



# On the Complexity of Best Arm Identification with Fixed Confidence

Discrete Optimization with Noise

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## Preliminaries: Basics of Large Deviation Bounds

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# Chernoff Bound for Bernoulli variables

Let  $\mu \in (0, 1)$ . Let  $X_1, X_2, \dots, X_n \sim \mathcal{B}(\mu)$ , and let  $\bar{X}_n = (X_1 + \dots + X_n)/n$ .

## Theorem

For all  $x > \mu$ ,

$$P_\mu (\bar{X}_n \geq x) \leq e^{-n \text{kl}(x, \mu)}$$

where  $\text{kl}(x, y) = x \log \frac{x}{y} + (1-x) \log \frac{1-x}{1-y}$  is the binary relative entropy

## Corollary

For every  $\delta > 0$ ,

$$\mathbb{P}_\mu \left( n \text{kl} (\bar{X}_n, \mu) \geq \log \frac{1}{\delta} \right) \leq 2\delta$$

## Proof: Fenchel-Legendre transform of log-Laplace

For every  $\lambda > 0$ ,

$$\begin{aligned}\mathbb{P}_\mu(\bar{X}_n \geq x) &= \mathbb{P}_\mu\left(e^{\lambda(X_1+\dots+X_n)} \geq e^{\lambda nx}\right) \\ &\leq \frac{\mathbb{E}_\mu[e^{\lambda(X_1+\dots+X_n)}]}{e^{\lambda nx}} \\ &= e^{-n(\lambda x - \log \mathbb{E}_\mu[\exp \lambda X_1])}.\end{aligned}$$

Thus,

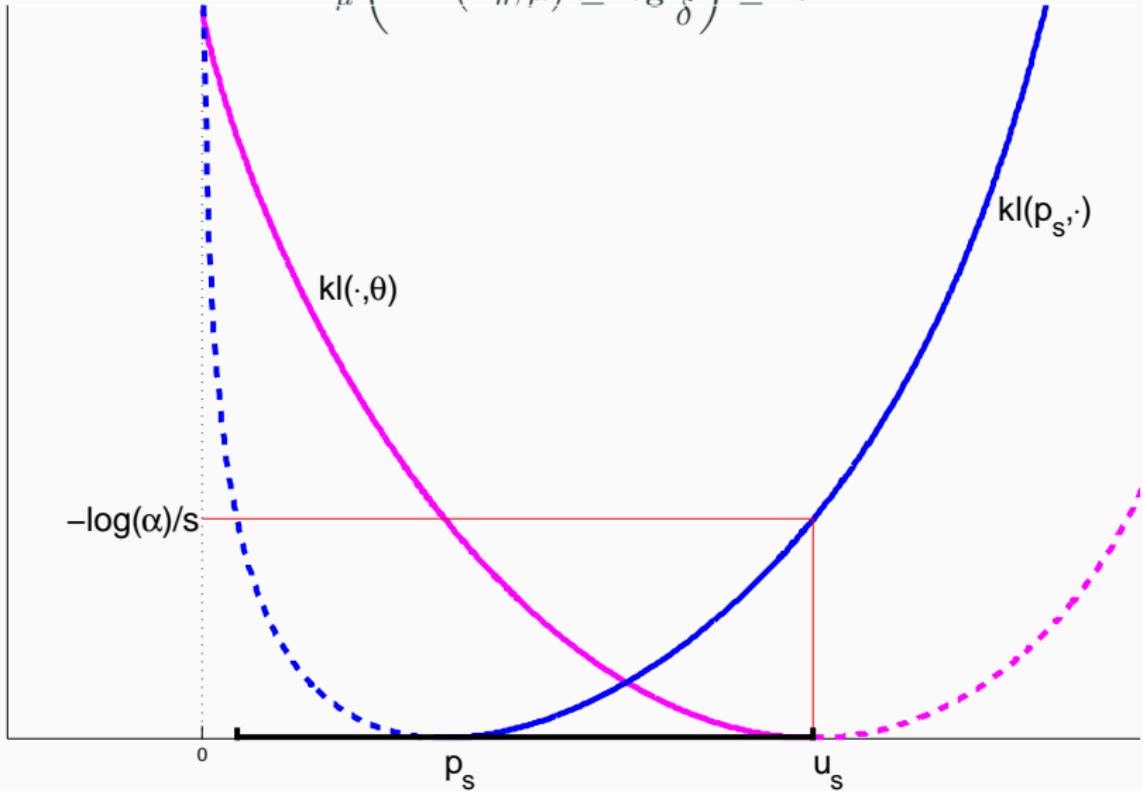
$$\begin{aligned}-\frac{1}{n} \log \mathbb{P}_\mu(\bar{X}_n \geq x) &\geq \sup_{\lambda > 0} \{\lambda x - \log \mathbb{E}_\mu[\exp \lambda X_1]\} \\ &= \sup_{\lambda > 0} \{\lambda x - \log(1 - \mu + \mu e^\lambda)\} \\ &= \text{kl}(x, \mu).\end{aligned}$$

kl = binary Kullback-Leibler divergence: more generally

$$\text{KL}(P, Q) = \mathbb{E}_{X \sim P} \left[ \log \frac{dP}{dQ}(X) \right]$$

# A Divergence on the Set of Possible Means

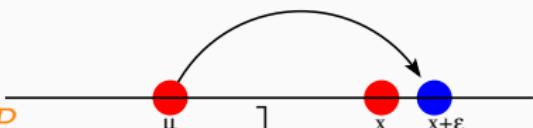
$$\mathbb{P}_\mu \left( n \text{kl} (\bar{X}_n, \mu) \geq \log \frac{1}{\delta} \right) \leq 2\delta$$



