

Quantum Monte Carlo methods

Many-body problems in quantum mechanics

N degrees of freedom

$N \gg 1$

$$\hat{H} = \sum_{i=1}^N \hat{H}_i + \sum_{i < j} \hat{V}_{ij} + \dots$$

single-body (single-mode) term

two-body term

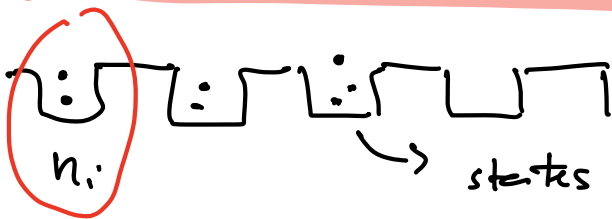
1) Particles in continuous space

$$\hat{H}_i = \frac{\hat{p}_i^2}{2m_i} + U_{\text{ext}}(\vec{r}_i)$$

$$\hat{V}_{ij} = V(|\vec{r}_i - \vec{r}_j|)$$

ex.

2) Lattice quantum gases



states / modes
for single particles

ex. electrons in a solid,
protons in cavities,
atoms in arrays of traps, ...

indistinguishable quantum particles

second quantization


$$\hat{H}_i = -\mu n_i + \frac{U}{2} n_i (n_i - 1) + \dots$$

of pairs of particles

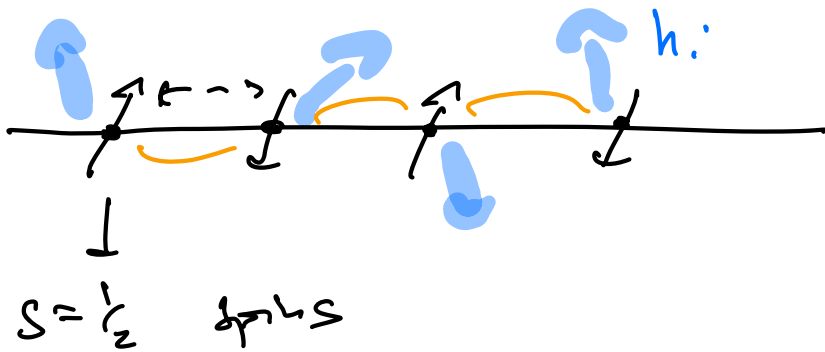
$$\hat{V}_{ij} = -t (c_i^\dagger c_j + c_j^\dagger c_i) + V_{ij} n_i n_j$$

creates a particle @ site i

destroys a particle @ site j



3) Lattice spin models



$$\hat{H}_i = -\vec{h}_i \cdot \vec{S}_i$$

ex.

$$V_{ij} = \sum_{\alpha, \beta} J_{ij}^{\alpha\beta} S_i^\alpha S_j^\beta$$

4) example of your choice

...

In principle

just too hard !

$$\hat{H} |\psi\rangle = E |\psi\rangle$$

diagonalizing a matrix $D \times D$

$$D \sim d(\exp(N))$$

lattice spin models

$$S = 1/2$$

$$D = 2^N$$

impossible when

$$\underline{N \gtrsim 50}$$



$$\langle \hat{A} \rangle_T$$

observables @ thermal equilibrium

$$= \text{Tr}(\hat{\rho} \hat{A})$$

QMC

$$\hat{\rho} = \frac{e^{-\beta \hat{H}}}{Z}$$

$$\beta = \frac{1}{k_B T}$$

$$Z = \text{Tr}(e^{-\beta \hat{H}})$$

$k_B =$ Boltzmann constant

Classical statistical mechanics

states

α

α .

$\uparrow \downarrow \uparrow \uparrow \downarrow \uparrow$

$\Rightarrow E_\alpha$

energy

$\Rightarrow A_\alpha$

observable

$$\langle A \rangle_T =$$

$$\sum_\alpha \frac{A_\alpha e^{-\beta E_\alpha}}{Z}$$

$$Z = \sum_\alpha e^{-\beta E_\alpha}$$

Quantum Monte Carlo

for some Hamiltonians, a solution to eq. statistical mechanics

\rightarrow scalable : at physical cost you can tackle bigger systems

$$\text{Time} \sim \text{poly}(N)$$

→ not specific to # of dimensions
of space

→ fully unbiased : solution is
"numerically exact"

↑
path-integral MC { particles
Stochastic Series Expansions { spins
....

There are also "biased" QMC approaches

↓
quantum chemistry

Classical vs. quantum statistical mechanics

↓

$$\langle A \rangle_T = \frac{\sum_{\alpha} A_{\alpha} e^{-\beta E_{\alpha}}}{Z} \Rightarrow \boxed{\text{Monte Carlo approach}}$$

↑

A = energy
density
magnetization
...

