

The theory of regular cost functions.

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01-05-2013

Introduction

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Which problems can be answered by an algorithm ?

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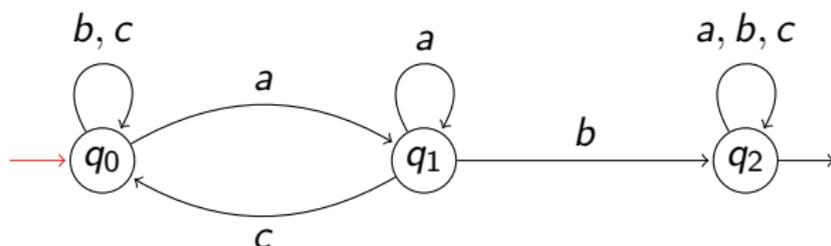
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Toolbox to decide many problems arising naturally.
Verification of systems can be done automatically.
Theoretical and practical advantages.

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Theoretical and practical advantages.
- **Problem:**
Decidability is still open for some automata-related problems.

- 1 Automata theory
- 2 Regular Cost Functions
- 3 Contributions of the thesis
- 4 Zoom: Aperiodic Cost Functions

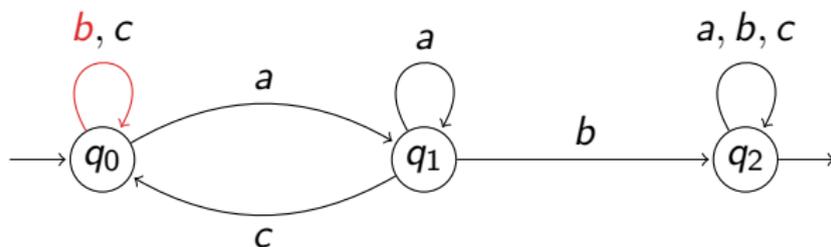
Finite Automaton



A word $u \in \mathbb{A}^*$ is **accepted** by \mathcal{A} if there is an accepting path labeled by u :

Example : Accepting path for the word $babbc$.

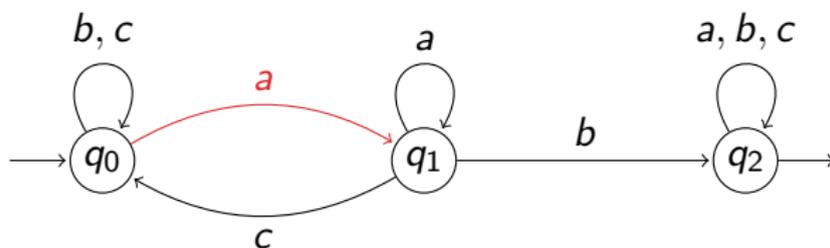
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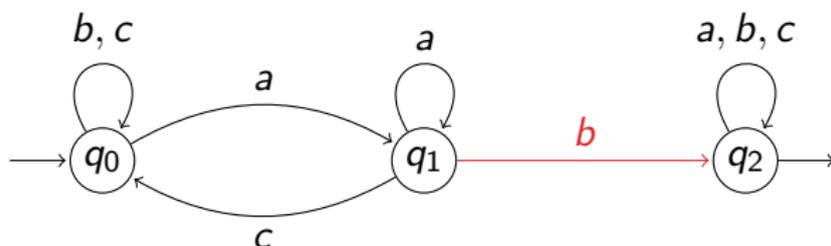
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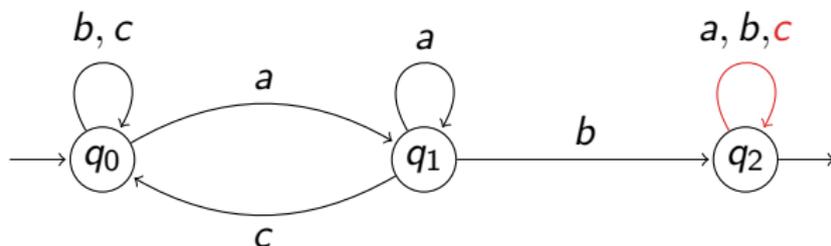
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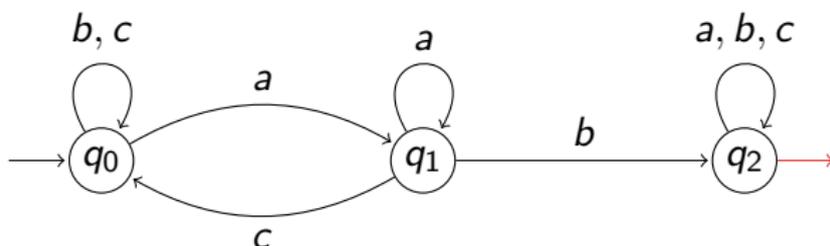
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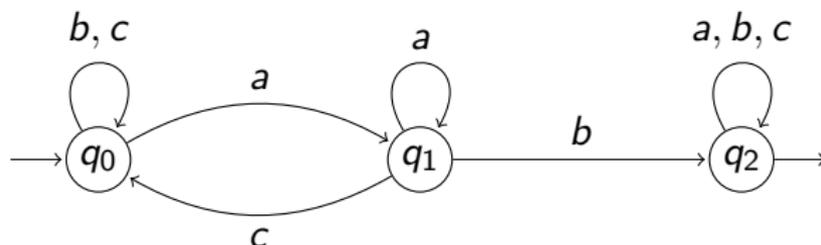