## Lower Bound: Change of Measure

For all  $\epsilon > 0$  and all  $\alpha > 0$ ,

$$\begin{aligned}
 \mathbb{P}_\mu(\bar{X}_n \geq x) &= \mathbb{E}_\mu[\mathbf{1}\{\bar{X}_n \geq x\}] \\
 &= \mathbb{E}_{x+\epsilon} \left[ \mathbf{1}\{\bar{X}_n \geq x\} \times \frac{dP_\mu}{dP_{x+\epsilon}}(X_1, \dots, X_n) \right] \\
 &= \mathbb{E}_{x+\epsilon} \left[ \mathbf{1}\{\bar{X}_n \geq x\} \times e^{-\sum_{i=1}^n \log \frac{dP_{x+\epsilon}}{dP_\mu}(X_i)} \right] \\
 &\geq \mathbb{E}_{x+\epsilon} \left[ \mathbf{1}\{\bar{X}_n \geq x\} \mathbf{1}\left\{ \frac{1}{n} \sum_{i=1}^n \log \frac{dP_{x+\epsilon}}{dP_\mu}(X_i) \leq \mathbb{E}_{x+\epsilon} \left[ \log \frac{dP_{x+\epsilon}}{dP_\mu}(X_1) \right] + \alpha \right\} \right. \\
 &\quad \times \left. e^{-\sum_{i=1}^n \log \frac{dP_{x+\epsilon}}{dP_\mu}(X_i)} \right] \\
 &\geq e^{-n \left\{ \mathbb{E}_{x+\epsilon} \left[ \log \frac{dP_{x+\epsilon}}{dP_\mu}(X_1) \right] + \alpha \right\}} \left[ 1 - \mathbb{P}_{x+\epsilon}(\bar{X}_n < x) \right. \\
 &\quad \left. - \mathbb{P}_{x+\epsilon} \left( \frac{1}{n} \sum_{i=1}^n \log \frac{dP_{x+\epsilon}}{dP_\mu}(X_i) > \mathbb{E}_{x+\epsilon} \left[ \log \frac{dP_{x+\epsilon}}{dP_\mu}(X_1) \right] + \alpha \right) \right] \\
 &= e^{-n \{ \text{kl}(x+\epsilon, \mu) + \alpha \}} (1 - o_n(1)) .
 \end{aligned}$$



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## Asymptotic Optimality (Large Deviation Lower Bound)

$$\liminf_n \frac{1}{n} \log \mathbb{P}_\mu (\bar{X}_n \geq x) \geq -\text{kl}(x, \mu)$$

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 &\geq \mathbb{E}_{x+\epsilon} \left[ \mathbb{1}\{\bar{X}_n \geq x\} \mathbb{1} \left\{ \frac{1}{n} \sum_{i=1}^n \log \frac{dP_{x+\epsilon}}{dP_\mu} (X_i) \leq \mathbb{E}_{x+\epsilon} \left[ \log \frac{dP_{x+\epsilon}}{dP_\mu} (X_1) \right] + \alpha \right\} \right. \\
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 &\geq e^{-n \left\{ \mathbb{E}_{x+\epsilon} \left[ \log \frac{dP_{x+\epsilon}}{dP_\mu} (X_1) \right] + \alpha \right\}} \left[ 1 - \mathbb{P}_{x+\epsilon} (\bar{X}_n < x) \right. \\
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## Asymptotic Optimality (Large Deviation Lower Bound)

$$\frac{1}{n} \log \mathbb{P}_\mu (\bar{X}_n \geq x) \xrightarrow{n \rightarrow \infty} -\text{kl}(x, \mu)$$

# Lower Bound: the Entropy Way

Notation:  $\mathcal{KL}(Y, Z) = \text{KL}(\mathcal{L}(Y), \mathcal{L}(Z))$ .



For all  $\epsilon > 0$ , if  $X_1, \dots, X'_n \stackrel{iid}{\sim} \mathcal{B}(\mu)$  and  $X'_1, \dots, X'_n \stackrel{iid}{\sim} \mathcal{B}(x + \epsilon)$ :

$$\begin{aligned}
 n \text{kl}(x + \epsilon, \mu) &= \text{KL}(\mathcal{B}(x + \epsilon)^{\otimes n}, \mathcal{B}(\mu)^{\otimes n}) & \text{KL}(P \otimes P', Q \otimes Q') &= \text{KL}(P, Q) + \text{KL}(P', Q') \\
 &= \mathcal{KL}((X'_1, \dots, X'_n), (X_1, \dots, X_n)) \\
 &\geq \mathcal{KL}\left(\mathbb{1}\{\bar{X}'_n \geq x\}, \mathbb{1}\{\bar{X}_n \geq x\}\right) && \begin{matrix} \text{contraction of entropy} \\ = \text{data-processing inequality} \end{matrix} \\
 &= \text{kl}\left(\mathbb{P}_{x+\epsilon}(\bar{X}'_n \geq x), \mathbb{P}_\mu(\bar{X}_n \geq x)\right) \\
 &\geq \mathbb{P}_{x+\epsilon}(\bar{X}'_n \geq x) \log \frac{1}{\mathbb{P}_\mu(\bar{X}_n \geq x)} - \log(2) & \text{kl}(p, q) &\geq p \log \frac{1}{q} - \log 2
 \end{aligned}$$

