

DESCRIBING EVENT STRUCTURES MODELS

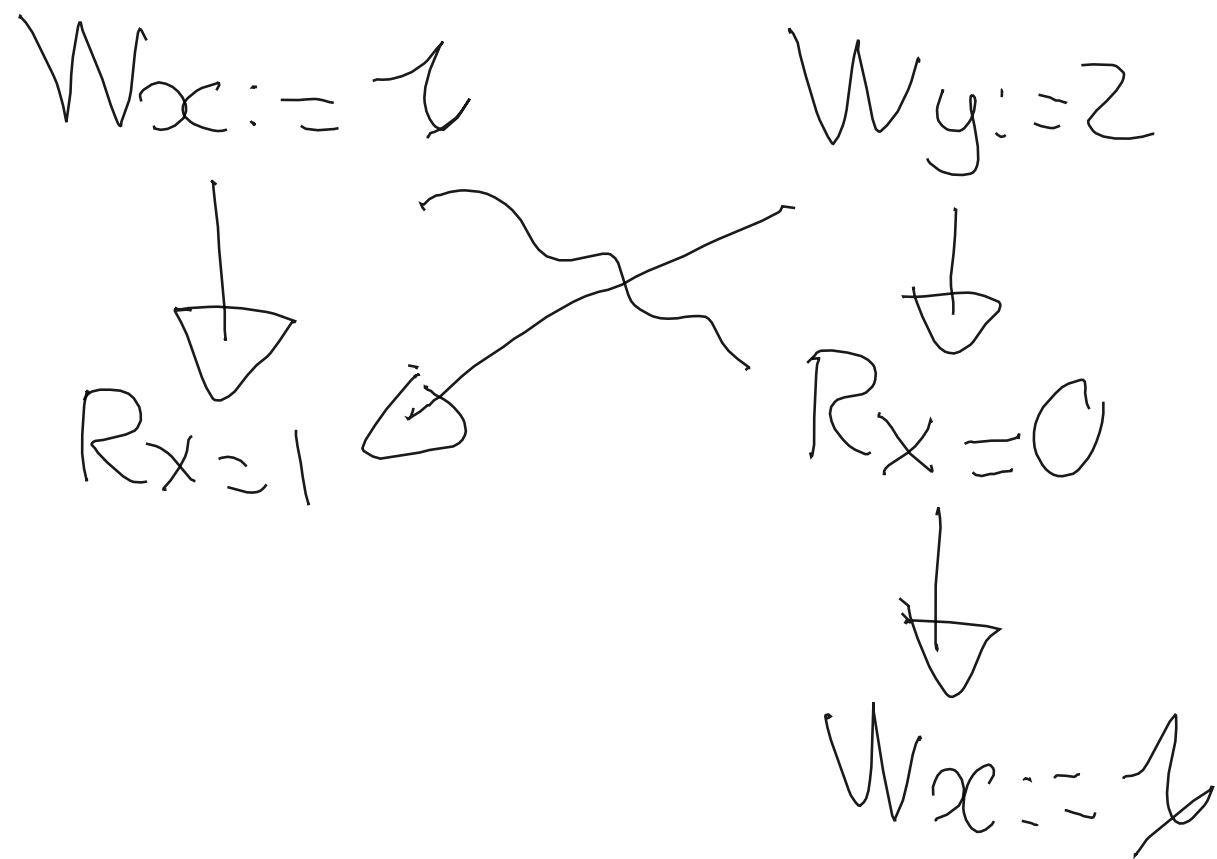
Simon Castellan

Igoria Renros

Concurrent games café⁻

From Programs to Event Structures

$$\llbracket x := 1 \parallel \begin{array}{l} y := 2 \\ \text{read } x \end{array} \rrbracket =$$

