The Leader Election Protocol (IEEE 1394)

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- Background :-)
- An informal presentation of the protocol :-)
- Step by step formal design :-
- Short Conclusion. :-)

IEEE 1394 High Performance Serial Bus (FireWire)

- It is an international standard
- There exists a widespread commercial interest in its correctness
- Sun, Apple, Philips, Microsoft, Sony, etc involved in its development
- Made of three layers (physical, link, transaction)
- The protocol under study is the Tree Identify Protocol
- Situated in the Bus Reset phase of the physical layer

The Problem (1)

- The bus is used to transport digitized video and audio signals
- It is "hot-pluggable"
- Devices and peripherals can be added and removed at any time
- Such changes are followed by a bus reset
- The leader election takes place after a bus reset in the network
- A leader needs to be chosen to act as the manager of the bus

- After a bus reset: all nodes in the network have equal status
- A node only knows to which nodes it is directly connected
- The network is connected
- The network is acyclic

BASIC

- IEEE. *IEEE Standard for a High Performance Serial Bus. Std* 1394-1995. 1995
- IEEE. *IEEE Standard for a High Performance Serial Bus (supplement). Std* 1394a-2000. 2000

GENERAL

- N. Lynch. *Distributed Algorithms*. Morgan Kaufmann. 1996
- R. G. Gallager et al. *A Distributed Algorithm for Minimum Weight Spanning Trees.* IEEE Trans. on Prog. Lang. and Systems. 1983.

MODEL CHECKING

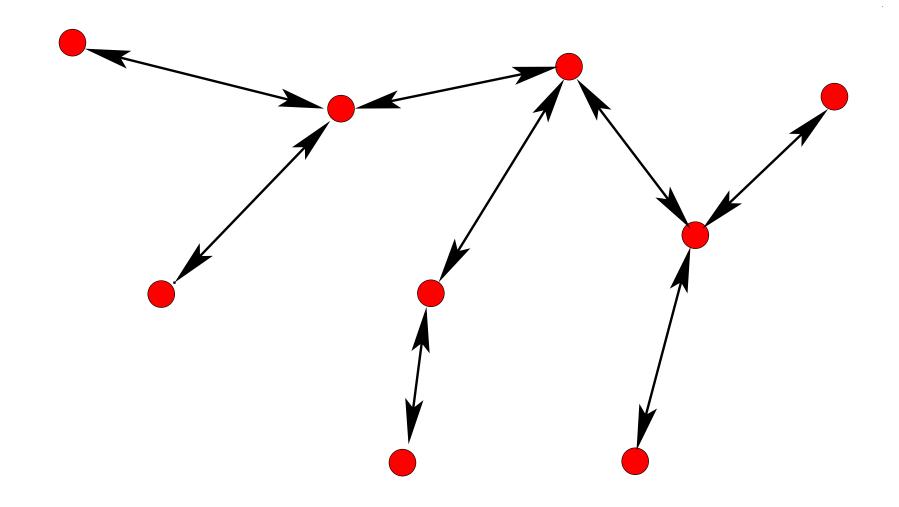
- D.P.L. Simons et al. *Mechanical Verification of the IEE 1394a Root Contention Protocol using Uppaal2* Springer International Journal of Software Tools for Technology Transfer. 2001
- H. Toetenel et al. Parametric verification of the IEEE 1394a Root
 Contention Protocol using LPMC Proceedings of the 7th International
 Conference on Real-time Computing Systems and Applications. IEEE
 Computer Society Press. 2000

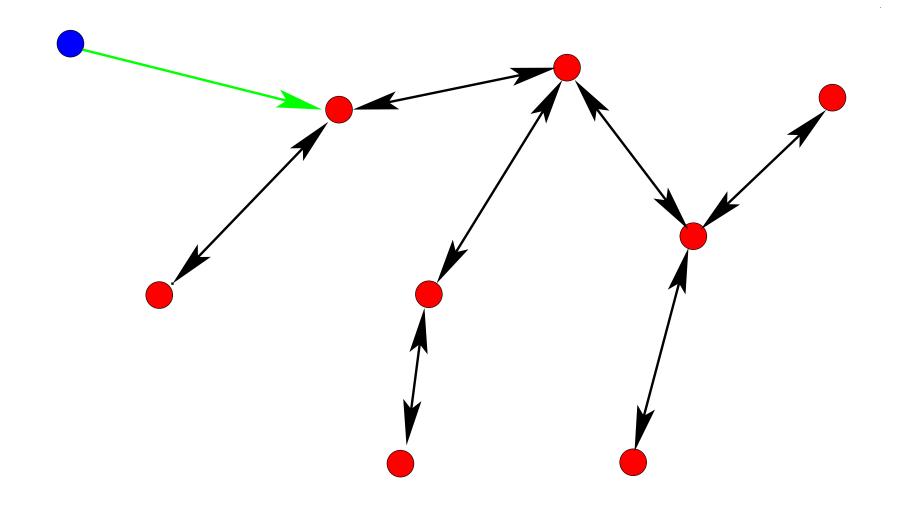
THEOREM PROVING

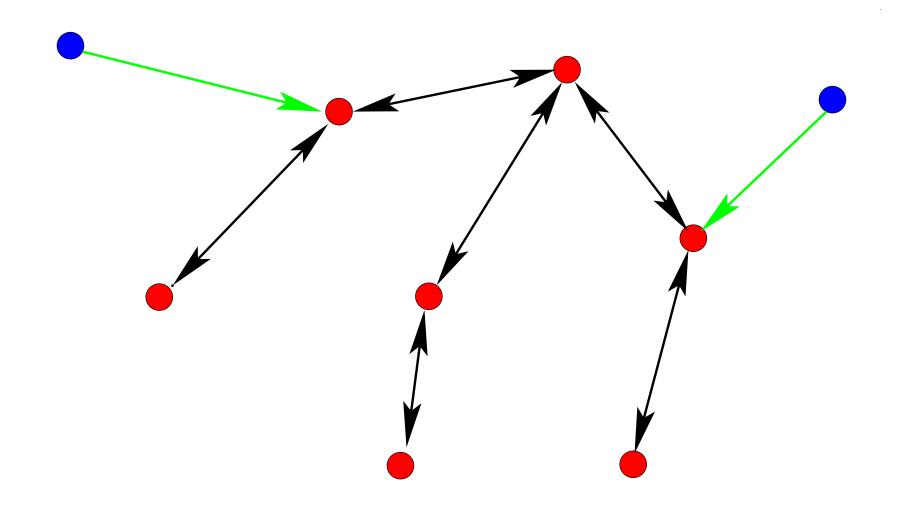
- M. Devillers et al. *Verification of the Leader Election: Formal Method Applied to IEEE 1394.* Formal Methods in System Design. 2000
- J.R. Abrial et al. *A Mechanically Proved and Incremental Development of IEEE 1394*. To be published 2002

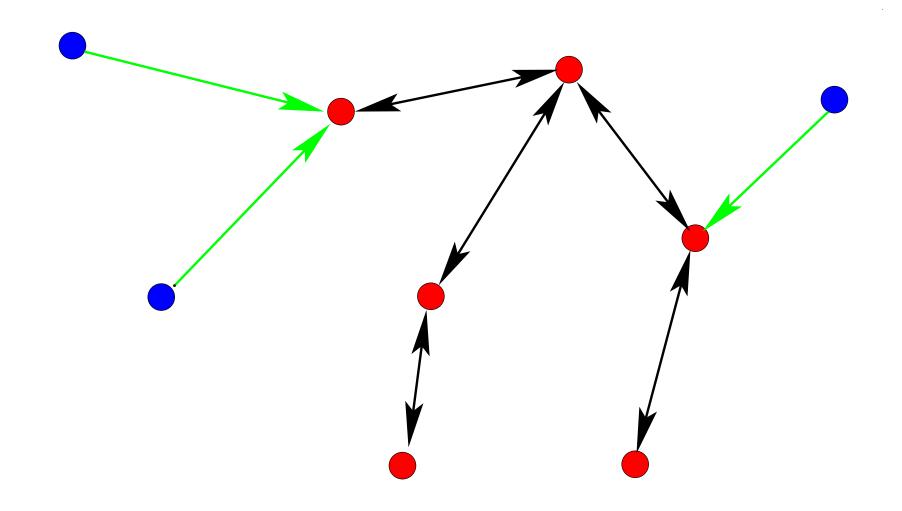
Informal Abstract Properties of the Protocol

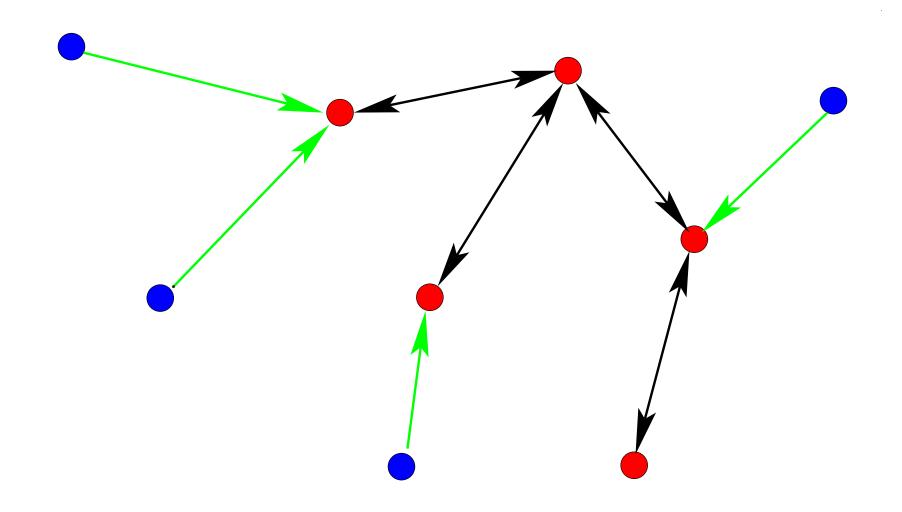
- We are given a connected and acyclic network of nodes
- Nodes are linked by bidirectional channels
- We want to have one node being elected the leader in a finite time
- This is to be done in a distributed and non-deterministic way
- Next are two distinct abstract animations of the protocol

