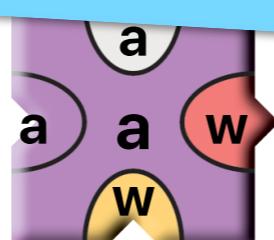
$$2 \leq |w| \leq b$$



$\times 2^b$

Minimized when
 $n/b = 2^{2b}$
i.e. for $b = \log(n/\log n)/2$

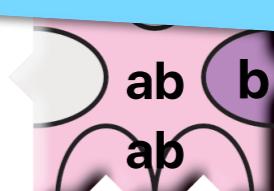
The total number of tiles is:
 $\sim n/\log n$ (optimal !)



$\times 2^{b+1}$



$\times 2^b$

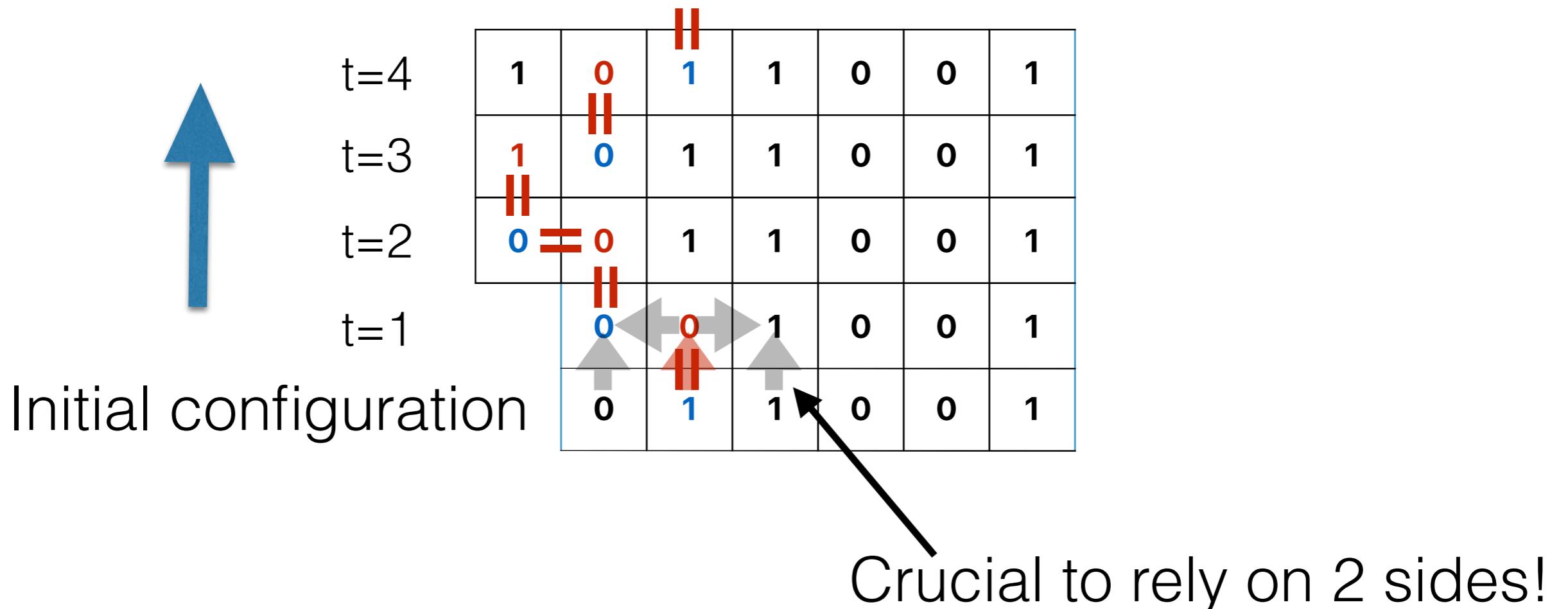


$\times 4$

What about $T^{\circ}=1$?

Does algorithmic self-assembly simulate Turing machine at $T^{\circ}1$ in 2D?

- How to read and propagate the position of the head?



Does algorithmic self-assembly simulate Turing machine at $T^{\circ}1$ in 2D?