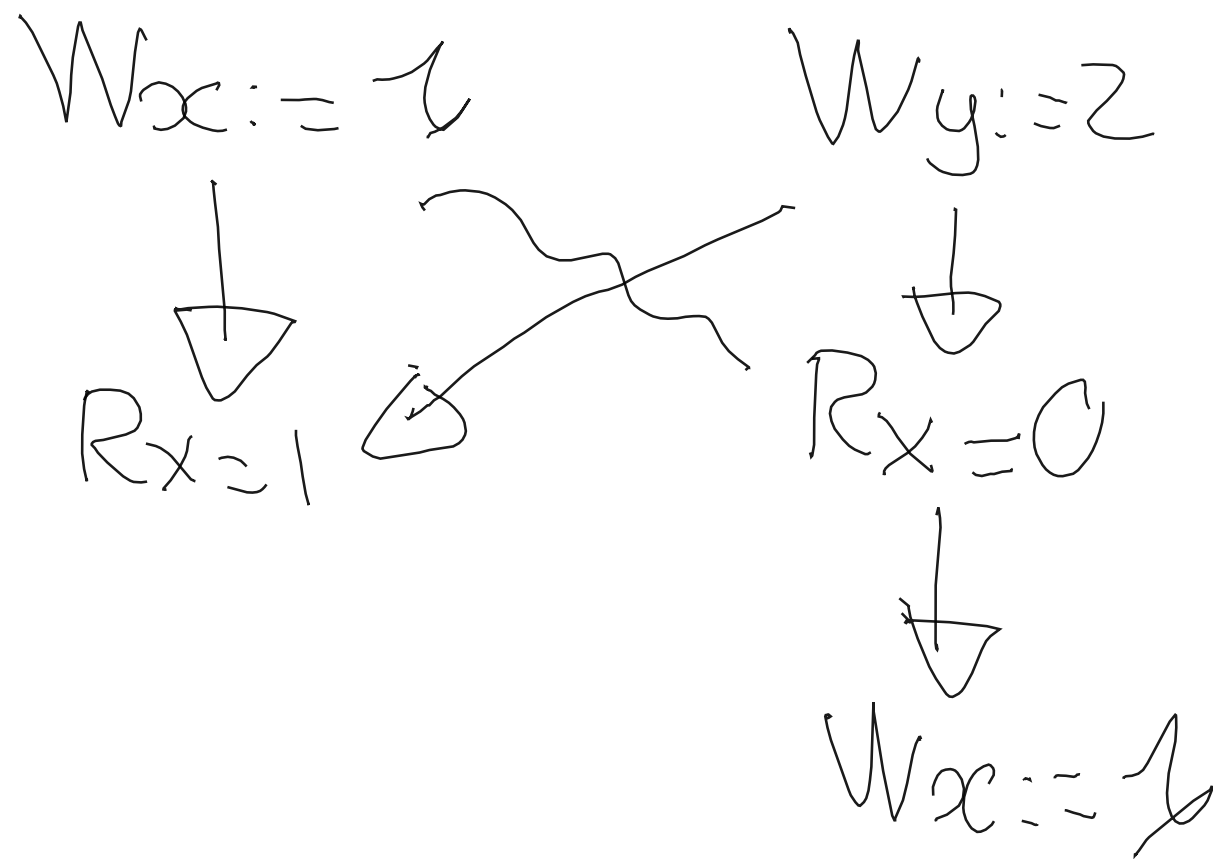


Methodology:

- 1_ Define a suitable space of event structures (labelling, ...)
- 2_ Interpret each language construct by a semantic operation
- 3_ Write a paper

From Programs to Event Structures

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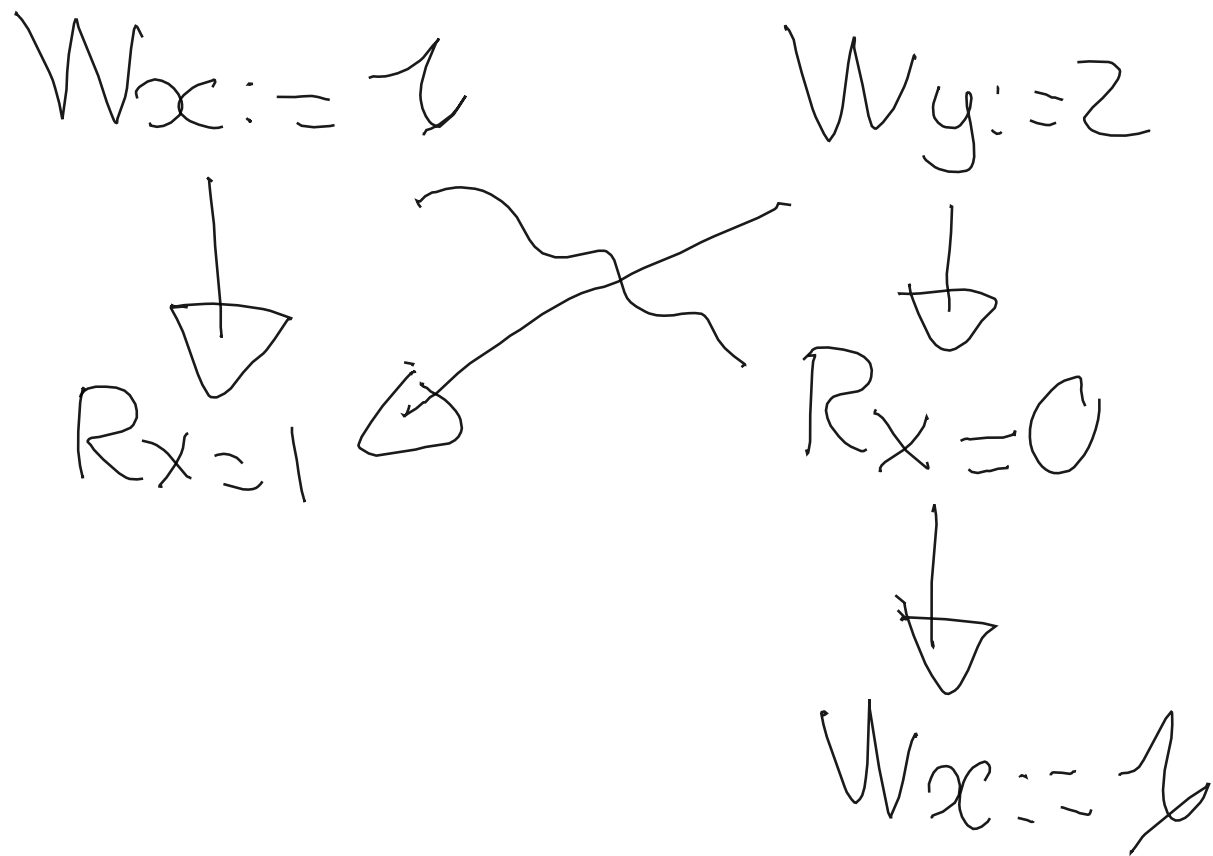


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- 4_ Get rejected: "It's too complicated, also what is a pullback"

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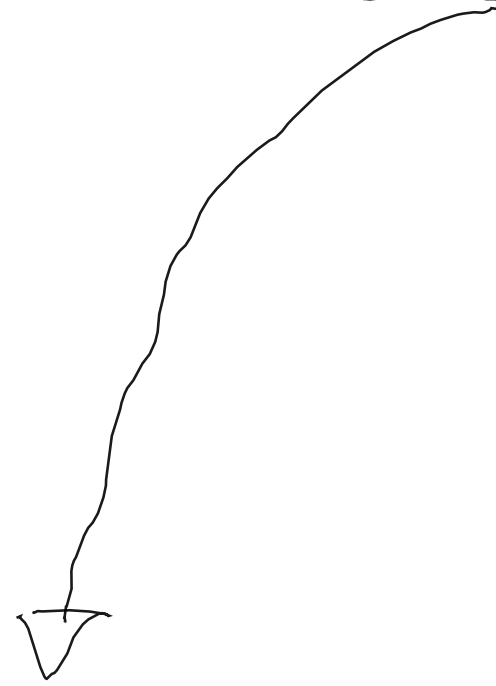
Question: do we need to know what a pullback is?

