

Multilevel Physics Informed Neural Networks (MPINNs)

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Joint work with:

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The context

The problem: numerical approximation of PDE's solutions.

- ▶ *Classical approaches:* discretization and multigrid methods (MG)
- ▶ *New advances in machine learning:* Physics Informed Neural Networks (PINNs)

Our objective:

Transfer the advantages of the first approach to the second.

Outline

Multigrid methods (MG)

Physics Informed Neural Networks (PINNs)

Multilevel PINNs (MPINNs)

Outline

Multigrid methods (MG)

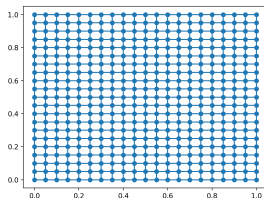
Physics Informed Neural Networks (PINNs)

Multilevel PINNs (MPINNs)



The numerical solution of PDEs

- ▶ Classically PDEs are **discretized** on a grid using finite differences or finite elements
- ▶ The resulting **linear system** $Au = f$ is solved using a fixed point iterative method (Gauss-Siedel or Jacobi)
- ▶ The size of the grids impacts the **size of the system** and the **accuracy** of the solution approximation



The intuition behind multigrid methods

- ▶ Example: $\Delta u = 0$, $v_k(j) = \sin(\frac{kj\pi}{n})$, k -th Fourier mode
- ▶ The **smoothing property**: hard for fixed point iterative methods to reduce the low frequency components of the error

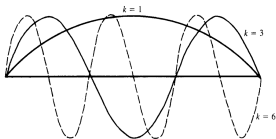
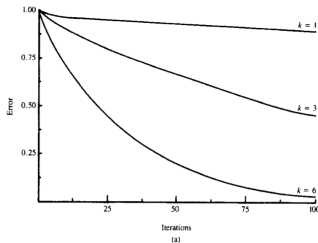


Figure 2.2: The modes $v_j = \sin(\frac{jk\pi}{n})$, $0 \leq j \leq n$, with wavenumbers $k = 1, 3, 6$. The k th mode consists of $\frac{k}{2}$ full sine waves on the interval.



The intuition behind multigrid methods

- ▶ How does a smooth component look like on a coarser grid?

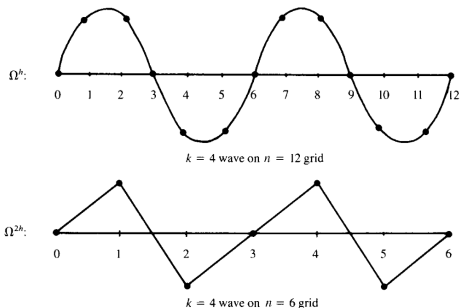
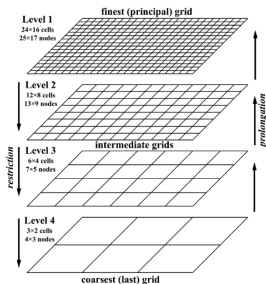


Figure 3.1: Wave with wavenumber $k = 4$ on Ω^h ($n = 12$ points) projected onto Ω^{2h} ($n = 6$ points). The coarse grid “sees” a wave that is more oscillatory on the coarse grid than on the fine grid.

Multigrid methods for PDEs

State-of-the-art methods for PDEs: exploit representation of the problem at different scales



- ▶ Fine scales: eliminate **high frequency** components of the error
- ▶ Coarse scales: eliminate **low frequency** components of the error

Two-level multigrid methods

Consider a linear PDE:

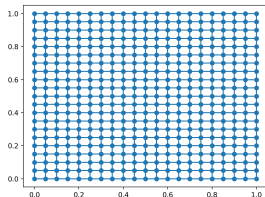
$$Au = f.$$

Consider two discretizations of the same system:

