

On the Parameterized Complexity of Red-Blue Points Separation

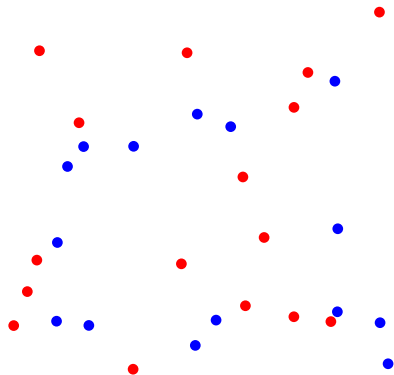
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September 6, 2017, IPEC, Vienna

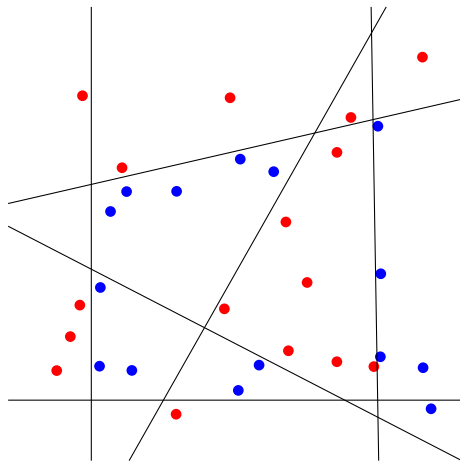


Red-Blue Separation



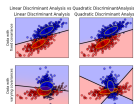
Given a set \mathcal{R} of red points and \mathcal{B} of blue points...

Red-Blue Separation



...find at most k lines making each cell monochromatic.

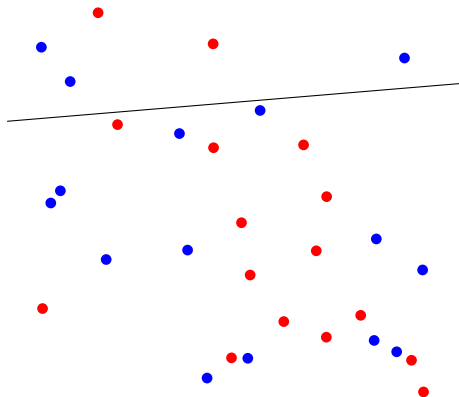
A few words on the problem



- ▶ motivated by machine learning applications
- ▶ natural geometric separation problem
- ▶ NP-hard [Megiddo '88]
- ▶ APX-hard for the variant with axis-parallel lines...
- ▶ ...with an LP-based 2-approximation [Calinescu et al. '05]
- ▶ we will forbid the selected lines to contain any input point