N Ising spins : 2^N terms
↑ ↓

$$Z = \sum_{\alpha} e^{-\beta E_{\alpha}} \quad \Leftarrow$$

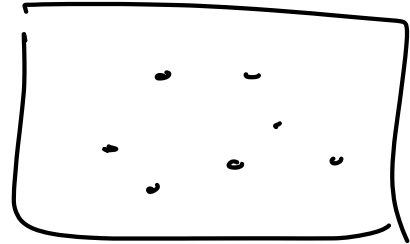
$$F(T, \dots) = -k_B T \log Z$$

ex. T, N, V

$$U = \frac{\partial(\beta F)}{\partial \beta} \Big|_{N, V}$$

fixed

V



$$P = - \frac{\partial F}{\partial V} \Big|_{N, T}$$

...

What's special about quantum mechanics

$$\langle \hat{A} \rangle_T = \frac{\text{Tr}(e^{-\beta \hat{H}} \hat{A})}{\text{Tr}(e^{-\beta \hat{H}})}$$

$$= \frac{\sum_{\alpha} \langle \phi_{\alpha} | e^{-\beta \hat{H}} \hat{A} | \phi_{\alpha} \rangle}{\sum_{\alpha} \langle \phi_{\alpha} | e^{-\beta \hat{H}} | \phi_{\alpha} \rangle}$$

$$\hat{H} | \phi_{\alpha} \rangle = E_{\alpha} | \phi_{\alpha} \rangle \quad \leftarrow$$

unknown

$$= \frac{\sum_{\alpha} A_{\alpha} e^{-\beta E_{\alpha}}}{\sum_{\alpha} e^{-\beta E_{\alpha}}}$$

$$A_{\alpha} = \langle \phi_{\alpha} | \hat{A} | \phi_{\alpha} \rangle$$

QMC : rewriting $\langle \hat{A} \rangle_T$ as

$$\langle \hat{A} \rangle_T = \frac{\sum_c A_c e^{-S_c}}{\sum_c e^{-S_c}}$$

"estimator"

Quantum-to-classical mapping

c : configuration

S_c : "action" associated with c

c is NOT a quantum state $|\psi_c\rangle$

A_c is NOT (necessarily) $\langle \psi_c | \hat{A} | \psi_c \rangle$

S_c is NOT $\langle \psi_c | \hat{H} | \psi_c \rangle$

Efficient QMC approach :

① A_c, S_c are efficiently computable

I give you c \rightarrow you know $\underline{A_c}, \underline{S_c}$
 in a time $\sim \text{poly}(N)$.

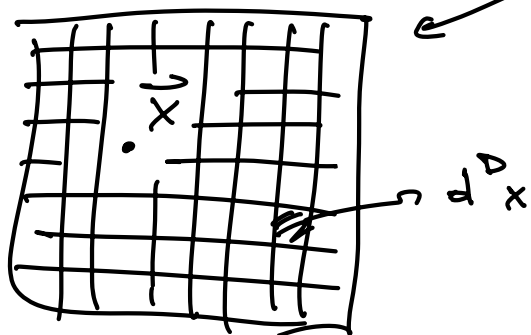
② $e^{-S_c} \geq 0$

semi-positive definite
 statistical weights

MONTÉ CARLO METHOD

Statistical integrals : integral in a high-dimensional space

$$I = \langle g \rangle_P = \int d^D x \ g(\vec{x}) \frac{P(\vec{x})}{N}$$



D dimensions

$$\int d^D x \ P(\vec{x}) = N$$

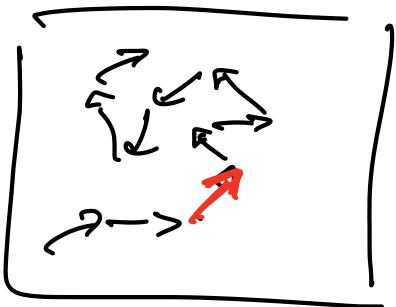
"sample" the distribution

$$\frac{P(\vec{x})}{N}$$

produce a set of points $(\vec{x}_1, \vec{x}_2, \dots, \vec{x}_L)$

$$\text{s.t.} \quad \frac{n(\vec{x}_u)}{L} \underset{L \rightarrow \infty}{\approx} \frac{P(\vec{x}_u)}{N} d^D x$$

