

# THEORIE DES PERTURBATIONS

1

$$\hat{H} = \hat{H}_0 + \lambda \hat{V}$$

$\lambda \ll 1$

↑  
réduite

$$[\hat{H}_0, \hat{V}] \neq 0$$

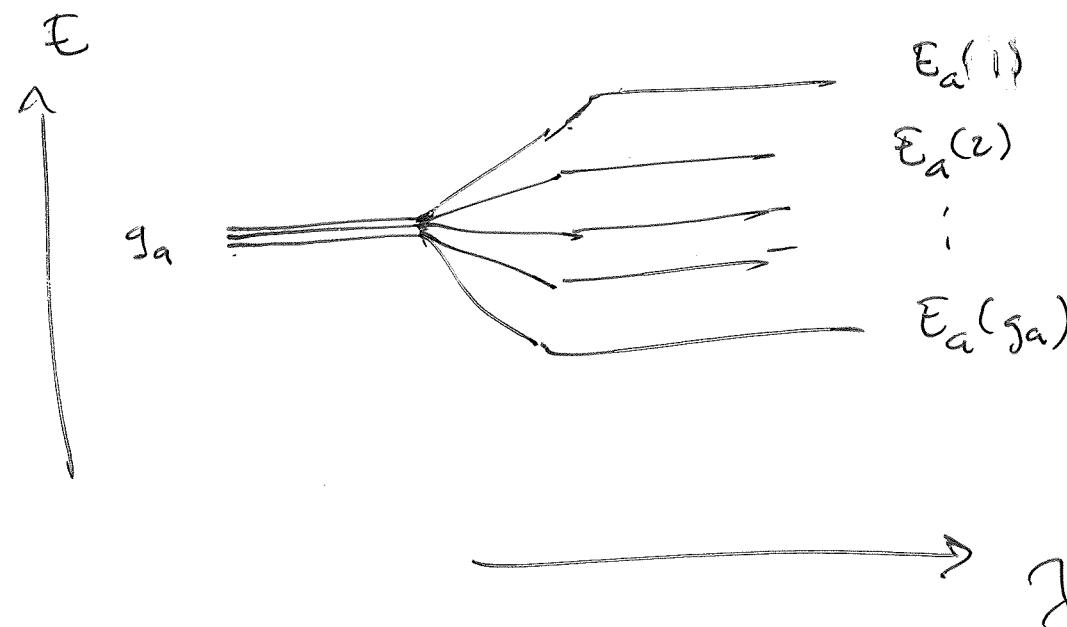
$$\hat{H}_0 |\tilde{\epsilon}_a^{(0)}\rangle = \tilde{\epsilon}_a^{(0)} |\tilde{\epsilon}_a^{(0)}\rangle$$

cas dégénéré:

$$\hat{H}_0 (\tilde{\epsilon}_a^{(0)}; p) = \tilde{\epsilon}_a^{(0)} (\tilde{\epsilon}_a^{(0)}; p)$$

$$p = 1 \rightarrow g_a$$

$g_a$  dégénérence  
de  $\tilde{\epsilon}_a^{(0)}$



$$\tilde{\epsilon}_a(q) = \tilde{\epsilon}_a^{(0)} + \lambda \epsilon_a^{(1)}(q) + \lambda^2 \epsilon_a^{(2)}(q) + \dots$$

$$\hat{H} |\psi_a; q\rangle = \tilde{\epsilon}_a(q) |\psi_a; q\rangle$$

$$|\psi_a; q\rangle = \sum_{p=1}^{g_a} \alpha_p^{(q)} |\tilde{\epsilon}_a^{(0)}; p\rangle + \lambda |\phi_a^{(1)}(q)\rangle + \lambda^2 |\phi_a^{(2)}(q)\rangle + \dots$$