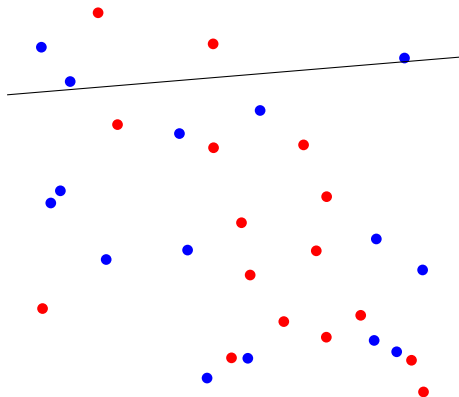
Discretization of the problem

There is an easy $(4n^2)^k = n^{O(k)}$ -time algorithm



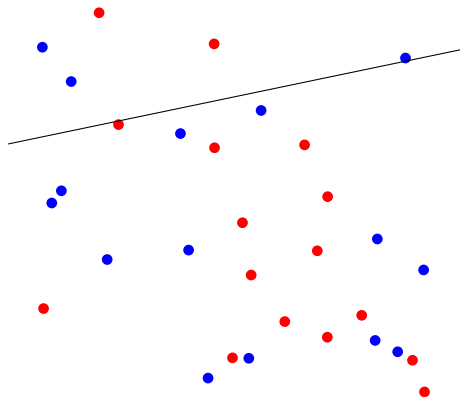
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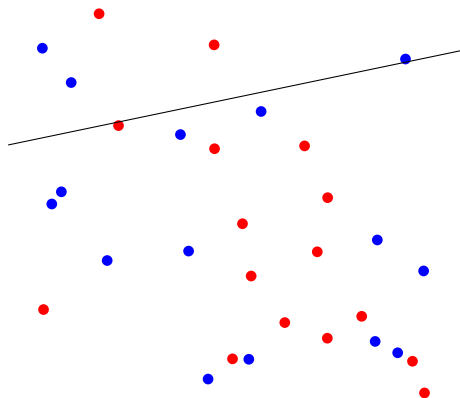
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$O(n)$ for $k = 1$ and $O(n \log n)$ for $k = 2$ [Hurtado et al. '04].

Parameterized complexity?



A line arrangement created by k lines has $O(k^2)$ cells.

YES-instances are well-structured:

decomposable into $f(k) = O(k^2)$ convex monochromatic regions.

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Maybe FPT algorithm based on a kernel...

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Our main result

Red-Blue Separation cannot be solved in time $f(k)n^{o(k/\log k)}$ unless the ETH fails.

It almost matches the brute-force $n^{O(k)}$:

Red-Blue Separation is *not* part of those geometric problems solvable in $n^{O(\sqrt{k})}$.

Intermediate problems worth knowing

...to design parameterized lower bounds of geometric problems

- ▶ Grid Tiling [Marx '05] → no $f(k)n^{o(\sqrt{k})}$ for several geometric packing and covering problems
- ▶ Many classical optimisation problems on multiple-interval graphs [Jiang '10, Jiang and Zhang '12]: typically **W[1]-hardness** on (unit) 2-track interval and (unit) 2-interval graphs

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The latter can potentially give $f(k)n^{o(k/\log k)}$ -lower bounds (and confirm the absence of square-root phenomenon)

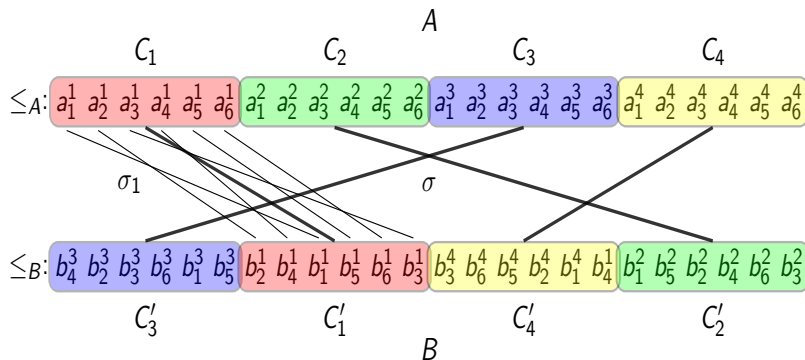
Structured 2-Track Hitting Set

2-elements: $\forall i \in [t], \forall j \in [k] (a_i^j, b_i^j)$

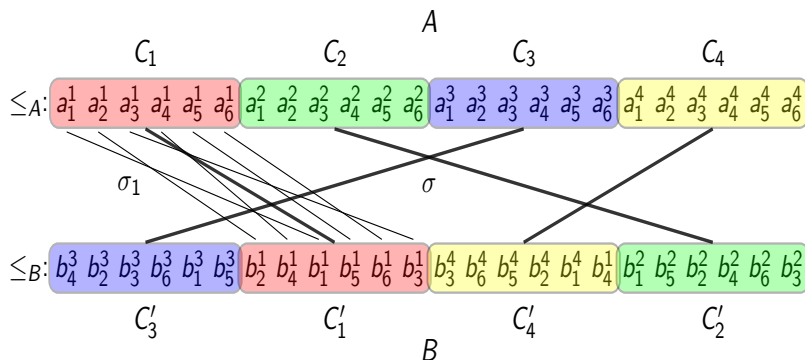
Total orderings of the a -elements and the b -elements

Sets: A -intervals and B -intervals

Goal: Find k 2-elements that hits all the sets



Structured 2-Track Hitting Set



Theorem (B. & Miltzow, ESA'16)

Unless the ETH fails, STRUCTURED 2-TRACK HITTING SET cannot be solved in time $f(k)n^{o(k/\log k)}$.

