

# Universality in assembly models

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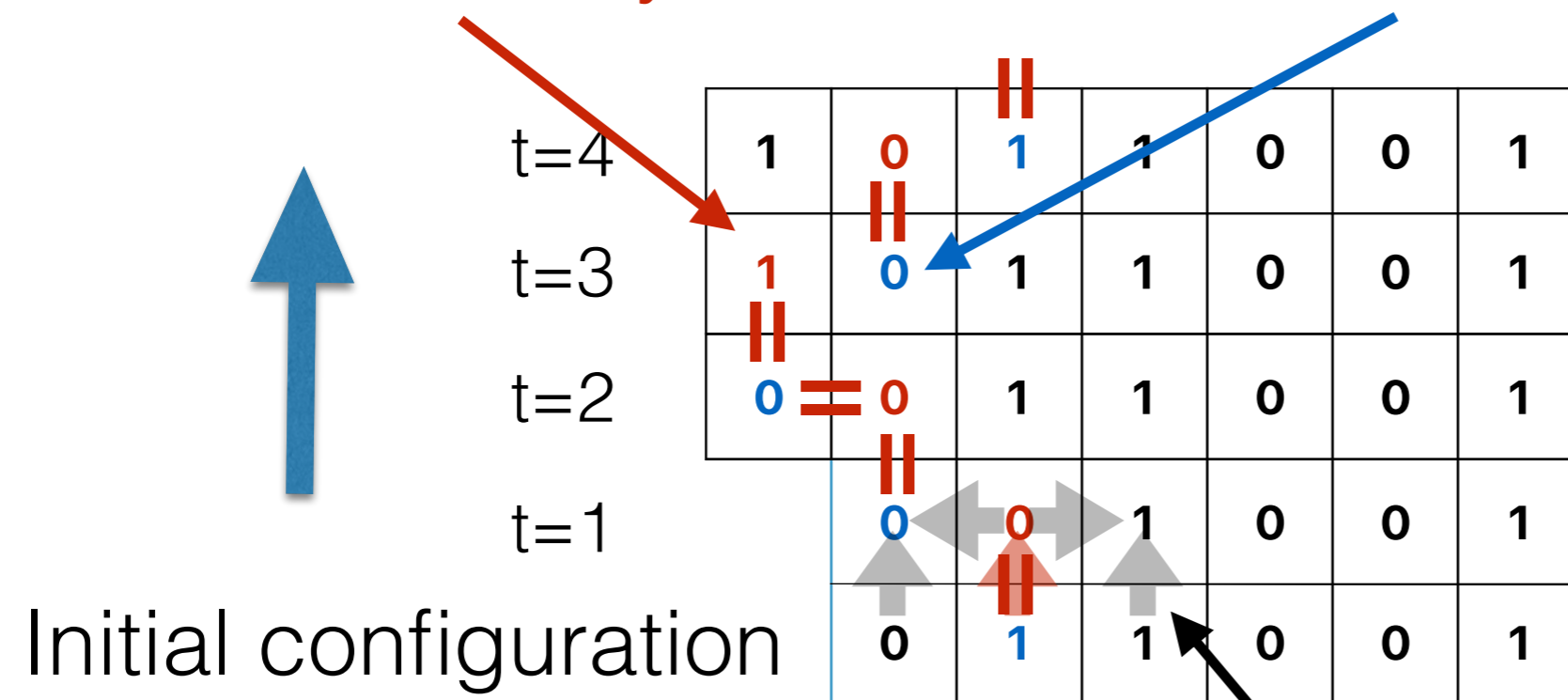
# Universality in algorithmic self-assembly

- Can we decide if an assembly terminates?
- Can we design a tile system for a given shape?
- Do I need more than one tileset?
- Do I need more than one tile?
- Do I need more than one molecule?

# Algorithmic self-assembly simulates any Turing machine at $T^2$ in 2D

letters written by the head

Positions of the head



Initial configuration

Order of assembly

# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

Position and state of the head

Current tape right end

t=4	0	0	1,Halt	1	★
t=3	0	0	0,q'''	1	★
t=2	0	0	0	0,q''	★
t=1	0	0	1,q'	★	
t=0	0	1,q	1	★	

Transitions:

$(0,q''') \mapsto (1,\text{Halt},\bullet)$

$(0,q'') \mapsto (1,q''',\leftarrow)$

$(1,q') \mapsto (0,q'',\rightarrow)$

$(1,q) \mapsto (0,q',\rightarrow)$

# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

t+1	<b>a-L</b>	...	<b>a-2</b>	<b>a-1,q'</b>	<b>b</b>	<b>a<sub>1</sub></b>	...	<b>a<sub>R</sub></b>	<b>0</b>	<b>★</b>
t	<b>a-L</b>	...	<b>a-2</b>	<b>a-1</b>	<b>a,q</b>	<b>a<sub>1</sub></b>	...	<b>a<sub>R</sub></b>	<b>★</b>	

Tiles for  $(a,q) \mapsto (b,q',\leftarrow)$

# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

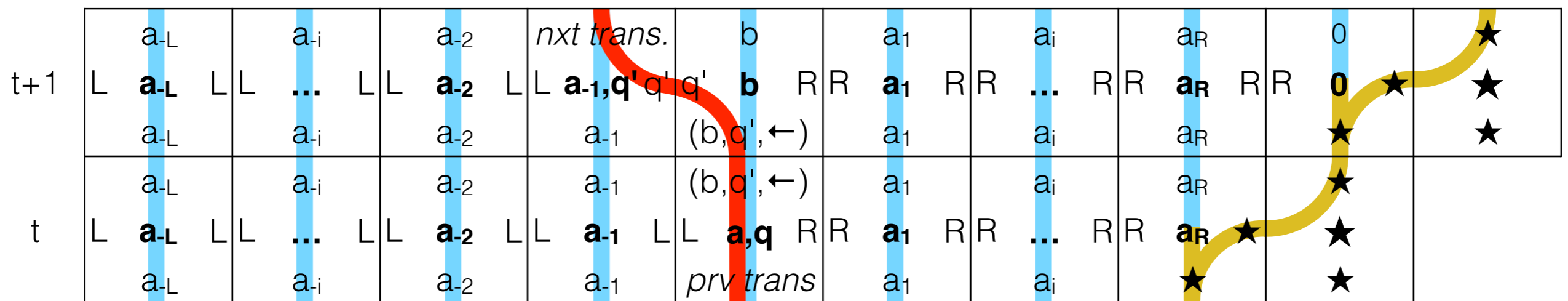
- 1) Organize the information flow passing through the glues on the sides

	$a_{-L}$	$a_{-i}$	$a_{-2}$	<i>nxt trans.</i>	$b$	$a_1$	$a_i$	$a_R$	0	★
t+1	L <b>a<sub>-L</sub></b> L	L <b>...</b> L	L <b>a<sub>-2</sub></b> L	L <b>a<sub>-1</sub>,q'</b> q'	q' <b>b</b> R	R <b>a<sub>1</sub></b> R	R <b>...</b> R	R <b>a<sub>R</sub></b> R	R <b>0</b> ★	★
	$a_{-L}$	$a_{-i}$	$a_{-2}$	$a_{-1}$	$(b, q', \leftarrow)$	$a_1$	$a_i$	$a_R$	★	★
t	$a_{-L}$	$a_{-i}$	$a_{-2}$	$a_{-1}$	$(b, q', \leftarrow)$	$a_1$	$a_i$	$a_R$	★	
	L <b>a<sub>-L</sub></b> L	L <b>...</b> L	L <b>a<sub>-2</sub></b> L	L <b>a<sub>-1</sub></b> L	L <b>a, q</b> R	R <b>a<sub>1</sub></b> R	R <b>...</b> R	R <b>a<sub>R</sub></b> ★	★	
	$a_{-L}$	$a_{-i}$	$a_{-2}$	$a_{-1}$	<i>prv trans</i>	$a_1$	$a_i$	★	★	