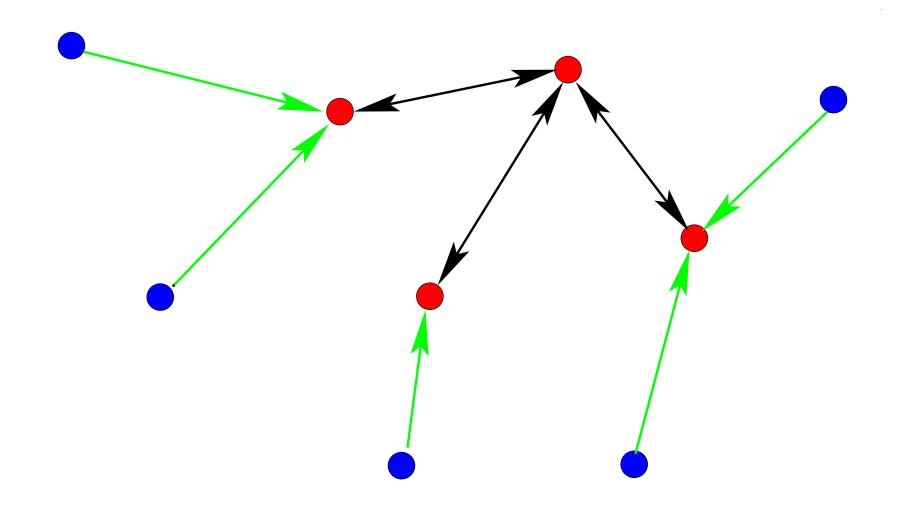


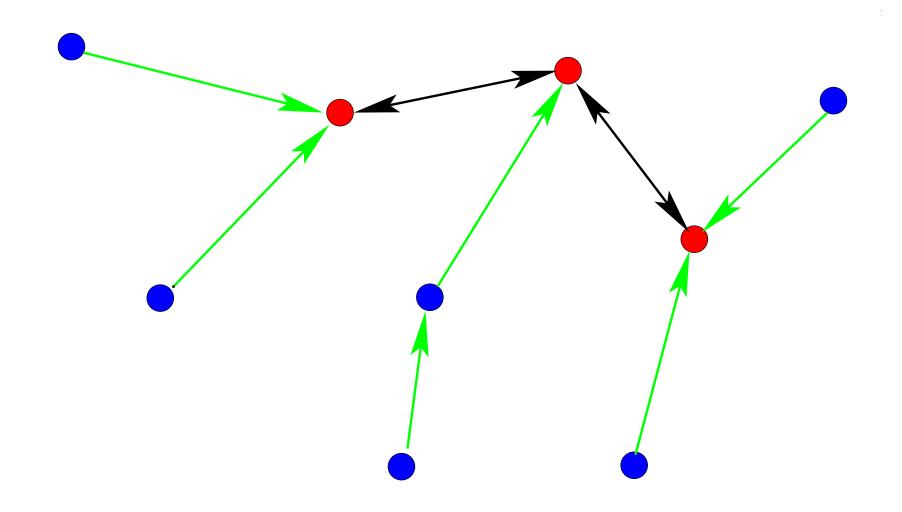


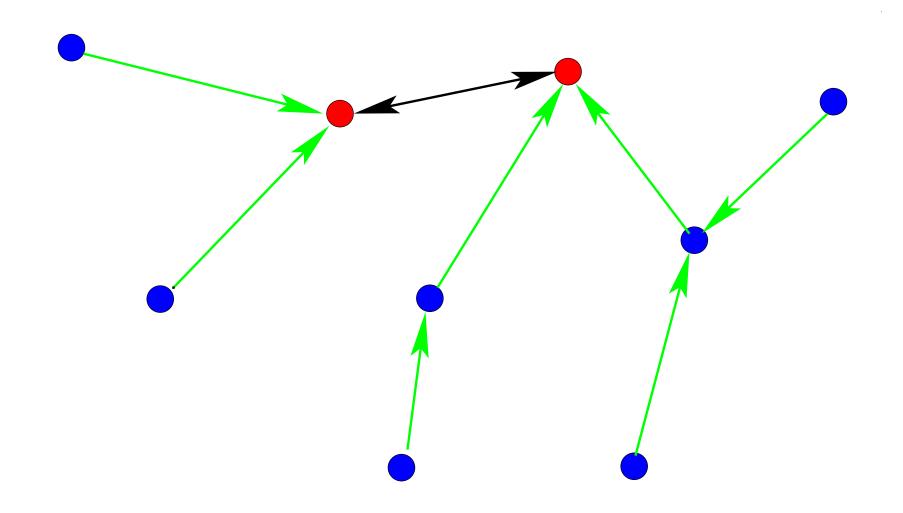


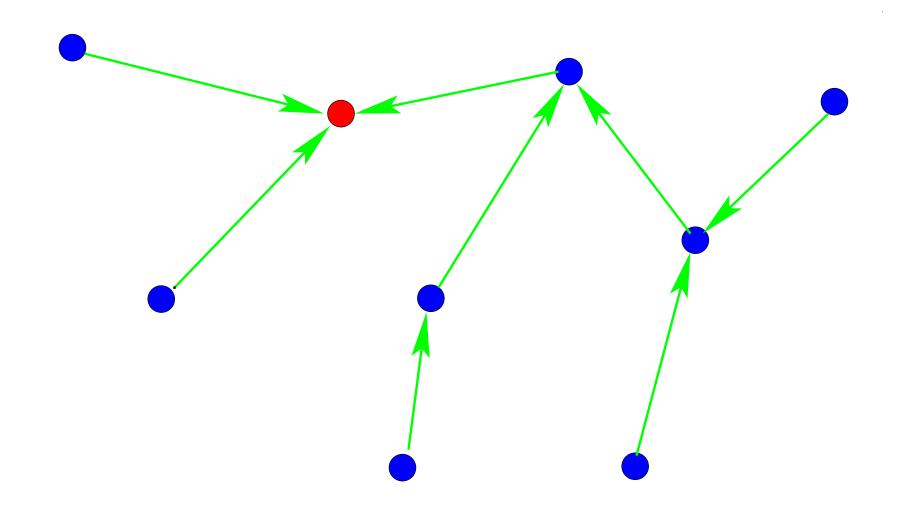


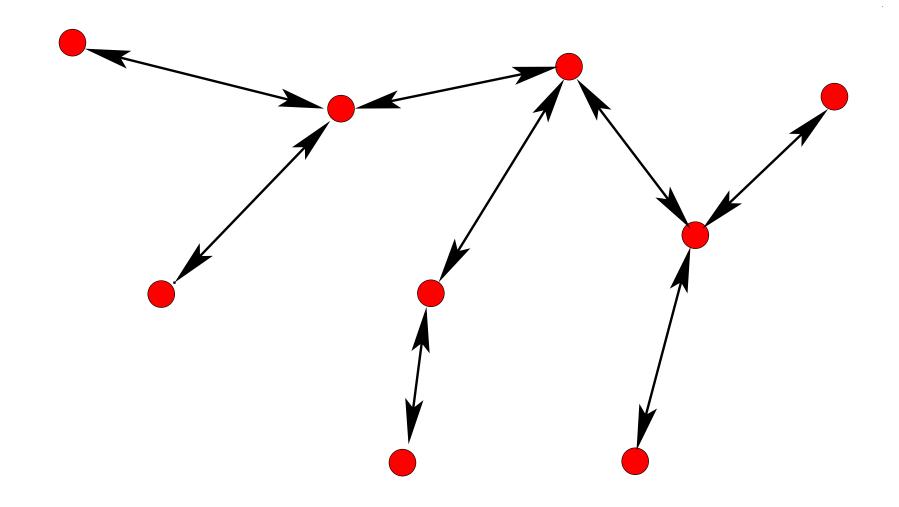


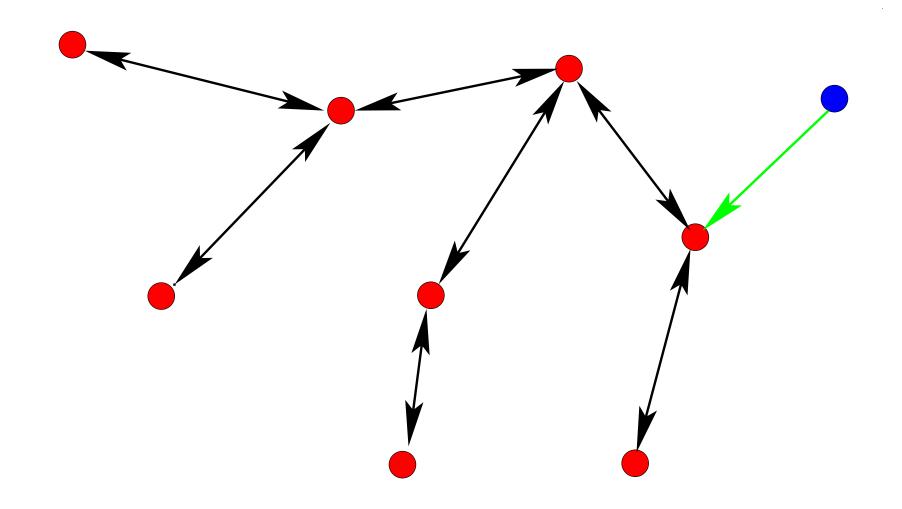


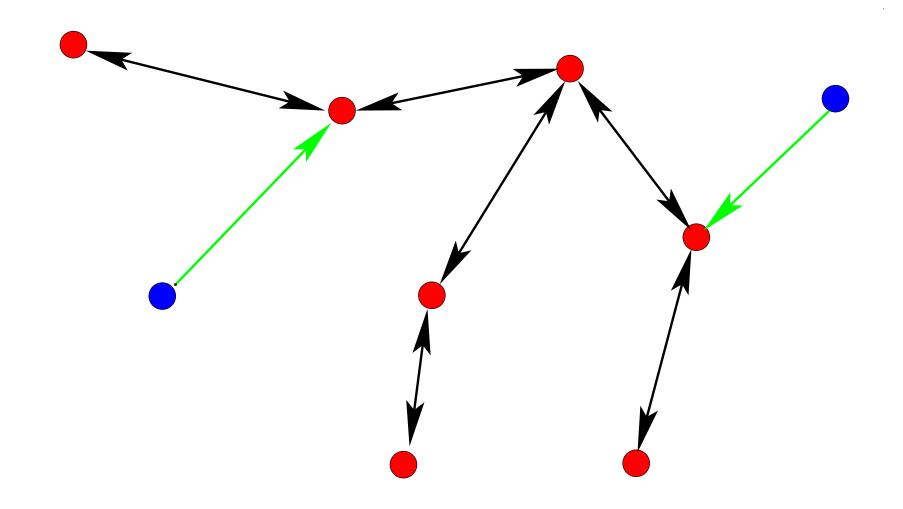


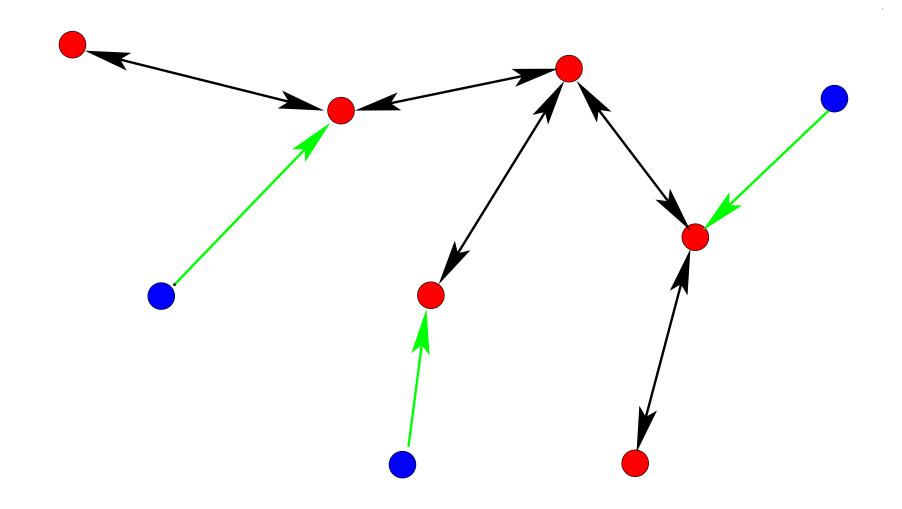


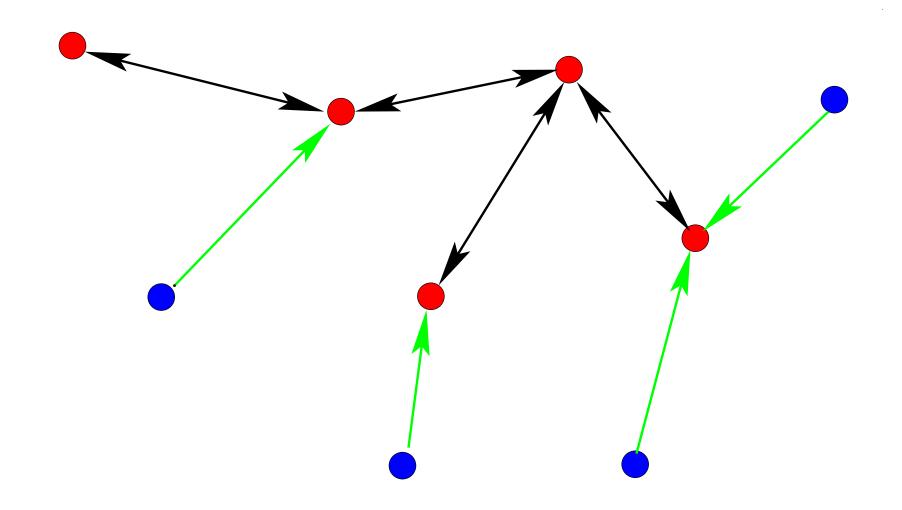


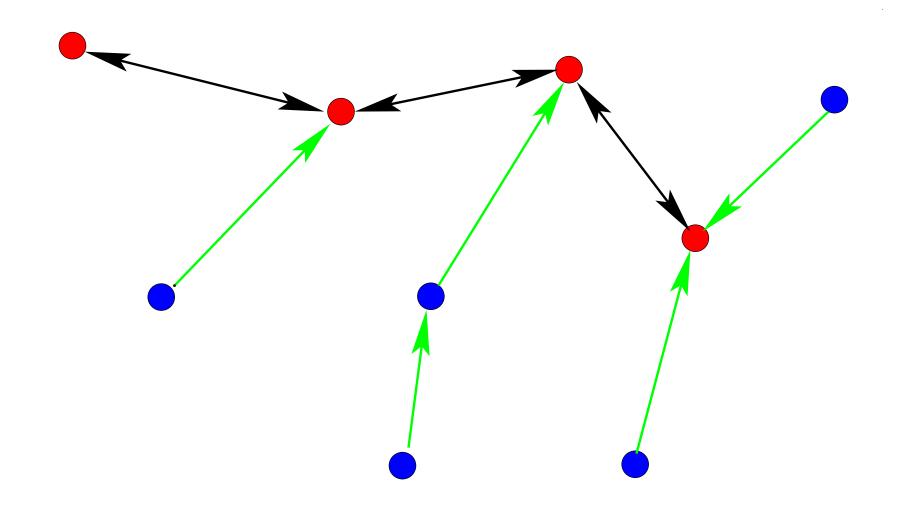


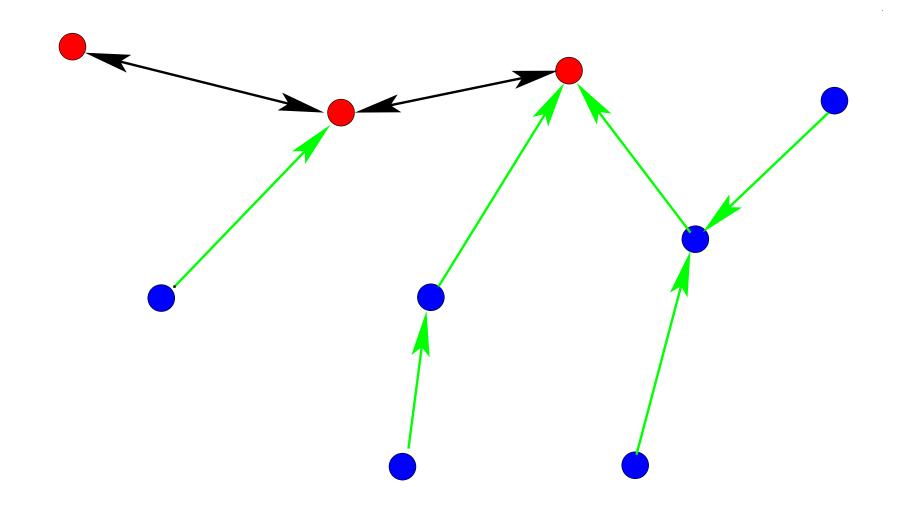


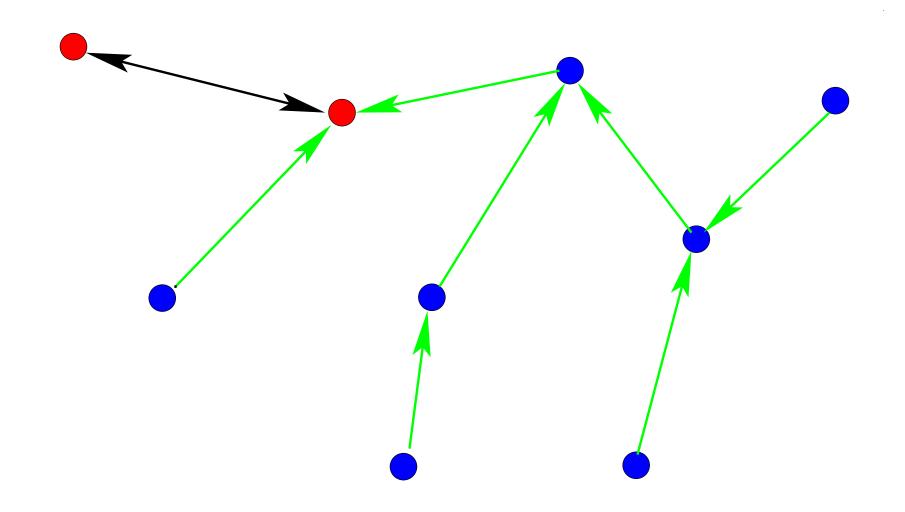


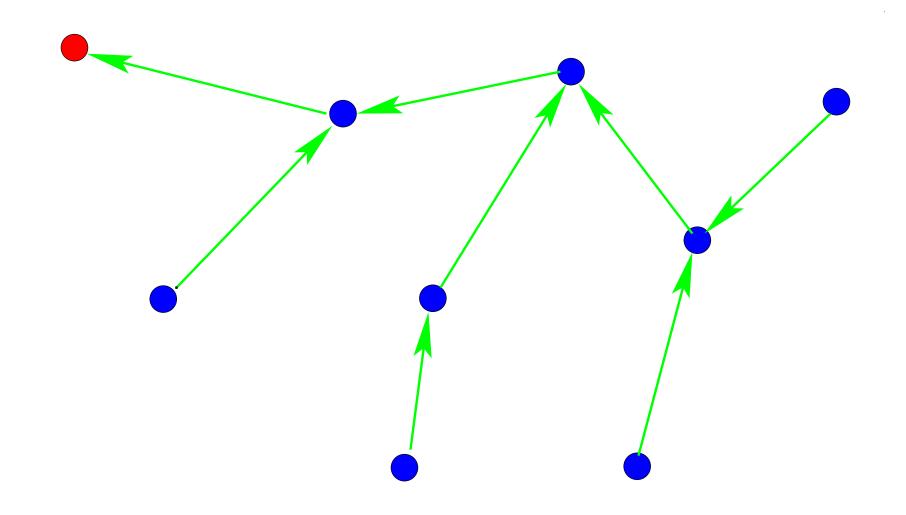






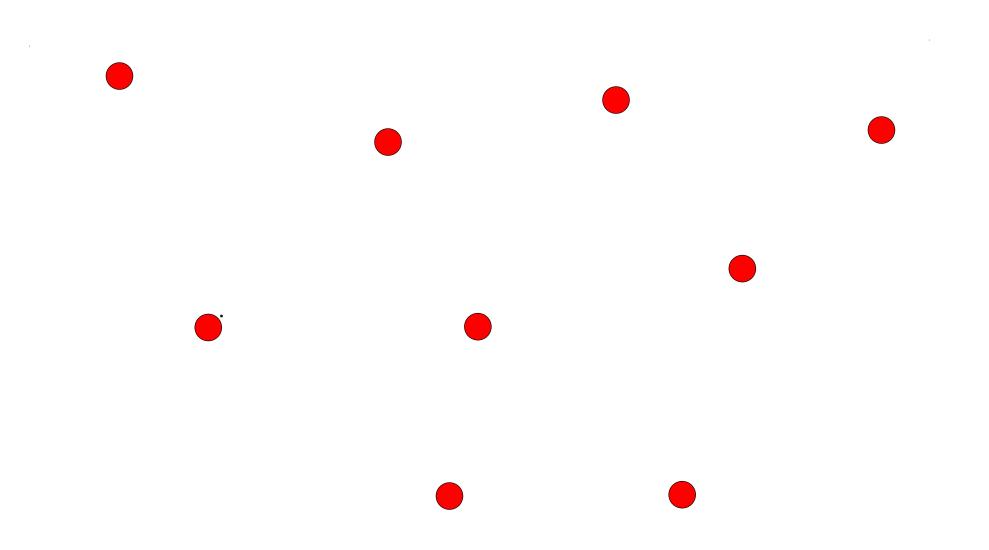




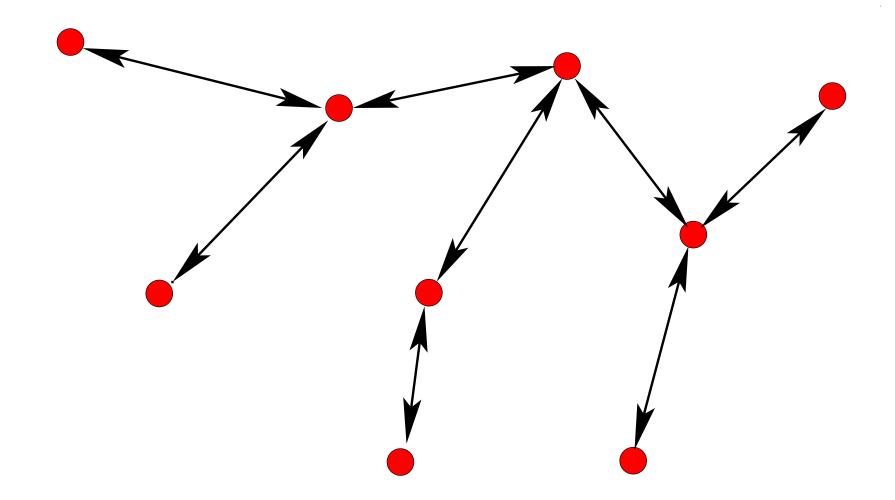


Summary of Development Process

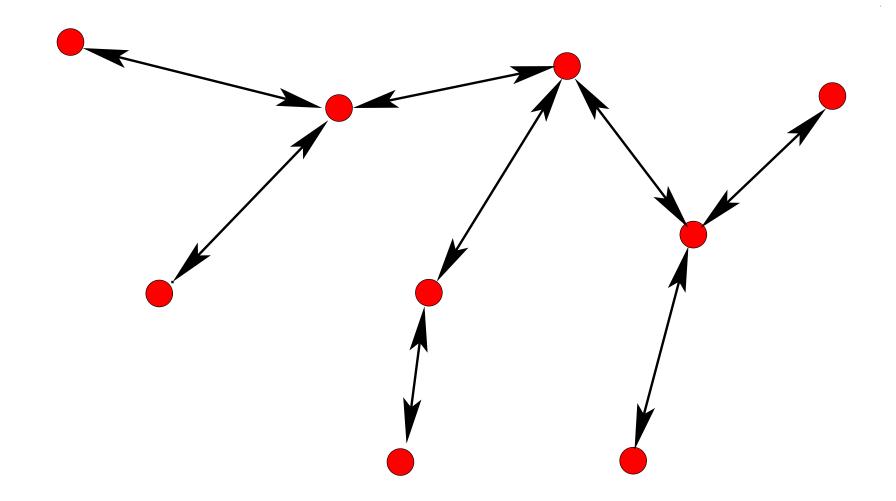
- Formal definition and properties of the network
- A one-shot abstract model of the protocol
- Presenting a (still abstract) loop-like centralized solution
- Introducing message passing between the nodes (delays)
- Modifying the data structure in order to distribute the protocol



Let ND be a set of nodes (with at least 2 nodes)



Let gr be a graph built and defined on ND



gr is a symmetric and irreflexive graph

gr is a graph built on ND $gr \subseteq ND \times ND$

gr is a graph built on ND

gr is defined on ND

 $gr \subseteq ND \times ND$

 $\operatorname{dom}\left(gr\right) = ND$

gr is a graph built on ND

gr is defined on ND

 $gr \subseteq ND \times ND$

$$\operatorname{dom}\left(gr\right) = ND$$

gr is symmetric

 $gr = gr^{-1}$

gr is a graph built on ND

gr is defined on ND

gr is symmetric

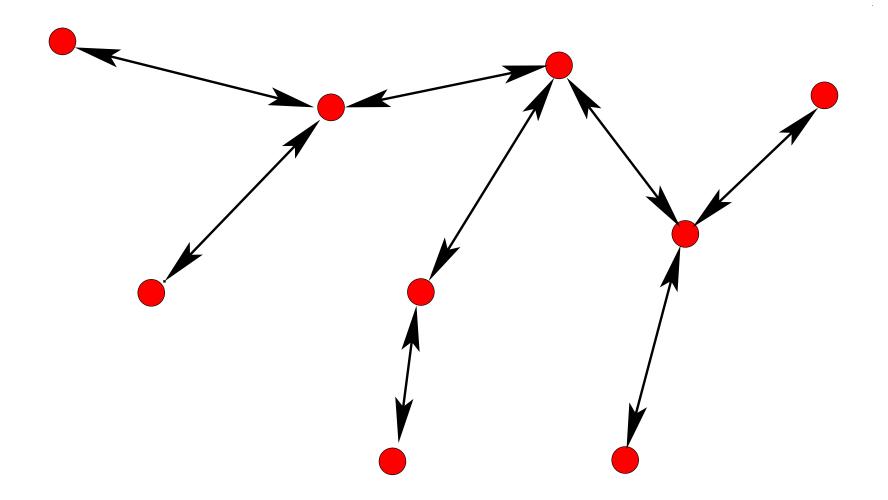
gr is irreflexive

 $gr \subseteq ND \times ND$

 $\mathrm{dom}\left(gr\right)=ND$

 $gr = gr^{-1}$

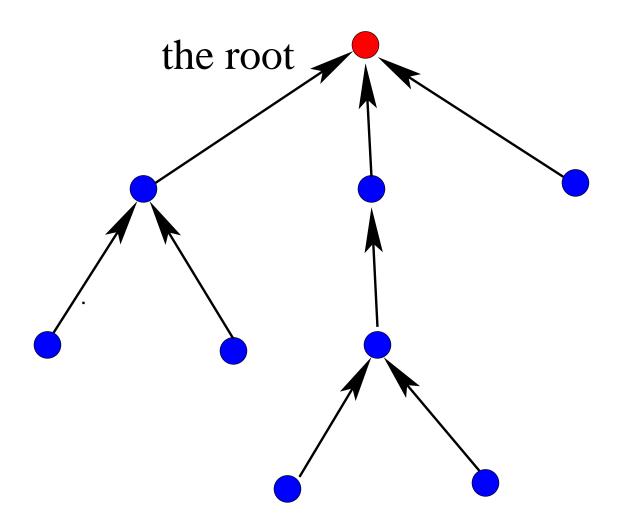
 $\mathsf{id}(ND) \cap gr = \emptyset$



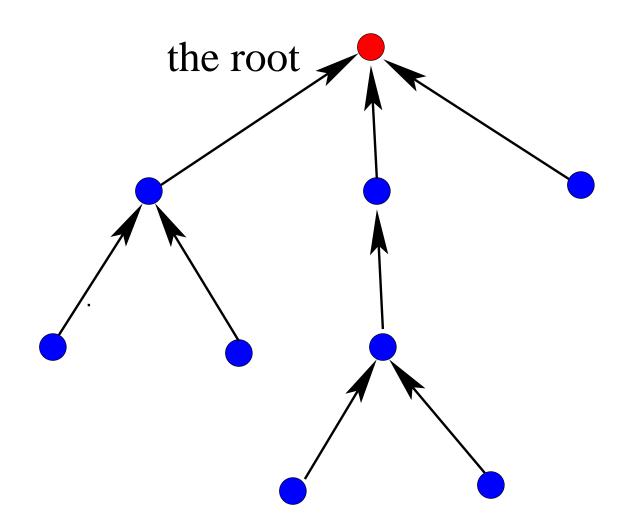
gr is connected and acyclic

A Little Detour Through Trees

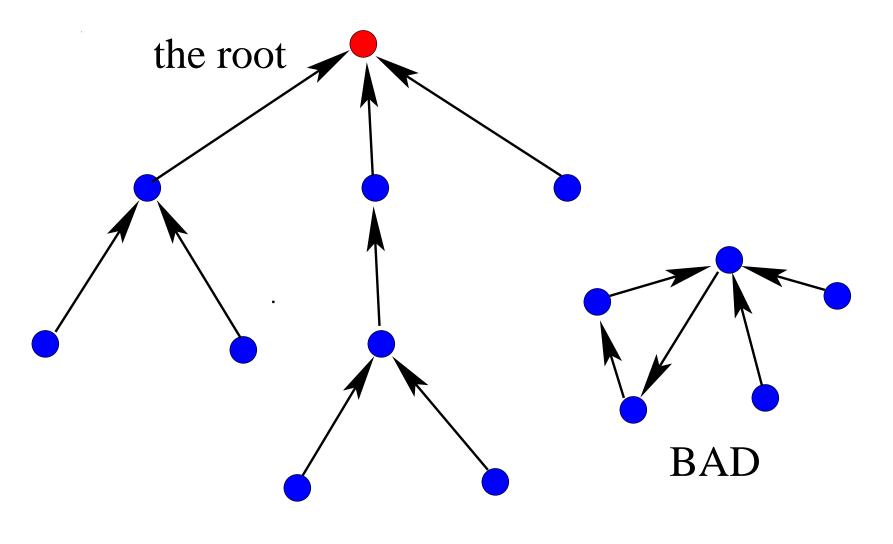
- A tree is a special graph
- A tree has a root
- A tree has a, so-called, father function
- A tree is acyclic
- A tree is connected from the root



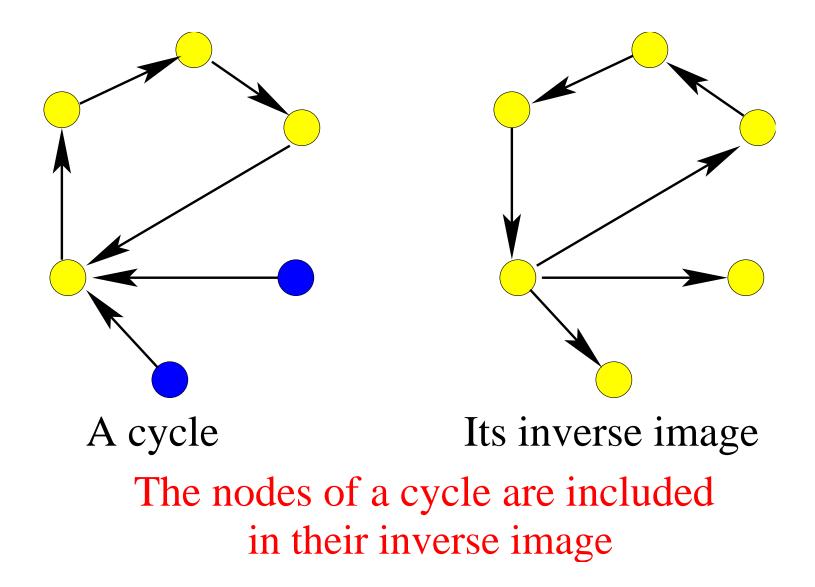
A tree t built on a set of nodes



t is a function defined on ND except at the root



Avoidind cycles



- Given
 - a set ND
 - a subset $p \ {\rm of} \ ND$
 - a binary relation t built on ND
- The inverse image of p under t is denoted by $t^{-1}[p]$

$$t^{-1}[p] \cong \{ x \mid x \in ND \land \exists y \cdot (y \in p \land (x,y) \in t) \}$$

