Linear differential and recurrence equations viewed as data-structures

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Computer Algebra

Effective mathematics (what can we compute?) Their complexity (how fast?)



Several million users. 30 years of algorithmic progress.

Thesis in this presentation: linear differential and recurrence equations are a good data-structure.

Topics

Fast computation with high precision; automatic proofs of identities; «computation» of expansions, of (multiple) integrals, of (multiple) sums.

The objects of study

Def. A power series is called differentially finite (D-finite) when it is the solution of a linear differential equation with polynomial coefficients.

Exs: sin, cos, exp, log, arcsin, arccos, arctan, arcsinh, hypergeometric series, Bessel functions,...

Def. A sequence is polynomially recursive (P-recursive) when it is the solution of a linear recurrence with polynomial coefficients.

Prop.
$$f = \sum_{n=0}^{\infty} f_n z^n$$
 D-finite $\iff f_n$ P-recursive.

Example

Coefficient of X^{20000} in $P(X)=(1+X)^{20000}(1+X+X^2)^{10000}$?

Linear differential equation of order 1

- → linear recurrence of order 2
- → unroll (cleverly).
- > P := $(1+x)^{(2*N)*(1+x+x^2)^N}$:
- > deq := gfun:-holexprtodiffeq(P,y(x)):
- > rec := gfun:-diffeqtorec(%,y(x),u(k)):
- > p := gfun:-rectoproc(subs(N=10000,rec),u(k)):
- > p(20000);

23982[...10590 digits...]33952

Total time: 0.5 sec

I. Fast computation at large precision

From large integers to precise numerical values

Fast multiplication

Fast Fourier Transform (Gauss, Cooley-Tuckey, Schönhage-Strassen). Two integers of n digits can be multiplied with O(n log(n) loglog(n)) bit operations.

Direct consequence (by Newton iteration):

inverses, square-roots,...: same cost.

Binary Splitting for linear recurrences (70's and 80's)

• n! by divide-and-conquer:

$$n! := \underbrace{n \times \cdots \times \lfloor n/2 \rfloor}_{\text{size } O(n \log n)} \times \underbrace{(\lfloor n/2 \rfloor + 1) \times \cdots \times 1}_{\text{size } O(n \log n)}$$

Cost: O(n log³n loglog n) using FFT

- linear recurrences of order 1 reduce to $p!(n) := (p(n) \times \cdots \times p(\lfloor n/2 \rfloor)) \times (p(\lfloor n/2 \rfloor + 1) \times \cdots \times p(1))$
- arbitrary order: same idea, same cost (matrix factorial):

ex:
$$e_n := \sum_{k=0}^n \frac{1}{k!}$$
 satisfies a 2nd order rec, computed via
 $\begin{pmatrix} e_n \\ e_{n-1} \end{pmatrix} = \frac{1}{n} \underbrace{\begin{pmatrix} n+1 & -1 \\ n & 0 \end{pmatrix}}_{A(n)} \begin{pmatrix} e_{n-1} \\ e_{n-2} \end{pmatrix} = \frac{1}{n!} A!(n) \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$

Numerical evaluation of solutions of LDEs



f solution of a LDE with coeffs in $\mathbf{Q}(x)$ (our data-structure!)

- 1. linear recurrence in N for the first sum (easy);
- 2. tight bounds on the tail (technical);
- 3. no numerical roundoff errors.

The technique used for fast evaluation of constants like

$$\frac{1}{\pi} = \frac{12}{\mathsf{C}^{3/2}} \sum_{\mathsf{n}=\mathsf{0}}^{\infty} \frac{(-1)^{\mathsf{n}}(\mathsf{6n})!(\mathsf{A}+\mathsf{n}\mathsf{B})}{(\mathsf{3n})!\mathsf{n}!^{\mathsf{3}}\mathsf{C}^{\mathsf{3n}}}$$

with A=13591409, B=545140134, C=640320.





Again: computation on integers. No roundoff errors.

II. Proofs of Identities



k+1 vectors in dimension $k \rightarrow$ an identity

LDE ←→ the function and all its derivatives are confined in a finite dimensional vector space

⇒ the sum and product of solutions of LDEs satisfy LDEs⇒ same property for P-recursive sequences

Proof technique

> series(sin(x)^2+cos(x)^2-1,x,4);

f satisfies a LDE f, f', f'', \dots live in a finite-dim. vector space

 $O(x^4)$

Why is this a proof?