Deconstructing Structured 2-Track Hitting Set

To reduce from this problem, we need to encode:

- ▶ **intervals**; usually easy
- ▶ the **interclass permutation** σ (on k elements)
- ▶ **intraclasses permutations** σ_j (on $t \gg k$ elements); trickier

Deconstructing Structured 2-Track Hitting Set

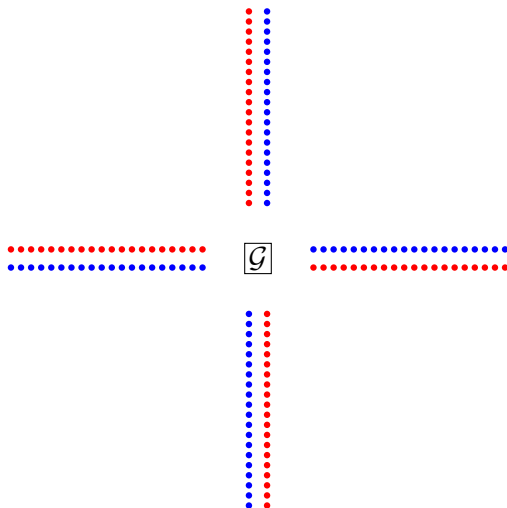
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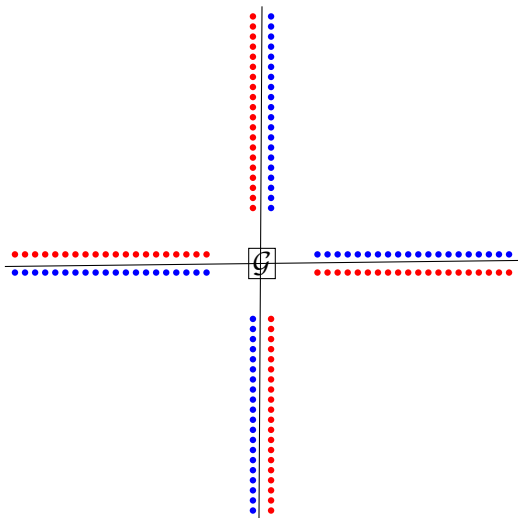
Why such an intermediate problem is convenient?

The non geometricity is pushed to **mere permutations**;
easier to simulate than
arbitrary binary relations (reduction from a graph problem) or
arbitrary ternary relations (reduction from a 3-CSP)

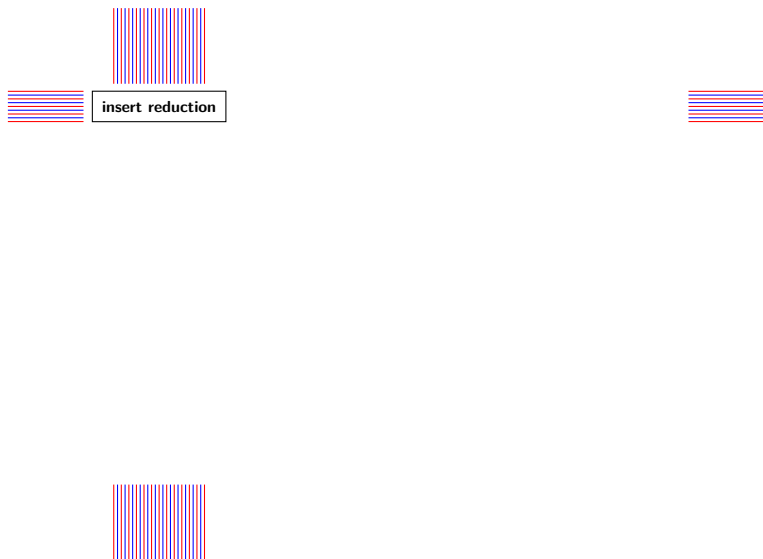
Enforcing near axis-parallelism with long alleys