## A non-asymptotic lower bound

$$\mathbb{P}_\mu(\bar{X}_n \geq x) \geq e^{-\frac{n \text{kl}(x+\epsilon, \mu) + \log(2)}{1 - e^{-2n\epsilon^2}}}$$

## Identifying the Best Arm with Fixed Confidence

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# The Stochastic Multi-Armed Bandit Model (MAB)

$K$  arms =  $K$  probability distributions ( $\nu_a$  has mean  $\mu_a$ , here:  $\nu_a = \mathcal{B}(\mu_a)$ )



At round  $t$ , an agent:

- chooses an arm  $A_t \in \mathcal{A} := \{1, \dots, K\}$
- observes a sample  $X_t \sim \mathcal{B}(\mu_{A_t})$

using a sequential sampling strategy ( $A_t$ ):

$$A_{t+1} = \phi_t(A_1, X_1, \dots, A_t, X_t),$$

aimed for a prescribed objective, e.g. related to learning

$$a^* = \operatorname{argmax}_a \mu_a \text{ and } \mu^* = \max_a \mu_a.$$

# Usual Objective: Regret Minimization

Samples = **rewards**,  $(A_t)$  is adjusted to

- maximize the (expected) sum of rewards,  $\mathbb{E} \left[ \sum_{t=1}^T X_t \right]$
- or equivalently minimize *regret*:

$$R_T = \mathbb{E} \left[ T\mu^* - \sum_{t=1}^T X_t \right]$$

⇒ exploration/exploitation tradeoff

**Motivation:** clinical trials [1933]



$\mathcal{B}(\mu_1)$

$\mathcal{B}(\mu_2)$

$\mathcal{B}(\mu_3)$

$\mathcal{B}(\mu_4)$

$\mathcal{B}(\mu_5)$

Goal: maximize the number of patients healed during the trial

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$\mathcal{B}(\mu_5)$

Goal: maximize the number of patients healed during the trial

Alternative goal: identify as quickly as possible the best treatment

# Our Objective: Best-arm Identification

Goal : identify the best arm,  $a^*$ , as fast and accurately as possible.

No incentive to draw arms with high means !

⇒ **optimal exploration**

The agent's strategy is made of:

- a sequential **sampling strategy** ( $A_t$ )
- a **stopping rule**  $\tau$  (stopping time)
- a **recommendation rule**  $\hat{a}_\tau$

Possible goals:

Fixed-budget setting	Fixed-confidence setting
given $\tau = T$ $\text{minimize } \mathbb{P}(\hat{a}_\tau \neq a^*)$	$\text{minimize } \mathbb{E}[\tau]$ under constraint $\mathbb{P}(\hat{a}_\tau \neq a^*) \leq \delta$

**Motivation:** clinical trials, market research, A/B testing...

# Wanted: Optimal Algorithms for PAC-BAI

$\mathcal{S}$  a class of bandit models  $\nu = (\nu_1, \dots, \nu_K)$ .

A strategy is  $\delta$ -PAC on  $\mathcal{S}$  is  $\forall \nu \in \mathcal{S}, \mathbb{P}_\nu(\hat{a}_\tau = a^*) \geq 1 - \delta$ .

Goal: for some classes  $\mathcal{S}$ , find

- a lower bound on  $\mathbb{E}_\nu[\tau]$  for any  $\delta$ -PAC strategy and any  $\nu \in \mathcal{S}$ ,
- a  $\delta$ -PAC strategy such that  $\mathbb{E}_\nu[\tau]$  matches this bound for all  $\nu \in \mathcal{S}$

(distribution-dependent bounds)

best achievable  $\mathbb{E}_\nu[\tau] =$  sample complexity of model  $\nu$

## Racing Strategy see [Kaufmann & Kalyanakrishnan '13]

$\mathcal{R} := \{1, \dots, K\}$  set of **remaining arms**.

$r := 0$  current round

**while**  $|\mathcal{R}| > 1$

- $r := r + 1$
- draw each  $a \in \mathcal{R}$ , compute  $\hat{\mu}_{a,r}$ , the empirical mean of the  $r$  samples observed sofar
- compute the **empirical best** and **empirical worst** arms:

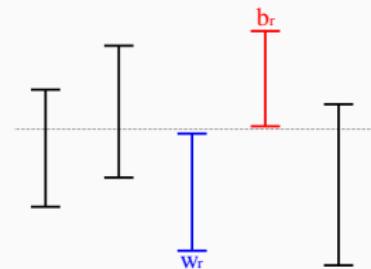
$$b_r = \operatorname{argmax}_{a \in \mathcal{R}} \hat{\mu}_{a,r} \quad w_r = \operatorname{argmin}_{a \in \mathcal{R}} \hat{\mu}_{a,r}$$

- Elimination step: if

$$\ell_{b_r}(r) > u_{w_r}(r),$$

then eliminate  $w_r$  :  $\mathcal{R} := \mathcal{R} \setminus \{w_r\}$

**end**



**Output**:  $\hat{a}$  the single element in  $\mathcal{R}$ .

## Lower Bound on the Sample Complexity

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# Key Inequality for Lower Bounds in Bandit Models

Let  $\mu = (\mu_1, \dots, \mu_K)$  and  $\lambda = (\lambda_1, \dots, \lambda_K)$  be two bandit models with KL-divergence  $d$  ( $= \text{kl}$  for Bernoulli models).

