Response to external perturbations in systems with long-range interactions

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Fondation des Treilles, october 22-27 (2012)

Plan

- HMF model
- Quasistationary states
- Inhomogeneous steady states
- Linear response of quasistationary states

Gravity

Einstein equations

$$\frac{d^2x^{\lambda}}{d\tau^2} + \Gamma^{\lambda}_{\mu\nu}\frac{dx^{\mu}}{d\tau}\frac{dx^{\nu}}{d\tau} = 0$$

Newton equations

$$\frac{d^2 \mathbf{r}_i}{d\tau^2} = \nabla_i \sum_{j=1}^{N-1} \frac{Gm_j}{|\mathbf{r}_j - \mathbf{r}_i|}$$

HMF model

$$H = \sum_{i=1}^{N} \frac{p_i^2}{2} + \frac{1}{2N} \sum_{i,j=1}^{N} (1 - \cos(\theta_i - \theta_j))$$



Magnetization
$$\mathbf{M} = \lim_{N \to \infty} \left(\frac{\sum_{i=1}^{N} \cos \theta_i}{N}, \frac{\sum_{i=1}^{N} \sin \theta_i}{N} \right) = (M_x, M_y)$$

Energy $U = \lim_{N \to \infty} \frac{H}{N}$

Self-gravitating ring

$$H = \frac{1}{2} \sum_{i=1}^{N} p_i^2 + \frac{1}{2N} \sum_{i,j} V_{\varepsilon}(\theta_i - \theta_j),$$
$$V_{\varepsilon}(\theta_i - \theta_j) = -\frac{1}{\sqrt{2}} \frac{1}{\sqrt{1 - \cos(\theta_i - \theta_j) + \varepsilon}}$$

where ε is the softening parameter.



T. Tatekawa, F. Bouchet, T. Dauxois

Quasi-stationary states



U = 0.69, from left to right $N = 10^2, 10^3, 2 \times 10^3, 5 \times 10^3, 10^4, 2 \times 10^4$. Initially $\Delta \theta = \pi$, hence $M_0 = 0$.

Y. Y. Yamaguchi, J. Barre, F. Bouchet, T. Dauxois

Time scale



Power law increase of the lifetime, exponent 1.7

1D self-gravitating



The lifetime increases with N.

M. Joyce and T. Worrakitpoonpon

Separation of time scales



Vlasov equation

$$\frac{\partial f}{\partial t} + p \frac{\partial f}{\partial \theta} - \frac{d\Phi(\theta)[f]}{d\theta} \frac{\partial f}{\partial p} = 0$$

$$\Phi(\theta)[f] = 1 - M_x[f] \cos(\theta) - M_y[f] \sin(\theta) ,$$

$$M_x[f] = \int f(\theta, p, t) \cos \theta d\theta dp ,$$

$$M_y[f] = \int f(\theta, p, t) \sin \theta d\theta dp .$$

Energy

$$U[f] = \int (p^2/2)f(\theta, p, t)d\theta dp + 1/2 - (M_x^2 + M_y^2)/2$$

and momentum

$$P[f] = \int pf(\theta, p, t) \mathrm{d}\theta \mathrm{d}p$$

are conserved.

Water bag







Exact inhomogeneous steady states

Vlasov equation for the HMF model

$$\frac{\partial f}{\partial t} + p \frac{\partial f}{\partial \theta} - \frac{\partial V[f](\theta, t)}{\partial \theta} \frac{\partial f}{\partial p} = 0$$

where

$$V[f](\theta, t) = \iint d\theta' dp' f(\theta', p', t) \left(1 - \cos(\theta' - \theta)\right)$$

Any function

$$f_S(heta,p)=F(h(heta,p))$$
 with

with

$$h(\theta, p) = \frac{p^2}{2} + V[f_S](\theta).$$

and

$$V(\theta)[f_S] = 1 - M_x[f_S]\cos(\theta) - M_y[f_S]\sin(\theta)$$

is a stationary solution of the Vlasov equation, once we require that it has the correct properties of a one-particle distribution (Bernstein-Green-Kruskal (BGK) modes).