- ▶ Fine grid: $A_h u_h = f_h$
- ▶ Coarse grid: $A_H u_H = f_H$

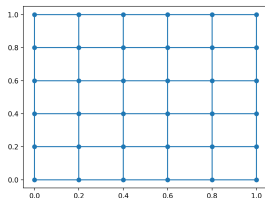
Idea: write the solution u as the sum of a fine and a coarse term:

$$u \sim \underbrace{v_h}_{\in \mathbb{R}^h} + P(\underbrace{e_H}_{\in \mathbb{R}^H}), \quad H < h.$$



$R \downarrow$

$P \uparrow$



Two-level multigrid methods

Update the two components in an **alternate** fashion:

$$u \sim v + e$$

$$r = f - Av$$

$$Ae = r \text{ residual equation}$$

- ▶ Fine level: get v_h by iterating on $A_h u = f_h$
- ▶ Compute $r_h = f - Av_h$ and project $r_H = Rr_h$
- ▶ Coarse level: compute correction: $A_H e_H = r_H$
- ▶ Correct: $v_h \leftarrow v_h + P(e_H)$

Two-level multigrid methods

Update the two components in an **alternate** fashion:

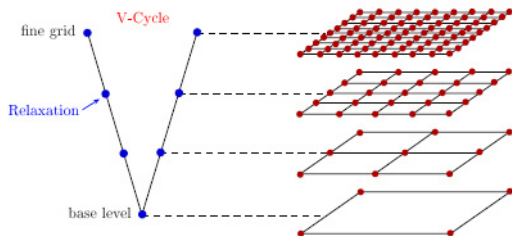
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General multigrid methods



W. Briggs, V. Henson, S. McCormick. A Multigrid Tutorial, SIAM, 2000.

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A new approach for PDEs

A recent development: use neural networks to approximate the solution of a PDE



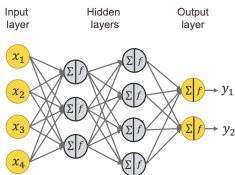
M. Raissi, P. Perdikaris, G. Karniadakis, Physics-informed neural networks: A deep learning framework for solving forward and inverse problems involving nonlinear partial differential equations, 2019.

Why this approach ?

- ▶ Natural approach for **nonlinear** equations
- ▶ Provides **analytic** and continuously differentiable expression of the approximate solution
- ▶ The solution is **meshless**, well suited for problems with **complex geometries**
- ▶ The training is highly **parallelizable** on GPU
- ▶ Allows to alleviate the effect of the **curse of dimensionality**

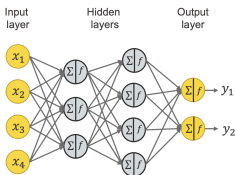


General NN strategy for learning problems



- ▶ Dataset composed of input/output couples (x_i, y_i) , $i = 1, \dots, m$.
- ▶ Loss function $L(\theta; x, y) = \frac{1}{m} \sum_{i=1}^m (NN(x_i, \theta) - y_i)^2 = MSE$
- ▶ The associated minimization problem : $\min_{\theta \in \Theta} L(\theta; x, y)$
- ▶ Optimize by SGD

General NN strategy for learning problems

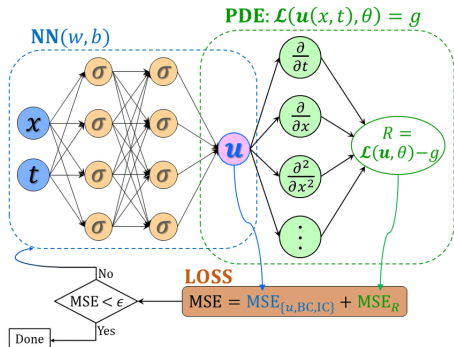


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- ▶ The associated minimization problem : $\min_{\theta \in \Theta} L(\theta; x, y)$
- ▶ Optimize by SGD

How to integrate the physical knowledge in the model?