- When t is a partial function, this reduces to

$$\{x \mid x \in \mathsf{dom}(t) \land t(x) \in p\}$$

- If p is included in its inverse image, we have then:

 $\forall x \cdot (x \in p \implies x \in \text{dom}(t) \land t(x) \in p)$

- Notice that the empty set enjoys this property

 $\emptyset \subseteq t^{-1}[\emptyset]$

- The property of having no cycle is thus equivalent to:

The only subset p of ND s.t. $p \subseteq t^{-1}[p]$ is EMPTY

$$\forall p \cdot \begin{pmatrix} p \subseteq ND \land \\ p \subseteq t^{-1}[p] \\ \Rightarrow \\ p = \emptyset \end{pmatrix}$$

r is a member of ND $r \in ND$

r is a member of ND $r \in ND$

t is a function $t \in ND - \{r\} \rightarrow ND$

- $r \text{ is a member of } ND \quad r \in ND$
- *t* is a function $t \in ND \{r\} \rightarrow ND$

t is acyclic

$$\forall p \cdot \begin{pmatrix} p \subseteq ND \land \\ p \subseteq t^{-1}[p] \\ \Rightarrow \\ p = \emptyset \end{pmatrix}$$

t is acyclic: equivalent formulations

$$\forall p \cdot \begin{pmatrix} p \subseteq ND \land \\ p \subseteq t^{-1}[p] \\ \Rightarrow \\ p = \emptyset \end{pmatrix} \quad \Leftrightarrow \quad \forall q \cdot \begin{pmatrix} q \subseteq ND \land \\ r \in q \land \\ t^{-1}[q] \subseteq q \\ \Rightarrow \\ ND \subseteq q \end{pmatrix}$$

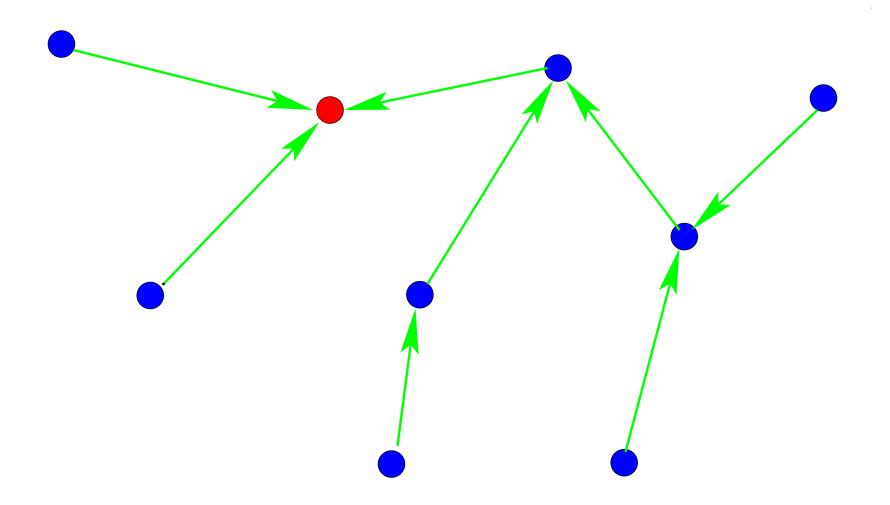
This gives an Induction Rule

$$\forall q \cdot \begin{pmatrix} q \subseteq ND \land \\ r \in q \land \\ \forall x \cdot (x \in ND - \{r\} \land t(x) \in q \Rightarrow x \in q) \\ \Rightarrow \\ ND \subseteq q \end{pmatrix}$$

- $r \text{ is a member of } ND \quad r \in ND$
- *t* is a function $t \in ND \{r\} \rightarrow ND$

t is acyclic

$$\forall q \cdot \begin{pmatrix} q \subseteq ND \land \\ r \in q \land \\ t^{-1}[q] \subseteq q \\ \Rightarrow \\ ND \subseteq q \end{pmatrix}$$



A spanning tree t of the graph gr

The predicate spanning (r, t, gr)

r, t is a tree tree(r, t)

t is included in gr $t \subseteq gr$

The graph gr is connected and acyclic (1)

- Defining a relation fn linking a node to the possible spanning trees of gr having that node as a root:

$$fn \subseteq ND \times (ND \leftrightarrow ND)$$

$$\forall (r,t) \cdot \begin{pmatrix} r \in ND \land \\ t \in ND \leftrightarrow ND \\ \Rightarrow \\ (r,t) \in fn \Leftrightarrow \text{ spanning } (r,t,gr) \end{pmatrix}$$

The graph gr is connected and acyclic (2)

Totality of relation $fn \Rightarrow$ Connectivity of gr

Functionality of relation $fn \Rightarrow$ Acyclicity of gr

$$gr \subseteq ND \times ND$$

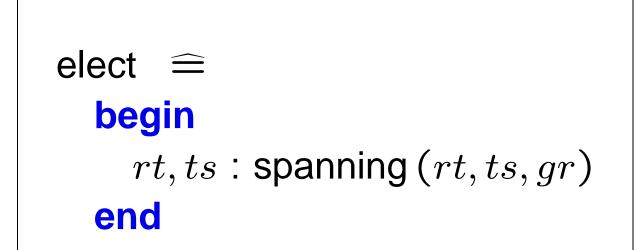
dom $(gr) = ND$
 $gr = gr^{-1}$
id $(ND) \cap gr = \emptyset$

$$\begin{aligned} fn \in ND \to (ND \leftrightarrow ND) \\ & \forall (r,t) \cdot \begin{pmatrix} r \in ND \land \\ t \in ND \leftrightarrow ND \\ \Rightarrow \\ t = fn(r) \Leftrightarrow \text{ spanning } (r,t,gr) \end{pmatrix} \end{aligned}$$

Election in One Shot: Building a Spanning Tree

- Variables rt and ts

 $rt \in ND$ $ts \in ND \leftrightarrow ND$

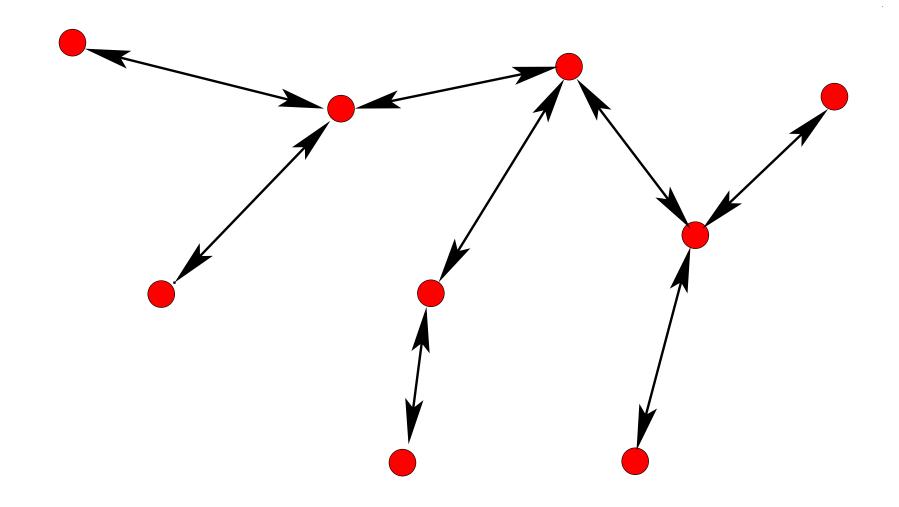


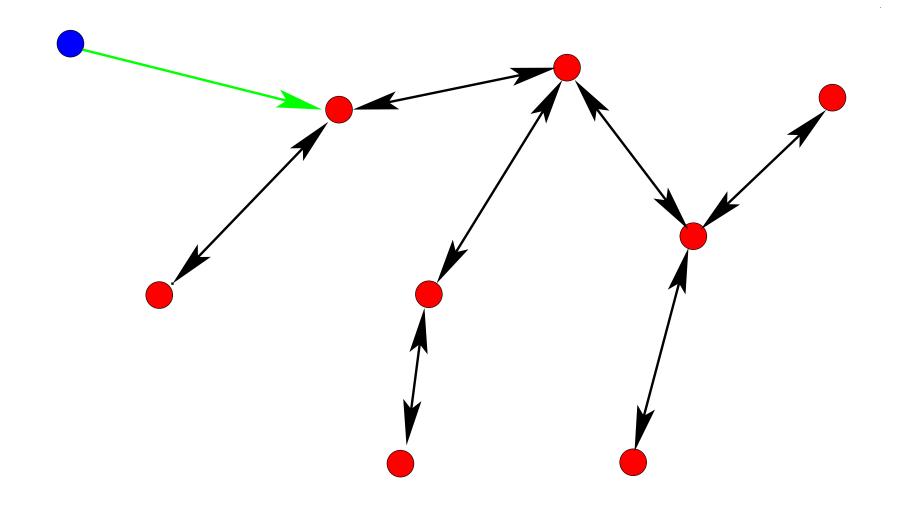
- Introducing a new variable, tr, corresponding to the "tree" in construction

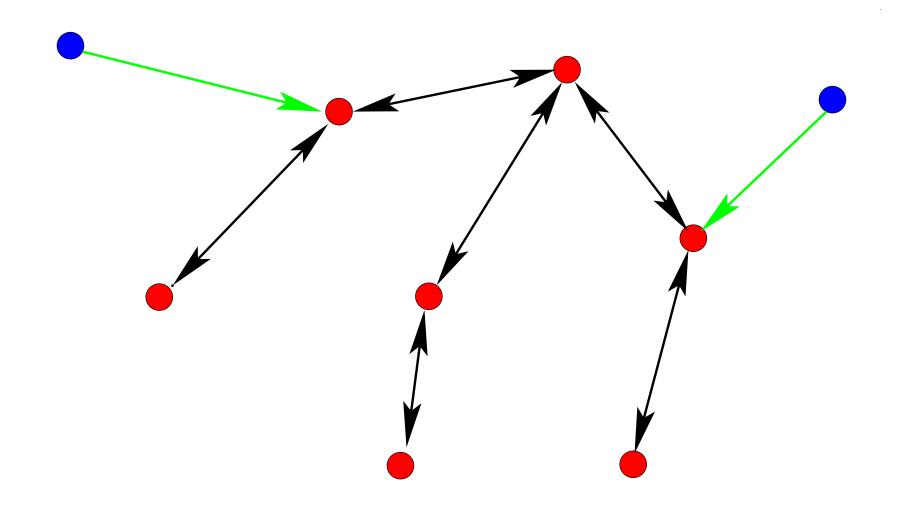
- Introducing a new event: the progression event

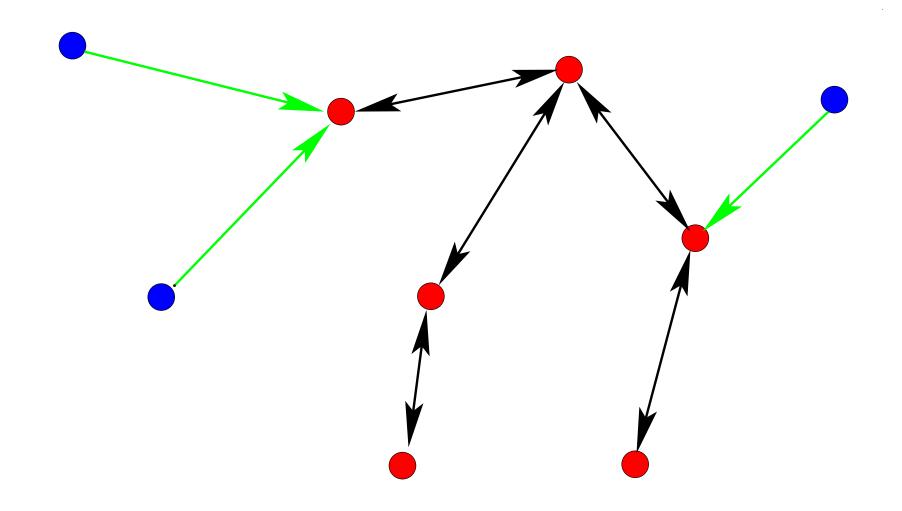
- Defining the invariant

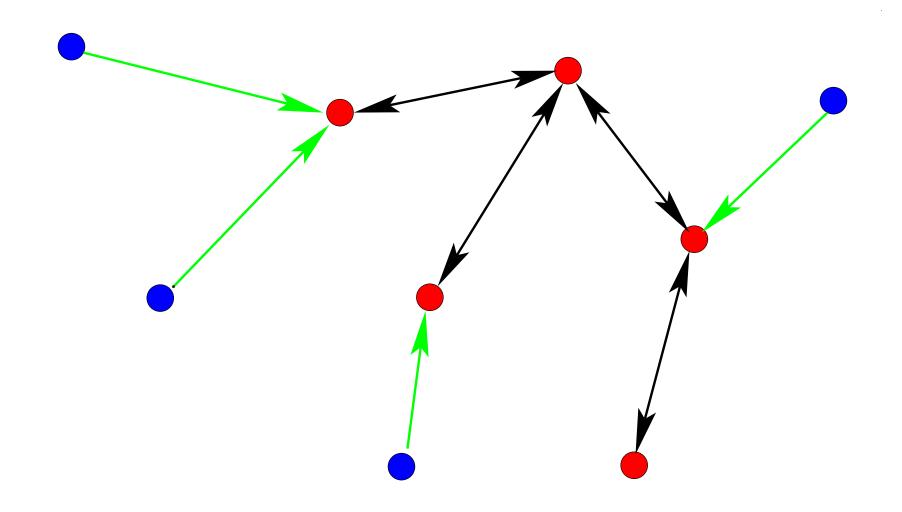
- Back to the animation : Observe the construction of the tree

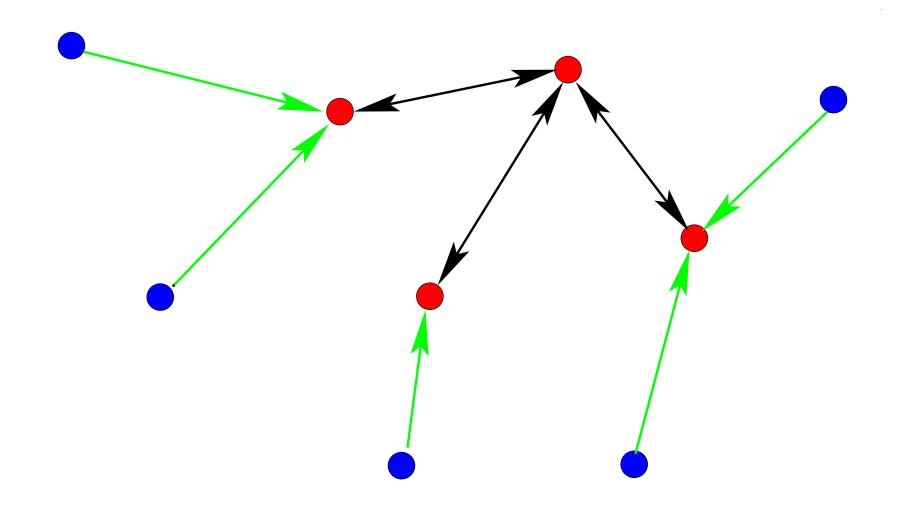


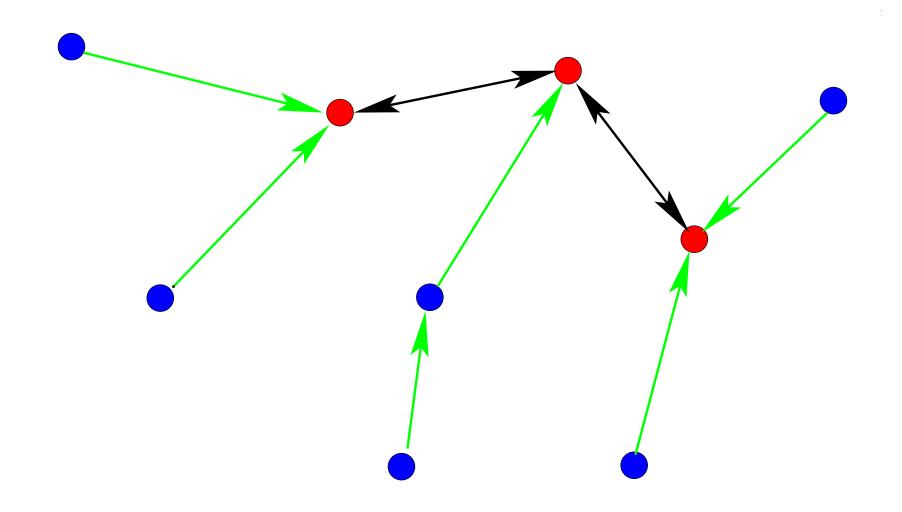


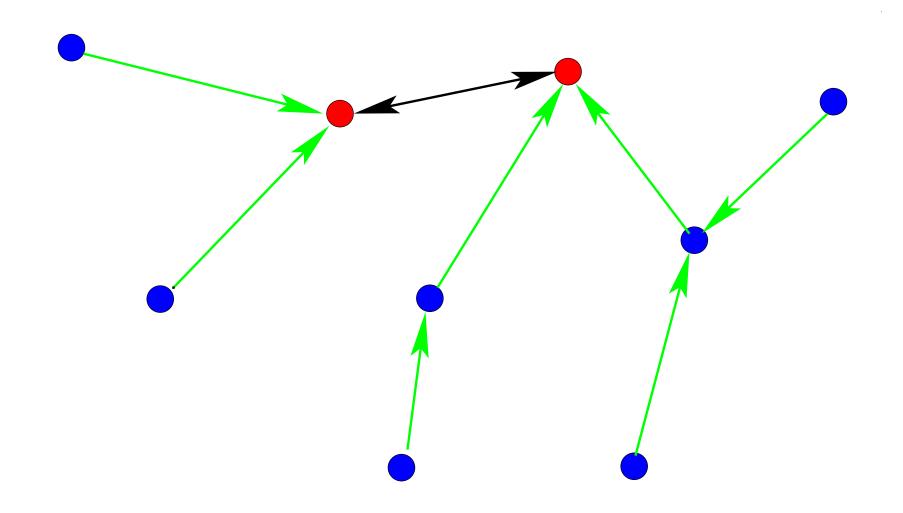


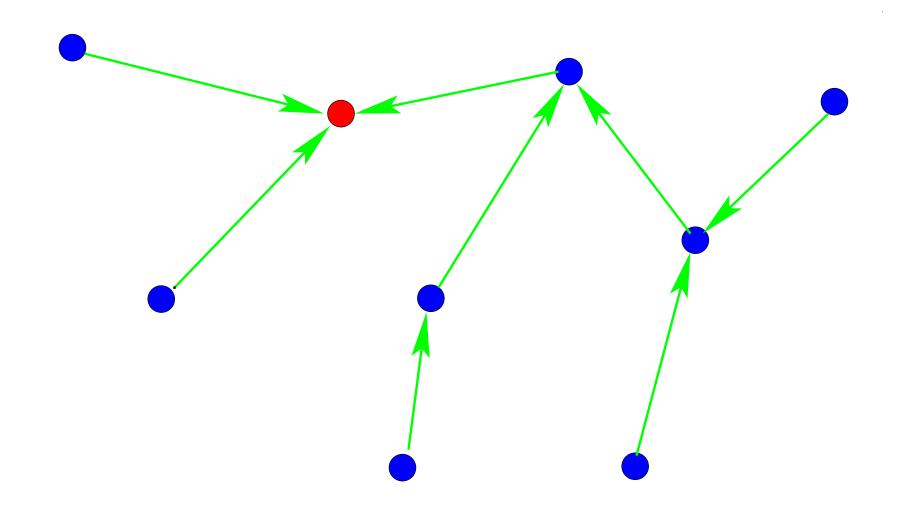












- The green arrows correspond to the tr function

- The blue nodes are the domain of tr

- The function tr is a forest (multi-tree) on nodes

- The red nodes are the roots of these trees

The predicate invariant (tr)

$tr \in ND \nrightarrow ND$

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 $tr \in ND \nrightarrow ND$