## Change of distribution lemma [G., Ménard, Stoltz '16]

For every stopping time  $\tau$  and every  $\mathcal{F}_\tau$ -measurable variable  $Z$  almost surely bounded in  $[0, 1]$ ,

$$\sum_{a=1}^K \mathbb{E}_\mu[N_a(\tau)] d(\mu_a, \lambda_a) \geq \text{kl}(\mathbb{E}_\mu[Z], \mathbb{E}_\lambda[Z])$$

- cf lower bound  $n d(x + \epsilon, \mu) \geq \text{kl}\left(\mathbb{P}_{x+\epsilon}(\bar{X}'_n \geq x), \mathbb{P}_\mu(\bar{X}_n \geq x)\right)$
- Useful if the behaviour of the algorithm (and of  $Z$ ) is supposed to be very different under  $\mu$  and under  $\lambda$ .
- Permits to prove the famous Lai&Robbins lower bound on regret clearly in a few lines.

# Key Inequality for PAC-BAI

Let  $\mu = (\mu_1, \dots, \mu_K)$  and  $\lambda = (\lambda_1, \dots, \lambda_K)$  be two bandit models.

## Change of distribution lemma [Kaufmann, Cappé, G.'15]

If  $a^*(\mu) \neq a^*(\lambda)$ , any  $\delta$ -PAC algorithm satisfies

$$\sum_{a=1}^K \mathbb{E}_\mu [N_a(\tau)] d(\mu_a, \lambda_a) \geq \text{kl}(\delta, 1 - \delta)$$

Using it for each arm separately, one obtains:



## Theorem

For any  $\delta$ -PAC algorithm,

$$\mathbb{E}_\mu [\tau] \geq \left( \frac{1}{d(\mu_1, \mu_2)} + \sum_{a=2}^K \frac{1}{d(\mu_a, \mu_1)} \right) \text{kl}(\delta, 1 - \delta)$$

**Remark:**  $\text{kl}(\delta, 1 - \delta) \underset{\delta \rightarrow 0}{\sim} \log\left(\frac{1}{\delta}\right)$  and  $\text{kl}(\delta, 1 - \delta) \geq \log\left(\frac{1}{2.4\delta}\right)$

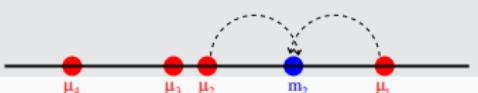
# Combining the Inequalities

$\mu = (\mu_1, \dots, \mu_K)$  and  $\lambda = (\lambda_1, \dots, \lambda_K)$  be two bandit models.

## Uniform $\delta$ -PAC Constraint [Kaufmann, Cappé, G. '15]

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Let  $\text{Alt}(\mu) = \{\lambda : a^*(\lambda) \neq a^*(\mu)\}$ .

$$\inf_{\lambda \in \text{Alt}(\mu)} \sum_{a=1}^K \mathbb{E}_\mu[N_a(\tau)] d(\mu_a, \lambda_a) \geq \text{kl}(\delta, 1 - \delta)$$

$$\mathbb{E}_\mu[\tau] \times \inf_{\lambda \in \text{Alt}(\mu)} \sum_{a=1}^K \frac{\mathbb{E}_\mu[N_a(\tau)]}{\mathbb{E}_\mu[\tau]} d(\mu_a, \lambda_a) \geq \text{kl}(\delta, 1 - \delta)$$

$$\mathbb{E}_\mu[\tau] \times \left( \sup_{w \in \Sigma_K} \inf_{\lambda \in \text{Alt}(\mu)} \sum_{a=1}^K w_a d(\mu_a, \lambda_a) \right) \geq \text{kl}(\delta, 1 - \delta)$$

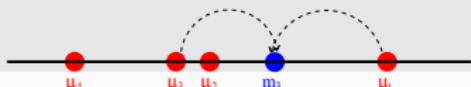
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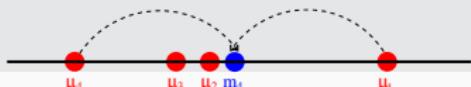
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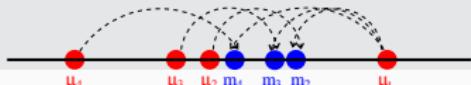
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$$\mathbb{E}_\mu[\tau] \times \left( \sup_{w \in \Sigma_K} \inf_{\lambda \in \text{Alt}(\mu)} \sum_{a=1}^K w_a d(\mu_a, \lambda_a) \right) \geq \text{kl}(\delta, 1 - \delta)$$

# Lower Bound: the Complexity of BAI

## Theorem

For any  $\delta$ -PAC algorithm,

$$\mathbb{E}_\mu[\tau] \geq T^*(\mu) \text{kl}(\delta, 1 - \delta),$$

where

$$T^*(\mu)^{-1} = \sup_{w \in \Sigma_K} \inf_{\lambda \in \text{Alt}(\mu)} \left( \sum_{a=1}^K w_a d(\mu_a, \lambda_a) \right).$$