P. de Buyl, D. Mukamel

Non interacting particles

Consider the dynamics of an ensemble of *uncoupled particles* moving in a fixed external field H

$$\epsilon(\theta, p) = \frac{p^2}{2} - H\cos\theta$$

For an arbitrary function $F(\epsilon(\theta, p))$ to be a steady state of the interacting model, H has to satisfy the following self-consistency condition

$$H = m_x = \iint d\theta dp F(\epsilon(\theta, p)) \cos \theta \quad ; \quad m_y = 0$$

To relate an initial distribution to the steady state to which it evolves, consider an initial distribution $f_0(\theta, p)$. The dynamics of the uncoupled model is such that particles in a given energy shell $[\epsilon, \epsilon + d\epsilon]$ keep moving inside that shell, eventually reaching a homogeneous distribution within it. As a result, the system attains the following steady state distribution

$$P(\theta, p) = \frac{\iint d\theta' dp' f_0(\theta', p') \,\delta\left(\epsilon(\theta', p') - \epsilon(\theta, p)\right)}{\iint d\theta' dp' \,\delta\left(\epsilon(\theta', p') - \epsilon(\theta, p)\right)}$$

Initial waterbag

$$f_0(\theta, p) = \begin{cases} (4\Delta\theta\Delta p)^{-1} &, \text{ for } |\theta| \le \Delta\theta \text{ and } |p| \le \Delta p \\ 0 &, \text{ otherwise.} \end{cases}$$



Energy distribution

In order to evaluate $P(\theta, p)$, it is convenient to first consider the energy distribution $P_{\epsilon}(\epsilon)$. For the waterbag initial state it is given by

$$P_{\epsilon}(\epsilon) = \frac{1}{4\Delta\theta\Delta p} \int d\theta \int_{-\Delta p}^{\Delta p} dp \,\,\delta(\frac{p^2}{2} - H\cos\theta - \epsilon)$$

Integrating over p

$$P_{\epsilon}(\epsilon) = \frac{1}{2\Delta\theta\Delta p} \int d\theta \, \frac{1}{\sqrt{2(\epsilon + H\cos\theta)}} \,,$$

for $-H \leq \epsilon \leq \Delta p^2/2 - H \cos \Delta \theta$ and zero outside this range.

The integration over θ need to be done in the domain enclosed by the initial waterbag

$$0 \le \epsilon + H\cos\theta \le \frac{\Delta p^2}{2}.$$

Thus,

$$P_{\epsilon}(\epsilon) = \frac{\sqrt{2}}{2\Delta\theta\Delta p} \int_{\theta_1}^{\theta_0} d\theta \frac{1}{\sqrt{(\epsilon + H\cos\theta)}}$$

where θ_0 and θ_1 satisfy the conditions described in the next slide.

(1)

Integration limits



$$\theta_0 = \begin{cases} \arccos(-\epsilon/H) &, \text{ for } -H < \epsilon < -H \cos \Delta \theta \\ \Delta \theta &, \text{ for } \epsilon \ge -H \cos \Delta \theta \end{cases},$$

$$\theta_1 = \begin{cases} 0 & , \text{ for } -H < \epsilon \le \Delta p^2/2 - H \\ \arccos(\frac{\Delta p^2/2 - \epsilon}{H}) & , \text{ for } \Delta p^2/2 - H \le \epsilon < \\ \Delta p^2/2 - H \cos \Delta \theta \\ \Delta \theta & , \text{ for } \epsilon \ge \Delta p^2/2 - H \cos \Delta \theta \end{cases}$$