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The **language recognized** by \mathcal{A} is the set $L \subseteq \mathbb{A}^*$ of words accepted by \mathcal{A} .

Descriptions of a language

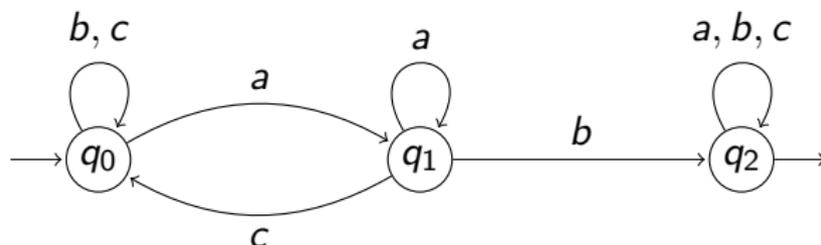


Language recognized : $L_{ab} = \{\text{words containing } ab\}$.

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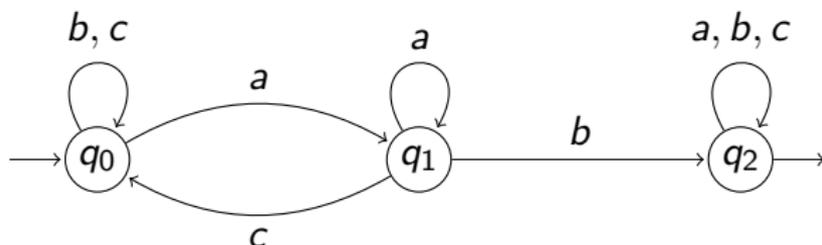


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- **Regular expression** : $\mathbb{A}^* ab \mathbb{A}^*$,
- **Logical sentence (MSO)** : $\exists x \exists y a(x) \wedge b(y) \wedge (y = Sx)$.
- **Finite monoid** : $M = \{1, a, b, c, ba, 0\}$, $P = \{0\}$
 $ab = 0$, $aa = ca = a$, $bb = bc = b$, $cc = ac = cb = c$

Regular Languages

All these formalisms are effectively equivalent.