$(\phi_1)$   
 $(\phi_2)$

$$\hat{H} |\psi_a; q\rangle = \tilde{\epsilon}_a(q) |\psi_a; q\rangle$$

$$(\hat{H}_0 - \tilde{\epsilon}_a^{(0)}) |\phi_1\rangle + (\tilde{\epsilon}_a^{(0)} - \epsilon_1) \sum_{p=1}^{g_a} \alpha_p^{(q)} (\tilde{\epsilon}_a^{(0)}; p) = 0$$

$$p, q, p' = 1, \dots, g_a$$

$$\langle \tilde{\epsilon}_a^{(0)}; p' | \left( \underbrace{\Gamma V_{pp'}}_{\sum_{p=1}^{g_a} \langle \tilde{\epsilon}_a^{(0)}; p' | V | \tilde{\epsilon}_a^{(0)}; p \rangle \alpha_p^{(q)}} \right) = 0$$

$$\Rightarrow \sum_p V_{pp'} \alpha_p^{(q)} = \epsilon_a^{(1)}(q) \alpha_{p'}^{(q)}$$

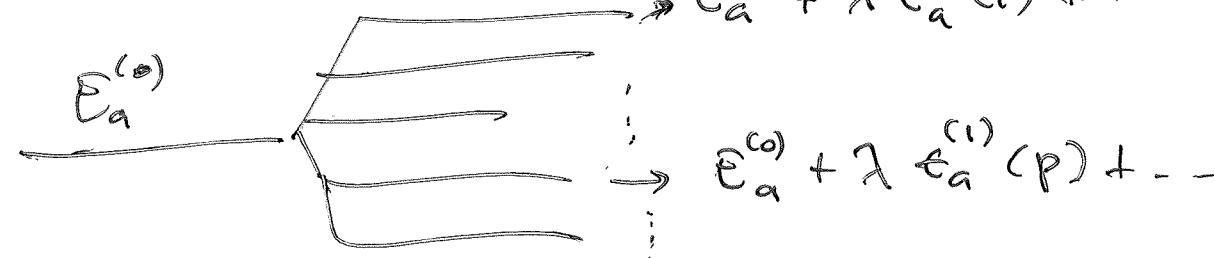
$$V \vec{\alpha}^{(q)} = \epsilon_a^{(q)} \vec{\alpha}^{(q)}$$

pour calculer

$$\epsilon_a^{(1)}(q)$$

construire la matrice de  $V$  sur le  $\mathbb{C}^2$   
base des états propres dégénérés de  $H_0$

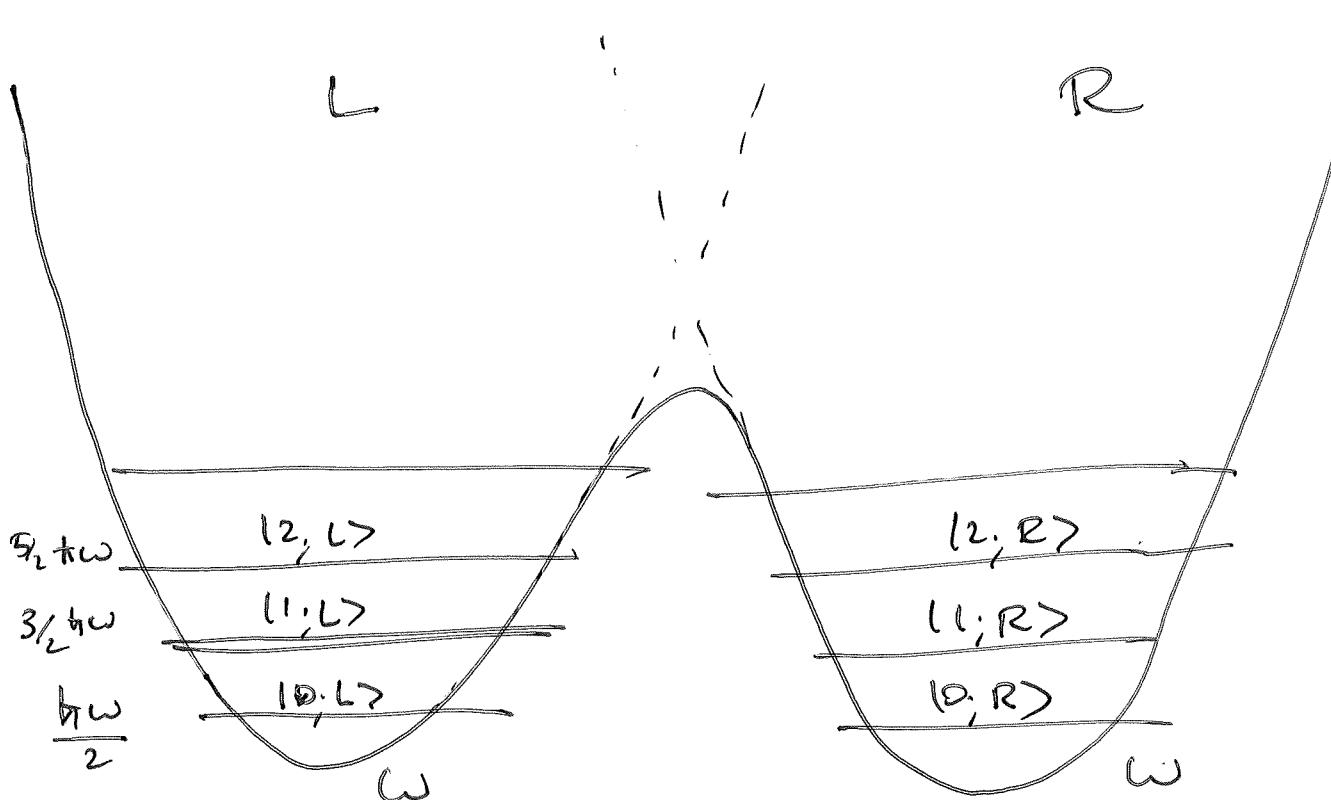
si  $\epsilon_a^{(1)}(q)$  sont tous  
différents