- 1. sin and cos satisfy a 2nd order LDE: y''+y=0;
- 2. their squares and their sum satisfy a 3rd order LDE;
- 3. the constant -1 satisfies y'=0;
- 4. thus sin²+cos²-1 satisfies a LDE of order at most 4;
- 5. Cauchy's theorem concludes.

Proofs of non-linear identities by linear algebra!

Example: Mehler's identity for Hermite polynomials

$$\sum_{n=0}^{\infty} H_n(x) H_n(y) \frac{u^n}{n!} = \frac{\exp\left(\frac{4u(xy - u(x^2 + y^2))}{1 - 4u^2}\right)}{\sqrt{1 - 4u^2}}$$

- Definition of Hermite polynomials: recurrence of order 2;
- 2. Product by linear algebra: $H_{n+k}(x)H_{n+k}(y)/(n+k)!$, $k \in \mathbb{N}$ generated over $\mathbb{Q}(x,n)$ by

 $\frac{H_n(x)H_n(y)}{n!}, \frac{H_{n+1}(x)H_n(y)}{n!}, \frac{H_n(x)H_{n+1}(y)}{n!}, \frac{H_n(x)H_{n+1}(y)}{n!}$

→ recurrence of order at most 4;

3. Translate into differential equation.



Dynamic Dictionary of Mathematical Functions

- User need
- Recent algorithmic progress
- Maths on the web

http://ddmf.msr-inria.inria.fr/





Demonstration

Dynamic Dictionary of Mathematical Functions

Home

Dynamic Dictionary of Mathematical Functions

Welcome to this interactive site on <u>Mathematical Functions</u>, with properties, truncated expansions, numerical evaluations, plots, and more. The functions currently presented

are elementary functions and special functions of a single variable. More functions special functions with parameters, orthogonal polynomials, sequences - will be added with the project advances.

This is release 1.9.1 of DDMF Select a special function from the list

What's new? The main changes in this release 1.9.1, dated May 2013, are:

· Proofs related to Taylor polynomial approximations.

Release history.

More on the project:

- <u>Help</u> on selecting and configuring the mathematical rendering
- DDMF developers list
- Motivation of the project
- Article on the project at ICMS'2010
- Source code used to generate these pages
- List of related projects



Mathematical Functions

- The Airy function of the first kind Ai(x)
- The Airy function of the second kind Bi(x)
- The Anger function $J_n(x)$
- The inverse cosine $\arccos(x)$
- The inverse hyperbolic cosine $\operatorname{arccosh}(x)$
- The inverse cotangent $\operatorname{arccot}(x)$
- The inverse hyperbolic cotangent $\operatorname{arccoth}(x)$
- The inverse cosecant $\operatorname{arccsc}(x)$
- The inverse hyperbolic cosecant $\operatorname{arccsch}(x)$
- The inverse secant $\operatorname{arcsec}(x)$
- The inverse hyperbolic secant $\operatorname{arcsech}(x)$
- The inverse sine $\arcsin(x)$
- The inverse hyperbolic sine $\operatorname{arcsinh}(x)$
- The inverse tangent $\arctan(x)$
- The inverse hyperbolic tangent $\operatorname{arctanh}(x)$
- The modified Bessel function of the first kind $I_{\nu}(x)$
- The Bessel function of the first kind $J_{\nu}(x)$
- The modified Bessel function of the second kind $K_{\nu}(x)$
- The Bessel function of the second kind $Y_{\nu}(x)$
- The Chebyshev function of the first kind $T_n(x)$
- The Chebyshev function of the second kind $U_n(x)$
- The hyperbolic cosine integral Chi(x)
- The cosine integral $\operatorname{Ci}(x)$
- The cosine $\cos(x)$
- The hyperbolic cosine $\cosh(x)$
- The <u>Coulomb function</u> $F_n(l,x)$
- The Whittaker's parabolic function $D_a(x)$ 16
- The parabolic cylinder function U(a, x)
- The parabolic cylinder function V(a, x)

Guess & prove continued fractions

1. Differential equation produces first terms (easy):



3. Prove that the CF with these a_n satisfies the differential equation.

No human intervention needed.