$a^n b^n$

Regular Languages

Expressions

MSO

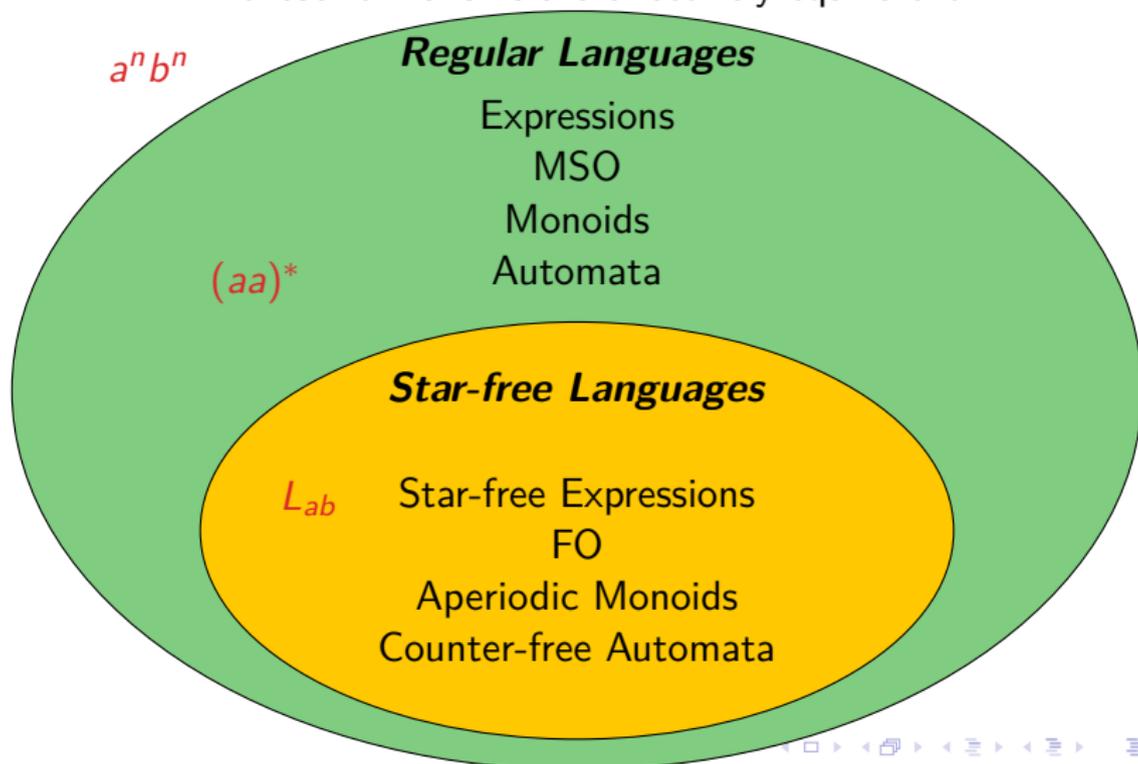
Monoids

Automata

$(aa)^*$

Regular Languages

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Historical motivation

Given a class of languages \mathcal{C} , is there an algorithm which given an automaton for L , decides whether $L \in \mathcal{C}$?

Theorem (Schützenberger 1965)

It is decidable whether a regular language is star-free, thanks to the equivalence with aperiodic monoids.

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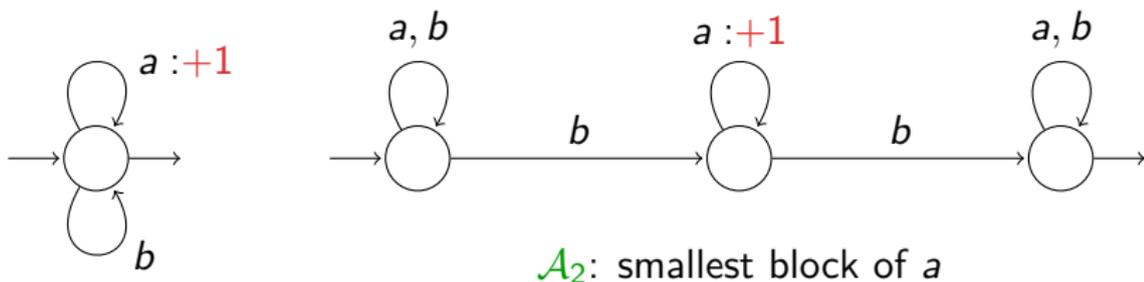
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Finite Power Problem: Given L , is there n such that
$$(L + \varepsilon)^n = L^* ?$$

There is no known algebraic characterization,
other technics are needed to show decidability.

Distance Automata



Unbounded: There are words with arbitrarily large value.

Deciding **Boundedness** for distance automata \Rightarrow solving finite power problem.

Theorem (Hashiguchi 82, Kirsten 05)

Boundedness is decidable for distance automata.

Problems solved using counters

- **Finite Power** (finite words) [Simon '78, Hashiguchi '79]

Is there n such that $(L + \varepsilon)^n = L^*$?

- **Fixed Point Iteration** (finite words)

[Blumensath+Otto+Weyer '09]

Can we bound the number of fixpoint iterations in a MSO formula ?

- **Star-Height** (finite words/trees)

[Hashiguchi '88, Kirsten '05, Colcombet+Löding '08]

Given n , is there an expression for L , with at most n nesting of Kleene stars?

- **Parity Rank** (infinite trees)

[reduction in Colcombet+Löding '08, decidability open, deterministic input Niwinski+Walukiewicz '05]

Given $i < j$, is there a parity automaton for L using ranks $\{i, i + 1, \dots, j\}$?

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Theory of Regular Cost Functions

Aim: General framework for previous constructions.

- Generalize from languages $L : \mathbb{A}^* \rightarrow \{0, 1\}$
to functions $f : \mathbb{A}^* \rightarrow \mathbb{N} \cup \{\infty\}$
- Accordingly generalize automata, logics, semigroups, in order to obtain a **theory of regular cost functions**, which behaves as well as possible.
- Obtain decidability results thanks to this new theory.