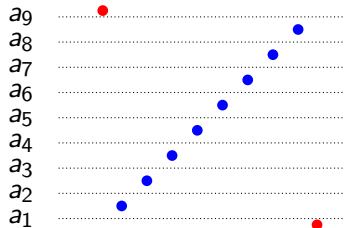
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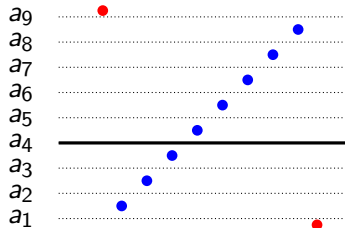
How we will in fact use them



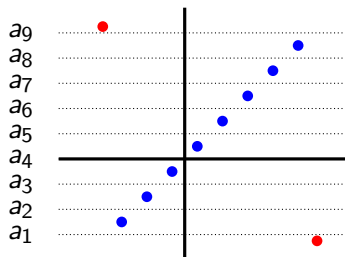
Encoding of an interval



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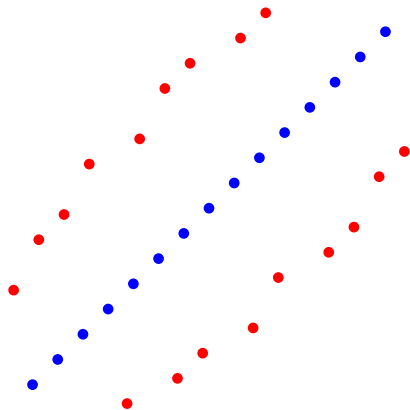


Encoding of an interval and choice propagation

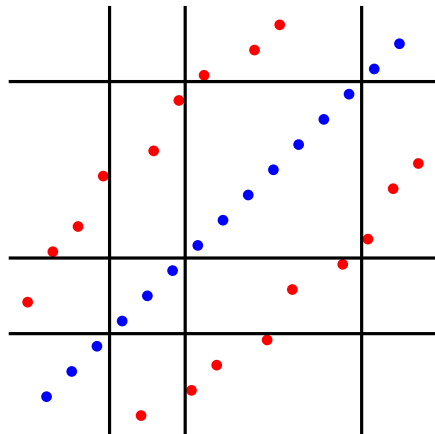


only solutions with a budget of 2 almost axis-parallel lines

Intervals put together to form the whole track



Intervals put together to form the whole track



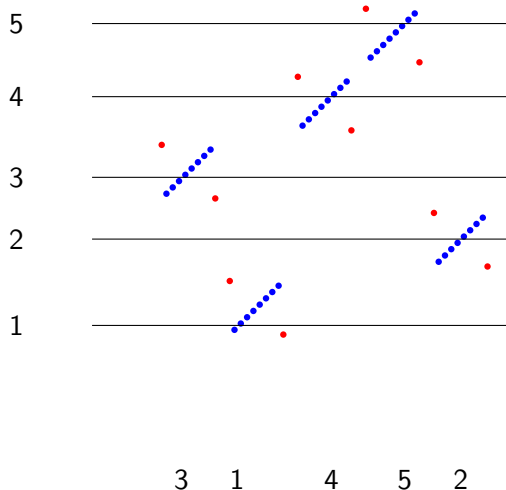
budget of k horizontal and k vertical lines