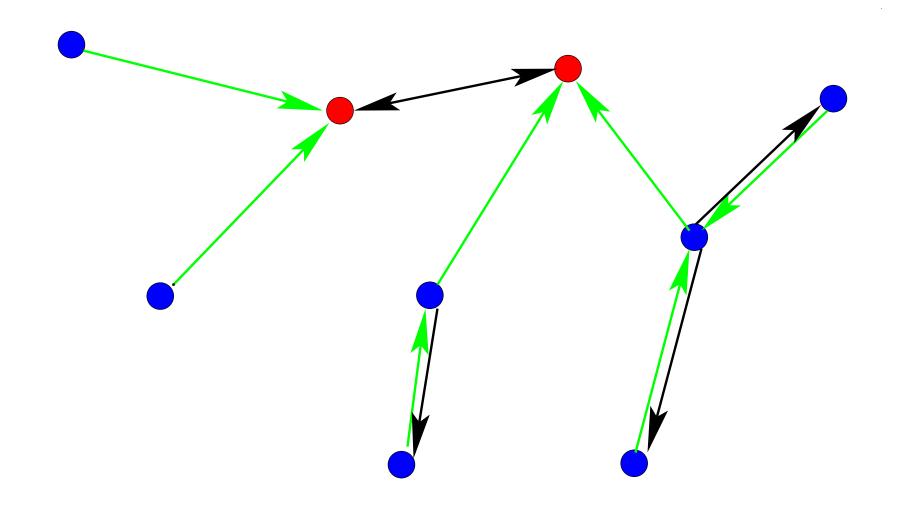
$$\forall p \cdot \begin{pmatrix} p \subseteq ND & \land \\ ND - \operatorname{dom}(tr) \subseteq p & \land \\ tr^{-1}[p] \subseteq p \\ \Rightarrow \\ ND \subseteq p \end{pmatrix}$$

The predicate invariant (tr)

 $tr \in ND \twoheadrightarrow ND$

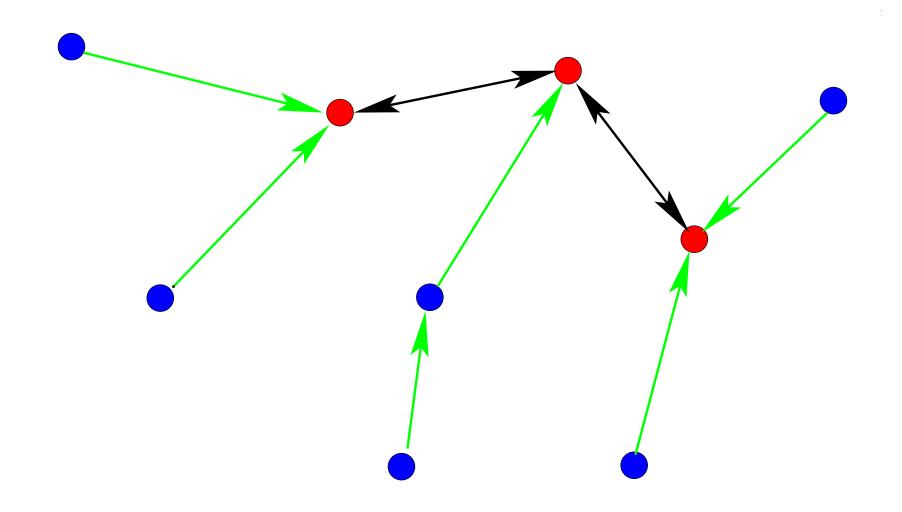
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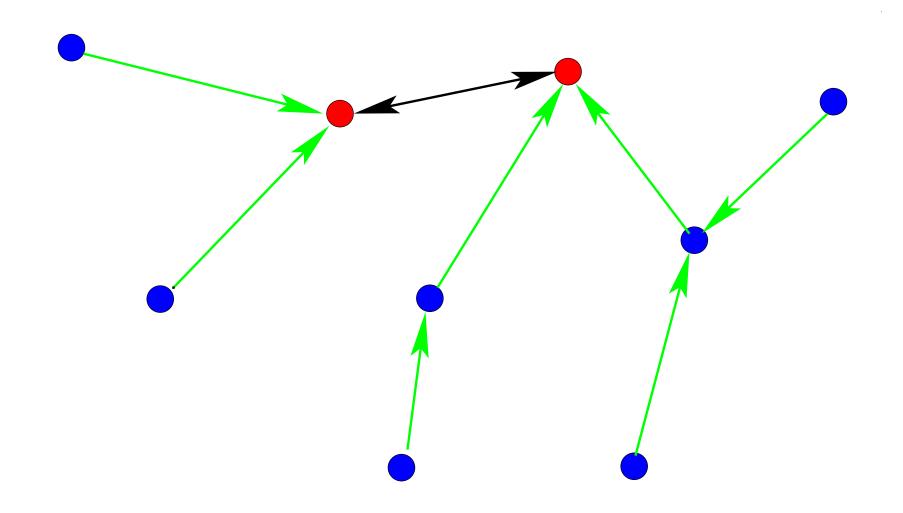
 $\operatorname{dom}(tr) \triangleleft (tr \cup tr^{-1}) = \operatorname{dom}(tr) \triangleleft gr$



- Introducing the new event "progress"
- Refining the abstract event "elect"

- Back to the animation : Observe the "guard" of progress



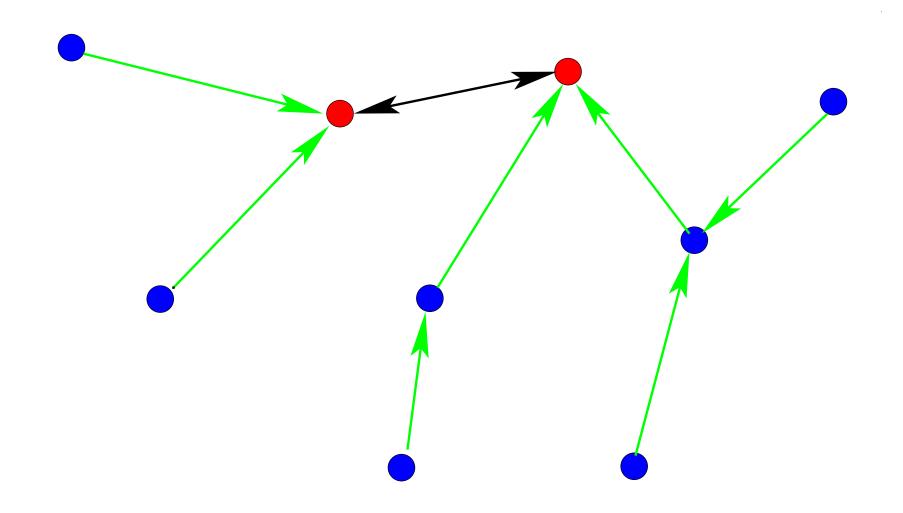


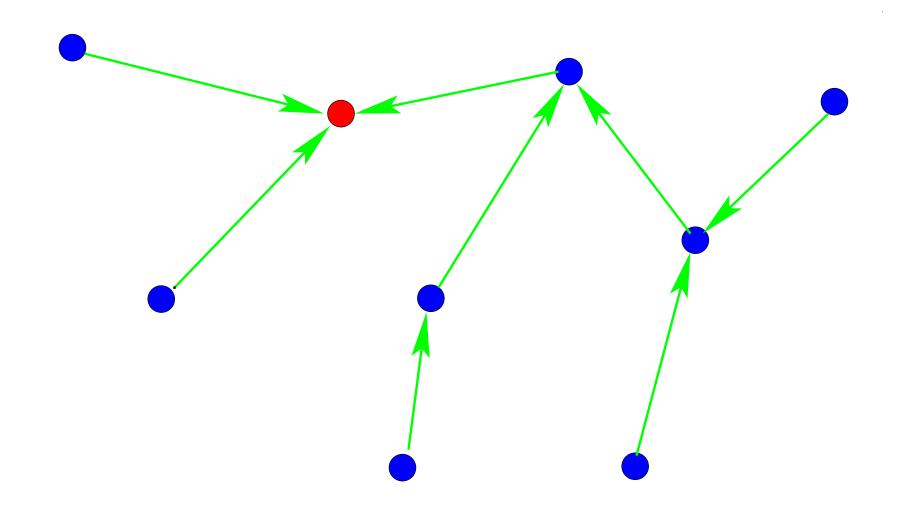
When a red node x is connected to AT MOST one other red node y then event "progress" can take place

```
progress \widehat{=}
   any x, y where
       x, y \in gr \land
       x \notin \operatorname{dom}(tr) \land
      y \notin \operatorname{dom}(tr) \land
      qr[\{x\}] = tr^{-1}[\{x\}] \cup \{y\}
   then
      tr := tr \cup \{x \mapsto y\}
   end
```

To be proved

invariant $(tr) \wedge$ $x, y \in gr \land$ $x \notin \operatorname{dom}(tr) \wedge$ $y \notin \operatorname{dom}(tr) \wedge$ $gr[\{x\}] = tr^{-1}[\{x\}] \cup \{y\}$ \Rightarrow invariant($tr \cup \{x \mapsto y\}$)





When a red node x is ONLY connected to blue nodes then event "elect" can take place

> elect $\widehat{=}$ any x where $x \in ND \land$ $gr[\{x\}] = tr^{-1}[\{x\}]$ then rt, ts := x, trend

```
elect \widehat{=}

begin

rt, ts : spanning (rt, ts, gr)

end
```

```
elect \widehat{=}

any x where

x \in ND \land

gr[\{x\}] = tr^{-1}[\{x\}]

then

rt, ts := x, tr

end
```

To be proved

$$invariant(tr) \land$$

$$x \in ND \land$$

$$gr[\{x\}] = tr^{-1}[\{x\}]$$

$$ts = tr$$

$$\Rightarrow$$

$$spanning(x, ts, gr)$$

- 15 proofs

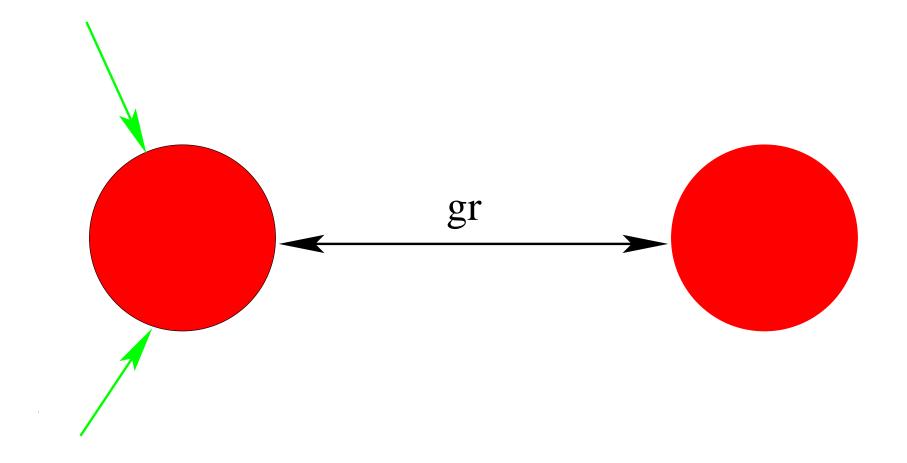
- Among which 9 were interactive (one is a bit difficult !)

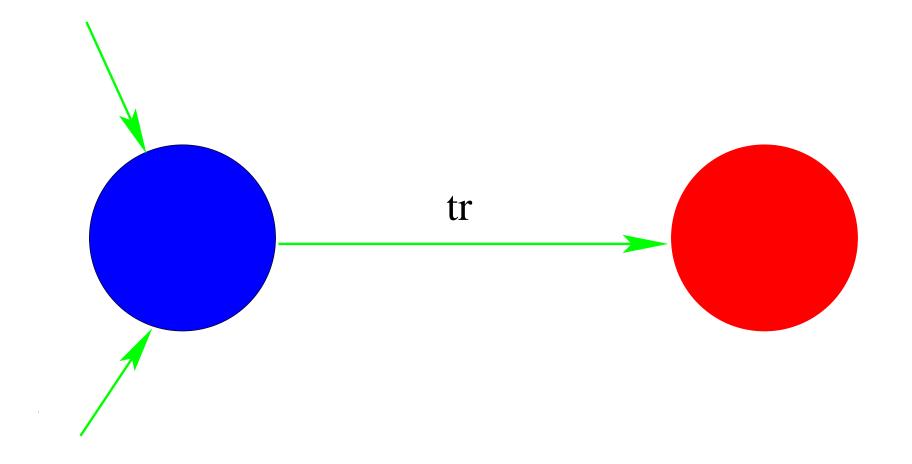
- Nodes are communicating with their neighbors

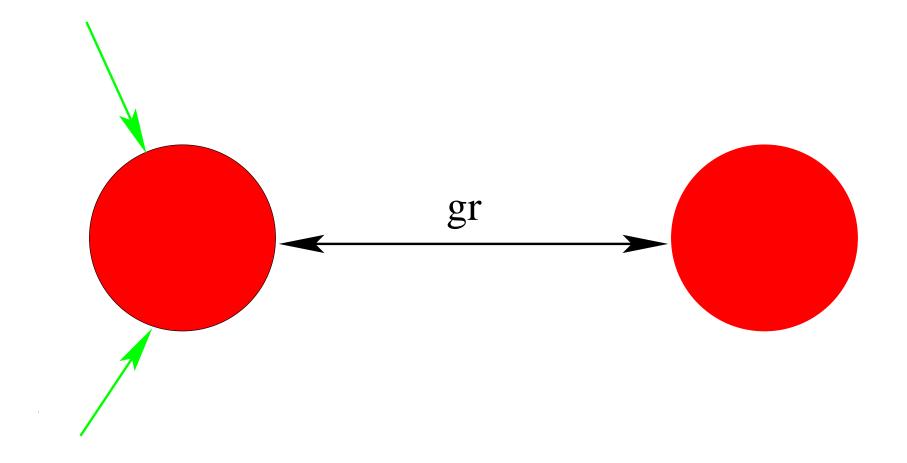
- This is done by means of messages
- Messages are acknowledged

