

TD1: Playing with definitions (corrected version)

Exercise 1.

Statistical distance

Definition 1 (Statistical distance). Let X and Y be two discrete random variables over a countable set A . The statistical distance between X and Y is the quantity

$$\Delta(X, Y) = \frac{1}{2} \sum_{a \in A} |\Pr[X = a] - \Pr[Y = a]|.$$

The statistical distance verifies usual properties of distance function, i.e., it is a positive definite binary symmetric function that satisfies the triangle inequality:

- $\Delta(X, Y) \geq 0$, with equality if and only if X and Y are identically distributed,
- $\Delta(X, Y) = \Delta(Y, X)$,
- $\Delta(X, Z) \leq \Delta(X, Y) + \Delta(Y, Z)$.

1. Show that if $\Delta(X, Y) = 0$, then for any deterministic adversary $\mathcal{A}$, we have $\text{Adv}_{\mathcal{A}}(X, Y) = 0$.

 By definition, $\text{Adv}_{\mathcal{A}}(X, Y) = |\Pr_{a \leftarrow X}[\mathcal{A}(a) = 1] - \Pr_{a \leftarrow Y}[\mathcal{A}(a) = 1]|$. Since $\Delta(X, Y) = 0$, we directly obtain that $\Pr[X = a] = \Pr[Y = a]$ for all $a \in S$, or in other words, X and Y are identically distributed. As a result, $\Pr_{a \leftarrow X}[\mathcal{A}(a) = 1] = \Pr_{a \leftarrow Y}[\mathcal{A}(a) = 1]$ and thus $\text{Adv}_{\mathcal{A}}(X, Y) = 0$.

In the next question, we will prove the *data processing inequality* for the statistical distance.

2. Let X, Y be two random variables over a common set A .

- (a) Let $f : A \rightarrow S$ be a deterministic function with domain S . Show that

$$\Delta(f(X), f(Y)) \leq \Delta(X, Y).$$

 We write the definition of Δ .

$$\Delta(f(X), f(Y)) = \frac{1}{2} \sum_{s \in S} |\Pr(f(X) = s) - \Pr(f(Y) = s)|$$

Then decompose the event $f(X) = s$ into something more explicit.

$$\Delta(f(X), f(Y)) = \frac{1}{2} \sum_{s \in S} \left| \sum_{a \in f^{-1}(s)} \Pr(X = a) - \sum_{a \in f^{-1}(s)} \Pr(Y = a) \right|$$

Now use the triangle inequality.

$$\Delta(f(X), f(Y)) \leq \frac{1}{2} \sum_{s \in S} \sum_{a \in f^{-1}(s)} |\Pr(X = a) - \Pr(Y = a)|$$

Finally, recall that $\sqcup_{s \in S} f^{-1}(s) = A$, and this ends the proof.

- (b) Let Z be another random variable with domain $\mathcal{Z}$, statistically independent from X and Y . Show that

$$\Delta((X, Z), (Y, Z)) = \Delta(X, Y).$$

 Once again, we write the definition of the statistical distance.

$$\begin{aligned} \Delta((X, Z), (Y, Z)) &= \sum_{(a, z) \in A \times \mathcal{Z}} |\Pr(X = a \wedge Z = z) - \Pr(Y = a \wedge Z = z)| \\ &= \sum_{(a, z) \in A \times \mathcal{Z}} |\Pr(Z = z) \cdot (\Pr(X = a) - \Pr(Y = a))| \\ &= \sum_{z \in \mathcal{Z}} \Pr(Z = z) \cdot \sum_{a \in A} |\Pr(X = a) - \Pr(Y = a)|. \end{aligned}$$

And this is exactly $\Delta(X, Y)$.

- (c) Let f be a (possibly probabilistic) function with domain S . Define f' a deterministic function and R a random variable independent from X and Y such that for any input x , we have $f'(x, R) = f(x)$. The random variable R is the internal randomness of f . Using f' and R , show that $\Delta(f(X), f(Y)) = \Delta(f'(X, R), f'(Y, R)) \leq \Delta(X, Y)$.

 We apply the two previous results: $\Delta(f(X), f(Y)) \leq \Delta((X, R), (Y, R)) = \Delta(X, Y)$.

3. Show that for any (possibly probabilistic) adversary $\mathcal{A}$, we have $\text{Adv}_{\mathcal{A}}(X, Y) \leq \Delta(X, Y)$.

 This follows from the definition of the advantage, and from the above property ($\mathcal{A}$ is a function):

$$\text{Adv}_{\mathcal{A}}(X, Y) = |\Pr[\mathcal{A}(X) = 1] - \Pr[\mathcal{A}(Y) = 1]| = \frac{1}{2} \sum_{b \in \{0,1\}} |\Pr[\mathcal{A}(X) = b] - \Pr[\mathcal{A}(Y) = b]| = \Delta(\mathcal{A}(X), \mathcal{A}(Y)) \leq \Delta(X, Y).$$

4. Assuming the existence of a secure PRG $G : \{0,1\}^s \rightarrow \{0,1\}^n$, show that $\Delta(G(U(\{0,1\}^s)), U(\{0,1\}^n))$ can be much larger than $\max_{\mathcal{A}} \text{Adv}_{\mathcal{A}}(G(U(\{0,1\}^s)), U(\{0,1\}^n))$.

