

Elementary linear logic revisited for polynomial time and an exponential time hierarchy

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Abstract. Elementary linear logic is a simple variant of linear logic, introduced by Girard and which characterizes in the proofs-as-programs approach the class of elementary functions, that is to say computable in time bounded by a tower of exponentials of fixed height.

Our goal here is to show that despite its simplicity, elementary linear logic can nevertheless be used as a common framework to characterize the different levels of a hierarchy of deterministic time complexity classes, within elementary time. We consider a variant of this logic with type fix-points and weakening. By selecting specific types we then characterize the class \mathbf{P} of polynomial time predicates and more generally the hierarchy of classes $\mathbf{k-EXP}$, for $k \geq 0$, where $\mathbf{k-EXP}$ is the union of $\mathbf{DTIME}(2_k^{n^i})$, for $i \geq 1$.

1 Introduction

Implicit computational complexity. This line of research promotes investigations to delineate classical complexity classes by programming languages or logics, without referring to explicit bounds on resources (time, space ...) but instead by restricting the primitives or the features of the languages. Various approaches have been used for that, primarily in logic and in functional languages: restrictions of the comprehension scheme in second-order logic [Lei91,Lei02]; ramification in logic or in recursion [Lei94,BC92]; *read-only* functional programs [Jon01]; variants of linear logic [Gir98,Laf04]... to name only a few.

Note that the programming disciplines induced by these systems are quite restrictive, but some of these characterizations have in a second step led to more flexible criteria for statically checking complexity bounds on programs: ramification and safe recursion have inspired the work on interpretation methods for complexity [BMM11] on the one-hand, and linear type systems for non-size-increasing computation [Hof03] on the other, which itself has led to typing methods for amortized complexity analysis [HJ06,HAH11].

Linear logic. The linear logic approach to implicit complexity fits in the proofs-as-programs paradigm. It stems from the observation that as duplication is controlled in linear logic by the modality $!$, weaker versions of this modality can define systems with a complexity-bounded normalization procedure: *elementary*

linear logic (ELL) [Gir98,DJ03] characterizes in this way the class of Kalmar elementary functions (computable in time bounded by a tower of exponentials of fixed height), while light linear logic (LLL) [Gir98] and soft linear logic (SLL) [Laf04] characterize functions computable in polynomial time. These logical systems have then enabled the design of type systems for λ -calculus or functional languages ensuring that a well-typed program has a polynomial time complexity bound [BT09,GR07,BGM10].

Note that initially ELL does not sound as interesting as LLL and SLL since it corresponds to elementary complexity, which is not very relevant from a programming point of view. However it has nice logical properties, a simpler language of formulas than LLL (no \S modality) and allows for a more natural programming style than SLL. It has also been studied for its remarkable properties concerning λ -calculus optimal reduction [ACM04].

Calibrating complexity. One might however deplore a lack of homogeneity in these characterizations of complexity classes by variants of linear logic: indeed some common deterministic complexity classes like EXP have not yet been characterized, a different system is needed for each complexity class, and these various systems are not easy to compare.

By contrast, other methods in implicit complexity have provided frameworks that can be calibrated to delineate different complexity classes inside the (large) Kalmar elementary class:

- Jones considers in [Jon01] a *read-only* functional programming language and characterizes in it the classes k -EXP, for $k \geq 0$, by considering, for each k , programs using only arguments of type-order at most k ;
- Leivant investigates in [Lei02] second-order logic with comprehension (quantifier elimination) restricted to various families of first-order formulas: the functions provably total in this logic with comprehension restricted to formulas of type-order at most k are precisely the functions of k -EXP.

Note that even if these two frameworks fit in different computational approaches, they both use as parameter the type-order (or implicational rank) of formulas.

Objective and contribution. A goal of the present work is to provide an analogous framework in linear logic, allowing to characterize in a single logic a hierarchy of complexity classes by calibrating a certain parameter. We will use elementary linear logic, which offers the advantage of simplicity. A key parameter in this system, as in LLL, is the number of nested modalities (!) and this will be the value calibrating our complexity bounds.

For technical reasons we will actually consider an extension of ELL obtained by adding to it type fixpoints. It had been observed from the beginning [Gir98] that this feature does not modify the dynamics of ELL and its complexity bounds. We will also allow unrestricted weakening, which is innocuous and common practise since [AR02]. Given some types \mathbf{W} for binary words and \mathbf{B} for booleans, we will then show that for $k \geq 0$, the proofs of conclusion $!\mathbf{W} \multimap !^{k+2}\mathbf{B}$, where $!^i$ stands for a sequence of i ls, correspond to the predicates of k -EXP. In particular this gives, in the case where $k = 0$, a characterization of the class P in an elementary logic, with the type $!\mathbf{W} \multimap !^2\mathbf{B}$.

Note that a distinctive point of our characterization is that it does not rely on a restriction of a particular operation *inside* the proof-program, like the application of a function to an argument in [Jon01] or the comprehension rule in [Lei02]. Instead it only imposes a condition on the *conclusion* of the proof (or type of the program), that its to say on its interface. In this sense it is more modular than these previous characterizations. Observe also that our system is a second-order logic, as the one of [Lei02], but here comprehension is not restricted.