Cost automata over words

Nondeterministic finite-state automaton \mathcal{A}

+ **finite set of counters**

(initialized to 0, values range over \mathbb{N})

+ **counter operations on transitions**

(increment I, reset R, check C, no change ε)

Semantics: $\llbracket \mathcal{A} \rrbracket : \Sigma^* \rightarrow \mathbb{N} \cup \{\infty\}$

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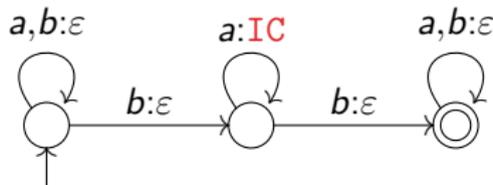
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$val_B(\rho) := \max$ checked counter value during run ρ

$\llbracket \mathcal{A} \rrbracket_B(u) := \min\{val_B(\rho) : \rho \text{ is an accepting run of } \mathcal{A} \text{ on } u\}$

Example

$\llbracket \mathcal{A} \rrbracket_B(u) = \min$ length of block of a 's surrounded by b 's in u



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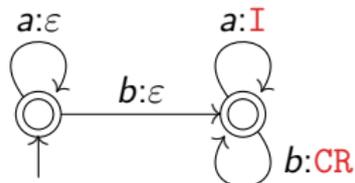
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Boundedness relation

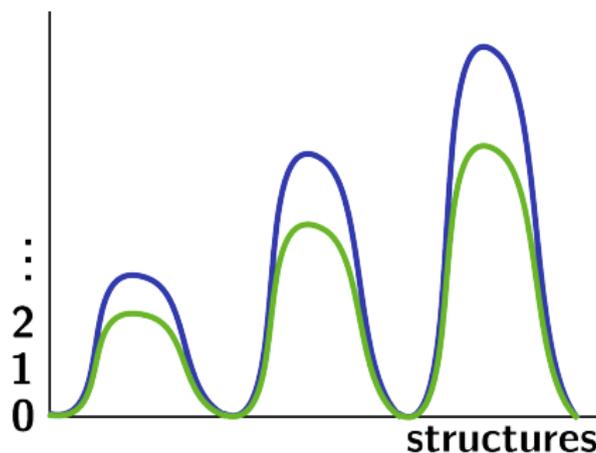
" $[[\mathcal{A}]] = [[\mathcal{B}]]$ ": undecidable [Krob '94]

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“ $\llbracket \mathcal{A} \rrbracket \approx \llbracket \mathcal{B} \rrbracket$ ” : decidable on words

[Colcombet '09, following Bojányczyk+Colcombet '06]
for all subsets U , $\llbracket \mathcal{A} \rrbracket(U)$ bounded iff $\llbracket \mathcal{B} \rrbracket(U)$ bounded



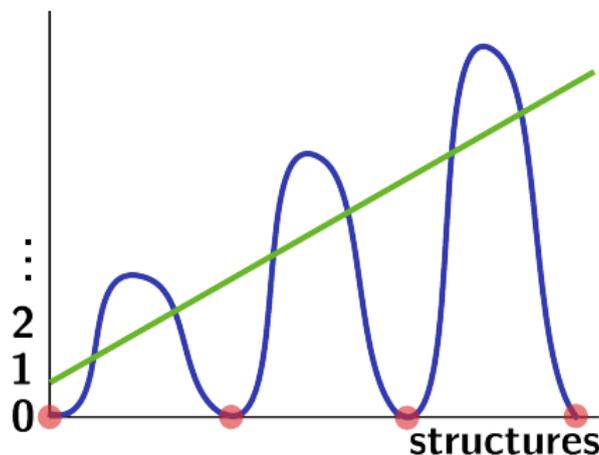
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$\llbracket \mathcal{A} \rrbracket \neq \llbracket \mathcal{B} \rrbracket$

Therefore we always identify two functions if they are bounded on the same sets.

Example

For any function f , we have $f \approx 2f \approx \exp(f)$.

But $(u \mapsto |u|_a) \not\approx (u \mapsto |u|_b)$, as witnessed by the set a^* .

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Theorem (Colcombet '09, following Hashiguchi, Leung, Simon, Kirsten, Bojańczyk+Colcombet)

Cost automata \Leftrightarrow Cost logics \Leftrightarrow Stabilisation monoids.

For some suitable models of Cost Logics and Stabilisation Monoids, extending the classical ones.

Boundedness decidable.

All these equivalences are only valid up to \approx .

It provides a toolbox to decide boundedness problems.

