

Markov - Chain Monte Carlo

$$M \rightarrow P$$

$$I = \int_V d^D x \frac{p(\vec{x})}{N} g(\vec{x}) = \langle g \rangle_P$$

$$\vec{x}_n : \quad \vec{x}_1 \rightarrow \vec{x}_2 \rightarrow \dots \rightarrow \vec{x}_M$$



$$\frac{n(\vec{x}_n)}{M} \xrightarrow{M \rightarrow \infty}$$

$$\frac{p(\vec{x}_n)}{N} d^D x$$

$$I_M = \frac{1}{M} \sum_{n=1}^M g(\vec{x}_n) = \sum_{\vec{x}} \frac{n(\vec{x})}{M} g(\vec{x})$$

$$\xrightarrow{M \rightarrow \infty} I$$

$$\text{rule} \Rightarrow T(\vec{x} \rightarrow \vec{y}) = T_{prop}(\vec{x} \rightarrow \vec{y}) A(\vec{x} \rightarrow \vec{y})$$

$$A(\vec{x} \rightarrow \vec{y}) = \min \left(1, \frac{p(\vec{y})}{p(\vec{x})} \right)$$

$$\underline{\underline{|I_M - I| \xrightarrow{M \rightarrow \infty} 0}} \quad \text{How?}$$

I_M is a sum of random variables

$g(\vec{x}_n)$ are random variables

$\vec{x}_n$ are distributed according to $p(\vec{x})$

$$\overline{g(\vec{x})} = \int d^D x \frac{P(\vec{x})}{N} g(\vec{x}) = \underline{I}$$

$$\Rightarrow \overline{I_M} = \underline{I}$$

$$\sigma_{I_M}^2 \sim |I - I_M|^2$$

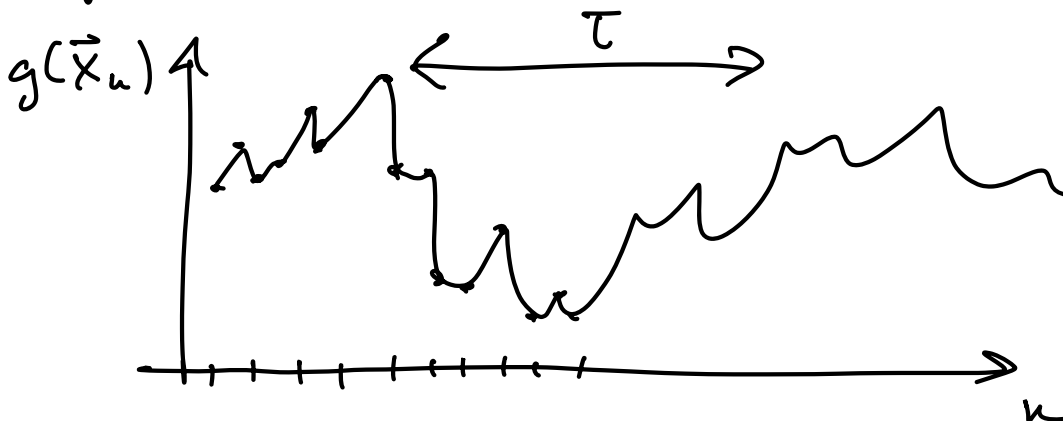
$g(\vec{x}_u)$ is a random variable

$$\overline{g} = \underline{I}, \quad \sigma_g^2 \text{ variance}$$

$$\sigma_{I_M}^2 \stackrel{?}{=} \frac{M \sigma_g^2}{M^2} = \frac{\sigma_g^2}{M}$$

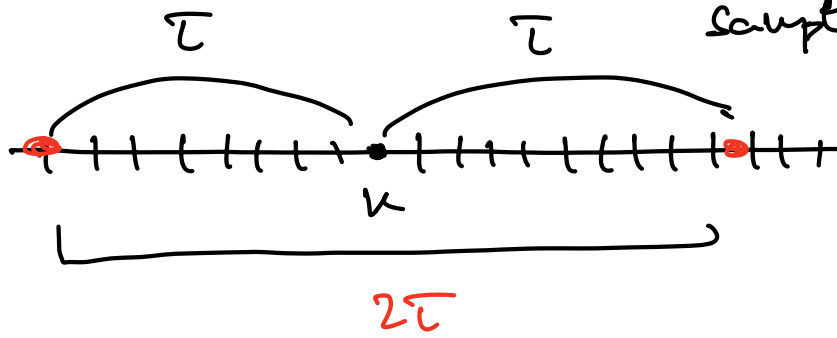
true if $g(\vec{x}_u)$ are independent random variables

equilibration time / autocorrelation time (τ)



$$M \text{ samples of } g(\vec{x}_u) \rightarrow M_{\text{eff}} = \frac{M}{2\tau}$$

