

Computer-assisted proofs: Packings in containers

Daria Pchelina

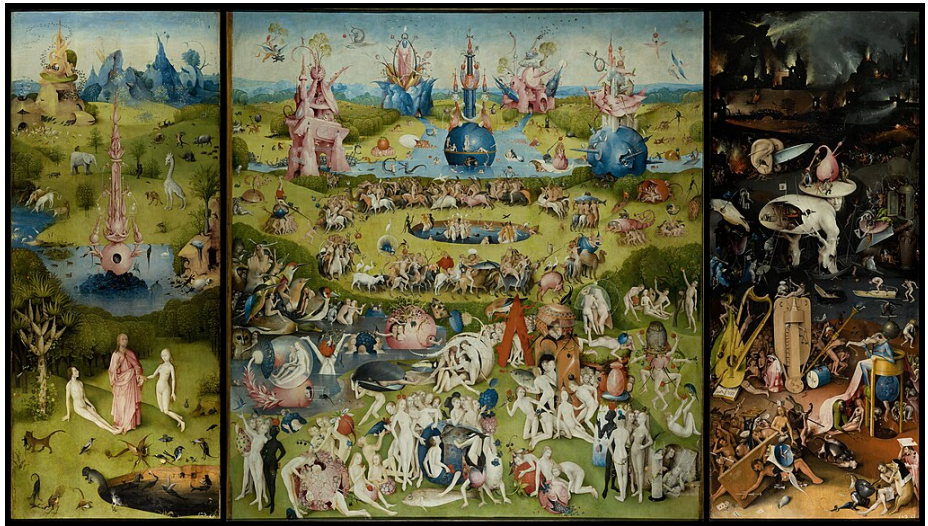
CNRS

équipe MC2, LIP, ENS Lyon

20/11 and 2/12/2025

- 1 Formalizing packings in containers
- 2 Bounds on objective value for square container
- 3 Homework I
- 4 Find candidate packings
- 5 Prove optimality by hand
- 6 Prove optimality by computer
- 7 Critical density
- 8 Homework II

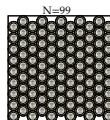
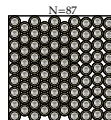
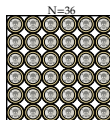
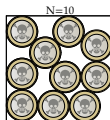
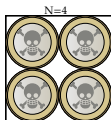
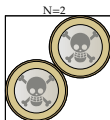
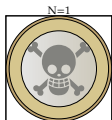
"The Garden of Earthly Delights" Hieronymus Bosch, between 1490 and 1510



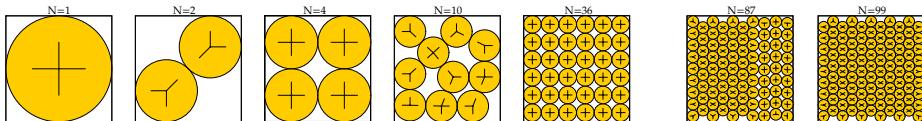
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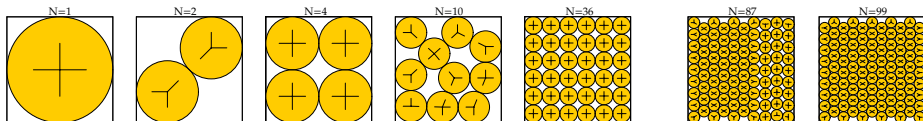
Place n identical coins in a smallest possible square solved for 1–33, 36 (1964–2021)



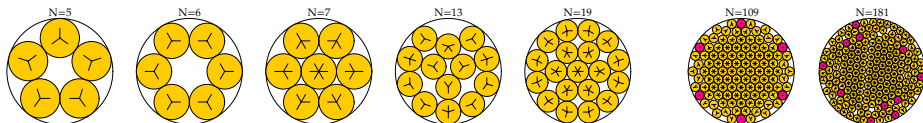
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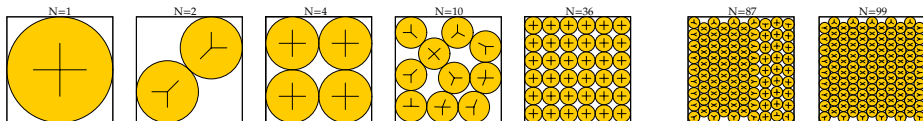
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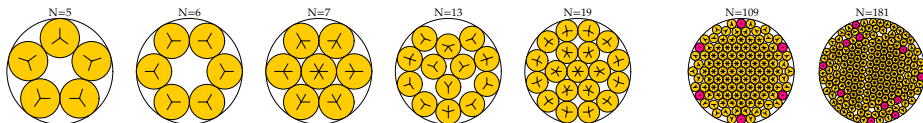
... circle solved for 1–13, 19 (1967–2003)



Place n identical coins in a smallest possible square solved for 1–33, 36 (1964–2021)



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Find candidates: by hand for small n , billiard simulation, perturbation method

Prove optimality: by hand for small n and circles, interval analysis, branch-and-bound

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Geometrical models: circular container

$P_n(r, R)$: the set of packings of n circles of radius r in a circle of radius R .

$$P_n(r, R) := \{ \{c_i = (x_i, y_i)\}_{i=1}^n \text{ s.t. } |c_i| \leq R - r \text{ and } |c_i - c_j| \geq 2r \forall i, j \}$$

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Π_1 : $r = 1$ find the smallest circular container such that n unit circle fit inside.

$$R_n := \min_{P_n(1, R) \neq \emptyset} R$$

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$A_n(d, R)$: the set of arrangement of n points with pairwise distance at least d in a circle of radius R .

$$A_n(d, R) := \{ \{p_i = (x_i, y_i)\}_{i=1}^n \text{ s.t. } |p_i| \leq R \text{ and } |p_i - p_j| \geq d \forall i, j \}$$

$\Pi'_1 : d = 1$ find the smallest circular containers such that n points with pairwise distance at least 1 fit inside.

$$R'_n := \min_{A_n(1, R') \neq \emptyset} R'$$

$\Pi'_2 : R = 1$ find the biggest d such that n with pairwise distance at least d fit inside unit circular container.

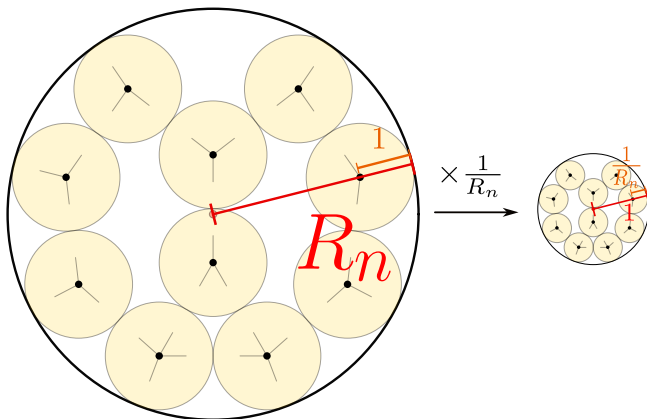
$$d_n := \max_{A_n(d, 1) \neq \emptyset} d$$

Equivalence of geometrical models: $\Pi_1 \sim \Pi_2$

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If $P \in P_n(1, R_n)$ then $\frac{1}{R_n} \times P \in P(r_n, 1)$, i.e., $r_n = \frac{1}{R_n}$.

