

Verification of DNNs with Marabou

Omri Isac, The Hebrew University of Jerusalem

Workshop on Logical Methods for Neural Network Analysis
(LogicNN), July 2026

Agenda

Learn the **basic theory** behind Marabou

Run Marabou with simple examples

Understand **Maraboupy** main objects and **try it**

Follow along (Linux users)

pip install **maraboupy**

--- or ---

git clone **<https://github.com/NeuralNetworkVerification/Marabou/>**

cd Marabou

mkdir build

cd build

cmake ..

cmake --build .



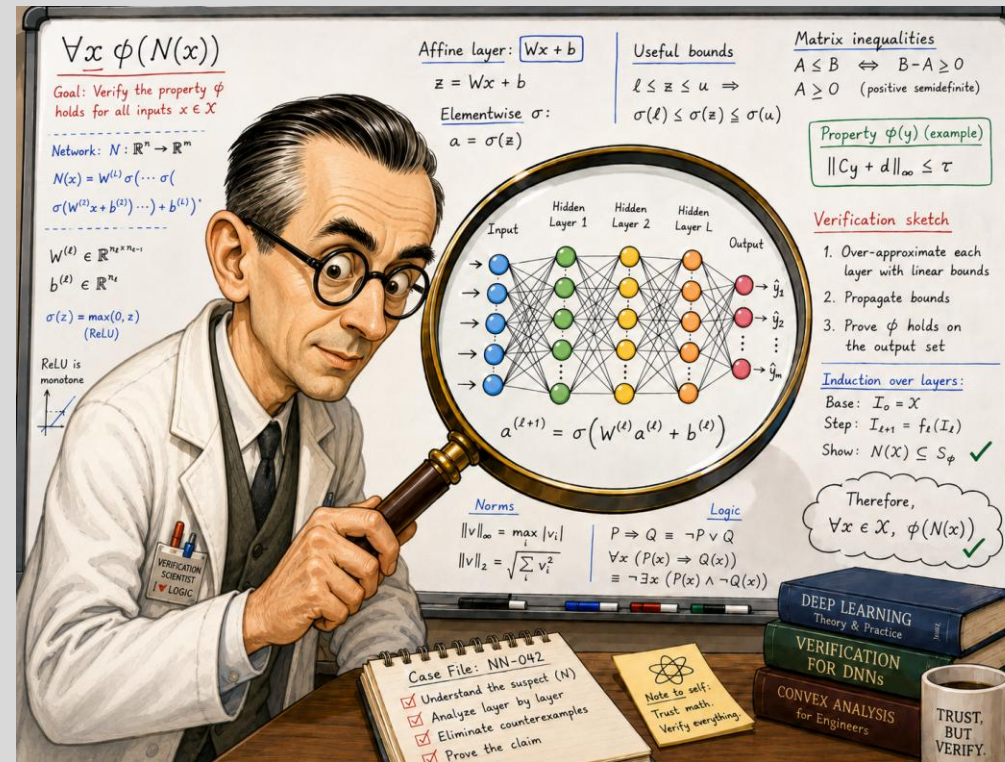
DNN Verification

Deep Neural Networks (DNNs) accomplish groundbreaking results in many fields, **including safety-critical.**



Unlike traditional software, **DNNs are opaque functions,** **trained** over a large set of input and output examples.

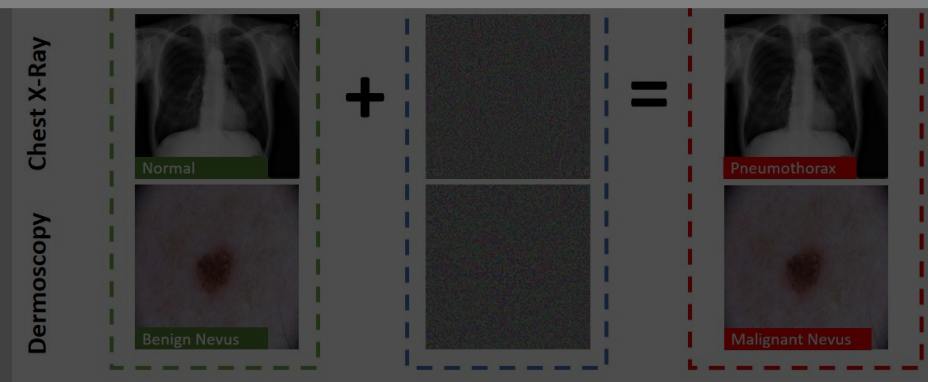
Understanding the behavior of DNNs is then **necessary**,



and calls for **logical analysis** for reasoning on edge cases.

This may lead to undesirable behavior of DNNs, which is **hard to predict** and **potentially dangerous**.

