

Signal Processing and Networks Optimization Part VI: Duality

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Fenchel-Rockafellar duality

Primal problem

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$. Let $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

We want to

$$\underset{x \in \mathcal{H}}{\text{minimize}} \quad f(x) + g(Lx).$$

Dual problem

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$. Let $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

We want to

$$\underset{v \in \mathcal{G}}{\text{minimize}} \quad f^*(-L^*v) + g^*(v).$$

Fenchel-Rockafellar duality

Weak duality

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let f be a proper function from \mathcal{H} to $]-\infty, +\infty]$, g be a proper function from \mathcal{G} to $]-\infty, +\infty]$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$. Let

$$\mu = \inf_{x \in \mathcal{H}} f(x) + g(Lx) \quad \text{and} \quad \mu^* = \inf_{v \in \mathcal{G}} f^*(-L^*v) + g^*(v).$$

We have $\mu \geq -\mu^*$. If $\mu \in \mathbb{R}$, $\mu + \mu^*$ is called the **duality gap**.

Fenchel-Rockafellar duality

Weak duality

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We have $\mu \geq -\mu^*$. If $\mu \in \mathbb{R}$, $\mu + \mu^*$ is called the **duality gap**.

Proof: According to Fenchel-Young inequality, for every $x \in \mathcal{H}$ and $v \in \mathcal{G}$,

$$f(x) + g(Lx) + f^*(-L^*v) + g^*(v) \geq \langle x \mid -L^*v \rangle + \langle Lx \mid v \rangle = 0$$

Fenchel-Rockafellar duality

Strong duality

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

If $\text{int}(\text{dom } g) \cap L(\text{dom } f) \neq \emptyset$ or $\text{dom } g \cap \text{int}(L(\text{dom } f)) \neq \emptyset$, then

$$\mu = \inf_{x \in \mathcal{H}} f(x) + g(Lx) = - \min_{v \in \mathcal{G}} f^*(-L^*v) + g^*(v) = -\mu^* .$$

Example 1: Linear programming

Let $L \in \mathbb{R}^{K \times N}$, $b \in \mathbb{R}^K$, and $c \in \mathbb{R}^N$.

The primal problem

$$\text{Primal-LP : } \quad \underset{x \in [0, +\infty[^N}{\text{minimize}} \quad \langle c \mid x \rangle \quad \text{s.t.} \quad Lx \geq b$$

is associated with the the dual problem

$$\text{Dual-LP : } \quad \underset{y \in [0, +\infty[^K}{\text{maximize}} \quad \langle b \mid y \rangle \quad \text{s.t.} \quad L^T y \leq c.$$

In addition, if the primal problem has a solution, then strong duality holds.

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$$\text{Dual-LP : } \quad \underset{y \in [0, +\infty[^K}{\text{maximize}} \quad \langle b \mid y \rangle \quad \text{s.t.} \quad L^\top y \leq c.$$

In addition, if the primal problem has a solution, then strong duality holds.

Proof: Set

$$\begin{cases} (\forall x \in \mathcal{H} = \mathbb{R}^N) & f(x) = \langle c \mid x \rangle + \iota_{[0, +\infty[^N}(x), \\ (\forall z \in \mathcal{G} = \mathbb{R}^K) & g(z) = \iota_{[0, +\infty[^K}(z - b), \\ & y = -v \end{cases}$$

Example 2: Consensus and sharing

Let \mathcal{H} be a real Hilbert space.

For every $i \in \{1, \dots, m\}$, let $g_i: \mathcal{H} \rightarrow]-\infty, +\infty]$ and $h_i: \mathcal{H} \rightarrow]-\infty, +\infty]$.