Because of space constraints we had to omit some proofs; they can be found in [Bai11].

2 Characterization of the classes P and k-EXP

We consider intuitionistic affine elementary logic with type fixpoints that we denote by EAL_μ . Actually for our purpose it is sufficient to consider its multiplicative fragment. The grammar of types is:

$$A ::= \alpha \mid A \multimap A \mid A \otimes A \mid !A \mid \forall \alpha. A \mid \mu \alpha. A$$

We will represent functions by proofs, but as often it will be convenient to use λ -calculus to denote the algorithmic content of proofs. For that we will consider an extension of λ -calculus with a \otimes construction:

$$t, u ::= x \mid \lambda x. t \mid (t \ u) \mid t \otimes u \mid \text{let } t \text{ be } x \otimes y \text{ in } u$$

Its reduction rule is obtained by the context-closure of the usual β -reduction rule and of the following one:

$$\text{let } t_1 \otimes t_2 \text{ be } x \otimes y \text{ in } u \rightarrow u[t_1/x, t_2/y].$$

The rules of EAL_μ are now given on Fig. 1, as a sequent calculus decorated with λ -terms. This system only differs from the intuitionistic version of elementary linear logic without additive connectives [Gir98,DJ03] by the fact that we have added the fixpoint construction (rules L_μ and R_μ) and allowed for general weakening (rule (Weak)). Observe that some rules do not have any effect on the term ($!$, L_μ , R_μ , L_\forall , R_\forall): this is because we want to keep the term calculus as simple as possible, and the current calculus is anyway sufficient to represent the functions denoted by the proofs.

Observe that the formulas $!A \multimap A$ and $!A \multimap !!A$ are *not* provable, which is the distinctive feature of elementary linear logic with respect to ordinary linear logic.

Finally, note that if we added the fixpoint rules to intuitionistic logic or linear logic cut elimination would not be normalizing anymore, but strong normalization does hold for EAL_μ (see [Gir98]).

Let us denote the following types respectively for booleans, n -ary finite types, tally integers and binary words, which are adapted from system F:

$$\mathbf{B} = \forall \alpha. \alpha \multimap \alpha \multimap \alpha, \quad \mathbf{B}^n = \forall \alpha. \alpha \multimap \dots \multimap \alpha, \text{ with } n + 1 \text{ occurrences of } \alpha \\ \mathbf{N} = \forall \alpha. !(\alpha \multimap \alpha) \multimap !(\alpha \multimap \alpha), \quad \mathbf{W} = \forall \alpha. !(\alpha \multimap \alpha) \multimap !(\alpha \multimap \alpha) \multimap !(\alpha \multimap \alpha)$$

Axiom and Cut.	
$\frac{}{x : A \vdash x : A} Ax$	$\frac{\Gamma \vdash t : A \quad \Delta, x : A \vdash u : B}{\Gamma, \Delta \vdash u[t/x] : B} Cut$
Structural Rules.	
$\frac{\Gamma \vdash t : A}{\Gamma, x : B \vdash t : A} Weak$	$\frac{\Gamma, x_1 : !A, x_2 : !A \vdash t : B}{\Gamma, x : !A \vdash t[x/x_1, x/x_2] : B} Contr$
Multiplicative Rules.	
$\frac{\Gamma \vdash t : A \quad \Delta, x : B \vdash u : C}{\Gamma, \Delta, y : A \multimap B \vdash u[(y t)/x] : C} L_{\multimap}$	$\frac{\Gamma, x : A \vdash t : B}{\Gamma \vdash \lambda x. t : A \multimap B} R_{\multimap}$
$\frac{\Gamma, x_1 : A, x_2 : B \vdash t : C}{\Gamma, x : A \otimes B \vdash \text{let } x \text{ be } x_1 \otimes x_2 \text{ in } t : C} L_{\otimes}$	$\frac{\Gamma \vdash t_1 : A \quad \Delta \vdash t_2 : B}{\Gamma, \Delta \vdash t_1 \otimes t_2 : A \otimes B} R_{\otimes}$
Exponential Logical Rule.	
$\frac{\Gamma \vdash t : A}{! \Gamma \vdash t : !A} !$	
Second Order Rules	
$\frac{\Gamma, x : C[A/\alpha] \vdash t : B}{\Gamma, x : \forall \alpha. C \vdash t : B} L_{\forall}$	$\frac{\Gamma \vdash t : C \quad \alpha \notin FV(\Gamma)}{\Gamma \vdash t : \forall \alpha. C} R_{\forall}$
Fixpoint Rules	
$\frac{\Gamma, x : A[\mu \alpha. A/\alpha] \vdash t : B}{\Gamma, x : \mu \alpha. A \vdash t : B} L_{\mu}$	$\frac{\Gamma \vdash t : A[\mu \alpha. A/\alpha]}{\Gamma \vdash t : \mu \alpha. A} R_{\mu}$

Fig. 1. The system EAL_{μ}

Recall that these data-types admit some coercions [Gir98]. For \mathbf{W} for instance, one can give a proof of type $\mathbf{W} \multimap !\mathbf{W}$ which, as a λ -term, acts as an identity on the terms encoding binary words.