Tiles for  $(a, q) \mapsto (b, q', \leftarrow)$

# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

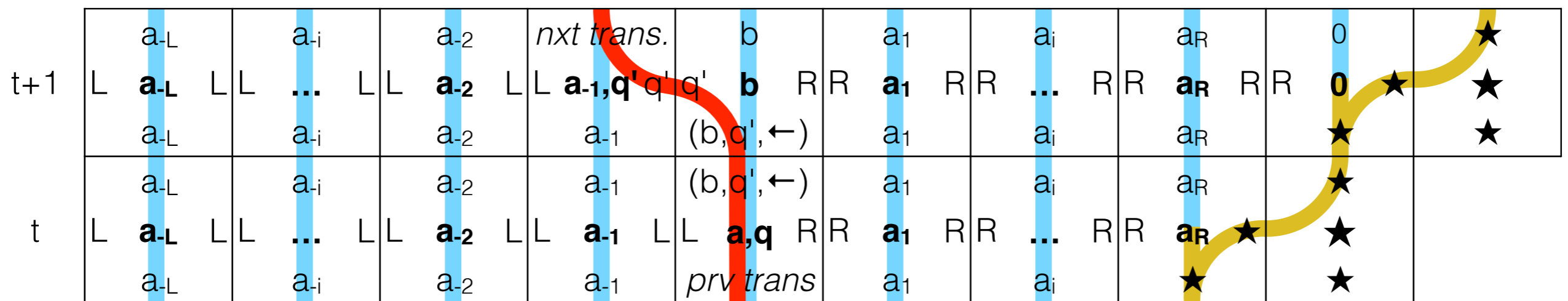
- 1) Organize the information flow passing through the glues on the sides



Tiles for  $(a, q) \mapsto (b, q', \leftarrow)$

# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles



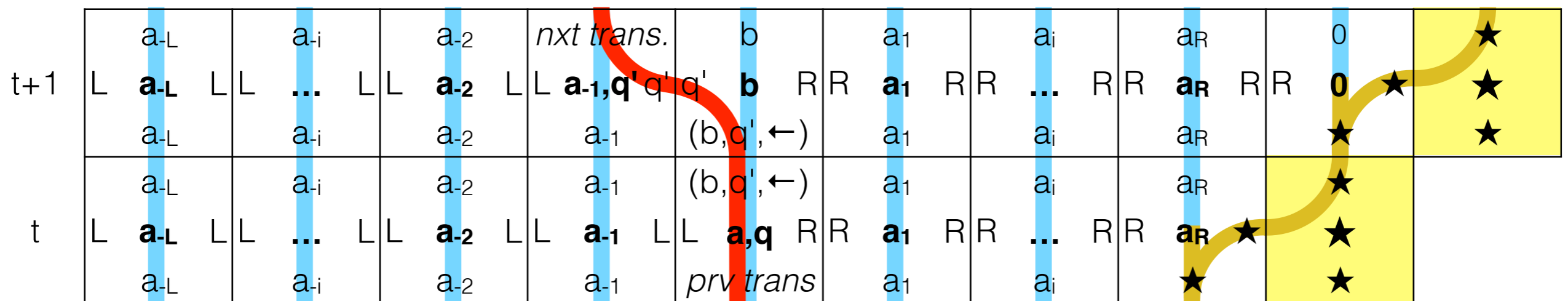
Tiles for  $(a, q) \mapsto (b, q', \leftarrow)$



# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles

The skeleton

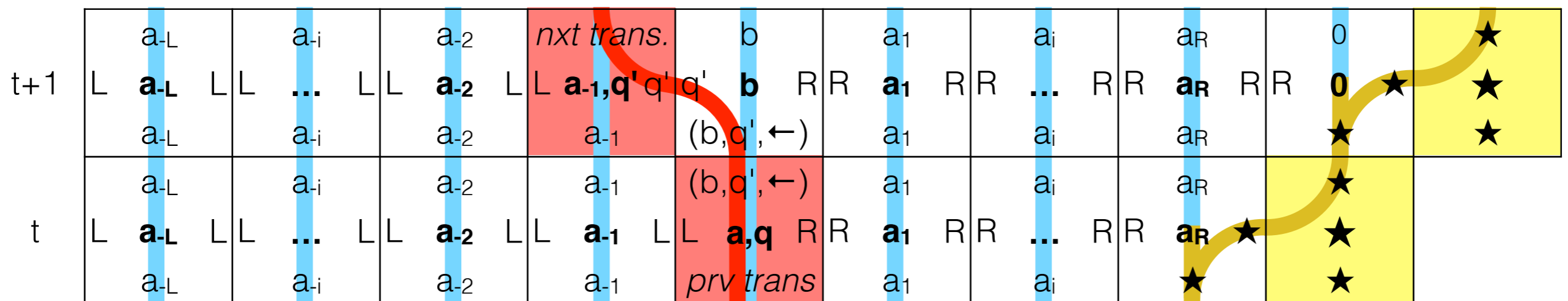


Tiles for  $(a, q) \mapsto (b, q', \leftarrow)$

# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles

The skeleton

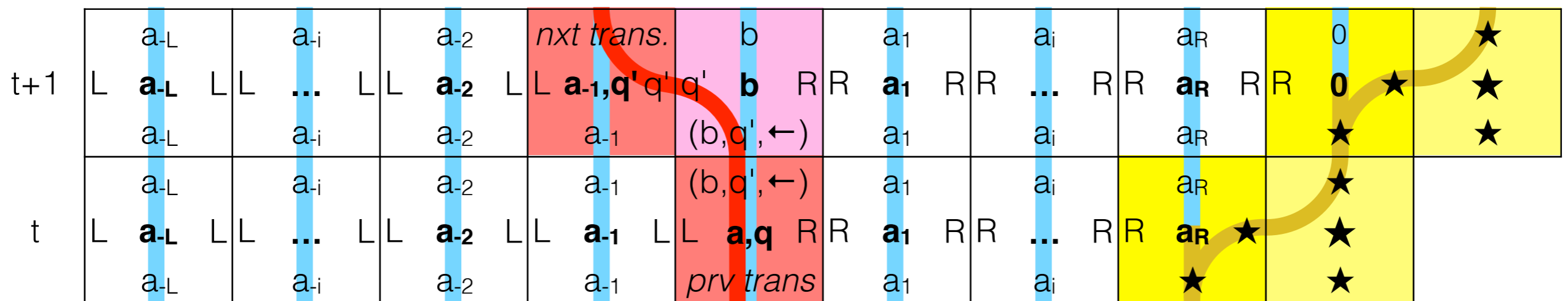


Tiles for  $(a, q) \mapsto (b, q', \leftarrow)$

# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles

## The carriers

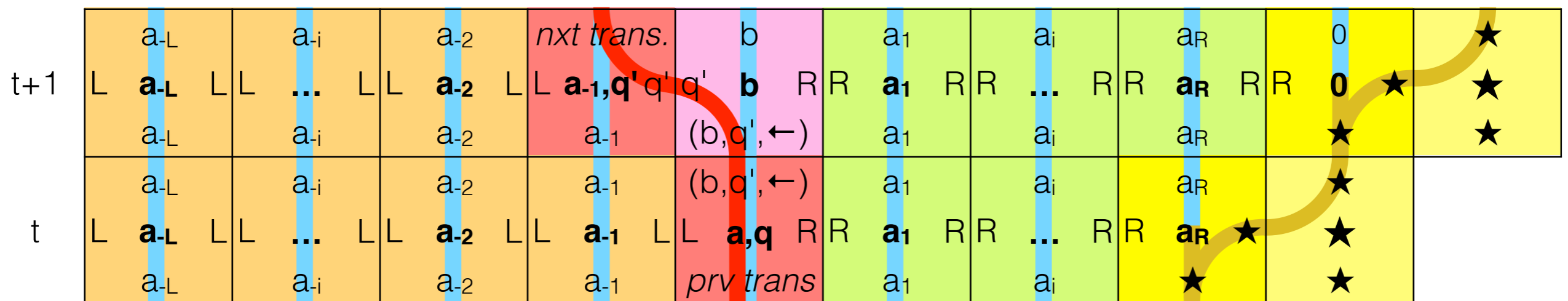


Tiles for  $(a, q) \mapsto (b, q', \leftarrow)$

# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles

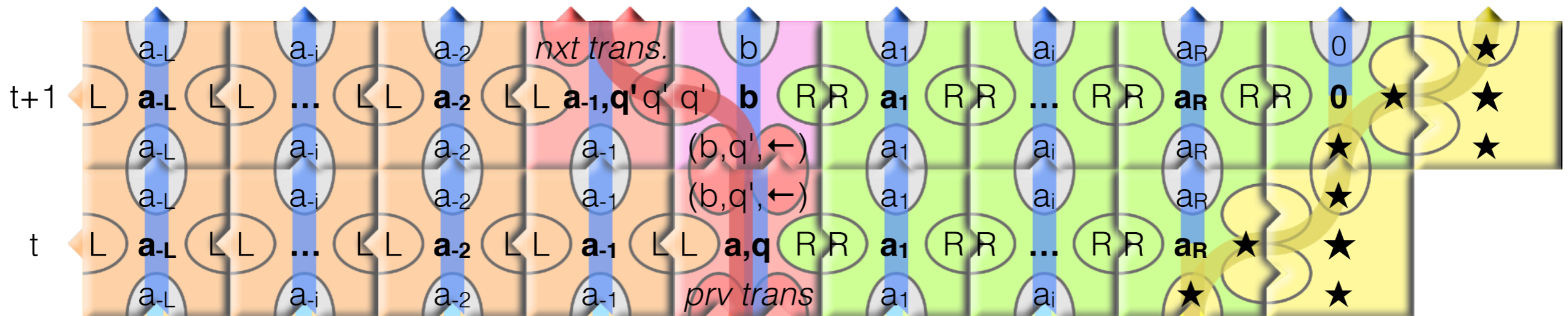
## The filling tiles



Tiles for  $(a, q) \mapsto (b, q', \leftarrow)$

# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}2$ in 2D

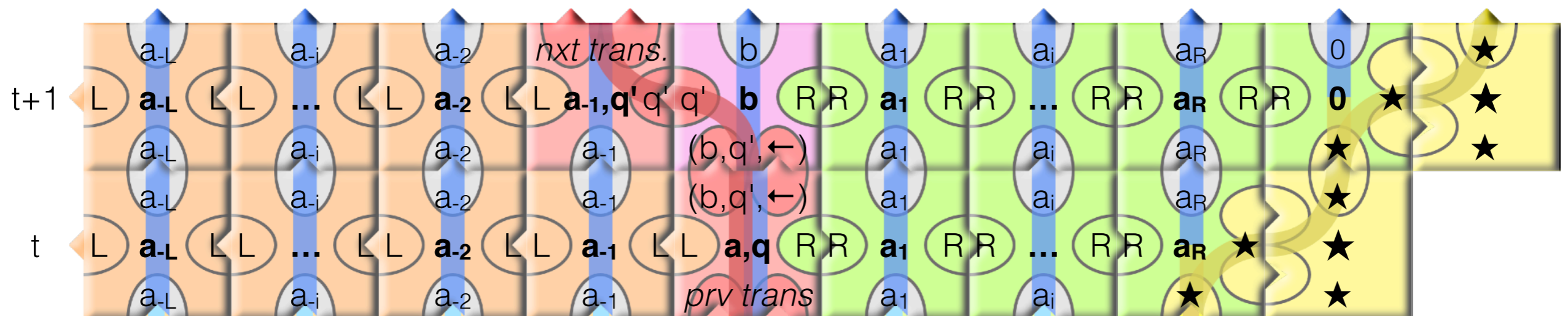
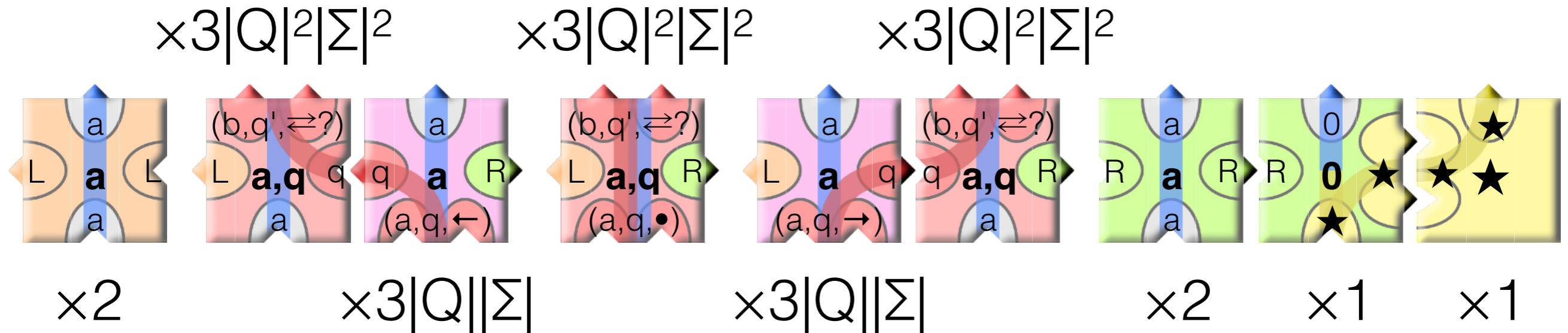
- 1) Organize the information flow passing through the glues on the sides
- 2) Identify each type of tiles
- 3) Set the order, glue strength & colors to match the flow



Tiles for  $(a, q) \mapsto (b, q', \leftarrow)$

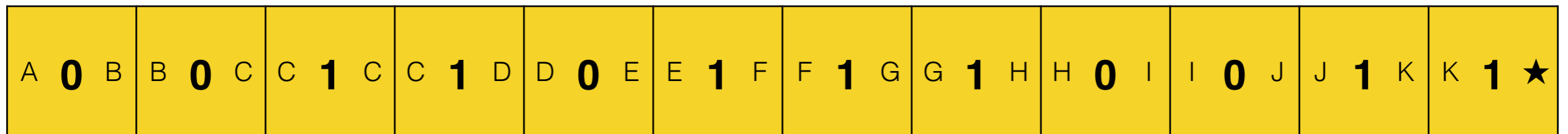
# The tileset with size $O(|Q|^2|\Sigma|^2)$

The tiles for each transition  $(a, q) \mapsto (b, q', \Leftarrow?)$



# Encoding the input as a seed

- **Solution 1: hardcoding**  
Uses **n** tiles for n bits



- Each tile requires **4 log n bits** to encode its glues, thus this encoding uses **4n log n bits** in total
- Can we do better, with less tiles ?

# Kolmogorov complexity

- Given a universal Turing machine  $U$ :

$$K_U(x) = \min \{ |p| : U(p, \varepsilon) = x \}$$

is the size of the smallest program in  $U$  that outputs  $x$

- **Fact.**  $\forall U, \exists A$  s.t.  $\forall x, K_U(x) \leq |x| + A$

*Proof.*  $A$  is the size of the program "print" in  $U$ .

- **Theorem.**  $K_U(x)$  is independent of  $U$ , indeed:

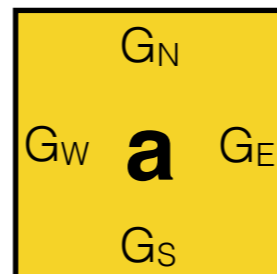
$$\forall U, U' \exists A, B \text{ s.t. } \forall x, K_{U'}(x) - A \leq K_U(x) \leq K_{U'}(x) + B$$

*Proof.*  $A$  and  $B$  are the sizes of the programs that execute  $U$  and  $U'$  respectively in  $U'$  and  $U$ .



# Lower bounding the required number of tiles to encode the seed

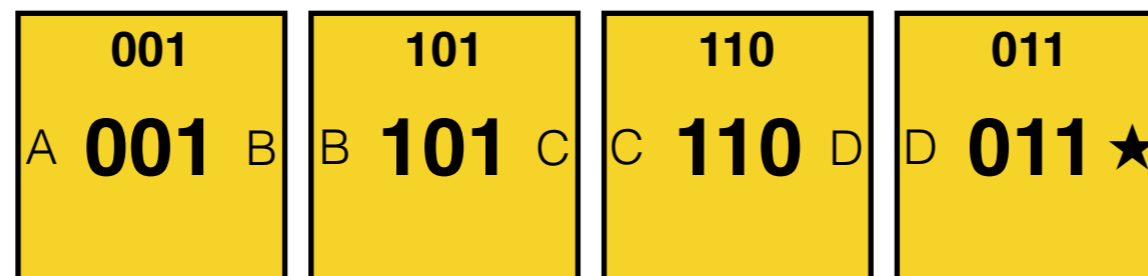
- The Kolmogorov complexity  $\mathbf{K(x)}$  is the size of the smallest program that outputs  $\mathbf{x}$
- Bit size of the encoding with  $\mathbf{T}$  tiles is  $\leq 4 \mathbf{T} \log_2 \mathbf{T}$



- A tileset that self-assembles  $x$  is a program that outputs  $x$ ,  
Thus:  $4\mathbf{T} \log \mathbf{T} \geq \mathbf{K(x)}$ , i.e.  $\mathbf{T} \geq \mathbf{K(x)} / 4 \log \mathbf{K(x)}$

