

TD 9 - Correction

Exercise 1

1) \mathcal{L}_X is a derivation of $\Omega^*(\mathbb{R}^3)$ of degree 0. In particular, $\mathcal{L}_X \omega \in \Omega^3(\mathbb{R}^3)$.

Since $\Omega^3(\mathbb{R}^3)$ is a rank 1 free $\mathcal{C}^\infty(\mathbb{R}^3)$ -module with basis ω , there exists a unique function $\operatorname{div} X: \mathbb{R}^3 \rightarrow \mathbb{R}$ such that $\mathcal{L}_X \omega = (\operatorname{div} X)\omega$. ▣

2) By Cartan's magic formula, $\mathcal{L}_X \omega = d(i_X \omega) + i_X d\omega$.

Recall that $d\omega = 0$ since ω is a top form. Moreover, if $Y = Y^1 \partial_1 + Y^2 \partial_2 + Y^3 \partial_3$

and $Z = Z^1 \partial_1 + Z^2 \partial_2 + Z^3 \partial_3$, then

$$\begin{aligned} (i_X \omega)(Y, Z) &= \omega(X, Y, Z) = \begin{vmatrix} X^1 & Y^1 & Z^1 \\ X^2 & Y^2 & Z^2 \\ X^3 & Y^3 & Z^3 \end{vmatrix} = X^1 (Y^2 Z^3 - Y^3 Z^2) - X^2 (Y^1 Z^3 - Y^3 Z^1) + X^3 (Y^1 Z^2 - Y^2 Z^1) \\ &= X^1 d\alpha^2 \wedge d\alpha^3 (Y, Z) - X^2 d\alpha^1 \wedge d\alpha^3 (Y, Z) + X^3 d\alpha^1 \wedge d\alpha^2 (Y, Z) \end{aligned}$$

Hence, $i_X \omega = X^1 d\alpha^2 \wedge d\alpha^3 - X^2 d\alpha^1 \wedge d\alpha^3 + X^3 d\alpha^1 \wedge d\alpha^2$, and therefore,

$$\begin{aligned} d(i_X \omega) &= \frac{\partial X^1}{\partial \alpha^1} d\alpha^1 \wedge d\alpha^2 \wedge d\alpha^3 - \frac{\partial X^2}{\partial \alpha^2} d\alpha^2 \wedge d\alpha^1 \wedge d\alpha^3 + \frac{\partial X^3}{\partial \alpha^3} d\alpha^3 \wedge d\alpha^1 \wedge d\alpha^2 \\ &= \left(\frac{\partial X^1}{\partial \alpha^1} + \frac{\partial X^2}{\partial \alpha^2} + \frac{\partial X^3}{\partial \alpha^3} \right) d\alpha^1 \wedge d\alpha^2 \wedge d\alpha^3 \end{aligned}$$

Finally, $\operatorname{div} X = \frac{\partial X^1}{\partial \alpha^1} + \frac{\partial X^2}{\partial \alpha^2} + \frac{\partial X^3}{\partial \alpha^3}$ ▣

3) Let $M = B(0, r)$. It is a smooth manifold with boundary $\partial M = S(0, r)$.

It follows by Stokes formula that $\int_{S(0, r)} i^*(i_X \omega) = \int_{B(0, r)} d(i_X \omega)$.

By 2), $d(i_X \omega) = (\operatorname{div} X) d\alpha^1 \wedge d\alpha^2 \wedge d\alpha^3$

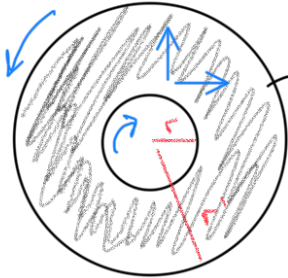
By its expression, $\operatorname{div} X \equiv 3$, hence, it follows that

$$\int_{S(0, r)} i^*(i_X \omega) = \int_{B(0, r)} 3 \cdot d\alpha^1 \wedge d\alpha^2 \wedge d\alpha^3 = 3 \times \operatorname{Vol}(B(0, r)) = 4\pi r^3. \quad \text{▣}$$

$\succ (a, r)$ $\sim B(a, r)$

Exercise 2

1) For $0 < r < r'$, let $A(r, r') = \{(x, y) \in \mathbb{R}^2 \mid r^2 \leq x^2 + y^2 \leq r'^2\}$, endowed with the



$A(r, r')$ orientation of \mathbb{R}^2 . It is a smooth manifold with

$$\text{boundary } \partial A(r, r') = \mathcal{C}(a, r)^+ \cup \mathcal{C}(a, r)^-$$

\uparrow
anti-clockwise
 \uparrow
clockwise

Hence, by Stokes Theorem, $\int_{\mathcal{C}(a, r)} i^* \omega - \int_{\mathcal{C}(a, r')} i^* \omega = \int_{\partial A(r, r')} i^* \omega = \int_{A(r, r')} d\omega$.