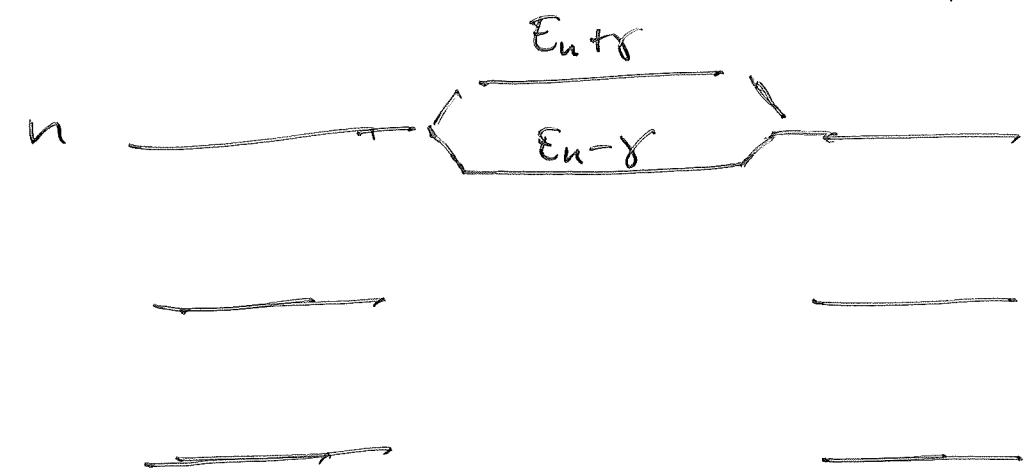
$$\langle \epsilon_a^{(0)}; p | V | \epsilon_a^{(0)}; p \rangle = V_{pp}$$

$$(n_a; 1) = \sum_{p=1}^{g_a} \alpha_p^{(1)} (\epsilon_a^{(0)}; p) + \dots$$

clivage ("splitting")



clivage par effet tunnel  
("tunnel splitting")



$$E_n = \hbar \omega \left(n + \frac{1}{2}\right)$$

$$|n; L\rangle, |n; R\rangle$$

vecteurs propres importants

$$V = \begin{pmatrix} \langle n; L | & |n; L\rangle \\ \langle n; R | & |n; R\rangle \end{pmatrix} \begin{pmatrix} \beta^{(n)} & -\gamma^{(n)} \\ -\gamma^{(n)} & \beta^{(n)} \end{pmatrix}$$

$$\rightarrow \epsilon_n^{(1)} = \pm |\gamma^{(n)}| \rightarrow \frac{|n; L\rangle + |n; R\rangle}{\sqrt{2}}$$

$$\underline{\beta^{(n)} \pm \gamma^{(n)}}$$

# MÉTHODE DES VARIATIONS

(3)