If P is an optimal packing of n unit circles, then P deflated by R_n is an optimal packing of n circles in unit circular container.

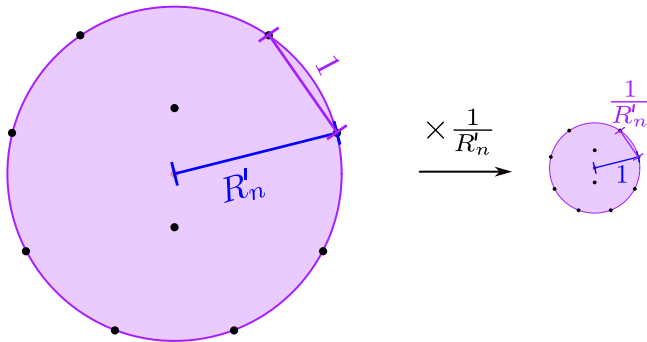


Equivalence of geometrical models: $\Pi'_1 \sim \Pi'_2$

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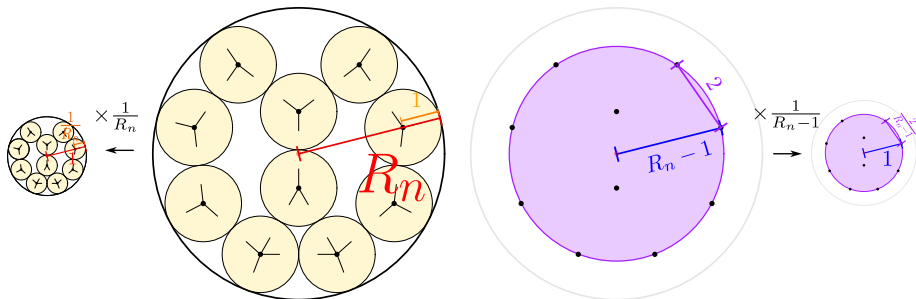


Equivalence of geometrical models: $\Pi_1 \sim \Pi'_2$

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If $P \in P_n(1, R_n)$ then centers $\left(\frac{1}{R_n-1} \times P\right) \in A(d_n, 1)$, i.e., $d_n = \frac{2}{R_n-1}$.

If P is an optimal packing of n unit circles, then the centers of circles in P deflated by $R_n - 1$ correspond to an optimal arrangement of n points in unit circular container.



Geometrical models : circular container

Π_1 Place n unit discs in a circle of radius R_n

minimize R_n .

Π_2 Place n equal discs of radius r_n in a unit circle

maximize r_n .

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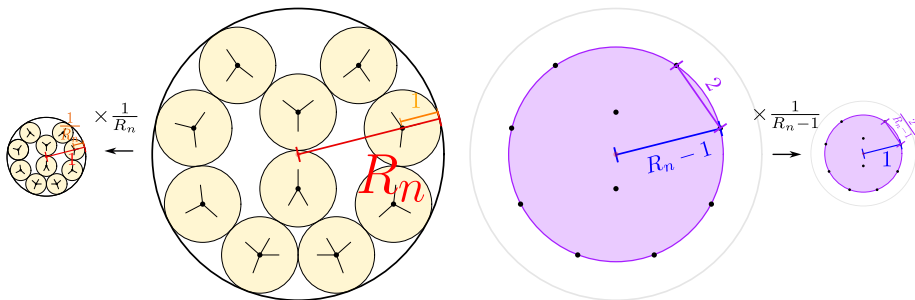
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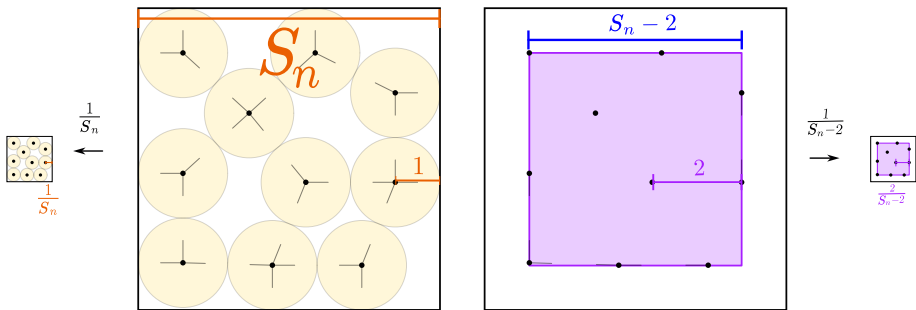
Geometrical models : circular or square container

Π_1 Place n unit discs in a circle (square) of radius R_n (of side S_n) minimize R_n (S_n).

Π_2 Place n equal discs of radius r_n in a unit circle (square) maximize r_n .

Π'_2 Place n points in a unit circle (square) to maximize the min distance between points d_n .

$$r_n = \frac{1}{R_n}, \quad d_n = \frac{2}{R_n - 1} \quad \left(r_n = \frac{1}{S_n}, \quad d_n = \frac{2}{S_n - 2} \right)$$



Mathematical programming models

$$\text{Maximize } d_n := \min_{1 \leq i < j \leq n} \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$$

$$0 \leq x_i, x_j, y_i, y_j \leq 1$$

$$0 \leq x_i^2 + y_i^2, x_j^2 + y_j^2 \leq 1$$

max-min

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Maximize t

$$t \leq (x_i - x_j)^2 + (y_i - y_j)^2 \quad \frac{n(n-1)}{2} \text{ non-convex constraints}$$

$$0 \leq x_i, y_i \leq 1 \quad 2n \text{ box constraints}$$

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What is a “solution”?

Numerical candidate: might be unfeasible (not a packing), “good” objective value

Candidate packing: feasible, good objective value but not proved optimal

Validated enclosure of the optimum: all feasible, contains the optimum

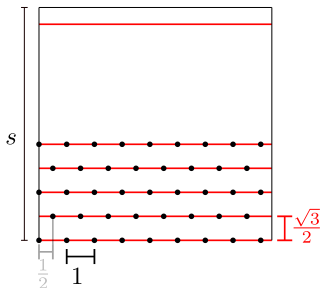
Unique optimal packing: feasible, proved optimal

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Lower bound on the maximal distance d_n

Lower bound on the optimal objective value: objective value of any feasible solution.