But it holds that

$$\begin{aligned} d\omega &= d\left(\frac{-y}{x^2+y^2}\right) \wedge dx + d\left(\frac{x}{x^2+y^2}\right) \wedge dy \\ &= \frac{-(x^2+y^2) + 2y^2}{(x^2+y^2)^2} dy \wedge dx + \frac{(x^2+y^2) - 2x^2}{(x^2+y^2)^2} dx \wedge dy \\ &= \frac{y^2 - x^2}{(x^2+y^2)^2} (dx \wedge dy - dy \wedge dx) \\ &= 0. \end{aligned}$$

The result follows. ▣

2) By Cartan's magic formula, $\mathcal{L}_X \omega = d(i_X \omega) + i_X d\omega$

By 1), $d\omega = 0$, and by its expression, $i_X \omega = \frac{-y}{x^2+y^2} x dx + \frac{x}{x^2+y^2} x y dy = 0$.

Hence, $\mathcal{L}_X \omega = 0$. ▣

Exercise 3

$$1) H^0(M) = \frac{\{f \in \mathcal{C}^\infty(M) \mid df = 0\}}{\sim} \simeq \{f \in \mathcal{C}^\infty(M) \mid df = 0\}.$$

Write $M = M_1 \cup \dots \cup M_k$ partition in connected components.

$k \in \{1, \dots, k\}$, fix $x_i \in M_i$. Let F be defined as

$$F: H^0(M) \longrightarrow \mathbb{R}^k$$

$$f \longmapsto (f(x_1), \dots, f(x_k))$$

F is clearly linear. Since functions that are constant on each connected component are closed, F is surjective. Finally, F is injective: if $f \in \text{Ker } F$, then $df = 0$, and by the mean value theorem, f is locally constant, hence constant

on each connected component. It follows from $f(x_1) = \dots = f(x_k) = 0$ that $f = 0$. □

2) Recall that $H^m(M) = \frac{\{\omega \in \Omega^m(M) \mid d\omega = 0\}}{\{d\alpha \mid \alpha \in \Omega^{m-1}(M)\}}$

That is, $[\omega] = [\omega'] \in H^m(M) \iff \exists \alpha \in \Omega^{m-1}(M), \omega - \omega' = d\alpha$.

Let $I: \Omega^m(M) \longrightarrow \mathbb{R}$. Then I is linear. Let us show that I descends to the quotient.

$$\omega \longmapsto \int_M \omega$$

Let $\omega, \omega' \in \Omega^m(M)$ with $[\omega] = [\omega']$. There exists $\alpha \in \Omega^{m-1}(M)$, $\omega - \omega' = d\alpha$.

Hence, $I(\omega) - I(\omega') = \int_M d\alpha = \int_{\partial M} \alpha = 0$ since $\partial M = \emptyset$, and

$I(\omega) = I(\omega')$. I descends to the quotient as

$$\bar{I}: H^m(M) \longrightarrow \mathbb{R}$$

$$[\omega] \longmapsto \int_M \omega.$$

Let us show that \bar{I} is an isomorphism. Let ω_0 be a volume form.

Then $\bar{I}([\omega_0]) = \int_M \omega_0 \neq 0$ and \bar{I} is a non-zero linear form, hence surjective.

Let us show that \bar{I} is injective.

Lemma: let $\omega \in \Omega^n(\mathbb{R}^n)$ be a top. form with compact support, with $\int_{\mathbb{R}^n} \omega = 0$.

Then there exists $\alpha \in \Omega^{n-1}(\mathbb{R}^n)$ with $\omega = d\alpha$, and with compact support.

Write $\omega = f(x^1, \dots, x^n) dx^1 \wedge \dots \wedge dx^n$ with $f \in C_c^\infty(\mathbb{R}^n)$ with compact support.

Let $h: \mathbb{R} \rightarrow \mathbb{R}$ be smooth, with compact support, and $\int_{\mathbb{R}} h = 1$.