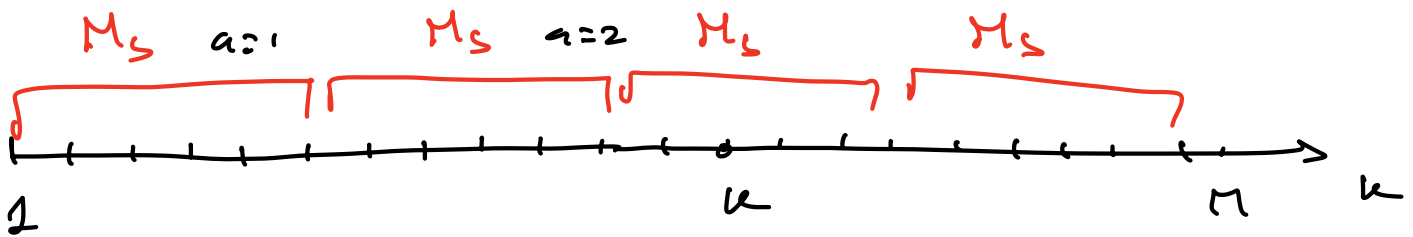
of effectively independent samples



$$\sigma_{\bar{I}_M}^2 = \frac{\sigma_g^2}{M_{\text{eff}}} = \frac{2\tau}{M} \sigma_g^2 \quad \left| \text{Central limit theorem} \right.$$

How to estimate τ ?

An independent estimate of $\sigma_{\bar{I}_M}^2$:



$$n_b = \frac{M}{M_s}$$

$$n_b \geq \tau$$

$$\bar{I}_M = \frac{1}{M} \sum_{u=\bar{u}+1}^{\bar{u}+M} g(\bar{x}_u) = \frac{1}{n_b} \sum_{a=1}^{n_b} \frac{1}{M_s} \sum_{j=1}^{M_s} g(\underbrace{\bar{x}_{(a-1)M_s+j}}_u)$$