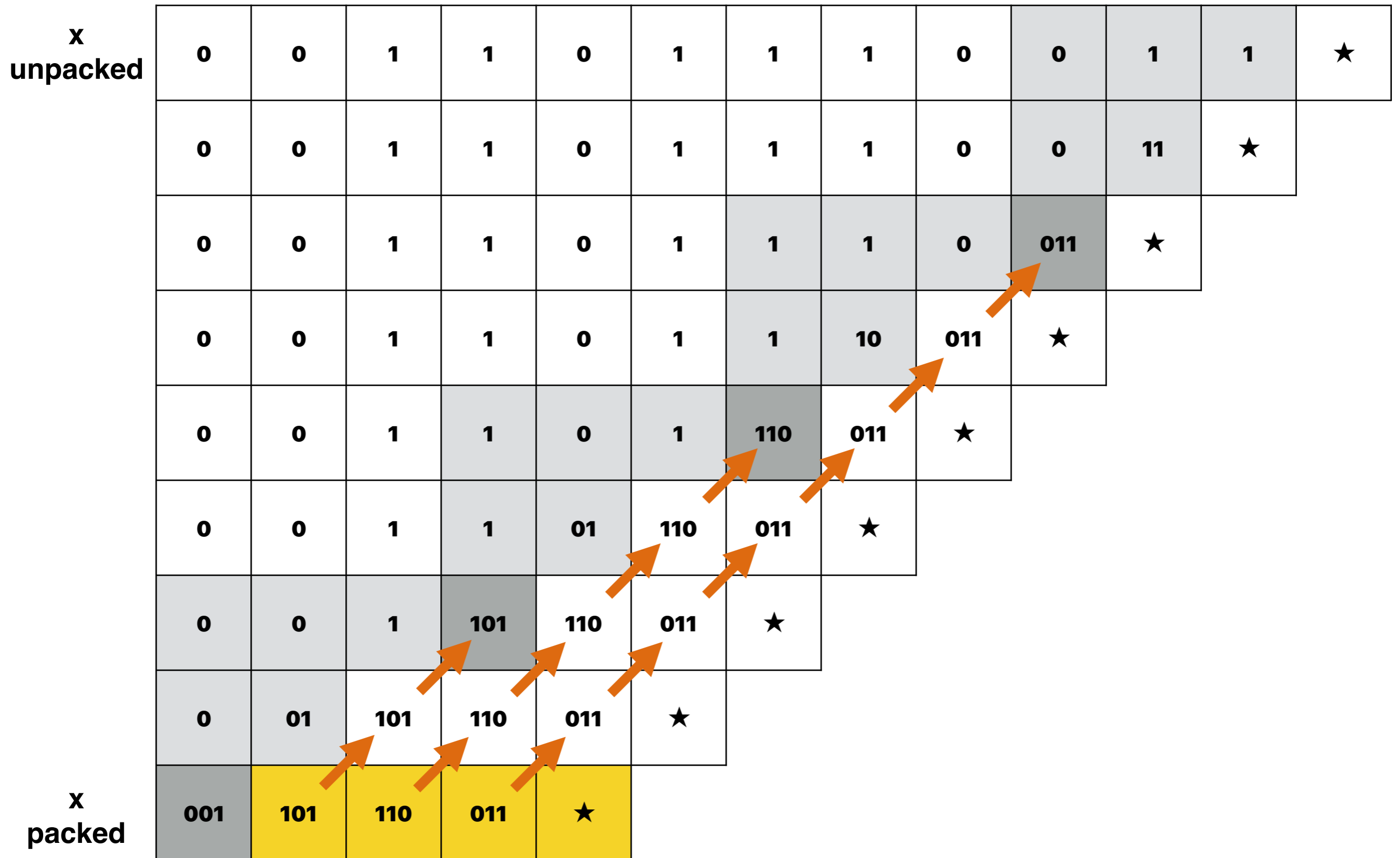
# Unpacking a binary string

- Cut string **x** in **n / b** chunks of **b** bits and uncompress it
- Example: **x = 001 101 110 011** and **b = 3**