Physics Informed Neural Networks (PINNs)

$$\mathcal{L}(u(x, t), \theta) = g(x, t) \\ + \text{BC} + \text{IC} \\ \text{in } \Omega \times [0, T]$$

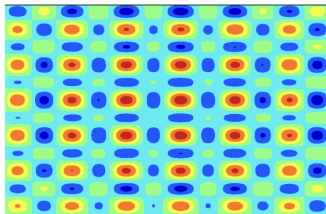


Given x_i, t_i sampled randomly, and $y_i = u^*(x_i, t_i)$,

$$MSE_{\{u, BC, IC\}} = \frac{1}{N_m} \sum_{x_i \in \Omega \cup \partial\Omega, t_i \in [0, T]} (NN(x_i, t_i) - y_i)^2,$$

$$MSE_R = \frac{1}{N_r} \sum_{x_i \in \Omega, t_i \in [0, T]} R(x_i, t_i)^2$$

On the spectral bias of neural networks



On the Spectral Bias of Neural Networks

Nasim Rahaman^{*1,2} Aristide Baratin^{*1} Devansh Arpit¹ Felix Draxler² Min Lin¹ Fred A. Hamprecht²
Yoshua Bengio¹ Aaron Courville¹

WHEN AND WHY PINNs FAIL TO TRAIN: A NEURAL TANGENT KERNEL PERSPECTIVE

A PREPRINT

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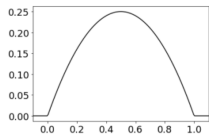
⇒ PINNs are not effective in approximating highly oscillatory solutions

Mscale networks

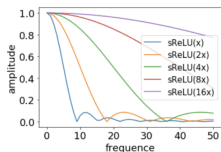


Z.Q. Liu, W. Cai, and Z.Q. John Xu, Multi-scale Deep Neural Network (MscaleDNN) for Solving Poisson-Boltzmann Equation in Complex Domains, 2020

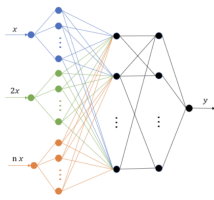
Idea: **simultaneous** training of frequency-selective subnetworks



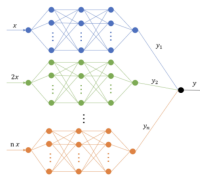
(b) sReLU



(a) sReLU



(a) MscaleDNN-1



(b) MscaleDNN-2

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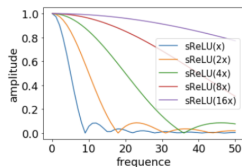
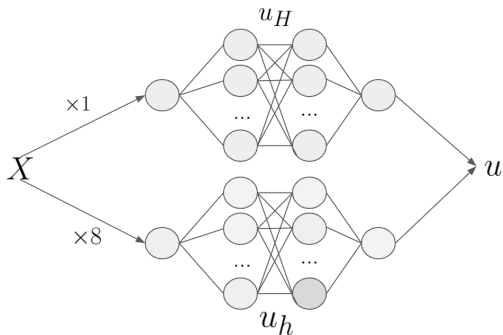
Multilevel PINNs (MPINNs)



Multilevel PINNs: the architecture

Idea: $u_{sol}(x) \sim u_h(\theta_h, x) + u_H(\theta_H, x)$

Also exploit frequency-selective subnetworks



(a) sReLU

Multilevel PINNs: the loss

Problem definition

$$\begin{aligned}\mathcal{L}(u(x)) &= g(x), \quad x \in \Omega, \\ u_{sol}(x) &\sim u_h(\theta_h, x) + u_H(\theta_H, x)\end{aligned}$$