$\uparrow$
 after every visit
 $\bar{u}$ configurations

$\underbrace{\qquad\qquad\qquad}_{\bar{g}_a \text{ block average}}$

$M_b > \tau \Rightarrow \bar{g}_a$ block averages are n-independent

$$I_M = \frac{1}{n_b} \sum_a \bar{g}_a$$

↑

⇒ central limit theorem

$$\sigma_{I_M}^2 = \frac{\sigma_{\bar{g}}^2}{n_b}$$

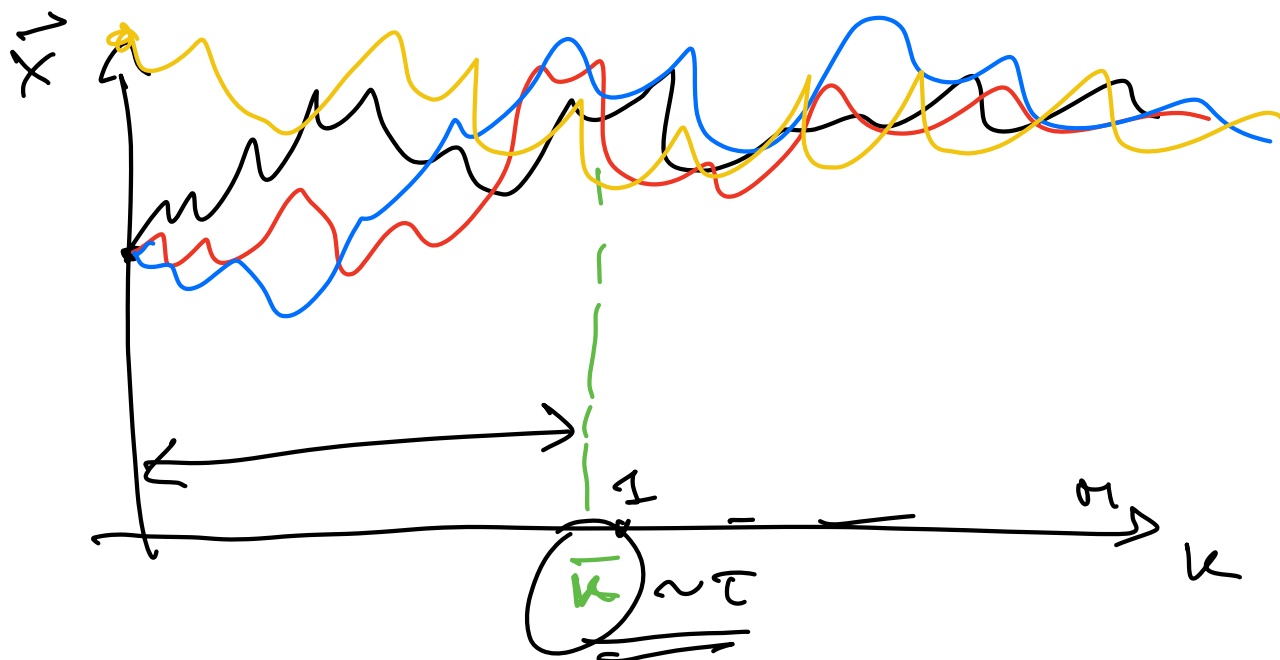
$$\sigma_{\bar{g}}^2$$

variance of the fluctuations of $\bar{g}_a$

$$= \frac{2\tau}{M} \sigma_g^2$$

↪ variance of the fluctuations of $g(\vec{x}_n)$

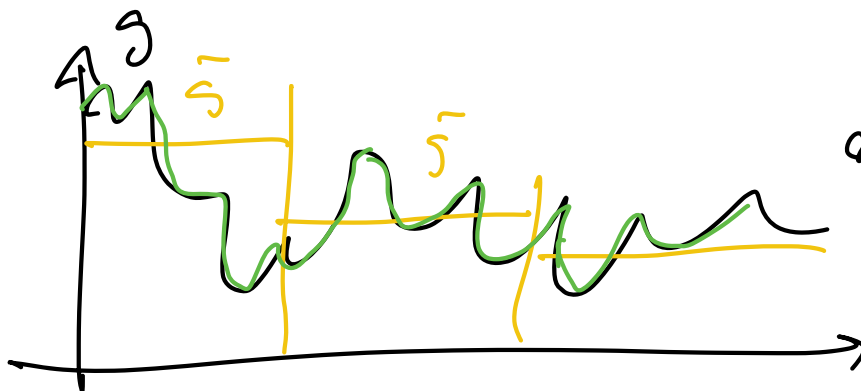
$$\tau = \frac{1}{2} \sigma_{\bar{g}}^2 M_b$$



In practice : guess $\bar{u}$ (thermalization time)

guess M_s ($\geq \tau$)

estimate $\tau = \frac{1}{2} M_s \frac{\sigma_{\bar{u}}^2}{\sigma_g^2}$



$\Rightarrow$ if $\tau \leq M_s, \bar{u}$

✓

$$\sigma_{\bar{u}}^2 = \frac{\sigma_g^2}{n_s}$$

$$|\bar{u} - \bar{u}_M| \sim_{M \rightarrow \infty} \sqrt{\frac{2\tau}{M}} \sigma_g$$

$$\sim \sqrt{\frac{\tau}{M}}$$

$$\bar{I} = \int d^D x \frac{p(x)}{Z} g(x)$$

$$\underline{V} = \underline{L}^D$$

$$\tau = \tau(D, L) \quad ?$$

luckily :

$$\tau \simeq A D^{\frac{1}{z}} L^z \leftarrow$$

$$z \sim \mathcal{O}(1)$$

typically

$\rightarrow z =$ dynamical exponent

typically

$$\underline{z = 2}$$

$\Rightarrow$ Efficient estimate of $\underline{\tau}$

$$M \rightarrow P$$

Path-integral Formulation of quantum
statistical
mechanics

$\rightarrow$ path-integral Monte Carlo (PIMC)