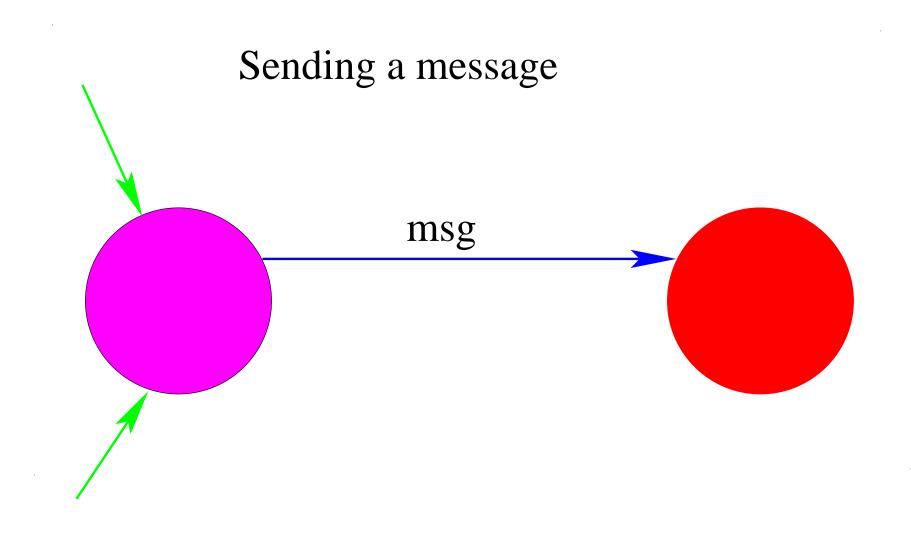
- Acknowledgements are confirmed

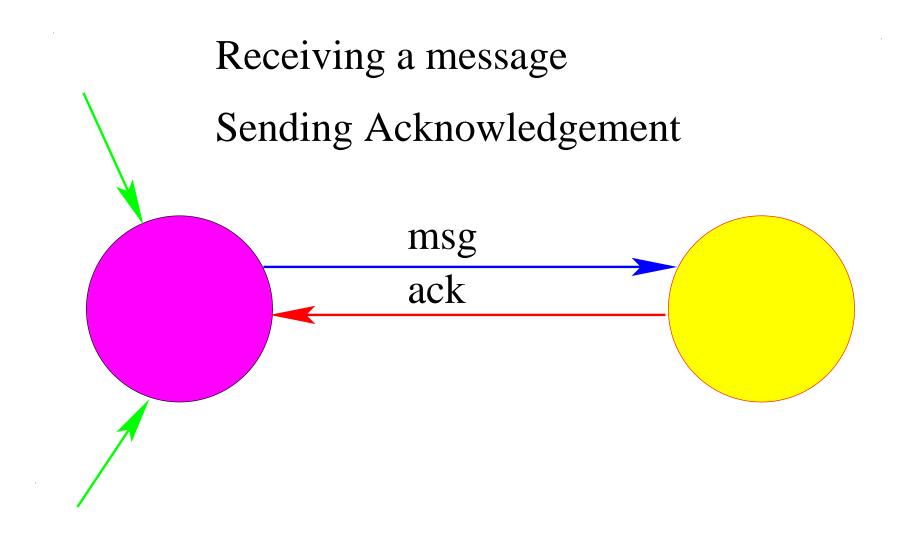
- Next is a local animation

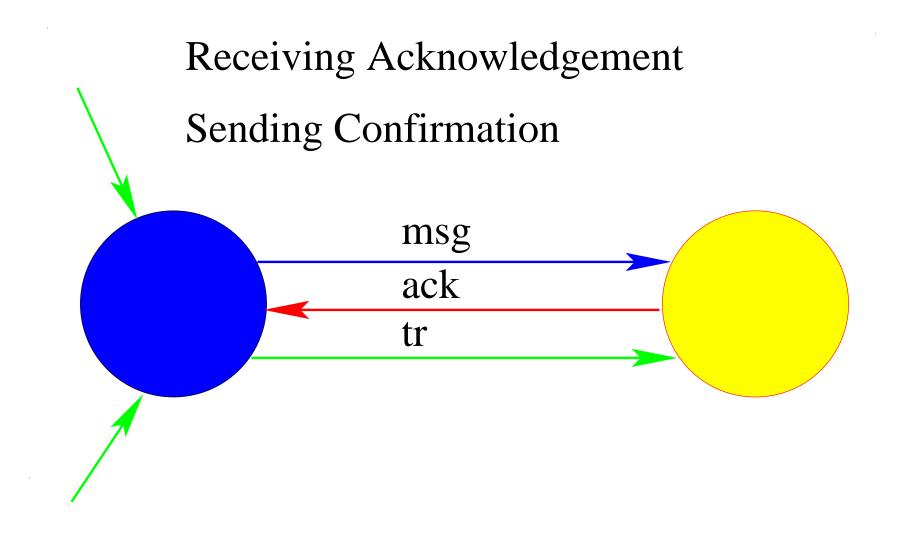


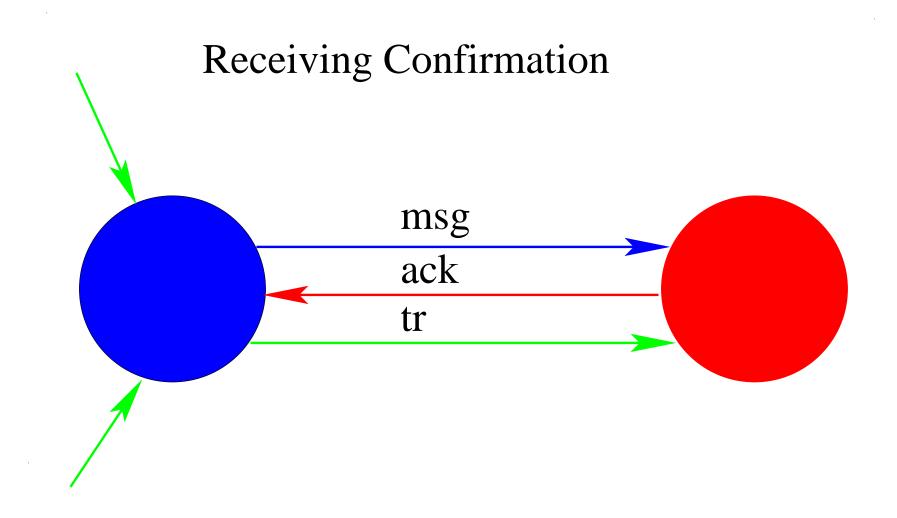


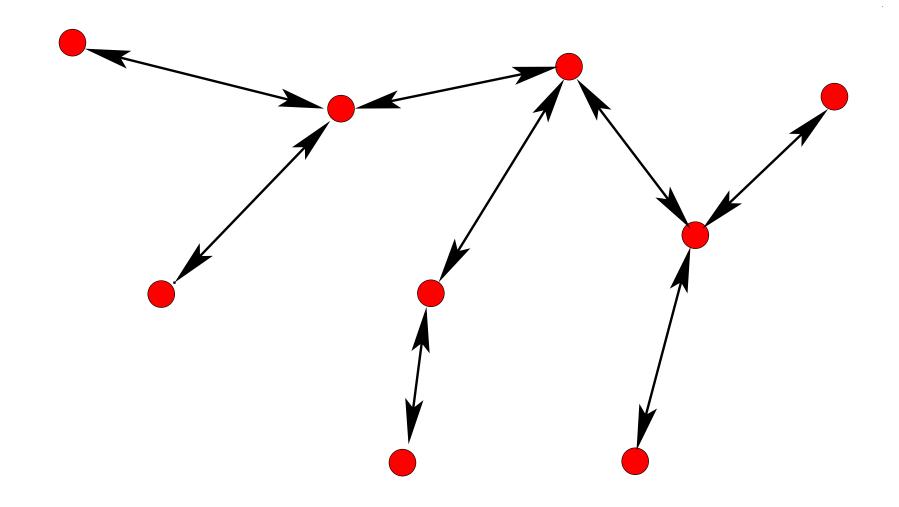


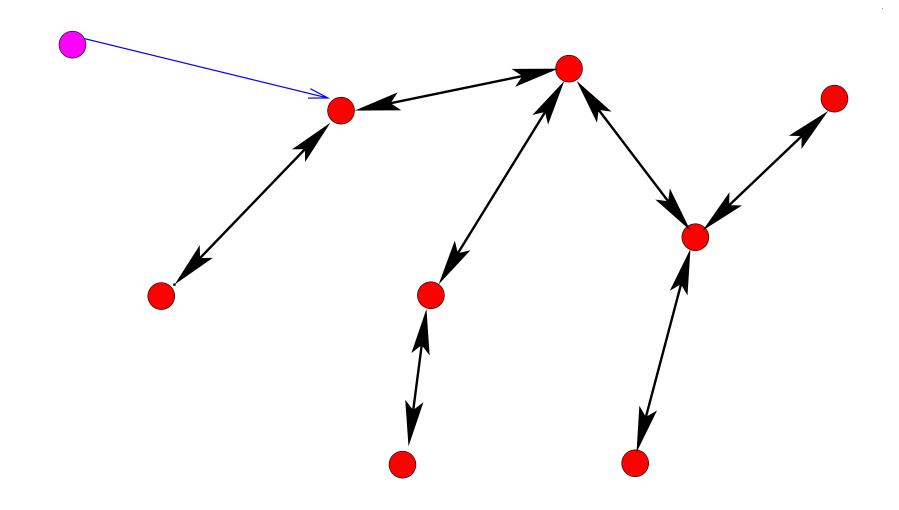


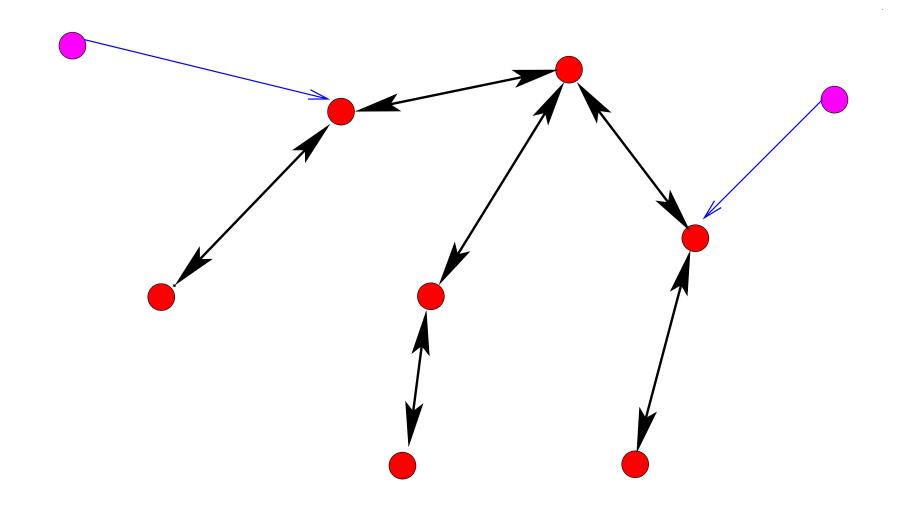


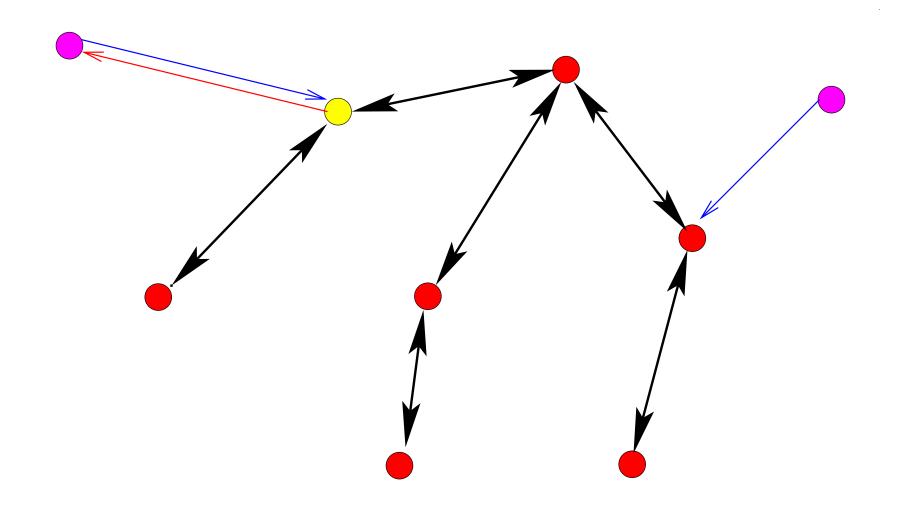


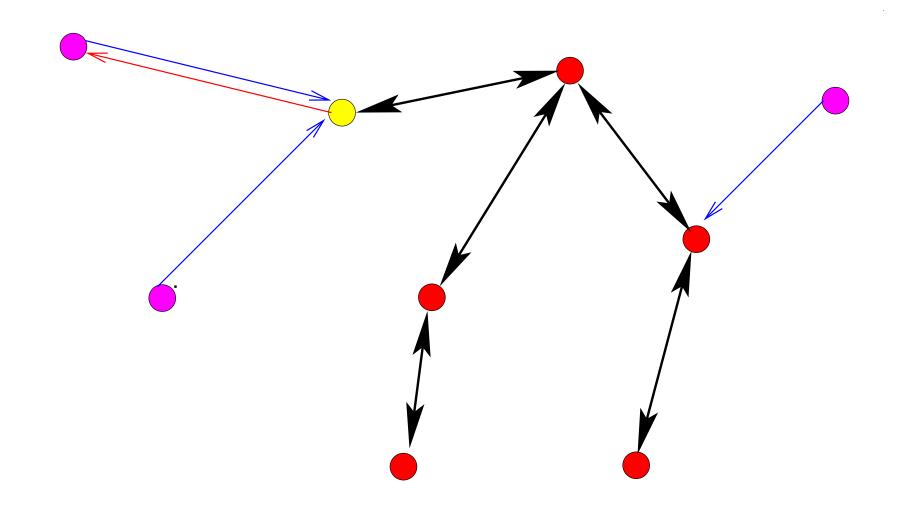


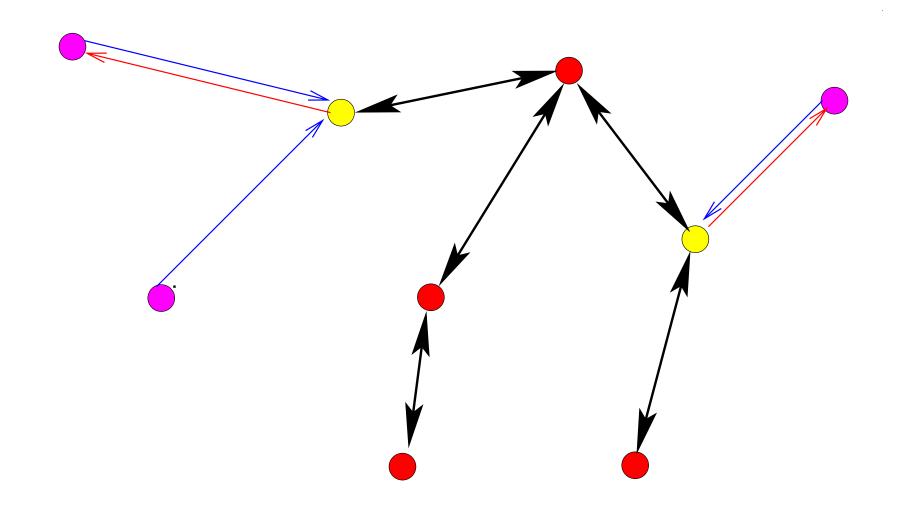


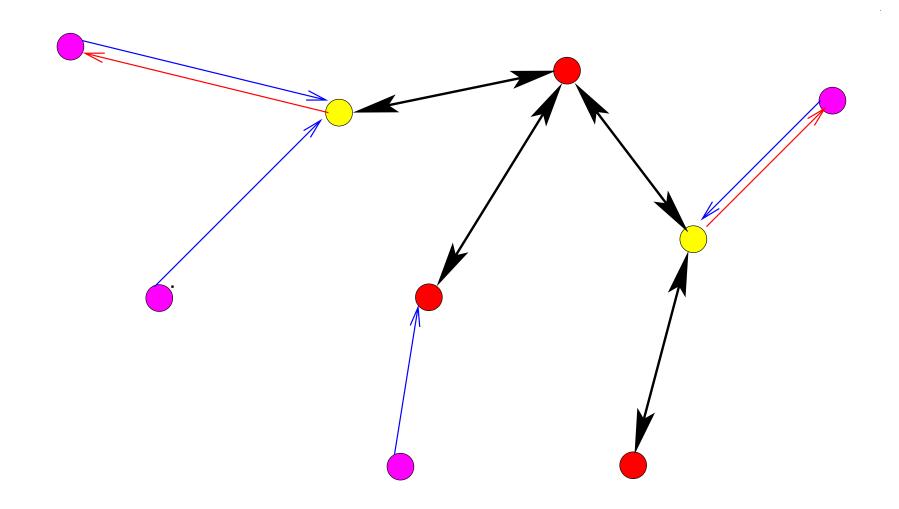


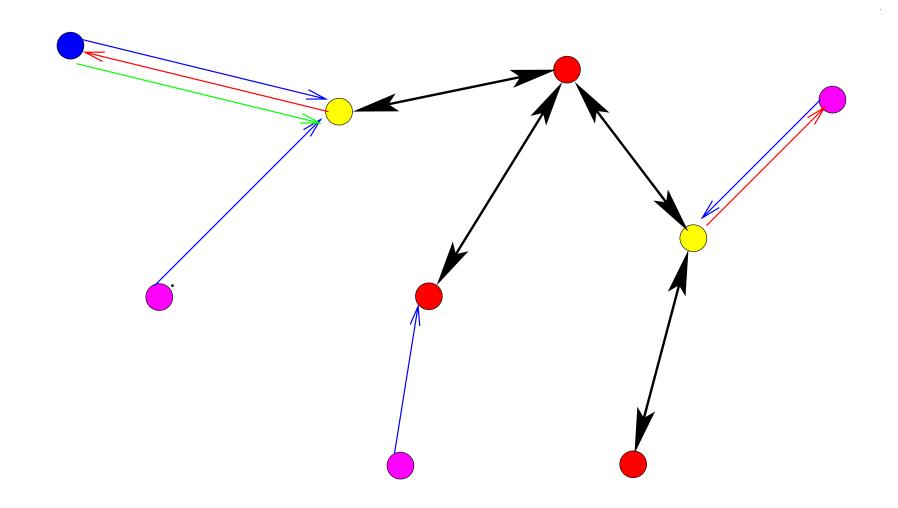


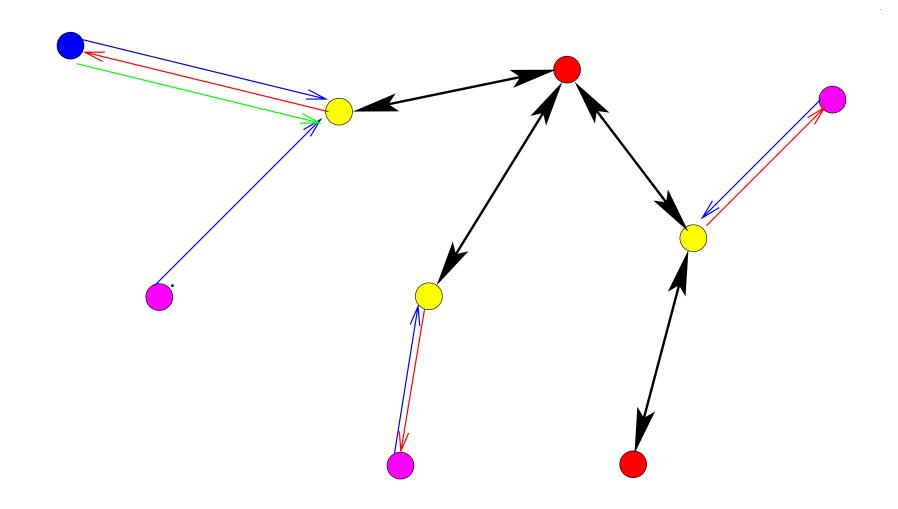


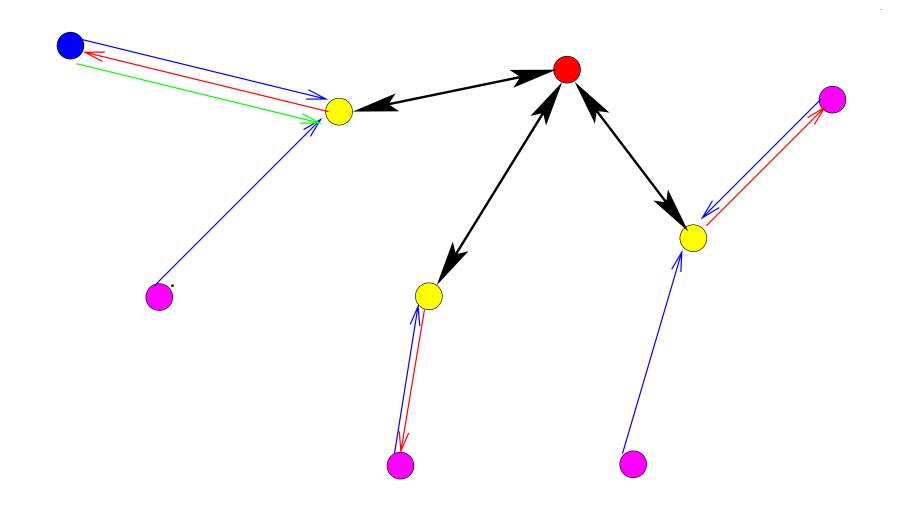


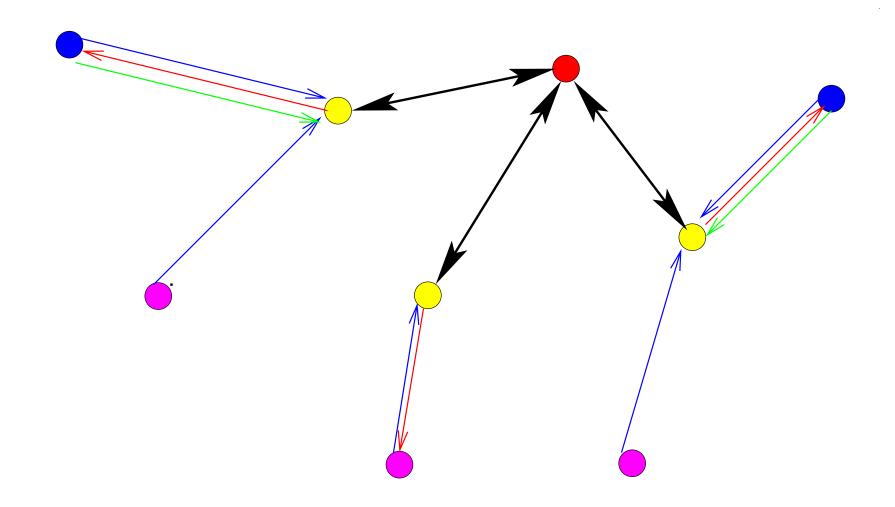


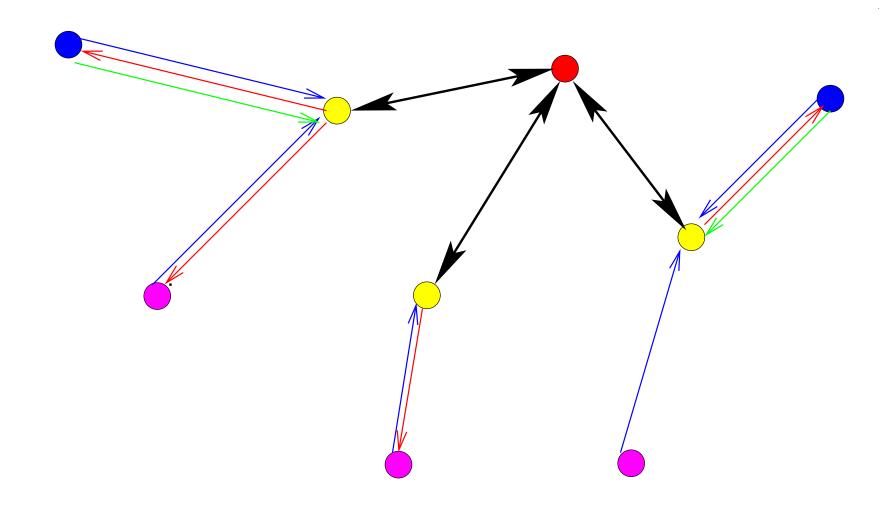


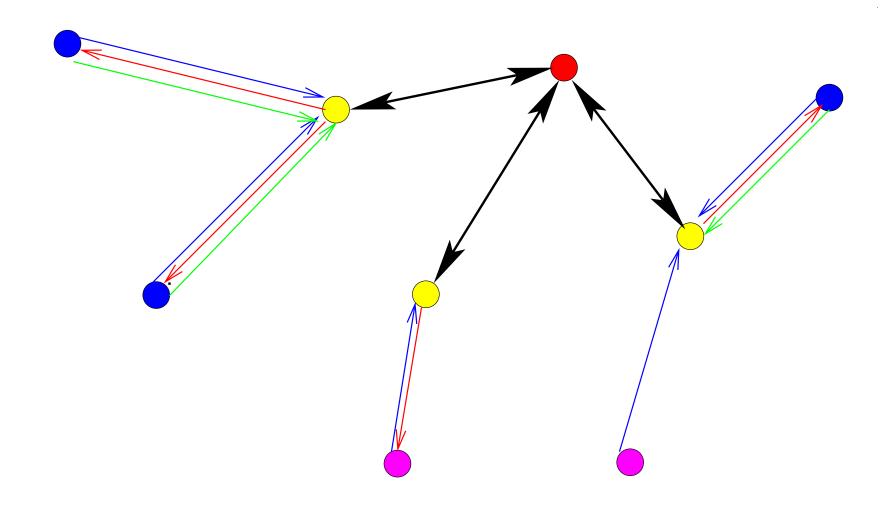


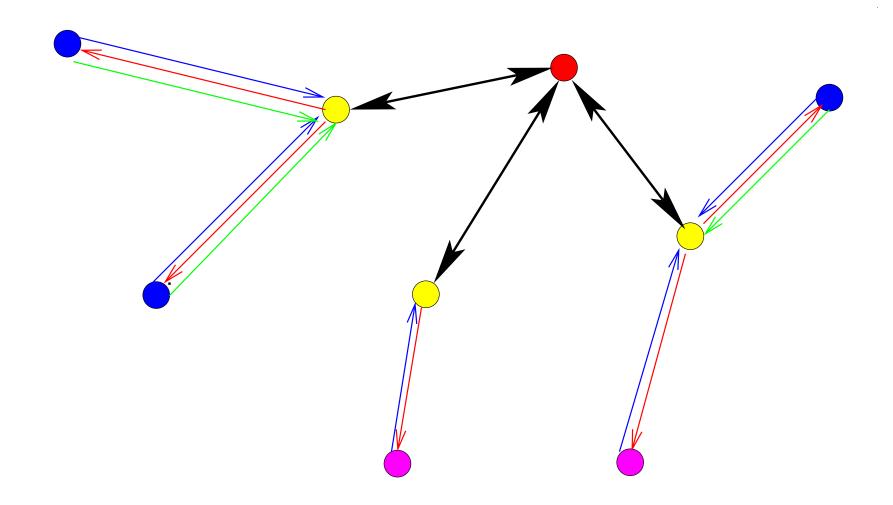