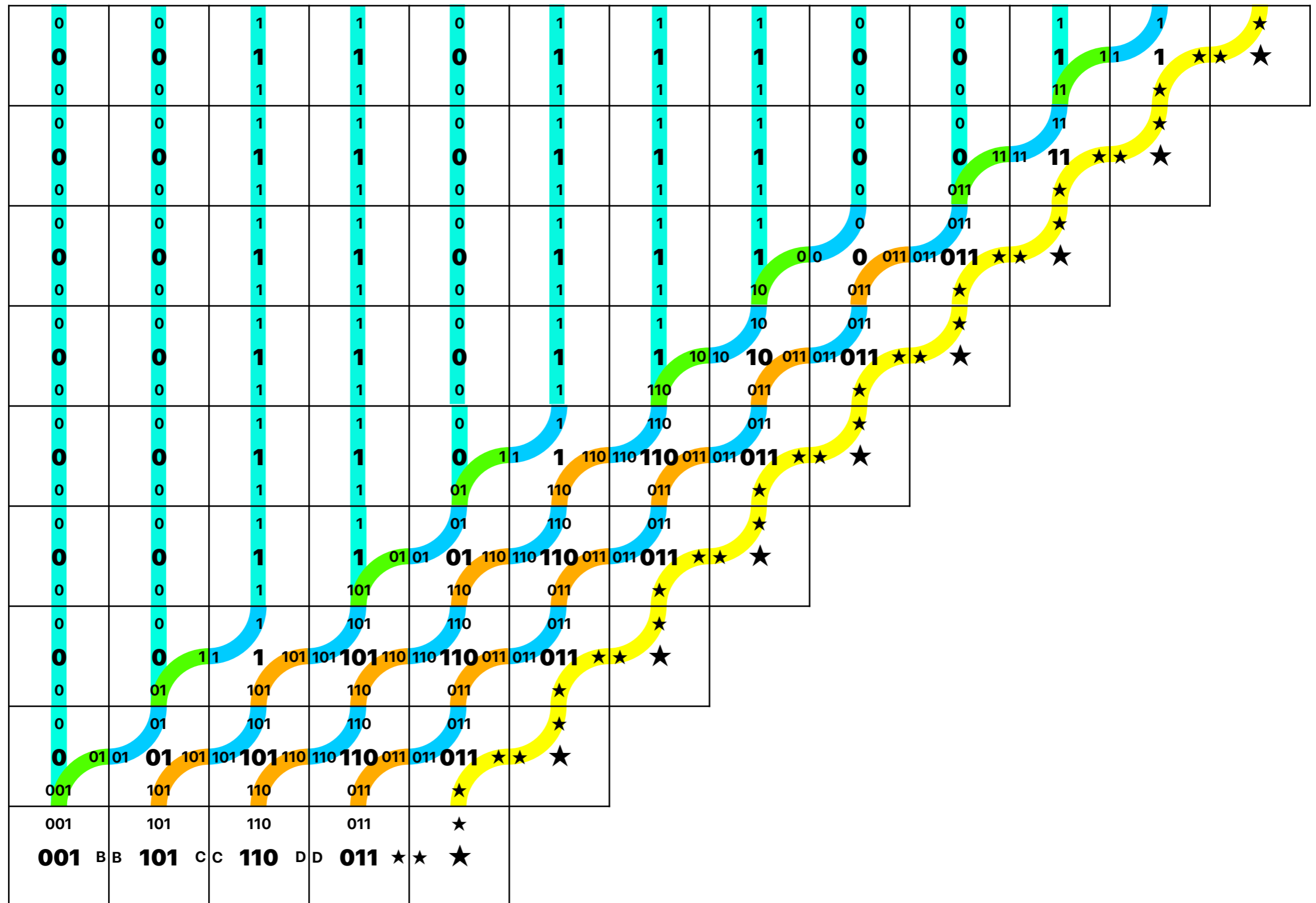


**n / b tiles**

# Unpacking a binary string

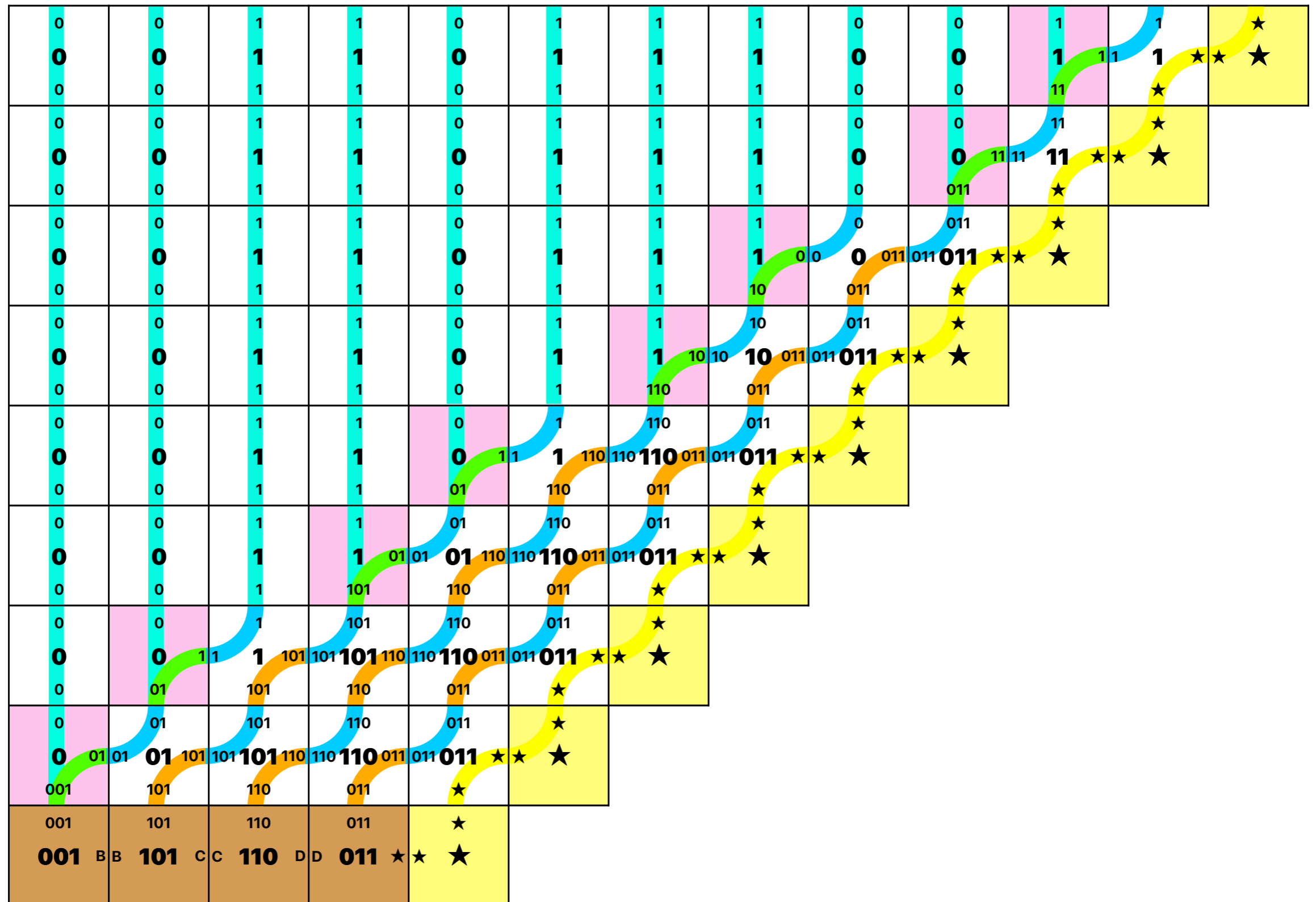


# Determine the flow of information

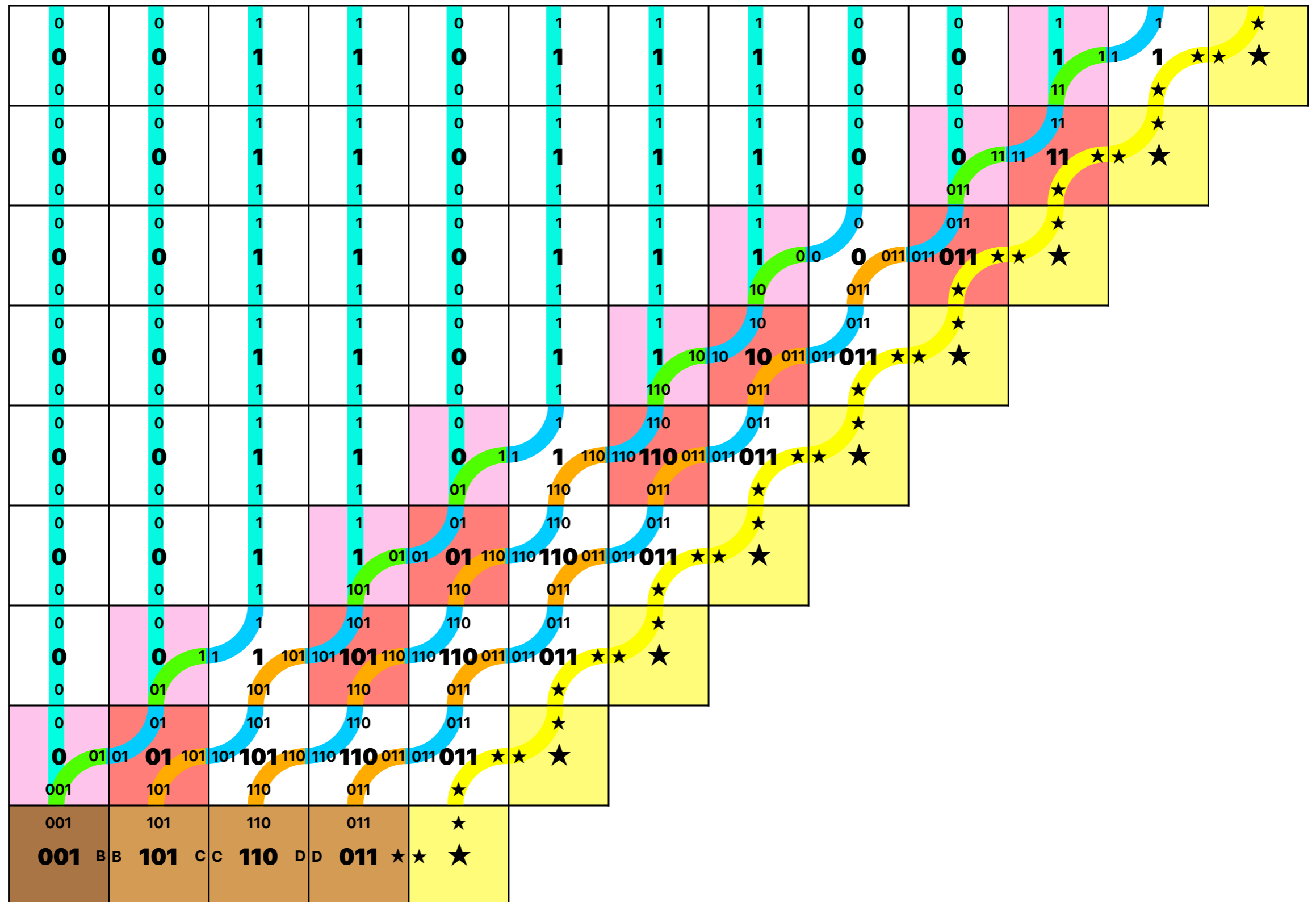




# Determine the various tile types



# Determine the various tile types





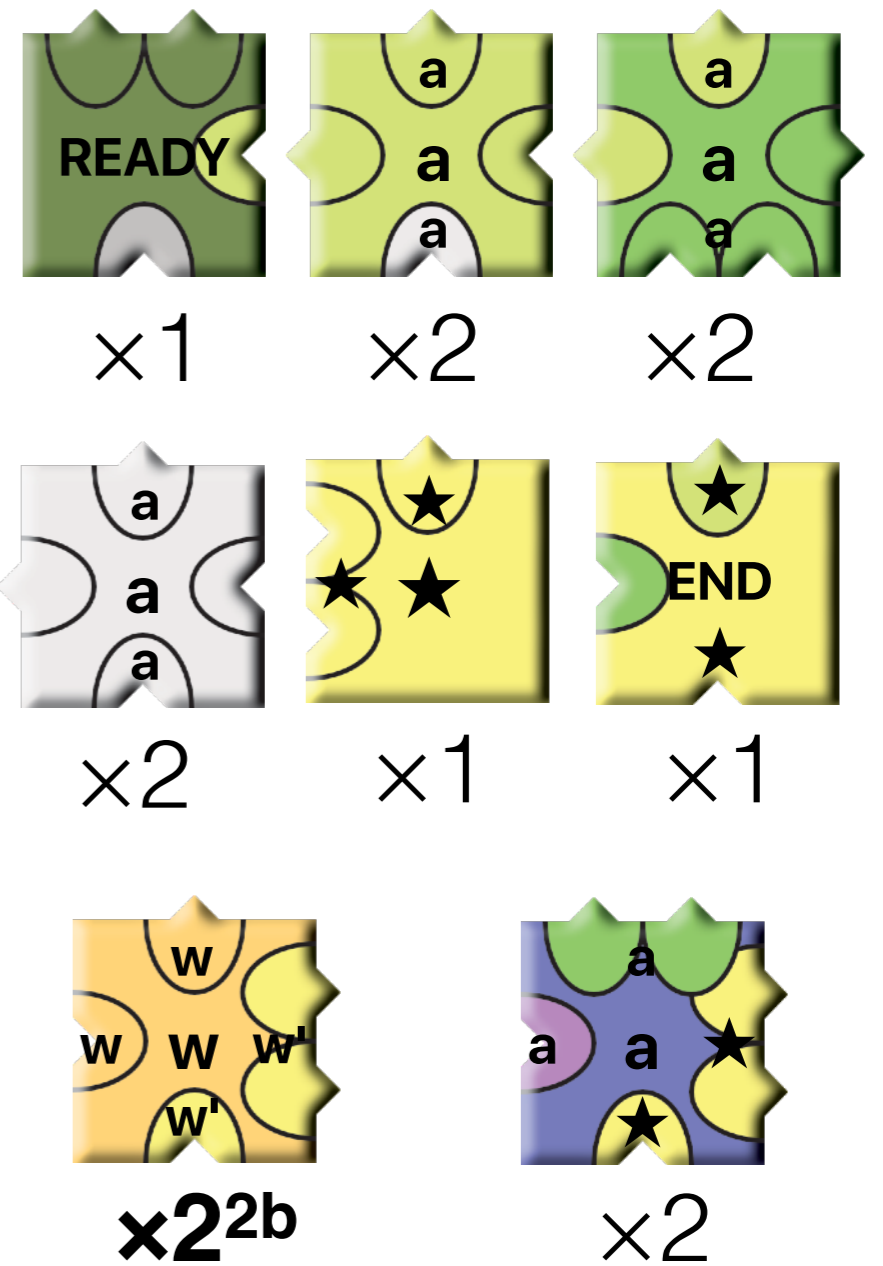
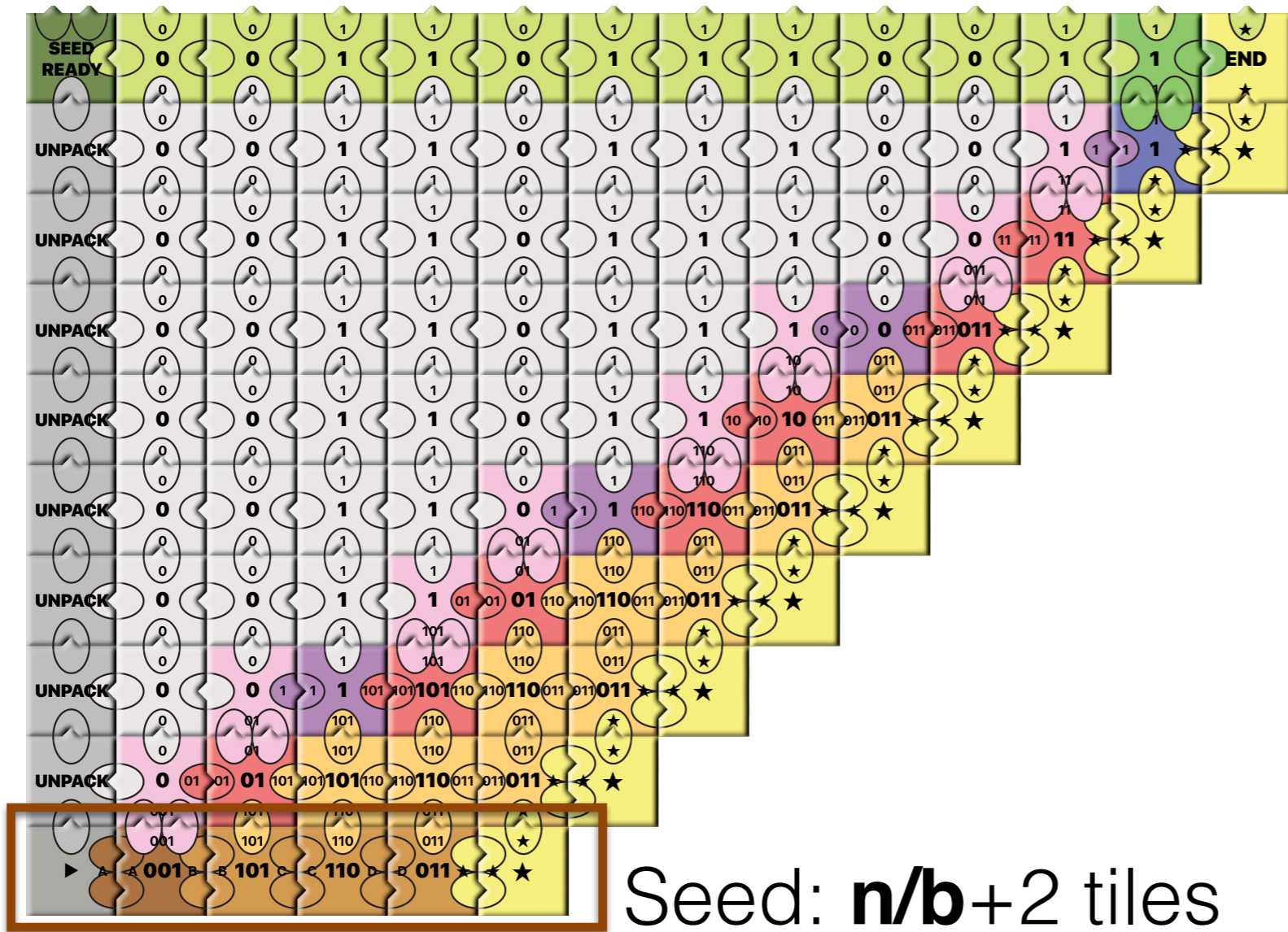




<b>SEED READY</b>	0 <b>0</b> 0	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	1 <b>1</b> 1	0 <b>0</b> 0	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	<b>END</b>
<b>UNPACK</b>	0 <b>0</b> 0	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	1 <b>1</b> 1	0 <b>0</b> 0	0 <b>0</b> 0	1 <b>1</b> 11	1 <b>1</b> ★	★
<b>UNPACK</b>	0 <b>0</b> 0	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	1 <b>1</b> 1	0 <b>0</b> 0	0 <b>0</b> 011	11 <b>11</b> ★	★	★