- Cf. [Graves and Lai 1997, Vaidhyani and Sundaresan, 2015]
  - A kind of **game** : you choose the proportions of draws  $(w_a)_a$ , the opponent chooses the alternative
- the **optimal proportions of arm draws** are

$$w^*(\mu) = \operatorname{argmax}_{w \in \Sigma_K} \inf_{\lambda \in \text{Alt}(\mu)} \left( \sum_{a=1}^K w_a d(\mu_a, \lambda_a) \right)$$

## PAC-BAI as a Game

Given a parameter  $\mu = (\mu_1, \dots, \mu_K)$  such that  $\mu_1 > \mu_2 \geq \dots \geq \mu_K$ :

- the statistician chooses proportions of arm draws  $w = (w_a)_a$
- the opponent chooses an alternative model  $\lambda$
- the payoff is the minimal number  $T = T(w, \lambda)$  of draws necessary to ensure that he does not violate the  $\delta$ -PAC constraint

$$\sum_{a=1}^K T w_a d(\mu_a, \lambda_a) \geq \text{kl}(\delta, 1 - \delta)$$

- $T^*(\mu)$  = value of the game
- $w^*$  = optimal action for the statistician

## PAC-BAI as a Game

Given a parameter  $\mu = (\mu_1, \dots, \mu_K)$  such that  $\mu_1 > \mu_2 \geq \dots \geq \mu_K$ :

- the statistician chooses proportions of arm draws  $\mathbf{w} = (w_a)_a$
- the opponent chooses an arm  $a \in \{2, \dots, K\}$  and  
$$\lambda_a = \arg \min_{\lambda} w_1 d(\mu_1, \lambda) + w_a d(\mu_a, \lambda)$$
- the payoff is the minimal number  $T = T(\mathbf{w}, a)$  of draws necessary to ensure that

$$\begin{aligned}\mathbb{P}_{\mu}(\hat{\mu}_{1, T w_1} \leq \hat{\mu}_{a, T w_a}) &\approx \mathbb{P}_{\mu}(\hat{\mu}_{1, T w_1} < \lambda_a \text{ and } \hat{\mu}_{a, T w_a} \geq \lambda_a) \\ &\leq \exp \left( -T(w_1 \text{kl}(\mu_1, \lambda_a)) + w_a \text{kl}(\mu_a, \lambda_a) \right) \leq \delta\end{aligned}$$

that is  $T(\mathbf{w}, a) = \frac{\log(1/\delta)}{w_1 \text{kl}(\mu_1, \lambda_a - \epsilon) + w_a \text{kl}(\mu_a, \lambda)}$

- $T^*(\mu)$  = value of the game  
 $\mathbf{w}^*$  = optimal action for the statistician

# Computing the optimal proportions

## Computing $w^*$

$$w^* \in \operatorname{argmax}_{w \in \Sigma_K} \underbrace{\inf_{\lambda \in \text{Alt}(\mu)} \left( \sum_{a=1}^K w_a d(\mu_a, \lambda_a) \right)}_{(*)}$$

An explicit calculation yields

$$\begin{aligned} (*) &= \min_{a \neq 1} \left[ w_1 d \left( \mu_1, \frac{w_1 \mu_1 + w_a \mu_a}{w_1 + w_a} \right) + w_a d \left( \mu_a, \frac{w_1 \mu_1 + w_a \mu_a}{w_1 + w_a} \right) \right] \\ &= w_1 \min_{a \neq 1} g_a \left( \frac{w_a}{w_1} \right) \quad (w_1 \neq 0) \end{aligned}$$

where  $g_a(x) = d \left( \mu_1, \frac{\mu_1 + x \mu_a}{1+x} \right) + x d \left( \mu_a, \frac{\mu_1 + x \mu_a}{1+x} \right)$  (Jensen-Shannon divergence)

$g_a$  is a one-to-one mapping from  $[0, +\infty[$  onto  $[0, d(\mu_1, \mu_a)[$ .

# Computing the optimal proportions

## Computing $w^*$

$$w^* \in \operatorname{argmax}_{w \in \Sigma_K} \underbrace{\inf_{\lambda \in \text{Alt}(\mu)} \left( \sum_{a=1}^K w_a d(\mu_a, \lambda_a) \right)}_{(*)}$$

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$g_a$  is a one-to-one mapping from  $[0, +\infty[$  onto  $[0, d(\mu_1, \mu_a)[$ .

$$x_1^* = 1 \quad x_2^* = w_2^*/w_1^* \quad \dots \quad x_K^* = w_K^*/w_1^*$$

## Computing the optimal proportions

Letting  $x_a^* = w_a^*/w_1^*$  for all  $a \geq 2$ ,

$$x_2^*, \dots, x_K^* \in \operatorname{argmax}_{x_2, \dots, x_K \geq 0} \frac{\min_{a \neq 1} g_a(x_a)}{1 + x_2 + x_K}.$$

It is easy to check that there exists  $y^* \in [0, d(\mu_1, \mu_2)[$  such that

$$\forall a \in \{2, \dots, K\}, g_a(x_a^*) = y^*.$$

Letting  $x_a(y) = g_a^{-1}(y)$ , one has  $x_a^* = x_a(y^*)$  where

$$y^* \in \operatorname{argmax}_{y \in [0, d(\mu_1, \mu_2)[} \frac{y}{1 + x_2(y) + x_K(y)}.$$

