## Submanifolds, Tangent spaces and Differentials Critical values, Sard's Theorem Correction

**Exercise 1** (Tangent space of a submanifold).

Let  $M \subset \mathbb{R}^m$  and  $N \in \mathbb{R}^n$  be submanifolds of  $\mathbb{R}^m$  and  $\mathbb{R}^n$  respectively.

1. (a) If M is locally given by a submersion  $f: U \subset \mathbb{R}^n \to \mathbb{R}^{n-m}$ , with  $M \cap U = f^{-1}(\{0\})$ , then

$$T_p M = \ker \left( \mathrm{d}f(p) \right)$$

(b) If M is locally given by an immersion  $f: V \subset \mathbb{R}^m \to U \subset \mathbb{R}^n$ , with f(0) = p and f homeomorphism from V to  $U \cap M$ , then

$$T_p M = \operatorname{Im} \left( \mathrm{d} f(0) \right)$$

(c) If M is locally given by a diffeomorphism  $f: U \subset \mathbb{R}^n \to V \subset \mathbb{R}^n$ , with f(p) = 0and  $M \cap U = f^{-1}(V \cap (\mathbb{R}^m \times \{0\}))$ , then

$$T_p M = \mathrm{d} f^{-1}(0) \cdot (\mathbb{R}^m \times \{0\})$$

Note that if M is considered as an abstract manifold in itself, and  $T_pM$  as an abstract vector space, then the inclusion map

$$\iota: M \to \mathbb{R}^n$$

is a smooth embedding and its differential at p

$$\mathrm{d}\iota(p)\colon T_pM\to\mathbb{R}^n$$

is an injective linear map with image  $d\iota(p)(T_pM)$  canonically isomorphic to the extrinsic definitions of  $T_pM$  above.

2. Let  $U \subset \mathbb{R}^m$  and  $V \subset \mathbb{R}^n$  be open neighborhoods. Let  $\tilde{f} : U \to V$  be a smooth map such that  $f := \tilde{f}|_{M \cap U} : M \cap U \to N \cap V$ . Show that f is a smooth map between manifolds and that

$$\mathrm{d}f_p = \left(\mathrm{d}\widetilde{f}_p\right)\Big|_{T_pM} : T_pM \to T_{f(p)}N$$

Exercise 2 (Veronese embedding).

- 1. It suffices to show that f is a homeomorphism onto its image. It will then be a smooth immersion which is an homeomorphism onto its image, that is, an embedding. Notice that it is sufficient to show that  $f^{-1}$  is continuous. Here are two proofs:
  - (a) Using that a manifold is metrizable, *i.e* that its topology is defined thanks to a metric.

Let  $\{y_n\}_{n\in\mathbb{N}}$  be a converging sequence in f(M) with limit  $y \in f(M)$ . Let  $x_n$  and x be the unique point in M with  $f(x_n) = y_n$  and f(x) = y (which do exist because f is injective). Then the subset  $K = (\bigcup_{n\in\mathbb{N}}\{y_n\}) \cup \{y\}$  is compact. The function f

being proper,  $f^{-1}(K) = (\bigcup_{n \in \mathbb{N}} \{x_n\}) \cup \{x\}$  is compact. Hence,  $\{x_n\}_{n \in \mathbb{N}}$  has a limit points. Let  $\widetilde{x}$  be on of them. By continuity of f, we have  $f(x_n) \to f(\widetilde{x})$ , that is  $y_n \to f(\widetilde{x})$ , and  $f(x) = f(\widetilde{x})$ . By injectivity of f,  $\widetilde{x} = x$ . It follows that  $(x_n)$  has a unique limit point x, and thus,  $x_n \to x$ , that is,  $f^{-1}(y_n) \to f^{-1}(y)$ . Finally,  $f^{-1}$  is continuous.

(b) Using that a manifold is compactly generated, that is a subset is open / closed if and only if it is open / closed in any compact subset. In particular, it suffices to show that the restriction of  $f^{-1}$  to any compact subset of f(M) is continuous.