We denote: $2_0^n = n$, $2_{k+1}^n = 2^{2^k}$. Recall that elementary functions are the functions computable on a Turing machine in time $O(2_k^n)$, for some k .

The standard results of elementary linear logic [DJ03] still hold in the setting of EAL_{μ} :

- for any integer d , any proof of $\mathbf{N} \multimap !^d \mathbf{N}$ represents an elementary function (*complexity soundness*);
- for any elementary function $f : \mathbb{N} \rightarrow \mathbb{N}$ there exists an integer d and a proof of $\mathbf{N} \multimap !^d \mathbf{N}$ representing it (*extensional completeness*).

Now, by considering alternative types we will be able to delineate more complexity classes:

Theorem 1. *We consider the system EAL_μ .*

- *The functions representable by proofs of $!W \multimap !^2B$ (resp. $!W \multimap !^3B$) are exactly the class P (resp. EXP);*
- *More generally, for any $k \geq 0$, the functions representable by proofs of conclusion $!W \multimap !^{k+2}B$ are exactly the class $k\text{-EXP}$, where:*
 $k\text{-EXP} = \cup_{i \in \mathbb{N}} \text{DTIME}(2_k^{n^i})$, $EXP = 1\text{-EXP}$.

Remark 1. Note that we do not use fixpoints in the final types involved. However, technically speaking the fixpoints are used in the proofs of completeness, in order to simulate polynomial time (resp. k -exponential time) Turing machines, as we will see in Sect. 4.

Observe that as in [Jon01] we are characterizing here predicates and not general functions. We will come back to this point later, in Remark 5.

In the rest of the paper we will prove Theorem 1: Sect. 3 will establish the complexity soundness (proofs with these types represent predicates of the given complexity classes) and Sect. 4 will prove the extensional completeness (all predicates of these complexity classes can be computed by suitable proofs).

3 Proof-nets and complexity soundness

In order to prove the complexity bound we study the cut elimination process and take advantage of the assumption that the conclusion of the proof is of type $!W \multimap !^{k+2}B$ in order to derive a sharper bound. For that, as usual in linear logic it is convenient to use *proof-nets* to analyse cut elimination as proof-net reduction. The proof-nets will use formulas of classical elementary linear logic with fixpoints:

$$A ::= \alpha \mid \alpha^\perp \mid A \otimes A \mid A \wp A \mid !A \mid ?A \mid \mu\alpha.A \mid \bar{\mu}\alpha.A \mid \forall\alpha.A \mid \exists\alpha.A$$

The connectives (modalities) $!$ and $?$ are called *exponentials* and \otimes/\wp are *multiplicatives*.

Formulas of EAL_μ are translated in this grammar by using $A \multimap B \equiv A^\perp \wp B$ and the usual linear logic De Morgan laws for linear negation:

$$\begin{aligned} (A \otimes B)^\perp &\equiv A^\perp \wp B^\perp, & (!A)^\perp &\equiv ?A^\perp, \\ (\mu\alpha.A)^\perp &\equiv \bar{\mu}\alpha.A^\perp, & (\forall\alpha.A)^\perp &\equiv \exists\alpha.A^\perp, & A^{\perp\perp} &\equiv A. \end{aligned}$$

In order to handle weakening we will use proof-nets with polarities, following [AR02]. Note that proof-nets with polarities had been considered before, e.g. in [Lam96], but here we will follow the conventions and notations of [AR02]. The nodes are described on Fig. 2:

- nodes have ports which are positive (dark bullet) or negative (white bullet); an edge can link together either two positive or two negative ports; we say that an edge is positive (resp. negative) if it is connected to a positive (resp. negative) port;

- as the system is affine, the proof-nets use, beside the weakening w-node, also an h-node;
- two nodes μ and $\bar{\mu}$ are added, corresponding resp. to the fixpoint rules R_μ and L_μ ;
- each node ! or ? comes with a !-box, as shown on Fig. 3; two boxes are either disjoint or one is included in the other; the !-node is called the *principal door* of the box and the ?-nodes are its *auxilliary doors*.

One will translate an EAL_μ proof π of conclusion $x_1 : A_1, \dots, x_n : A_n \vdash t : B$ by a graph π^* with conclusions $A_1^\perp, \dots, A_n^\perp, B$ where the edges of the A_i^\perp ($1 \leq i \leq n$) are negative and the edge of B is positive. This translation is standard [Gir87] and we only describe a couple of illustrative cases:

- if π is obtained by an Ax rule, then π^* is an ax -node;
- if π is obtained by a Cut rule between π_1 and π_2 , then π^* is obtained by linking π_1^* and π_2^* by a cut -node;
- if π is obtained by a !-rule on π_1 , then π^* is obtained by applying a !-box on π_1^* (see Fig. 3),

and so on. On Fig. 2 below each node we have indicated the sequent calculus rule it corresponds to. Note that the h -node is not used for this translation; it will only appear during normalisation. Now, a graph R is called a *proof-net* if there exists a proof π such that $R = \pi^*$.