# Computing the optimal proportions

## Theorem

For every  $a \in \{1, \dots, K\}$ ,

$$w_a^*(\mu) = \frac{x_a(y^*)}{\sum_{a=1}^K x_a(y^*)} ,$$

where  $y^*$  is the unique solution of the equation  $F_\mu(y) = 1$ , where

$$F_\mu : y \mapsto \sum_{a=2}^K \frac{d\left(\mu_1, \frac{\mu_1 + x_a(y)\mu_a}{1+x_a(y)}\right)}{d\left(\mu_a, \frac{\mu_1 + x_a(y)\mu_a}{1+x_a(y)}\right)}$$

is a continuous, increasing function on  $[0, d(\mu_1, \mu_2)]$  such that  $F_\mu(0) = 0$  and  $F_\mu(y) \rightarrow \infty$  when  $y \rightarrow d(\mu_1, \mu_2)$ .

→ an efficient way to compute the vector of proportions  $w^*(\mu)$

## Properties of $T^*(\mu)$ and $w^*(\mu)$

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1. For all  $\mu \in \mathcal{S}$ , for all  $a$ ,  $w_a^*(\mu) > 0$
2.  $w^*$  is continuous in every  $\mu \in \mathcal{S}$
3. If  $\mu_1 > \mu_2 \geq \dots \geq \mu_K$ , one has  $w_2^*(\mu) \geq \dots \geq w_K^*(\mu)$   
(one may have  $w_1^*(\mu) < w_2^*(\mu)$ )
4. Case of two arms [Kaufmann, Cappé, G. '14]:

$$\mathbb{E}_\mu[\tau_\delta] \geq \frac{\text{kl}(\delta, 1 - \delta)}{d_*(\mu_1, \mu_2)}.$$

where  $d_*$  is the ‘reversed’ Chernoff information

$$d_*(\mu_1, \mu_2) := d(\mu_1, \mu_*) = d(\mu_2, \mu_*).$$

5. Gaussian arms : algebraic equation but no simple formula when  $K \geq 3$ , only:

$$\sum_{a=1}^K \frac{2\sigma^2}{\Delta_a^2} \leq T^*(\mu) \leq 2 \sum_{a=1}^K \frac{2\sigma^2}{\Delta_a^2}.$$

## The Track-and-Stop Strategy

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## Sampling rule: Tracking the optimal proportions

$\hat{\mu}(t) = (\hat{\mu}_1(t), \dots, \hat{\mu}_K(t))$ : vector of empirical means

Introducing

$$U_t = \{a : N_a(t) < \sqrt{t}\},$$

the arm sampled at round  $t + 1$  is

$$A_{t+1} \in \begin{cases} \underset{a \in U_t}{\operatorname{argmin}} N_a(t) \text{ if } U_t \neq \emptyset & (\text{forced exploration}) \\ \underset{1 \leq a \leq K}{\operatorname{argmax}} [t w_a^*(\hat{\mu}(t)) - N_a(t)] & (\text{tracking}) \end{cases}$$

### Lemma

Under the Tracking sampling rule,

$$\mathbb{P}_{\mu} \left( \lim_{t \rightarrow \infty} \frac{N_a(t)}{t} = w_a^*(\mu) \right) = 1.$$

# Sequential Generalized Likelihood Test

High values of the Generalized Likelihood Ratio

$$Z_{a,b}(t) := \log \frac{\max_{\{\lambda: \lambda_a \geq \lambda_b\}} dP_\lambda(X_1, \dots, X_t)}{\max_{\{\lambda: \lambda_a \leq \lambda_b\}} dP_\lambda(X_1, \dots, X_t)}$$

reject the hypothesis that  $(\mu_a < \mu_b)$ .

We stop when one arm is accessed to be significantly larger than all other arms, according to a GLR Test:

$$\begin{aligned}\tau_\delta &= \inf \{t \in \mathbb{N} : \exists a \in \{1, \dots, K\}, \forall b \neq a, Z_{a,b}(t) > \beta(t, \delta)\} \\ &= \inf \left\{ t \in \mathbb{N} : \max_{a \in \{1, \dots, K\}} \min_{b \neq a} Z_{a,b}(t) > \beta(t, \delta) \right\}\end{aligned}$$

Chernoff stopping rule [Chernoff '59]

## Stopping Rule: Alternative Formulations

One has  $Z_{a,b}(t) = -Z_{b,a}(t)$  and, if  $\hat{\mu}_a(t) \geq \hat{\mu}_b(t)$ ,

$$Z_{a,b}(t) = N_a(t) d(\hat{\mu}_a(t), \hat{\mu}_{a,b}(t)) + N_b(t) d(\hat{\mu}_b(t), \hat{\mu}_{a,b}(t)),$$

where  $\hat{\mu}_{a,b}(t) := \frac{N_a(t)}{N_a(t) + N_b(t)} \hat{\mu}_a(t) + \frac{N_b(t)}{N_a(t) + N_b(t)} \hat{\mu}_b(t)$ .