$\hat{H}$

$|\psi(\vec{a})\rangle$

$\vec{a} = (a_1, a_2, \dots, a_N)$

exemple

$\vec{a} = (a_1, a_2)$

$$\psi(x, \vec{a}) = N e^{-\frac{(x-a_1)^2}{2a_2^2}}$$

"Ausatz" variationnel

principes variationnels

1) état fondamental  $\hat{H} \rightarrow E_0$  énergie de l'état fondamental

$|\psi\rangle$  vecteur quelconque en  $H$   $\|\psi\|^2 = 1$

$$\langle \psi | \hat{H} | \psi \rangle \geq E_0$$

$$|\psi\rangle = \sum_n c_n |\phi_n\rangle$$

$$\hat{H} |\phi_n\rangle = E_n |\phi_n\rangle$$

$$E_n \geq E_0$$

$$\langle \psi | \hat{H} | \psi \rangle = \sum_{n,n'} c_n^* c_{n'} \langle \phi_n | \hat{H} | \phi_{n'} \rangle = \sum_n (c_n)^2 E_n \geq \underbrace{\sum_n (c_n)^2}_{1} E_0 = E_0$$

$$h(\vec{a})$$

$$\min_{\vec{a}} \frac{\langle \psi(\vec{a}) | \hat{H} | \psi(\vec{a}) \rangle}{\langle \psi(\vec{a}) | \psi(\vec{a}) \rangle} = E(\vec{a}) \Leftrightarrow \vec{a}_0$$

$h(\vec{a}_0)$  meilleure approximation  
de  $|\psi\rangle$  à l'utile  
de la forme d'état  $|\psi(\vec{a})\rangle$

2) états propres

$$\underline{\langle \psi | \hat{H} | \psi \rangle}, \quad \hat{H}$$

$$\epsilon_{\psi} = \frac{\langle \psi | \hat{H} | \psi \rangle}{\langle \psi | \psi \rangle}$$

$\epsilon_{\psi}$  est stationnaire par rapport à tout changement de  $|\psi\rangle$

$\Leftrightarrow |\psi\rangle$  est état propre de  $\hat{H}$ .

$$|\psi\rangle \rightarrow |\psi\rangle + |\delta\psi\rangle$$

$$\cancel{\langle |\psi| \hat{H}|^2 = 1}$$

$$\begin{aligned} \epsilon_{\psi+\delta\psi} &= \frac{(\langle \psi + \delta\psi | \hat{H} | \psi + \delta\psi \rangle)}{(\langle \psi + \delta\psi | (\psi + \delta\psi) \rangle)} = \frac{1}{\langle \psi | \psi \rangle} \left[ \frac{\langle \psi | \hat{H} | \psi \rangle + \langle \delta\psi | \hat{H} | \psi \rangle + \langle \psi | \hat{H} | \delta\psi \rangle + \mathcal{O}(\delta\psi^2)}{1 + \frac{\langle \psi | \delta\psi \rangle + \langle \delta\psi | \psi \rangle}{\langle \psi | \psi \rangle} + \mathcal{O}(\delta\psi^2)} \right] \\ &= \frac{1}{\langle \psi | \psi \rangle} \left( 1 - \frac{\langle \psi | \delta\psi \rangle}{\langle \psi | \psi \rangle} - \frac{\langle \delta\psi | \psi \rangle}{\langle \psi | \psi \rangle} \right) \left( \langle \psi | \hat{H} | \psi \rangle + \langle \delta\psi | \hat{H} | \psi \rangle + \langle \psi | \hat{H} | \delta\psi \rangle + \mathcal{O}(\delta\psi^2) \right) \\ &= \left[ \frac{\epsilon_{\psi} - \langle \psi | \hat{H} | \psi \rangle}{\langle \psi | \psi \rangle} + \frac{\langle \delta\psi | (\hat{H} - \epsilon_{\psi}) | \psi \rangle}{\langle \psi | \psi \rangle} + \frac{\langle \psi | (\hat{H} - \epsilon_{\psi}) | \delta\psi \rangle}{\langle \psi | \psi \rangle} + \mathcal{O}(\delta\psi^2) \right] \end{aligned}$$