Fine problem

$$MSE_h(\theta_h) = MSE_{R,h}(\theta_h) + MSE_{B,h}(\theta_h)$$

$$MSE_{R,h}(\theta_h) = \|\mathcal{L}(\hat{u}_h(\theta_h) + u_H) - g\|^2$$

$$MSE_{B,h}(\theta_h) = \|\hat{u}_h(\theta_h) + u_H - u\|^2$$

Computed on z_h the **fine sampling**

Coarse problem

$$MSE_H(\theta_H) = MSE_{R,H}(\theta_H) + MSE_{B,H}(\theta_H)$$

$$MSE_{R,H}(\theta_H) = \|\mathcal{L}(\hat{u}_H(\theta_H) + u_h) - g\|^2$$

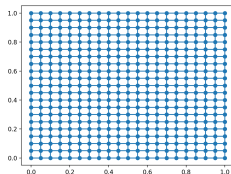
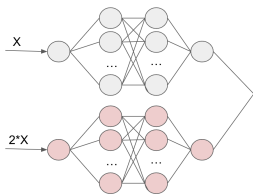
$$MSE_{B,H}(\theta_H) = \|\hat{u}_H(\theta_H) + u_h - u\|^2$$

Computed on z_H the **coarse sampling**

Multilevel PINNs: the training

Algorithm 1 2-level training of PINNs

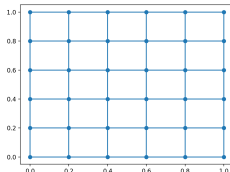
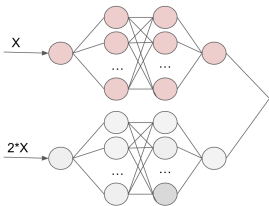
- 1: Freeze coarse-network parameters, unfreeze fine-network parameters
 - 2: **for** $i=1,2,\dots$ **do**
 - 3: Perform ν_1 epochs for the minimization of the fine problem
 - 4: Freeze fine-network parameters, unfreeze coarse-network parameters
 - 5: Perform ν_2 epochs for the minimization of the coarse problem
 - 6: **end for**
 - 7: Return : $u_H + u_h$
-



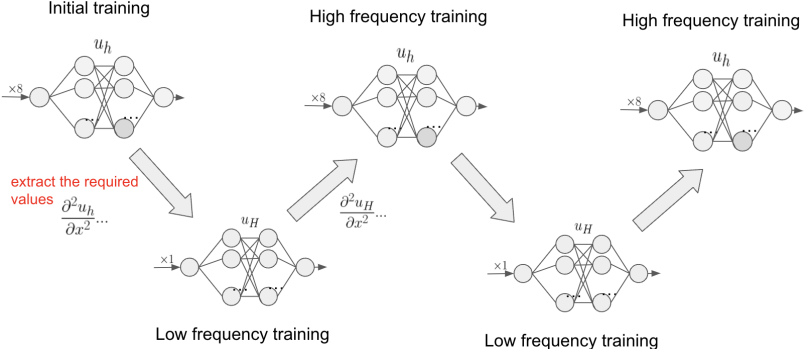
Multilevel PINNs: the training

Algorithm 2 2-level training of PINNs

- 1: Freeze coarse-network parameters, unfreeze fine-network parameters
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 - 3: Perform ν_1 epochs for the minimization of the fine problem
 - 4: Freeze fine-network parameters, unfreeze coarse-network parameters
 - 5: Perform ν_2 epochs for the minimization of the coarse problem
 - 6: **end for**
 - 7: Return : $u_H + u_h$
-

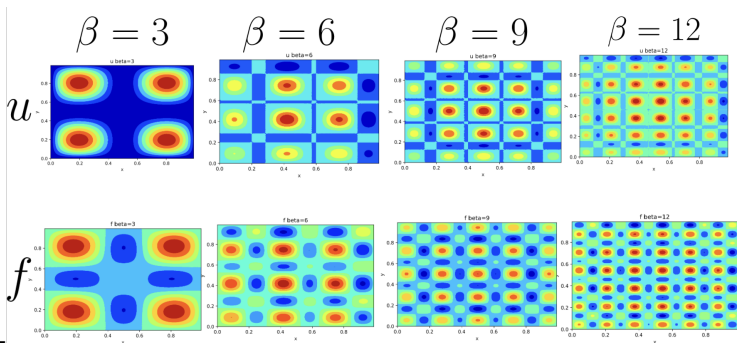


Multilevel PINNs: V-cycles



A simple Poisson problem

- ▶ $\Omega = [0, 1] \times [0, 1]$
- ▶ $\Delta u = f \quad \forall x \in \Omega$
- ▶ $u = 0 \quad \forall x \in \partial\Omega$
- ▶ $u(x, y) = (\sin(\pi x) + \sin(\beta\pi x)) * (\sin(\pi y) + \sin(\beta\pi y))$