Encoding the interclass permutation σ

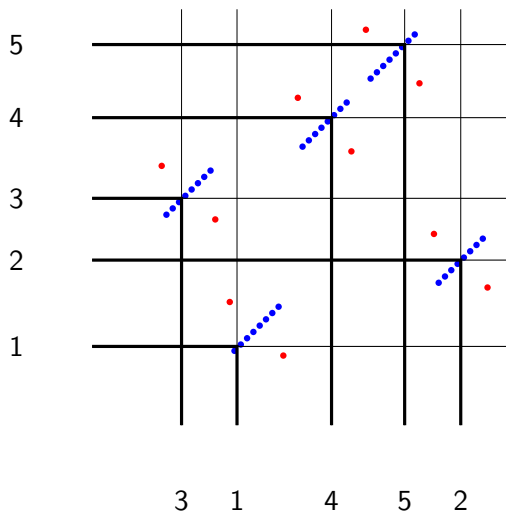


3 1 4 5 2

Encoding the interclass permutation σ



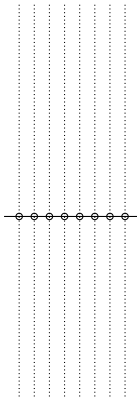
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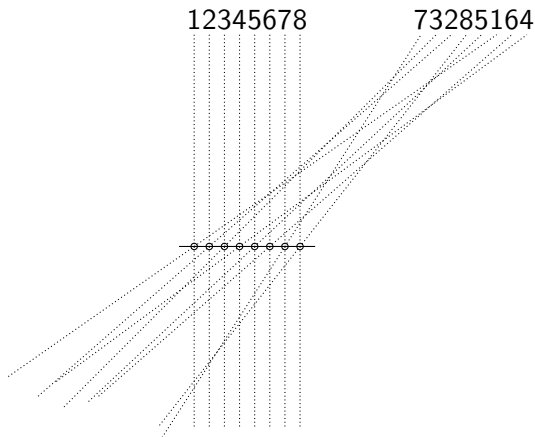
Half-encoding the intraclass permutation σ_j

12345678

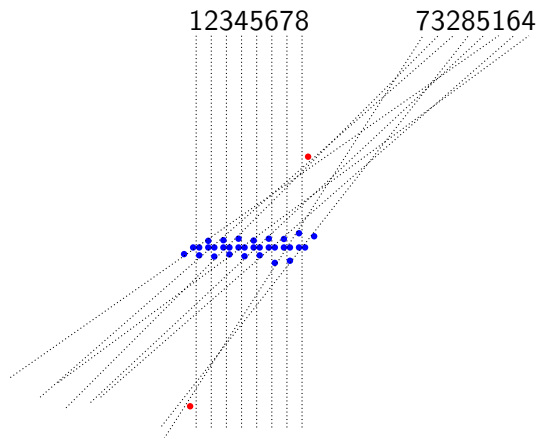
73285164



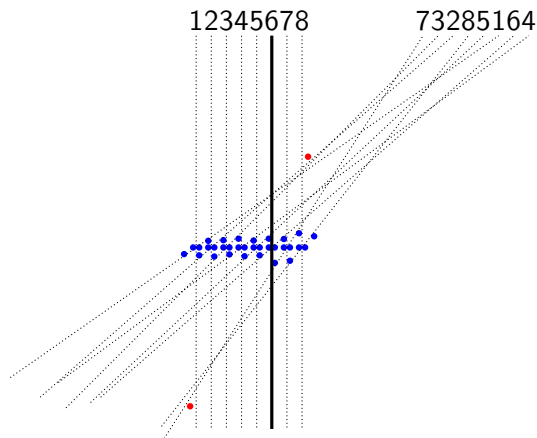
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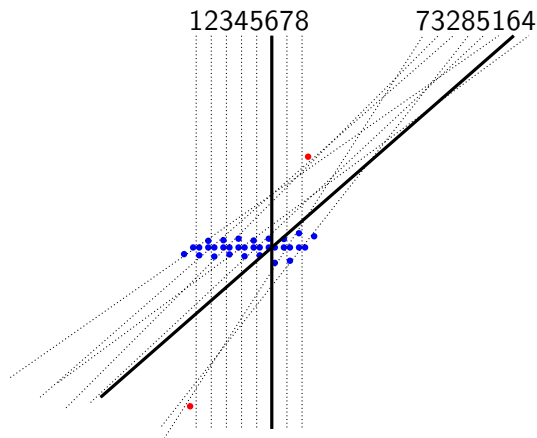
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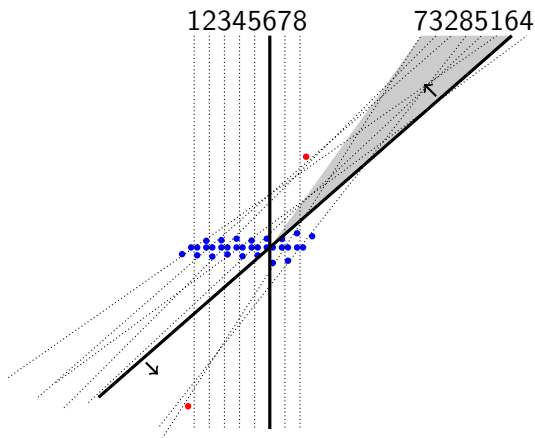