Composition : a priori , a posteriori

[DIR '92, GT'12, LS'14, Jab'15]

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$$[t \vee u] \stackrel{\text{def}}{=} [t] \wedge [u]$$

Composition : a priori , a posteriori

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$$\llbracket t \vee u \rrbracket \stackrel{\text{def}}{=} \llbracket t \rrbracket \wedge \llbracket u \rrbracket$$

Lemma. $\llbracket t \vee u \rrbracket = \llbracket t \rrbracket \wedge \llbracket u \rrbracket$

Composition : a priori , a posteriori

[DHR '92, GT'12, LS'14, Jab'15]



$$\llbracket t \parallel v \rrbracket \stackrel{\text{def}}{=} \llbracket t \rrbracket \wedge \llbracket v \rrbracket$$

Lemma. $\llbracket t \parallel v \rrbracket = \llbracket t \rrbracket \wedge \llbracket v \rrbracket$

Understanding \parallel is necessary for :

Everything from the interpretation

Soundness of compositional reasoning

Composition: a priori, a posteriori

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What could causal models a posteriori compositional look like?

Compose as early as possible

Interpretation with \wedge

Language

—————→ E.S.

Compose as early as possible

Interpretation with Λ

Language

D.E.S.

Simpler interpretation
with $\tilde{\Lambda}$

Something

Projection

Theorem. $\text{project}(t \tilde{\Lambda} u) = \text{project } t \wedge \text{project } u$

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Projection

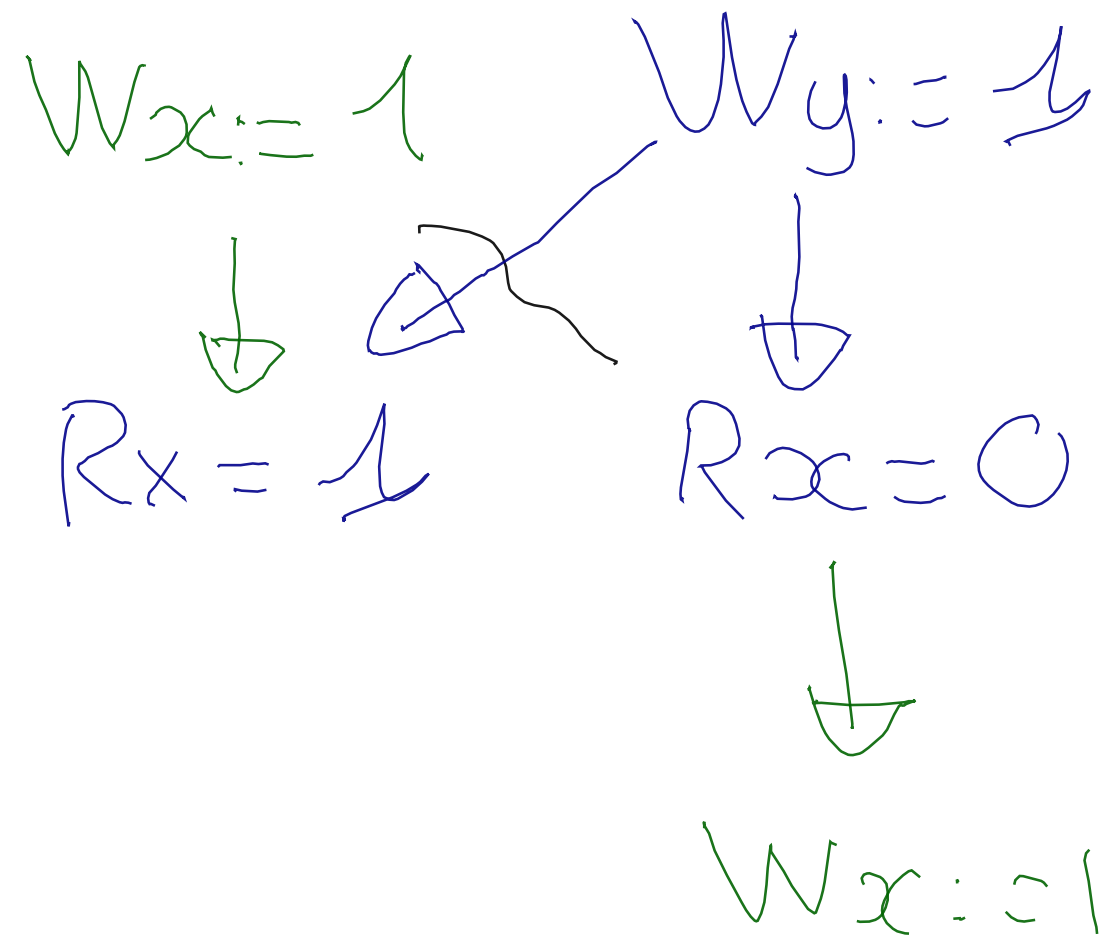
Theorem. $\text{project}(t \tilde{\Lambda} u) = \text{project } t \wedge \text{project } u$

Benefits :