Single particle in continuous space

$$\hat{H} = \frac{\hat{\vec{p}}^2}{2m} + V(\hat{\vec{x}})$$

$$Z = \text{Tr} (e^{-\beta \hat{H}})$$

$$\beta = \frac{1}{k_B T}$$

$$\langle \hat{A} \rangle = \frac{\text{Tr} (\hat{A} e^{-\beta \hat{H}})}{\text{Tr} (e^{-\beta \hat{H}})}$$

$$\vec{x} = (x_1, x_2, \dots, x_d)$$

$$Z = \sum_{\alpha} \langle \alpha | e^{-\beta \hat{H}} | \alpha \rangle$$

$$|\alpha\rangle \rightarrow |\vec{x}\rangle$$

basis of the position operator(s)

$$\hat{x}_1, \hat{x}_2, \dots, \hat{x}_d$$

$$= \int d^d x \underbrace{\langle \vec{x} | e^{-\beta \hat{H}} | \vec{x} \rangle}_{\leftarrow}$$

$$\underbrace{\langle \vec{x} | e^{-\beta \hat{H}} | \vec{x}' \rangle}_{\substack{\uparrow \\ \text{it} = \beta}} = \rho(\vec{x}, \vec{x}'; \beta)$$

imaginary-time propagator

$$\langle \vec{x} | e^{\frac{-i}{\hbar} \hat{H} t} | \vec{x}' \rangle$$

= amplitude of prob. of going from $\vec{x}'$ to $\vec{x}$ in a time t (propagates)

$$\langle \vec{x} | e^{-\beta \left(\frac{\hat{p}^2}{2m} + U(\hat{x}) \right)} | \vec{x}' \rangle$$

$$\neq e^{-\beta \frac{\hat{p}^2}{2m}} e^{-\beta U(\hat{x})}$$

Trotter-Lie decomposition

$$e^{-\beta \left(\frac{\hat{p}^2}{2m} + U(\hat{x}) \right)} = \lim_{M \rightarrow \infty} \left(e^{-\frac{\beta}{M} \left(\frac{\hat{p}^2}{2m} + U(\hat{x}) \right)} \right)^M$$

$$e^A = \left(e^{A/M} \right)^M$$

$$= \lim_{M \rightarrow \infty} \left(e^{-\frac{\beta}{M} \frac{\hat{p}^2}{2m}} e^{-\frac{\beta}{M} U(\hat{x})} \right)^M$$

diagonal on $|\vec{x}\rangle$

$$e^{-\beta/M \left(\frac{\hat{p}^2}{2m} + U(\hat{x}) \right)} \simeq e^{-\beta/M \frac{\hat{p}^2}{2m}} e^{-\beta/M U(\hat{x})} + O\left(\frac{\beta}{M}\right)^2$$

$$\int d\vec{x} |\vec{x}\rangle \langle \vec{x}| = \mathbb{1}$$

↑

completeness relations

$$\langle \vec{x} | e^{-\beta \left(\frac{\vec{p}^2}{2m} + U \right)} | \vec{x}' \rangle$$

$$= \lim_{M \rightarrow \infty} \int \left(\frac{M-1}{M} d^d x_k \right)$$

$$\langle \vec{x} | e^{-\frac{\beta}{M} \frac{\vec{p}^2}{2m}} e^{-\frac{\beta}{M} U} | \vec{x}_1 \rangle \langle \vec{x}_1 | e^{-\frac{\beta}{M} \frac{\vec{p}^2}{2m} - \frac{\beta}{M} U} | \vec{x}_2 \rangle$$

$$\dots \langle \vec{x}_{M-1} | e^{-\frac{\beta}{M} \frac{\vec{p}^2}{2m}} | \vec{x}' \rangle$$

$$e^{-\frac{\beta}{M} [U(\vec{x}_1) + U(\vec{x}_2) + \dots + U(\vec{x}_{M-1}) + U(\vec{x}')]}$$

evaluate the Free propagator

$$\langle \vec{x}_u | e^{-\frac{\beta}{M} \frac{\vec{p}^2}{2m}} | \vec{x}_{u+1} \rangle$$

$$\vec{p} \rightarrow |\vec{p}\rangle : \int d^d p |\vec{p}\rangle \langle \vec{p}| = \mathbb{1}$$

$$\int d^d p$$

$$\langle \vec{x}_u | \vec{p} \rangle \langle \vec{p} | \vec{x}_{u+1} \rangle e^{-\frac{\beta}{M} \frac{\vec{p}^2}{2m}}$$