The **consensus** problem is given by

$$\underset{\substack{(x_1, \dots, x_m) \in \mathcal{H}^m \\ x_1 = \dots = x_m}}{\text{minimize}} \sum_{i=1}^m g_i(x_i).$$

The **sharing problem** is given by

$$\underset{\substack{(u_1, \dots, u_m) \in \mathcal{H}^m \\ u_1 + \dots + u_m = u}}{\text{maximize}} \sum_{i=1}^m h_i(u_i), \quad u \in \mathcal{H}.$$

If, for every $i \in \{1, \dots, m\}$, $h_i = -g_i^*(\cdot - u/m)$, then sharing is the dual problem of consensus.

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The **sharing problem** is given by

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If, for every $i \in \{1, \dots, m\}$, $h_i = -g_i^*(\cdot - u/m)$, then sharing is the dual problem of consensus.

Proof: Set $L = \text{Id}$ and $(\forall x = (x_1, \dots, x_m) \in \mathcal{H}^m) \begin{cases} f(x) = \iota_{\Lambda_m}(x), \\ g(x) = \sum_{i=1}^m g_i(x_i) \end{cases}$
 where $\Lambda_m = \{(x_1, \dots, x_m) \in \mathcal{H}^m \mid x_1 = \dots = x_m\}$.

Fenchel-Rockafellar duality

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

If $\text{dom } g \cap L(\text{dom } f) \neq \emptyset$, then

$$(\forall x \in \mathcal{H}) \quad \partial f(x) + L^* \partial g(Lx) \subset \partial(f + g \circ L)(x)$$

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$. If $\text{int}(\text{dom } g) \cap L(\text{dom } f) \neq \emptyset$ and $\text{dom } g \cap \text{int}(L(\text{dom } f)) \neq \emptyset$, then

$$\partial f + L^* \partial g L = \partial(f + g \circ L)$$

Fenchel-Rockafellar duality

Duality theorem (1)

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

$$\text{zer}(\partial f + L\partial gL^*) \neq \emptyset \quad \Leftrightarrow \quad \text{zer}((-L)\partial f^*(-L^*) + \partial g^*) \neq \emptyset$$

Fenchel-Rockafellar duality

Duality theorem (1)

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

$$\text{zer}(\partial f + L\partial gL^*) \neq \emptyset \quad \Leftrightarrow \quad \text{zer}((-L)\partial f^*(-L^*) + \partial g^*) \neq \emptyset$$

Proof:

$$\begin{aligned} (\exists x \in \mathcal{H}) \quad 0 \in \partial f(x) + L^* \partial g(Lx) &\Leftrightarrow (\exists x \in \mathcal{H})(\exists v \in \mathcal{G}) \quad \begin{cases} -L^*v \in \partial f(x) \\ v \in \partial g(Lx) \end{cases} \\ &\Leftrightarrow (\exists x \in \mathcal{H})(\exists v \in \mathcal{G}) \quad \begin{cases} x \in \partial f^*(-L^*v) \\ Lx \in \partial g^*(v) \end{cases} \\ &\Leftrightarrow (\exists v \in \mathcal{G}) \quad 0 \in -L\partial f^*(-L^*v) + \partial g^*(v). \end{aligned}$$

Fenchel-Rockafellar duality

Duality theorem (2)

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

- ▶ If there exists $\hat{x} \in \mathcal{H}$ such that $0 \in \partial f(\hat{x}) + L^* \partial g(L\hat{x})$, then \hat{x} is a solution to the primal problem. Moreover, there exists a solution \hat{v} to the dual problem such that $-L^* \hat{v} \in \partial f(\hat{x})$ and $L\hat{x} \in \partial g^*(\hat{v})$.
- ▶ If there exists $(\hat{x}, \hat{v}) \in \mathcal{H} \times \mathcal{G}$ such that $-L^* \hat{v} \in \partial f(\hat{x})$ and $L\hat{x} \in \partial g^*(\hat{v})$ then \hat{x} (resp. \hat{v}) is a solution to the primal (resp. dual) problem.