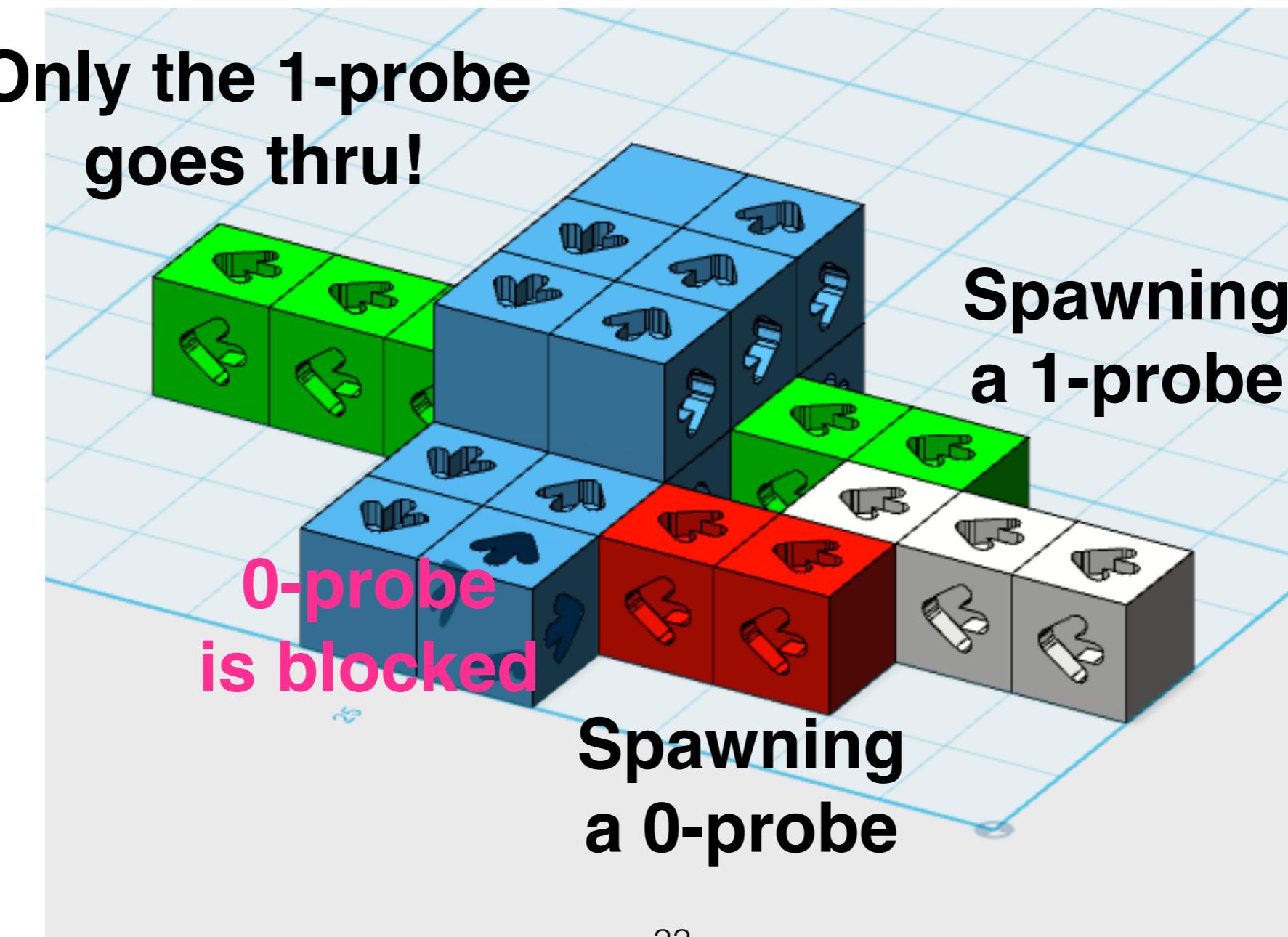
- **Theorem.** [Meunier, Regnault, 2015]
Any deterministic $T^{\circ}1$ tile set can be pumped outside a fixed radius in 2D
- **Corollary.** No $T^{\circ}1$ tilesystem is Turing complete in 2D

Algorithmic self-assembly simulates any Turing machine at T°1 in 3D

- **Theorem.** [Cook, Fu, Schweller, 2011]
There is a T°1 tile set that simulates any Turing machine with 2-layers in 3D.
- *Key beautiful idea:* Blocking probe crystal