A cut -node between an ax -node (resp. w -node) and another node (resp. another node which is not an ax -node) is called an *axiom cut* (resp. a *weakening cut*). A cut between a \otimes -node and a \wp -node is called a *multiplicative cut*. A cut between a !-node and a ?-node or ?-node (resp. a ?-node) is called an *exponential cut* (resp. a contraction cut). *Quantifier cuts* and μ -cuts are defined in an analogous way.

In a proof-net, a maximal tree with ?-nodes, ax -nodes and w -nodes (of type $?A^\perp$) as leaves, and ?-nodes as internal nodes, is called an *exponential tree*.

Now, given R , the *depth* of a node is the number of exponential boxes containing it, and the depth $d(R)$ of R is the maximal depth of its nodes. Let $|R|_i$ denote the number of nodes at depth i which are not cut nodes, w-nodes or h-nodes. We denote $|R| = \sum_{i=0}^{d(R)} |R|_i$.

Reduction. The reduction procedure on proof-nets consists in eliminating cuts. Because of space constraints we do not give here all reduction rules, but only the most important ones, described on Fig. 4, 5, 6:

- Fig. 5 shows the reduction of exponential cuts (contraction step and box-box step);
- Fig. 6 gives a sample of reduction rules for weakening cuts (notice that one of these steps introduces h -nodes) and cuts on h -nodes; the remaining rules are similar and can be found in [Bai11].

Observe that during a reduction step the depth of an edge does not change, hence the depth of the proof-net does not increase. This is called the *stratification*

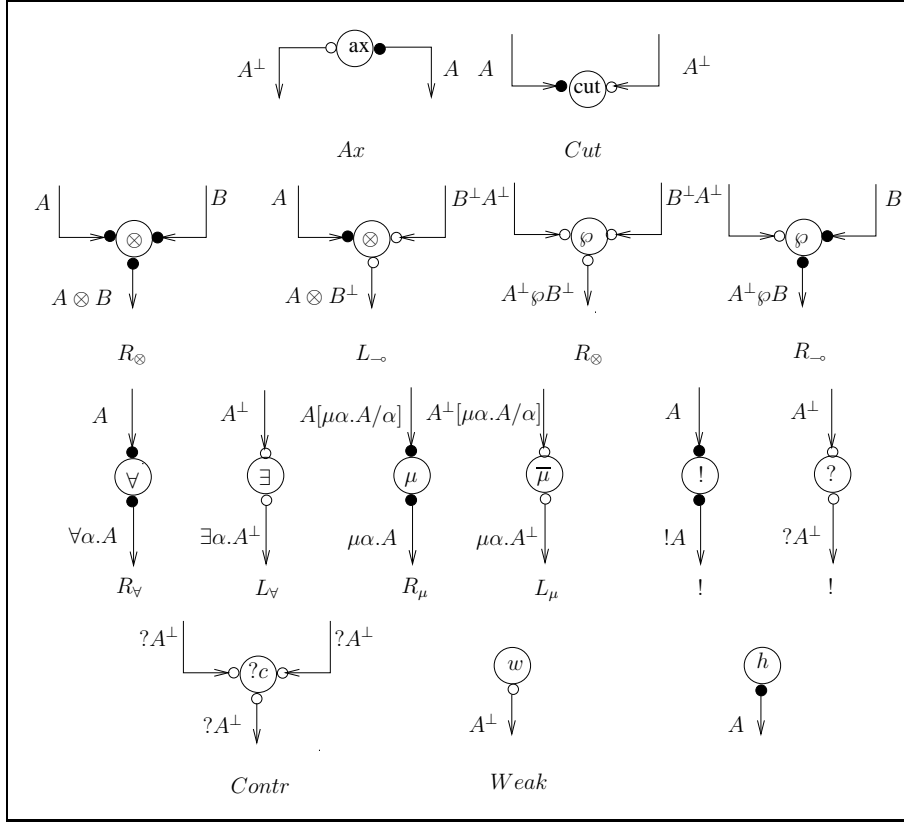


Fig. 2. Nodes of the proof-nets.

property [DJ03] and it is a key ingredient for the complexity properties. It is not valid in ordinary linear logic, and it comes from the fact that during reduction a $!$ -box is not opened and does not enter another box (see Fig. 5).

We say that an exponential cut c is a *special cut* if the box \mathcal{B} corresponding to the $!$ node does not have any cut below its auxiliary doors. The following fact can be easily verified by examining each reduction step other than the contraction reduction step:

Lemma 1. *Let R be a proof-net and R' be obtained from R by reducing a cut at depth i which is not a contraction cut. Then we have $|R'|_i < |R|_i$ and $|R'| < |R|$.*

Now let us briefly recall the method used in [Gir98] to establish complexity bounds on proof-net reduction in light linear logic and elementary linear logic. It uses a specific reduction strategy, obtained by the two following ideas:

- reduce the cuts level-by-level, that is to say first at depth i (*round i*) for i successively equal to $0, 1, \dots, d(R)$;

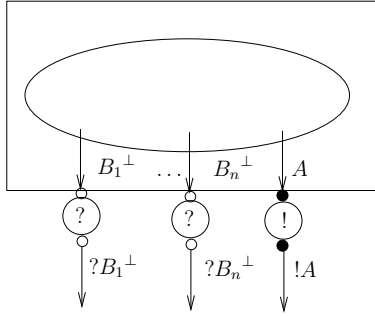


Fig. 3. !-box.