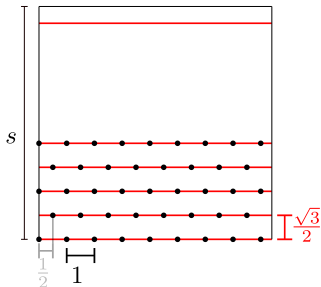
How to fit at least $\frac{2s^2}{\sqrt{3}}$ points at distance at least 1 in the square of side s for all $s \in \mathbb{R}^+$:



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$$N = \left\lfloor \frac{2s}{\sqrt{3}} \right\rfloor + 1 \text{ red segments}$$

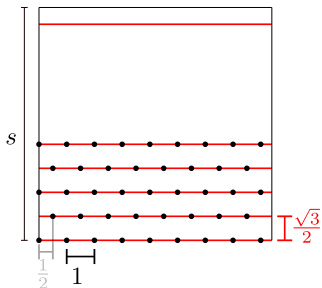
$\lfloor s \rfloor + 1$ points on each odd segment

$\lfloor s - \frac{1}{2} \rfloor + 1$ points on each even segment

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number of points in the square:

if N is even, $\frac{N}{2} (\lfloor s \rfloor + 1 + \lfloor s - \frac{1}{2} \rfloor + 1)$

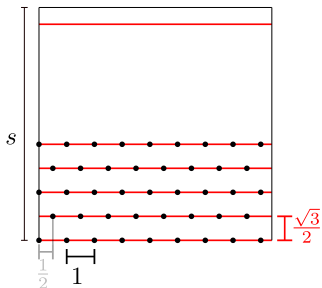
if N is odd, $\frac{N-1}{2} (\lfloor s \rfloor + 1 + \lfloor s - \frac{1}{2} \rfloor + 1) + \lfloor s \rfloor + 1$

in both cases, $\geq N s \geq \frac{2s^2}{\sqrt{3}}$

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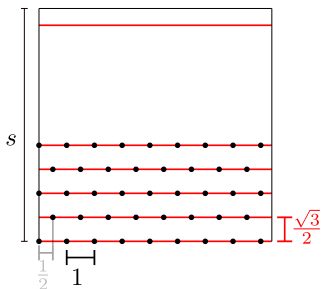
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$\times \frac{1}{s} \Rightarrow$ fit at least $\frac{2}{d^2\sqrt{3}}$ points at distance at least d in the unit square for all $d (= \frac{1}{s})$

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Lower bound on the optimal objective value: objective value of any feasible solution.

How to fit at least $\frac{2s^2}{\sqrt{3}}$ points at distance at least 1 in the square of side s for all $s \in \mathbb{R}^+$:



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$d = \sqrt{\frac{2}{n\sqrt{3}}} \Rightarrow$ fit at least n points at distance at least $\sqrt{\frac{2}{n\sqrt{3}}}$ in the unit square for all n

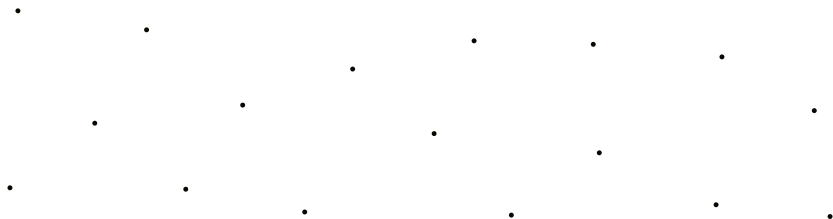
$$\Rightarrow d_n \geq \sqrt{\frac{2}{n\sqrt{3}}}$$

Voronoi diagrams

Given $S \subset \mathbb{R}^2$ set of points,

Voronoi cell of point $p \in S$: $\text{Vor}(p) := \{q \in \mathbb{R}^2 \mid \text{dist}(q, p') > \text{dist}(q, p) \forall p' \in S \setminus \{p\}\}$

Voronoi cell is **convex** polygonal domain (possibly unbounded)

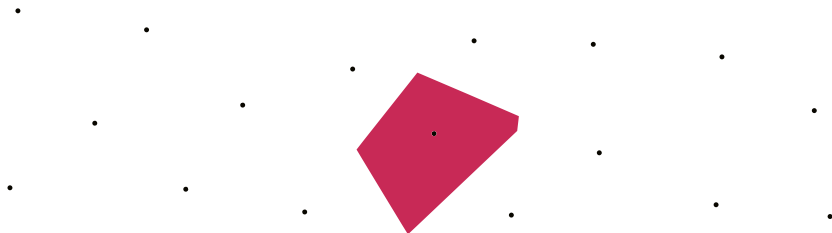


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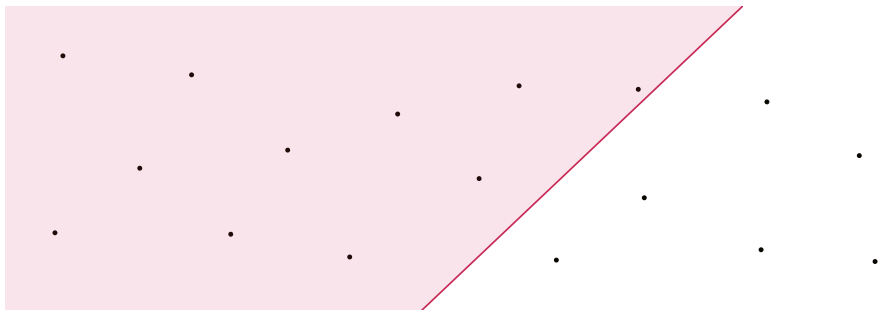


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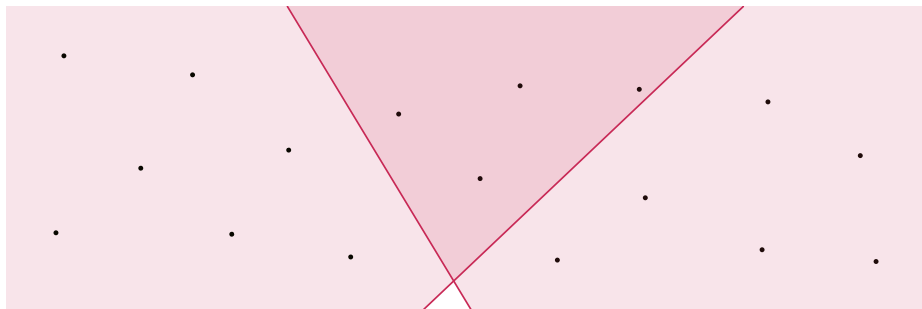


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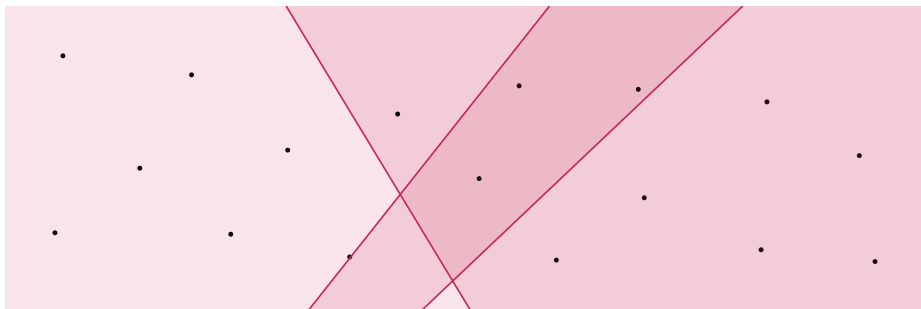


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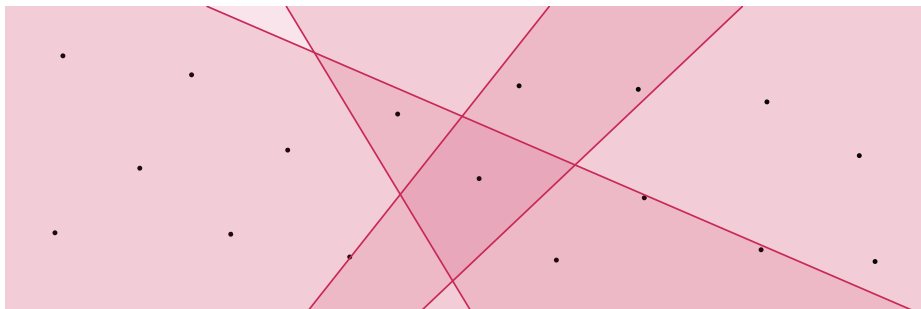