<b>UNPACK</b>	0 <b>0</b> 0	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	1 <b>1</b> 10	0 <b>0</b> 011	011 <b>011</b> ★	★	★	★
<b>UNPACK</b>	0 <b>0</b> 0	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 110	10 <b>10</b> 011	011 <b>011</b> ★	★	★	★	★
<b>UNPACK</b>	0 <b>0</b> 0	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 1	0 <b>0</b> 01	1 <b>1</b> 110	110 <b>110</b> 011	10 <b>10</b> 011	011 <b>011</b> ★	★	★	★	★
<b>UNPACK</b>	0 <b>0</b> 0	0 <b>0</b> 0	1 <b>1</b> 1	1 <b>1</b> 101	01 <b>01</b> 110	110 <b>110</b> 011	011 <b>011</b> ★	★	★	★	★	★	★
<b>UNPACK</b>	0 <b>0</b> 0	0 <b>0</b> 01	1 <b>1</b> 101	101 <b>101</b> 110	110 <b>110</b> 011	011 <b>011</b> ★	★	★	★	★	★	★	★
<b>UNPACK</b>	0 <b>0</b> 001	01 <b>01</b> 101	101 <b>101</b> 110	110 <b>110</b> 011	011 <b>011</b> ★	★	★	★	★	★	★	★	★
▶	001 <b>001</b>	101 <b>101</b>	110 <b>110</b>	011 <b>011</b>	★	★	★	★	★	★	★	★	★