Automatic Proof of the guessed CF

- Aim: RHS satisfies $(x^2+1)y'-1=0;$ Convergents P_n/Q_n where P_n and Q_n satisfy the $1 + \frac{\frac{n^2}{4n^2-1}x^2}{1+\cdots}$ LRE $u_n = u_{n-1} + a_n u_{n-2}$ (and $Q_n(0) \neq 0$);
- Define $H_n:=(Q_n)^2((x^2+1)(P_n/Q_n)'-1);$
- H_n is a polynomial in P_n,Q_n and their derivatives;
- therefore, it satisfies a LRE that can be computed;
- from it, $H_n = O(x^n)$ visible
- from there, $(P_n/Q_n)'-1/(1+x^2)=O(x^n)$ too;
- conclude $P_n/Q_n \rightarrow$ arctan by integrating.

III. Ore Polynomials

From equations to operators

 $\begin{array}{l} D_x \leftrightarrow d/dx \\ x \leftrightarrow \mbox{ mult by } x \\ \mbox{ product} \leftrightarrow \mbox{ composition} \\ D_x x = x D_x + 1 \end{array}$

 $\begin{array}{l} S_n \leftrightarrow (n \mapsto n + 1) \\ n \leftrightarrow mult \ by \ n \\ product \leftrightarrow composition \\ S_n n = (n + 1) S_n \end{array}$

Taylor morphism: $D_x \mapsto (n+1)S_n$; $x \mapsto S_n^{-1}$ produces linear recurrence from LDE

Framework: Ore polynomials

$$\begin{split} (fg)' &= f'g + fg', \quad S_n(f_ng_n) = f_{n+1}S_n(g_n), \quad \Delta_n(f_ng_n) = f_{n+1}\Delta_n(g_n) + \Delta_n(f_n)g_n, \\ & \text{ and many more (e.g., q-analogues)} \\ & \text{ are captured by } \mathbb{A}\langle\partial\rangle \text{ (A integral domain) with commutation} \\ & \partial a = \sigma(a)\partial + \delta(a) \end{split}$$

σ a ring morphism, δ a σ-derivation ($\delta(ab) = \sigma(a)\delta(b) + \delta(a)b$).

Main property: A,B in $\mathbb{A}\langle\partial\rangle$, then deg AB=deg A+deg B.

Consequence 1: (non-commutative) Euclidean division **Consequence** 2: (non-commutative) Euclidean algorithm

GCRD & LCLM

greatest common right divisor & least common left multiple

GCRD(A,B): maximal operator whose solutions are common to A and B. **LCLM**(A,B): minimal operator having the solutions of A and B for solutions.

Example: closure by sum.

Computation: Euclidean algorithm or linear algebra.

Reduction of order

Input: a (large) linear recurrence equation + *ini*. *cond* **Output**: a factor annihilating *this* solution

- Step 1: use the recurrence and its initial conditions to compute a large number of terms;
- Step 2: guess a linear recurrence equation annihilating this sequence (linear algebra);
- Step 3: take the gcrd of this operator and the initial one;
- Step 3: prove that this factor annihilates the solution by checking sufficiently many initial conditions.

Example from a continued fraction expansion

1

$$\mathsf{P}_k = \mathsf{a}_k \mathsf{x}^2 \mathsf{P}_{k-2} + \mathsf{P}_{k-1}, \quad \mathsf{a}_k = \begin{cases} \frac{2\mathsf{k}}{(2\mathsf{k}+1)(2\mathsf{k}+3)}, \\ \frac{-2(\mathsf{k}+2)}{(2\mathsf{k}+1)(2\mathsf{k}+3)}, \end{cases}$$

k even, k odd.

Aim: a recurrence for all k.

- Step 1: use both recurrences to find a relation between P_k, P_{k+2}, P_{k+4} for even k and one for odd k;
- Step 2: compute their LCLM (order 8);
- Step 3: use the initial conditions to reduce (order 4).

Chebyshev expansions



Ore fractions

Generalize commutative case:

 $R=Q^{-1}P$ with P & Q operators.