Languages as cost functions

A language L is represented by its characteristic function

$$\chi_L(u) = \begin{cases} 0 & \text{if } u \in L \\ \infty & \text{if } u \notin L \end{cases}$$

If \mathcal{A} is a classical automaton for L , then $\llbracket \mathcal{A} \rrbracket_B = \chi_L$ and $\llbracket \mathcal{A} \rrbracket_S = \chi_{\bar{L}}$. Switching between B and S is the generalization of **language complementation**.

Cost function theory strictly extends language theory.

All theorems on cost functions are in particular true for languages.

Goal of the thesis: Studying cost function theory, and generalise known theorems from languages to cost functions.

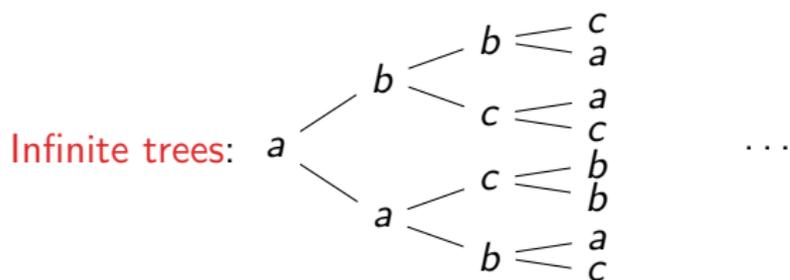
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Contributions of the thesis

Input structures:

Finite words: *accba*

Infinite words: *abaabaccbaba...*



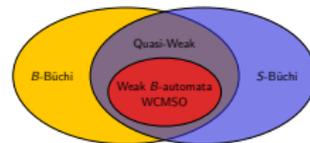
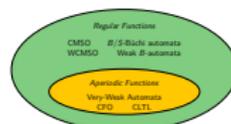
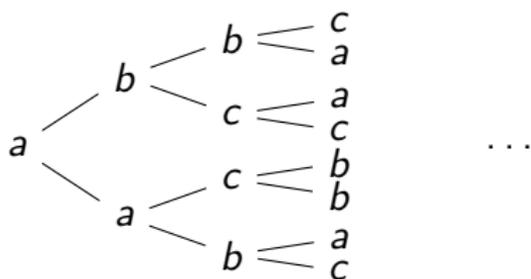
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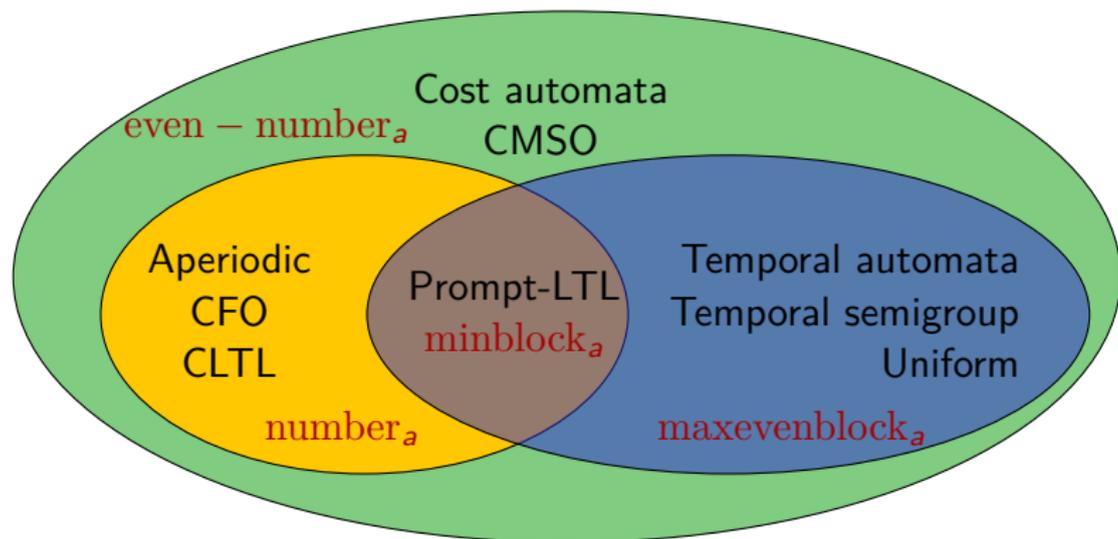
Infinite trees:



Different kinds of results:

- Generalisation of language notions and theorems,
- Study of classes specific to cost functions,
- Reduction of classical decision problems to boundedness problems.