Let  $K \subset f(M)$  be a compact: f being proper,  $f^{-1}(K)$  is compact. Then, the restriction  $f|_{f^{-1}(K)}: f^{-1}(K) \to K$  is continuous between  $f^{-1}(K)$ , compact Hausdorff, and K, compact. Hence, it is a homeomorphism. It follows that  $f^{-1}|_K$  is continuous. This concludes the proof.

2. Let us first show that f is well defined. Let  $(x : y : z) \in \mathbb{RP}^2$  be represented by  $(x, y, z) \neq (0, 0, 0)$  and  $(x', y', z') \neq (0, 0, 0)$ : there exists  $\lambda \neq 0$  such that  $(x, y, z) = (\lambda x, \lambda y, \lambda z)$ . But then,  $(x^2, y^2, z^2, xy, yz, zx) = \lambda^2 (x'^2, y'^2, z'^2, x'y', y'z', z'x') \neq (0, 0, 0, 0, 0, 0)$  and it follows that f is well defined.

Let us show that f is injective. Suppose f(x : y : z) = f(x' : y' : z'). Then there exists  $t \neq 0$  with

$$\begin{cases} x^2 &= tx'^2 \\ y^2 &= ty'^2 \\ z^2 &= tz'^2 \\ xy &= tx'y' \\ yz &= ty'z' \\ yx &= tz'x' \end{cases}$$

Notice first that t > 0. The three first equations shows that

$$\begin{cases} x &= \pm \sqrt{t} x' \\ y &= \pm \sqrt{t} y' \\ z' &= \pm \sqrt{t} z' \end{cases}$$

The fourth equation shows that either  $(x, y) = \sqrt{t}(x', y')$  or  $(x, y) = -\sqrt{t}(x', y')$ : that is, the sign is the same for the two first equations. Similarly, the fifth equation shows that the sign before  $\sqrt{t}$  is the same for y and z. It follows that (x : y : z) = (x' : y' : z'), and then, f is injective.

Let us now show that f is an immersion. Consider the affine chart  $(\varphi_x, U_x)$  of  $\mathbb{RP}^2$ defined by  $U_x = \{(x : y : z) \in \mathbb{RP}^2 \mid x \neq 0\}$  and  $\varphi_x^{-1} \colon \mathbb{R}^2 \to U_x$  defined by  $\varphi_x^{-1}(y, z) = (1 : y : z)$ . Similarly, consider the chart  $(U_0, \varphi_0)$  of  $\mathbb{RP}^5$  defined by  $U_a = \{(a : b : c : d : e : f) \in \mathbb{RP}^5 \mid a \neq 0\}$  and  $\varphi_a(a : b : c : d : e : f) = \frac{1}{a}(b, c, d, e, f)$ . Then  $f(U_x) \subset U_a$  and in these charts, we have

$$\widetilde{f} = \varphi_a \circ f \circ \varphi_x^{-1} \colon \quad \mathbb{R}^2 \quad \longrightarrow \quad \mathbb{R}^5 \\ (z, y) \quad \longmapsto \quad (y^2, z^2, y, yz, z)$$

It is smooth as a polynomial function, and if  $(y, z) \in \mathbb{R}^2$ , the differential of  $\tilde{f}$  at (x, y)

has matrix in the canonical bases

$$\operatorname{Mat}_{\operatorname{can}}\left(\mathrm{d}\widetilde{f}(x,y)\right) = \begin{bmatrix} 2y & 0\\ 0 & 2z\\ 1 & 0\\ z & y\\ 0 & 1 \end{bmatrix}$$

and thus,  $d\tilde{f}(y, z)$  has rank 2. Hence, f is an immersion on  $U_x$ . Similarly, f is a smooth immersion on  $U_y = \{(x : y : z) \in \mathbb{RP}^2 \mid y \neq 0\}$  and on  $U_z = \{(x : y : z) \in \mathbb{RP}^2 \mid z \neq 0\}$  and finally, f is a smooth immersion on  $U_x \cup U_y \cup U_z = \mathbb{RP}^2$ .