If $(\hat{x}, \hat{v}) \in \mathcal{H} \times \mathcal{G}$ is such that $-L^* \hat{v} \in \partial f(\hat{x})$ and $L\hat{x} \in \partial g^*(\hat{v})$, then (\hat{x}, \hat{v}) is called a **Kuhn-Tucker point**.

Fenchel-Rockafellar duality

Proof:

$$0 \in \partial f(\hat{x}) + L^* \partial g(L\hat{x}) \subset \partial(f + g \circ L)(\hat{x}).$$

Then, according to Fermat rule, \hat{x} is a solution to the primal problem.
In addition, there exists $\hat{v} \in \mathcal{G}$ such that

$$\begin{cases} 0 \in \partial f(\hat{x}) + L^* \hat{v} \\ \hat{v} \in \partial g(L\hat{x}) \end{cases} \Leftrightarrow \begin{cases} -L^* \hat{v} \in \partial f(\hat{x}) \\ L\hat{x} \in \partial g^*(\hat{v}). \end{cases}$$

We have also $\hat{x} \in \partial f^*(-L^* \hat{v})$, which implies that

$$0 \in -L \partial f^*(-L^* \hat{v}) + \partial g^*(\hat{v}).$$

On the other hand,

$$0 \in -L \partial f^*(-L^* \hat{v}) + \partial g^*(\hat{v}) \subset \partial(f^* \circ (-L^*) + g^*)(\hat{v})$$

$\Rightarrow \hat{v}$ solution to the dual problem.

The second assertion is shown in a similar manner.

Fenchel-Rockafellar duality

Particular case:

If $f = \varphi + \frac{1}{2}\|\cdot - z\|^2$ where $\varphi \in \Gamma_0(\mathcal{H})$ and $z \in \mathcal{H}$, then

$$\begin{aligned} -L^*\hat{v} \in \partial f(\hat{x}) &\Leftrightarrow -L^*\hat{v} \in \partial\varphi(\hat{x}) + \hat{x} - z \\ &\Leftrightarrow 0 \in \hat{x} + L^*\hat{v} - z + \partial\varphi(\hat{x}). \end{aligned}$$

Hence,

$$\hat{x} = \text{prox}_{\varphi}(-L^*\hat{v} + z).$$

Link with Lagrange duality

Minimax problem

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

The primal problem is equivalent to finding

$$\mu = \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \sup_{v \in \mathcal{G}} \mathcal{L}(x, y, v)$$

where \mathcal{L} is the Lagrange function defined as

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(x, y, v) = f(x) + g(y) + \langle v \mid Lx - y \rangle$$

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$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(x, y, v) = f(x) + g(y) + \langle v \mid Lx - y \rangle$$

Proof:

$$\begin{aligned} \mu &= \inf_{x \in \mathcal{H}} f(x) + g(Lx) = \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} f(x) + g(y) + \iota_{\{0\}}(Lx - y) \\ &= \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} f(x) + g(y) + \sup_{v \in \mathcal{G}} \langle v \mid Lx - y \rangle \\ &= \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \sup_{v \in \mathcal{G}} f(x) + g(y) + \langle v \mid Lx - y \rangle. \end{aligned}$$

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Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

The dual problem is equivalent to finding

$$-\mu^* = \sup_{v \in \mathcal{G}} \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \mathcal{L}(x, y, v)$$

where \mathcal{L} is the **Lagrange function** defined as

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(x, y, v) = f(x) + g(y) + \langle v \mid Lx - y \rangle$$

Proof:

$$\begin{aligned} \mu^* &= \inf_{v \in \mathcal{G}} f^*(-L^*v) + g^*(v) = \inf_{v \in \mathcal{G}} \left(\sup_{x \in \mathcal{H}} \langle x \mid -L^*v \rangle - f(x) \right) + \left(\sup_{y \in \mathcal{G}} \langle y \mid v \rangle - g(y) \right) \\ &= \inf_{v \in \mathcal{G}} - \left(\inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} f(x) + g(y) + \langle v \mid Lx - y \rangle \right) \\ &= - \sup_{v \in \mathcal{G}} \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} f(x) + g(y) + \langle v \mid Lx - y \rangle. \end{aligned}$$