Cost Functions on finite words



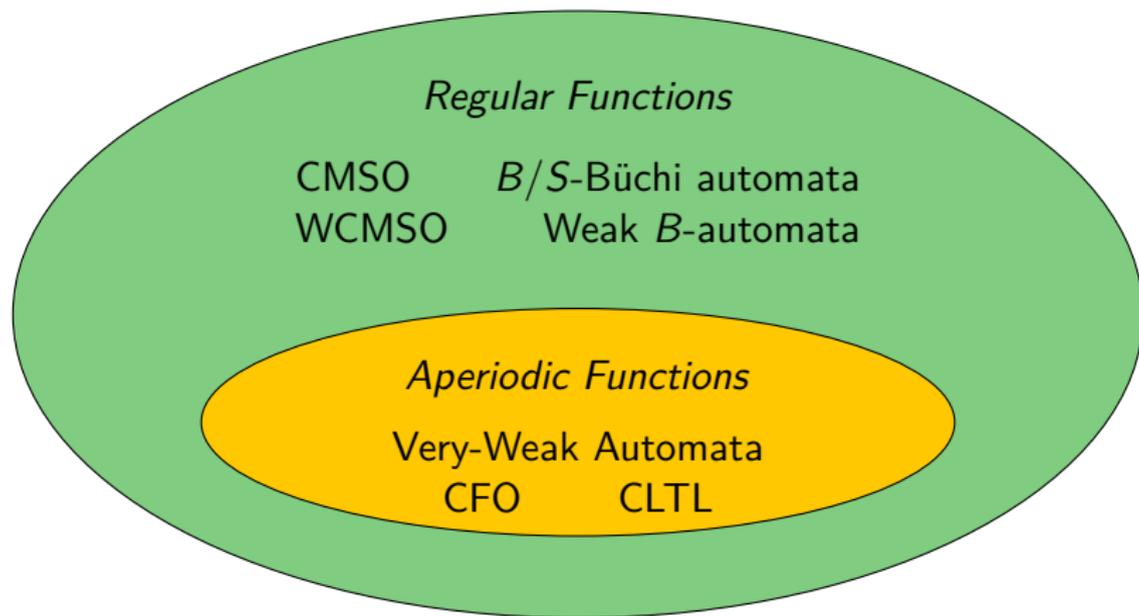
Decidability of membership and effectiveness of translations

[Colcombet+K.+Lombardy ICALP '10, K. STACS '11].

Generalization of Myhill-Nerode Equivalence [K. STACS '11].

Boundedness of CLTL is PSPACE-complete [Submitted to LMCS].

Cost Functions on infinite words



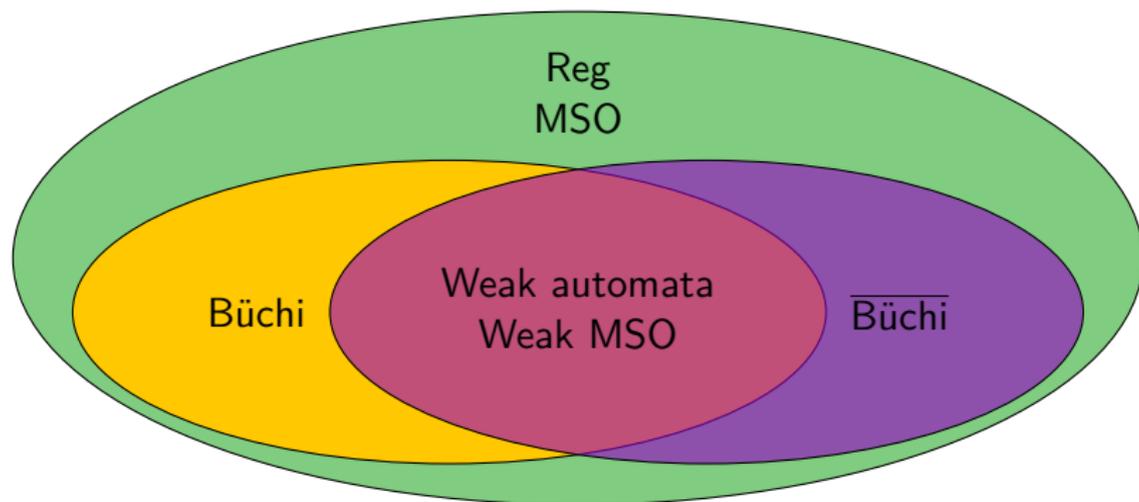
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Languages on infinite trees