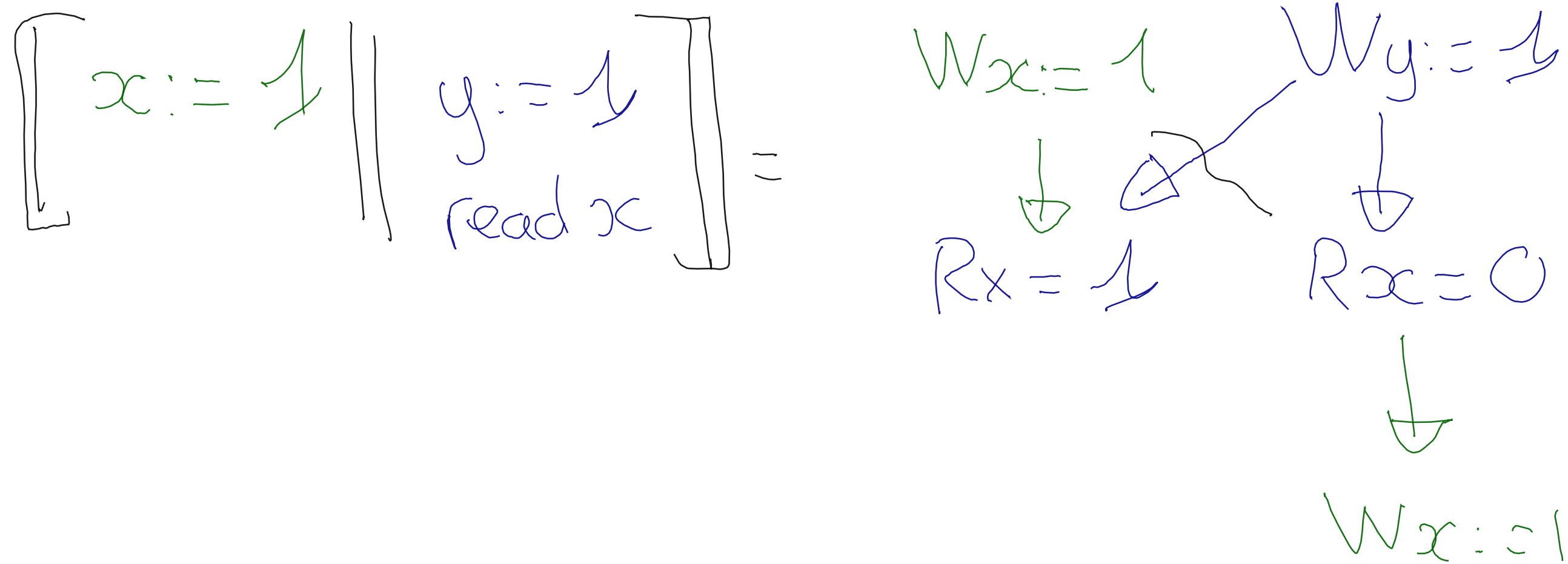
- simplicity
- implementability / performance (avoid computing Λ)

Causal models: why is it so hard?

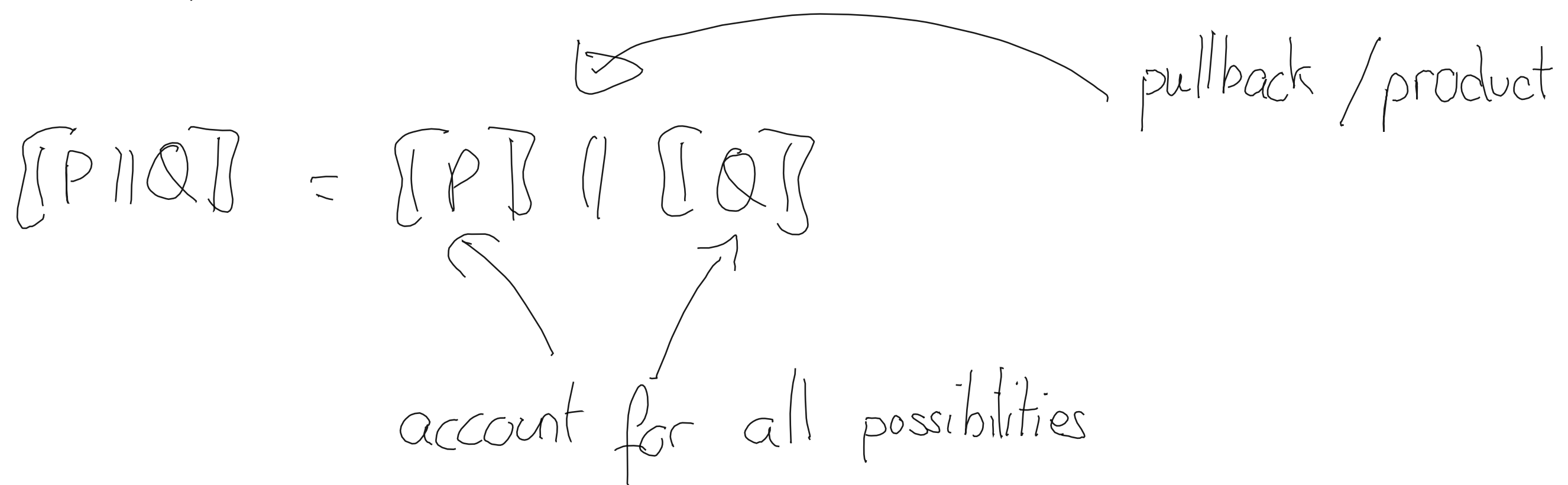
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Causal models: why is it so hard?



Standard interpretation:



→ Alternative description?