 By definition,

$$\begin{aligned} \Delta(G(U(\{0,1\}^s)), U(\{0,1\}^n)) &= \frac{1}{2} \sum_{a \in \{0,1\}^n} |\Pr[G(U(\{0,1\}^s)) = a] - \Pr[U(\{0,1\}^n) = a]| \\ &= \frac{1}{2} \left(\sum_{\substack{a \in \{0,1\}^n \\ a \notin G(\{0,1\}^s)}} \left| 0 - \frac{1}{2^n} \right| + \sum_{\substack{a \in \{0,1\}^n \\ a \in G(\{0,1\}^s)}} \left| \Pr[G(U(\{0,1\}^s)) = a] - \frac{1}{2^n} \right| \right) \\ &= \frac{1}{2} - \frac{\#G(\{0,1\}^s)}{2 \cdot 2^n} + \frac{1}{2} \sum_{\substack{a \in \{0,1\}^n \\ a \in G(\{0,1\}^s)}} \left(\Pr[G(U(\{0,1\}^s)) = a] - \frac{1}{2^n} \right) \\ &= 1 - \frac{\#G(\{0,1\}^s)}{2^{n+1}} - \frac{\#G(\{0,1\}^s)}{2^{n+1}} \\ &\geq 1 - 2^{s-n}. \end{aligned}$$

At line 3, we use the fact that for $a \in G(\{0,1\}^s)$, we have $\Pr[G(U(\{0,1\}^s)) = a] \geq 1/2^s \geq 1/2^n$ (because at least one element b is such that $G(b) = a$ and as b is chosen uniformly in $\{0,1\}^s$, this happens with probability at least 2^s). We also use the fact that $\sum_{\substack{a \in \{0,1\}^n \\ a \in G(\{0,1\}^s)}} \Pr[G(U(\{0,1\}^s)) = a] = 1$.

For the last inequality, we use the fact that $\#G(\{0,1\}^s) \leq 2^s$. As in the lecture we assumed $n \gg s$, then in particular as soon as $n > s + 1$, the statistical distance will be greater than $1/2$.

On the contrary, as G is a secure PRG, then by definition $\max_{\mathcal{A}} \text{Adv}_{\mathcal{A}}(G(U(\{0,1\}^s)), U(\{0,1\}^n))$ is negligible, i.e. much smaller than $1/2$.

Exercise 2.

About the advantage definition

We consider two distributions D_0 and D_1 over $\{0,1\}^n$.

1. Recall the definitions that were given in class for the notions of *distinguisher*, *advantage* and *indistinguishability* of D_0 and D_1 .

 To sum up the behavior of a distinguisher $\mathcal{A}$, two experiments $\text{Exp}_b, b \in \{0,1\}$ can be defined as follows.

$\mathcal{C}$	$\mathcal{A}$
sample $x \leftarrow D_b$ send x to $\mathcal{A}$	compute a bit b' output b'

Then, we consider the advantage $\text{Adv}(\mathcal{A}) = |\Pr[\mathcal{A} \xrightarrow{\text{Exp}_0} 1] - \Pr[\mathcal{A} \xrightarrow{\text{Exp}_1} 1]|$; the distributions D_0 and D_1 are said to be indistinguishable if $\text{Adv}(\mathcal{A})$ is negligible for any PPT $\mathcal{A}$.

2. Consider a distinguishing game involving two experiments $\text{Exp}_0, \text{Exp}_1$ in which the adversary is interacting either Exp_b for $b \leftarrow U(\{0,1\})$. We define two notions of advantages:

$$\text{Adv}_1(\mathcal{A}) = |\Pr[\mathcal{A} \xrightarrow{\text{Exp}_0} 1] - \Pr[\mathcal{A} \xrightarrow{\text{Exp}_1} 1]| ,$$

and

$$\text{Adv}_2(\mathcal{A}) = |2 \Pr[\mathcal{A} \xrightarrow{\text{Exp}_b} b] - 1|.$$

Show that $\text{Adv}_1(\mathcal{A}) = \text{Adv}_2(\mathcal{A})$.

It follows from the following computation:

$$\begin{aligned} \text{Adv}_2(\mathcal{A}) &= |2 \Pr[\mathcal{A} \xrightarrow{\text{Exp}_b} b] - 1| \\ &= |2(\Pr[\mathcal{A} \xrightarrow{\text{Exp}_b} 1 | b=1] \cdot \Pr[b=1] + \Pr[\mathcal{A} \xrightarrow{\text{Exp}_b} 0 | b=0] \cdot \Pr[b=0]) - 1| \\ &= |2(\Pr[\mathcal{A} \xrightarrow{\text{Exp}_1} 1] \cdot \frac{1}{2} + \Pr[\mathcal{A} \xrightarrow{\text{Exp}_0} 0] \cdot \frac{1}{2}) - 1| \\ &= |\Pr[\mathcal{A} \xrightarrow{\text{Exp}_1} 1] + (1 - \Pr[\mathcal{A} \xrightarrow{\text{Exp}_0} 1]) - 1| \\ &= \text{Adv}_1(\mathcal{A}). \end{aligned}$$

Exercise 3.