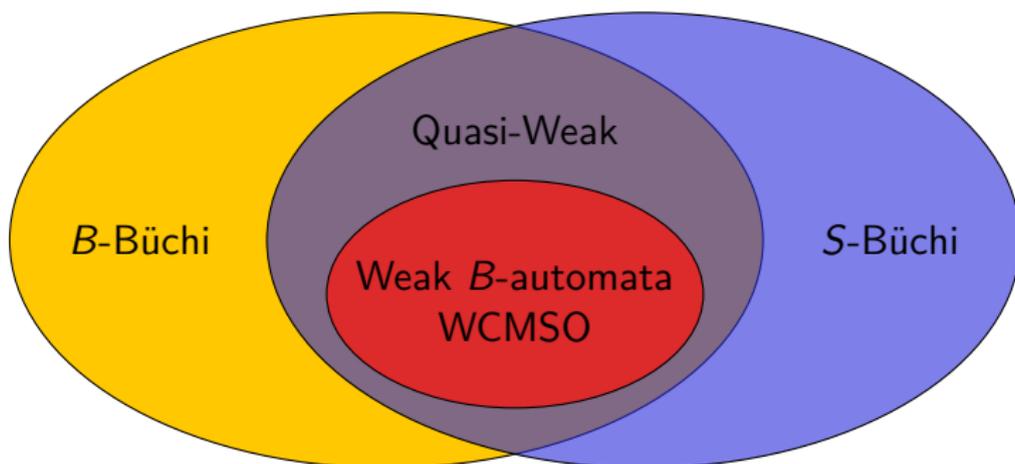
Theorem (Rabin 1970, Kupferman + Vardi 1999)

L recognizable by an alternating weak automaton \Leftrightarrow

L recognizable by WMSO \Leftrightarrow there are Büchi automata \mathcal{U} and \mathcal{U}' such that $L = L(\mathcal{U}) = \overline{L(\mathcal{U}')}$.



Cost functions on infinite trees



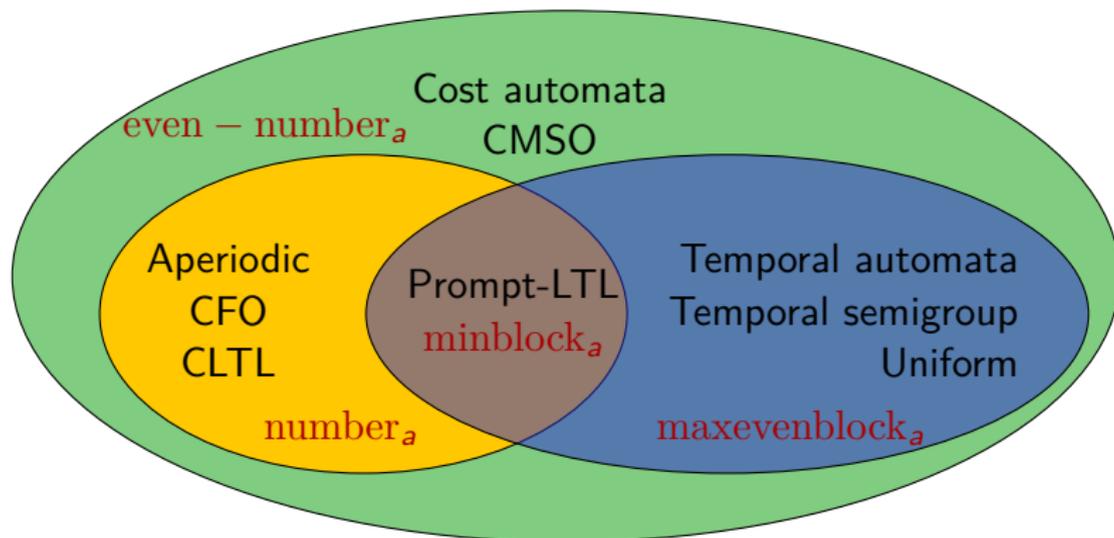
Decidability of boundedness for Quasi-Weak automata. [K.+Vanden Boom, FSTTCS '11].

If \mathcal{A} is a Büchi automaton, it is decidable whether $L(\mathcal{A})$ is weak [submitted to CSL '13].

Logic for the Quasi-Weak class.

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Cost Functions on finite words



Logics on Finite Words

- **First-Order Logic (FO)**: we quantify over positions in the word.

$$\varphi := a(x) \mid x \leq y \mid \neg\varphi \mid \varphi \vee \psi \mid \exists x\varphi$$

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- **MSO**: FO with quantification on sets, noted X, Y .

