Part 3: Memory-Aware DAG Scheduling

CR05: Data Aware Algorithms

October 12 & 15, 2020

Outline

Minimize Memory for Trees

Minimize Memory for Series-Parallel Graphs

Minimize I/Os for Trees under Bounded Memory

Complexity and Space-Time Tradeoffs for Parallel Tree Processing

Parallel Processing of DAGs with Limited Memory

- Model and maximum parallel memory
- Maximum parallel memory/maximal topological cut
- Efficient scheduling with bounded memory
- Heuristics and simulations

Summary of the course

- Part 1: Pebble Games
  models of computations with limited memory
- Part 2: External Memory and Cache Oblivous Algoritm
  2-level memory system, some parallelism (work stealing)
- Part 3: Streaming Algoritms
  Deal with big data, distributed computing
- Part 4: DAG scheduling (today)
  structured computations with limited memory
- Part 5: Communication Avoiding Algorithms
  regular computations (lin. algebra) in distributed setting

Introduction

- Directed Acyclic Graphs: express task dependencies
  - nodes: computational tasks
  - edges: dependencies
    (data = output of a task = input of another task)
- Formalism proposed long ago in scheduling
- Back into fashion thanks to task based runtimes

- Decompose an application (scientific computations) into tasks
- Data produced/used by tasks created dependancies
- Task mapping and scheduling done at runtime
- Numerous projects:
  - StarPU (Inria Bordeaux) – several codes for each task to execute on any computing resource (CPU, GPU, *PU)
  - DAGUE, ParSEC (ICL, Tennessee) – task graph expressed in symbolic compact form, dedicated to linear algebra
  - StartSs (Barcelona), Xkaapi (Grenoble), and others...
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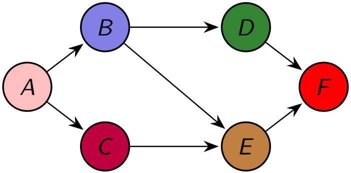
Task graph scheduling and memory

- Consider a simple task graph
- Tasks have durations and memory demands



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- Trade-off between peak memory and performance (time to solution)

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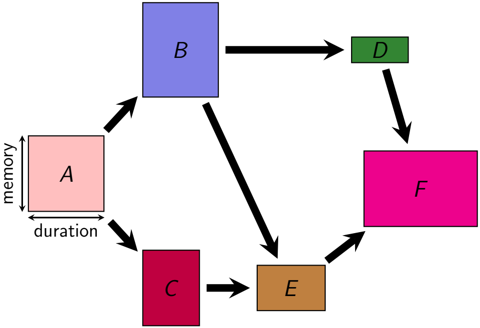

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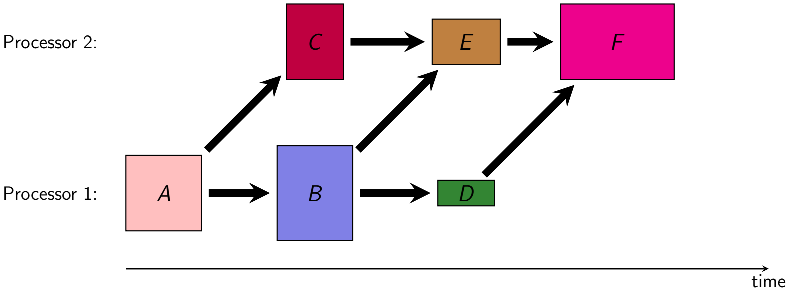

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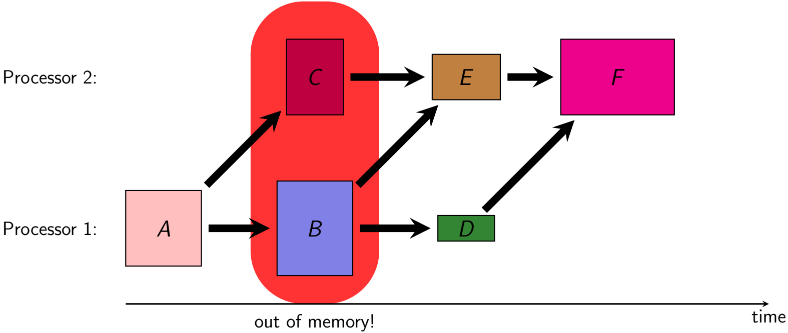

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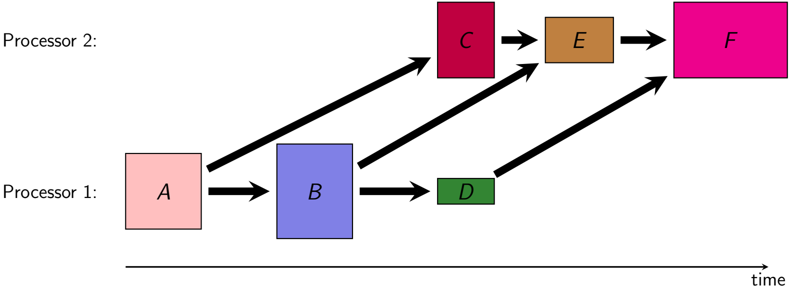

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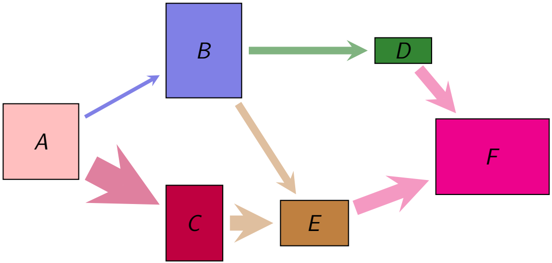
Going back to sequential processing

- Temporary data require memory
- Scheduling influences the peak memory



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- Store some temporary data on a larger, slower storage (disk)
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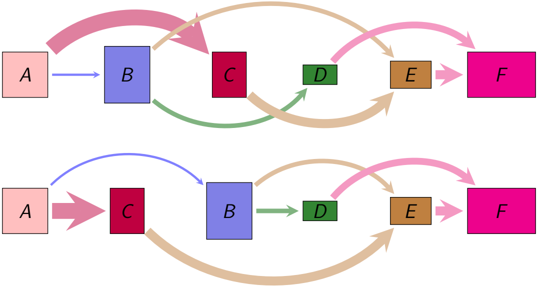

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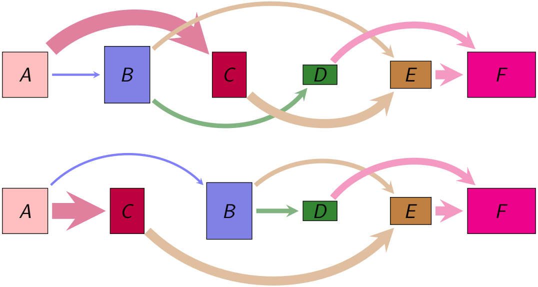

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- In case of parallel processing:
  - Tradeoffs between memory and time (makespan)
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Most (all?) of these problems: NP-hard on general graphs ☹

Sometimes restrict on simpler graphs:

1. Trees (single output, multiple inputs for each task)
   Arise in sparse linear algebra (sparse direct solvers), with large data to handle: memory is a problem
2. Series-Parallel graphs
   Natural generalization of trees, close to actual structure of regular codes