 $B^{-1}A=D^{-1}C$ when bA=dC with bB=dD=LCLM(B,D).

Algorithms for sum and product:

 $B^{-1}A+D^{-1}C=LCLM(B,D)^{-1}(bA+dC)$, with bB=dD=LCLM(B,D)

 $B^{-1}AD^{-1}C = (aB)^{-1}dC$, with aA = dD = LCLM(A,D).

Application: Chebyshev expansions

Extend Taylor morphism to Chebyshev expansions

Taylor $2xT_n(x)=T_{n+1}(x)+T_{n-1}(x)$ $x^{n+1}=x \cdot x^n \leftrightarrow x \mapsto X := S^{-1}$ $\leftrightarrow x \mapsto X := (S+S^{-1})/2$ $(x^n)'=nx^{n-1} \leftrightarrow d/dx \mapsto D := (n+1)S$ $2(1-x^2)T_n'(x)=-nT_{n+1}(x)+nT_{n-1}(x)$ $\leftrightarrow d/dx \mapsto D := (1-X^2)^{-1}n(S-S^{-1})/2.$

Prop. If y is a solution of L(x,d/dx), then its Chebyshev coefficients annihilate the numerator of L(X,D).

IV. Systems of equations

Example: Contiguity of Hypergeometric Series

 $(a+1)(z-1)S_a^2F + ((b-a-1)z+2-c+2a)S_aF + (c-a-1)F = 0_{29}$

Ore Algebras

 $\bigcirc := \mathbb{K}(x_1, \ldots, x_r) \langle \partial_1, \ldots, \partial_r \rangle := \mathbb{K}(x_1, \ldots, x_r) \langle \partial_1 \rangle \cdots \langle \partial_r \rangle,$

with commuting ∂_i 's and for $i \neq j$, $\delta_i(\partial_j) = 0$ and $\sigma_i(\partial_j) = \partial_j$.

Def. LM (leading monomial) on next slide.

Main property: A,B in \mathbb{O} , then LM(AB)=LM(A)LM(B).

Consequence: (non-commutative) Gröbner bases

Gröbner bases as a data-structure to encode special functions

Gröbner Bases

1. Monomial ordering: order on \mathbb{N}^k , compatible with +, 0 minimal.

2. Leading monomial of a polynomial: the largest one.

- 3. Gröbner basis of a (left) ideal *I*: corners of stairs.
- 4. Quotient mod *I*:

basis below the stairs (Vect{ $\partial^{\alpha} f$ }).

5. Reduction of *P*:

Rewrite *P* mod *I* on this basis.

- 6. Dimension:
 - « size » of the quotient.
- 7. D-finiteness: dimension 0.

An access to (finite-dimensional) vector spaces.





$$\begin{split} \text{Proposition.} \\ \dim & \operatorname{ann}(f+g) \leq \max(\dim & \operatorname{ann} f, \dim & \operatorname{ann} g), \\ & \dim & \operatorname{ann}(fg) \leq \dim & \operatorname{ann} f + \dim & \operatorname{ann} g, \\ & \dim & \operatorname{ann}(\partial f) \leq \dim & \operatorname{ann} f. \end{split}$$

Algorithms by linear algebra

simple definitions \rightarrow data-structures for more complicated functions₃₂

V. Sums and Integrals

Examples

$$\sum_{k=0}^{n} {\binom{n}{k}}^{2} {\binom{n+k}{k}}^{2} = \sum_{k=0}^{n} {\binom{n}{k}} {\binom{n+k}{k}} \sum_{j=0}^{k} {\binom{k}{j}}^{3}$$

$$\sum_{j,k} (-1)^{j+k} {\binom{j+k}{k+l}} {\binom{r}{j}} {\binom{n}{k}} {\binom{s+n-j-k}{m-j}} = (-1)^{l} {\binom{n+r}{n+l}} {\binom{s-r}{m-n-l}}$$

$$\int_{0}^{+\infty} x J_{1}(ax) I_{1}(ax) Y_{0}(x) K_{0}(x) dx = -\frac{\ln(1-a^{4})}{2\pi a^{2}}$$