- at a given depth i , proceed in two phases:
 - first reduce cuts that make the size decrease, so in the case of ELL all cuts but the exponential cuts,
 - then reduce the exponential cuts, by repeatedly reducing a *special cut*.

Let us denote by R^i the proof-net at the beginning of round i . In order to bound the number of steps of this reduction strategy, the proof proceeds by, for $i = 0$ to $d(R)$:

- bounding the number of steps of round i by using $|R^i|_i$,
- bounding the size increase, that is to say bounding $|R^{i+1}|_{i+1}$ by using $|R^i|_i$.

Now, here we will essentially adapt the same reduction strategy and methodology for obtaining the bound, with the following modifications:

- on the strategy: we will not perform the reduction until obtaining a normal form (proof-net without cut), but we will stop when we can extract the result;
- on the methodology for obtaining the bound: we will use the assumption that the proof has a conclusion $!\mathbf{W} \multimap !^{k+2}\mathbf{B}$ and we will make a finer analysis of the size increase.

Now let us state the key Lemma that we will use:

Lemma 2 (Size bound). *Let R be a proof-net with:*

- *only exponential and weakening cuts at depth 0,*
- *k cuts at depth 0.*

Let R' be the proof-net obtained by reducing R at depth 0. Then we have:

$$|R'|_1 \leq |R|_0^k \cdot |R|_1.$$

So if we have a bound on the number k of cuts, we obtain a polynomial bound on the size of the proof-net R' after reduction at depth 0. In any case we can bound k by $|R|_0$, but then we basically recover the usual exponential bound [Gir98].

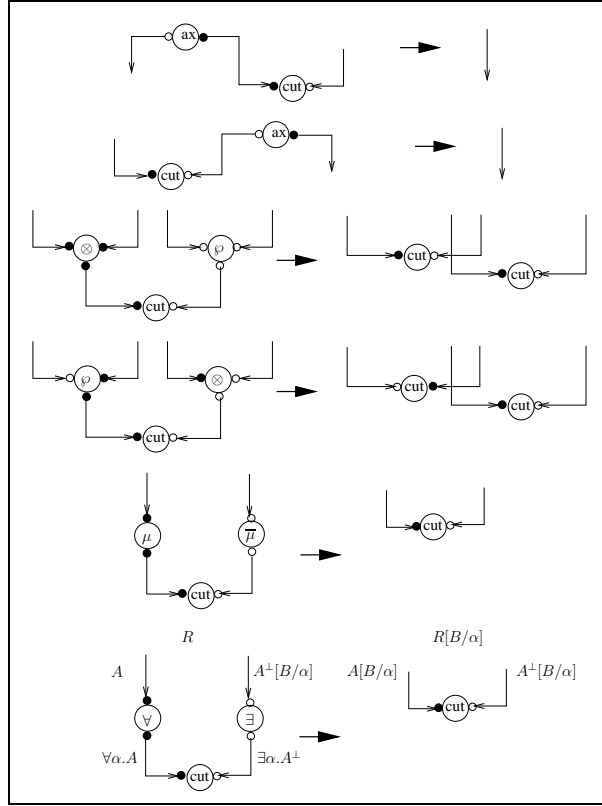


Fig. 4. Reduction steps (1/3).

Proof. We say a contraction node of R at depth 0 is *active* if it is above a cut node. We denote by $|R|_a$ the number of active nodes of R at depth 0. Observe that we have $|R|_a + 1 \leq |R|_0$. We will prove the following statement by induction on k : $|R'|_1 \leq (|R|_a + 1)^k \cdot |R|_1$.

If $k = 0$ the result is trivial. Assume now the result valid for k and consider R with $k + 1$ exponential cuts at depth 0.

First let us consider the case where there is a weakening cut among these $k + 1$ cuts. We then reduce it persistently, following the weakening steps and h -steps of Fig. 6, and we end up with a proof-net R' such that: $|R'|_a \leq |R|_a$, $|R'|_1 \leq |R|_1$ and R' has k cuts at depth 0. We can then apply the induction hypothesis to R' and easily conclude.