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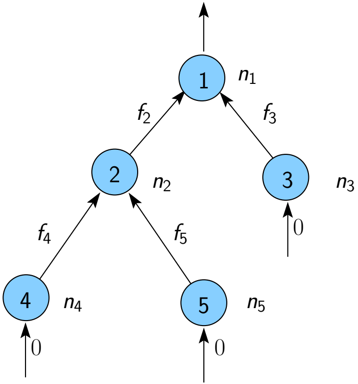
Notations: Tree-Shaped Task Graphs



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- Output data of size f_i
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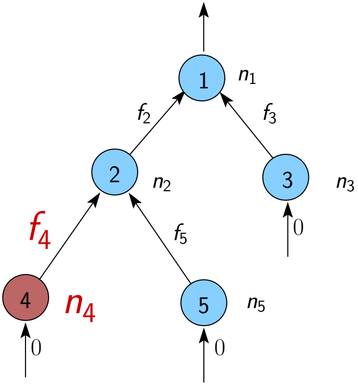

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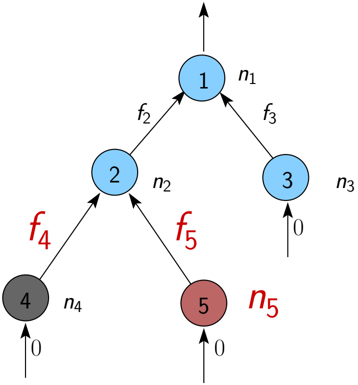

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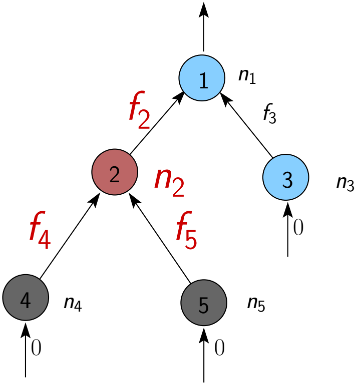

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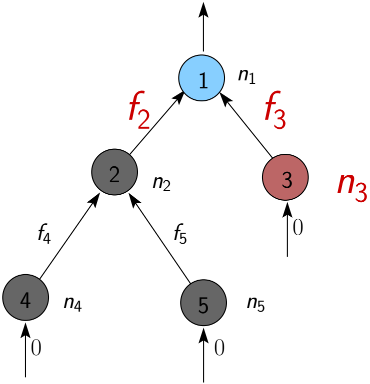

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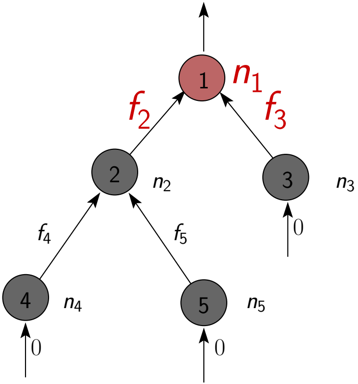

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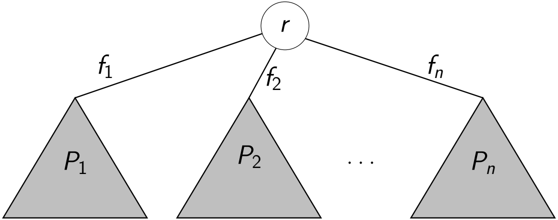
Liu's Best Post-Order Traversal for Trees

Post-Order: entirely process one subtree after the other (DFS)



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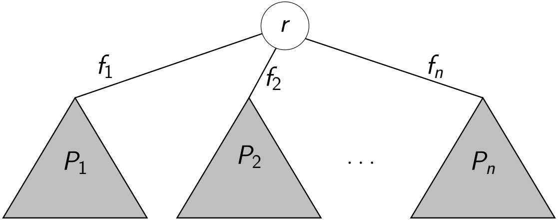

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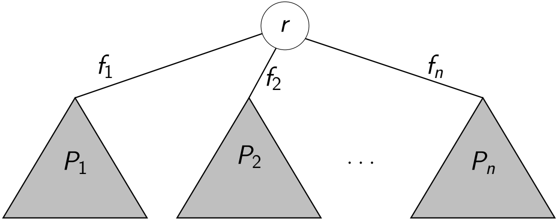

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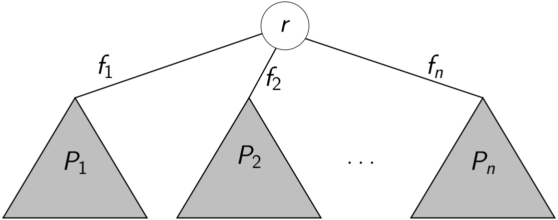

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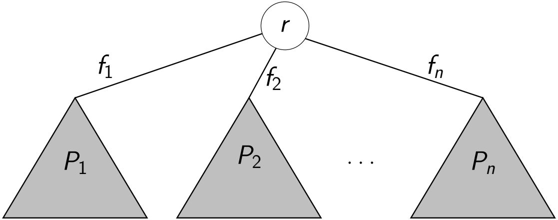

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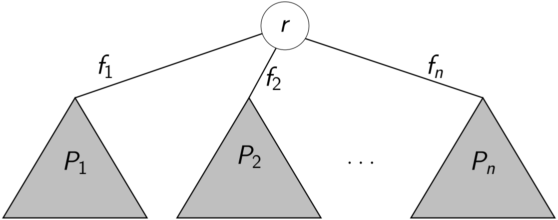

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- Optimal order: non-increasing $P_i - f_i$

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Theorem (Best Post-Order).

The best post-order traversal is obtain by processing subtrees in non-increasing order $P_i - f_i$.

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Proof:

- Consider an optimal traversal which does not respect the order:
  - subtree j is processed right before subtree k
  - $P_k - f_k \geq P_j - f_j$

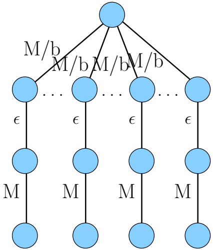
	peak when j, then k	peak when k, then j
during first subtree	$mem\_before + P_j$	$mem\_before + P_k$
during second subtree	$mem\_before + f_j + P_k$	$mem\_before + f_k + P_j$

- $f_k + P_j \leq f_j + P_k$
- Transform the schedule step by step without increasing the memory.

Post-Order is not optimal

Post-Order traversals are arbitrarily bad in the general case

There is no constant k such that the best post-order traversal is a k-approximation.