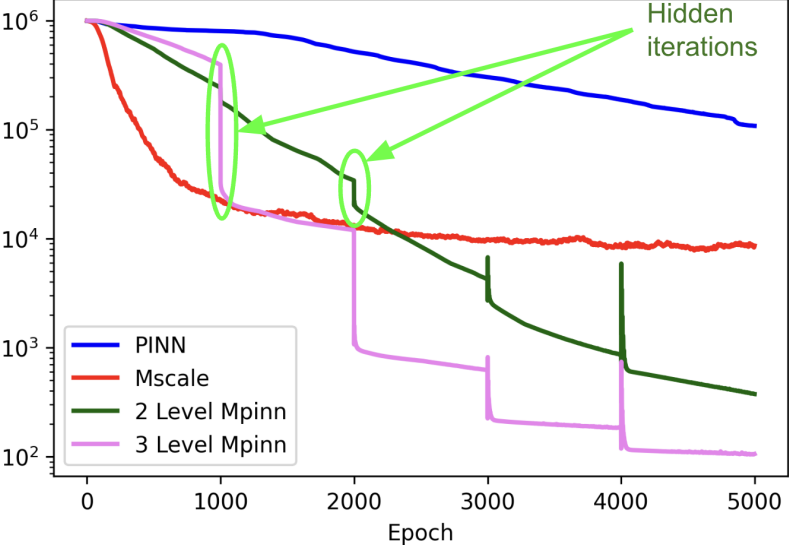
Experimental settings

In what follows:

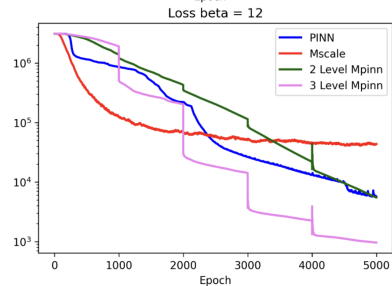
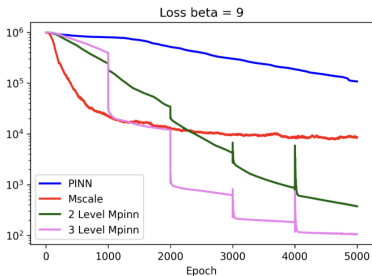
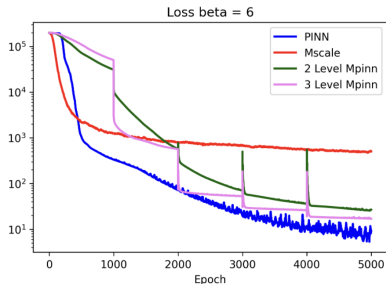
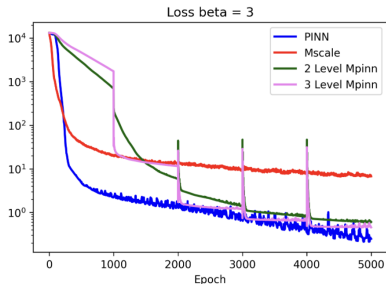
- ▶ The **PINNs** have two hidden layers of 300 neurons each.
- ▶ The **Mscale** have four subnetworks of two hidden layers of 150 neurons each, the input scaling used are 1,2,4 and 8.
- ▶ The **two-level MPINN** is composed of two networks of two hidden layers of 210 neurons each and trained in a **V-cycle** with 1 and 8 input scalings ($\nu_1 = \nu_2 = 1000$).
- ▶ The **three-level MPINN** is composed of three networks of two hidden layers of 150 neurons each and trained in a **V-cycle** with 1,4 and 8 input scalings ($\nu_1 = \nu_2 = \nu_3 = 1000$).
- ▶ The input of all networks is a regular grid sample of 80×80 points
- ▶ In all cases, we plot the median for ten random runs.