Link with Lagrange duality

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Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$, $g: \mathcal{G} \rightarrow]-\infty, +\infty]$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

The dual problem is equivalent to finding

$$-\mu^* = \sup_{v \in \mathcal{G}} \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \mathcal{L}(x, y, v)$$

where \mathcal{L} is the **Lagrange function** defined as

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(x, y, v) = f(x) + g(y) + \langle v \mid Lx - y \rangle$$

Remark: v is called the Lagrange multiplier associated with the constraint $Lx = y$.

Link with Lagrange duality

Let $(\hat{x}, \hat{y}, \hat{v}) \in \mathcal{H} \times \mathcal{G}^2$.

$(\hat{x}, \hat{y}, \hat{v})$ is a **saddle point** of the Lagrange function \mathcal{L} if

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(\hat{x}, \hat{y}, v) \leq \mathcal{L}(\hat{x}, \hat{y}, \hat{v}) \leq \mathcal{L}(x, y, \hat{v}).$$

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$. Let $(\hat{x}, \hat{y}, \hat{v}) \in \mathcal{H} \times \mathcal{G}^2$.

Assume that $\text{int}(\text{dom } g) \cap L(\text{dom } f) \neq \emptyset$ or $\text{dom } g \cap \text{int}(L(\text{dom } f)) \neq \emptyset$.

$(\hat{x}, \hat{y}, \hat{v})$ is a saddle point of the Lagrange function



(\hat{x}, \hat{v}) is a Kuhn-Tucker point and $\hat{y} = L\hat{x}$.

Link with Lagrange duality

Proof (\Rightarrow): If $(\hat{x}, \hat{y}, \hat{v})$ is a saddle point of \mathcal{L} , then it is a critical point of \mathcal{L} , that is

$$\begin{aligned} & \begin{cases} 0 \in \partial_x \mathcal{L}(\hat{x}, \hat{y}, \hat{v}) = \partial f(\hat{x}) + L^* \hat{v} \\ 0 \in \partial_y \mathcal{L}(\hat{x}, \hat{y}, \hat{v}) = \partial g(\hat{y}) - \hat{v} \\ 0 = \nabla_v \mathcal{L}(\hat{x}, \hat{y}, \hat{v}) = L\hat{x} - \hat{y} \end{cases} \\ \Leftrightarrow & \begin{cases} -L^* \hat{v} \in \partial f(\hat{x}) \\ \hat{v} \in \partial g(\hat{y}) \\ \hat{y} = L\hat{x} \end{cases} \\ \Leftrightarrow & \begin{cases} -L^* \hat{v} \in \partial f(\hat{x}) \\ L\hat{x} \in \partial g^*(\hat{v}) \\ \hat{y} = L\hat{x}. \end{cases} \end{aligned}$$

Link with Lagrange duality

Proof (\Leftarrow): Conversely, assume that (\hat{x}, \hat{v}) is a Kuhn-Tucker point and $\hat{y} = L\hat{x}$. Since \hat{x} (resp. \hat{v}) is a solution to the primal (resp. dual) problem, then

$$\begin{aligned}\mu &= \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \sup_{v \in \mathcal{G}} \mathcal{L}(x, y, v) = \sup_{v \in \mathcal{G}} \mathcal{L}(\hat{x}, \hat{y}, v) \\ -\mu^* &= \sup_{v \in \mathcal{G}} \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \mathcal{L}(x, y, v) = \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \mathcal{L}(x, y, \hat{v}).\end{aligned}$$

By strong duality, $\sup_{v \in \mathcal{G}} \mathcal{L}(\hat{x}, \hat{y}, v) = \inf_{(x,y) \in \mathcal{H} \times \mathcal{G}} \mathcal{L}(x, y, \hat{v})$, which can be rewritten as