$$e^{-\frac{i}{\hbar} \vec{p} \cdot (\vec{x}_u - \vec{x}_{u+1})}$$

$$(2\pi\hbar)^d$$

$$\begin{aligned}
 &= \prod_{j=1}^d \int \frac{d\mathbf{p}}{(2\pi\hbar)^d} e^{-\beta \sum_{u=1}^M (\mathbf{x}_u^{(j)} - \mathbf{x}_{u+1}^{(j)})^2} \\
 &\approx \left(\frac{1}{2\pi\hbar} \right)^d \int \frac{d\mathbf{p}}{(2\pi\hbar)^d} e^{-\frac{M}{2\beta\hbar^2} (\mathbf{x}_u^{(j)} - \mathbf{x}_{u+1}^{(j)})^2} \\
 &\quad \sim e^{-2}
 \end{aligned}$$

de Broglie thermal wavelength

$$\lambda = \frac{h}{\sqrt{2\pi m k_B T}}$$

$$\frac{mM}{2\beta\hbar^2} = \frac{M}{\lambda^2}$$

$$\langle \vec{x} | e^{-\beta \hat{H}} | \vec{x}' \rangle$$

$$\begin{aligned}
 \vec{x}_0 &= \vec{x} \\
 \vec{x}_M &= \vec{x}'
 \end{aligned}$$

$$= \lim_{M \rightarrow \infty} \left(\frac{M^{1/2}}{\lambda} \right)^d \int \frac{1}{M} \left(d^d x_u \right)$$

$$= \frac{1}{M} \sum_{u=0}^{M-1} (\vec{x}_u - \vec{x}_{u+1})^2 = \frac{1}{M} \sum_{u=1}^M U(\vec{x}_u)$$

$$Z = \int d^d x \quad \boxed{\langle \vec{x} \rangle} \quad e^{-\beta \mathcal{H}} \quad \boxed{\vec{x}} \quad \vec{x}_0 = \vec{x}_M = \vec{x}$$

$$= \lim_{M \rightarrow \infty} \left(\frac{M^{d/2}}{\Lambda} \right)^d \int \left(\prod_{n=1}^{M-1} \frac{1}{\Lambda^d} d^d x_n \right) e^{-S[\{\vec{x}_n\}]}$$

$\boxed{\vec{x}_0} \quad \vec{x}_1 \quad \vec{x}_2 \quad \dots \quad \vec{x}_{M-1} \quad \boxed{\vec{x}_M} = \vec{x}$

$$S[\{\vec{x}_n\}] = \beta \left[\frac{\tau M}{\beta \Lambda^2} \sum_{n=0}^{M-1} (\vec{x}_n - \vec{x}_{n+1})^2 + \frac{1}{M} \sum_{n=1}^M U(\vec{x}_n) \right]$$