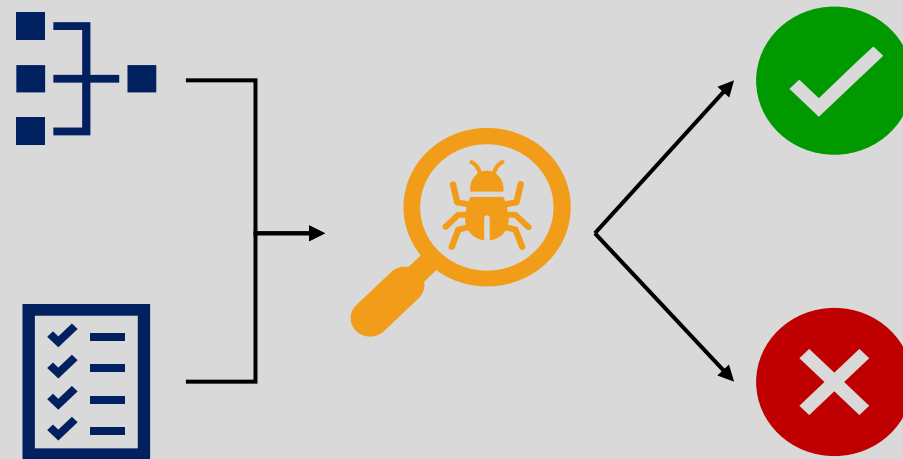
Can we **rule out** possibility of errors?
Or **find hidden** errors, if exist



Understanding Adversarial Attacks on Deep Learning Based Medical Image Analysis Systems, Ma et al., 2019

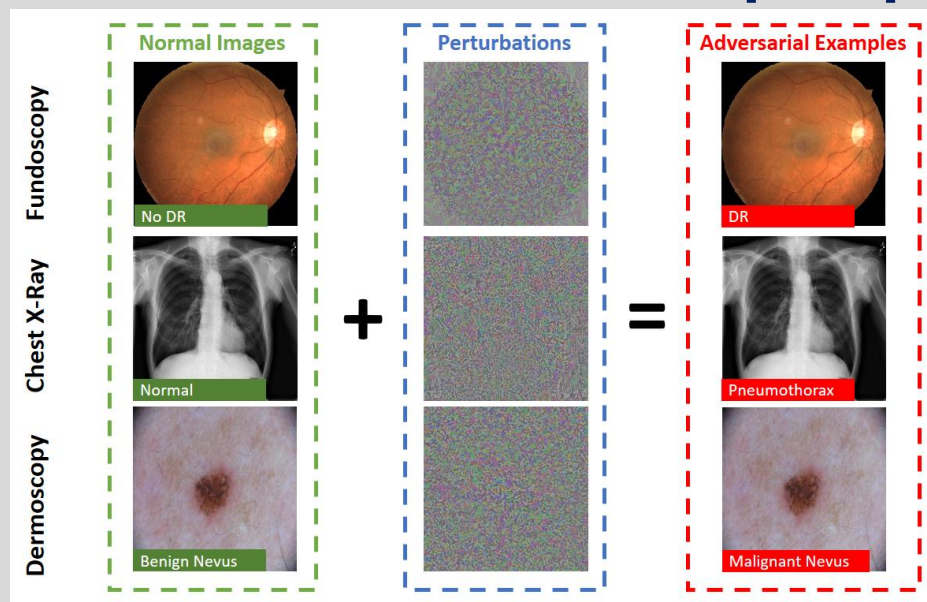
DNN Verification

- Given a DNN $\mathcal{N}$ an input property $\varphi(x)$ and an output property $\psi(y)$, **decide whether there exists an input x such that $\varphi(x) \wedge \neg\psi(\mathcal{N}(x))$.**
 - If exists, the problem is **satisfiable (SAT)**;
 - Otherwise **unsatisfiable (UNSAT)**.



Back to Adversarial Examples

- For an image classifier and a given image, we wish to check the network's robustness to small input perturbations.



- Decide whether there exists a small perturbations that alters the image's class.

Local Adversarial Robustness

- Given an image classifier $\mathcal{N}$, an input image α and its classification $c_i \in \mathcal{C}$:
- **Slight noise perturbation** $\varphi(\alpha, \epsilon): \{x_{i,j} = \alpha_{i,j} + e_{i,j} \mid |e_{i,j}| \leq \epsilon\}$
- **Classification changes** $\neg\psi(c_i): \forall_{c_j \neq c_i \in \mathcal{C}} c_j \geq c_i$
- Can be **generalized** in several ways.

Marabou

The Marabou Verifier

- A **mature DNN verifier**, employing multiple state-of-the-art features.



- Operates mainly by casting the **verification problem to SMT-like queries**.