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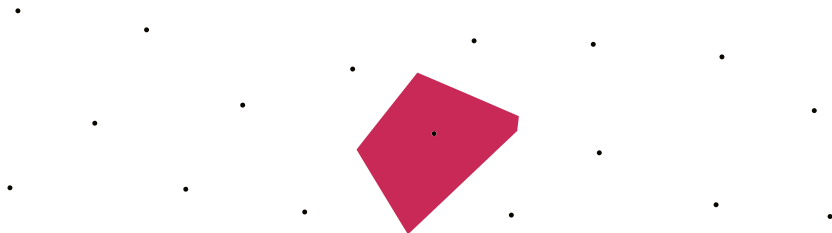


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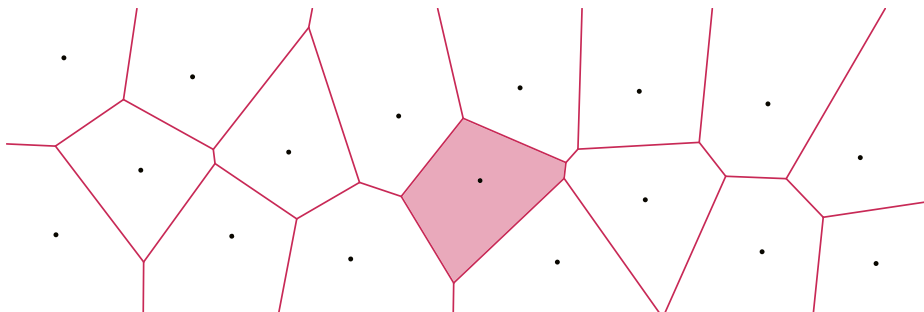
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Voronoi diagram of S : union of Voronoi cells of its points $\bigcup_{p \in S} \text{Vor}(p)$



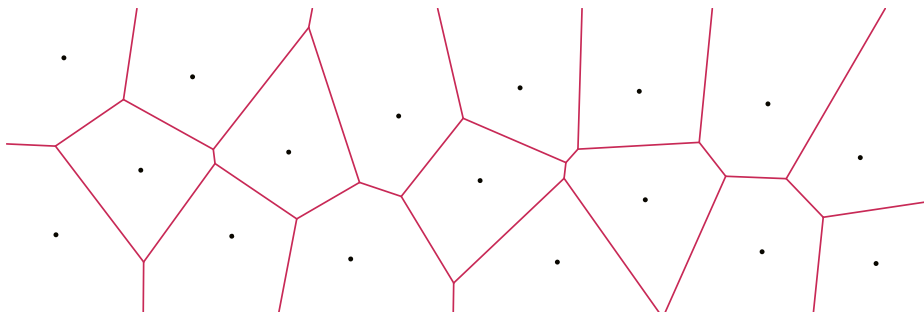
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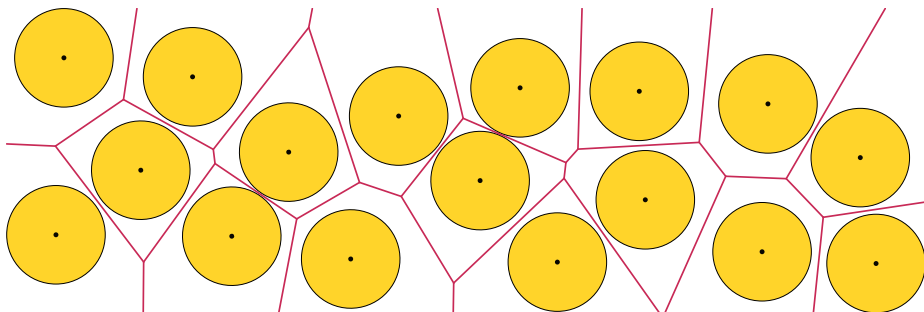
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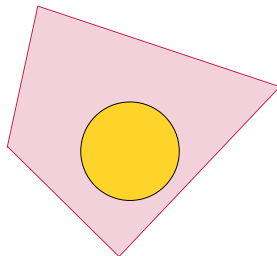
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Voronoi diagram of a circle packing: Voronoi diagram of the circle centers

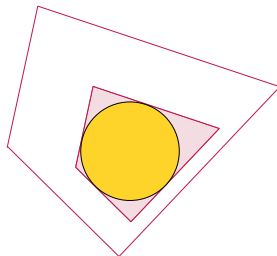
Smallest Voronoi cells in a circle packing

What is the Voronoi cell of smallest area in a packing of unit circles?



Smallest Voronoi cells in a circle packing

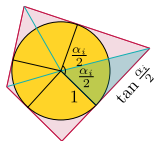
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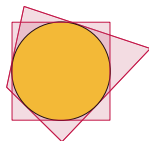


• circumscribed \Rightarrow $\text{area} = \frac{\text{perimeter}}{2} = \sum_i \tan\left(\frac{\alpha_i}{2}\right)$, $\sum_i \alpha_i = 2\pi$, $\tan\frac{x}{2}$ is convex \Rightarrow

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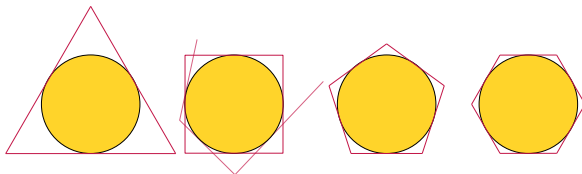
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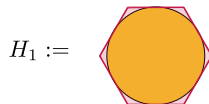
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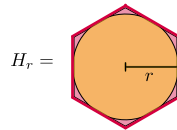
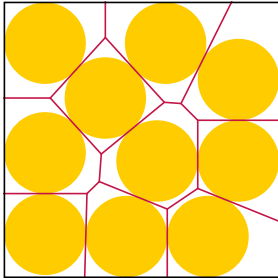
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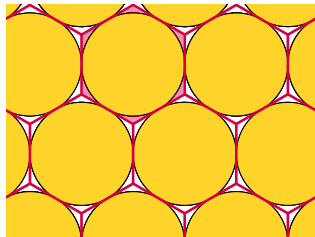
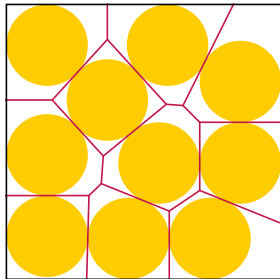
Upper bound on the maximal radius r_n

Voronoi cell of minimal area in a packing of r -circles: circumscribed regular hexagon H_r .