Therefore, f is an injective smooth immersion on  $\mathbb{RP}^2$ . As  $\mathbb{RP}^2$  is compact and f continuous, f is obviously proper. By 1., f is an embedding.

Exercise 3 (Tangent space of the torus).

1. Consider the map  $f: \mathbb{R}^2 \to \mathbb{R}^4$  defined by

$$f(t_1, t_2) = (\cos 2\pi t_1, \sin 2\pi t_1, \cos 2\pi t_2, \sin 2\pi t_2)$$

It is  $\mathbb{Z}^2$ -invariant and descends as a smooth map  $\overline{f} \colon \mathbb{T}^2 \to \mathbb{R}^4$  such that  $f = \overline{f} \circ p$ . If  $(t_1, t_2) \in \mathbb{R}^2$ , then  $df(t_1, t_2)$  has matrix in the canonical bases

$$\operatorname{Mat}_{\operatorname{can}}\left(\mathrm{d}f(t_{1},t_{2})\right) = 2\pi \begin{bmatrix} -\sin 2\pi t_{1} & 0\\ \cos 2\pi t_{1} & 0\\ 0 & -\sin 2\pi t_{2}\\ 0 & \cos 2\pi t_{2} \end{bmatrix}$$

and  $df(t_1, t_2)$  is of rank 2. Recall that  $p \colon \mathbb{R}^2 \to \mathbb{T}^2$  is a local diffeomorphism. Therefore, if  $(t_1, t_2) \in \mathbb{R}^2$ , the chain rule yields

$$df(t_1, t_2) = d\overline{f}(\overline{t_1, t_2}) \circ dp(t_1, t_2)$$

from which we deduce, recalling that  $dp(t_1, t_2)$  is a linear isomorphism

$$\mathrm{d}\overline{f}(\overline{t_1,t_2}) = \mathrm{d}f(t_1,t_2) \circ (\mathrm{d}p(t_1,t_2))^{-1}$$

Thus,  $d\overline{f}(\overline{t_1, t_2})$  has rank 2. This being true for all  $\overline{(t_1, t_2)} \in \mathbb{T}^2$ ,  $\overline{f}$  is an immersion.

One can check that  $\overline{f}$  is injective: for example,  $f \colon \mathbb{R}^2 \to \mathbb{C}^* \times \mathbb{C}^*$  is a group homomorphism with kernel  $\mathbb{Z}^2$ , so that  $\overline{f}$  is injective.

Finally,  $\mathbb{T}^2$  is compact Hausdorff, so that  $\overline{f}$  is proper (any continuous function on a compact Haussdorff space is proper). Hence,  $\overline{f}$  is an injective proper immersion, and is an embedding.

Let us now consider  $\mathbf{T}^2 = \overline{f}(\mathbb{T}^2) \subset \mathbb{R}^4$  the embedded torus in  $\mathbb{R}^4$  and fix any point  $p = (\cos 2\pi t_1, \sin 2\pi t_1, \cos 2\pi t_2, \sin 2\pi t_2) \in \mathbf{T}_2$ . Then  $\mathbf{T}^2$  is locally given by the immersion  $f: \mathbb{R}^2 \to \mathbb{R}^4$  defined above, and  $T_p \mathbf{T}^2 = \operatorname{Im} df(t_1, t_2)$ , which is then

$$T_p \mathbf{T}_2 = \left\{ \lambda X_1(p) + \mu X_2(p) \mid (\lambda, \mu) \in \mathbb{R}^2 \right\}$$

with 
$$X_1(p) = \begin{bmatrix} -\sin 2\pi t_1 \\ \cos 2\pi t_1 \\ 0 \\ 0 \end{bmatrix}$$
 and  $X_2(p) = \begin{bmatrix} 0 \\ 0 \\ -\sin 2\pi t_2 \\ \cos 2\pi t_2 \end{bmatrix}$ , which are linearly independent.