For $k \in \{1, \dots, n\}$, define

$$f_k: \mathbb{R}^n \rightarrow \mathbb{R} \text{ by } f_k(x^1, \dots, x^n) = h(x^k) \cdot h(x^{k+1}) \int_{\mathbb{R}} f(y^1, \dots, y^{k-1}, x^{k+1}, \dots, x^n) dy^1 \dots dy^{k-1}$$

and set $f_0 = f$. By assumption on ω , $f_0 = 0$.

Fix $k \in \{1, \dots, n\}$, and set

$$g_k(x^1, \dots, x^n) = \int_{t=-\infty}^{x^k} f_k(x^1, \dots, x^{k-1}, t, x^{k+1}, \dots, x^n) - \int_{t=-\infty}^{x^{k+1}} f_k(x^1, \dots, x^k, t, x^{k+1}, \dots, x^n) dt.$$

g_k is smooth with compact support. Moreover, $\frac{\partial g_k}{\partial x^k} = f_k - f_{k+1}$.

It follows that

$$\begin{aligned} \omega &= f dx^1 \wedge \dots \wedge dx^n = (f_0 - f_n) dx^1 \wedge \dots \wedge dx^n \\ &= -\sum_{k=1}^n (f_k - f_{k+1}) dx^1 \wedge \dots \wedge dx^n \\ &= -\sum_{k=1}^n \frac{\partial g_k}{\partial x^k} dx^1 \wedge \dots \wedge dx^n \\ &= \sum_{k=1}^n (-1)^k d(g_k dx^1 \wedge \dots \wedge \widehat{dx^k} \wedge \dots \wedge dx^n) \\ &= d\alpha \end{aligned}$$

$$\text{with } \alpha = \sum_{k=1}^n g_k dx^1 \wedge \dots \wedge \widehat{dx^k} \wedge \dots \wedge dx^n$$

Let us show that this result extends to compact manifolds. Let $\omega \in \Omega^n(M)$ with

$\int_{\Gamma} \omega = 0$. Choose an open cover $M = U_1 \cup U_2 \cup \dots \cup U_N$ where

each U_i is diffeomorphic to \mathbb{R}^n . Choose an adapted partition of unity

$\{\varphi_i\}_{i=1}^N$ (with $\text{supp } \varphi_i \subset U_i$) and write $\omega = \sum_{i=1}^N \varphi_i \omega = \sum_{i=1}^N \omega_i$

with $\omega_i = \varphi_i \omega$ which has compact support in U_i . By induction, it suffices to

show the case when $N=2$.

Since $\omega = \omega_1 + \omega_2$, it follows that

$$0 = \int_{U_1 \cup U_2} \omega = \int_{U_1 \cup U_2} \omega_1 + \omega_2 = \int_{U_1} \omega_1 + \int_{U_2} \omega_2 \quad \text{and} \quad \int_{U_1} \omega_1 = - \int_{U_2} \omega_2$$

Let η be a top-form with compact support in $U_1 \cap U_2$, such that $\int_{U_1 \cap U_2} \eta = - \int_{U_1} \omega_1$.

Then $\omega = \omega_1 + \omega_2 = (\omega_1 - \eta) + (\omega_2 + \eta) = \tilde{\omega}_1 + \tilde{\omega}_2$

with $\tilde{\omega}_1$ with compact support in U_1 and $\int_{U_1} \tilde{\omega}_1 = 0$ and

$\tilde{\omega}_2$ with compact support in U_2 and $\int_{U_2} \tilde{\omega}_2 = 0$.

By the Lemma (U_1 and U_2 are $\simeq \mathbb{R}^n$), there exist d_1 and $d_2 \in \Omega^{n-1}(U_i)$ with

compact support in U_1 and U_2 respectively such that $\tilde{\omega}_i = dd_i$

Hence, $\omega = dd_1 + dd_2 = d(d_1 + d_2)$.

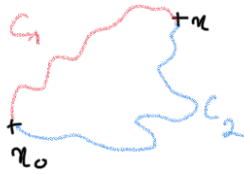
By induction, all n -form with $\int_{\Gamma} \omega = 0$ are exact.

It follows that if $[\omega]$ is such that $\bar{I}([\omega]) = 0$, then $[\omega] = 0$, and \bar{I} is

injective. Hence, it is an isomorphism. ▣

Exercise 4

1) a) Suppose $c_1, c_2: [0,1] \rightarrow M$ are two paths with $c_1(0) = c_2(0) = x_0$ and $c_1(1) = c_2(1) = x_1$.