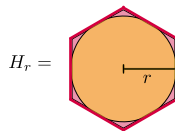
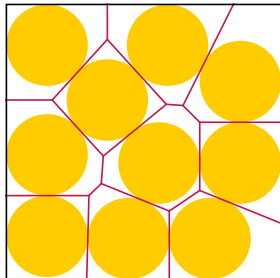
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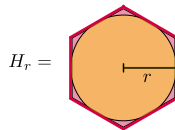
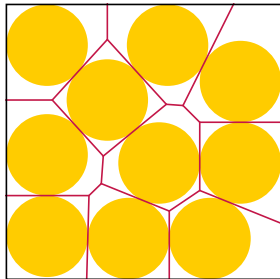
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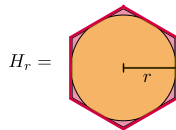
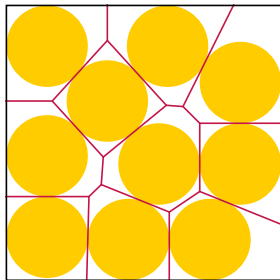
Voronoi cells are disjoint and their union is the unit square :

$$n \times 2\sqrt{3}r^2 \leq \sum_{i=1}^n \text{area}(\text{Vor}(O_i)) = 1$$

$$r \leq \sqrt{\frac{1}{2\sqrt{3}n}}$$

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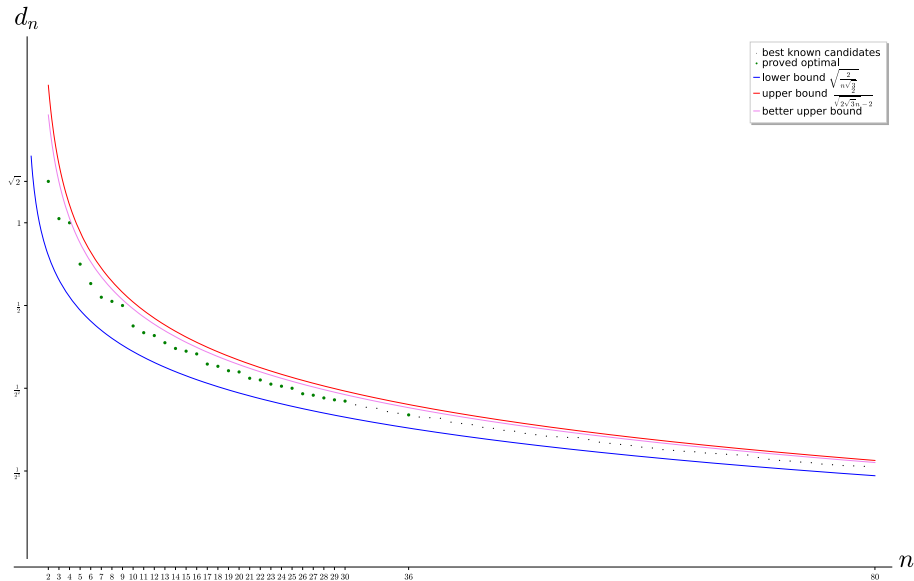
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$$r \leq \sqrt{\frac{1}{2\sqrt{3}n}} \implies d = \frac{2}{\frac{1}{r} - 2} \leq \frac{2}{\sqrt{2\sqrt{3}n} - 2}$$

Bounds on d_n vs best known



- 1 Formalizing packings in containers
- 2 Bounds on objective value for square container
- 3 Homework I**
- 4 Find candidate packings
- 5 Prove optimality by hand
- 6 Prove optimality by computer
- 7 Critical density
- 8 Homework II

20/11–25/11

- ➊ Improve the upper bound on d_n in square container $\left(\frac{2}{\sqrt{2}\sqrt{3n-2}}\right)$.
- ➋* What is the best way to put discs of radii 1 and $\sqrt{2} - 1$ in a 4×4 square?
(best = cover most surface)

To be submitted by email to: daria.pchelina@ens-lyon.fr

Deadline: beginning of next lecture (25/11, 15h45)

- 1 Formalizing packings in containers
- 2 Bounds on objective value for square container
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Perturbation method

Ball et al 2000: “new” candidates up to 200

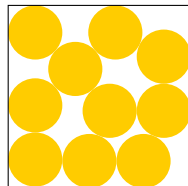
- random n points in unit square, $\epsilon = \frac{1}{4}$
- for each point, perturb by ϵ to increase distance to the nearest neighbor
repeat until no points to move
- $\epsilon = \frac{2\epsilon}{3}$
- stop when ϵ small

[what it looks like](#)

$$d_{10} \approx 0.4212795439839, \quad r_{10} = 0.1482043225652$$

Stuck in local optima \Rightarrow need MANY iterations

[what it looks like with 100 iterations](#)



Billiard simulation

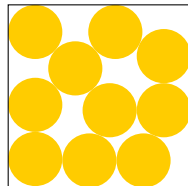
Graham and Lubachevsky 1996: “new” candidates up to 50

Start with an arrangement of n identic circles, of some initial radius, and random velocity vector.

Gradually inflate circles, until they can not move anymore.

[what it looks like](#)

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Modified Billiard Simulation or Pulsating Disk Shaking algorithm 2007

no initial velocities \Rightarrow only store local interactions (circle-circle and circle-wall contacts)
improved ≈ 100 cases up to 200

Billiard simulation

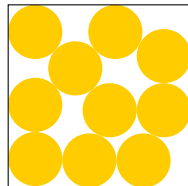
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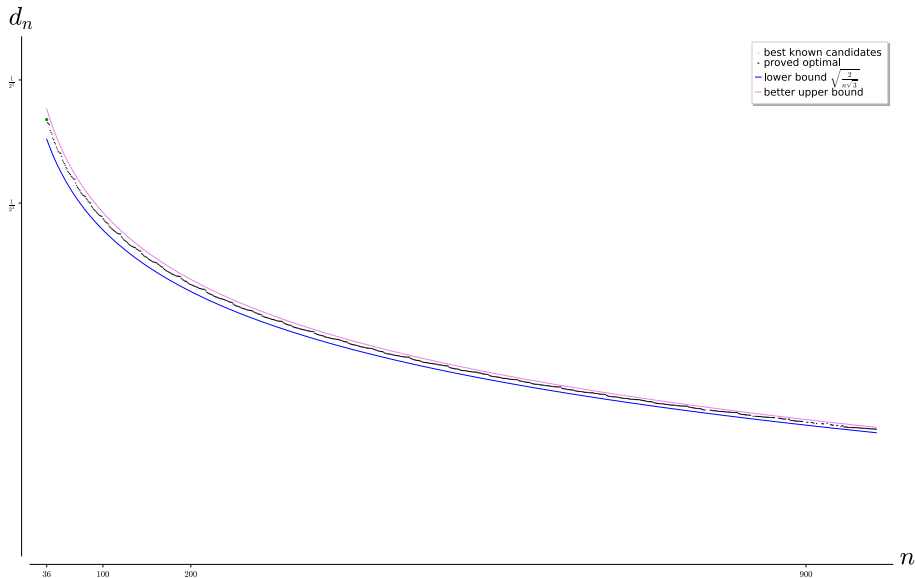


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numerical candidate \rightarrow feasible candidate: **interval arithmetic** in the

► Next Lecture

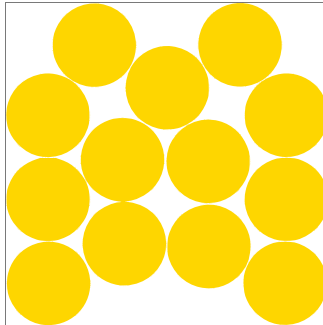


From numerical candidate to feasible packing

Numerical candidate packing might be unfeasible due to rounding errors

Number of Circles: Growth Rate:
Initial Radius: Initial Velocity:

Current Radius: 0.130259



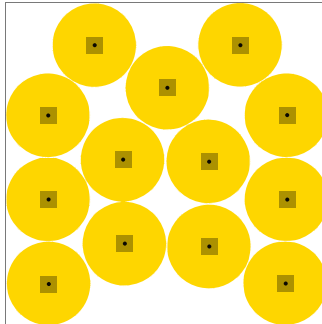
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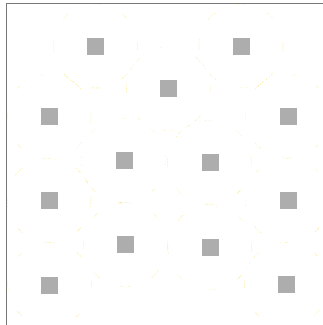


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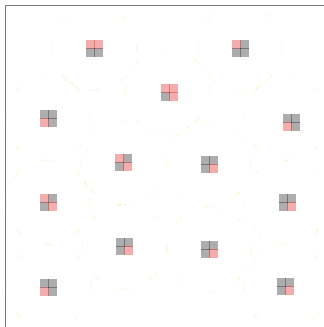


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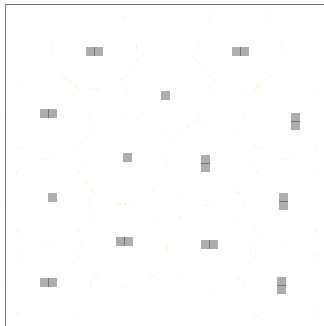


From numerical candidate to feasible packing

Numerical candidate packing might be unfeasible due to rounding errors

- 1 centers \rightarrow interval error boxes
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- 3 subdivide boxes if not enough precision
- 4 we got an enclosure of feasible packings

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Circular container: $n \leq 7$

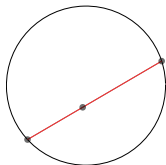
Lemma

If $n > 2$ points a_1, \dots, a_n lie in a unit disk then some pair points is at distance at most

$$\max(1, 2 \sin(\frac{\pi}{n})).$$

Proof.

If point $x \in \text{convex hull}(a_1, \dots, a_k)$, then $d(x, a_j) < 1$ for some j .



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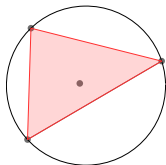
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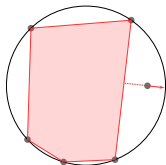
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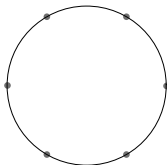
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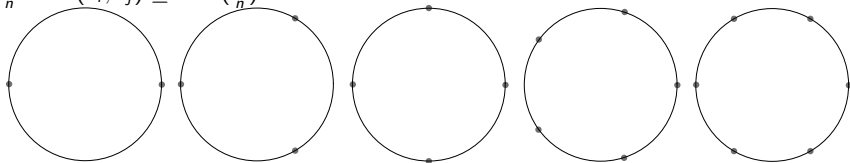
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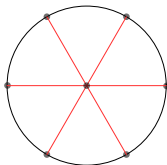
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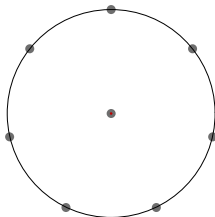
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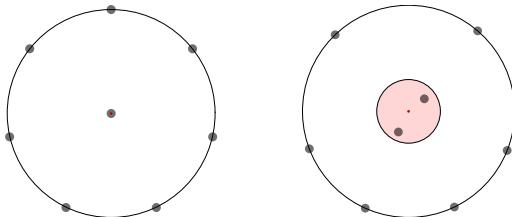
$n = 7$: 6 points on the boundary, 7th point in the center $d_7 = d_6 = 1$.

Suppose we can do better than $d_8 = 2 \sin\left(\frac{\pi}{7}\right)$ with < 7 points on the boundary.



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If 6 points on the boundary, then each pair of points at distance at least d_8 , each arc is at least $\frac{2\pi}{7}$, then the maximal arc is at most $2\pi - 5\frac{2\pi}{7} = \frac{4\pi}{7}$ $\frac{2\pi}{7} \leq \phi \leq \frac{4\pi}{7}$

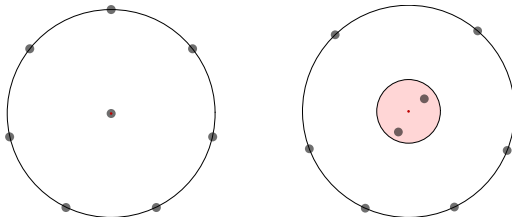


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Thus, $d(x_1, x_2) < 2 \sin(\frac{\pi}{7}) = d_8$: contradiction.



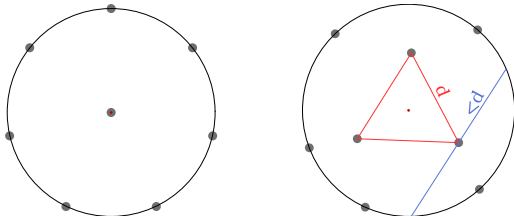
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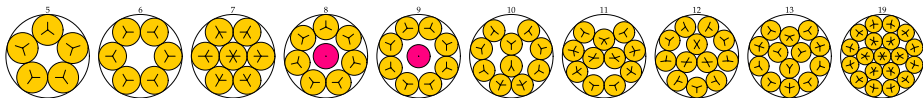
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If < 6 points on the boundary, ≥ 3 points inside, separated by at least d_8 .



Circular container: optimal packings

1–13,19



- Pirl 1969: 1–10
- Mellisen 1994: 11
- Fodor 2000: 12, 2003: 13, 1999: 19

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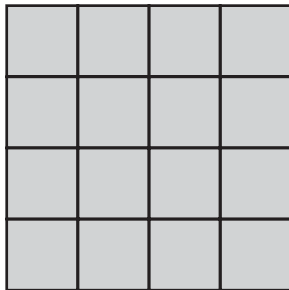
Find certified enclosure of the optima: method of active cells

1 find a good lower bound \underline{d} on d_n

$$n = 10 : 0.42$$

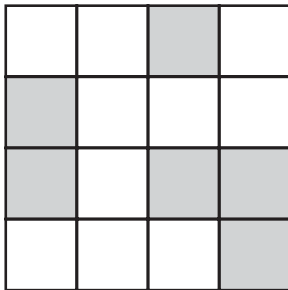
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at most one point in each tile