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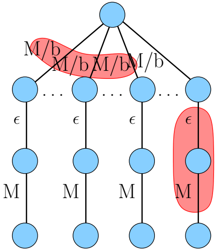

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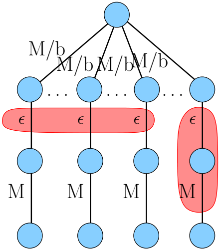

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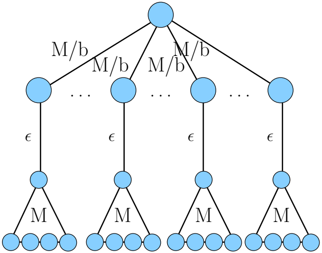

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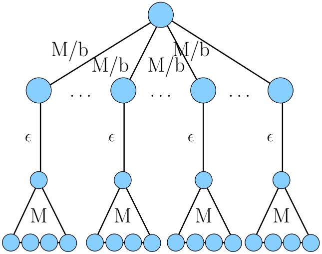

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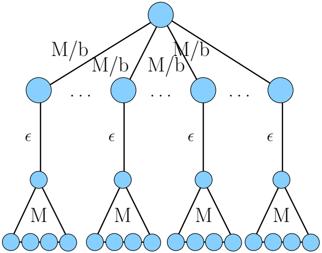

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	actual assembly trees	random trees
Non optimal traversals	4.2%	61%
Maximum increase compared to optimal	18%	22%
Average increased compared to optimal	**1%**	12%

Liu's optimal traversal – sketch

- Recursive algorithm: at each step, merge the optimal ordering of each subtree (sequence)
- Sequence: divided into segments:
  - H_1: maximum over the whole sequence (hill)
  - V_1: minimum after H_1 (valley)
  - H_2: maximum after H_1
  - V_2: minimum after H_2
  - ...
  - The valleys V_is are the boundaries of the segments
- Combine the sequences by non-increasing $H - V$
- Complex proof based on a partial order on the cost-sequences: $(H_1, V_1, H_2, V_2, \dots, H_r, V_r) \prec (H'_1, V'_1, H'_2, V'_2, \dots, H'_{r'}, V'_{r'})$ if for each $1 \leq i \leq r$, there exists $1 \leq j \leq r'$ with $H_i \leq H'_j$ and $V_i \leq V'_j$.

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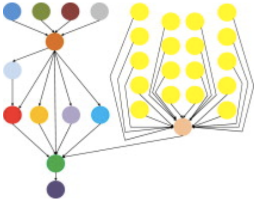
Series-Parallel Graphs: Motivation

- Not all scientific workflows are trees
- But most workflows exhibit some regularity
- Large class of workflows: Series-Parallel graphs



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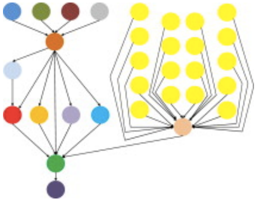

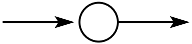

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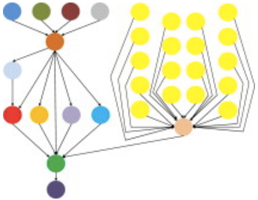

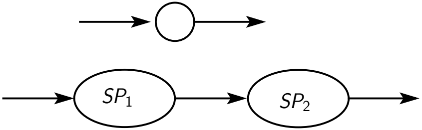

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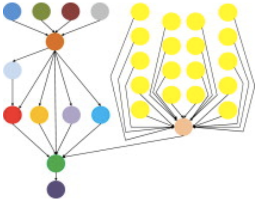
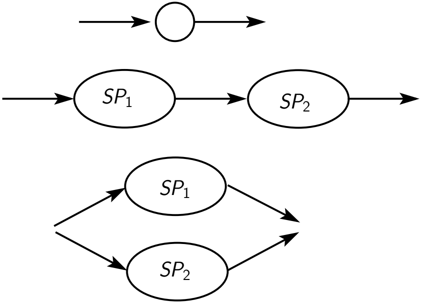
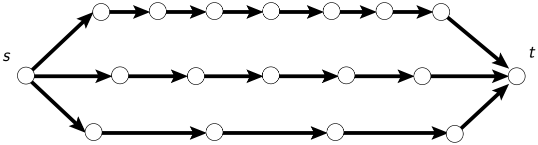




First Step: Parallel-Chain Graphs



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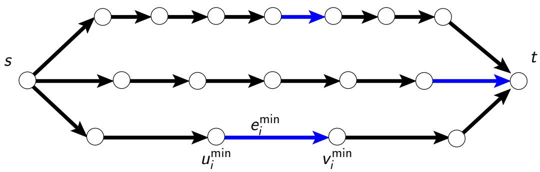

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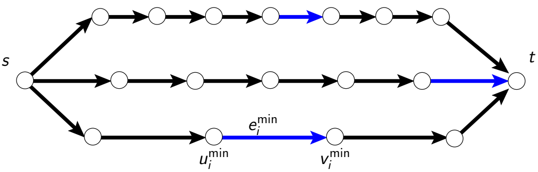

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There exists a schedule with minimal memory which synchronises at $e_1^{\min}, \ldots, e_B^{\min}$.

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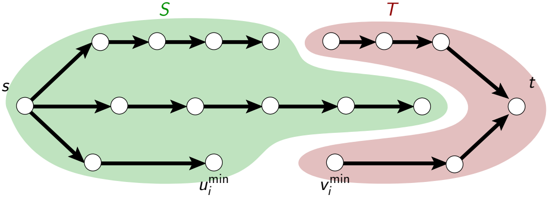

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Sketch of an optimal algorithm:

1. Apply optimal algorithm for out-trees on the left part
2. Apply optimal algorithm for in-trees on the right part

Synchronization on minimal cut – proof

- Consider optimal schedule σ_1
- Transform it into σ_2:
  1. Schedule all nodes from S (following σ_1)
  2. Then, schedule all nodes from T
- New schedule respect precedence constraints
  (processing order not changed within each branch)
- After scheduling all vertices from S, all $e_i^{\min}$ in memory
- Consider the memory when processing $u \in L$ from branch i:

	in σ_1	in σ_2
edge from branch $j \neq i$	some edge (v, w)	$\begin{cases} (v, w) & \text{if } v \in L \\ e_j^{\min} & \text{otherwise} \end{cases}$

$\Rightarrow$ Memory needed when processing u not larger in σ_2

- Same analysis if $u \in T$

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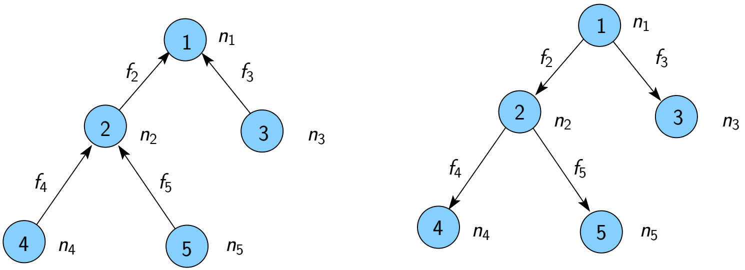
From in-trees to out-trees



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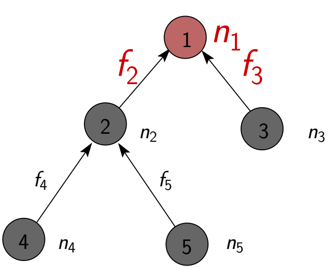

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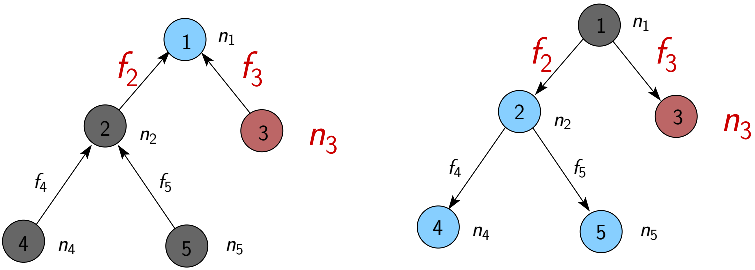