$$\Rightarrow \langle \delta\psi | (\hat{H} - \epsilon_{\psi}) | \psi \rangle = 0 \quad \forall |\delta\psi\rangle$$

$$\hat{H} |\psi\rangle = \epsilon_{\psi} |\psi\rangle \quad |\psi\rangle \text{ étant propre de } \hat{H}$$



$$(\hat{H} - E_\psi) |\psi\rangle = 0$$

$E_\psi$  stationäre



$$|\psi(\vec{a})\rangle$$

$$\text{extrema de } E(\vec{a}) = \frac{\langle \psi(\vec{a}) | \hat{H} | \psi(\vec{a}) \rangle}{\langle \psi(\vec{a}) | \psi(\vec{a}) \rangle}$$

$$\vec{a}_e$$

$$\nabla_{\vec{a}} E(\vec{a}) \Big|_{\vec{a}_e} = 0$$

# MOMENT ANGULAI RE ou CINÉTIQUE en MQ

(6)

MQ

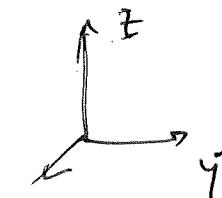
$$\vec{L} = \vec{r} \times \vec{p} = (y p_z - z p_y, -x p_z + z p_x, x p_y - y p_x)$$

$$[\hat{x}, \hat{p}_y] = 0$$

$$\rightarrow \hat{L} = (\hat{y} \hat{p}_z - \hat{z} \hat{p}_y, \dots)$$

$$[\hat{L}^x, \hat{L}^y] = \dots = i\hbar [\hat{L}^z] \neq 0$$

$$\epsilon_{\alpha\beta\gamma} = \begin{cases} 1 & \text{si } (\alpha\beta\gamma) \text{ est une permutation paire de } (xyz) : (xyt), (yzx), (zxy) \\ -1 & \text{si } " " " " \text{ impaire } " " \\ 0 & \text{autrement} \end{cases}$$



si  $(\alpha\beta\gamma)$  est une permutation paire de  $(xyz)$  :  $(xyt)$ ,  $(yzx)$ ,  $(zxy)$   
si " " " " impaire " "

$$[\hat{x}, \hat{p}_x] = i\hbar$$

$$[\hat{x}, \hat{p}_y] = [\hat{z}, \hat{p}_z]$$

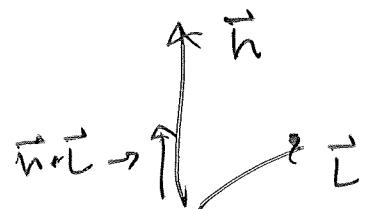
$$[\hat{L}^\alpha, \hat{L}^\beta] = i\hbar \sum_\gamma \epsilon_{\alpha\beta\gamma} \hat{L}^\gamma$$



$\vec{n} \cdot \vec{L}$  est conservé

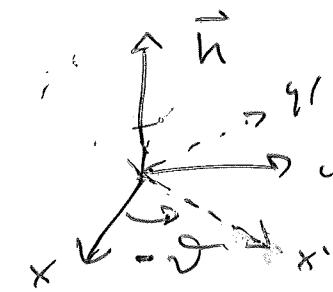
$\Leftrightarrow$

invariance par rotation  
autour de l'axe  $\vec{n}$



(7)

$$\hat{R}_{\vec{n}}(\vartheta) | \psi \rangle = | \psi' \rangle$$



$$\vec{v} \rightarrow \vec{v}' = R_{\vec{n}}(\vartheta) \vec{v}$$

↓  
3x3

$\vec{v}$   
ex.  $\hat{L}, \hat{\tau}, \hat{p}$  etc--

$$\langle \vec{v} \rangle_{\psi} \rightarrow \langle \vec{v} \rangle_{\psi'} = \langle \psi | \hat{R}_{\vec{n}}^+(\vartheta) \vec{v} \hat{R}_{\vec{n}}(\vartheta) | \psi \rangle = R_{\vec{n}}(\vartheta) \langle \vec{v} \rangle_{\psi}$$