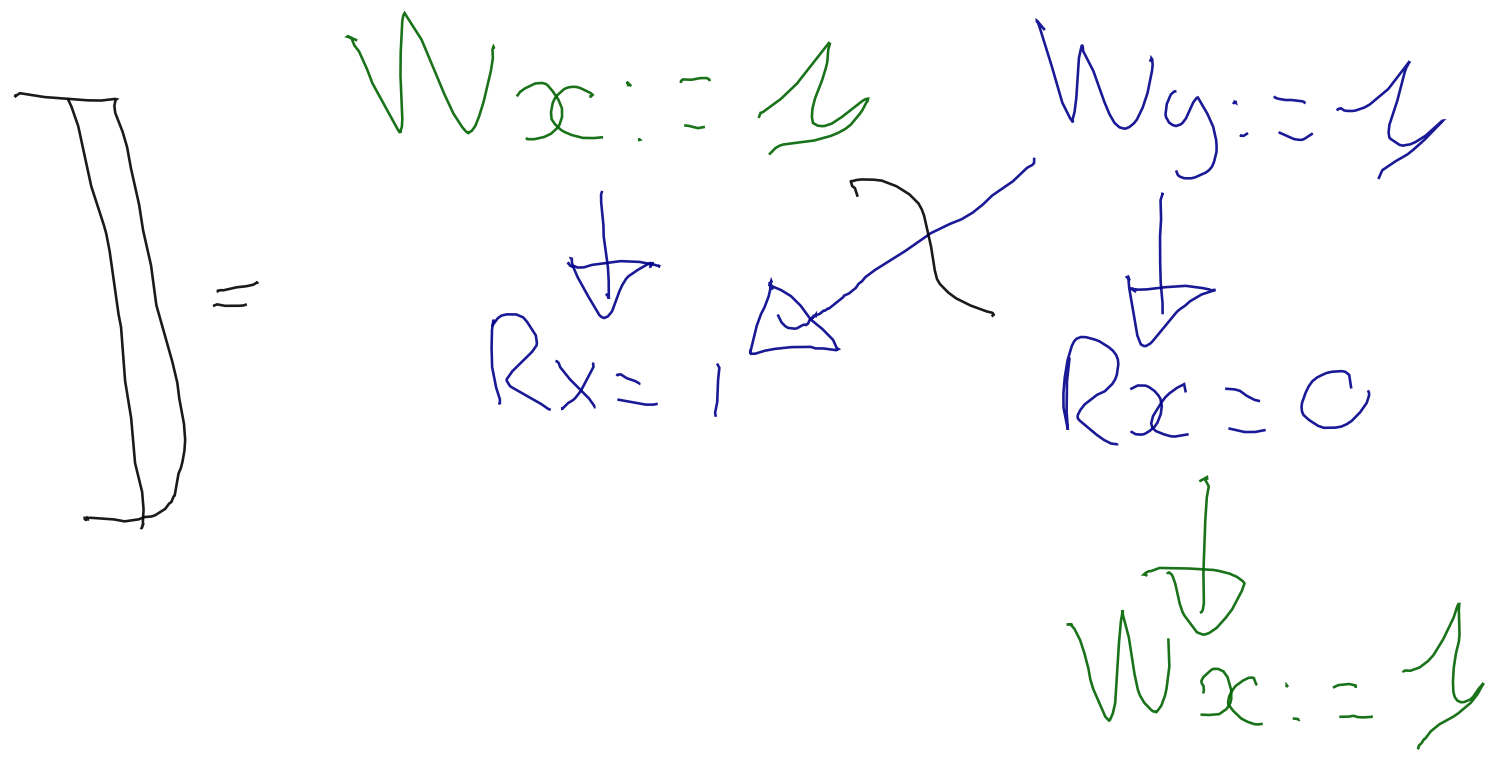
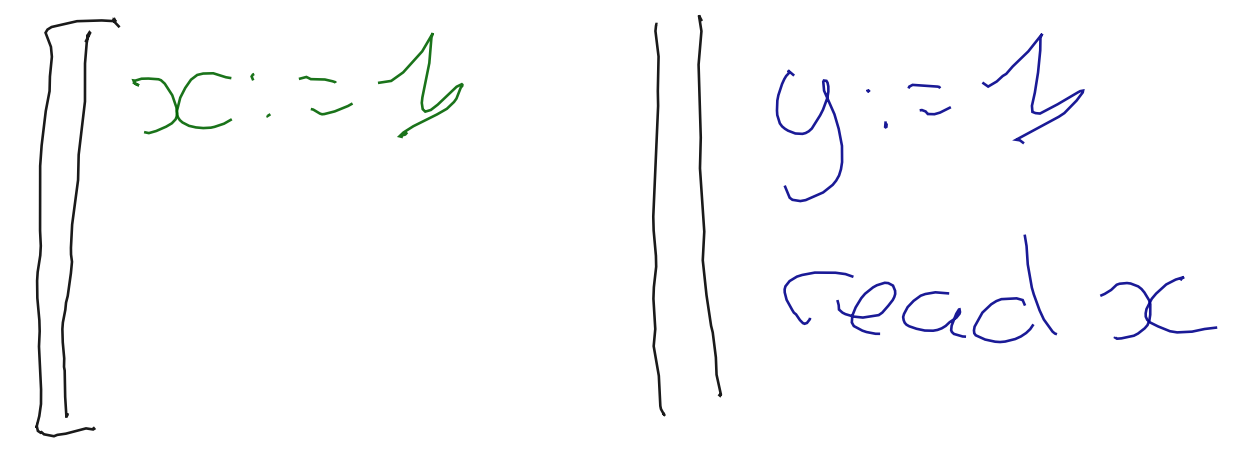
Incrementality

$$\left[\begin{array}{l} x := 1 \\ \parallel \\ y := 1 \\ \text{read } x \end{array} \right] =$$

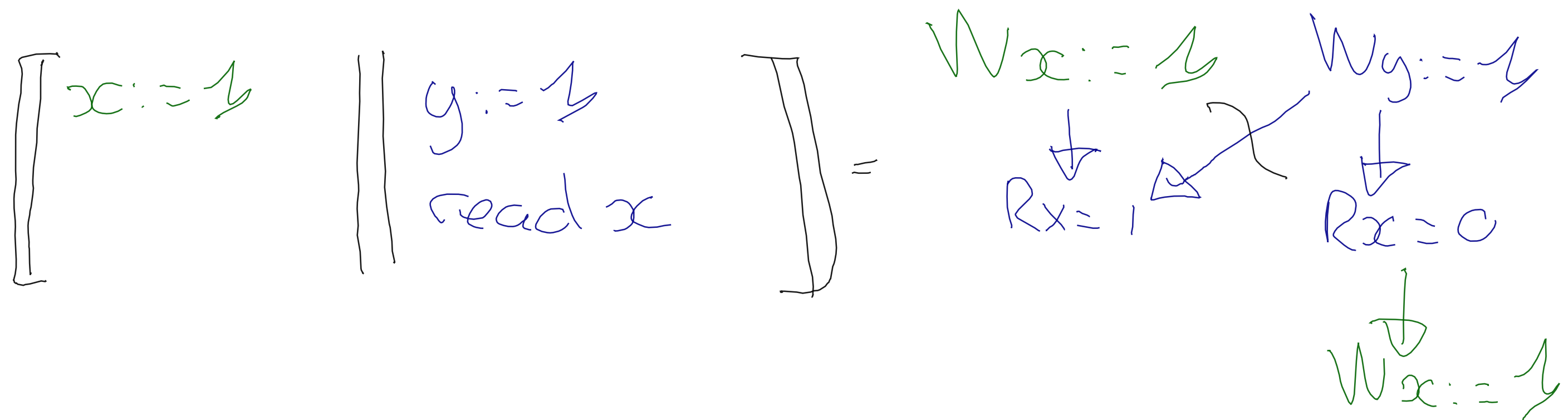
Incrementality

 $\boxed{x := 1}$ \parallel
 $\boxed{\begin{array}{l} y := 1 \\ \text{read } x \end{array}}$ $=$ $\forall x := 1$ $\forall y := 1$ \downarrow $Rx = 0$