$$\frac{1}{2\pi i} \oint \frac{(1+2xy+4y^{2}) \exp\left(\frac{4x^{2}y^{2}}{1+4y^{2}}\right)}{y^{n+1}(1+4y^{2})^{\frac{3}{2}}} dy = \frac{H_{n}(x)}{\lfloor n/2 \rfloor!}$$

$$\sum_{k=0}^{n} \frac{q^{k^{2}}}{(q;q)_{k}(q;q)_{n-k}} = \sum_{k=-n}^{n} \frac{(-1)^{k}q^{(5k^{2}-k)/2}}{(q;q)_{n-k}(q;q)_{n+k}}$$
Aims: 1. Prove them automatically
2. Find the rhs given the lhs

Creative telescoping
$$I(x) = \int f(x,t) dt =?$$
 or $U(n) = \sum_{k} u(n,k) =?$

Input: equations (differential for *f* or recurrence for *u*). **Output**: equations for the sum or the integral.

Example:

$$\begin{split} \mathsf{u}(\mathsf{n},\mathsf{k}) &= \binom{\mathsf{n}}{\mathsf{k}} \text{ def. by } \left\{ \binom{\mathsf{n}+1}{\mathsf{k}} = \frac{\mathsf{n}+1}{\mathsf{n}+1-\mathsf{k}} \binom{\mathsf{n}}{\mathsf{k}}, \binom{\mathsf{n}}{\mathsf{k}+1} = \frac{\mathsf{n}-\mathsf{k}}{\mathsf{k}+1} \binom{\mathsf{n}}{\mathsf{k}} \right\} \\ \mathsf{S}(\mathsf{n}+1) &= \sum_{\mathsf{k}} \binom{\mathsf{n}+1}{\mathsf{k}} = \sum_{\mathsf{k}} \underbrace{\binom{\mathsf{n}+1}{\mathsf{k}} - \binom{\mathsf{n}+1}{\mathsf{k}+1}}_{\mathsf{telesc.}} + \underbrace{\binom{\mathsf{n}}{\mathsf{k}+1} - \binom{\mathsf{n}}{\mathsf{k}}}_{\mathsf{telesc.}} + 2 \binom{\mathsf{n}}{\mathsf{k}} = 2\mathsf{S}(\mathsf{n}). \end{split}$$

$$\begin{aligned} \mathsf{IF} \text{ one knows } \mathsf{A}(\mathsf{n},\mathsf{S}_{\mathsf{n}}) \text{ and } \mathsf{B}(\mathsf{n},\mathsf{k},\mathsf{S}_{\mathsf{n}},\mathsf{S}_{\mathsf{k}}) \text{ such that } \overset{\mathsf{relesc.}}{\mathsf{Pascal}} \\ (\mathsf{A}(\mathsf{n},\mathsf{S}_{\mathsf{n}}) + \Delta_{\mathsf{r}}\mathsf{B}(\mathsf{n},\mathsf{k},\mathsf{S}_{\mathsf{n}},\mathsf{S}_{\mathsf{k}}) \cdot \mathsf{u}(\mathsf{n},\mathsf{k}) = 0, \qquad \text{certificate } \mathsf{then the sum telescopes, leading to } \mathsf{A}(\mathsf{n},\mathsf{S}_{\mathsf{n}}) \cdot \mathsf{U}(\mathsf{n}) = 0. \qquad 35 \end{split}$$

Creative Telescoping $I(x) = \int f(x,t) dt =?$

IF one knows $A(x,\partial_x)$ and $B(x,t,\partial_x,\partial_t)$ such that

 $(A(x,\partial_x) + \partial_t B(x,t,\partial_x,\partial_t) \cdot f(x,t)=0,$

then the integral « telescopes », leading to $A(x,\partial_x) \cdot I(x)=0$.

Then I come along and try differentiating under the integral sign, and often it worked. So I got a great reputation for doing integrals.