Markov - chain Monte Carlo



random walk : Markov process

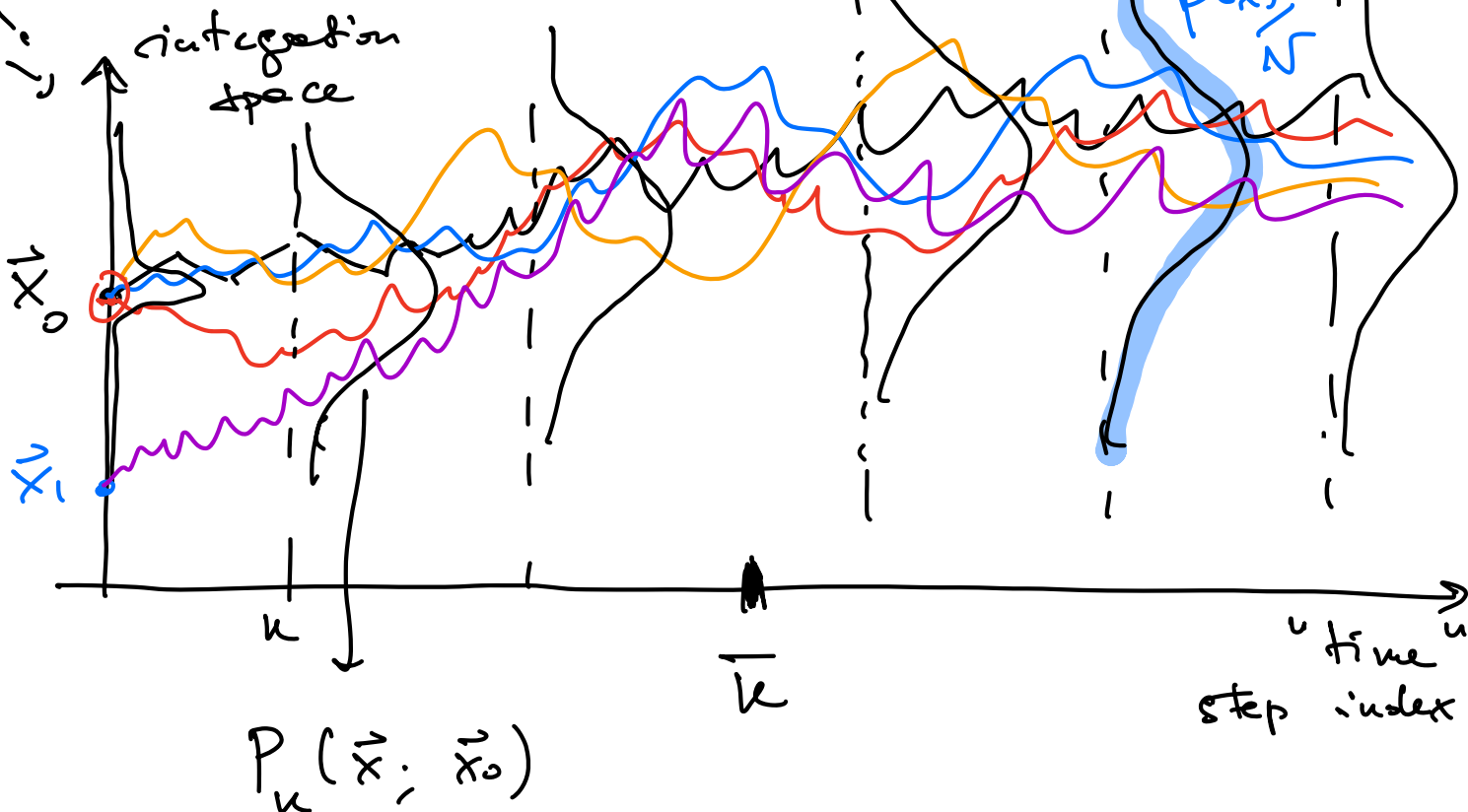
\vec{x}_u is extracted by knowing \vec{x}_{u-1}

$T(\vec{x} \rightarrow \vec{y})$

transition probability

Phenomenology

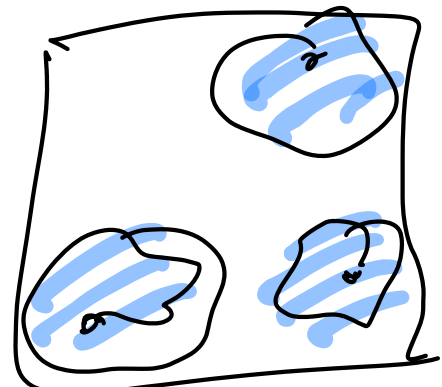
of Markov random walks



transient regime
(equilibration time)