DNN Verification as SMT

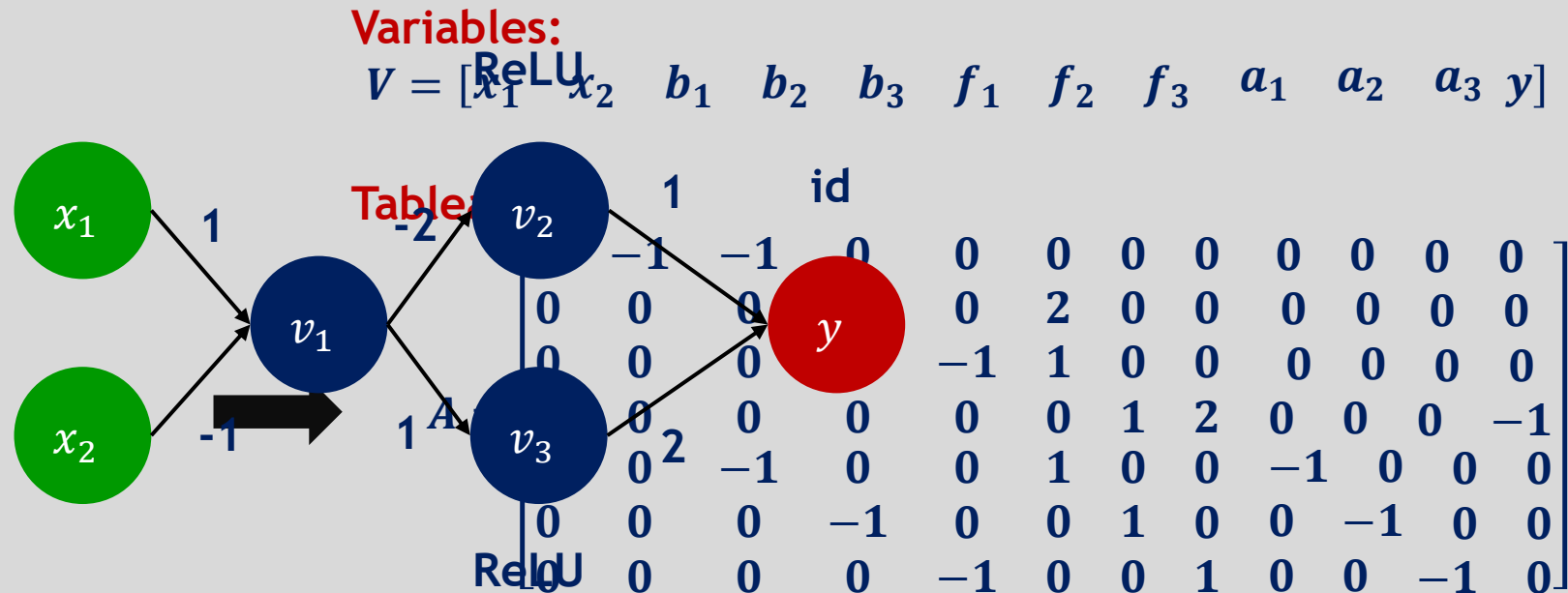
- Decide if there is assignment to V such that:

$$A \cdot V = 0 \text{ for some matrix } A$$

$$l \leq V \leq u \text{ for some bound vectors } l, u$$

Activation constraints over a subset of V

Verification Query Example



Bounds:

$$\varphi(x) := x \in [1, 2]^2$$

$$\neg\psi(y) := y = [1, -1]$$

ReLU:

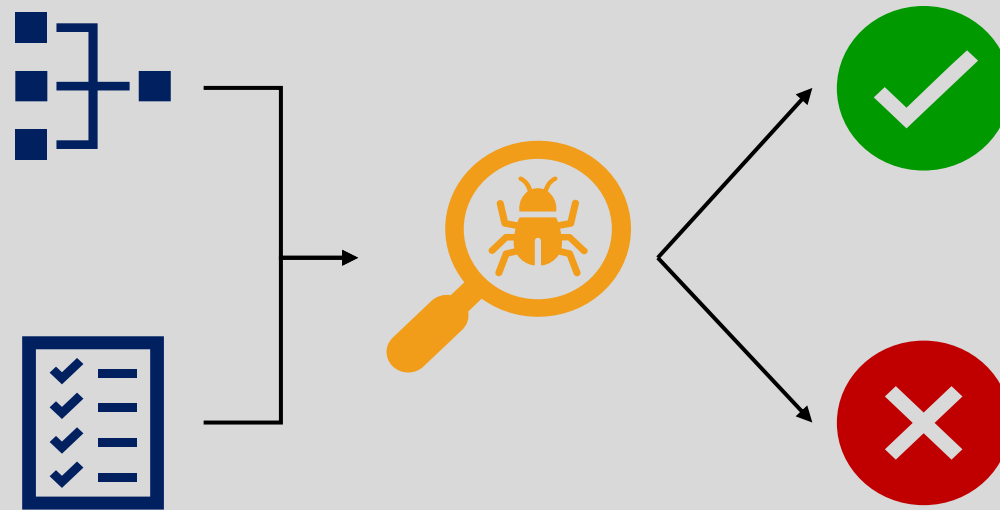
$$f_1 = \text{ReLU}(b_1)$$

$$f_2 = \text{ReLU}(b_2)$$

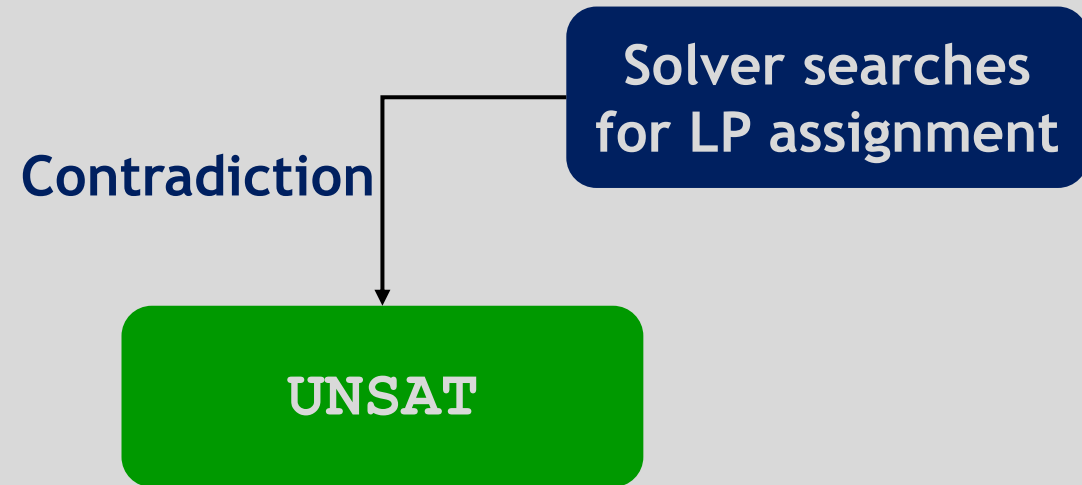
$$f_3 = \text{ReLU}(b_3)$$