unitaire

$$[\hat{H}, \hat{R}_{\vec{n}}(\vartheta)] = 0$$

Si le système est invariant par rotation autour de  $\vec{n}$

$$[\hat{H}, \hat{L} \cdot \vec{n}] = 0$$

$$\hat{R}_{\vec{n}}(\vartheta) = e^{i \frac{\hbar}{\hbar} f(\vartheta) (\hat{L} \cdot \vec{n})}$$

$[H] = [L]$

$$\hat{R}_{\vec{n}}(\vartheta_1) \hat{R}_{\vec{n}}(\vartheta_2) = \hat{R}_{\vec{n}}(\vartheta_1 + \vartheta_2)$$

$$f(\vartheta) = \underbrace{\alpha \vartheta}_{= -1}$$

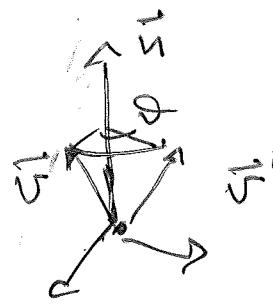
$$\hat{U} = e^{i \frac{\hbar}{\hbar} \hat{A}}$$

$$\hat{R}_{\vec{n}}(\vartheta) = e^{-i \frac{\hbar}{\hbar} \vartheta (\hat{L} \cdot \vec{n})}$$

$\downarrow$

$$\hat{L} \cdot \vec{n}$$
 est générateur des rotations

(8)



$$\vec{v}' = (1 - \cos \theta) (\vec{n} \cdot \vec{v}) \vec{n} + \cos \theta \vec{v} + \sin \theta (\vec{n} \times \vec{v})$$

$$\underset{\theta \rightarrow 0}{\approx} \vec{v} + \theta (\vec{n} \times \vec{v}) + O(\theta^2)$$

$$= \left[ \mathbb{1} + \theta \begin{pmatrix} 0 & -n_z & n_y \\ n_z & 0 & -n_x \\ -n_y & n_x & 0 \end{pmatrix} + \dots \right] \vec{v}$$

$$= [\mathbb{1} - (i \theta \vec{n} \cdot \vec{\tau})] \vec{v} + \dots$$

$$\vec{T}_x = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}$$

$$\vec{T}_y = \begin{pmatrix} 0 & 0 & i \\ 0 & 0 & 0 \\ -i & 0 & 0 \end{pmatrix}$$

$$\vec{T}_z = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\vec{v}' = R_{\vec{n}}(\theta) \vec{v} = \exp(-i \theta \vec{n} \cdot \vec{\tau}) \vec{v}$$

$$\langle \hat{v} \rangle_{\psi'} = \langle \psi | (\mathbb{1} + \frac{i}{\hbar} \theta (\vec{\tau} \cdot \vec{n})) \hat{v} (\mathbb{1} + \frac{i}{\hbar} \theta (\vec{\tau} \cdot \vec{n})) | \psi \rangle$$

$$= \langle \hat{v} \rangle_{\psi} + \frac{i}{\hbar} \theta ([\vec{\tau} \cdot \vec{n}, \hat{v}])_{\psi} + O(\theta^2)$$

$$= [\mathbb{1} - i \theta (\vec{n} \cdot \vec{\tau})] \langle \hat{v} \rangle_{\psi} = \langle \hat{v} \rangle_{\psi} - i \theta \langle \psi | (\vec{n} \cdot \vec{\tau}) \hat{v} | \psi \rangle +$$

$$[\vec{\tau} \cdot \vec{n}, \hat{v}] = -\hbar (\vec{n} \cdot \vec{\tau}) \hat{v}$$

$$\vec{V} = \vec{E}$$

(9)

$$[\hat{L}^x, \hat{L}^y] = i\hbar (\hat{r}_x \hat{L})_y = i\hbar \hat{L}^z$$