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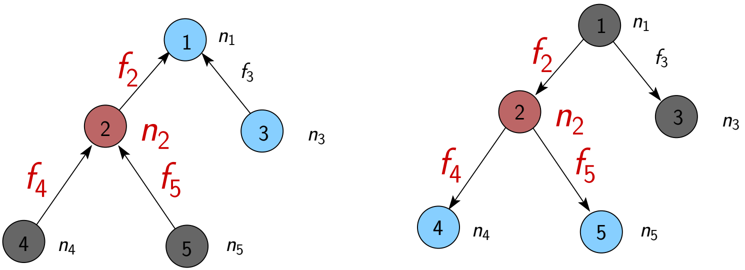

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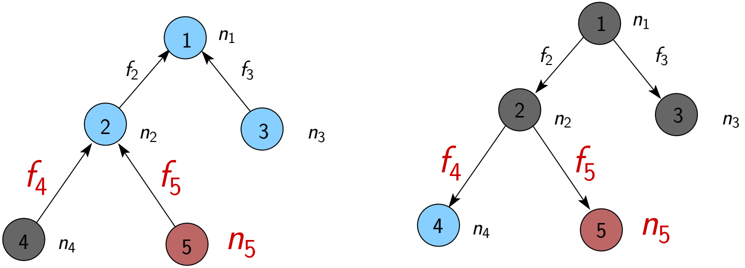

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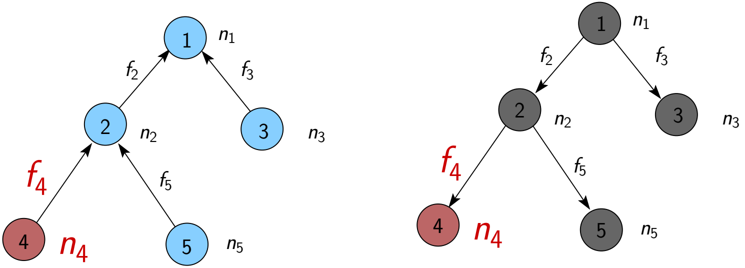

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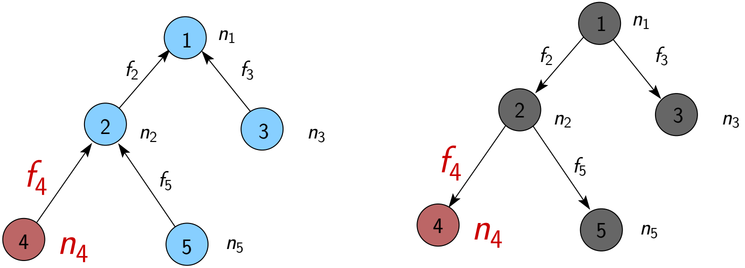

- Given a schedule σ_1 with memory M for the left in-tree, derive a schedule σ_2 for the right out-tree, obtained by reversing all edges?
- Choose $\sigma_2 = \text{reverse}(sigma_1)$

General Series-Parallel Graphs

Principle:

- Follow the recursive definition of the SP-graph
- Compute both optimal schedule and minimal cut
- Replace subgraphs by chains of nodes (based on opt. sched.)

For sequential composition:

- Select minimal cut
- Concatenate schedules

For parallel composition (as for Parallel-Chains):

- Merge cuts
- On the left part, use algo. for out-trees for merging schedules
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Simple algorithm vs. very complex proof of optimality

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Outline

Minimize Memory for Trees

Minimize Memory for Series-Parallel Graphs

Minimize I/Os for Trees under Bounded Memory

Complexity and Space-Time Tradeoffs for Parallel Tree Processing

Parallel Processing of DAGs with Limited Memory

- Model and maximum parallel memory
- Maximum parallel memory/maximal topological cut
- Efficient scheduling with bounded memory
- Heuristics and simulations

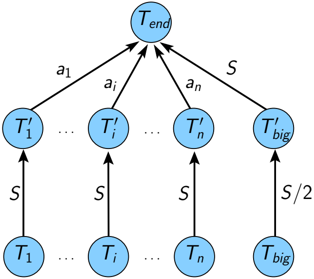
Minimizing I/Os for Trees

Problem:

- Available memory M too small to compute the whole tree
- Some data needs to be written to disk, and read back later
- Objective: minimize the amount of I/Os (total volume)

Theorem.

When data must either be kept in memory or fully evicted to disk, deciding which data to write to disk is NP-complete.



$n_i = 0$ for all tasks

Reduction from Partition:

- Integers $a_1, \ldots a_n$, $S = \sum_i a_i$
- Split in two subsets of sum $S/2$

Memory $M = 2S$
Is it possible to schedule the tree with a volume of I/O at most $S/2$?

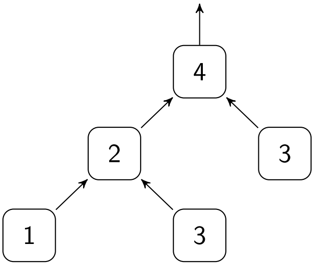
Minimizing I/O for Trees – with Paging

With paging:

- Partial data may be written to disk
- I/O cost metric: volume of data written to disk

Simpler model of memory/computation:

- memory weight only on edges output of $i = w_i$
- When processing a node, max(input, output) is needed
- Can easily emulate previous model (on the board)



Memory: 0 / 5

Disk: 0

I/Os: 0

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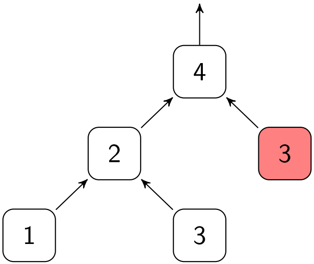

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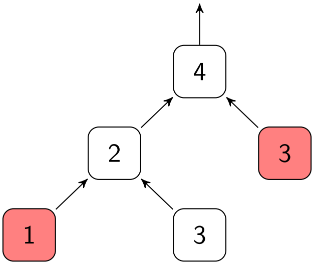

Memory: 4 / 5

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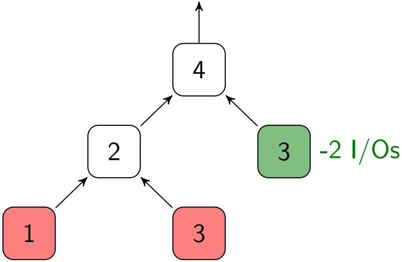

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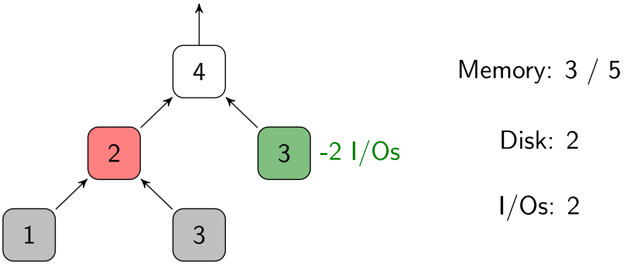