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(\hat{x}, \hat{y}, v) \leq \mathcal{L}(x, y, \hat{v})$$

or equivalently

$$(\forall (x, y, v) \in \mathcal{H} \times \mathcal{G}^2) \quad \mathcal{L}(\hat{x}, \hat{y}, v) \leq \mathcal{L}(\hat{x}, \hat{y}, \hat{v}) \leq \mathcal{L}(x, y, \hat{v}).$$

Alternating-direction method of multipliers

Idea: iterations for finding a saddle point $(\hat{x}, \hat{y}, \hat{z})$:

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_n \in \operatorname{Argmin} \mathcal{L}(\cdot, y_n, z_n) \\ y_{n+1} \in \operatorname{Argmin} \mathcal{L}(x_n, \cdot, z_n) \\ v_{n+1} \text{ such that } \mathcal{L}(x_n, y_{n+1}, v_{n+1}) \geq \mathcal{L}(x_n, y_{n+1}, v_n). \end{cases}$$

But the convergence is not guaranteed in general !

Alternating-direction method of multipliers

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But the convergence is not guaranteed in general !

Solution: introduce an **Augmented Lagrange function**.

Let $\gamma \in]0, +\infty[$, we define

$$(\forall (x, y, z) \in \mathcal{H} \times \mathcal{G}^2) \quad \tilde{\mathcal{L}}(x, y, z) = f(x) + g(y) + \gamma \langle z \mid Lx - y \rangle + \frac{\gamma}{2} \|Lx - y\|^2$$

The Lagrange multiplier is **$v = \gamma z$** .

Alternating-direction method of multipliers

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces.

Let $f \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$. Let $(\hat{x}, \hat{y}, \hat{v}) \in \mathcal{H} \times \mathcal{G}^2$.

Assume that $\text{int}(\text{dom } g) \cap L(\text{dom } f) \neq \emptyset$ or $\text{dom } g \cap \text{int}(L(\text{dom } f)) \neq \emptyset$.

$(\hat{x}, \hat{y}, \hat{z})$ is a saddle point of the augmented Lagrange function



$(\hat{x}, \gamma \hat{z})$ is a Kuhn-Tucker point and $\hat{y} = L\hat{x}$.

Alternating-direction method of multipliers

Proof (\Rightarrow): If $(\hat{x}, \hat{y}, \hat{z})$ is a saddle point of \tilde{L} , then

$$\begin{cases} 0 \in \partial_x \tilde{\mathcal{L}}(\hat{x}, \hat{y}, \hat{z}) = \partial f(\hat{x}) + \gamma L^* \hat{z} + \gamma L^*(L\hat{x} - \hat{y}) \\ 0 \in \partial_y \tilde{\mathcal{L}}(\hat{x}, \hat{y}, \hat{z}) = \partial g(\hat{y}) - \gamma \hat{z} + \gamma(\hat{y} - L\hat{x}) \\ 0 = \nabla_z \tilde{\mathcal{L}}(\hat{x}, \hat{y}, \hat{z}) = L\hat{x} - \hat{y} \end{cases}$$

$$\Leftrightarrow \begin{cases} 0 \in \partial_x \mathcal{L}(\hat{x}, \hat{y}, \gamma \hat{z}) \\ 0 \in \partial_y \mathcal{L}(\hat{x}, \hat{y}, \gamma \hat{z}) \\ 0 = \nabla_v \mathcal{L}(\hat{x}, \hat{y}, \gamma \hat{z}). \end{cases}$$

Alternating-direction method of multipliers

Proof (\Leftarrow): Conversely, if $(\hat{x}, \gamma\hat{z})$ is a Kuhn-Tucker point and $\hat{y} = L\hat{x}$, then it is a saddle point of \mathcal{L} . In addition,

$$(\forall (x, y, z) \in \mathcal{H} \times \mathcal{G}^2) \quad \tilde{\mathcal{L}}(x, y, z) = \mathcal{L}(x, y, \gamma z) + \frac{\gamma}{2} \|Lx - y\|^2.$$