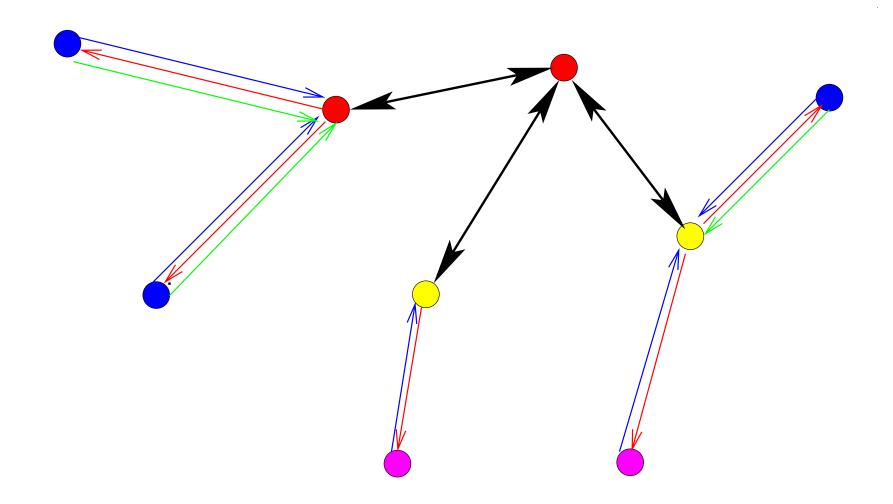


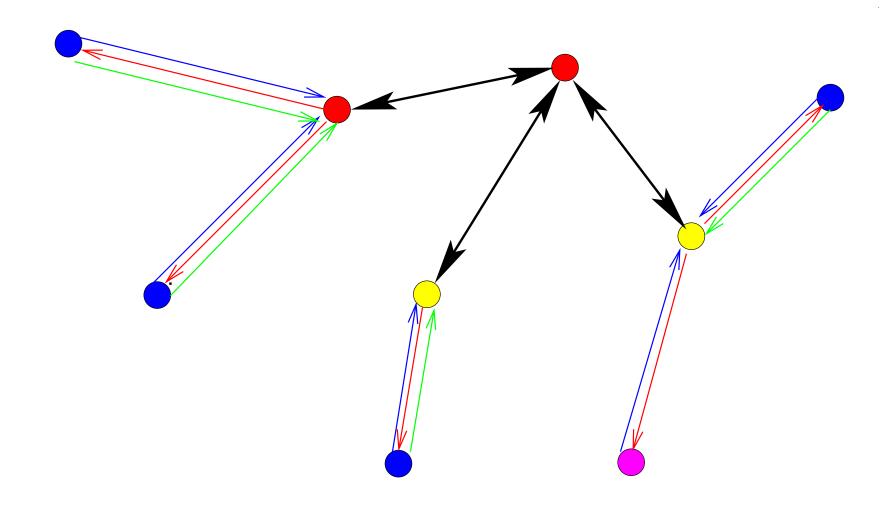


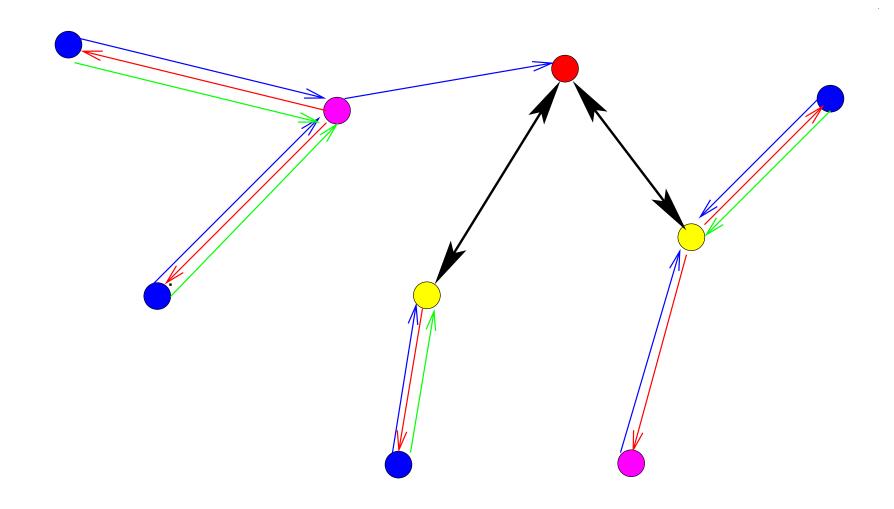


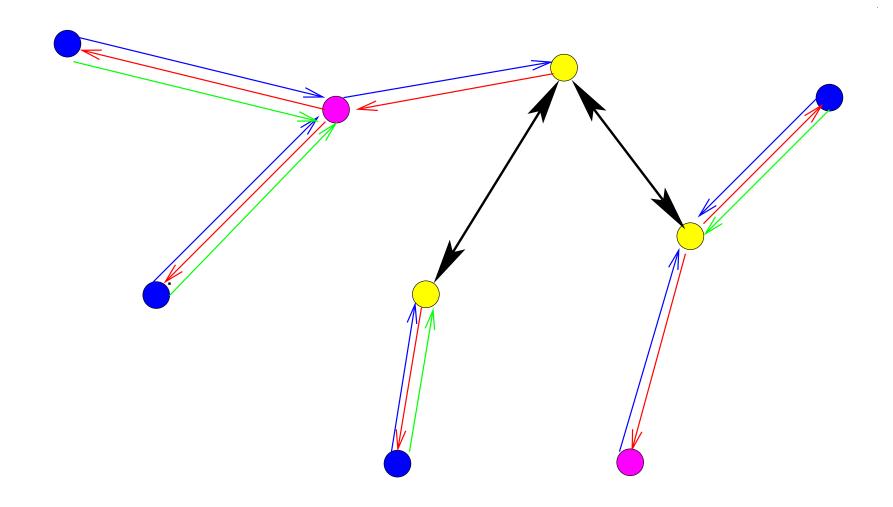


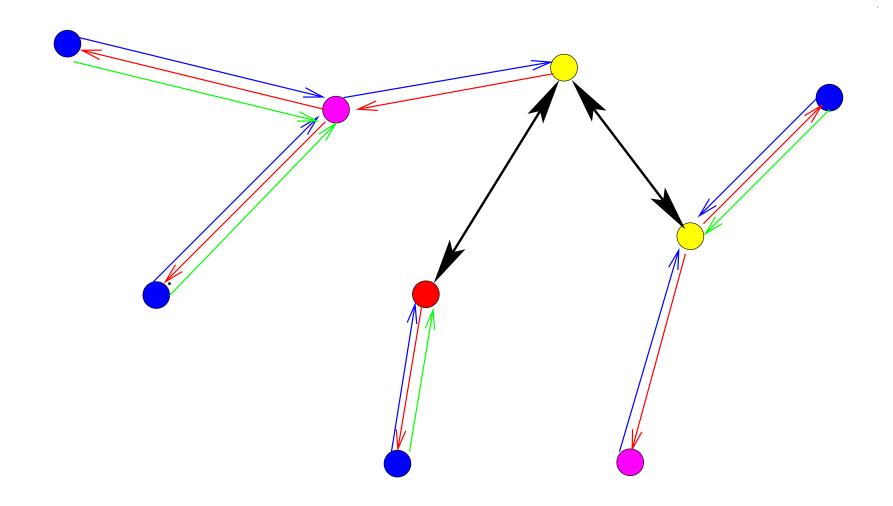


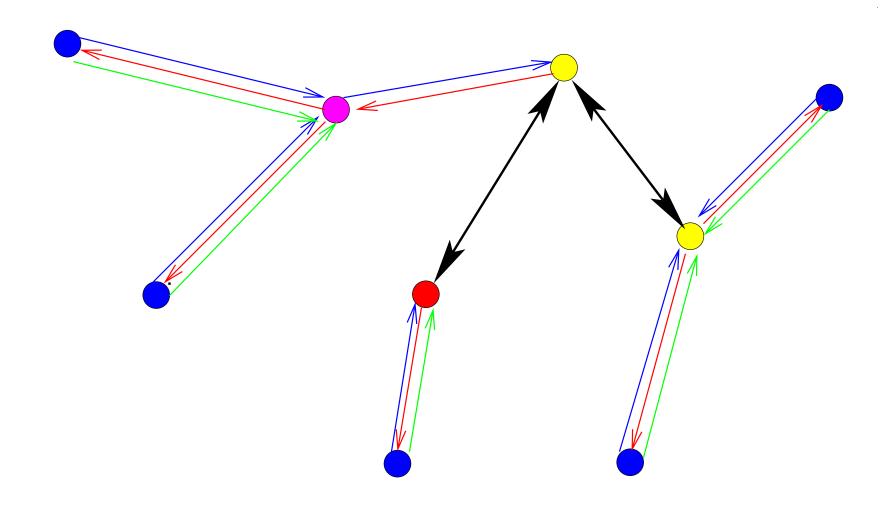


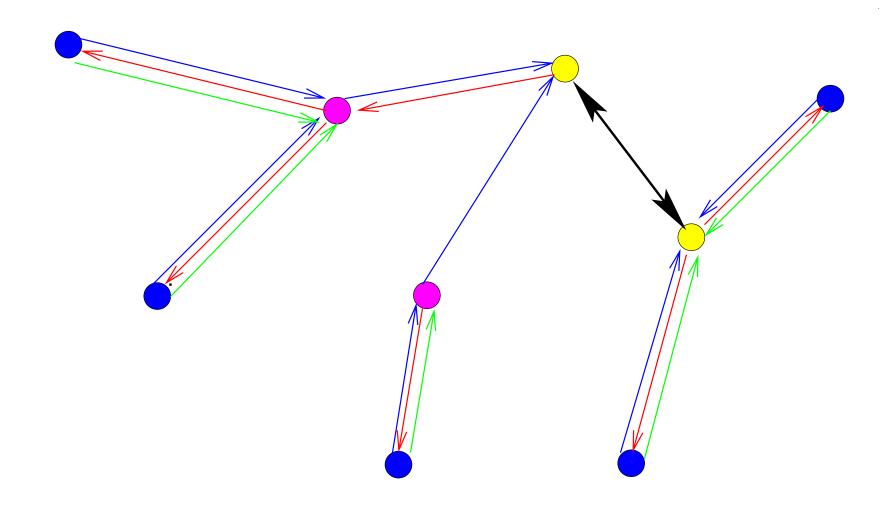


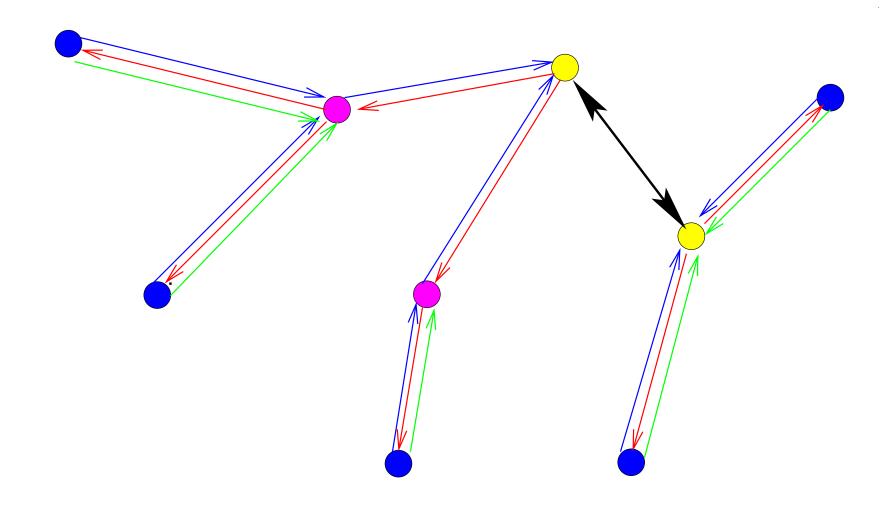


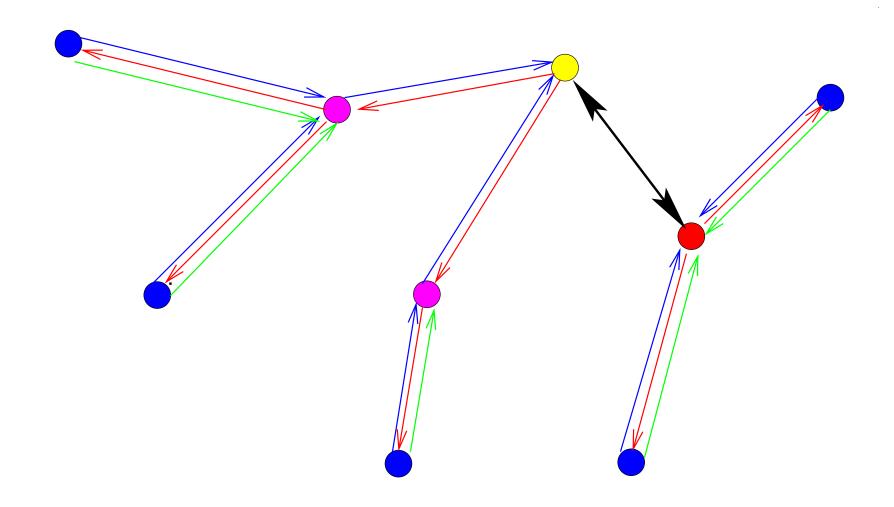


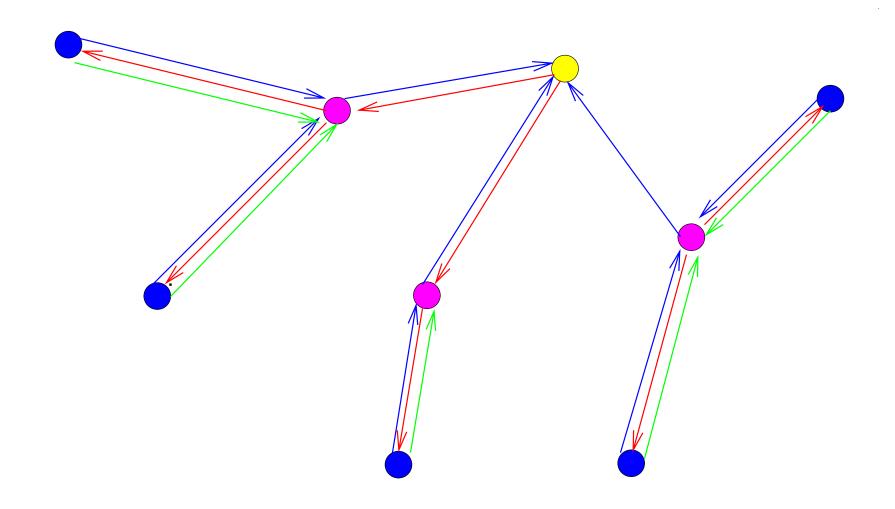


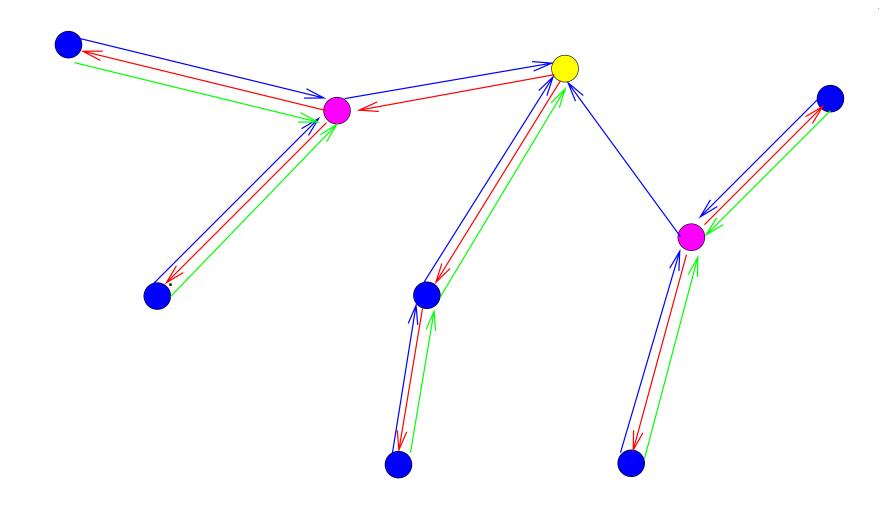


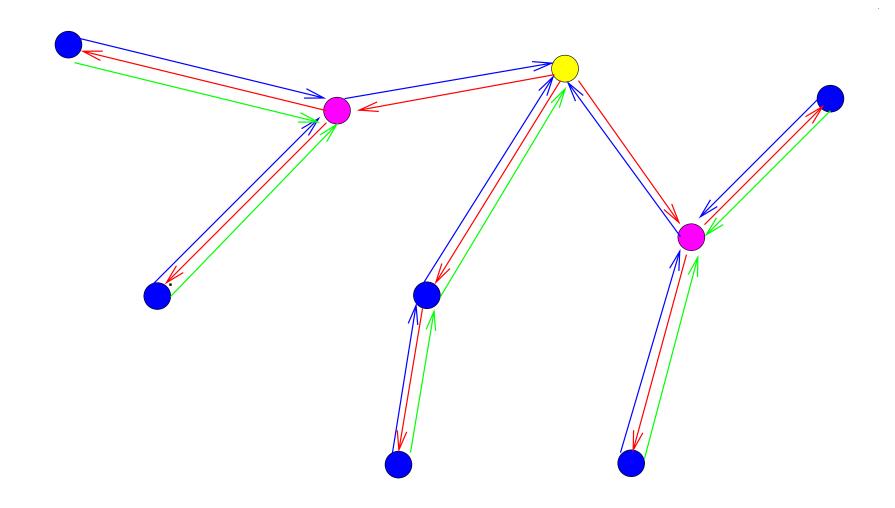


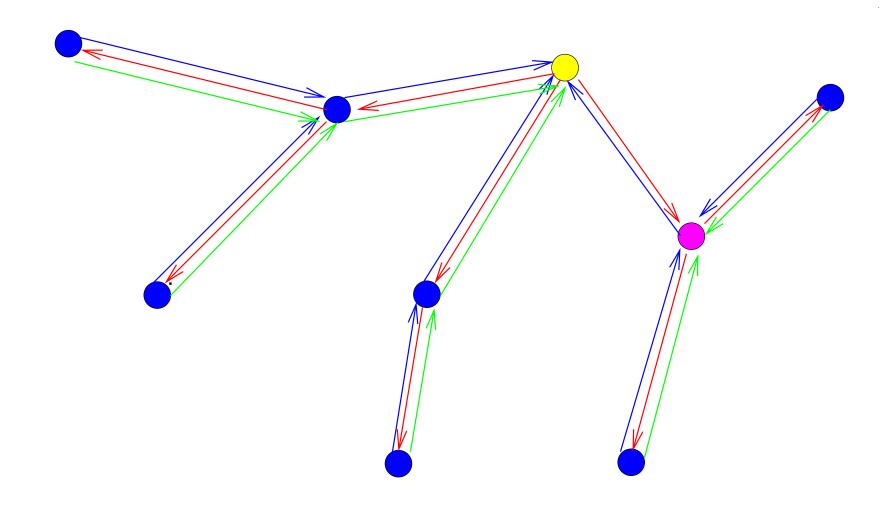


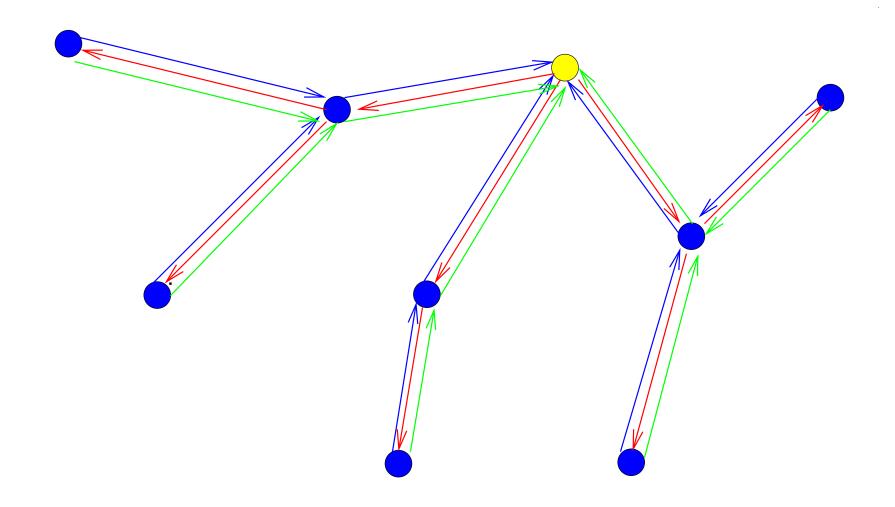


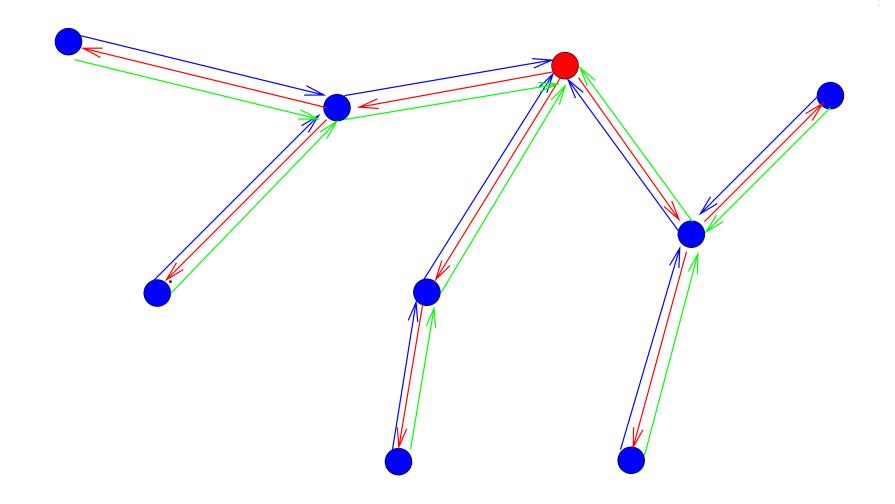












Invariant (1)

- Each node sends AT MOST one message
- Each node receives AT MOST one acknowledgment
- Each node sends AT MOST one confirmation