It follows that  $X_1$  and  $X_2$  are smooth vector fields on  $\mathbf{T}_2$  which are everywhere linearly independent, so that  $\mathbf{T}_2$  is trivializable.

2. If R > r, the map

$$g_{R,r}: \mathbb{R}^2 \longrightarrow \mathbb{R}^3$$

$$(t_1, t_2) \longmapsto \begin{pmatrix} (R + r \cos 2\pi t_1) \cos 2\pi t_2 \\ (R + r \cos 2\pi t_1) \sin 2\pi t_2 \\ r \sin 2\pi t_1 \end{pmatrix}$$

is  $\mathbb{Z}^2$  invariant and descends to the quotient as  $\overline{g}_{R,r} \colon \mathbb{T}^2 \to \mathbb{R}^3$  which is an embedding: this can be derived from the exact same study as in 1.



Figure 1: A torus embedded in  $\mathbb{R}^3$ 

3. An exact same study as in 1. shows that one can embed  $\mathbb{T}^n$  in  $\mathbb{R}^{2n}$  and that the vector fields

$$X_{i} \begin{pmatrix} \cos 2\pi t_{1} \\ \cos 2\pi t_{2} \\ \vdots \\ \cos 2\pi t_{n} \\ \sin 2\pi t_{n} \end{pmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ -\sin 2\pi t_{i} \\ \cos 2\pi t_{i} \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

give a parallelization of  $\mathbb{T}^n \subset \mathbb{R}^{2n}$ .

*Remark:* we have shown that these particular embedded tori in  $\mathbb{R}^4$  or  $\mathbb{R}^3$  are parallelizable. In fact, this notion is intrinsic and does not depends on the embedding in  $\mathbb{R}^N$ , but it requires the definition of vector bundle isomorphism, which has not been seen yet.

Exercise 4 (Tangent space of spheres).

1. Let  $\gamma : (-\varepsilon, \varepsilon) \to \mathbb{R}^2$  be a smooth arc. Then for all t,  $\|\gamma(t)\|^2 = 1$ . Differentiating this shows that  $\langle \gamma(0), \gamma'(0) \rangle = 0$ , so that  $\gamma'(0) \in \gamma(0)^{\perp}$ . We deduce that  $T_{\gamma(0)} \mathbb{S}^1 \subset \gamma(0)^{\perp}$ ,

and we have in fact an equality because  $\mathbb{S}^1$  is a one dimensional submanifold of  $\mathbb{R}^2$ , so that  $T_{\gamma(0)}\mathbb{S}^1$  is one dimensional.

If follows that X(x,y) = (-y,x) is a smooth vector field on  $\mathbb{S}^1$ , which does not vanish. Thus, we have found a parallelization of  $T\mathbb{S}^1$ .

The two dimensional sphere is not parallelizable because of the Hairy ball Theorem: any smooth (in fact, continuous) vector field on  $\mathbb{S}^2$  vanishes somewhere.

- 2. Let  $G \subset \mathbb{R}^n$  be a Lie group.
  - (a) For  $g \in G$ , consider the left translation by g:

which is smooth as the restiction to  $\{g\} \times G$  of the multiplication  $\mu$ . Then  $L_{g^{-1}}$  is also smooth and  $L_q \circ L_{g^{-1}} = L_{g^{-1}} \circ L_g = \mathrm{Id}_G$ , so that  $L_g$  is a diffeomorphism. As  $L_g(e) = g$ , the linear map

$$\mathrm{d}L_q(e)\colon T_eG \to T_qG \subset \mathbb{R}^n$$

is a linear isomorphism. It follows from the smoothness of  $\mu$  that the map  $g \in G \mapsto$  $dL_g(e) \in \mathcal{L}(T_eG, \mathbb{R}^n)$  is smooth.