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- **MSO**: FO with quantification on sets, noted X, Y .
- **Linear Temporal Logic (LTL)** over \mathbb{A}^* :

$$\varphi := a \mid \Omega \mid \neg\varphi \mid \varphi \vee \psi \mid \mathbf{X}\varphi \mid \varphi \mathbf{U}\psi$$

$$\varphi \mathbf{U}\psi: \quad \begin{array}{cccccccccccc} \varphi & \psi \\ a_0 & a_1 & a_2 & a_3 & a_4 & a_5 & a_6 & a_7 & a_8 & a_9 & a_{10} \end{array}$$

Future operators **G** (Always) and **F** (Eventually).

Example: To describe L_{ab} , we can write $\mathbf{F}(a \wedge \mathbf{X}b)$.

Generalisation: cost LTL

- **CLTL** over \mathbb{A}^* :

$$\varphi := a \mid \Omega \mid \varphi \wedge \psi \mid \varphi \vee \psi \mid \mathbf{X}\varphi \mid \varphi \mathbf{U}\psi \mid \varphi \mathbf{U}^{\leq N}\psi$$

Negations pushed to the leaves.

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- $\varphi \mathbf{U}^{\leq N}\psi$ means that ψ is true in the future, and φ is false at most N times in the mean time.

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- “Error variable” N is unique, shared by all occurrences of $\mathbf{U}^{\leq N}$.
- $\mathbf{G}^{\leq N}\varphi$: φ is false at most N times in the future ($\varphi \mathbf{U}^{\leq N}\Omega$).

Generalisation : Cost FO and Cost MSO

- **CFO** over \mathbb{A}^* :

$$\varphi := a(x) \mid x = y \mid x < y \mid \varphi \wedge \psi \mid \varphi \vee \psi \mid \exists x \varphi \mid \forall x \varphi \mid \forall^{\leq N} x \varphi$$

Negations pushed to the leaves.

- As before, N unique free variable.
- $\forall^{\leq N} x \varphi(x)$ means φ is false on at most N positions.
- **CMSO** extends CFO by allowing quantification over sets.

Semantics of Cost Logics

From formula to cost function:

Formula $\varphi \longrightarrow$ cost function $\llbracket \varphi \rrbracket : \mathbb{A}^* \rightarrow \mathbb{N} \cup \{\infty\}$, defined by

$$\llbracket \varphi \rrbracket(u) = \inf\{n \in \mathbb{N} : \varphi \text{ is true over } u \text{ with } n \text{ as error value}\}$$

Example with the alphabet $\{a, b\}$

- $\text{number}_a = \llbracket \mathbf{G}^{\leq N} b \rrbracket = \llbracket \forall^{\leq N} x \ b(x) \rrbracket$.

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- $\text{maxblock}_a = \llbracket \mathbf{G}(\perp \mathbf{U}^{\leq N}(b \vee \Omega)) \rrbracket$
 $= \llbracket \forall X \ \text{block}_a(X) \Rightarrow (\forall^{\leq N} x \ x \notin X) \rrbracket$.

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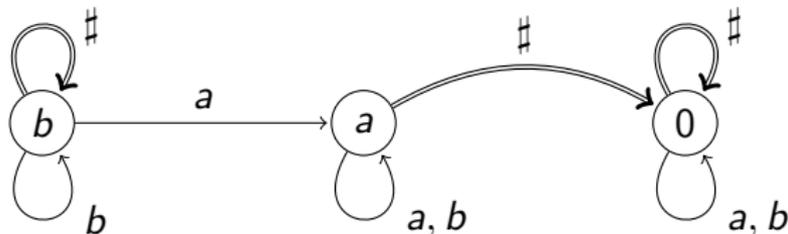
Stabilisation monoids

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Example: Stabilisation Monoid for number a

$M = \{b, a, 0\}$, $P = \{a, b\}$,

b : “no a ”, a : “a little number of a ”, 0 : “a lot of a ”.



Cayley graph

Aperiodic Monoids

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Theorem (McNaughton-Papert, Schützenberger, Kamp)

Aperiodic Monoids \Leftrightarrow *FO* \Leftrightarrow *LTL* \Leftrightarrow *Star-free Expressions*.

We want to generalise this theorem to cost functions.

The problems are:

- No complementation \Rightarrow No Star-free expressions.
- Deterministic automata are strictly weaker.
- Heavy formalisms (semantics of stabilisation monoids).
- New quantitative behaviours.
- Original proofs already hard.

Aperiodic cost functions

Theorem (K. STACS 2011)

Aperiodic stabilisation monoid \Leftrightarrow CLTL \Leftrightarrow CFO.

Proof Ideas:

- Generalisation of Myhill-Nerode \Rightarrow Syntactic object.
- Induction on $(|M|, |\mathbb{A}|)$.
- Extend functions to sequences of words.
- Use bounded approximations.
- Extend CLTL with Past operators, show Separability.