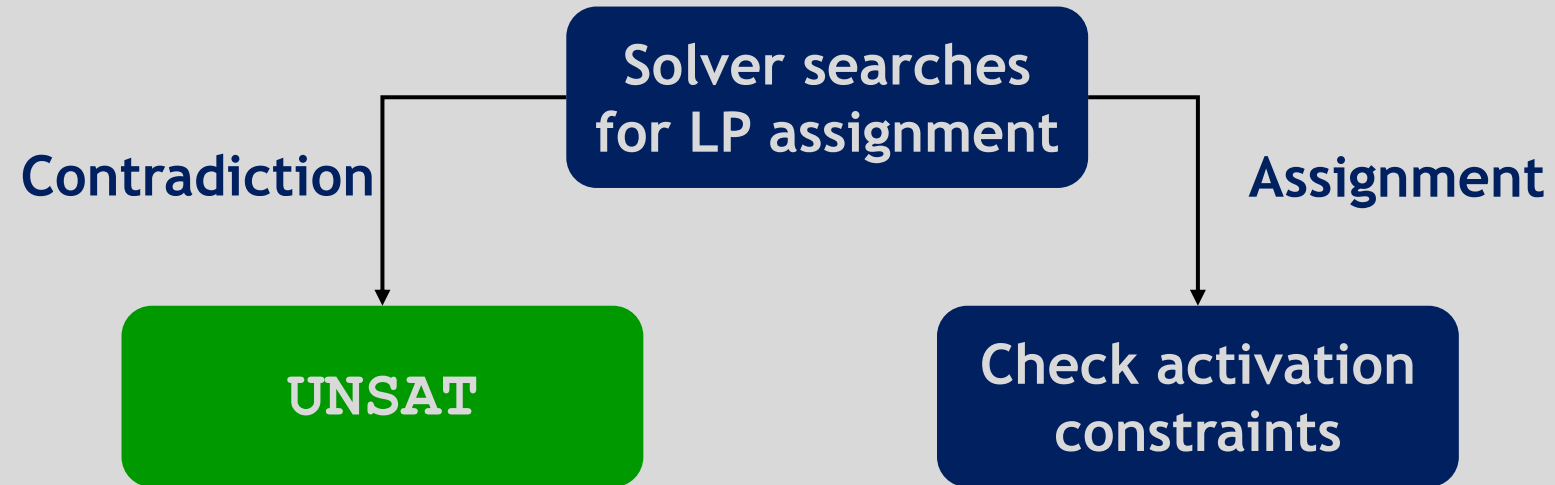
The Basic Approach

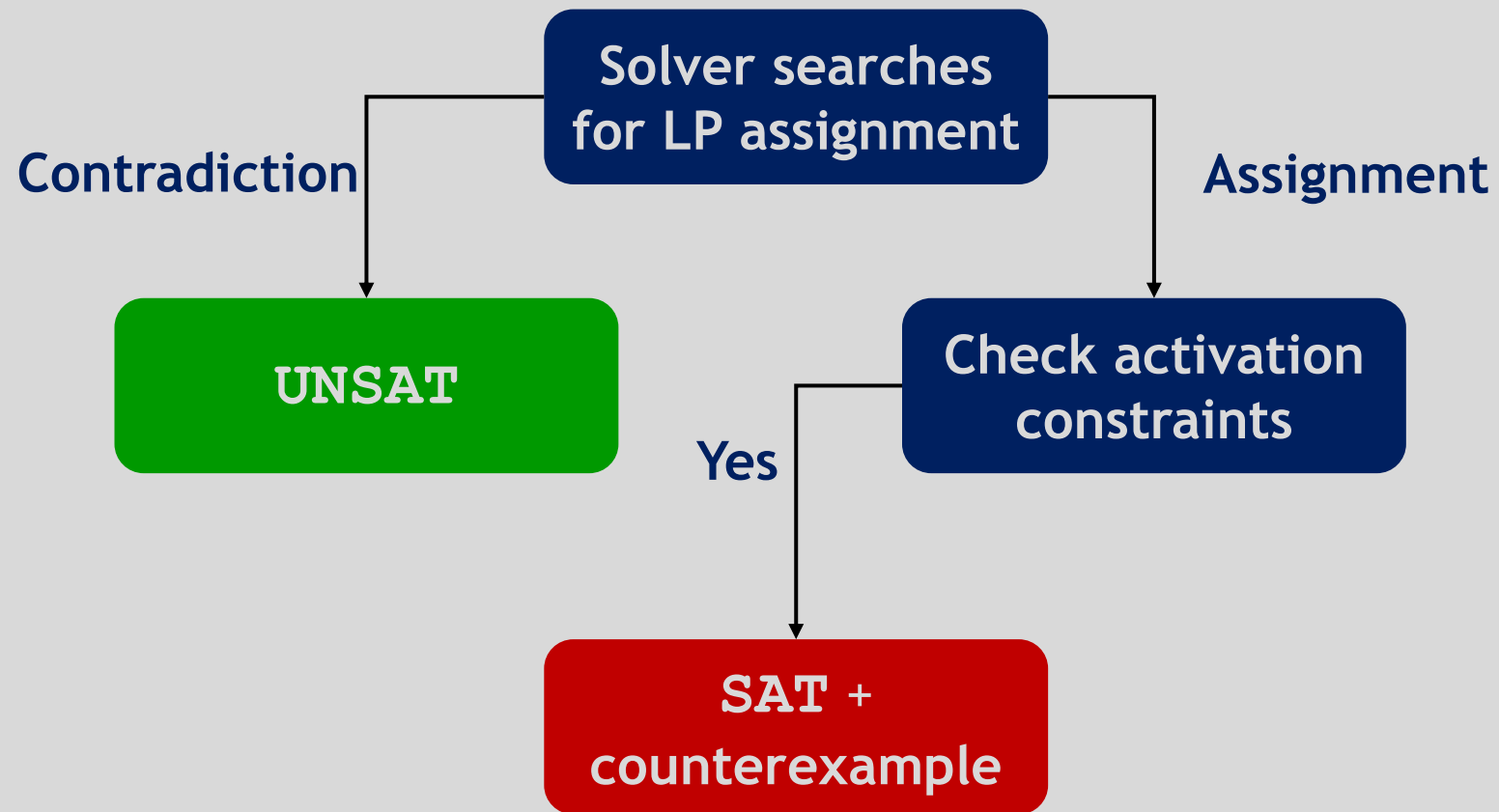
- Marabou **searches for a satisfying assignment** with LP solvers and splitting approach.