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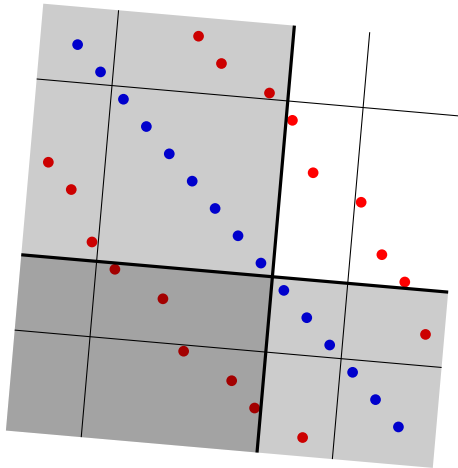
A budget of one line forces a line with the correct slope

Half-encoding the intraclass permutation σ_j



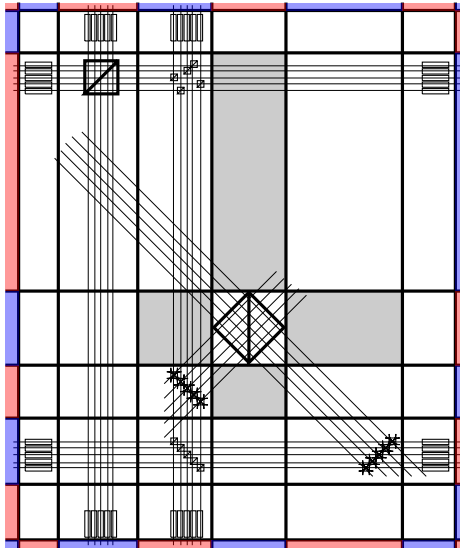
A budget of one line forces a line with the correct slope or higher

Simple fix: use two half-encodings; the second track



Gray areas correspond to possible lines; the only way to make the two lines meet at the diagonal is to take the boundary lines

The full picture

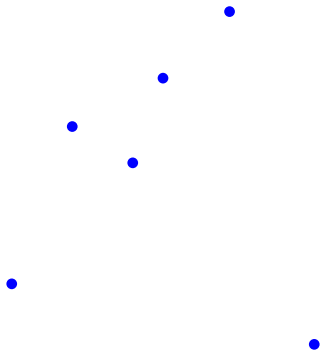


An FPT algorithm for the Axis-Parallel case¹

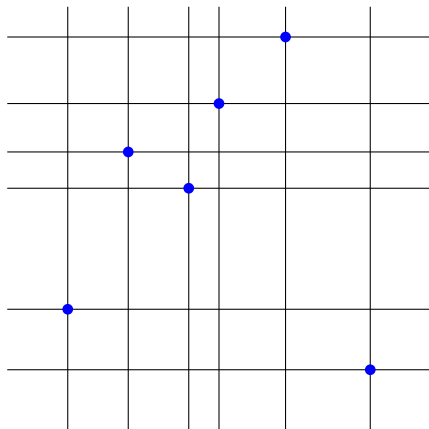


Axis-Parallel Red-Blue Separation can be solved in $O^*(9^{|\mathcal{B}|})$.