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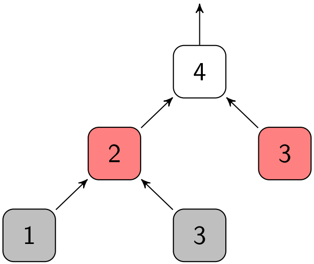

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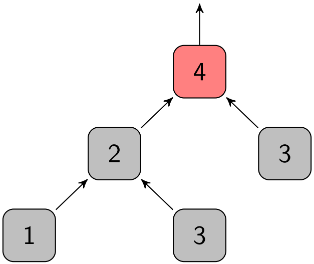

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Description of a solution

Traversal

- Schedule σ: $\sigma(i) = t$ if task i is the t- th executed
- I/O function τ: output data of task i has $\tau(i)$ slots written to disk
- W.l.o.g. data written to disk ASAP and read ALAP

Validity of a traversal

- Schedule respects precedences
- I/Os consistent: $\tau(i) \leq w_i$
- The main memory (size M) is never exceeded, $\forall i \in V$:

$$\left(\sum_{\substack{(k,p) \in E \\ \sigma(k) < \sigma(i) < \sigma(p)}} (w_k - \tau(k)) \right) + \max \left(w_i, \sum_{(j,i) \in E} w_j \right) \leq M$$

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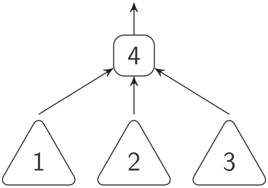
Objective

The MinIO problem

Given a tree G and a memory limit M, find a valid traversal that minimizes the total amount of I/Os (that is, $\sum \tau(i)$).

An interesting subclass: postorder traversals

- Fully process a subtree before starting a new one
- Completely characterized by the execution order of subtrees
- Widely used in sparse matrix softwares (e.g., MUMPS, QR-MUMPS)



Preliminary results

Let (σ, τ) be an optimal traversal for MinIO of a given instance

Lemma (Schedule is enough).

Given σ: the Furthest In the Future I/O policy minimizes I/Os.

Lemma (I/O function is enough).

Given τ: a valid traversal (σ', τ) can be computed in polynomial time.

Proof.

Expand each node following:

Then minimize the memory peak.

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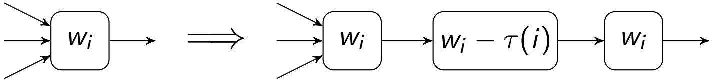

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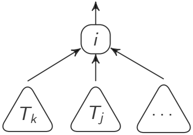
Postorder algorithms [Liu 1986, Agullo et al. 2010]

- When executing T_i : order of execution of children of i



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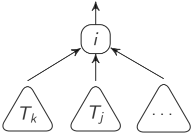

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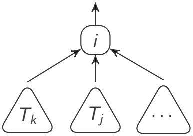

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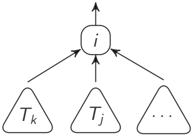

- Memory really used: $A_i = \min(S_i, M)$

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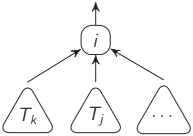
- First compute the storage requirement of subtree T_i:

$$S_i = \max\left(w_i \ , \max_{j \in Chil(i)} \left(S_j + \sum_{\substack{k \in Chil(i) \\ \sigma(k) < \sigma(j)}} w_k \right) \right)$$



- Memory really used: $A_i = \min(S_i, M)$
- For a given order σ, the volume of I/O is given by:

$$V_i = \max\left(0, \max_{j \in Chil(i)} \left(A_j + \sum_{\substack{k \in Chil(i) \\ \sigma(k) < \sigma(j)}} w_k \right) - M \right) + \sum_{j \in Chil(i)} V_j$$

Best Postorder for Minimizing I/Os

For a given order σ, the volume of I/O is given by:

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Theorem.

Given a set of values (x_i, y_i), the minimum of $\max(x_i + \sum_{j<i} y_j)$ is obtained by sorting the sequence by decreasing $x_i - y_i$.

Corollary

The postorder traversal that minimizes I/Os sorts the subtrees by decreasing $A_j - w_j$.

Minimizing I/Os for Homogeneous Trees

Theorem.

Both PostOrderMinMem and PostOrderMinIO minimize I/Os on homogeneous trees (unit sizes).

Note: PostOrderMinMem does not rely on M so is optimal for any memory size and several memory layers (cache-oblivious)

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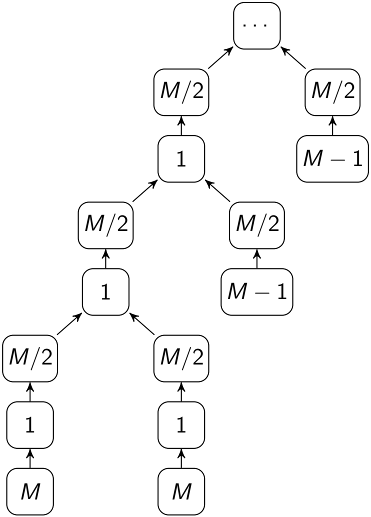
Both PostOrderMinMem and PostOrderMinIO minimize I/Os on homogeneous trees (unit sizes).

Note: PostOrderMinMem does not rely on M so is optimal for any memory size and several memory layers (cache-oblivious)

But PostOrderMinIO is not competitive on heterogeneous trees:

- Cases when PostOrderMinIO needs I/O why optimal traversal does not
- Even in when the optimal traversal requires I/Os...

PostOrderMinIO is not competitive



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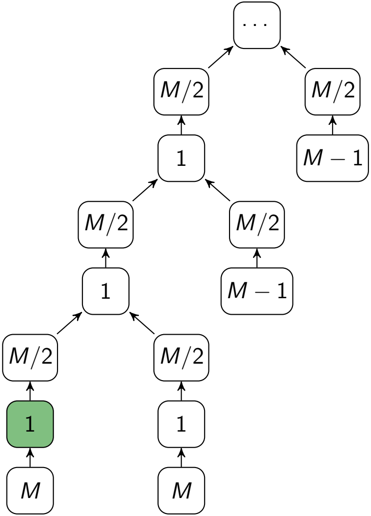

I/O optimal

- Peak memory: $M+1$
- I/Os: 1

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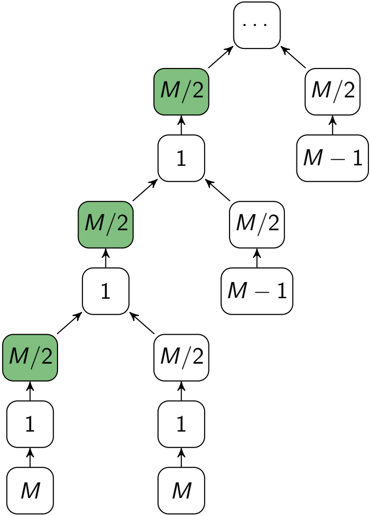


I/O optimal

- Peak memory: $M + 1$
- I/Os: 1

PostOrderMinIO

- Peak memory: $\frac{3}{2}M$
- I/Os: $\Theta(|V|M)$

Competitive ratio: $\Omega(|V|M)$

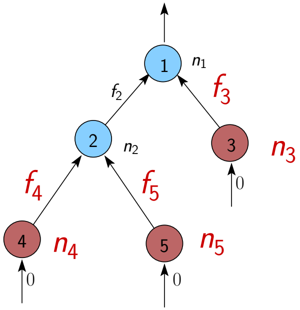
MinIO for Trees – Summary

- PostOrder algorithms optimal for homogeneous trees
- No known competitive algorithms for heterogeneous trees
- Heterogeneous trees: still an open problem!