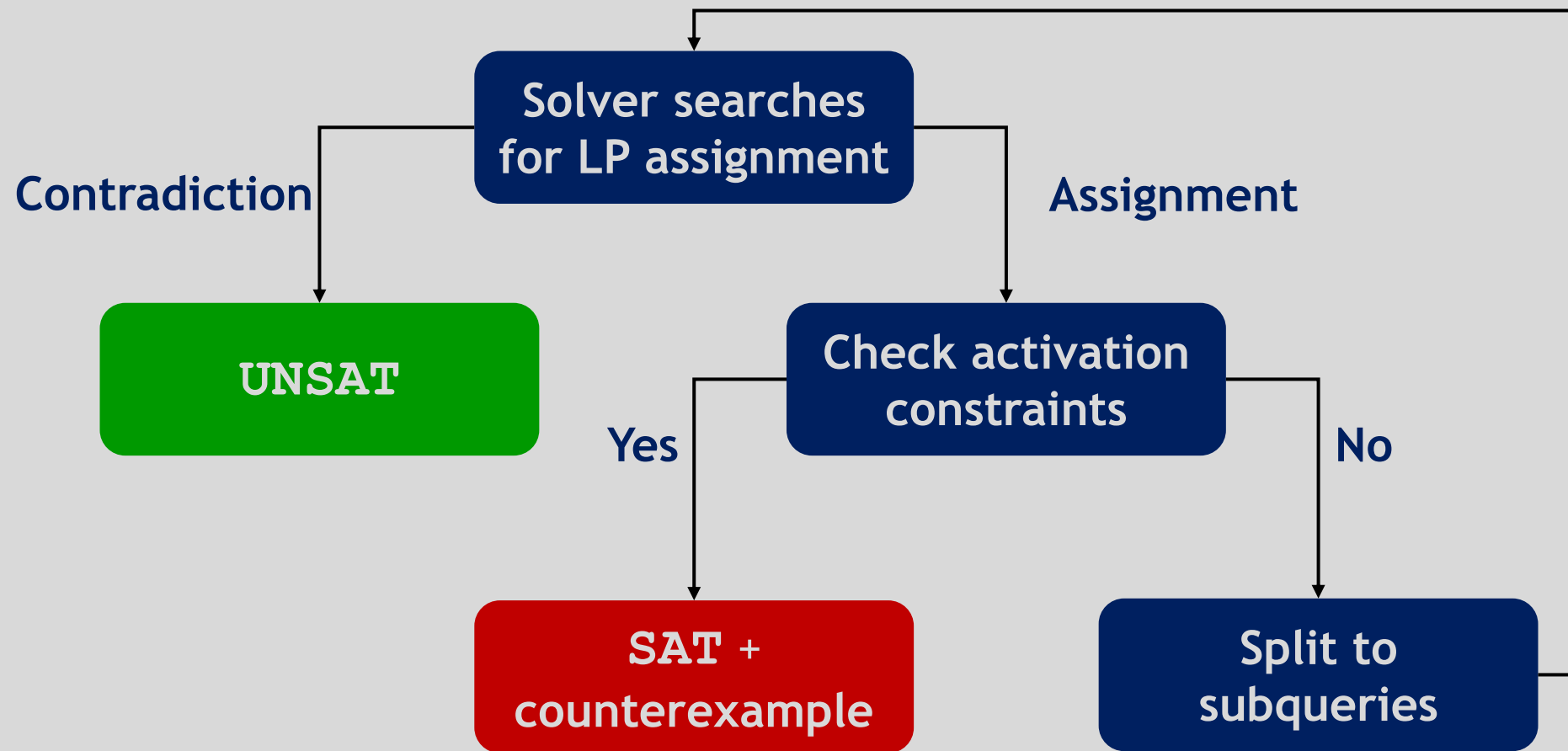


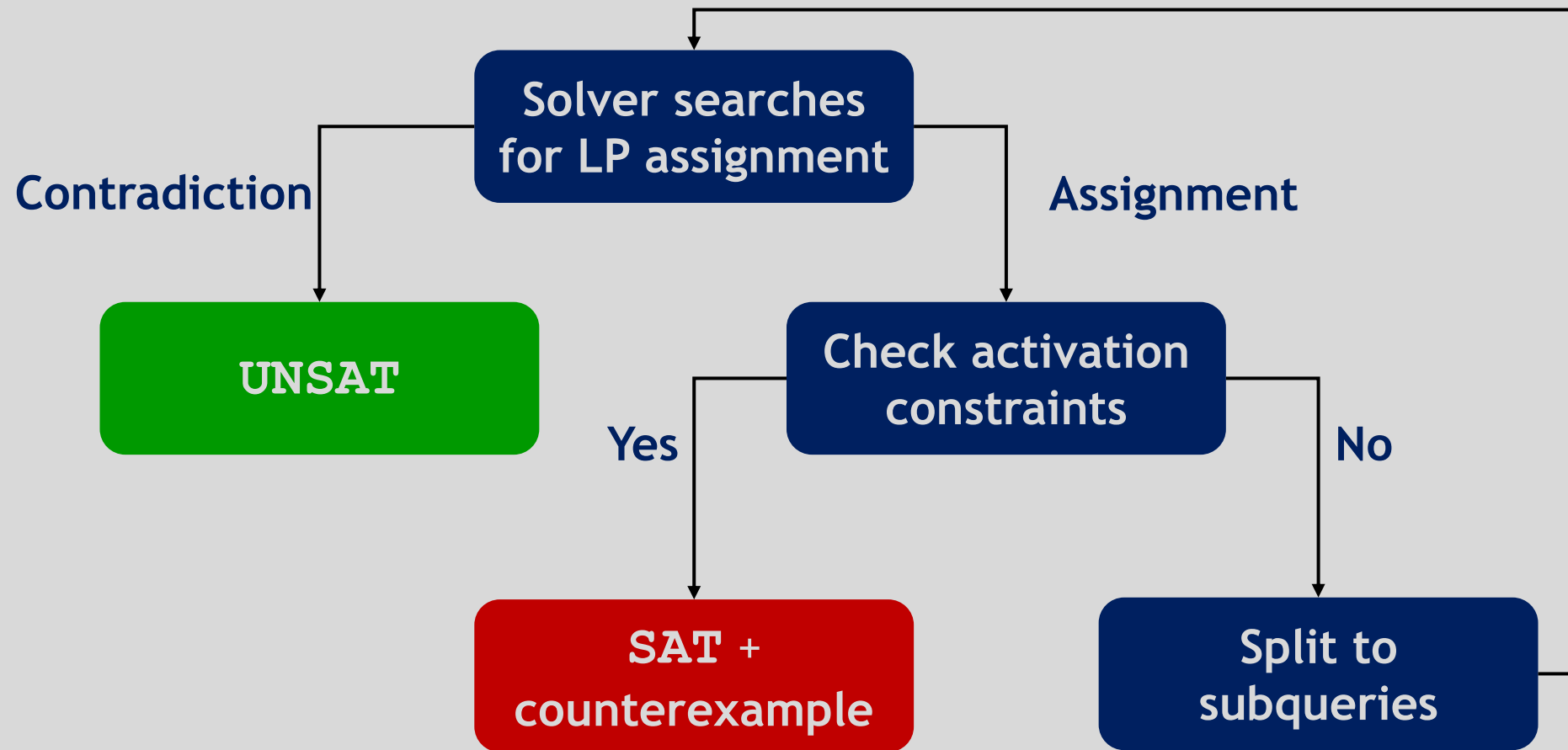
**Solver searches
for LP assignment**











Splitting creates a **tree structure** to the search.
The query is UNSAT if and only if all leaves are UNSAT.

The Search Tree

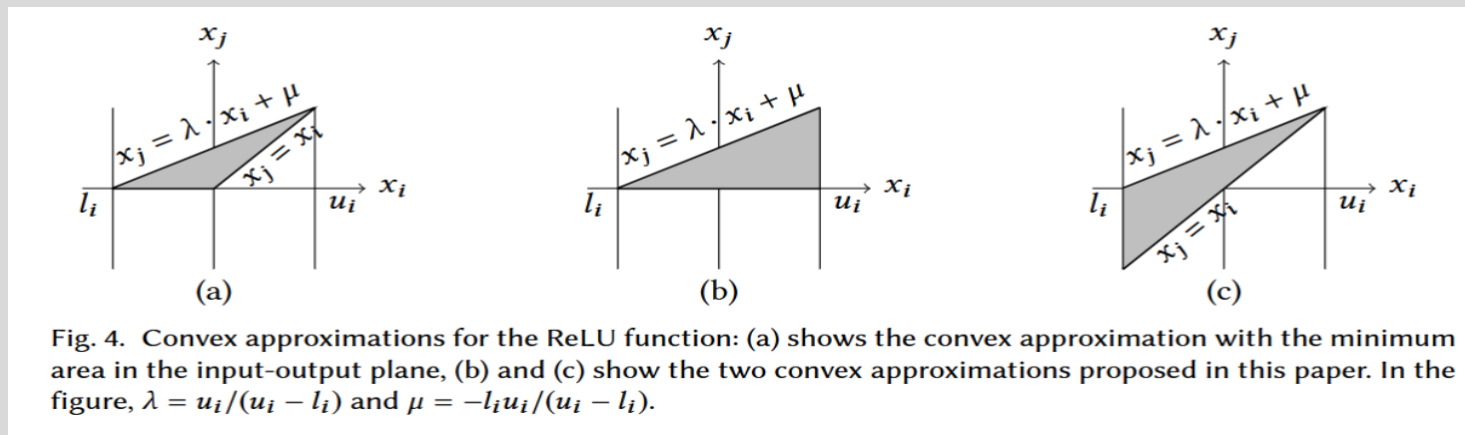
- Potentially, tree size is exponential $\sim 2^{|\mathcal{N}|}$.
- Possibly unavoidable, as **DNN verification is NP-Complete** for ReLU-networks [Katz et. al, '17; Sälzer and Lange, '21].
- However, can still be **solved in reasonable time**, using many optimizations (as in SAT solving).