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Steady state distribution

In the steady state, the distribution is such that all the microstates corresponding to a given energy are equally probable. The boundaries on (θ, p) imposed by the initial waterbag are no longer valid. Thus, the steady state distribution $P(\theta, p)$ may be expressed as

$$P(\theta, p) = \frac{1}{4\Delta\theta\Delta p} \frac{P_{\epsilon}(\epsilon(\theta, p))}{Q_{\epsilon}(\epsilon(\theta, p))} \equiv \bar{P}_{\epsilon}(\epsilon(\theta, p)) ,$$

where $Q(\epsilon)$ is given by $P(\epsilon)$ with the bounds given by the waterbag removed. Integrating over p, it is straightforward to express, without any approximation, the marginal in θ as

$$P_{\theta}(\theta, H) = \sqrt{2} \int_{-H\cos\theta}^{\infty} d\epsilon \, \frac{1}{\sqrt{(\epsilon + H\cos\theta)}} \, \bar{P}_{\epsilon}(\epsilon)$$

and then impose the consistency relation

$$H = \int_{-\pi}^{+\pi} d\theta P_{\theta}(\theta, H) \cos \theta \; .$$

Marginals



Marginals in θ and in p of the steady state distribution for $\Delta \theta = 1$ and $\Delta p = 1$.

Results

Unless $\Delta \theta = \pi$, the r.h.s of the consistency relations is proportional to \sqrt{H} . This implies that there is always a tail in magnetization at large values of Δp . Here, $\Delta \theta = 1$.



 $\Delta \theta = \pi$



Generic homogeneous distribution

$$f_0(\theta, p) = \frac{\phi_0(p)}{2\pi}$$

$$P_{QSS}(\epsilon) = \frac{1}{2\pi} \frac{\int d\theta' \phi_0(\sqrt{2(H\cos\theta' + \epsilon)})(H\cos\theta' + \epsilon)^{-1/2}}{\int d\theta'(H\cos\theta' + \epsilon)^{-1/2}}$$

Formally expanding around H = 0

$$P_{QSS}(\theta, p) = \frac{\phi_0(p)}{2\pi} - \frac{\phi'_0(p)\cos\theta}{2\pi p}H + O(H^2)$$

$$H = \int d\theta dp P_{QSS}(\theta, p) \cos \theta = \int d\theta dp \frac{\phi_0(p)}{2\pi} \cos \theta - \int d\theta dp \frac{\phi'_0 \cos^2 \theta}{2\pi p} H + O(H^2)$$

which gives

$$1 + \frac{1}{2} \int dp \frac{\phi_0'(p)}{p} = 0$$

Relaxation time scales



Perturbed hamiltonian

$$H(t) = H_0 + H_{\text{ext}} = H_0 - K(t) \sum_{i=1}^N b(q_i)$$

Vlasov equation as a Liouville equation for f

$$\frac{\partial f}{\partial t} - \mathcal{L}(q, p, t)[f]f = 0$$

$$\mathcal{L}(q, p, t)[f] \equiv -p\frac{\partial}{\partial q} + \frac{\partial \Phi(q, t)[f]}{\partial q}\frac{\partial}{\partial p} - K(t)\frac{\partial b}{\partial q}\frac{\partial}{\partial p}$$

Stationary state of the unperturbed Hamiltonian H_0

$$\mathcal{L}_0(q,p)[f_0]f_0 = 0$$

$$\mathcal{L}_0(q,p)[f_0] = -p\frac{\partial}{\partial q} + \frac{\partial\bar{\Phi}(q)[f_0]}{\partial q}\frac{\partial}{\partial p}$$

A. Patelli, S. Gupta, C. Nardini

Linearized Vlasov equation

$$f(q, p, t) = f_0(q, p) + \Delta f(q, p, t)$$

 $\Delta f(q, p, 0) = 0$

$$\frac{\partial \Delta f}{\partial t} - \mathcal{L}_0(q, p)[f_0]\Delta f = \mathcal{L}_{\text{ext}}(q, p, t)[\Delta f]f_0(q, p)$$
$$\mathcal{L}_{\text{ext}}(q, p, t)[\Delta f] = \frac{\partial v_{\text{eff}}(q, t)[\Delta f]}{\partial q}\frac{\partial}{\partial p}$$

$$v_{\text{eff}}(q,t)[\Delta f] = \Phi(q,t)[\Delta f] - K(t)b(q)$$

Evolution of an observable

Formal solution of the linearized equation

$$\Delta f(q, p, t) = \int_{0}^{t} d\tau \ e^{(t-\tau)\mathcal{L}_{0}(q, p)[f_{0}]} \mathcal{L}_{\text{ext}}(q, p, \tau)[\Delta f] f_{0}(q, p)$$