$$16 \text{ squares } \frac{1}{4} \times \frac{1}{4}$$



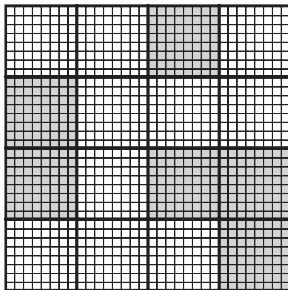
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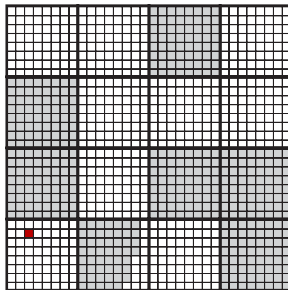
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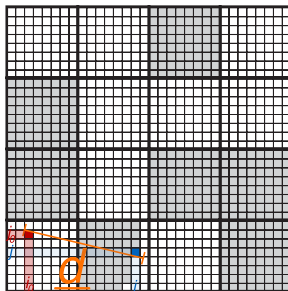
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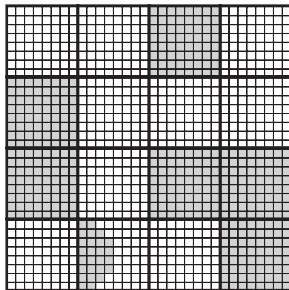
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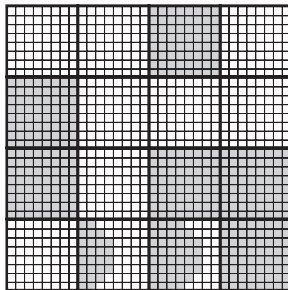
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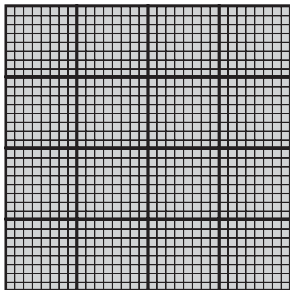
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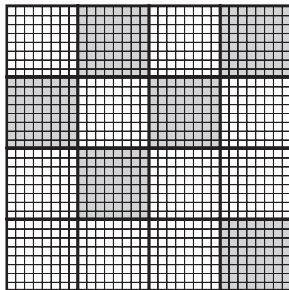
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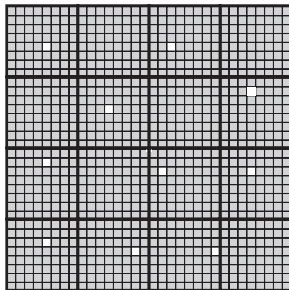
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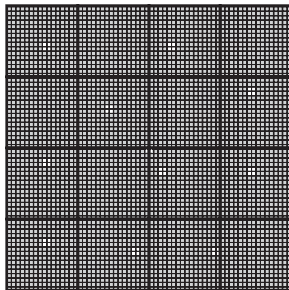
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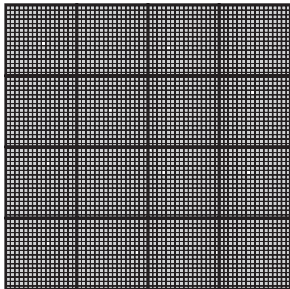
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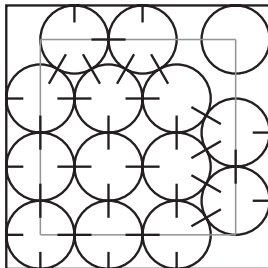
We got a validated enclosure of the optimum.



Proof of uniqueness (sketch): shrinking regions

Point arrangement \rightarrow disk packing

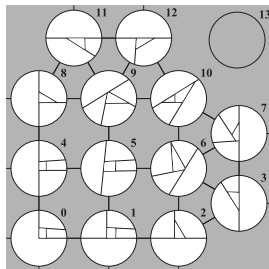
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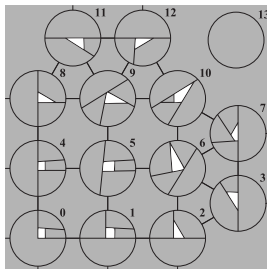
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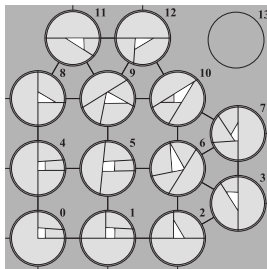
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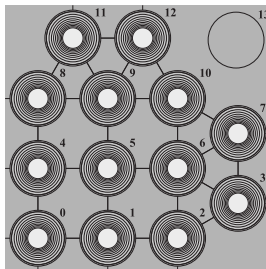
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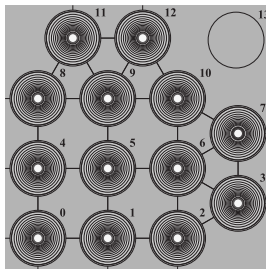
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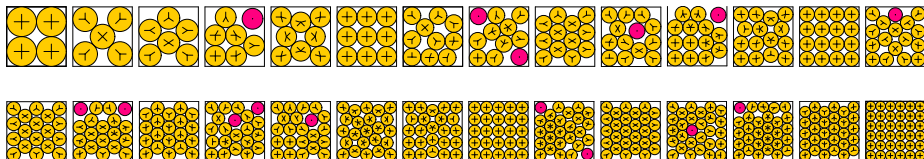
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- 6 each sequence of concentric error-disks converges to the guessed center
- 7 the optimum is unique and corresponds to the guessed structure

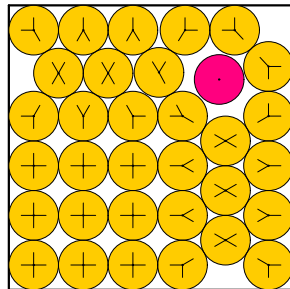
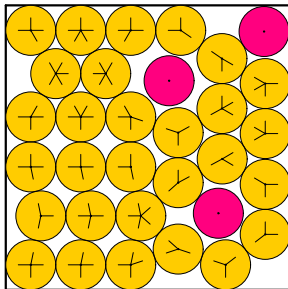
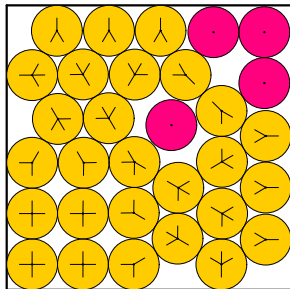


Square container: optimal packings

1–30, 36



- 1–9 by hand Schaer and Meir 1965, Schwartz 1970
 - 14, 16, 25, 36 by hand Kirchner, Wengerodt 1983, 1987
 - 10–20 computer-assisted Peikert, Wurtz, Monagan, de Groot 1990, 1992,
 - 21–27 computer-assisted Nurmela, Östergård 1999
 - 28–30 computer-assisted Markót, Csentes 2007
- 28,29 — combinatorial structure, uniqueness in enclosures but no symbolic solution for coordinates



• 31–33 computer-assisted Markót 2022

tangencies might not all be present in the optimum

- 1 Formalizing packings in containers
- 2 Bounds on objective value for square container
- 3 Homework I
- 4 Find candidate packings
- 5 Prove optimality by hand
- 6 Prove optimality by computer
- 7 Critical density**
- 8 Homework II

Circle Packing: given a set of n circles, can they be packed into a unit square?

Circle Placement: given a set of n circles, place their centers into a unit square.