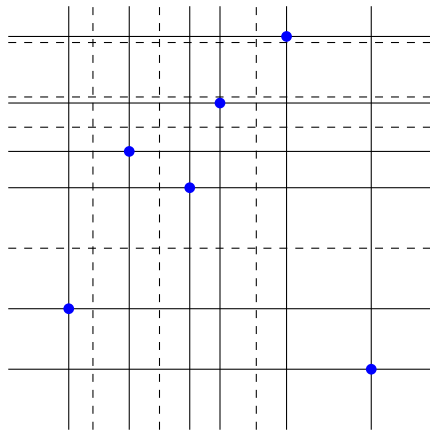
¹with a larger parameter



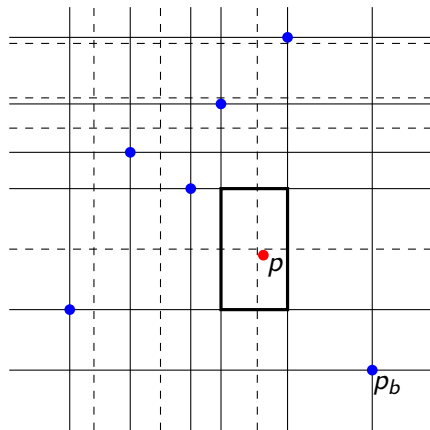
The number of blue points $k := |\mathcal{B}|$ is *small*



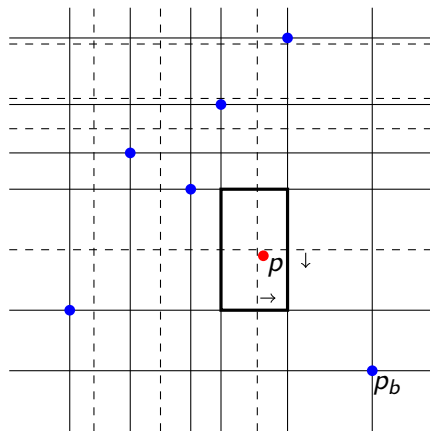
Imagine the $2k$ axis-parallel lines crossing them



Guess in time $3^{2(k+1)}$ how many lines of a solution each of the $k + 1$ rows and the $k + 1$ columns contain: it can be 0, 1, or 2

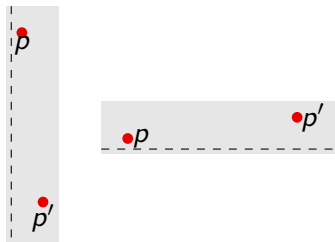


The problematic case is with 1: the lines are only *floating*



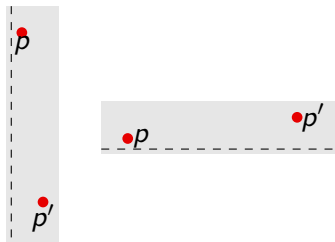
Each of the potential conflict can be expressed as a 2-clause:
VerticalLine3RightOfp or HorizontalLine1Belowp

Consistency can be ensured with 2-clauses



VerticalLine i RightOf p' \rightarrow VerticalLine i RightOf p
HorizontalLine j Below p \rightarrow HorizontalLine j Below p'

Consistency can be ensured with 2-clauses



VerticalLine i RightOf p' \rightarrow VerticalLine i RightOf p
HorizontalLine j Below p \rightarrow HorizontalLine j Below p'

For each of the $3^{2(k+1)}$ guesses, conclude by solving a 2-SAT instance in linear time.

Open questions

The algorithm breaks with a third direction, or a third dimension, or with the natural parameter

- ▶ Is Axis-Parallel Red-Blue Separation FPT parameterized by k the number of lines?
- ▶ Is Red-Blue Separation with a fixed number of allowed slopes FPT in $|\mathcal{B}|$? in k ?
- ▶ What happens in higher dimensions?

Best candidate to be FPT: Red-Blue Separation with 3 allowed slopes and parameterized by $|\mathcal{B}|$.