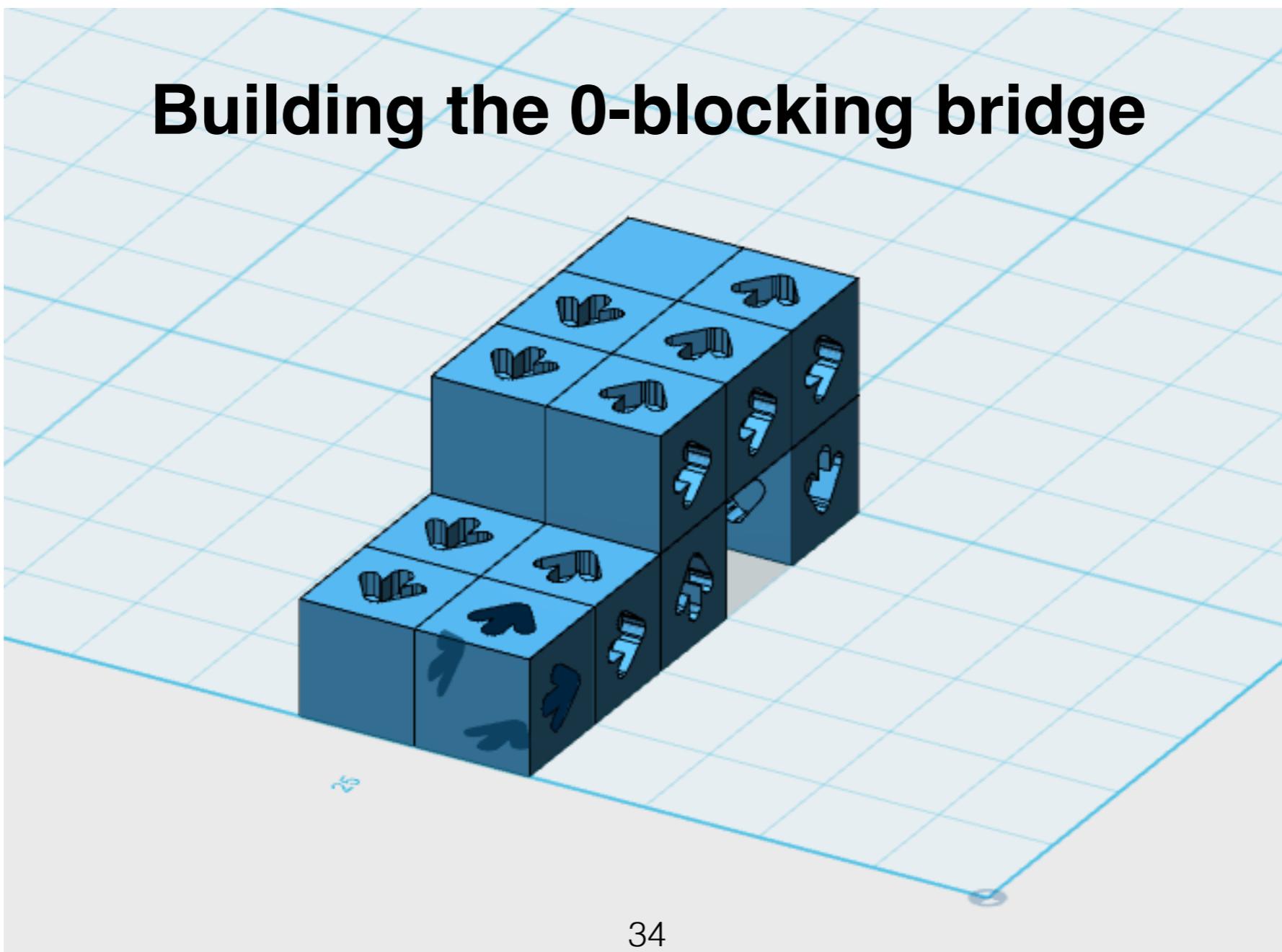
Algorithmic self-assembly simulates any Turing machine at $T^{\circ}1$ in 3D

- Key beautiful idea: Blocking probe crystal



Algorithmic self-assembly simulates any Turing machine at $T^{\circ}1$ in 3D

- Key beautiful idea: Blocking probe crystal



Algorithmic self-assembly simulates any Turing machine at T°1 in 3D

- *Key beautiful idea:* Blocking probe crystal

We can thus read and write 0 and 1 on the
“next tape” !

Crystals are Turing complete !!!

An experimental realization of a universal computer

Conclusion

- A lot of new models
- A new kind of geometric algorithmic
- A lot of implication in biology and bio-engineering
- Lots of extensions: mixed dynamics, errors,...
More on fixing errors at the last lecture