## Regular Sensing

Shaull Almagor<sup>1</sup>, **Denis Kuperberg**<sup>2</sup>, Orna Kupferman<sup>1</sup>

 $^{1}\mbox{Hebrew University of Jerusalem}$ 

<sup>2</sup>Onera/DTIM - IRIT.

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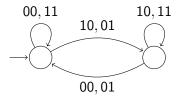
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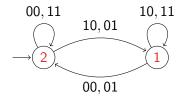
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- New approach: Reading signals via sensors costs energy.
- Goal: Minimize the energy consumption in an average run.

Deterministic automaton A on  $\{00, 01, 10, 11\}$ .



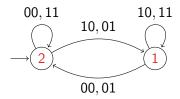
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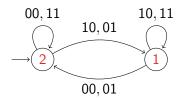
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$$scost(A) = \lim_{m \to \infty} |\Sigma|^{-m} \sum_{w:|w|=m} scost(w)$$

## **Computing the cost**

Remarks on the definition of sensing cost:

- Initial state plays a role but not acceptance condition.
- Works on finite or infinite words.
- Cost is deduced from the transition structure.
- Signals can be weighted with different probabilities or sensing cost.

# **Computing the cost**

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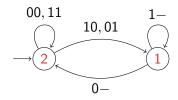
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#### Theorem

Sensing cost of an automaton is computable in polynomial time.

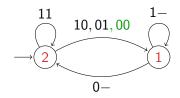
By computing the stationary distribution of the induced Markov chain.

# Back to the example



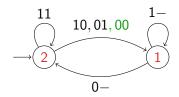
Stationary distribution:  $\frac{1}{2}, \frac{1}{2}$ Sensing cost:  $\frac{3}{2}$ .

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Limitation of the probabilistic model: Safety or Reachability automata always have cost 0. Only ergodic components matter in the long run.

## Sensing cost of a regular language

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On finite words, the optimal sensing cost of a language is always reached by its minimal automaton.

 $\rightarrow$  Sensing as a complexity measure is not interesting on finite words, coincides with size.

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#### Theorem

The sensing cost of an  $\omega$ -regular language is the one of its residual automaton.

#### **Corollary**

Computing the sensing cost of an  $\omega$ -regular language is in **PTime**.

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- Idea of the proof of general interest: one can "ignore" the input for arbitrary long periods and still recognize the language.

### **Conclusion**

#### On-going work

- Minimally-sensing transducer for safety specifications (exponential)
- Alternative definitions for
  - Safety languages
  - Transient components

#### Future work:

- Cost of realizing for parity specifications
- Precise study of the trade-off between different complexity measures