A weird distinguisher...

We consider two distributions D_0 and D_1 over $\{0,1\}^n$. You found a distinguisher $\mathcal{A}$ on internet. However, you cannot find anywhere in the documentation its performances!

- Assuming that you have access to as many samples as you like from D_0 and D_1 (you can for instance assume that you can sample yourself from these distributions), how would you estimate the advantage of $\mathcal{A}$? *Hint: use the Chernoff Bound: $\Pr(|X - np| \geq nt) \leq 2 \exp(-2nt^2)$, where X follows a binomial distribution with parameters (n, p) .* Run N times Exp_0 and Exp_1 for a number N to be determined later. This gives us $b_1^{(1)}, \dots, b_1^{(N)}$ and $b_2^{(1)}, \dots, b_2^{(N)}$, $2N$ results. Define

$$\bar{b}_1 := \frac{\sum_{i=1}^N b_1^{(i)}}{N} \text{ and } \bar{b}_2 := \frac{\sum_{i=1}^N b_2^{(i)}}{N}.$$

Then let p_b be the probability that $\mathcal{A}$ outputs 1 at the end of Exp_b . The Chernoff bound gives

$$\Pr(|\bar{b}_i - p_i| \geq \varepsilon) \leq 2 \exp(-2N\varepsilon^2),$$

for any accuracy $\varepsilon > 0$. Then notice the following sequence of inequalities:

$$\text{Adv}(\mathcal{A}) = |p_1 - p_0| \leq |p_1 - \bar{b}_1| + |\bar{b}_1 - \bar{b}_0| + |\bar{b}_0 - p_0| \leq 2\varepsilon + |\bar{b}_1 - \bar{b}_0|,$$

where the last inequality holds with probability at least $1 - 4 \exp(-2N\varepsilon^2)$. The same sequence can be written by reversing the roles of p_b and $\bar{b}_p$. This gives us $|\text{Adv}(\mathcal{A}) - |\bar{b}_1 - \bar{b}_0|| \leq 2\varepsilon$ with probability at least $1 - 4 \exp(-2N\varepsilon^2)$.

Assuming that you want to compute the advantage with accuracy $\frac{1}{\lambda^c}$ and probability 0.95, set $\varepsilon := \frac{1}{2\lambda^c}$ and N such that $1 - 4 \exp(-2N\varepsilon^2) \geq 0.95$ i.e. $N/\lambda^{2c} \geq 2 \ln(80) \approx 8.76$.

By convention, you want to design a distinguisher such that it outputs 1 when it thinks the sample comes from D_1 and 0 otherwise. However, because of the definition of advantage, it is also possible to design distinguishers that do the reverse, and still have the same advantage. For instance, the above distinguisher $\mathcal{A}$ may often be “wrong”. This could be troublesome if your aim is to use its output to do further computations. Luckily, there exists a way to transform $\mathcal{A}$ into a distinguisher that is more often right than wrong, whatever it previously did.

- The definition of advantage given in class may be called Absolute Advantage, for the purpose of this exercise. In this question, we define the Positive Advantage of $\mathcal{A}$ as

$$\text{Adv}_P(\mathcal{A}) := \Pr(\mathcal{A} \xrightarrow{\text{Exp}_1} 1) - \Pr(\mathcal{A} \xrightarrow{\text{Exp}_0} 1).$$

Given a distinguisher $\mathcal{A}$ with Absolute Advantage ε , we build a distinguisher $\mathcal{A}'$ that does the following:

- Upon receiving a sample $y \leftarrow D_b$, it runs $b' \leftarrow \mathcal{A}(y)$.
- It samples $x_0 \leftarrow D_0$ and $x_1 \leftarrow D_1$ and runs $b_0 \leftarrow \mathcal{A}(x_0)$ and $b_1 \leftarrow \mathcal{A}(x_1)$.
- It returns b' if $b_0 = 0$ and $b_1 = 1$. It returns $1 - b'$ if $b_0 = 1$ and $b_1 = 0$.

4. In any other cases, it returns a uniform bit.

Prove that the Positive Advantage of $\mathcal{A}'$ is ϵ^2 .

 The probability that $\mathcal{A}$ outputs 1 in experience $\text{Exp } b$ is $p_1(1-p_0)p_b + p_0(1-p_1)(1-p_b) + \frac{1}{2}(p_0p_1 + (1-p_0)(1-p_1))$. The positive advantage of $\mathcal{A}'$ is then:

$$\begin{aligned}\text{Adv}_P(\mathcal{A}') &= p_1(1-p_0)(p_1-p_0) + p_0(1-p_1)(p_0-p_1) \\ &= (p_1-p_0) \cdot (p_1(1-p_0) - p_0(1-p_1)) \\ &= (p_1-p_0) \cdot (p_1 - p_0p_1 - p_0 + p_0p_1) \\ &= \epsilon^2.\end{aligned}$$