Let  $(e_1, \ldots e_m)$  be a basis of  $T_e G$  and consider  $X_i \colon G \to \mathbb{R}^n$  defined by

$$X_i(g) = \mathrm{d}L_g(e) \cdot e_i$$

By construction, it is a smooth vector field on G, and at each point  $g \in G$ ,  $(X_1(g), \ldots, X_m(g))$  is a basis of  $T_gG$ . Thus, G is parallelizable.

(b) It is a well-known fact that SU(2) is a subgroup of  $GL_2(\mathbb{C})$  with

$$SU(2) = \left\{ \begin{bmatrix} \alpha & \beta \\ -\overline{\beta} & \overline{\alpha} \end{bmatrix} \mid |\alpha|^2 + |\beta|^2 = 1 \right\}.$$

Consider the map

$$\begin{array}{cccc} f \colon & \mathbb{R}^4 & \longrightarrow & M_2(\mathbb{C}) \\ & & (x, y, z, t) & \longmapsto & \begin{bmatrix} x + iy & z + it \\ -z + it & x - iy \end{bmatrix}$$

Then f is an injective linear map, and is thus a smooth embedding. Moreover,  $\mathbb{S}^3$  is a submanifold of  $\mathbb{R}^4$  whose image is precisely SU(2): it follows that SU(2) is a submanifold of  $M_2(\mathbb{C}) \simeq \mathbb{R}^8$  diffeomorphic to  $\mathbb{S}^3$ .

The multiplication in  $M_2(\mathbb{C})$  is smooth, and so is its restriction to SU(2). Also, the inversion in  $GL_2(\mathbb{C})$  is given by

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

which is smooth, and its restriction to SU(2) is smooth.

- (c) We know that SU(2) is parallelizable as a Lie group. Hence, it has 3 vectors fields  $Y_1$ ,  $Y_2$  and  $Y_3$  that are pointwise linearly independent. It follows that  $X_i(p) = df(p)^{-1}Y_i(f(p))$  are three vector fields on  $\mathbb{S}^3$  which are pointwise linearly independent, and then,  $\mathbb{S}^3$  is parallelizable.
- (d) *(bonus)* In  $\mathbb{C}^2$ , define

$$\mathbf{1} = (1,0),$$
  $\mathbf{i} = (i,0),$   $\mathbf{j} = (0,1),$   $\mathbf{k} = (0,i),$ 

which form an orthonormal basis if  $\mathbb{C}^2 \simeq \mathbb{R}^4$  for the usual inner product. One can show that the multiplication defined by

$$i^2 = j^2 = k^2 = ijk = -1$$

extended linearly, is associative (in fact, we have constructed the *quaternions*) and satisfies ||qq'|| = ||q|| ||q'||. Define on  $\mathbb{S}^3$  the functions

$$X_1(x) = \mathbf{i}x, \qquad \qquad X_2(x) = \mathbf{j}x, \qquad \qquad X_3(x) = \mathbf{k}x$$

Show that they are vector fields on  $\mathbb{S}^3$  and that they parallelize the sphere.

**Exercise 5** (Computation of a differential).

Exercise 6 (Extending smooth function).

Sketch of a proof:

- 1. First, note that if  $f: M^m \subset \mathbb{R}^p \to N^n \subset \mathbb{R}^q$  is smooth, then its co-extension  $f: M \to \mathbb{R}^q$  is smooth, and "there is nothing to tell on the right". Let us then focus on the left.
- 2. Second, take a chart on  $\mathbb{R}^p$  adapted to M, that is, in that chart, M is given by  $M \cap U = \{(x^1, \ldots, x^m, 0, \ldots, 0)\}.$
- 3. In that chart, extend f by  $\widetilde{f}(x^1, \ldots, x^p) = f(x^1, \ldots, x^m)$ .
- 4. Choose a locally finite open covering of M by charts as above and consider a partition of unity subordinate to this cover. Glue the extensions constucted above thanks to this partition of unity: this gives an extension of f on an open subset of  $\mathbb{R}^p$ .
- 5. Enjoy.