Consider the loop: $\gamma: [0,1] \rightarrow M$

$$t \mapsto \begin{cases} c_1(2t) & \text{if } t \in [0, \frac{1}{2}] \\ c_2(1-2t) & \text{if } t \in [\frac{1}{2}, 1] \end{cases}$$

then by assumption, $0 = \int_{S^1} \gamma^* \omega = \int_{[0,1]} c_1^* \omega - \int_{[0,1]} c_2^* \omega$. It follows that f is well defined

b) Let $x \in M$ and (U, φ) be a chart centered at x . Consider the path

$\sigma: (-\varepsilon, \varepsilon) \rightarrow M$ defined by $\sigma(t) = \varphi(\varphi^{-1}(x) + t e_j)$ for $j \in \{1, \dots, n\}$.

Then: $d_j f = df(e_j) = \lim_{t \rightarrow 0} \frac{f(\sigma(t)) - f(x)}{t} = \lim_{t \rightarrow 0} \frac{1}{t} \int_0^{1+t} \omega_{\sigma(s)}(\sigma'(s)) ds$

$= \omega_x(e_j)$

Hence, $df = \omega$. ▣

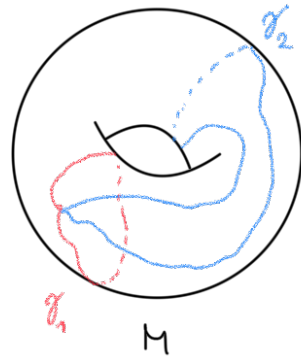
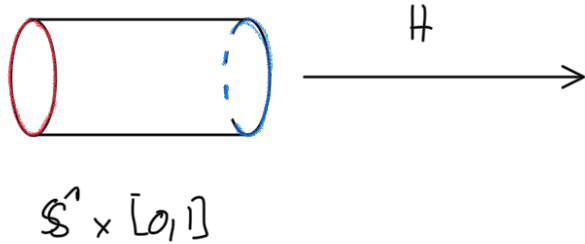
2) Let $\omega \in \Omega^1(M)$. Suppose that $\forall \gamma \in \pi_1(M), \int_\gamma \omega = 0$. By 1), there exists $f \in C^\infty(M)$ such that $\omega = df$. Hence, $[\omega] = 0 \in H_{dR}^1(M)$.

Conversely, suppose $\omega = df$. Let $\gamma: [0,1] \rightarrow M$ be a loop (with $\gamma(0) = \gamma(1)$).

then $\int_\gamma \omega = \int_0^1 \omega_{\gamma(t)}(\gamma'(t)) dt = \int_0^1 df(\gamma(t)) \cdot \gamma'(t) dt = f(\gamma(1)) - f(\gamma(0)) = 0$. ▣

3) a) Suppose that $\sigma_1 \sim \sigma_2$. Let $H: S^1 \times [0,1] \rightarrow M$

be an homotopy between γ_1 and γ_2



then $S^1 \times [0, 1]$ is an oriented manifold with oriented boundary

$S^1 \times \{0\} - S^1 \times \{1\}$. Let $\omega \in \Omega^1(M)$, then by Stokes thm:

$$\int_{\gamma_1} \omega - \int_{\gamma_2} \omega = \int_{S^1} \gamma_1^* \omega - \int_{S^1} \gamma_2^* \omega = \int_{S^1 \times \{0\}} H^* \omega - \int_{S^1 \times \{1\}} H^* \omega = \int_{S^1 \times [0, 1]} d(H^* \omega) = \int_{S^1 \times [0, 1]} H^*(d\omega).$$

Hence, $\int_{\gamma_1} \omega = \int_{\gamma_2} \omega$ as soon as $d\omega = 0$.

It follows that $[\gamma] \mapsto \int_{\gamma} \omega$ is well defined on $\{\omega \in \Omega^1(M) \mid d\omega = 0\}$.

Since S^1 has no boundary, Stokes Theorem shows that $\int_{\gamma} \omega$ only depends on the cohomology class $[\omega]$ therefore,

$$h: H_{dR}^1(M) \longrightarrow \text{Hom}(\pi_1(M), \mathbb{R})$$

$$[\omega] \longmapsto ([\gamma] \mapsto \int_{\gamma} \omega)$$

is well defined. Since the integral is linear and $[\lambda\omega + \omega'] = \lambda[\omega] + [\omega']$,

h is a linear map. ▣

b) This is a direct consequence of 1) and 2), since

$$\text{ker } h = \{[\omega] \mid \forall \gamma, \int_{\gamma} \omega = 0\}$$
▣

c) If M is contractible, then $\pi_1(M) \cong \{0\}$, hence $\text{ker } h = \pi_1(M) = \{0\}$.

Since h is injective, it follows that $h'_{dR}(1) = d\phi$.