Experimental results

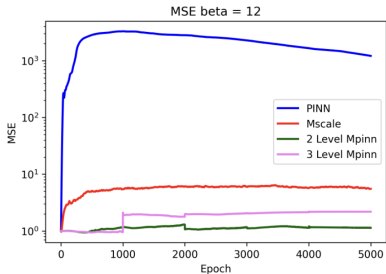
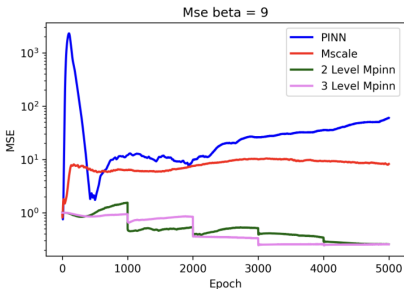
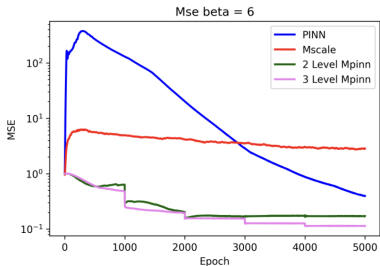
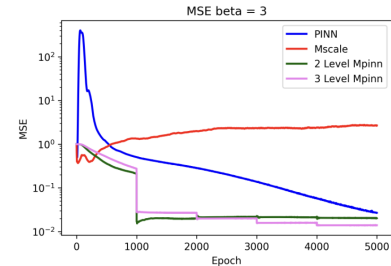
Loss beta = 9



Varying β (the frequency content)

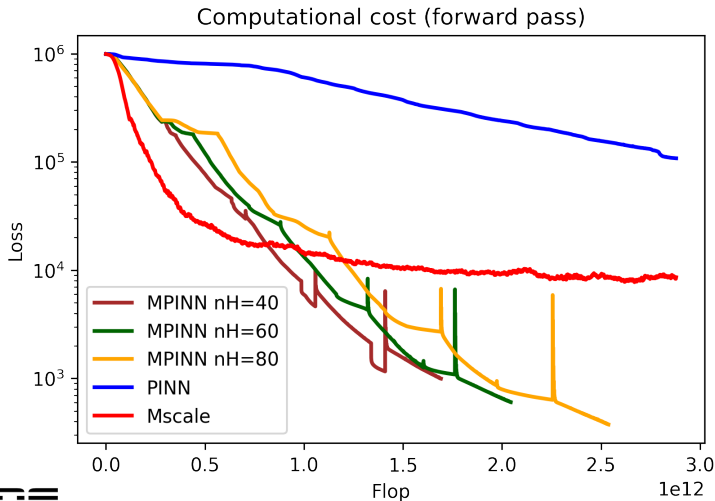


Convergence of MSE (extrapolation)



Computational cost for two levels...

... as a function of coarse grid size (nH)



Conclusions

- ▶ We have presented a new multigrid-inspired training **framework** using recent advances in NN to efficiently solve PINN-type problems.
- ▶ We have proposed an algorithm which works **without prior knowledge** of frequency content and which is promising.
- ▶ We have demonstrated that exploiting spectral complementarity using our framework may bring **significant computational benefits** (faster convergence).

Perspectives

- ▶ Perform further **extensive testing**, including more complex problems.
- ▶ Pursue the **sensitivity analysis** for
 - ▶ the relative sizes of the grids,
 - ▶ the relative sizes of the networks.
- ▶ Investigate **theoretical aspects**:
 - ▶ convergence of the iterates from an optimization point of view,
 - ▶ convergence to the solution in functional space.

Thank you for your attention!

A few references

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