Now, consider the case where we have $k + 1$ exponential cuts. Using the correctness criterion one can check (e.g. as in [BP01]) that R admits a *special cut* c , that is to say an exponential cut for which the box \mathcal{B} corresponding to the $!$ node does not have any cut below its auxiliary doors. We completely reduce the cut c , that is to say we reduce c and hereditarily all the cuts of its

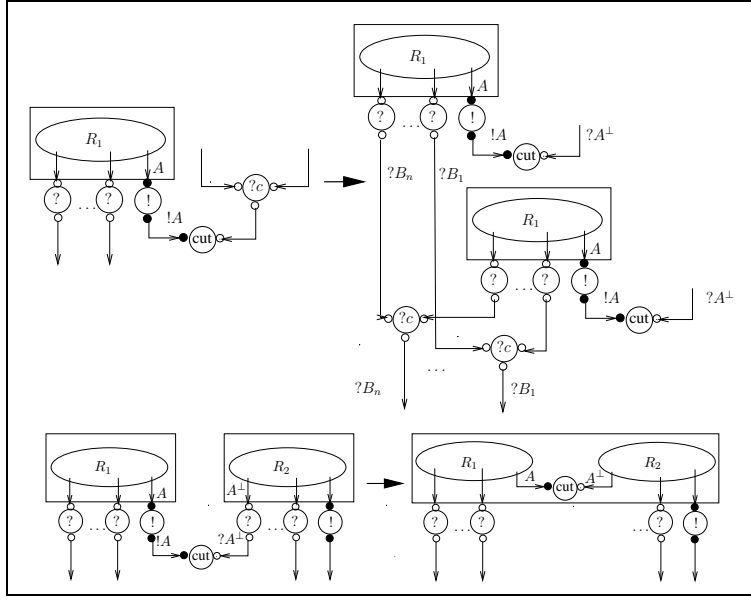


Fig. 5. Reduction steps (2/3).

exponential tree until performing box-box or axiom reduction steps. The increase of size at depth 1 is due to the duplications of the box \mathcal{B} , which is copied at most $|R|_a$ times. Note that no active node is created during these reduction steps, because c is a special cut. We obtain in this way a proof-net R' such that: $|R'|_1 \leq (|R|_a + 1) \cdot |R|_1$, $|R'|_a \leq |R|_a$ and R' has k cuts at depth 0.

Besides, by induction hypothesis we have that R' can be reduced to R'' which is normal at depth 0 and: $|R''|_1 \leq (|R'|_a + 1)^k \cdot |R'|_1$. Combining the inequalities we thus get: $|R''|_1 \leq (|R|_a + 1)^{k+1} \cdot |R|_1$. We conclude by using the fact that $|R|_a + 1 \leq |R|_0$. \square

We will need another result:

Lemma 3 (Readback). *Let R be a proof-net of conclusion \mathbf{B} which only has exponential cuts at depth 0. Given R , one can in constant time decide whether it reduces to true or false.*

The proof of this Lemma takes advantage of the restricted exponentials rules of EAL_μ ; it can be found in [Bai11].

Finally we get:

Proposition 1 (P soundness). *Let R be a normal proof-net of conclusion $!W \vdash !^2B$. Then there exists a polynomial P such that: any proof-net obtained by cutting R with a proof-net representing a word of length n can be evaluated in time bounded by $P(n)$.*

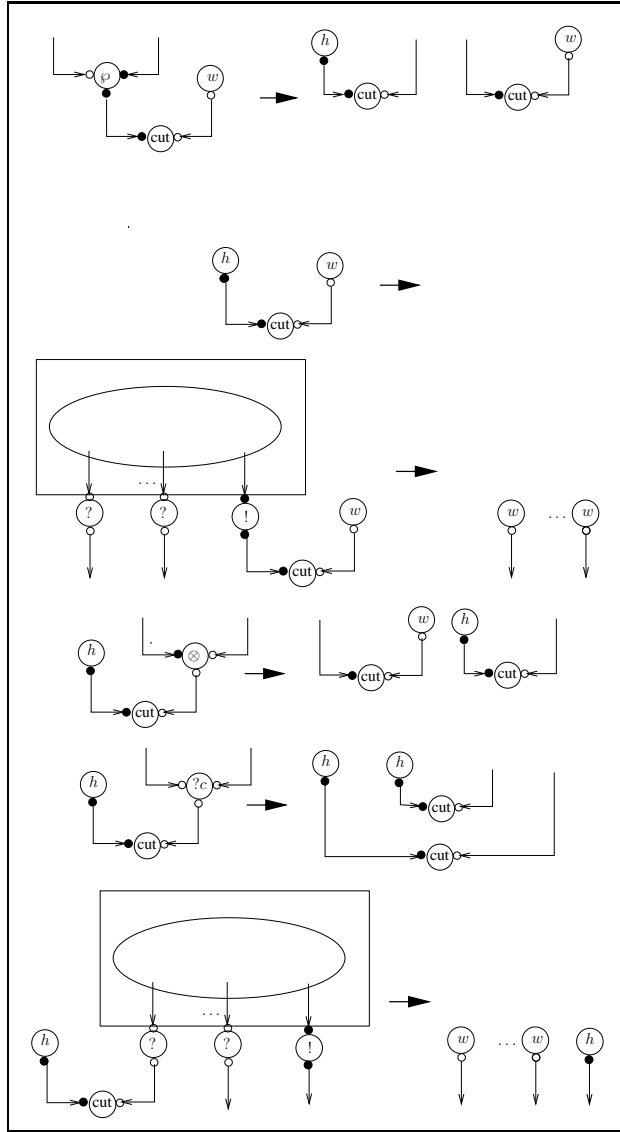


Fig. 6. Reduction steps: sample of weakening and h-steps (3/3).