Pruning The Search Tree

- “Lazy” Splits.
- Effective decision heuristics.
- Overapproximation of bounds, compromising completeness for scalability.

Bound Propagation

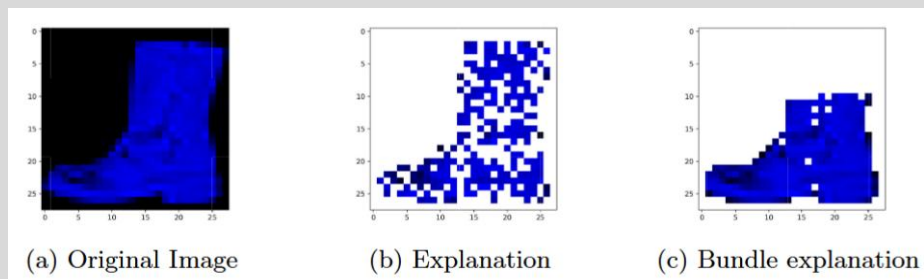
- Overapproximates bounds of neurons, as a linear function of neurons in preceding layers.



An Abstract Domain for Certifying Neural Networks, Singh et al., 2019

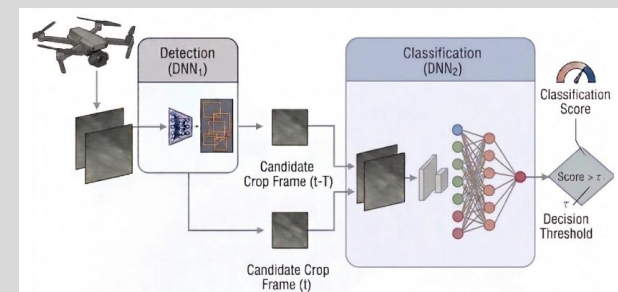
- Eliminates neuron phases (PL) + detects UNSAT early.
- Introduce incompleteness.

Formal Explainability



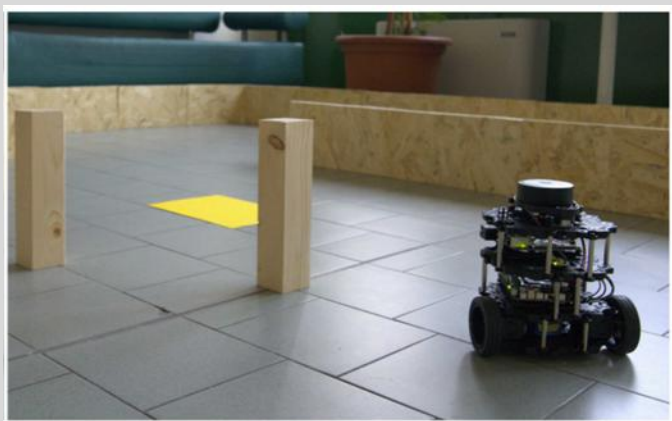
Towards Formal XAI: Formally Approximate Minimal Explanations of Neural Networks, Bassan et al., 2023

Wildfire Detection System



VeriFIRE: an Industrial Case Study in Verifying Consistency Properties for a DNN-Based, Wildfire Detection System, Refaeli et al., *SAIV 2026*.

Neural Robotics Controllers



Verifying Learning-Based Robotic Navigation Systems, Amir et al., 2023

Network Congestion Control



Verifying Generalization in Deep Learning, Amir et al., 2023

The background of the slide is a blurred photograph of a small, dark-colored robotic car with two large, light-colored wheels. The car is positioned in the center of a hallway with light-colored walls and a dark floor. The text "Simple Navigation- Example 1" is overlaid on the image in a white, bold, sans-serif font with a black outline.

Simple Navigation- Example 1

Using Marabou

The VNNLIB format

A format for defining input-output properties in DNN verification

```
(declare-const X_0 Real)
(declare-const X_1 Real)
(declare-const X_2 Real)
(declare-const X_3 Real)
(declare-const X_4 Real)

(declare-const Y_0 Real)
(declare-const Y_1 Real)
(declare-const Y_2 Real)
(declare-const Y_3 Real)
(declare-const Y_4 Real)

; Unscaled Input 0: (55947.691, 60760)
(assert (<= X_0 0.679857769))
(assert (>= X_0 0.6))

; Unscaled Input 1: (-3.141592653589793, 3.141592653589793)
(assert (<= X_1 0.5))
(assert (>= X_1 -0.5))

; Unscaled Input 2: (-3.141592653589793, 3.141592653589793)
(assert (<= X_2 0.5))
(assert (>= X_2 -0.5))

; Unscaled Input 3: (1145, 1200)
(assert (<= X_3 0.5))
(assert (>= X_3 0.45))

; Unscaled Input 4: (0, 60)
(assert (<= X_4 -0.45))
(assert (>= X_4 -0.5))

; Unsafe if COC >= 1500. Output scaling is 373.94992 with a bias of 7.518884: (1500 - 7.518884) / 373.94992 = 3.991125
(assert (>= Y_0 3.991125645861615))
```

Undergoing a **major update to VNNLIB 2.0** (Roy et al., CAV26)