### A link with the lower bound

$$\begin{aligned} \max_a \min_{b \neq a} Z_{a,b}(t) &= t \times \inf_{\lambda \in \text{Alt}(\hat{\mu}(t))} \sum_{a=1}^K \frac{N_a(t)}{t} d(\hat{\mu}_a(t), \lambda_a) \\ &\simeq \frac{t}{T^*(\mu)} \end{aligned}$$

under a “good” sampling strategy (for  $t$  large)

## Stopping Rule: Alternative Formulations

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where  $\hat{\mu}_{a,b}(t) := \frac{N_a(t)}{N_a(t) + N_b(t)} \hat{\mu}_a(t) + \frac{N_b(t)}{N_a(t) + N_b(t)} \hat{\mu}_b(t)$ .

### A Minimum Description Length interpretation

If  $H(\mu) = \mathbb{E}_{X \sim \nu^\mu}[-\log p_\mu(X)]$  is the Shannon entropy,

$$\begin{aligned} Z_{a,b}(t) &= \underbrace{(N_a(t) + N_b(t))H(\hat{\mu}_{a,b}(t))}_{\text{average \#bits to encode the samples of a and b together}} \\ &\quad - \underbrace{[N_a(t)H(\hat{\mu}_a(t)) + N_b(t)H(\hat{\mu}_b(t))]}_{\text{average \#bits to encode the sample of a and b separately}}, \end{aligned}$$

# Calibration

The Chernoff rule is  $\delta$ -PAC for  $\beta(t, \delta) = \log\left(\frac{2(K-1)t}{\delta}\right)$

## Lemma

If  $\mu_a < \mu_b$ , whatever the sampling rule,

$$\mathbb{P}_\mu \left( \exists t \in \mathbb{N} : Z_{a,b}(t) > \log\left(\frac{2t}{\delta}\right) \right) \leq \delta$$

i.e.,  $\mathbb{P}(T_{a,b} < \infty) \leq \delta$ , for  $T_{a,b} = \inf\{t \in \mathbb{N} : Z_{a,b}(t) > \log(2t/\delta)\}$

$$\begin{aligned} \{T_{a,b} = t\} &\subseteq \left( \frac{\max_{\mu'_a \geq \mu'_b} p_{\mu'_a}(X_t^a) p_{\mu'_b}(X_t^b)}{\max_{\mu'_a \leq \mu'_b} p_{\mu'_a}(X_t^a) p_{\mu'_b}(X_t^b)} \geq \frac{2t}{\delta} \right) \\ \mathbb{P}_\mu(T_{a,b} < \infty) &= \sum_{t=1}^{\infty} \mathbb{E}_\mu [\mathbb{1}\{T_{a,b} = t\}] \\ &\leq \sum_{t=1}^{\infty} \frac{\delta}{2t} \mathbb{E}_\mu \left[ \mathbb{1}\{T_{a,b} = t\} \frac{\max_{\mu'_a \geq \mu'_b} p_{\mu'_a}(X_t^a) p_{\mu'_b}(X_t^b)}{\max_{\mu'_a \leq \mu'_b} p_{\mu'_a}(X_t^a) p_{\mu'_b}(X_t^b)} \right] \end{aligned}$$

## Stopping rule: $\delta$ -PAC property

$$\begin{aligned}\mathbb{P}_\mu(T_{a,b} < \infty) &\leq \sum_{t=1}^{\infty} \frac{\delta}{2t} \mathbb{E}_\mu \left[ \mathbf{1}_{\{T_{a,b} = t\}} \frac{\max_{\mu'_a \geq \mu'_b} p_{\mu'_a}(X_t^a) p_{\mu'_b}(X_t^b)}{p_{\mu_a}(X_t^a) p_{\mu_b}(X_t^b)} \right] \\ &= \sum_{t=1}^{\infty} \frac{\delta}{2t} \underbrace{\sum_{x_t \in \{0,1\}^t} \mathbf{1}_{\{T_{a,b} = t\}} \underbrace{\max_{\mu'_a \geq \mu'_b} p_{\mu'_a}(x_t^a) p_{\mu'_b}(x_t^b)}_{\text{not a probability density...}} \prod_{i \in \{1, \dots, K\} \setminus \{a, b\}} p_{\mu_i}(x_t^i)}_{\text{not a probability density...}}\end{aligned}$$

**Lemma** [Willems et al. 95]

The Krichevsky-Trofimov distribution

$$kt(x) = \int_0^1 \frac{1}{\pi \sqrt{u(1-u)}} p_u(x) du$$

is a probability law on  $\{0, 1\}^n$  that satisfies

$$\sup_{x \in \{0,1\}^n} \frac{\sup_{u \in [0,1]} p_u(x)}{kt(x)} \leq 2\sqrt{n}$$