Proof. First, note that there exists a constant a such that for any n , for any binary word w of length n , w can be represented by a proof-net R_w of size $|R_w| \leq a \cdot n$.

Now, let us examine the structure of R at depth 0. If $?W^\perp$ is obtained by a weakening it is trivial. Otherwise there is an integer $k \geq 1$ and a proof-net S of conclusion $\vdash W^\perp, \dots, W^\perp, !B$ with k formulas W^\perp such that: R is obtained

from S by applying a $!$ -box and a certain number k' of contraction rules on $?W^\perp$ formulas.

Now let R_w be a proof-net representing a word w , and let T be the proof-net obtained by cutting R with a box enclosing R_w . The proof-net T can be reduced in at most $2k'$ steps (at depth 0) into a proof-net T' consisting in a box containing S cut with k copies of R_w . Therefore $|T'| \leq |R| + k \cdot |R_w|$.

Then, since $\mathbf{W} = \forall\alpha.!(\alpha \multimap \alpha) \multimap !(\alpha \multimap \alpha) \multimap !(\alpha \multimap \alpha)$, by applying k quantification reduction steps and $2k$ multiplicative reduction steps (at depth 1) we get a proof-net T'' with not cut at depth 0 and only exponential and weakening cuts at depth 1. Note that there are at most $3k$ exponential cuts at depth 1 and that $|T''| \leq |T'| \leq |R| + k \cdot |R_w|$.

Now by applying Lemma 2 to T'' at depth 1, we get that by reducing T'' at depth 1 we obtain $T^{(3)}$ with no cut at depths 0, 1 and such that $|T^{(3)}|_2 \leq |T''|_1^{3k} \cdot |T''|_2 \leq (|R| + k \cdot |R_w|)^{3k+1}$. The important point to notice here is that $(3k+1)$ does not depend on n .

Finally we perform on $T^{(3)}$, at depth 2, reduction of all cuts but exponential cuts. These only make the size decrease, by Lemma 1, and so the number of steps is bounded by $|T^{(3)}|_2$. We obtain in this way a proof-net $T^{(4)}$ of conclusion $!^2B$, which: (i) does not have any cut at depths 0 and 1, (ii) only has exponential cuts at depth 2.

By Lemma 3, applied here at depth 2, the result can then be computed in constant time. So on the whole the computation has been carried out in a number of steps which is polynomial in $|R_w|$, hence polynomial in n .

Moreover, as the size of each intermediary proof-net in the reduction sequence is polynomially-bounded w.r.t. n , each reduction step can be performed in polynomial time (on a Turing machine), hence the whole reduction is performed in polynomial time. \square

Proposition 2 (k-EXP soundness). *Let R be a normal proof-net of conclusion $!W \vdash !^{k+2}B$. Then there exists a polynomial P such that: any proof-net obtained by cutting R with a proof-net representing a word of length n can be evaluated in time bounded by $2_k^{P(n)}$.*

The proof of Prop. 2 is based on a generalization of the proof of Prop. 1, and needs an extra Lemma. See [Bai11] for more detail.

4 Extensional completeness

To prove the extensional completeness results we will need another datatype using type fixpoints, that of *Scott binary words*:

$$\mathbf{W}_S = \mu\beta.\forall\alpha.(\beta \multimap \alpha) \multimap (\beta \multimap \alpha) \multimap (\alpha \multimap \alpha).$$

Scott words have already been used in several works on implicit complexity [DLB06,BT10,RV10]. One can easily define terms for the basic operations on

binary words over the type \mathbf{W}_S :

$$\begin{aligned} cons_i &= \lambda w. \lambda s_0. \lambda s_1. \lambda x. (s_i w) : \mathbf{W}_S \multimap \mathbf{W}_S && \text{for } i = 0, 1 \\ nil &= \lambda s_0. \lambda s_1. \lambda x. x && : \mathbf{W}_S \\ tail &= \lambda w. (w id id nil) && : \mathbf{W}_S \multimap \mathbf{W}_S \end{aligned}$$

where $id = \lambda x. x$.

For this datatype we can define a term for case distinction on words:

$$\begin{aligned} case &: \forall \alpha. (\mathbf{W}_S \multimap \alpha) \multimap (\mathbf{W}_S \multimap \alpha) \multimap \alpha \multimap (\mathbf{W}_S \multimap \alpha) \\ case &= \lambda F_0. \lambda F_1. \lambda a. \lambda w. (w F_0 F_1 a) \end{aligned}$$

Remark 2. Actually Scott words can also be typed in elementary affine logic, without fixed points, e.g. with the following type: $\forall P. (P \multimap \forall X. ((P \multimap X \multimap P) \multimap P) \multimap P)$. However it is not clear if one could define a *case* function in this setting.

We define the following type representing the configurations of a one-tape Turing machine over a binary alphabet, with n states:

$$\mathbf{Config} = \mathbf{W}_S \otimes \mathbf{B} \otimes \mathbf{W}_S \otimes \mathbf{B}^n$$

Given an element of this type: the first component represents the left part of the tape, in reverse order; the second component represents the symbol scanned by the head ; the third component represents the right part of the tape; the fourth part represents the current state.