Outline

Model for Parallel Tree Processing

- p uniform processors
- Shared memory of size M
- Task i has execution times p_i
- Parallel processing of nodes $\Rightarrow$ larger memory
- Trade-off time vs. memory



NP-Completeness in the Pebble Game Model

Background:

- Makespan minimization NP-complete for trees ($P|trees|C_{\max}$)
- Polynomial when unit-weight tasks ($P|p_i = 1, trees|C_{\max}$)
- Pebble game polynomial on trees

Pebble game model:

- Unit execution time: $p_i = 1$
- Unit memory costs: $n_i = 0, f_i = 1$
  (pebble edges, equivalent to pebble game for trees)

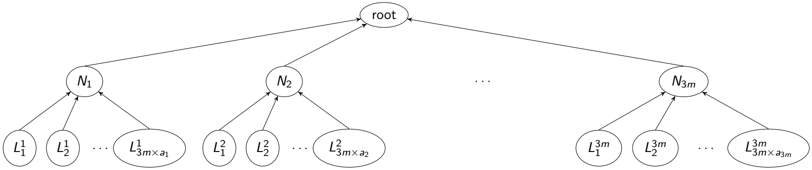
Theorem

Deciding whether a tree can be scheduled using at most B pebbles in at most C steps is NP-complete.

NP-Completeness – Proof

Reduction from 3-Partition:

- $3m$ integers a_i and B with $\sum ai = mB$,
- find m subsets S_k of 3 elements with $\sum_{i \in S_k} a_i = B$



Schedule the tree using:

- $p = 3mB$ processors,
- at most $B = 3m \times B + 3m$ pebbles,
- at most $C = 2m + 1$ steps.

Space-Time Tradeoff

Not possible to get a guarantee on both memory and time simultaneously:

Theorem 1

There is no algorithm that is both an α-approximation for makespan minimization and a β-approximation for memory peak minimization when scheduling tree-shaped task graphs.

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Lemma

For a schedule with peak memory M and makespan $C_{\max}$,

$$M \times C_{\max} \geq 2(n-1)$$

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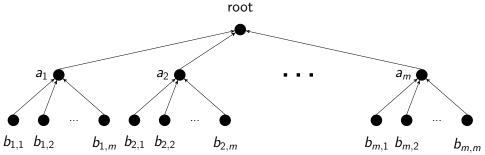
Corollary: Lower Bound on Space-Time Product

For a schedule with peak memory M and makespan $C_{\max}$,

$$M \times C_{\max} \geq \sum_i mem\_needed\_for\_task_i \times p_i$$

Space-Time Tradeoff – Proof



- With m^2 processors: $C^*_{\max} = 3$
- With 1 processor, sequentialize the a_i subtrees: $M^* = 2m$
- By contradiction, approximating both objectives: $C_{\max} \leq 3\alpha$ and $M \leq 2m\beta$
- But $M \times C_{\max} \geq 2(n-1) = 2m^2 + 2m$
- $2m^2 + 2m \leq 6m\alpha\beta$
- Contradiction for a sufficiently large value of m

Complexity – Summary

For task trees:

- Optimizing both makespan memory is NP-Complete
  $\Rightarrow$ Same for minimizing makespan under memory budget
- No scheduling algorithm can be a constant factor approximation on both memory and makespan

Outline

Minimize Memory for Trees

Minimize Memory for Series-Parallel Graphs

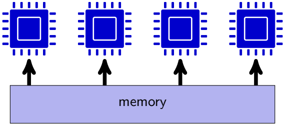
Minimize I/Os for Trees under Bounded Memory

Complexity and Space-Time Tradeoffs for Parallel Tree Processing

Parallel Processing of DAGs with Limited Memory

Processing DAGs with Limited Memory

- Schedule general graphs
- On a shared-memory platform



First option: design good static scheduler:

- NP-complete, non-approximable
- Cannot react to unpredicted changes in the platform or inaccuracies in task timings

Second option:

- Limit memory consumption of any dynamic scheduler
  Target: runtime systems
- Without impacting too much parallelism

Outline

Memory model

Task graphs with:

- Vertex weights (w_i): task (estimated) durations
- Edge weights ($m_{i,j}$): data sizes

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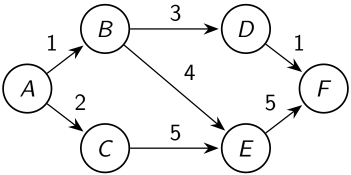
- Outputs are allocated

At the end of a task: outputs stay in memory



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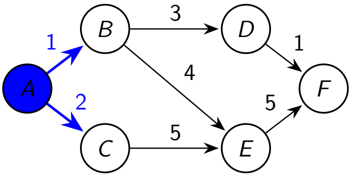

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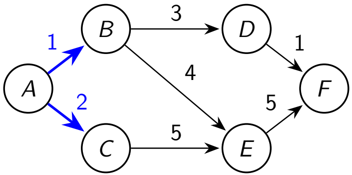

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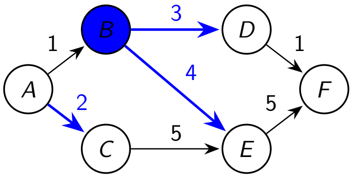

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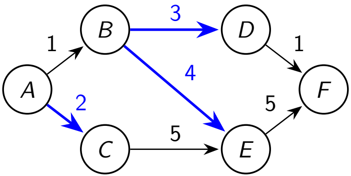

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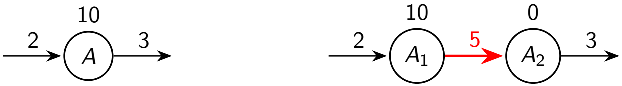
Emulation of other memory behaviours:

- Inputs + outputs allocated during task: duplicate nodes



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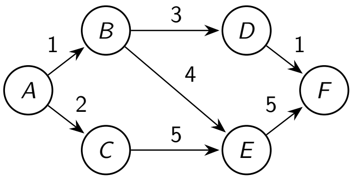
Complexity and Space-Time Tradeoffs for Parallel Tree Processing

Parallel Processing of DAGs with Limited Memory

- Model and maximum parallel memory
- Maximum parallel memory/maximal topological cut
- Efficient scheduling with bounded memory
- Heuristics and simulations

Computing the maximum memory peak

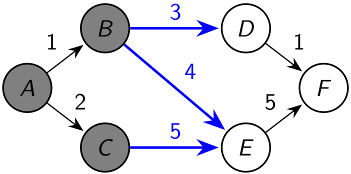


- What is the maximum memory of any parallel execution?

Computing the maximum memory peak

Topological cut: (S, T) with:

- S include the source node, T include the target node
- No edge from T to S
- Weight of the cut = weight of all edges from S to T



Any topological cut corresponds to a possible state when all node in S are completed or being processed.