Demaine, Fekete, Lang 2010

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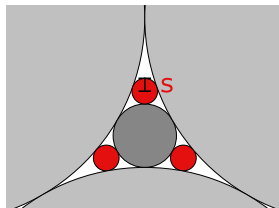
encoding 3-Partition into Circle Placement:

feasible partition iff $\forall (i_1, i_2, i_3)$ is feasible: $\sum_{j=1}^3 x_{ij} = 1$

$$r_i := s - (\frac{1}{3} - x_i)\varepsilon^2$$

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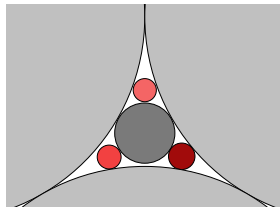
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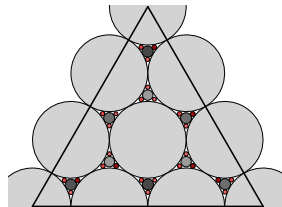
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Packing disks (of different sizes) in a unit circle/square,

worst-case density D : ratio between the combined area of disks that can always be packed and the area of the container

if $\frac{\sum_{d \in S} \text{area}(d)}{\pi} \leq D$ then all disks in S will fit in the unit circle/square \forall set of disks S

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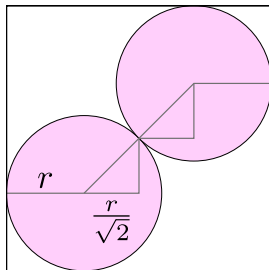
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example: unit square

two disks of radius $r = \frac{1}{2+\sqrt{2}}$

density: $2\pi r^2 = \frac{2\pi}{(2+\sqrt{2})^2} = \frac{\pi}{3+2\sqrt{2}}$

$\Rightarrow D_{\text{crit}} \geq \frac{\pi}{3+2\sqrt{2}}$



Disks in a square

Critical density for packing disks into a square is $\frac{\pi}{3+2\sqrt{2}} \approx 53.9\%$.

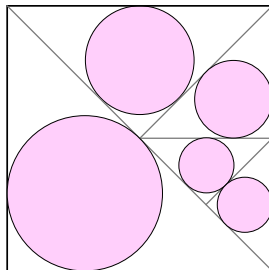
Morr 1977

Split Pack algorithm sketch:

divide-and-conquer

- 1 divide disks into two almost equal sum areas parts C_1, C_2
- 2 split the square into two right equilateral triangles T_1, T_2
- 3 Split Pack C_1 into T_1
- 4 Split Pack C_2 into T_2

greedy



Disks in a square

Critical density for packing disks into a square is $\frac{\pi}{3+2\sqrt{2}} \approx 53.9\%$.

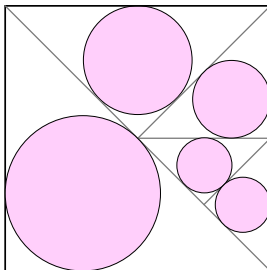
Morr 1977

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Disks in a square

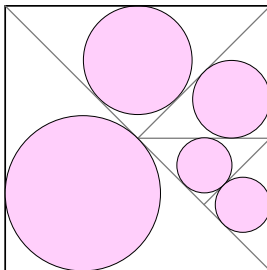
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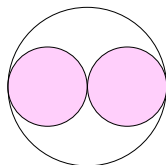
divide-and-conquer

- 1 divide disks into two almost equal sum areas parts C_1 , C_2 greedy
- 2 split the region into two parts T_1 , T_2 whose sizes depend on areas of C_1 and C_2
- 3 Split Pack C_1 into T_1
- 4 Split Pack C_2 into T_2



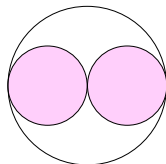
Critical density of disks in circle

two disks of radius $\frac{1}{2}$ density: $\frac{2 \cdot \frac{\pi}{4}}{\pi} = \frac{1}{2} \Rightarrow D_{\text{crit}} \geq \frac{1}{2}$



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Critical density for packing disks into a circle is $\frac{1}{2}$.

Fekete, Keldenich, Scheffer 2019

sketch of idea of algorithm:

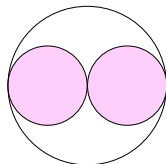
- ➊ boundary packing
- ➋ ring packing

$$r_1 \geq r_2 \geq \dots \geq r_n$$

glue disks to the interior boundary
layers of disks inside rings

Critical density of disks in circle

two disks of radius $\frac{1}{2}$ density: $\frac{2 \cdot \frac{\pi}{4}}{\pi} = \frac{1}{2} \Rightarrow D_{\text{crit}} \geq \frac{1}{2}$

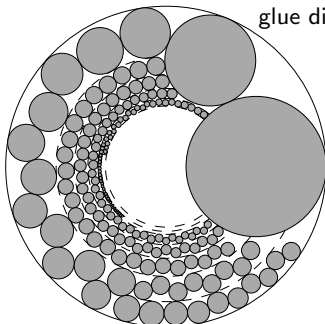


Critical density for packing disks into a circle is $\frac{1}{2}$.

Fekete, Keldenich, Scheffer 2019

sketch of idea of algorithm:

- 1 boundary packing
- 2 ring packing



glue disks to the interior boundary layers of disks inside rings

illustration from Fekete, Keldenich, Scheffer, SoCG 2019

- 1 Formalizing packings in containers
- 2 Bounds on objective value for square container
- 3 Homework I
- 4 Find candidate packings
- 5 Prove optimality by hand
- 6 Prove optimality by computer
- 7 Critical density
- 8 Homework II

Homework II

```
1  rA,rB,rC = 1,1,1
2  ab_init = RIF(rA+rB, (rA+rB+2*rC)) # RIF(x,y)=smallest interval containing
   [x,y]
3  bc_init = RIF(rC+rB, (rB+rC+2*rA))
4
5  area = lambda ab, bc: ab*bc/2
6  cov = lambda ab, bc: RIF(pi)/4*rB**2 + arctan(ab/bc)/2*rC**2 + arctan(bc/ab
   )/2*rA**2 # RIF(x) = smallest interval containing x
7  density = lambda ab, bc: cov(ab,bc) / area(ab,bc)
8
9  density_init = RIF(density(ab_init,bc_init))
10 max_lb_dens = density_init.lower() # lower bound of the interval
11
12 boxes = [(ab_init, bc_init)]
13 N = 1000
14 while len(boxes)>0 and N>0:
15     N-=1
16     box = boxes.pop()
17     if density(*box).upper()>max_lb_dens:
18         if density(*box).lower()>max_lb_dens:
19             max_lb_dens = density(*box).lower()
20             for new_box in [(new_ab, new_bc) for new_ab in box[0].bisection()
21 for new_bc in box[1].bisection()]: # subdivide each interval
22                 boxes = boxes + [new_box]
23
24 print(min([density(*b).lower() for b in boxes]))
25 print(max([density(*b).upper() for b in boxes]))
```

Listing 1: SageMath code for homework

2/12–9/12

For these exercises, install SageMath (or use Sage on CoCalc).

- ❶ What does the code do? Change one line to make the result much “better” without taking longer time. How to do the same for $r_A = \sqrt{2} - 1, r_B = 1, r_C = 1$? And $r_A = 1, r_B = \frac{2}{\sqrt{3}} - 1, r_C = 1$?
- ❷ * Write the code doing the same when $r_A = \sqrt{2} - 1, r_B = 1, r_C = 1$ without constraint on angle \widehat{ABC} .
- ❸ * Formally prove that Circle Packing is NP-hard.

Demaine, Fekete, Lang 2010: <https://arxiv.org/abs/1008.1224>.

L^AT_EX-generated pdfs, txt, anything except handwriting to be submitted by email to: daria.pchelina@ens-lyon.fr

Deadline: beginning of the lecture in one week (9/12, 15h45)