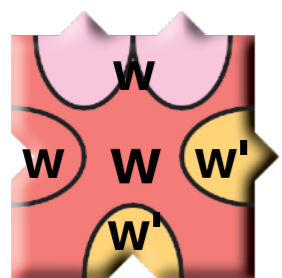
Add tiles at the boundary for continuation





$$2 \leq |w| \leq b$$

$$|w'| = b$$



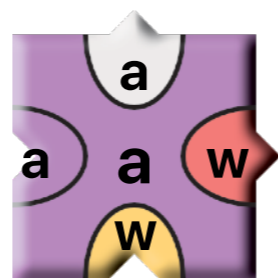
$$\times 2^{2b}$$

$$2 \leq |w| \leq b$$



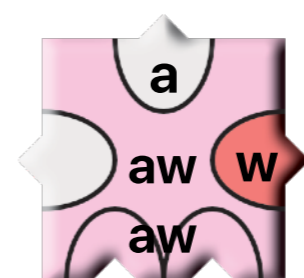
$$\times 2^b$$

$$|w| = b$$

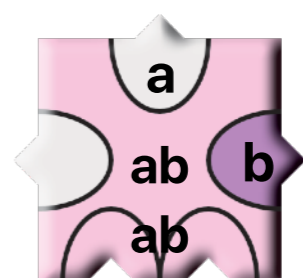


$$\times 2^{b+1}$$

$$2 \leq |w| < b$$



$$\times 2^b$$



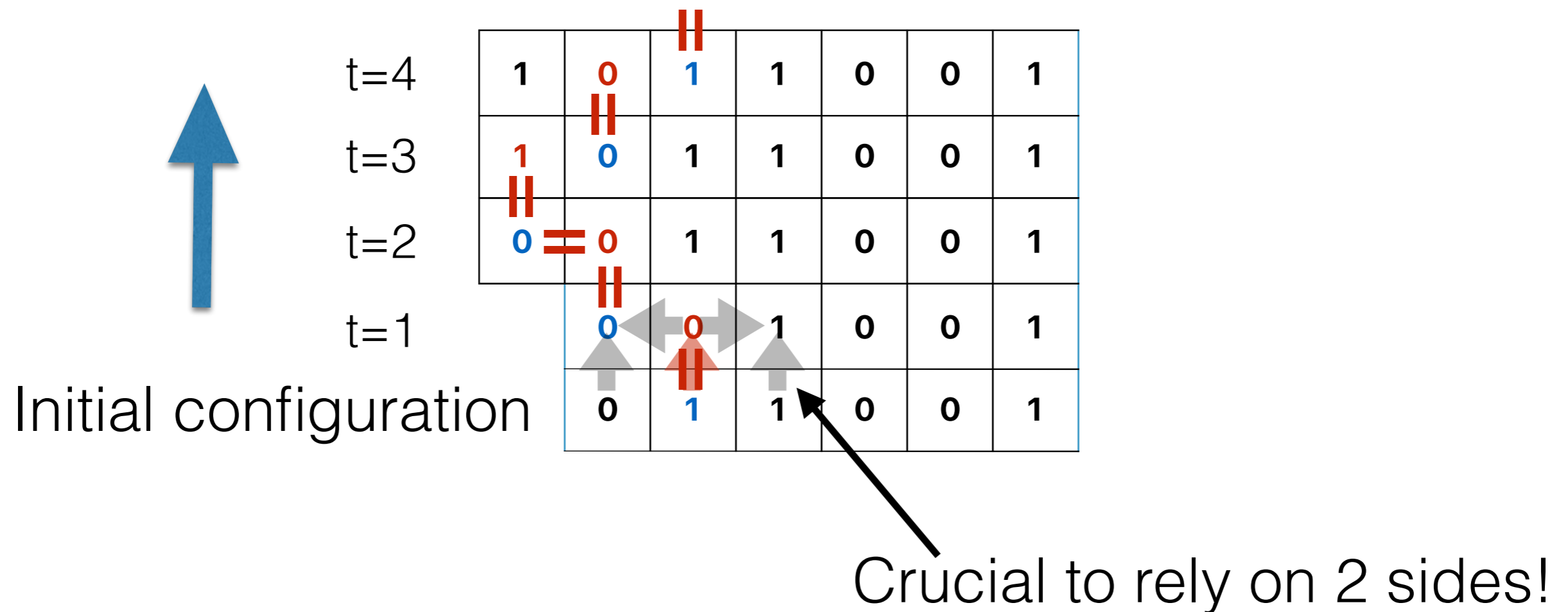
$$\times 4$$



What about  $T^{\circ} = 1$ ?

# Does algorithmic self-assembly simulate Turing machine at $T^O(1)$ in 2D?

- How to read and propagate the position of the head?



Does algorithmic self-assembly simulate  
Turing machine at  $T^{\circ}1$  in 2D?

- **Theorem.** [Meunier, Regnault, 2015]  
Any deterministic  $T^{\circ}1$  tile set can be pumped outside  
a fixed radius in 2D
- **Corollary.** No  $T^{\circ}1$  tilesystem is Turing complete in 2D

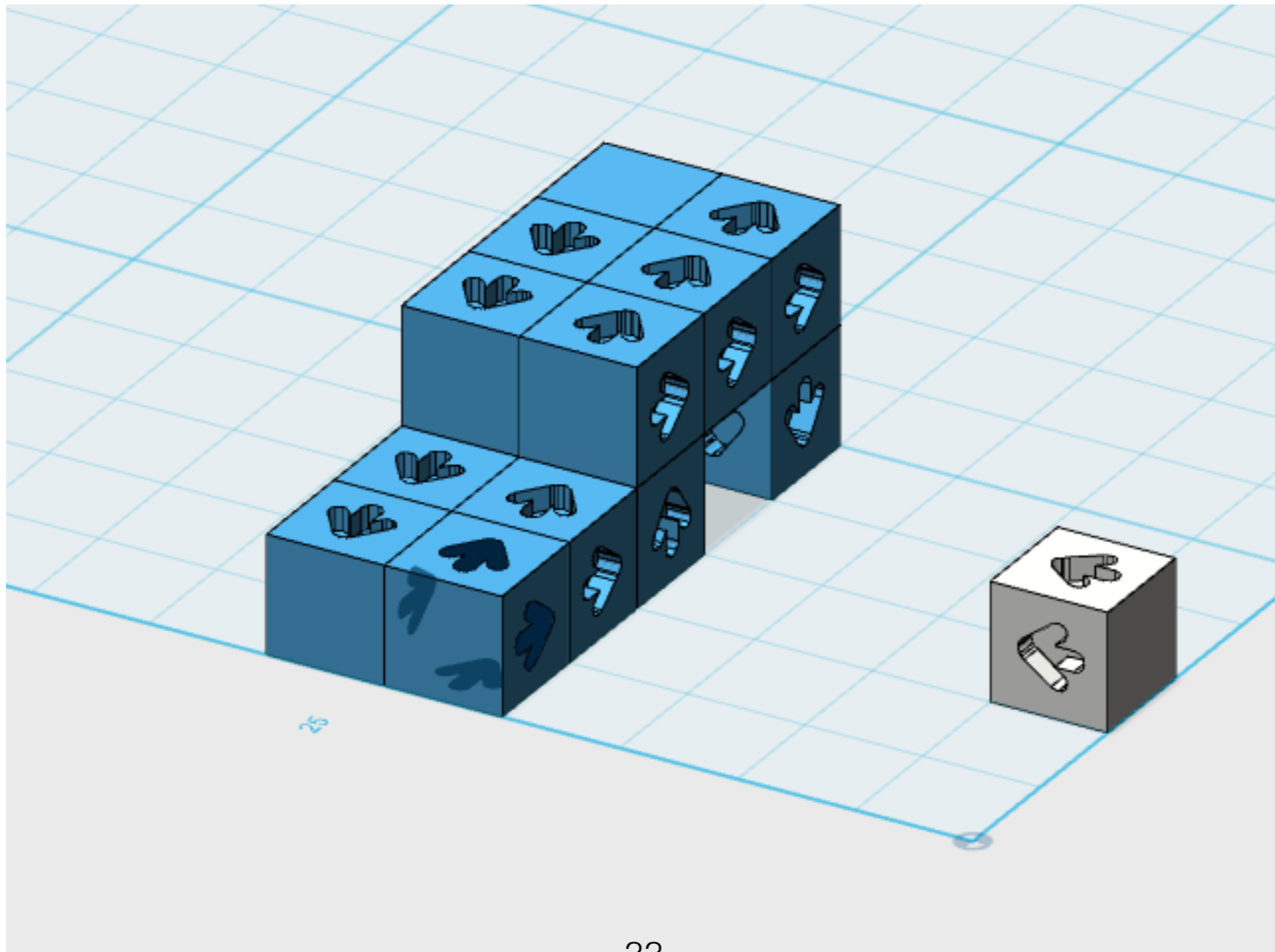


# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}1$ in 3D

- **Theorem.** *[Cook, Fu, Schweller, 2011]*  
There is a  $T^{\circ}1$  tile set that simulates any Turing machine with 2-layers in 3D.
- *Key beautiful idea:* Blocking probe crystal