Exercise 7 (Critical points VS critical values).

1.  $\mathbb{R} \setminus F$  is an open subset of the real line. If non-empty, it is a countable union of disjoint open intervals: say  $\mathbb{R} \setminus F = \bigcup_{i \in I} (a_i, b_i)$  with I finite or countable. It may be possible that one of the  $a_i$  (and only one) is equal to  $-\infty$ , and similarly, that one of the  $b_i$  (and only one) if equal to  $+\infty$ .

For  $i \in I$ , construct a smooth nonnegative function  $f_i \colon \mathbb{R} \to \mathbb{R}$  with  $f_i(x) > 0 \iff x \in (a_i, b_i)$ . Then the function  $f = \sum_{i \in I} f_i$  is a solution.

2. As K is closed, there exists by 1. a smooth nonnegative function  $g: \mathbb{R} \to \mathbb{R}$  with  $g(x) = 0 \iff x \in K$ . Define

$$f(x) = \int_0^x g(t) \,\mathrm{d}t$$

Then f is smooth with  $f' = g \ge 0$ , and is thus nondecreasing. The function g vanishes exactly on K, which is of empty interior: hence, if x < y, then  $f(y) - f(x) = \int_x^y g(t) dt > 0$ , and f is strictly increasing. If follows that f is a smooth homeomorphism of  $\mathbb{R}$  onto its image. Its set of critical points is K, by definition of g, which has Lebesgue measure  $\lambda(K) > 0$ . But by Sard's Theorem,  $f(\operatorname{Crit}(f))$  has measure zero.

*Remark:* the function f constructed above may not be a homeomorphism from  $\mathbb{R}$  onto  $\mathbb{R}$ , because its image may not be all of  $\mathbb{R}$ . But we can adapt the proof in order to do so: show it!

Exercise 8 (Change of variable).

First, notice that we have the disjoint union  $\varphi(U) = (\varphi(U) \setminus \varphi(\operatorname{Crit} \varphi)) \cup \varphi(\operatorname{Crit} \varphi)$ . Therefore:

$$\lambda(\varphi(U)) = \int_{\varphi(U)} 1 \, \mathrm{d}\lambda = \int_{\varphi(U) \setminus \varphi(\operatorname{Crit}\varphi)} 1 \, \mathrm{d}\lambda + \int_{\varphi(\operatorname{Crit}\varphi)} 1 \, \mathrm{d}\lambda$$

From Sard's Theorem,  $\varphi(\operatorname{Crit}\varphi)$  has measure zero, and thus, we have

$$\lambda(\varphi(U)) = \int_{\varphi(U) \setminus \varphi(\operatorname{Crit}\varphi)} 1 \,\mathrm{d}\lambda$$

Since  $\varphi$  is an homeomorphism, it is injective and it follows that  $\varphi(U) \setminus \varphi(\operatorname{Crit} \varphi) = \varphi(U \setminus \operatorname{Crit} \varphi)$ . But by definition of  $\operatorname{Crit} \varphi$ ,  $d\varphi(x)$  is invertible is  $x \in U \setminus \operatorname{Crit} \varphi$ , and from the inverse function Theorem, the restriction  $\varphi|_{U \setminus \operatorname{Crit} \varphi}$  is a diffeomorphism onto its image. The usual change of variable gives

$$\lambda(\varphi(U)) = \int_{U \setminus \operatorname{Crit}\varphi} |\det \mathrm{d}\varphi| \,\mathrm{d}\lambda$$

and to conclude, note that on  $\operatorname{Crit}\varphi$ , we have  $|\det d\varphi| = 0$ , so that we have the formula

$$\lambda(\varphi(U)) = \int_U |\det \mathrm{d}\varphi| \,\mathrm{d}\lambda$$