Incrementality



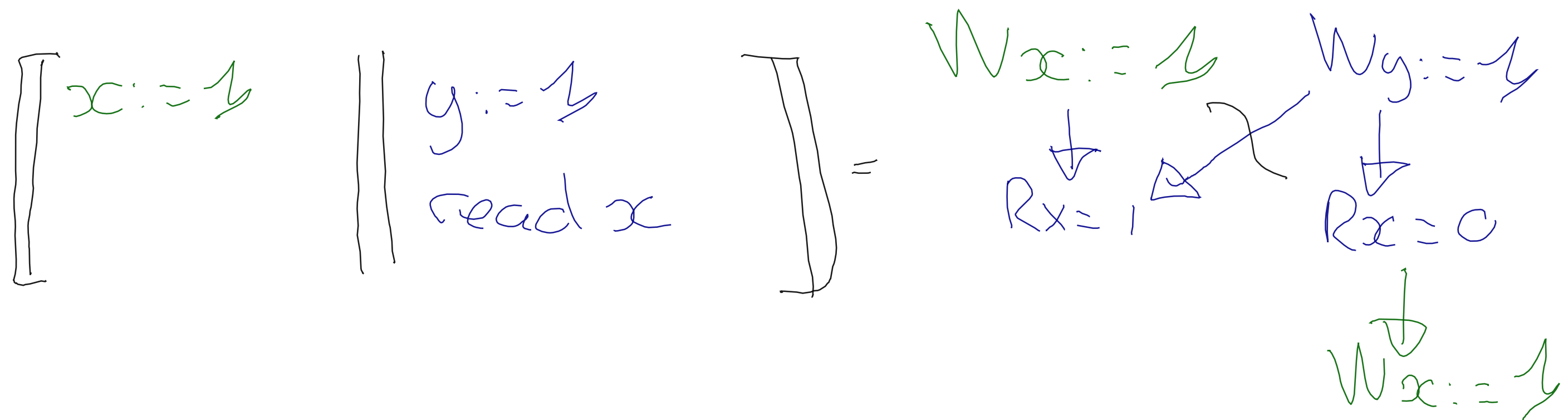
Incrementality



💡 Model programs by closure operators à la Abramsky-Melliès

$$\begin{aligned} \llbracket P \rrbracket : (ES, \subseteq) &\rightarrow (ES, \subseteq) \text{ with} \\ \mathcal{E} &\subseteq \llbracket P \rrbracket(\mathcal{E}) & \llbracket P \rrbracket \circ \llbracket P \rrbracket &= \llbracket P \rrbracket \end{aligned}$$

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Example:

$$\llbracket x := 1 \rrbracket(\mathcal{E}) := \mathcal{E} \cup \left\{ Wx := 1 \right\} \cup \left\{ Wx := 1 \right\}$$

$o \in \mathcal{E}$
 $\text{Var}(o) = X$

Alternative description of event Structures

$(E, \leq_E, \#_E)$



binary relations
not a local property
on events

Alternative description of event Structures

$$(E, \leq_E, \#_E) \rightsquigarrow \left(E, \text{view} : E \rightarrow \mathcal{P}_{\text{fin}}(E), \text{world} : E \rightarrow W \right)$$

↑ ↑
binary relations
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(W, \leq) a partial order
of worlds (abstract configurations)

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$$(W = (\mathcal{P}(E), \subseteq))$$

$$(E, \text{view}, \text{world}) \longmapsto (E, \leq_E, \#_E)$$

$$e \leq_E e' \Leftrightarrow e \in \text{view}(e')$$

$$e \#_E e' \Leftrightarrow \text{world}(e) \vee \text{world}(e') \text{ undefined}$$

↑
join in the partial order

Writing down closure operators

Consider (W, \leq) a partial order of worlds

Our domain for closure operators

Event := Label \times $\mathcal{P}(\text{Event}) \times W$

D := $\mathcal{P}(\text{Event})$

[there is a partial $D \rightarrow ES$]

Writing down closure operators

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$$D := \mathcal{P}(\text{Event})$$

[there is a partial $D \rightarrow ES$]

With $W =$ set of memory traces on x ordered by prefix:

$$\llbracket x := \perp \rrbracket (\mathcal{E}) := \mathcal{E} \cup \left\{ (W_{x := \perp}, \emptyset, W_{x := \perp}) \right\}$$

$$\cup \cup_{e = (l_x, v, w) \in \mathcal{E}} \left\{ (W_{x := \perp}, w \cup \{e\}, w \cdot W_{x := \perp}) \right\}$$

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action

$$\cup \cup_{e = (o_x, v, w) \in \mathcal{E}} \left\{ (Wx := \perp, w \cup \{e\}, w \cdot Wx := \perp) \right\}$$

reaction

updating the world

Increasing maps & closure operators

$f: \mathcal{P}(E) \rightarrow \mathcal{P}(E)$ is increasing when it is monotonic & $X \subseteq f(X) \forall X \subseteq E$

\leadsto A closure operator f is an increasing map s.t. $f \circ f = f$

Lemma. For each increasing $f: \mathcal{P}(E) \rightarrow \mathcal{P}(E)$ there exists
[a least closure operator f^∞ containing f

$$f^\infty(X) = \lim (X \subseteq f(X) \subseteq f^2(X) \subseteq \dots)$$

Following [AM'11], we define for f, g closure operators on $\mathcal{P}(E)$:

$$f \parallel g := (f \cup g)^\infty = (f \circ g)^\infty = (g \circ f)^\infty$$

Writing down closure operators (2)

In general: Local history when P is invoked

$$[[P]]: \underbrace{\text{View} \times \text{World}}_{P(E)} \rightarrow [D \rightarrow D] := \text{Comp}$$

What are the operations we use to describe such objects?