Richard P. Feynman 1985

Method: integration (summation) by parts and differentiation (difference) under the integral (sum) sign



$$\begin{aligned} & Chyzak's Algorithm \\ & \mathsf{T}_t(\mathsf{f}) := \left(\mathrm{Ann}\,\mathsf{f} + \underbrace{\partial_t \mathbb{Q}(\boldsymbol{x},t) \langle \boldsymbol{\partial}_{\boldsymbol{x}}, \partial_t \rangle}_{\mathrm{int. by parts}} \right) \cap \underbrace{\mathbb{Q}(\boldsymbol{x}) \langle \boldsymbol{\partial}_{\boldsymbol{x}} \rangle}_{\mathrm{diff. under } \int} \end{aligned}$$

Input: a Gröbner basis G for Ann f in $\mathbb{A}=\mathbb{Q}(x,t)\langle\partial_x,\partial_t\rangle$ **Output**: P in $\mathbb{Q}(x)\langle\partial_x\rangle$ and Q in A, reduced wrt G and such that $(P+\partial_tQ)f=0$.

For r=1,2,3,...

1. use indeterminate coefficients to define

$$\mathsf{Q} = \sum_{(\mathsf{i},\mathsf{j}) \text{ below stairs}} \mathsf{q}_{\mathsf{i},\mathsf{j}}(\mathsf{x},\mathsf{t})\partial_\mathsf{x}^\mathsf{i}\partial_\mathsf{t}^\mathsf{j}, \quad \mathsf{P} = \sum_{|\alpha| \leq \mathsf{r}} \mathsf{p}_\alpha(\mathsf{x})\partial_\mathsf{x}^\alpha.$$

2. reduce $P+\partial_t Q$ using G, leading to a 1st order system for $q_{i,j}(x,t)$ and $p_{\alpha}(x)$;

3. stop if a rational solution is found.

Examples of applications

• Hypergeometric: binomial sums, hypergeometric series;

$$\sum_{k=0}^{2n} (-1)^k \binom{2n}{k}^3 = (-1)^n \frac{(3n)!}{n!^3}$$

• **Higher dimension**: classical orthogonal polynomials, special functions like Bessel, Airy, Struve, Weber, Anger, hypergeometric and generalized hypergeometric,...

$$J_0(z) = \frac{2}{\pi} \int_0^1 \frac{\cos(zt)}{\sqrt{1 - t^2}} \, dt$$

• Infinite dimension: Bernoulli, Stirling or Eulerian numbers, incomplete Gamma function,...

$$\int_0^\infty \exp(-xy) \Gamma(n,x) \, dx = \frac{\Gamma(n)}{y} \left(1 - \frac{1}{(y+1)^n}\right)$$

VI. Faster Creative Telescoping

$$\label{eq:critical_constraints} \begin{array}{l} Certificates \ are \ big \\ C_n := \sum\limits_{r,s} \underbrace{(-1)^{n+r+s} \binom{n}{r} \binom{n}{s} \binom{n+s}{s} \binom{n+r}{r} \binom{2n-r-s}{n} }_{f_{n,r,s}} \end{array}$$

 $(n+2)^3C_{n+2} - 2(2n+3)(3n^2 + 9n + 7)C_{n+1} - (4n+3)(4n+4)(4n+5)C_n = 180 \ \text{kB} \simeq 2 \ \text{pages}$

$$I(z) = \oint \frac{(1+t_3)^2 dt_1 dt_2 dt_3}{t_1 t_2 t_3 (1+t_3 (1+t_1))(1+t_3 (1+t_2)) + z(1+t_1)(1+t_2)(1+t_3)^4}$$

 $z^{2}(4z+1)(16z-1)I'''(z) + 3z(128z^{2} + 18z - 1)I''(z) + (444z^{2} + 40z - 1)I'(z) + 2(30z + 1)I(z) = 1080 \text{ kB}$ $\simeq 12 \text{ pages}$