$\downarrow$
 effective action

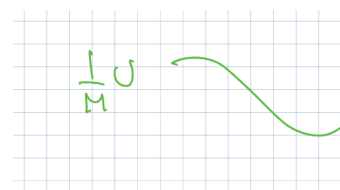
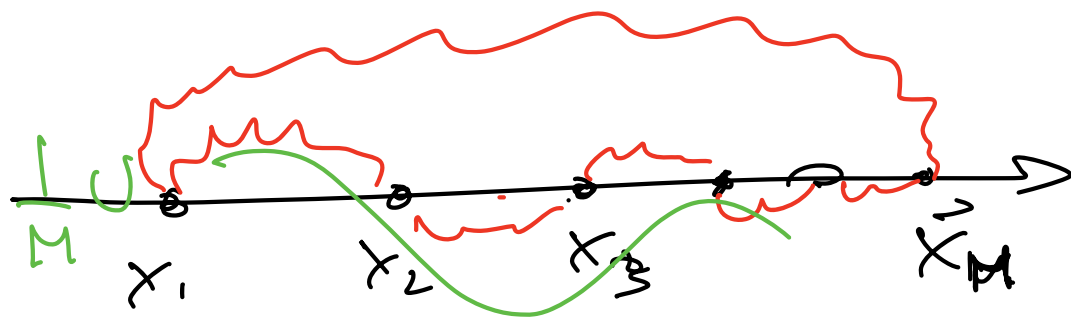
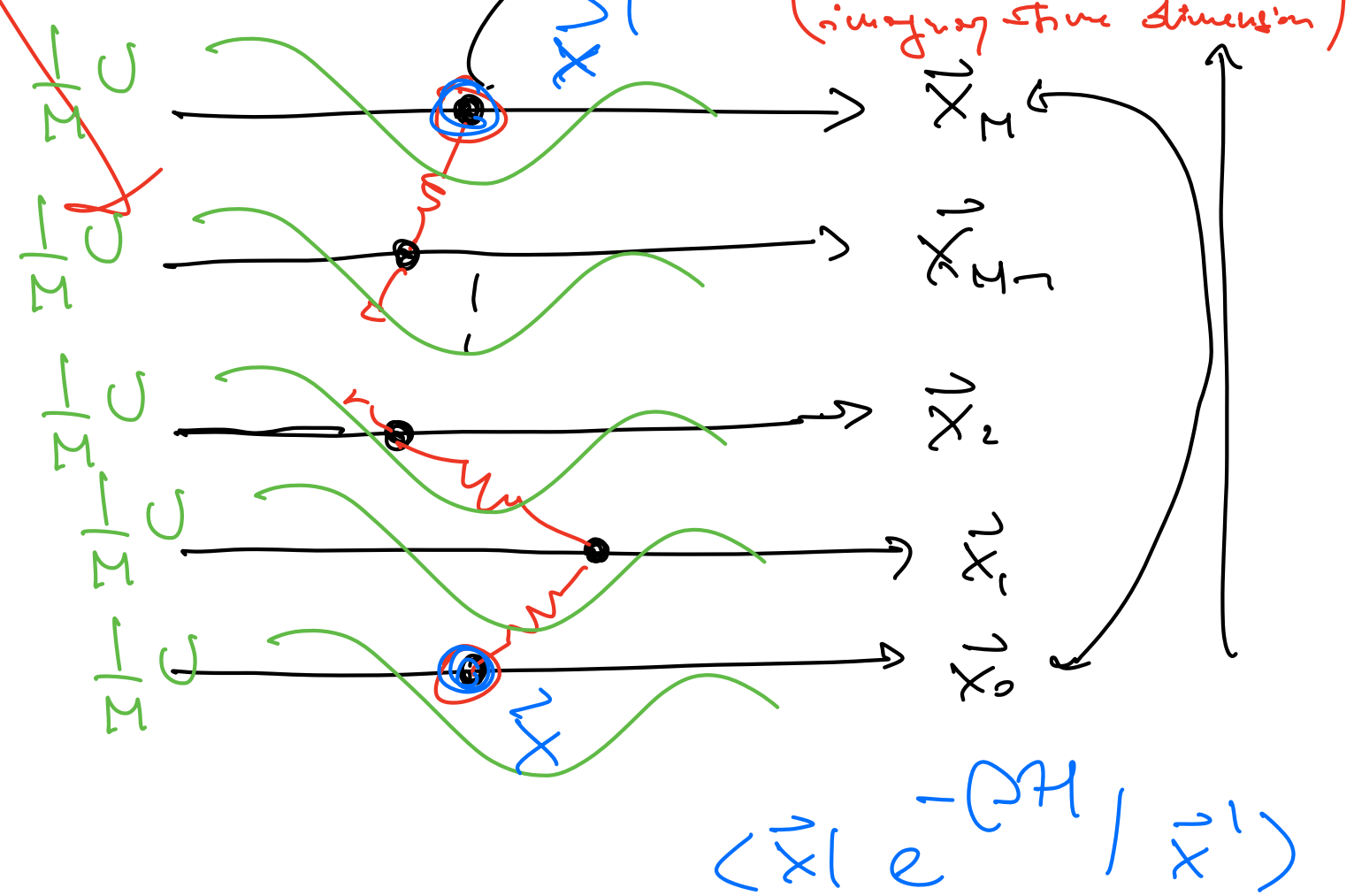
$$= \beta \mathcal{H}_{\text{eff}}(\{\vec{x}_n\})$$

$$\underline{\underline{\tau}} = \frac{2\tau M}{\beta \Lambda^2}$$

spring constant

leads to

(Frobenius dimension)



Ring elastic polymer

$Z = () \times \lim_{M \rightarrow \infty}$ partition function of a ring polymer of M beads