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① Emitting an event: $\text{emit}(l \in \text{Label}) = \lambda(\sigma, \omega). \lambda \xi. \xi \cup \{(P, \sigma, \omega)\}$

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② Inspecting existing events

$$\text{inspect} (c: \text{Label} \rightarrow \text{Comp}) := \lambda(\sigma, \omega). \left(\lambda \varepsilon. \varepsilon \cup \bigcup_{\substack{(l, \sigma', \omega') \\ \omega \vee \omega' = \overline{\omega}}} c l (\sigma \cup \sigma', \overline{\omega}) (\varepsilon) \right)$$

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③ Manipulating the world: $(\text{set } w; f) (\sigma, -) = f(\sigma, w)$

II. A process calculus

Source $\text{---} \rightarrow$ Process Calculus $\xrightarrow{[\cdot]}$ C.O. \longrightarrow E.S.

A process calculus inspired with the model.

Basic idea : emit \rightarrow sending a message

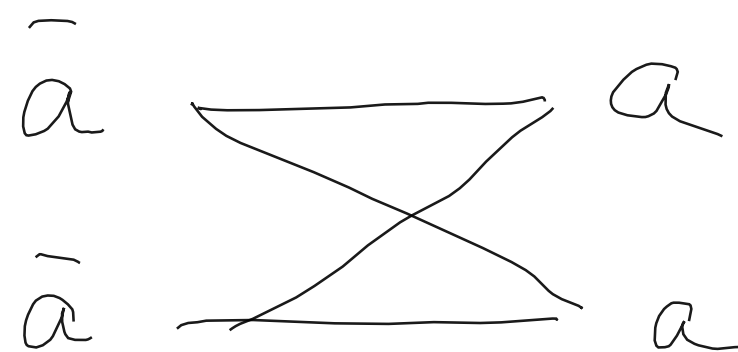
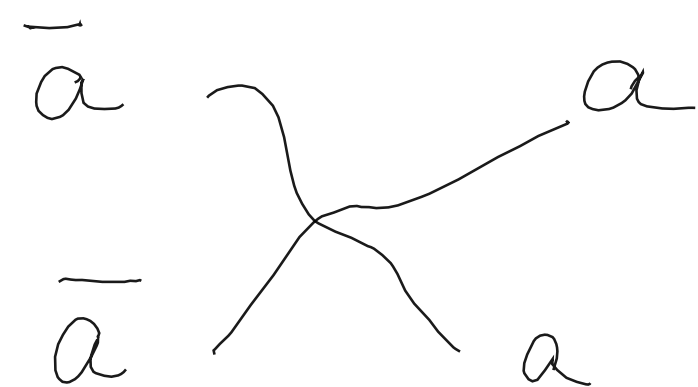
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Basic idea : emit \rightarrow sending a message

inspect \rightarrow receiving a message

⚠ Unusual semantics : "deterministic channels"



CCS

Our model

Terminology : sending \Rightarrow put

receiving \Rightarrow watch

Syntax

Let A be a set of names, and $\gamma \in Env := A \rightarrow Set$

We define by induction $\gamma \vdash P$

$$\frac{}{\gamma \vdash 0}$$

$$\frac{\gamma \vdash P \quad \gamma \vdash Q}{\gamma \vdash P \parallel Q}$$

$$\frac{\gamma, a: X \vdash P}{\gamma \vdash (\text{va}: X)P}$$

$$\frac{v \in \gamma(a) \quad \gamma \vdash P}{\gamma \vdash \text{put } a \text{ v. } P}$$

$$\frac{\forall v \in \gamma(a): \gamma \vdash P_v}{\gamma \vdash \text{watch } a \text{ } (P_v)_{v \in \gamma(a)}}$$

$$\frac{\forall w \in W: \gamma \vdash P_w}{\gamma \vdash \text{get. } (P_w)_{w \in W}}$$

$$\frac{\gamma \vdash P \quad w \in W}{\gamma \vdash \text{set } w. P}$$

Parameter: (W, \leq)

$$\text{Proc } \gamma = \{P \mid \gamma \vdash P\}$$

Semantics

$$\text{Msg } \gamma := \sum_{a \in A} \gamma(a) \times \mathcal{P}_{\text{fin}}(\text{Msg } \gamma) \times \text{World}$$

$$\text{State } \gamma := \mathcal{P}(\text{Msg } \gamma) \quad [\text{Linear model}]$$

$$[\gamma]_P: \mathcal{P}_{\text{fin}}(\text{Msg } \gamma) \times \text{World} \rightarrow \text{Closure operator on State } \gamma$$

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$$\llbracket \gamma \vdash P \rrbracket: \mathcal{P}_{\text{fin}}(\text{Msg } \gamma) \times \text{World} \rightarrow \text{Closure operator on State } \gamma$$

Examples:

$$\llbracket \gamma \vdash \text{put } a \text{ v. } P \rrbracket (h, w) := \text{let } e = (a, v, h, w) \text{ in} \\ \lambda \Xi. \Xi \cup \{e\} \cup \llbracket \gamma \vdash P \rrbracket (h \cup \{e\}, w)(\Xi)$$

$$\llbracket \gamma \vdash \text{watch } a \text{ (w. } P_v) \rrbracket (h, w)(\Xi) :=$$

$$\Xi \cup \bigcup_{\substack{(a, v', h', w') \in \Xi \\ w \vee w' = \bar{w}}} \llbracket \gamma \vdash P \rrbracket (w \cup w', \bar{w})(\Xi)$$

Equivalence

$$P \approx Q \quad := \quad \llbracket P \rrbracket = \llbracket Q \rrbracket$$

$$(vb) \left(\text{put } b \ 1 \parallel \text{put } b \ 2 \parallel \text{watch } b \ (\lambda v. \text{put } a \ v) \right. \\ \left. \parallel \text{watch } b \ (\lambda v. \text{put } a \ v) \right)$$

$$(vc) (vb) \left(\text{put } b \ t \parallel \text{put } b \ ff \parallel \text{watch } b \ (\lambda v. \text{if } v \text{ then put } a \ 1 \\ \text{else watch } a \ (\lambda c. \text{put } c \ 1)) \right)$$

final state : an event structure

Given $\gamma \vdash P$, we define

$\mathcal{E}(P) = \llbracket P \rrbracket(\emptyset, \emptyset)(\emptyset)$ an event structure if P is correct