Next, in
$$T_t(f) := \left(\operatorname{Ann} f + \underbrace{\partial_t \mathbb{Q}(\boldsymbol{x}, t) \langle \boldsymbol{\partial}_{\boldsymbol{x}}, \partial_t \rangle}_{\text{int. by parts}}\right) \cap \underbrace{\mathbb{Q}(\boldsymbol{x}) \langle \boldsymbol{\partial}_{\boldsymbol{x}} \rangle}_{\text{diff. under } \int}$$
.
we restrict to rational f and $\partial_t \mathbb{Q}(\boldsymbol{x})[t, 1/\operatorname{den} f] \langle \boldsymbol{\partial}_{\boldsymbol{x}}, \partial_t \rangle$
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Bivariate integrals by Hermite reduction

$$I(t) = \oint \frac{P(t,x)}{Q^{m}(t,x)} dx$$
Q square-free
Int. over a cycle
where Q \neq 0.
If m=1, Euclidean division: P=aQ+r, deg_x rx Q

$$\frac{P}{Q} = \frac{r}{Q} + \partial_{x} \int a$$
Def. Reduced form:
$$\begin{bmatrix} P\\{Q} \end{bmatrix} := \frac{r}{Q}$$
If m>1, Bézout identity and integration by parts

$$P = uQ + v\partial_{x}Q \rightarrow \frac{P}{Q^{m}} = \frac{u + \frac{\partial_{x}v}{m-1}}{Q^{m-1}} + \partial_{x}\frac{v/(1-m)}{Q^{m-1}}$$
Algorithm: R₀:=[P/Q^m]
for i=1,2,... do R_i:=[\partial_{i}R_{i-1}]
when there is a relation c₀(t)R₀+...+c_i(t)R_i=0
return c₀+...+c_i\partial_{t}^{i}}

Q square-free
Int. over a cycle
where Q \neq 0.
P = uQ + v\partial_{x}Q \rightarrow \frac{P}{Q^{m}} = \frac{u + \frac{\partial_{x}v}{m-1}}{Q^{m-1}} + \partial_{x}\frac{v/(1-m)}{Q^{m-1}}
Algorithm: R₀:=[P/Q^m]
for i=1,2,... do R_i:=[\partial_{i}R_{i-1}]
when there is a relation c₀(t)R₀+...+c_i(t)R_i=0
return c₀+...+c_i\partial_{t}^{i}}

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More variables: Griffiths-Dwork reduction

$$I(t) = \oint \frac{P(t,\underline{x})}{Q^{m}(t,\underline{x})} \, d\underline{x}$$

Q square-free Int. over a cycle where Q≠0.

1. Control degrees by homogenizing $(x_1, \dots, x_n) \mapsto (x_0, \dots, x_n)$ 2. If m=1, [P/Q]:=P/Q

3. If m>1, reduce modulo Jacobian ideal $J:=\langle \partial_0 Q,\ldots,\partial_n Q\rangle$

$$\begin{split} P &= r + v_0 \partial_0 Q + \dots + v_n \partial_n Q \\ \frac{P}{Q^m} &= \frac{r}{Q^m} - \frac{1}{m-1} \left(\partial_0 \frac{v_0}{Q^{m-1}} + \dots + \partial_n \frac{v_n}{Q^{m-1}} \right) + \underbrace{\frac{1}{m-1} \frac{\partial_0 v_0 + \dots + \partial_n v_n}{Q^{m-1}}}_{A_{m-1}} \\ \left[\frac{P}{Q^m} \right] &:= \frac{r}{Q^m} + [A_{m-1}] \end{split}$$

Thm. [Griffiths] In the regular case $(\mathbb{Q}(t)[\underline{x}]/J)$ (finite dim), if R=P/Q^m hom of degree -n-1, [R] = 0 $\Leftrightarrow \oint \text{Rd}\underline{x} = 0$.

→ SAME ALGORITHM.

Size and complexity $I(t) = \oint \frac{P(t,\underline{x})}{Q^{m}(t,\underline{x})} d\underline{x}$ no regularity assumed $\in \mathbb{Q}(t, x)$ $N := \deg_x Q, \quad d_t := \max(\deg_t Q, \deg_t P)$ deg_xP not too big **Thm.** A linear differential equation for I(t) can be computed

in $O(e^{3n}N^{8n}d_t)$ operations in \mathbb{Q} . It has order $\leq N^n$ and degree $O(e^nN^{3n}d_t)$.

tight

Note: generically, the certificate has at least $N^{n^2/2}$ monomials.

This has consequences for multiple binomial sums.

Conclusion

- Linear differential equations and recurrences are a great data-structure;
- Numerous algorithms have been developed in computer algebra;
- Efficient code is available;
- More is to be found (certificate-free algorithms, diagonals,...)