Two equivalent questions (in our model):

- What is the maximum memory of any parallel execution?
- What is the topological cut with maximum weight?

Computing the maximum topological cut

Literature:

- Lots of studies of various cuts in non-directed graphs ([Diaz,2000] on Graph Layout Problems)
- Minimum cut is polynomial on both directed/non-directed graphs
- Maximum cut NP-complete on both directed/non-directed graphs ([Karp 1972] for non-directed, [Lampis 2011] for directed ones)
- Not much for topological cuts

Theorem.

Computing the maximum topological cut of a DAG can be done in polynomial time.

Maximum topological cut – using LP

- Consider one classical LP formulation for finding a minimum cut:

$$\min \sum_{(i,j)\in E} m_{i,j} d_{i,j}$$

$$\forall (i,j) \in E, \quad d_{i,j} \geq p_i - p_j$$

$$\forall (i,j) \in E, \quad d_{i,j} \geq 0$$

$$p_s = 1, \quad p_t = 0$$

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- Integer solution $\Leftrightarrow$ topological cut
- Then change the optimization direction (min $\rightarrow$ max)
- Draw w uniformly in $]0,1[$, define the cut such that $S_w = \{i \mid p_i > w\}, \quad T_w = \{i \mid p_i \leq w\}$
- Expected cost of this cut $= M^*$ (opt. rational solution)
- All cuts with random w have the same cost M^*

Maximum topological cut – direct algorithm

- Dual problem: Min-Flow *(larger than all edge weights)*
- Idea: use an optimal algorithm for Max-Flow

Algorithm sketch

Complexity: same as maximum flow, e.g., $O(|V|^2|E|)$

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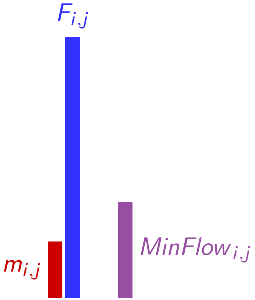

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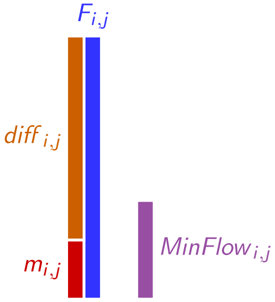
2. Consider G^{diff} with edge weights $F_{i,j} - m_{i,j}$



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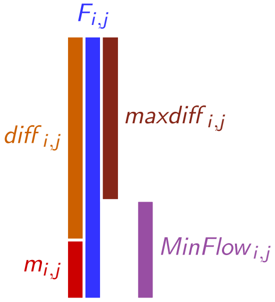

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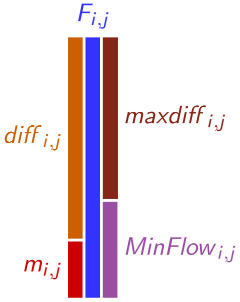
4. $F - maxdiff$ is a minimum flow in G
5. Residual graph → maximum topological cut



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Summary 1

Predict the maximal memory of any dynamic scheduling

$\Leftrightarrow$

Compute the maximal topological cut

Two algorithms:

- Linear program + rounding
- Direct algorithm based on MaxFlow/MinCut

Downsides:

- Large running time: $O(|V|^2|E|)$ or solving a LP
- May include edges corresponding to the computing of more than p tasks

Faster Max. Memory Computation for SP Graphs

Recursive algorithm to compute maximum topological cut on SP-graphs:

- Single edge $i \to j$:
  $M(G) = m_{i,j}$
- Series combination:
  $M(G) = max(M(G_1), M(G_2))$
- Parallel combination:
  $M(G) = M(G_1) + M(G_2)$

Complexity: $O(|E|)$
Proof:

- consider tree of compositions: (full) binary tree
- $|E|$ leaves
- $|E| - 1$ internal nodes (compositions)

Maximum memory with p processors

Change in the model:

- Black (regular) edges
- Red edges corresponding to computations

Definition.

P-MaxTopCut Given a graph with black/red edges and a number p of processor, what is the maximal weight of a topological cut including at most p red edges ?

Theorem.

P-MaxTopCut is NP-complete

Special Case of SP Graphs – Exact Algorithm

Compute the maximum memory with p red edges $M(G, p)$:

- Adapt previous algorithm:
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  $M(G, k) = max_{j=0,\ldots k} M(G_1, j) + M(G_2, k - j)$

Complexity:

- Simple Dynamic Programming algorithm: $O(|E|p^2)$.
- By restricting the search on each subgraph to $w(G)$ (maximum width), and with tighter analysis: $O(|E|p)$.

Special Case of SP Graphs – Approximation

Definition (Dual Approximation).

For a given guess λ, algo. that answers "1" if $M(G, p) \leq \lambda$ and "0" if $M(G, p) > \lambda/2$.

Idea:

- Consider only edges whose weight is $> \lambda/2p$
- Apply SP algorithms for without bound on p
- Return 1 iff $M(G, \infty) \geq \lambda/2$

Using binary search: 2-approximation algorithm

Summary 2

Predict the maximal memory of any dynamic scheduling

$\Leftrightarrow$

Compute the maximal topological cut

Two algorithms:

- Linear program + rounding
- Direct algorithm based on MaxFlow/MinCut

Downsides:

- Large running time ($O(|V|^2|E|)$)
- Taking into account the bound on task being processed makes the problem NP complete

Special case of SP graphs:

- Max. Top. cut computed in $O(|E|)$
- Max. Top. cut with p procs computed in $O(|E|p)$
- Max. Top. cut with p procs: 2-approximation in $O(|E|)$

Outline

Coping with limiting memory

Problem:

- Limited available memory M
- Allow use of dynamic schedulers
- Avoid running out of memory
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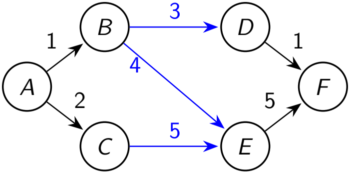
- Minimize the obtained critical path



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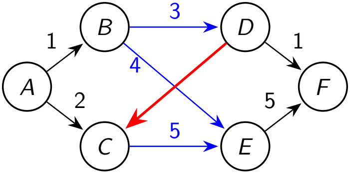

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Problem definition and complexity

Definition (PartialSerialization).

Given a DAG $G = (V, E)$ and a bound M, find a set of new edges E' such that $G' = (V, E \cup E')$ is a DAG, $MaxMem(G') \leq M$ and $CritPath(G')$ is minimized.

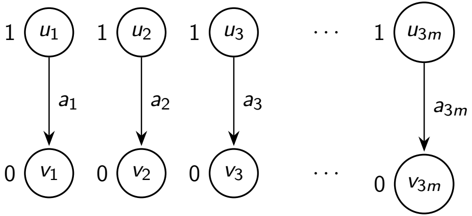
Theorem.

PartialSerialization is NP-hard in the stronge sense.

NB: stays NP-hard if we are given a sequential schedule σ of G which uses at most a memory M.