## Stopping rule: $\delta$ -PAC property

$$\begin{aligned}
\mathbb{P}_\mu(T_{a,b} < \infty) &\leq \sum_{t=1}^{\infty} \frac{\delta}{2t} \mathbb{E}_\mu \left[ \mathbb{1}\{T_{a,b} = t\} \frac{\max_{\mu'_a \geq \mu'_b} p_{\mu'_a}(X_t^a) p_{\mu'_b}(X_t^b)}{p_{\mu_a}(X_t^a) p_{\mu_b}(X_t^b)} \right] \\
&= \sum_{t=1}^{\infty} \frac{\delta}{2t} \sum_{x_t \in \{0,1\}^t} \mathbb{1}\{T_{a,b} = t\} (x_t) \max_{\mu'_a \geq \mu'_b} p_{\mu'_a}(x_t^a) p_{\mu'_b}(x_t^b) \prod_{i \in \{1, \dots, K\} \setminus \{a, b\}} p_{\mu_i}(x_t^i) \\
&\leq \sum_{t=1}^{\infty} \frac{\delta}{2t} \sum_{x_t \in \{0,1\}^t} \mathbb{1}\{T_{a,b} = t\} (x_t) \underbrace{4\sqrt{n_t^a n_t^b} \text{kt}(x_t^a) \text{kt}(x_t^b)}_{I(x_t)} \prod_{i \in \{1, \dots, K\} \setminus \{a, b\}} p_{\mu_i}(x_t^i) \\
&\leq \sum_{t=1}^{\infty} \delta \sum_{x_t \in \{0,1\}^t} \mathbb{1}\{T_{a,b} = t\} (x_t) I(x_t) \\
&= \delta \sum_{t=1}^{\infty} \tilde{\mathbb{E}}[\mathbb{1}\{T_{a,b} = t\}] = \delta \tilde{\mathbb{P}}(T_{a,b} < \infty) \leq \delta.
\end{aligned}$$

# Asymptotic Optimality of the T&S strategy

## Theorem

The Track-and-Stop strategy, that uses

- the Tracking sampling rule
- the Chernoff stopping rule with  $\beta(t, \delta) = \log\left(\frac{2(K-1)t}{\delta}\right)$
- and recommends  $\hat{a}_\tau = \operatorname{argmax}_{a=1\dots K} \hat{\mu}_a(\tau)$

is  $\delta$ -PAC for every  $\delta \in (0, 1)$  and satisfies

$$\limsup_{\delta \rightarrow 0} \frac{\mathbb{E}_\mu[\tau_\delta]}{\log(1/\delta)} = T^*(\mu).$$

## Sketch of proof (almost-sure convergence only)

- forced exploration  $\implies N_a(t) \rightarrow \infty$  a.s. for all  $a \in \{1, \dots, K\}$
- $\rightarrow \mu(t) \rightarrow \mu$  a.s.
- $\rightarrow w^*(\hat{\mu}(t)) \rightarrow w^*$  a.s.
- $\rightarrow$  tracking rule:  $\frac{N_a(t)}{t} \xrightarrow[t \rightarrow \infty]{} w_a^*$  a.s.
- but the mapping  $F : (\mu', w) \mapsto \inf_{\lambda \in \text{Alt}(\mu')} \sum_{a=1}^K w_a d(\mu'_a, \lambda_a)$  is continuous at  $(\mu, w^*(\mu))$ :
- $\rightarrow$  as  $\max_a \min_{b \neq a} Z_{a,b}(t) = t F\left(\hat{\mu}(t), (N_a(t)/t)_{a=1}^K\right)$ , for every  $\epsilon > 0$  there exists  $t_0$  such that

$$t \geq t_0 \implies \max_a \min_{b \neq a} Z_{a,b}(t) \geq (1 + \epsilon)^{-1} T^*(\mu)^{-1} t$$

$$\implies \text{Thus } \tau \leq t_0 \wedge \inf \left\{ t \in \mathbb{N} : (1 + \epsilon)^{-1} T^*(\mu)^{-1} t \geq \log(2(K-1)t/\delta) \right\}$$

and  $\limsup_{\delta \rightarrow 0} \frac{\tau}{\log(1/\delta)} \leq (1 + \epsilon) T^*(\mu).$

## Numerical Experiments

- $\mu_1 = [0.5 \ 0.45 \ 0.43 \ 0.4] \rightarrow w^*(\mu_1) = [0.42 \ 0.39 \ 0.14 \ 0.06]$
- $\mu_2 = [0.3 \ 0.21 \ 0.2 \ 0.19 \ 0.18] \rightarrow w^*(\mu_2) = [0.34 \ 0.25 \ 0.18 \ 0.13 \ 0.10]$

In practice, set the threshold to  $\beta(t, \delta) = \log\left(\frac{\log(t)+1}{\delta}\right)$  ( $\delta$ -PAC OK)

	Track-and-Stop	Chernoff-Racing	KL-LUCB	KL-Racing
$\mu_1$	4052	4516	8437	9590
$\mu_2$	1406	3078	2716	3334

**Table 1:** Expected number of draws  $\mathbb{E}_\mu[\tau_\delta]$  for  $\delta = 0.1$ , averaged over  $N = 3000$  experiments.

- Empirically good even for large values of the risk  $\delta$
- Racing is sub-optimal in general, because it plays  $w_1 = w_2$

For best arm identification, we showed that

$$\inf_{\text{PAC algorithm}} \limsup_{\delta \rightarrow 0} \frac{\mathbb{E}_{\mu}[\tau_{\delta}]}{\log(1/\delta)} = \sup_{w \in \Sigma_K} \inf_{\lambda \in \text{Alt}(\mu)} \left( \sum_{a=1}^K w_a d(\mu_a, \lambda_a) \right)$$

and provided an efficient strategy matching this bound.

## Future work:

- (easy) find an  $\epsilon$ -optimal arm
- give a simple algorithm with a finite-time analysis
- extend to structured and continuous settings

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