$\mathcal{E}(\text{put } a \perp \parallel \text{watch } a \text{ (rm. put } a \text{ (n+1))})$

Expressivity of the language

Able to encode:

- linearisable datatypes (eg. shared reference)

World: memory trace

- CCS/ π channels

World: partial bijections between output and input prefixes

Clean separation between communication / nondeterminism

Implementation

Goal: compute $\mathcal{E}(P)$

→ Model induces a lot of redundant computation at each iteration

However, we can look at normal forms upto \approx :

$$N := (\vec{v}a) \left(\underbrace{\text{put } \vec{a} \vec{v}}_{\text{initial state}} \parallel \underbrace{\text{watch } \vec{a} \vec{N}}_{\text{handlers}} \right)$$

$\mathcal{E}(P)$ can be computed via a transition system on normal forms

avoiding repetition

III. A monad for truly
concurrent computation



From programming languages to process calculi

$$\Gamma \vdash \Pi : \sigma \longrightarrow \Downarrow \llbracket \Gamma \vdash \Pi : \sigma \rrbracket : (0 \notin \text{dom } \gamma) \longrightarrow \text{Proc}(\llbracket \Gamma \rrbracket, 0 : \llbracket \sigma \rrbracket)$$

$$\llbracket e_1 + e_2 \rrbracket 0 = (\text{val } a) \left(\llbracket e_1 \rrbracket a \mid \text{watch } a \left(\lambda m_1. \llbracket e_2 \rrbracket b \right. \right. \\ \left. \left. \mid \text{watch } b \left(\lambda m_2. \text{put } 0(m_1 + m_2) \right) \right) \right)$$

Syntactic counterpart of composition in denotational semantics

$$\llbracket e_1 + e_2 \rrbracket = \text{add } \odot \langle \llbracket e_1 \rrbracket, \llbracket e_2 \rrbracket \rangle$$

From programming languages to process calculi

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Syntactic counterpart of composition in denotational semantics

$$\llbracket e_1 + e_2 \rrbracket = \text{add } \odot \langle \llbracket e_1 \rrbracket, \llbracket e_2 \rrbracket \rangle$$

Unsatisfactory:

Bad performance (each communication takes one iteration in the closure)

Translation hard to read and write

A simple remark

Defining $T_\gamma : \text{Set}_\omega \rightarrow \text{Set}_\omega$

$$X \mapsto (\sigma \notin \text{dom } \gamma) \rightarrow \text{Prce}(\gamma, \sigma : X)$$

This is a monad (up to \approx):

- return $x = \lambda \sigma. \text{put } \sigma x$

- bind $m f = \lambda \sigma. (\text{va}) (m a \mid \text{watch } a (\lambda \sigma. f \sigma \sigma))$

We can write now simple monadic interpreters:

$$\llbracket \Gamma + \Gamma; \sigma \rrbracket : T_{\llbracket \Gamma \rrbracket} (\llbracket \Gamma \rrbracket)$$

A simple remark

Defining $T_\gamma : \text{Set}_\omega \rightarrow \text{Set}_\omega$
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$\llbracket \Gamma + \Pi : \sigma \rrbracket : T_{\llbracket \Pi \rrbracket} (\llbracket \Gamma \rrbracket)$

$\llbracket e_1 + e_2 \rrbracket = \llbracket e_1 \rrbracket \gg = \lambda m_1.$

$\llbracket e_2 \rrbracket \gg = \lambda m_2.$

return $(m_1 + m_2)$

A simple remark

Defining $T_\gamma : \text{Set}_\omega \rightarrow \text{Set}_\omega$
 $X \mapsto (\sigma \notin \text{dom } \gamma) \rightarrow \text{Proc}(\gamma, \sigma : X)$

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$\llbracket e_2 \rrbracket \gg = \lambda m_2.$

return $(m_1 + m_2)$

\leadsto Trick works with most process calculi

But this is not completely trivial

We can actually define `bind` by induction on `m`:

$$\text{bind} (\lambda x. \text{put } 0 \ x. P) f = f\ x \parallel \text{bind} (\lambda x. P) f$$

$$\text{bind} (\lambda x. P \parallel Q) f = \text{bind} (\lambda x. P) f \parallel \text{bind} (\lambda x. Q) f$$

⋮

⇒ The information flow is now occurring at the meta level
(i.e. the language in which the interpreter runs)

⇒ Interpreting a sequential language incurs very little overhead
(w.r.t. to a sequential interpreter)

Operations of the monad

$$\text{watch} : A \rightarrow T_Y(\gamma(a))$$

$$\text{put} : (a : A) \rightarrow \gamma(a) \rightarrow T_Y(A)$$

$$\text{get} : T_Y(W)$$

$$\text{set} : W \rightarrow T_Y(\perp)$$

$$\parallel : T_Y(X) \times T_Y(X) \rightarrow T_Y(X)$$

$$\text{join} : T_Y(X) \times T_Y(Y) \rightarrow T_Y(X \times Y)$$

[derived]

The reference implementation: Causality

→ Monad implemented in OCaml

→ On top of it: references, channels

With monadic syntax, causal interpreters look like regular interpreters

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→ On top of it: references, channels

With monadic syntax, causal interpreters look like regular interpreters

Causal OCaml: an implementation of concurrent games of OCaml

Architecture:

- Monadic translation à la Moggi
- Game semantics used for sending/receiving functions on a channel.
 - depends only on values, not the whole AST

Conclusion

- * A monadic framework to write causal interpreters
Aim: explore interactively the causal behaviour of programs
- * No proofs written yet: formalisation of certain tricks used by the implementation is difficult
- * In the future: model complex language, eg. weak memory specs
approximate the model
formal link with the game semantics as we know it