Spring constant

$$\underline{k} = \frac{2\pi M}{(\Delta L)^2}$$

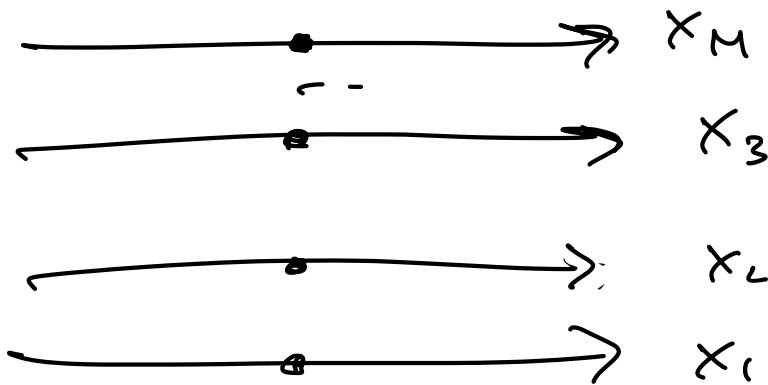
$$\mu = \frac{h}{\sqrt{2\pi m u_s}}$$

↑

$$= \frac{2\pi M}{h} 2\pi m (u_s \tau)^2$$

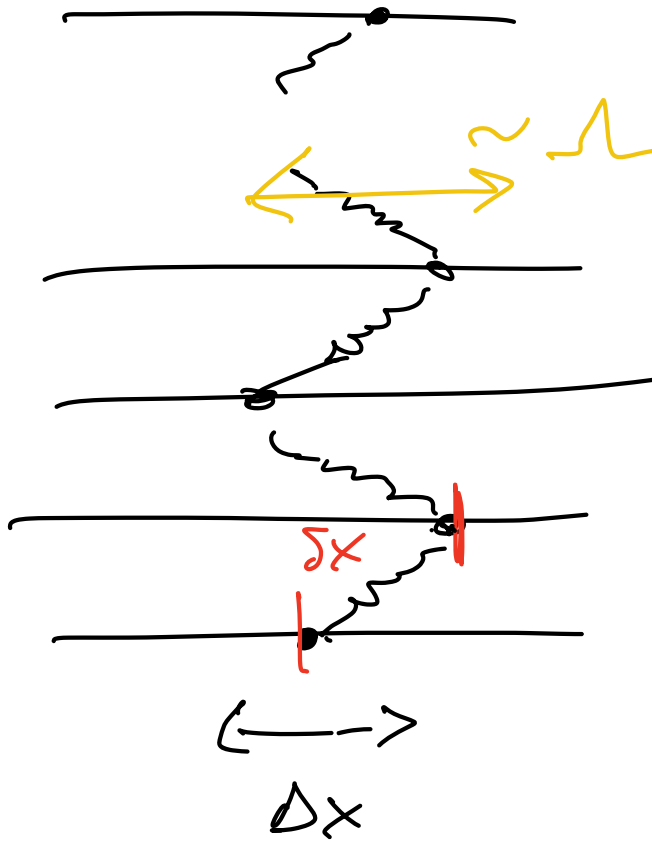
$$= \begin{cases} \rightarrow \underline{0} & \tau \rightarrow 0 \\ \rightarrow \infty & \tau \rightarrow \infty \end{cases}$$

my polymer becomes
infinitely stiff



$$Z \sim \int d^d x e^{-\beta U(\vec{x})} \int d^d p e^{-\beta \frac{p^2}{2m}}$$

$T \rightarrow 0$



$$\Delta x = x_u - x_{u+1}$$

Gaussian variables

$$\sim e^{-\frac{1}{2\sigma^2} \left(\frac{uM}{\lambda^2} (\Delta x)^2 \right)}$$

$$\rightarrow \sigma^2 = \frac{\lambda^2}{2uM}$$

$$(\Delta x)^2 = M \sigma^2 = \frac{\lambda^2}{2u}$$

$$\Delta x = \frac{\lambda}{\sqrt{2u}}$$

$$\vec{x}_1 \rightarrow \vec{x}_2 \rightarrow \dots \rightarrow \vec{x}_M$$

"path" in imaginary time

$Z =$ integral over paths $=$
 " over any possible configurations