 $msg \in ND \nrightarrow ND$

 $ack \in ND \nrightarrow ND$

 $tr \subseteq ack \subseteq msg \subseteq gr$

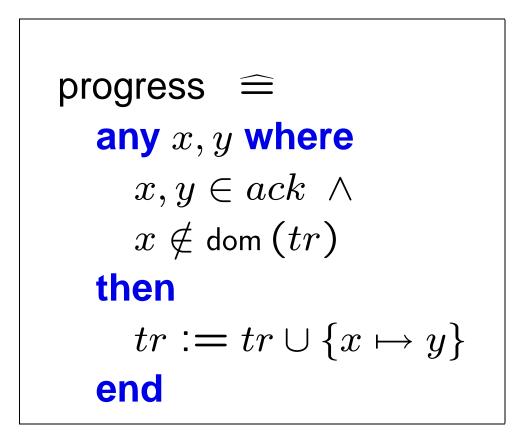
Node x sends a message to node y

send_msg ≘ any x, y where $x, y \in gr \land$ $x \notin \operatorname{dom}(tr) \land$ $y, x \notin tr \land$ $gr[\{x\}] = tr^{-1}[\{x\}] \cup \{y\} \land$ $y, x \notin ack \land$ $x \notin \operatorname{dom}(msq)$ then $msg := msg \cup \{x \mapsto y\}$ end

Node y sends an acknowledgement to node x

send_ack \cong any x, y where $x, y \in msg - ack \land$ $y \notin dom (msg)$ then $ack := ack \cup \{x \mapsto y\}$ end

Node x sends a confirmation to node y



Invariant (2)

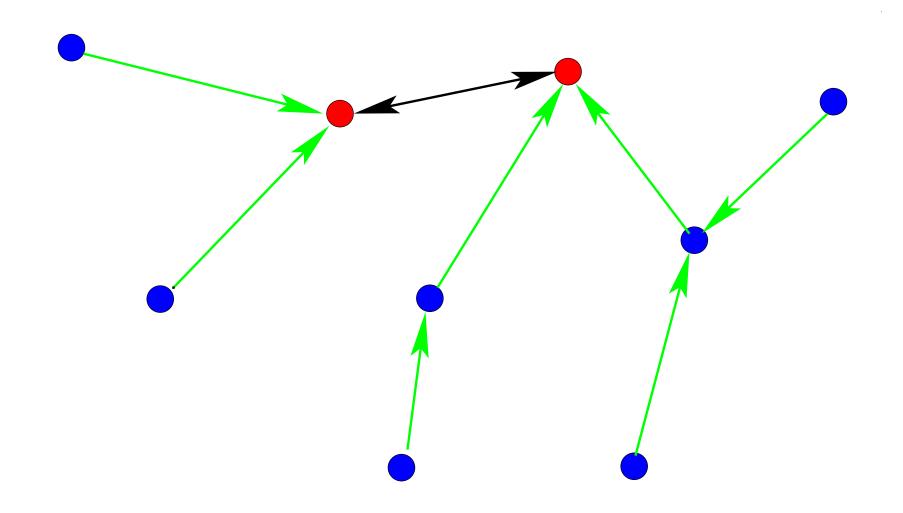
$$\forall (x, y) \cdot \begin{pmatrix} x, y \in msg - ack \\ \Rightarrow \\ x, y \in gr \land \\ x \notin dom(tr) \land y \notin dom(tr) \land \\ gr[\{x\}] = tr^{-1}[\{x\}] \cup \{y\} \end{pmatrix}$$

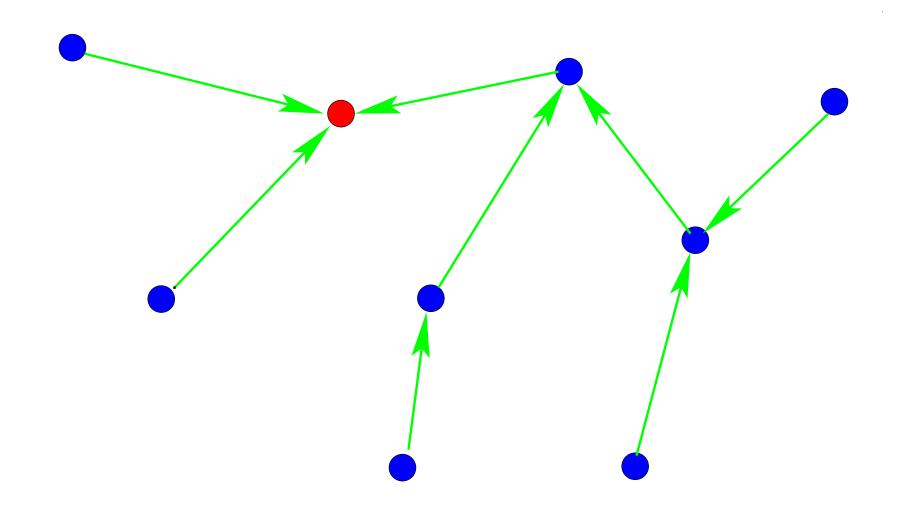
$$\forall (x, y) \cdot \begin{pmatrix} x, y \in ack \land \\ x \notin dom(tr) \\ \Rightarrow \\ x, y \in gr \land \\ y \notin dom(tr) \land \\ gr[\{x\}] = tr^{-1}[\{x\}] \cup \{y\} \end{pmatrix}$$

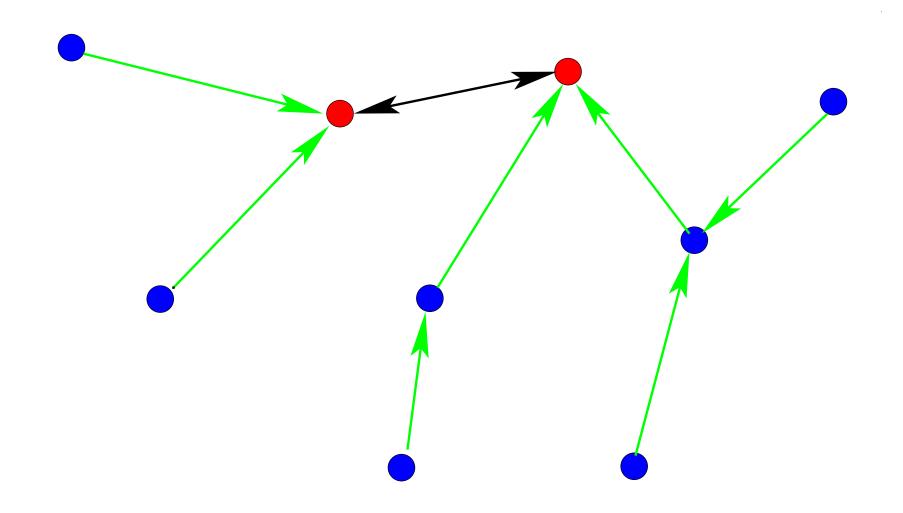
Second Refinement: The problem of contention

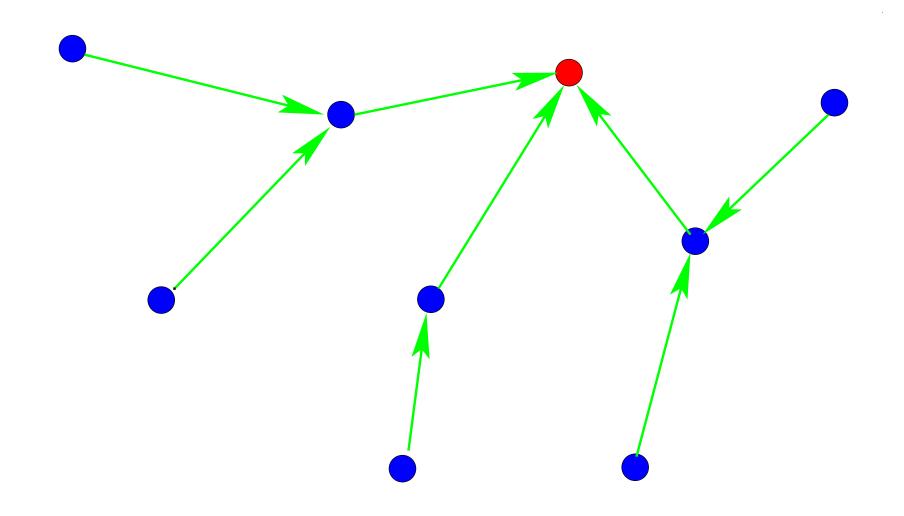
- Explaining the problem
- Proposing a partial solution
- Towards a better treatment