stationary regime

Evolution of $P_u(\vec{x}; \vec{x}_0)$



$$\frac{dP_u}{dt} = P_{u+1}(\vec{x}; \vec{x}_0) - P_u(\vec{x}; \vec{x}_0)$$

$$= \sum_{\vec{y}} \left[P_u(\vec{y}; \vec{x}_0) T(\vec{y} \rightarrow \vec{x}) - P_u(\vec{x}; \vec{x}_0) T(\vec{x} \rightarrow \vec{y}) \right] = 0$$

stationary regime

$$P_u(\vec{x}; \vec{x}_0)$$

$$\hookrightarrow P(\vec{x}) = \frac{p(\vec{x})}{N} \quad \text{forget}$$

$$\vec{x} = (1 \downarrow 1 \downarrow 1 \downarrow \dots) \quad \# \text{ of configurations} \\ \approx 2^N$$

$$T \quad \frac{2^N \times 2^N \text{ matrix}}$$

solution :

$$\frac{p(\vec{y})}{N} T(\vec{y} \rightarrow \vec{x}) = \frac{p(\vec{x})}{N} T(\vec{x} \rightarrow \vec{y})$$

detailed balance condition

$$T(\vec{x} \rightarrow \vec{y}) = \frac{p(\vec{y})}{p(\vec{x})} T(\vec{y} \rightarrow \vec{x})$$

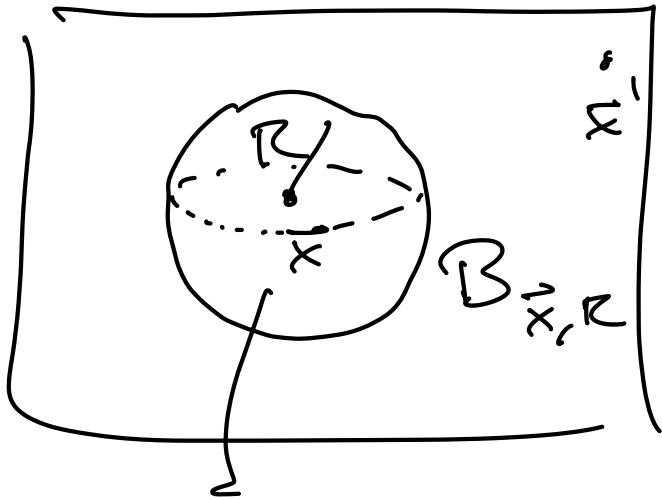
proposal probability (density)

$$T(\vec{x} \rightarrow \vec{y}) = T_{\text{prop}}(\vec{x} \rightarrow \vec{y}) \cdot \underline{A(\vec{x} \rightarrow \vec{y})}$$

↓
geometric

↓
acceptance probability

ex.



$$T_{\text{prop}}(\vec{x} \rightarrow \vec{y}) = T_{\text{prop}}(\vec{y} \rightarrow \vec{x})$$

extract \vec{y} at random
from $B_{\vec{x}, R}$

$$A(\vec{x} \rightarrow \vec{y}) = \frac{p(\vec{y})}{p(\vec{x})} A(\vec{y} \rightarrow \vec{x})$$

Metropolis's - Hastings solution

$$A(\vec{x} \rightarrow \vec{y}) = \min \left(1, \frac{p(\vec{y})}{p(\vec{x})} \right)$$

Build a sample of $\frac{p(\vec{x})}{N}$
k-th step.

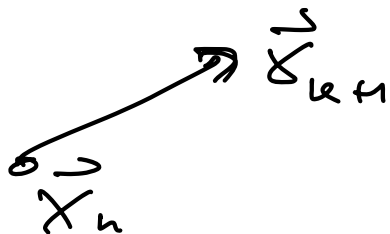
1) $\vec{x}_k \rightarrow$ propose \vec{y} with $T_{\text{prop}}(\vec{x}_k \rightarrow \vec{y})$

2) extract rand. number $z \in [0, 1]$

3) $z \leq A(\vec{x}_k \rightarrow \vec{y}) \Rightarrow \vec{x}_{k+1} = \vec{y}$

otherwise $\Rightarrow \vec{x}_{k+1} = \vec{x}_k$

4) goto 1



$(\vec{x}_1, \vec{x}_2, \dots, \vec{x}_L)$ sample

$$\begin{aligned}
 \bar{I}_L &= \frac{1}{L} \sum_{n=1}^L g(\vec{x}_n) \underset{L \rightarrow \infty}{\approx} \bar{I} \\
 &= \sum_{j=1}^J \left(\frac{n(\vec{x}_j)}{L} \right) g(\vec{x}_j) \\
 &\underset{L \rightarrow \infty}{\approx} \int \phi(\vec{x}_j) \frac{d^D x}{\mathcal{V}}
 \end{aligned}$$