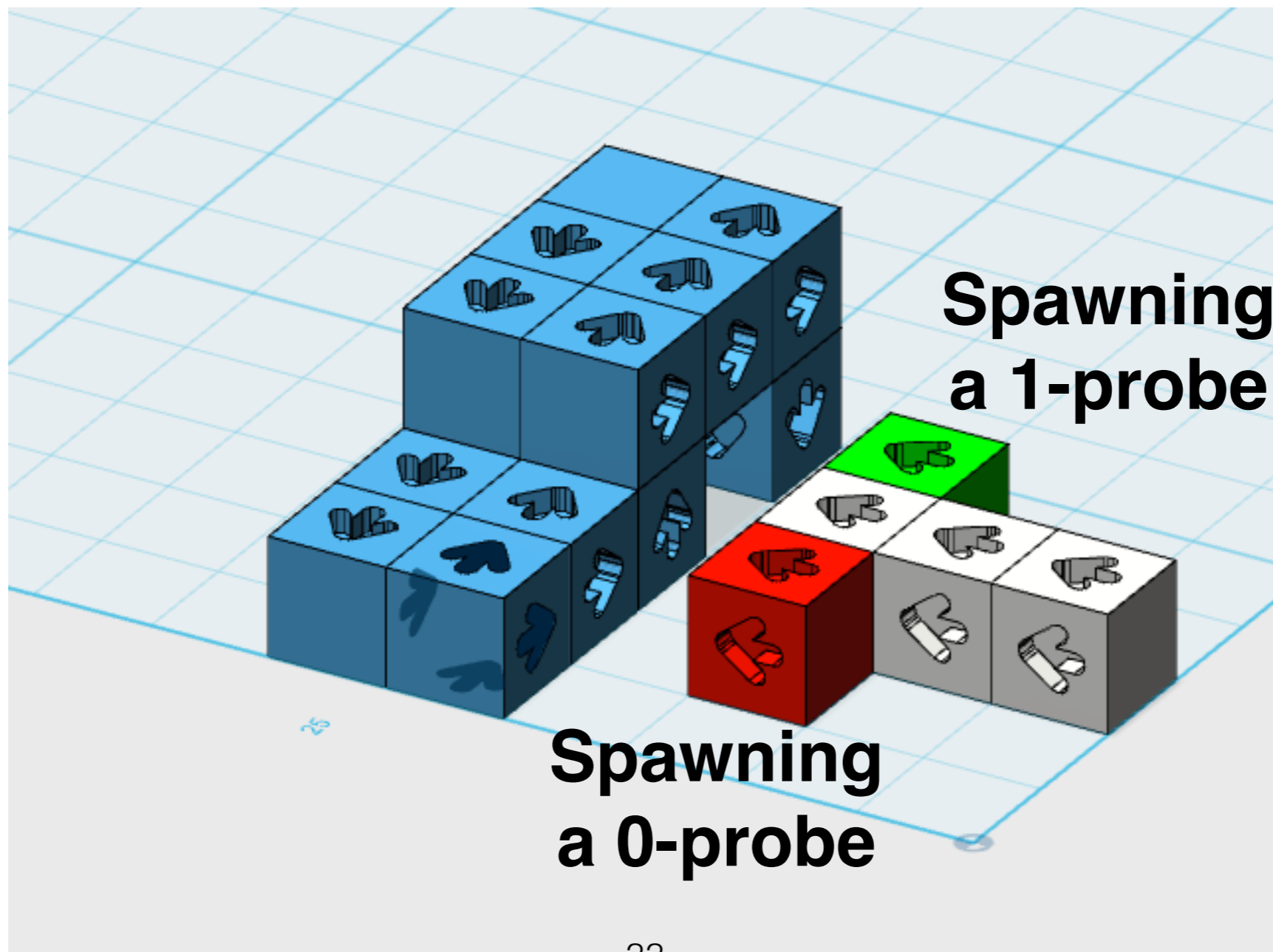
# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}1$ in 3D

- *Key beautiful idea:* Blocking probe crystal



# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}1$ in 3D

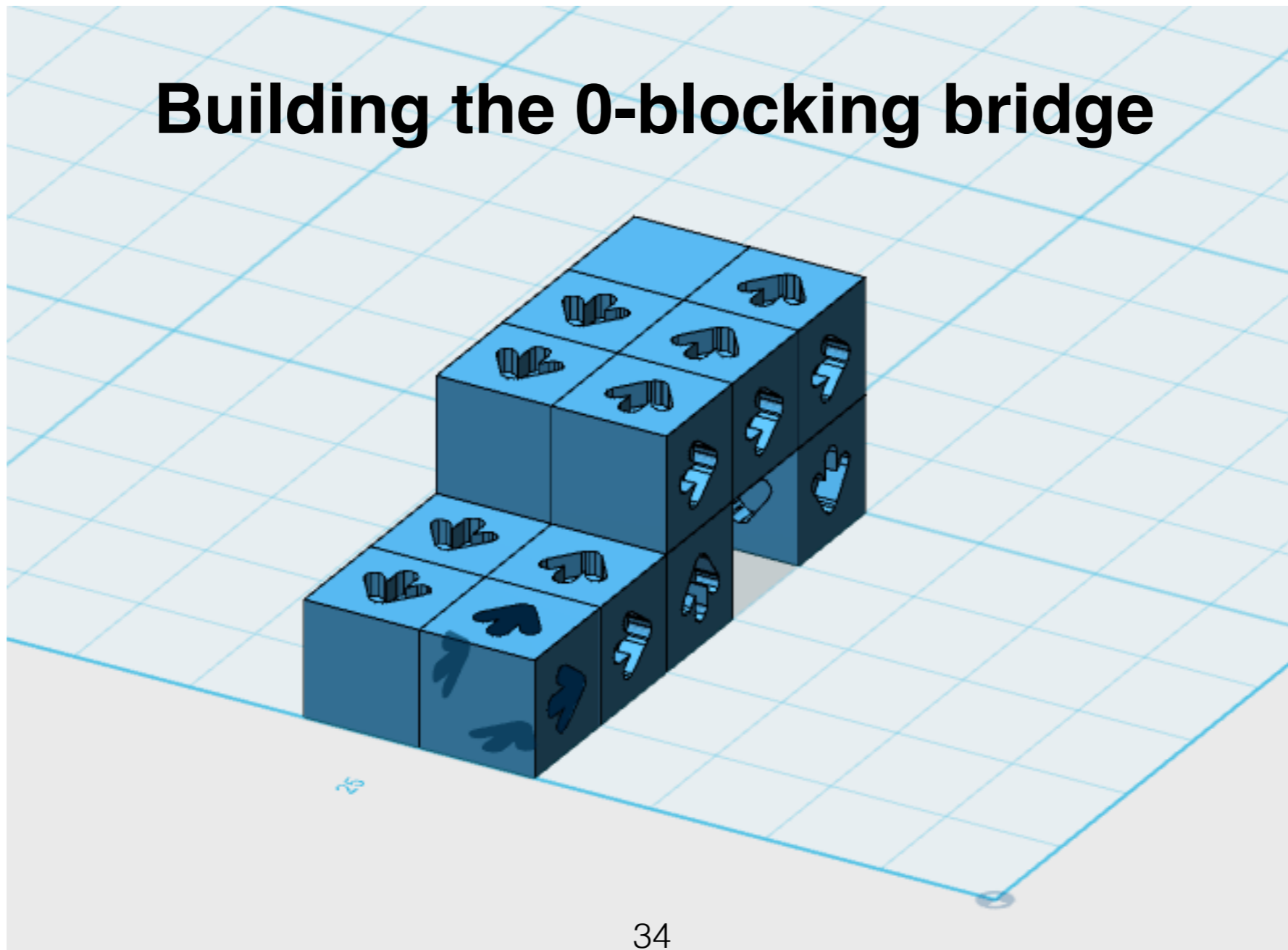
- *Key beautiful idea:* Blocking probe crystal





# Algorithmic self-assembly simulates any Turing machine at $T^{\circ}1$ in 3D

- *Key beautiful idea:* Blocking probe crystal



Algorithmic self-assembly simulates  
any Turing machine at  $T^{\circ}1$  in 3D

- *Key beautiful idea:* Blocking probe crystal

We can thus read and write 0 and 1 on the  
“next tape” !

**Crystals are Turing complete !!!**

An experimental  
realization of  
a universal computer

# Conclusion

- A lot of new models
- A new kind of geometric algorithmic
- A lot of implication in biology and bio-engineering
- Lots of extensions: mixed dynamics, errors, ...  
*More on fixing errors at the last lecture*