Lemma 4. *Let q be a polynomial of $\mathbb{N}[X]$. We have:*

1. *there exists a proof of $!N \multimap !N$ representing the function $q(n)$;*
2. *for any $k \geq 1$, there exists a proof of $!N \multimap !^{k+1}N$ representing the function $2_k^{q(n)}$.*

Lemma 5. *Let \mathcal{M} be a one-tape deterministic Turing machine. One can define:*

$$init : \mathbf{W}_S \multimap \mathbf{Config}, \quad step : \mathbf{Config} \multimap \mathbf{Config}, \quad accept? : \mathbf{Config} \multimap \mathbf{B},$$

such that:

- *given a binary word, $init$ produces the corresponding initial configuration of the machine,*
- *the term $step$ computes one step of the machine on a given configuration,*
- *given a configuration, the term $accept?$ returns true (resp. false) if its state is accepting (resp. rejecting).*

The terms *init* and *accept?* are easy. The term *step* can be constructed based on the transition function of \mathcal{M} , by doing a case distinction, using the term *case*, as in [DLB06] (Sect.7, Lemma 4).

Remark 3. The configuration type of (Asperti Roversi 2002) in LAL does not use type fixpoints and can be directly adapted in EAL (replacing the § connective by !). Let us denote here this EAL type by \mathbf{Config}_C , as it is defined by using a Church encoding of binary words, while \mathbf{Config} is defined by using the Scott encoding:

$$\mathbf{Config}_C = \forall \alpha.!(\alpha \multimap \alpha) \multimap !(\alpha \multimap \alpha) \multimap !(\alpha \multimap \alpha \multimap (\alpha \otimes \alpha \otimes \mathbf{B}^n)),$$

where \mathbf{B}^n is for representing the state of the machine.

Note that \mathbf{Config}_C allows to define a function $step_C$ with the analogous type $\mathbf{Config}_C \multimap \mathbf{Config}_C$. However the corresponding term $accept?_C$ has type $\mathbf{Config}_C \multimap !\mathbf{B}$. It does not seem possible to give a term for this purpose of type $\mathbf{Config}_C \multimap \mathbf{B}$.

This is why we are considering here EAL_μ with type fixpoints, so as to be able to use Scott binary words.

Proposition 3 (Extensional completeness).

1. Let f be a function representing a predicate of \mathbf{P} . There exists a proof of conclusion $!\mathbf{W} \vdash !^2\mathbf{B}$ representing f .
2. Consider $k \geq 1$ and let f be a function representing a predicate of $\mathbf{k}\text{-EXP}$. There exists a proof of conclusion $!\mathbf{W} \vdash !^{k+2}\mathbf{B}$ representing f .

The proof of this Proposition is based on simulations of Turing machines with the corresponding complexity bounds, using the results of Lemmas 4 and 5. See [Bai11] for more detail.

Finally, together the results of Propositions 1, 2 and 3 establish Theorem 1.

Remark 4. Observe that proofs of type $!\mathbf{W} \vdash !^2\mathbf{W}$ do not correspond to polynomial time functions. Indeed, one can easily define a proof *wdouble* of conclusion $\mathbf{W} \multimap \mathbf{W}$ which doubles the length of a word. By using iteration on words, applied here to this *wdouble* proof, one gets a proof *wexp* of conclusion $\mathbf{W} \vdash !\mathbf{W}$, which, given a word of length n , produces a word of length 2^n . Applying the ! rule one thus obtains a proof of $!\mathbf{W} \vdash !^2\mathbf{W}$ with the same behaviour.

To characterize the complexity class \mathbf{FP} of polynomial time functions, one could use the type $!\mathbf{W} \multimap !^2\mathbf{W}_S$, where \mathbf{W}_S is the type of Scott binary words. However a drawback of this characterization is that the proofs representing these functions could not be composed, because of the mismatch on the input and output types.

Remark 5. The proof of the previous theorem could be adapted in EAL (without fixpoint) instead of EAL_μ , by using the type \mathbf{Config}_C of Remark 3, instead of \mathbf{Config} . But as we have the type $accept?_C : \mathbf{Config}_C \multimap !\mathbf{B}$, we would thus get in the end the type $!\mathbf{W} \multimap !^3\mathbf{B}$ for the simulation of a polynomial time machine. This in turn would not provide a \mathbf{P} soundness result.

5 Conclusion and future work

Elementary linear logic was up to now considered as a simple variant of elementary linear logic with good structural properties but of limited interest for complexity. We have shown here that, provided one adds to it type fixpoints, it is expressive enough to characterize P, EXP and a time hierarchy inside the elementary class. An interesting feature is that this provides a single type system in which one characterizes different complexity classes with the same term calculus, simply by considering terms of different types.

Several questions remain open. Is it possible to obtain the same result without type fixpoint? Could one also characterize in this system PSPACE and other space complexity classes in a way similar to [Lei02]? It would also be interesting to examine whether one could re-prove in this purely logical framework some classical hierarchy results, like $P \neq EXP$, by carrying out a diagonalisation argument.

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