NP-completeness – proof sketch

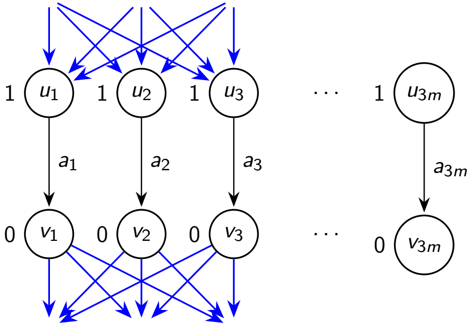
- Reduction from 3-Partition: a_i s.t. $\sum a_i = mB$, solution: m sets of 3 a_i's summing to B



- Set the memory bound to B
- Bound on the critical path: m

NP-completeness – proof sketch

- Reduction from 3-Partition: a_i s.t. $\sum a_i = mB$, solution: m sets of 3 a_i's summing to B



- Set the memory bound to B
- Bound on the critical path: m
- Solution to PartialSerialization $\Leftrightarrow$ group edges by 3 s.t. $\sum a_i = B$

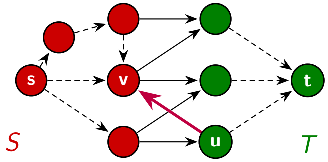
Outline

Heuristic solutions for PartialSerialization

Framework:

(inspired by [Sbîrlea et al. 2014])

1. Compute a max. top. cut (S, T)
2. If weight $\leq M$: succeeds
3. Add edge (u, v) with $u \in T,\ v \in S$ without creating cycles; or fail
4. Goto Step 1



Several heuristic choices for Step 3:

MinLevels does not create a large critical path

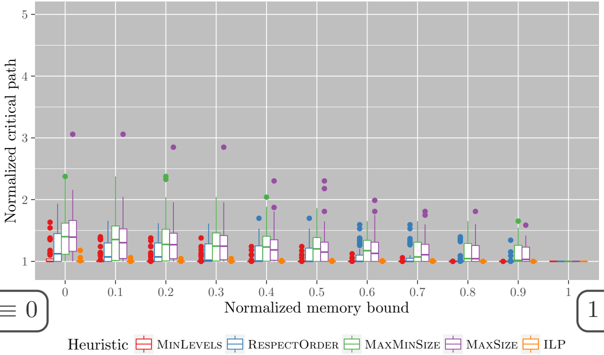
RespectOrder follows a precomputed memory-efficient schedule, always succeeds

MaxSize targets nodes dealing with large data

MaxMinSize variant of MaxSize

Simulations: dense random graphs (25, 50, 100 nodes)

lower is better



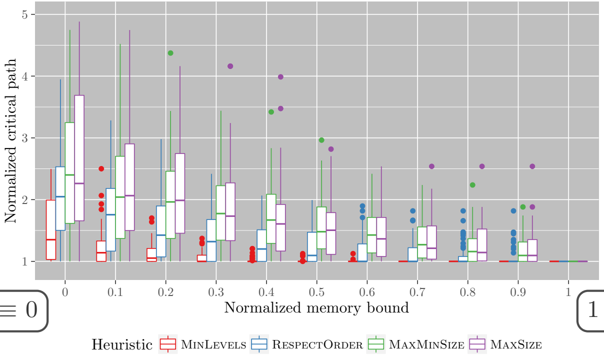
DFS memory ≡ 0

1 ≡ MaxTopCut

- *x: memory (0 = DFS, 1 = MaxTopCut)*
  median ratio MaxTopCut / DFS memory ≈ 1.3
- *y: CP / original CP → lower is better*
- MinLevels performs best

Simulations: sparse random graphs (25, 50, 100 nodes)

lower is better

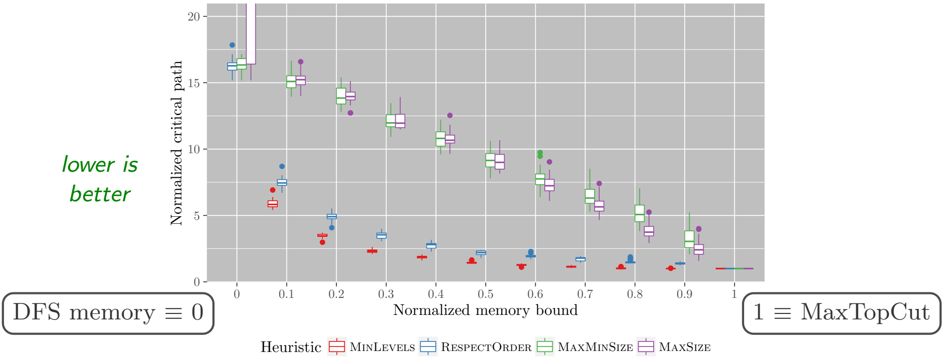


DFS memory ≡ 0

1 ≡ MaxTopCut

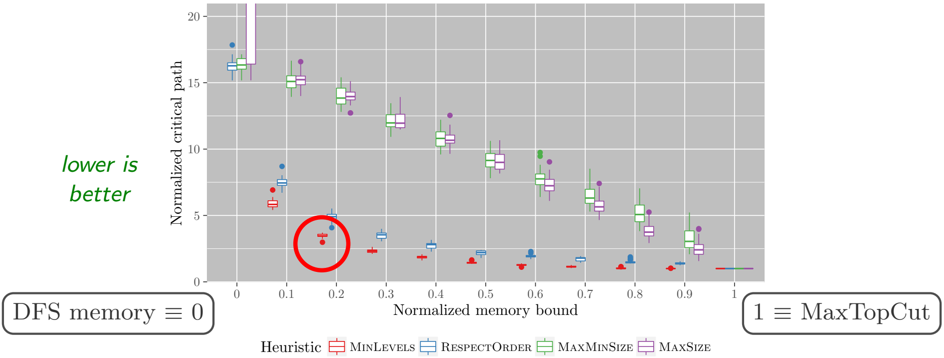
- *x: memory (0 = DFS, 1 = MaxTopCut)*
  median ratio MaxTopCut / DFS memory ≈ 2
- *y: CP / original CP → lower is better*
- MinLevels performs best, but might fail

Simulations – Pegasus workflows (LIGO 100 nodes)



- *Median ratio MaxTopCut / DFS ≈ 20*
- MinLevels performs best, RespectOrder always succeeds

Simulations – Pegasus workflows (LIGO 100 nodes)



- *Median ratio MaxTopCut / DFS ≈ 20*
- MinLevels performs best, RespectOrder always succeeds
- Memory divided by 5 for CP multiplied by 3

Summary – Memory-Aware DAG Scheduling

Several models:

1. Memory weights on edges and nodes,
   inputs+outputs+tmp needed to compute tasks
2. Memory weights only on edges
   Processing tasks ⇔ replace inputs by outputs
3. (Memory increment on nodes)

   - Model 2 emulates 1, Model 3 emulates 1 and 2, . . .
   - Choose the right model to solve each problem
   - Same for in-trees vs. out-trees

Summary – Memory-Aware DAG Scheduling

Several models:

1. Memory weights on edges and nodes,
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Results:

- One processor: optimal algorithms for trees (postorder or not)
- Several processors: NP-complete problem, no (α, β)-approx.
- Dynamic scheduling with memory bound:
  - Compute the worst memory: polynomial (linear for SP-graphs)
  - Limit memory: NP-complete, heuristic solutions