Demo (onnx + vnnlib)

./Marabou network/path/dnn.onnx property/path/prop.vnnlib

Exploring Options

- Split and Conquer (SnC)

`--snc --num-workers n`

- Branching heuristics

`--branch relu-violation/polarity/babsr` and more

- Proofs (if time permits, no SnC)

`--prove-unsat`

Demo (flags)

./Marabou network/path/dnn.onnx property/path/prop.vnnlib
--options

Maraboupy

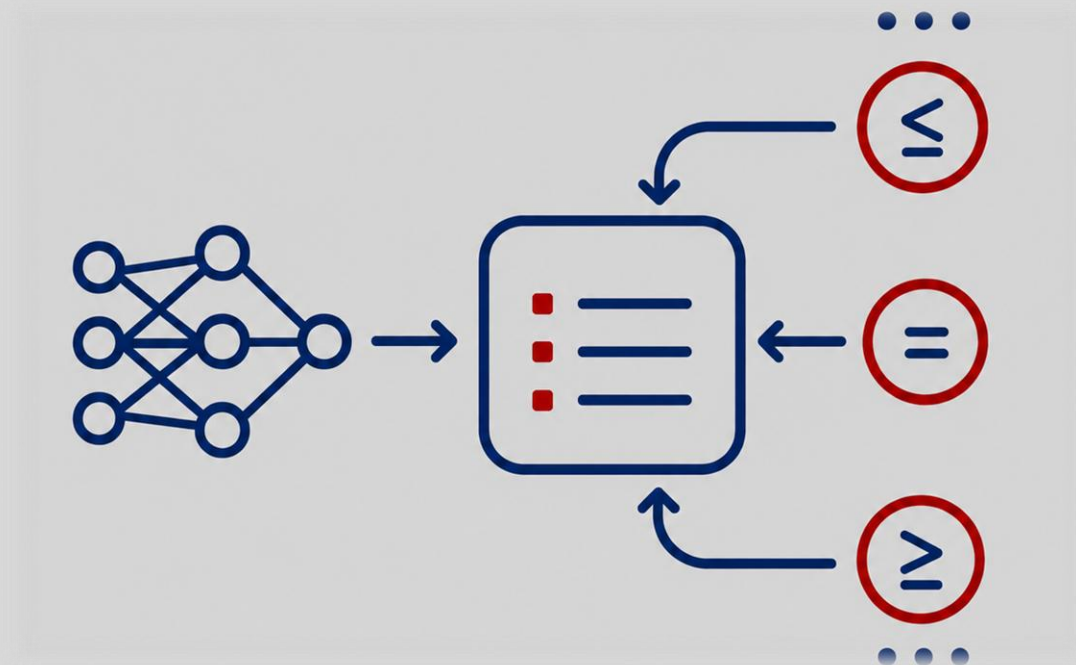
- Python interface for Marabou, (outdated) documentation:
 - <https://neuralnetworkverification.github.io/Marabou/>



- Begin with `pip --install maraboupy`

Query Object

- Base object that aggregates constraints:
 - Read a DNN using `Marabou.read_onnx(path)`
 - Start anew using `MarabouCore.InputQuery()`



Variables

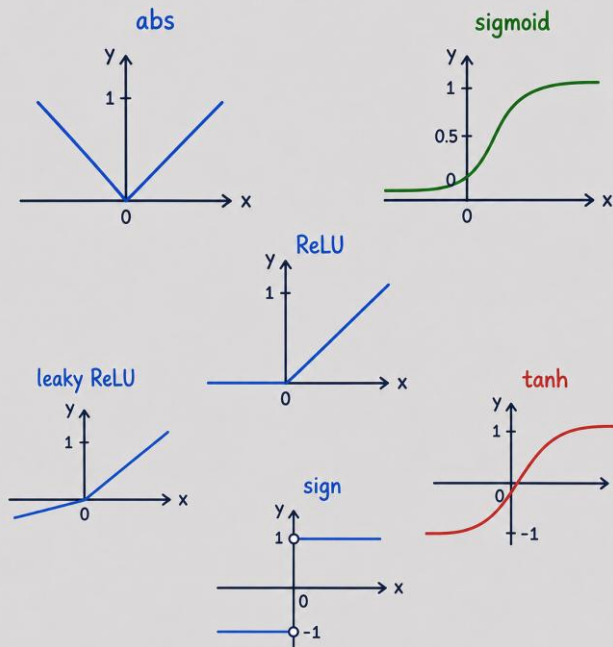
- Either use the network's inputs and outputs:
 - `network.inputVars` or `outputVars`
- Or manually define them:
 - `query.setNumberOfVariables(n)`
- Bound variables:
 - `setUpperBound(index,value)`, `setLowerBound(index,value)`

Linear Equations and Inequalities

- Either use the pythonic interface:
 - `query.addConstraint(expr)`
- Or manually define them:
 - `eq = MarabouCore.Equation()`
 - `eq.addAddend(index, coefficient)`
 - `eq.scalar = c`
 - `query.addEquation(eq)`

Activation function

- Dedicated function for each piecewise-linear constraint:
 - MarabouCore.addReluConstraint(query, input, output)
 - MarabouCore.addSignConstraint(query, input, output)
 - ...



Solving the query

- Define solving options (verbosity, heuristics, etc.):
 - Marabou.**createOptions(options)**
- Call the solving function and analyze its results:
 - Marabou.**solve(query)**

<https://github.com/OmrilsacHUJI/MarabouTutorial>

Your Turn

