

A Discrete Particle Swarm Optimization for IoT services placement over Fog infrastructures



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Outline









Introduction

Problem formulation

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Fog Infrastructures

"Fog computing is a horizontal, physical or virtual resource paradigm that resides between smart end-devices and traditional cloud or data centers." [NIST 2017]

Toplogy

We consider a Hierarchical Three-Layered Fog infrastructure represented with a non oriented gaph $G_{\mathcal{M}} = (\mathcal{M}, \mathcal{L})$.



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IoT applications

Class \QoS	Delay- sensitivity	Bandwidth demande	Communica tion frequency	CPU demande	Data Location	Mobility	Priority	Example
Interactive- Real Time	High <50ms	High	High	High- Medium	Local- vVcinity	High- medium- low	1	Augmented reality games
Mission- crintcal	High <20ms	High	High	High- Medium	Local- Vicinity	High- medium- low	0	EEG
Streaming	Medium <150	High	Medium	Medium- Low	Local- Vicinity- Remote	High- medium- low	2	Visoconfere nce, Camera suerveillanc e
Best effort	Low 	Low	Low	Low	Remote	High- medium- Low	3	File sharing etc.





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Energy & delay violation

objective function

$\begin{aligned} \forall k, t \in \mathbb{N} : \\ f &= \min_{i \in [0, N-1], j \in [0, M-1]} [(1 + \lambda) E_T] \\ s.t \begin{cases} ram_i \leq ram_j \forall i \in [0, N-1], \forall j \in [0, M-1]...(i) \\ mi_i \leq cpu_j \forall i \in [0, N-1], \forall j \in [0, M-1]...(ii) \\ \sum_{j \in [0, M-1]} y_k^t(i, j) = 1, \forall i \in [0, N-1]...(iii) \end{aligned}$

- (i) and (ii) are respectively memory and computing constraints for placing service *i* on machine *j*.
- (iii) means that a service s_i should be placed only in one device.



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Discrete Particle Swarm Optimization approach

- Semi-stochastic population-based approach.
- Inspired by the collective behavior of social animals (Birds flocking, Fish schooling).
- A set of particles with a position, velocity and a set of neighbors exploring the multidimensional search space throug iterations.
- The particle's movement (direction and speed) between each iteration is a consequence of its own experience (local search method) and its neighboring one (semi-global or global search).



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Velocity particle's position updating

We compute each particle new velocity matrix according to Eq (1).

$$\begin{aligned}
\nu_k^{t+1}(i,j) &= \omega^{(t+1)} \nu_k^t(i,j) + \varphi_1 \omega_1^{t+1}(i,j) [f(Pb_k^t) \\
&- f(X_k^t)] + \varphi_2 \omega_2^{t+1}(i,j) [f(Nb_k^t) - f(X_k^t)]
\end{aligned} \tag{1}$$

After new velocity computation, we deduce particle's new position vector with Eq (2)

$$x_k^t(i) = Z \iff v_k^t(i, Z) = \max_{\forall j \in [0, M-1]} \left\{ v_k^t(i, j) \right\}$$
(2)

Physical topology constraints can reduce placement possibilities for a service s_i .

$$\forall k \in [0, P-1], \forall t \in [0, T_{max} - 1] \Rightarrow v_k^t(i, j) = -\infty$$
(3)



Strategies _____



CloudOnly

IoTFogOnly

IoTCloud(IC)

FogCloud(FC)

Dicothomous (DCT)

Discret Particle Swarm Optimization (DPSO)



Conclusion ⁹



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TIRIT

SAS





(2) Mission Critical (MC)

(3) Streamin (ST)

(4) Best Effort (BE)

Experimental approach & results

Conclusion ¹⁰





Conclusion ¹¹



Strategies

Experimental approach results







Services Load per Layers for each methode

Conclusion (1)

- 1. Evolutionary approach and basic placement strategies.
- 2. DPSO gives a good tradeoff between energy and delay values.
- 3. Execution time.
- 4. Centralized approach.
- 5. Hierarchical topology.
- 6. Linear energy consumption profile.
- 7. Static infrastructure and VMs.

Conclusion (2)



Conclusion (3)



Solution quality impacted by time.

Users mobility estimation

Efficient handover and migrations approches Evaluation

Services availability.

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