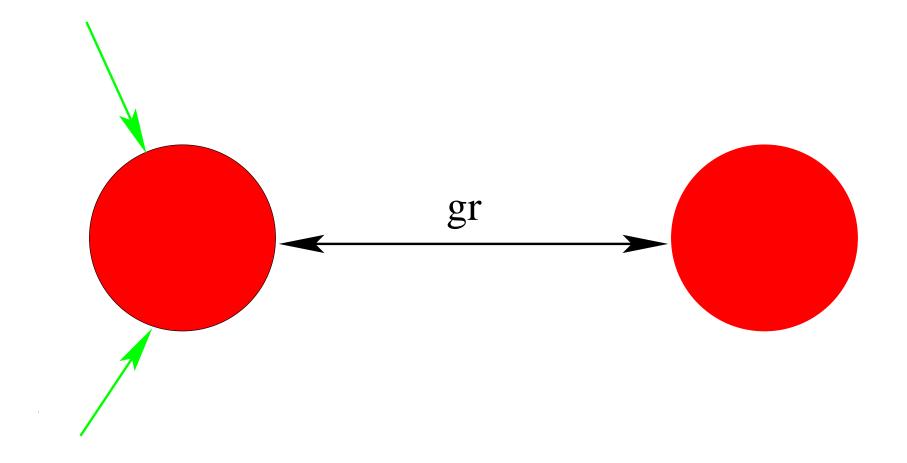
- Back to the local animation

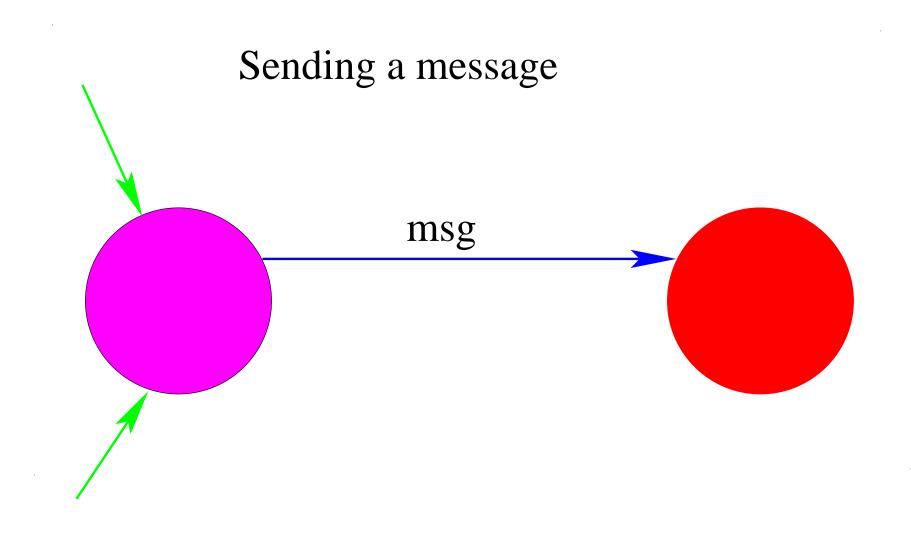


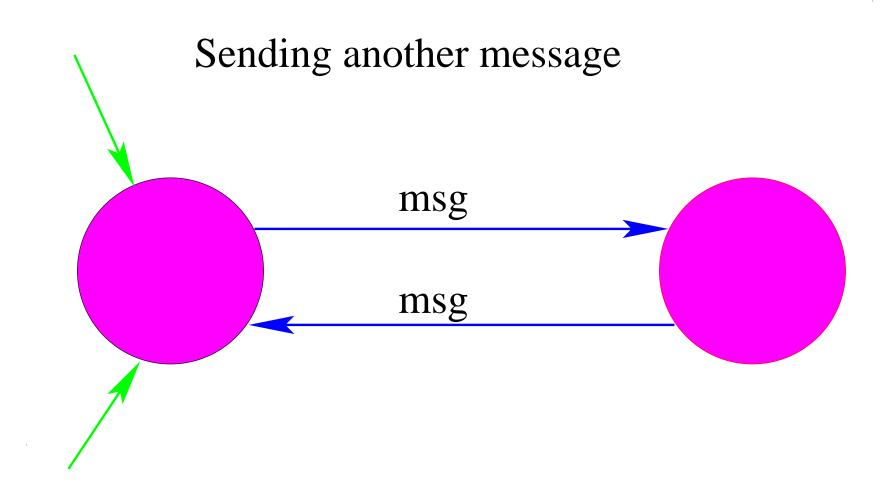


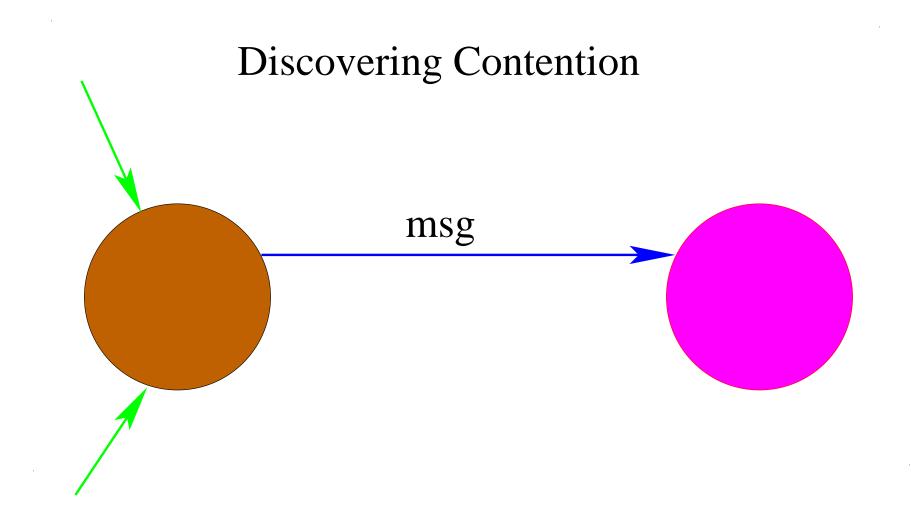


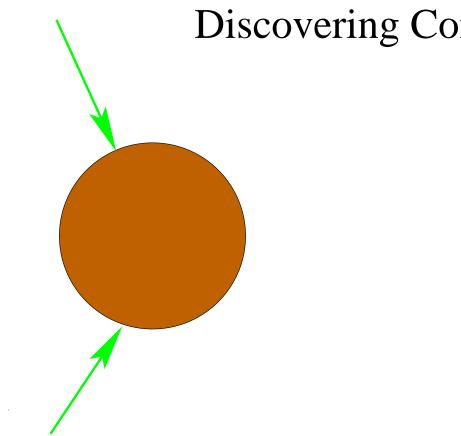


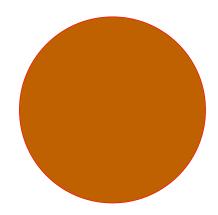




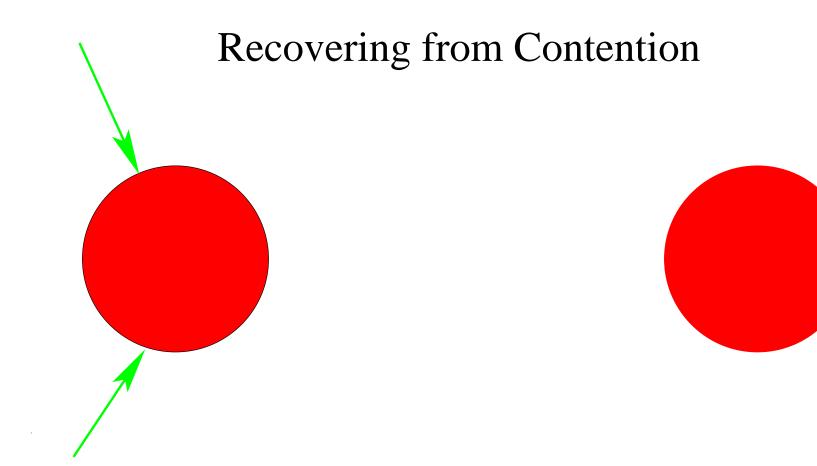


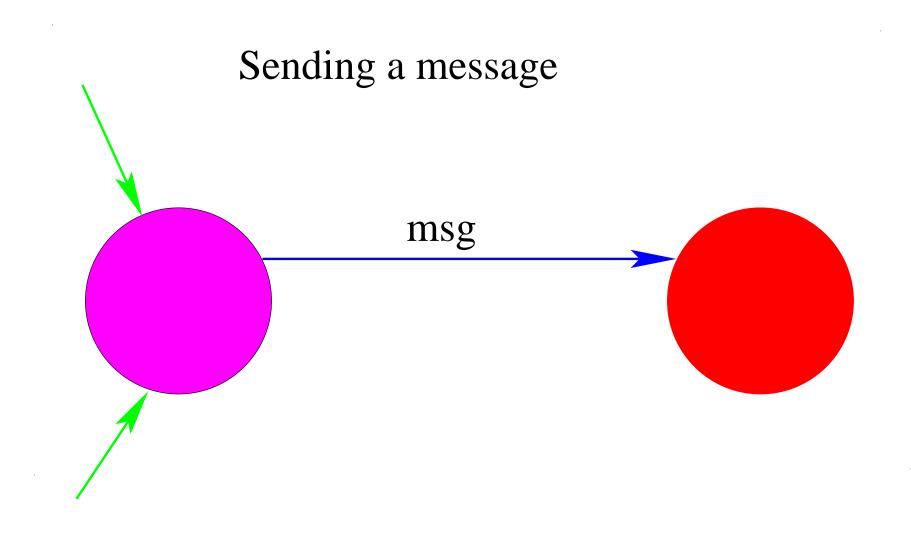


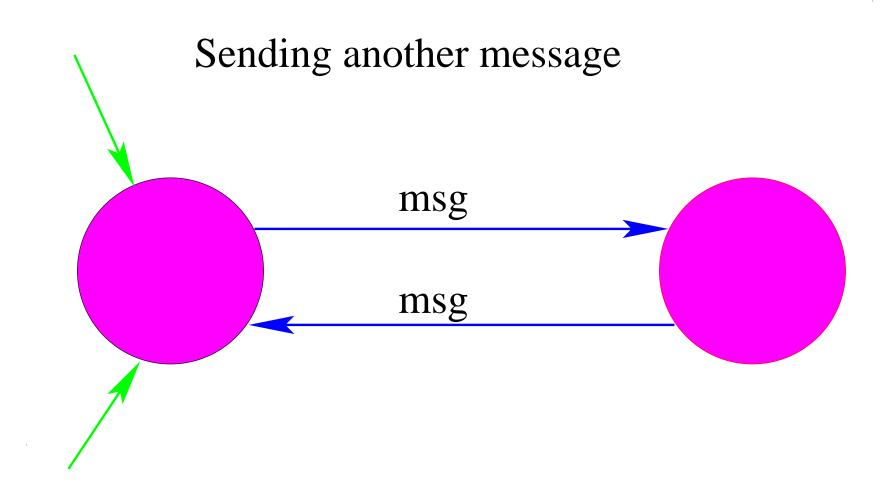


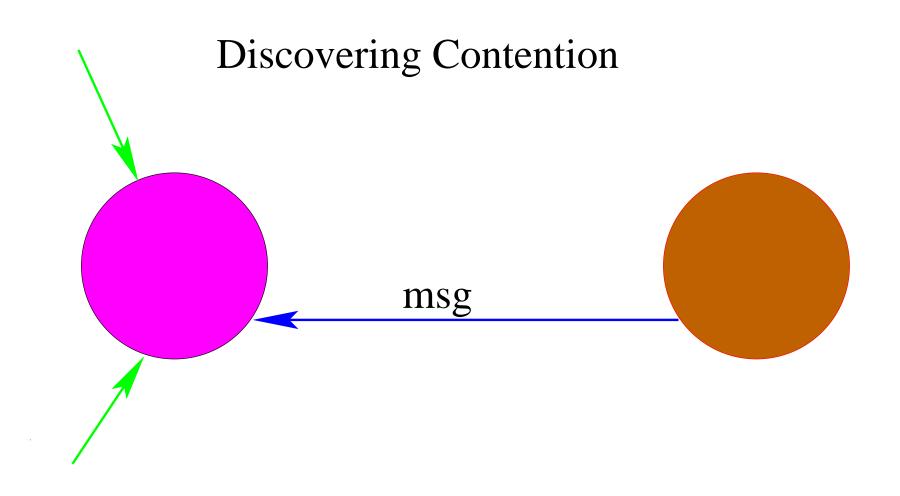


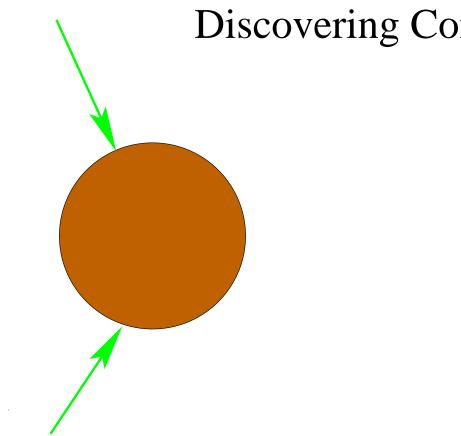
Discovering Contention

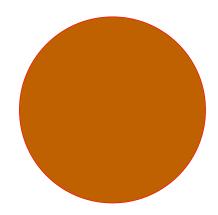




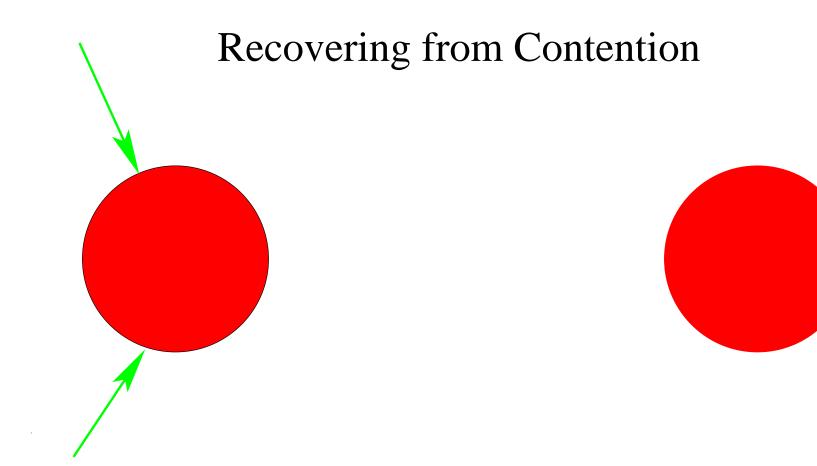


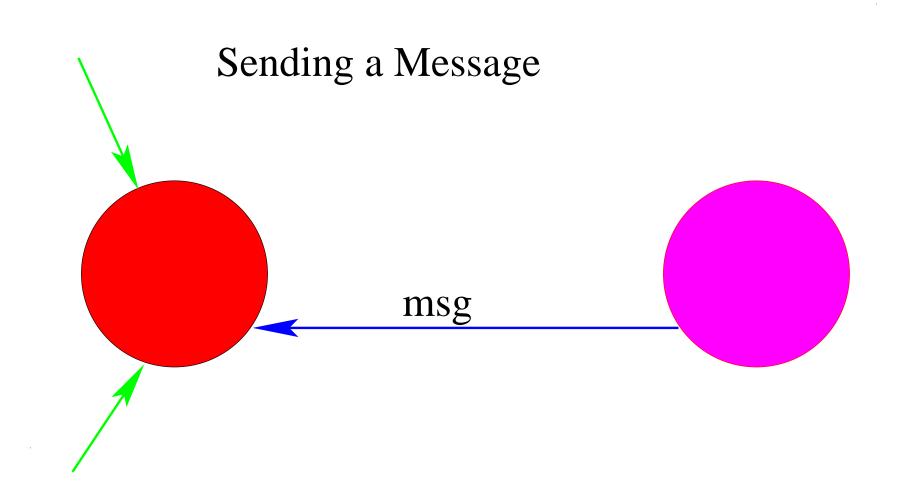


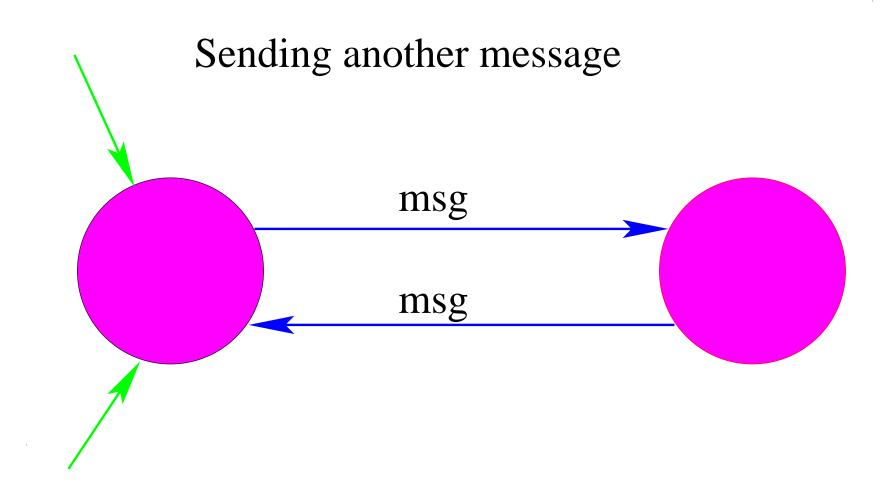


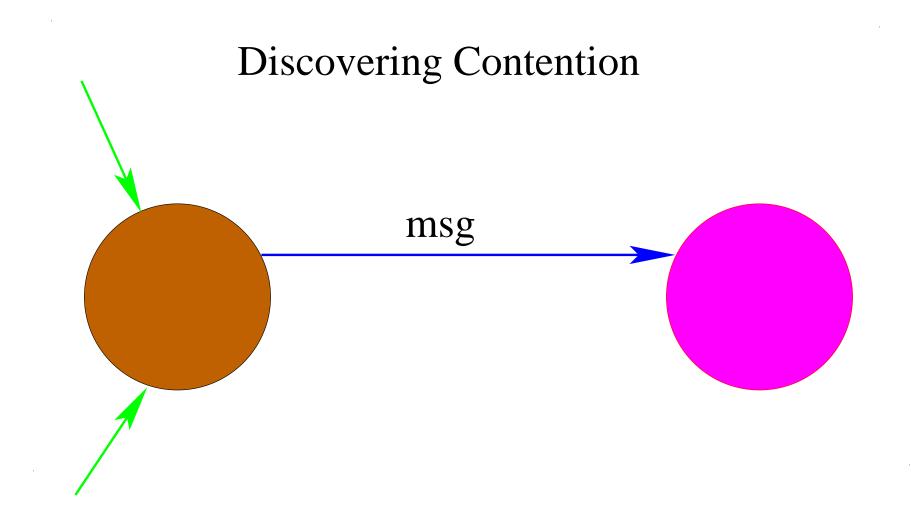


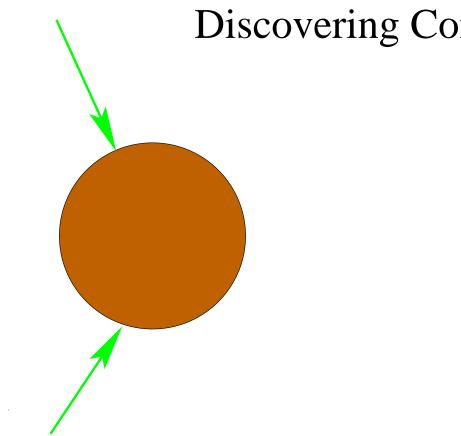
Discovering Contention

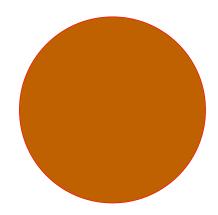




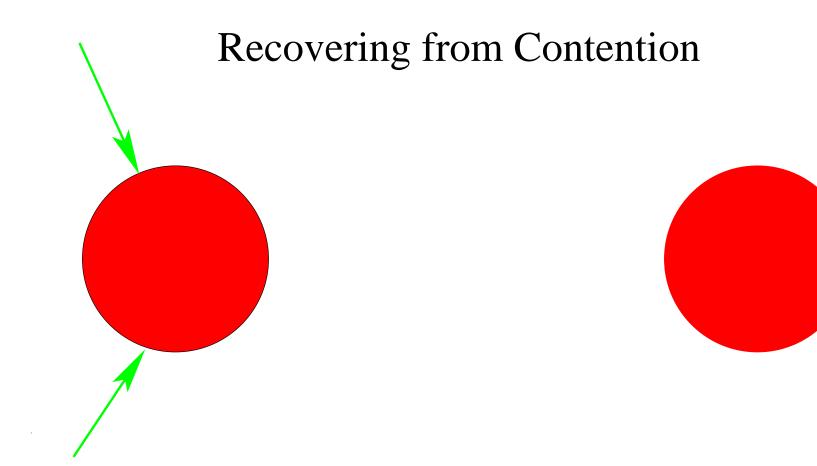


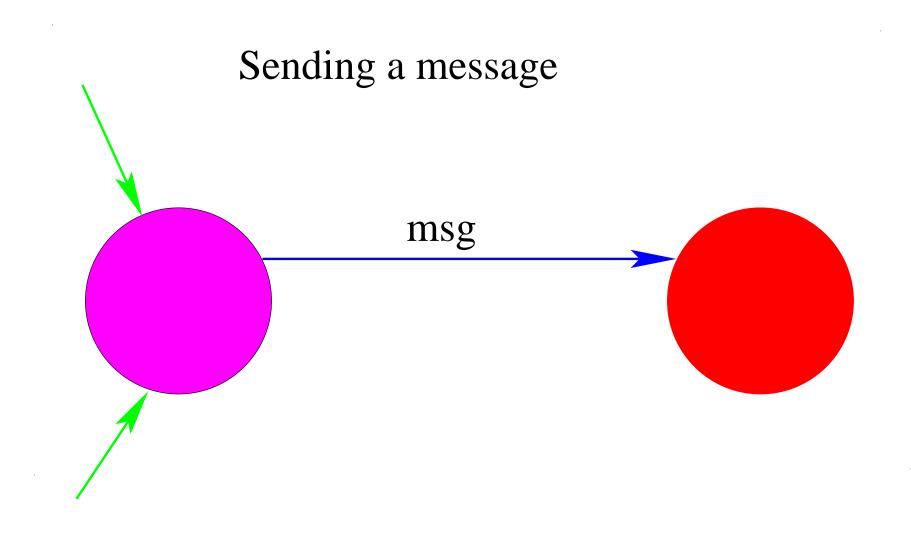


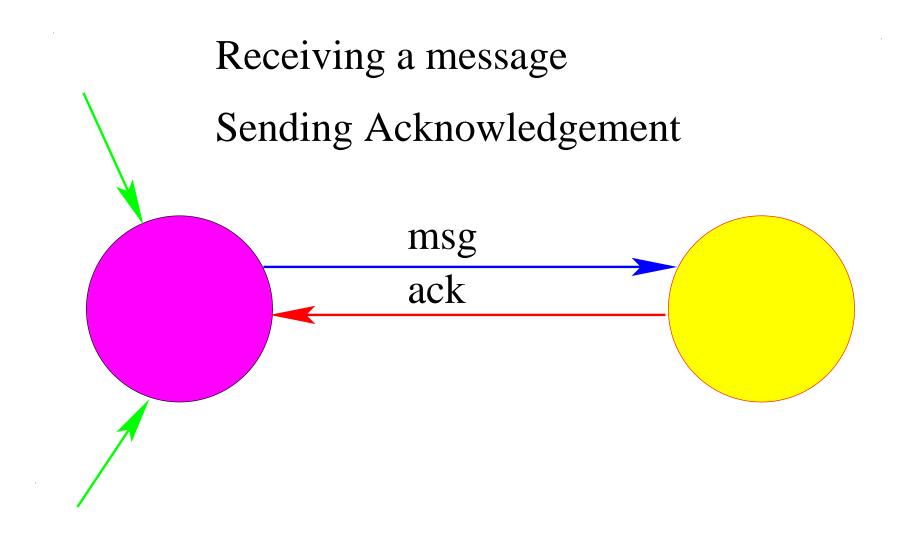


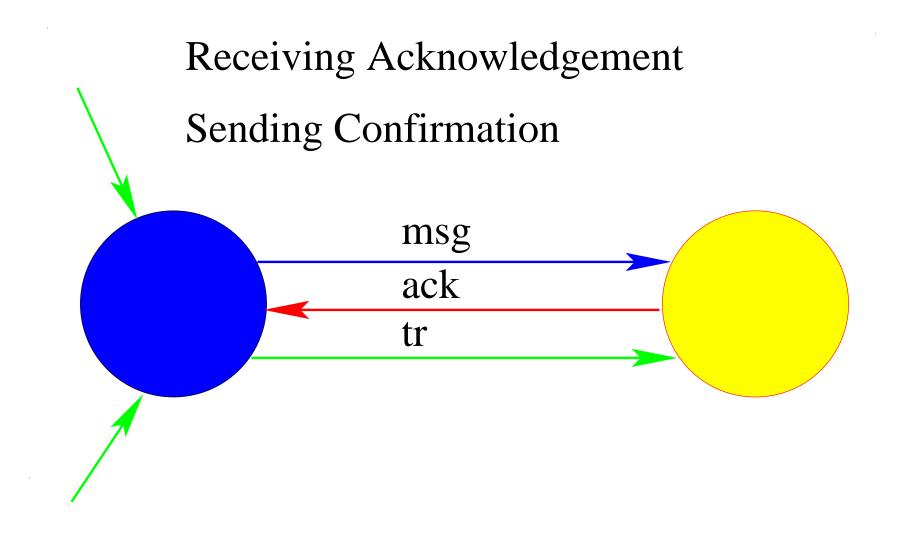


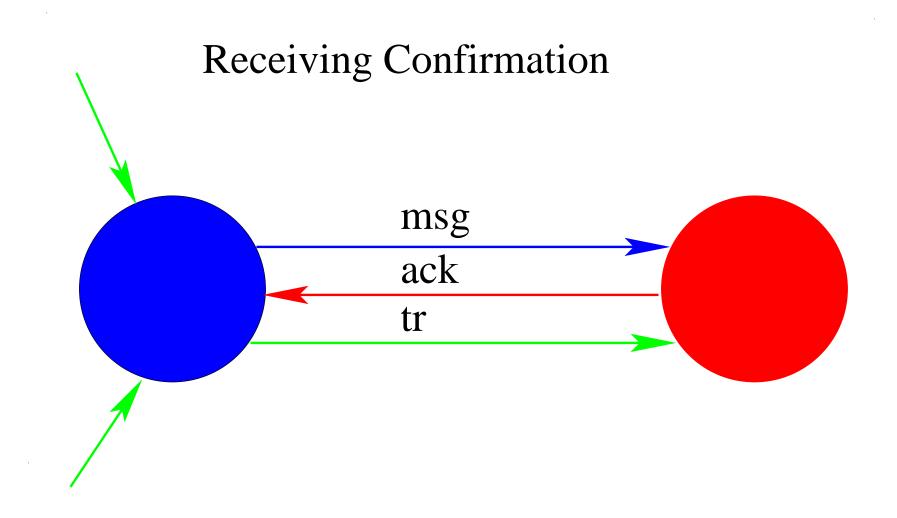
Discovering Contention











- Node y discovers the contention with node x because:
 - It has sent a message to node \boldsymbol{x}
 - It has not yet received acknowledgment \boldsymbol{x}
 - It receives instead a message from node \boldsymbol{x}

Discovering the Contention (2)

- Node \boldsymbol{x} also discovers the contention with node \boldsymbol{y}

- Assumption: The time between both discoveries IS SUPPOSED TO BE BOUNDED BY τ ms

- The time τ is the maximum transmission time between 2 connected nodes

- Each node waits for τ ms after its own discovery

 After this, each node thus knows that the other has also discovered the contention

- Each node then retries immediately
- PROBLEM: This may continue for ever

- Each node waits for τ ms after its own discovery

- Each node then choses with equal probability:
 - either to wait for a short delay
 - or to wait for a large delay

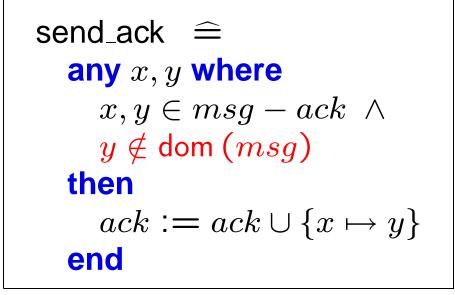
- Each node then retries

- Question: Does this solves the problem ?

- Are we sure to eventually have one node winning ?

- Answer: Listen carefully to Caroll Morgan's lectures

Node \boldsymbol{y} discovers a contention with node \boldsymbol{x}



contention $\widehat{=}$ any x, y where $x, y \in msg - ack \land$ $y \in dom (msg)$ then $cnt := cnt \cup \{x \mapsto y\}$ end

- Introducing a dummy contention channel: cnt

 $cnt \in ND \nrightarrow ND$

 $cnt \subseteq msg$

 $ack \cap cnt = \emptyset$

Solving the contention (simulating the τ delay)

solve_contention $\widehat{=}$ any x, y where $x, y \in cnt \cup cnt^{-1}$ then $msg := msg - cnt \parallel$ $cnt := \emptyset$ end - 73 proofs

- Among which 34 were interactive

- The representation of the graph gr is modified

- The representation of the tree tr is modified

- Other data structures are localized

The graph gr and the tree tr are now localized

 $nb \in ND \rightarrow \mathbb{P}(ND)$

 $\forall x \cdot (x \in ND \Rightarrow nb(x) = gr[\{x\}])$

 $sn \in ND \rightarrow \mathbb{P}(ND)$

 $\forall x \cdot (x \in ND \implies sn(x) \subseteq tr^{-1}[\{x\}])$

 $bm \subseteq ND$

bm = dom (msg)

 $bt \subseteq ND$

 $bt = \operatorname{dom}\left(tr\right)$

 $ba \in ND \to \mathbb{P}(ND)$

 $\forall x \cdot (x \in ND \implies ba(x) = ack^{-1}[\{x\}])$

- Node x is elected the leader

elect
$$\widehat{=}$$

any x where
 $x \in ND \land$
 $nb(x) = sn(x)$
then
 $rt := x$
end

- Node x sends a message to node y (y is unique)

send_msg
$$\cong$$

any x, y where
 $x \in ND - bm \land$
 $y \in ND - (ba(x) \cup sn(x)) \land$
 $nb(x) = sn(x) \cup \{y\}$
then
 $msg := msg \cup \{x \mapsto y\} \parallel$
 $bm := bm \cup \{x\}$
end

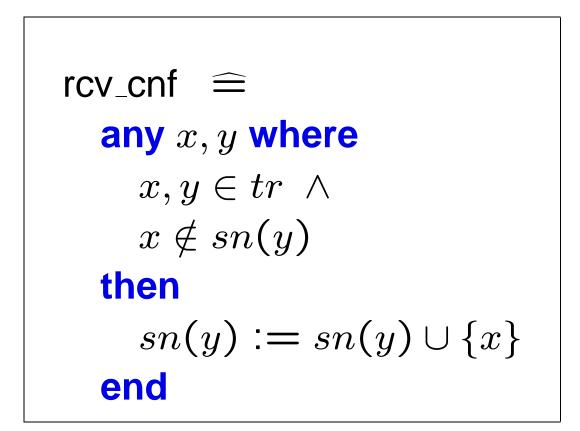
- Node y sends an acknowledgement to node x

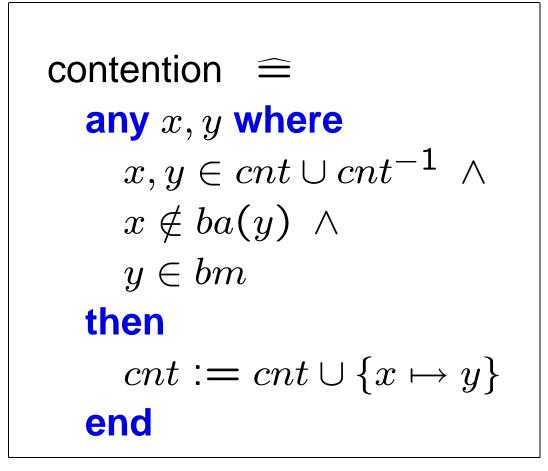
```
send_ack \widehat{=}
  any x, y where
     x, y \in msg \land
     x \notin ba(y) \land
     y \notin bm
  then
     ack := ack \cup \{x \mapsto y\}
                                    ba(y) := ba(y) \cup \{x\}
  end
```

- Node x sends a confirmation to node y

```
progress \widehat{=}
  any x, y where
     x, y \in ack \land
     x \notin bt
  then
     tr := tr \cup \{x \mapsto y\} \quad \|
     bt := bt \cup \{x\}
   end
```

- Node y receives confirmation from node x





solve_contention \cong any x, y where $x, y \in cnt \cup cnt^{-1}$ then msg := msg - cnt $bm := bm - dom(cnt) \parallel$ $cnt := \emptyset$ end

- 29 proofs

- Among which 19 were interactive

- 119 proofs

- Among which 63 were interactive

- Establishing the mathematical framework

- Establishing the mathematical framework

- Resolving the mathematical problem in one shot

- Establishing the mathematical framework

- Resolving the mathematical problem in one shot

- Resolving the same problem on a step by step basis

- Establishing the mathematical framework

- Resolving the mathematical problem in one shot
- Resolving the same problem on a step by step basis

- Involving communication by means of messages

- Establishing the mathematical framework

- Resolving the mathematical problem in one shot
- Resolving the same problem on a step by step basis

- Involving communication by means of messages

- Towards the localization of data structures