$$\langle \Delta a(q) \rangle(t) \equiv \langle a(q) \rangle(t) - \langle a(q) \rangle_{f_0} = \int dq dp \ a(q) \Delta f(q, p, t)$$

$$\langle \Delta a(q) \rangle(t) = -\int_{0}^{t} d\tau \int dq dp \left\langle \frac{\partial a(t-\tau)}{\partial p} \frac{\partial v_{\text{eff}}(q,\tau)[\Delta f]}{\partial q} \right\rangle_{f_{0}}$$

with

$$\langle a(q) \rangle_{f_0} \equiv \iint dq dp \ a(q) f_0(q, p), \quad a(t - \tau) = e^{-(t - \tau)\mathcal{L}_0(q, p)[f_0]} a(q)$$

Solution in Laplace-Fourier

$$\widehat{\Delta f}(k,p,\omega) = \frac{1}{2\pi} \int_0^\infty dt \int dq \exp(-ikq + i\omega t) \Delta f(q,p,t)$$

For homogeneous stationary states $f_0 = P(p)$, since we are interested in observables that depend only on q

$$\int dp \, \widehat{\Delta f}(k, p, \omega) = \frac{\widehat{K}(\omega)\widetilde{b}(k)}{2\pi \widetilde{v}(k)} \Big[\frac{\epsilon(k, \omega) - 1}{\epsilon(k, \omega)} \Big]$$

where $\widetilde{v}(k)$ is the Fourier transform of the two-body potential

$$\epsilon(k,\omega) = 1 - 2\pi k \widetilde{v}(k) \int \frac{dp}{kp - \omega} \frac{\partial P(p)}{\partial p}$$

is the so-called plasma response dielectric function and $K(\omega)$ is the Laplace transform of K(t).

Application to HMF

$$v(q) = 1 - \cos q, \quad \widetilde{v}(k) = \left[\delta_{k,0} - \frac{\delta_{k,-1} + \delta_{k,1}}{2}\right]$$
$$b(q) = \cos q, \quad \widetilde{b}(k) = \frac{\delta_{k,-1} + \delta_{k,1}}{2}$$
$$\widehat{K}(\omega) = -\frac{h}{i\omega}$$
$$\int dp \,\widehat{\Delta f}(\pm 1, p, \omega) = \frac{ih}{2\pi\omega} \left[\frac{1 - \epsilon(\pm 1, \omega)}{\epsilon(\pm 1, \omega)}\right]$$
$$\int dp \,\widetilde{\Delta f}(\pm 1, p, t) = \frac{ih}{4\pi^2} \int_L d\omega \,\frac{1}{\omega} \left[\frac{1}{\epsilon(\pm 1, \omega)} - 1\right] e^{-i\omega t}$$
$$\langle m_x \rangle(t) = \frac{ih}{2\pi} \int_L d\omega \,\frac{1}{\omega} \left[\frac{1}{\epsilon(\pm 1, \omega)} - 1\right] e^{-i\omega t}$$

while $\langle m_y \rangle(t) = 0$ for all times.

Homogeneous waterbag

$$P(p) = \frac{1}{2\pi} \frac{1}{2p_0} \Big[\Theta(p + p_0) - \Theta(p - p_0) \Big]; \quad p \in [-p_0, p_0]$$
$$\epsilon(\pm 1, \omega) = 1 - \frac{1}{2(p_0^2 - \omega^2)}$$
$$\langle m_x \rangle(t) = \frac{2h}{2p_0^2 - 1} \sin^2 \left(\frac{t}{2}\sqrt{p_0^2 - \frac{1}{2}}\right)$$

Permanent oscillations N-body



Permanent oscillations Vlasov



Vlasov simulation ($N = \infty$), U = 0.7.

Average over initial conditions



 $N = 10^{5}$

Fermi-Dirac



$$P(p) = \frac{A}{2\pi} \frac{1}{1 + \exp(\beta(p^2 - \mu))}$$

Gaussian



$$P(p) = \sqrt{\frac{\beta}{2\pi}} \exp(-\beta p^2/2)$$

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Relaxation to equilibrium