It can be deduced that

$$\begin{aligned} \tilde{\mathcal{L}}(\hat{x}, \hat{y}, z) &= \mathcal{L}(\hat{x}, \hat{y}, \gamma z) \leq \mathcal{L}(\hat{x}, \hat{y}, \gamma\hat{z}) = \tilde{\mathcal{L}}(\hat{x}, \hat{y}, \hat{z}) \\ &\leq \mathcal{L}(x, y, \gamma\hat{z}) \leq \tilde{\mathcal{L}}(x, y, \hat{z}). \end{aligned}$$

Alternating-direction method of multipliers

Algorithm for finding a saddle point:

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_n = \operatorname{argmin}_{x \in \mathcal{H}} \tilde{\mathcal{L}}(x, y_n, z_n) \\ y_{n+1} = \operatorname{argmin}_{y \in \mathcal{G}} \tilde{\mathcal{L}}(x_n, y, z_n) \\ z_{n+1} \text{ such that } \tilde{\mathcal{L}}(x_n, y_{n+1}, z_{n+1}) \geq \tilde{\mathcal{L}}(x_n, y_{n+1}, z_n). \end{cases}$$

By performing a gradient ascent on the Lagrange multiplier,

$$\begin{aligned} (\forall n \in \mathbb{N}) \quad & \begin{cases} x_n = \operatorname{argmin}_{x \in \mathcal{H}} f(x) + \gamma \langle z_n | Lx - y_n \rangle + \frac{\gamma}{2} \|Lx - y_n\|^2 \\ y_{n+1} = \operatorname{argmin}_{y \in \mathcal{G}} g(y) + \gamma \langle z_n | Lx_n - y \rangle + \frac{\gamma}{2} \|Lx_n - y\|^2 \\ z_{n+1} = z_n + \frac{1}{\gamma} \nabla_z \tilde{\mathcal{L}}(x_n, y_{n+1}, z_n) \end{cases} \\ \Leftrightarrow (\forall n \in \mathbb{N}) \quad & \begin{cases} x_n = \operatorname{argmin}_{x \in \mathcal{H}} \frac{1}{2} \|Lx - y_n + z_n\|^2 + \frac{1}{\gamma} f(x) \\ y_{n+1} = \operatorname{prox}_{\mathcal{G}}^{\frac{\gamma}{2}}(z_n + Lx_n) \\ z_{n+1} = z_n + Lx_n - y_{n+1}. \end{cases} \end{aligned}$$

Augmented Lagrangian method

ADMM algorithm (*Alternating-direction method of multipliers*)

Let \mathcal{H} and \mathcal{G} be two Hilbert spaces. Let $f \in \Gamma_0(\mathcal{H})$ and $g \in \Gamma_0(\mathcal{G})$.

Let $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$ such that L^*L is an isomorphism and let $\gamma \in]0, +\infty[$.

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We assume that $\text{int}(\text{dom } g) \cap L(\text{dom } f) \neq \emptyset$ or $\text{dom } g \cap \text{int}(L(\text{dom } f)) \neq \emptyset$, and that $\text{Argmin}(f + g \circ L) \neq \emptyset$. Let $(y_0, z_0) \in \mathcal{G}^2$ and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_n = \underset{x \in \mathcal{H}}{\text{argmin}} \frac{1}{2} \|Lx - y_n + z_n\|^2 + \frac{1}{\gamma} f(x) \\ s_n = Lx_n \\ y_{n+1} = \text{prox}_{\frac{g}{\gamma}}(z_n + s_n) \\ z_{n+1} = z_n + s_n - y_{n+1}. \end{cases}$$

We have:

- ▶ $x_n \rightarrow \hat{x}$ where $\hat{x} \in \text{Argmin}(f + g \circ L)$
- ▶ $\gamma z_n \rightarrow \hat{v}$ where $\hat{v} \in \text{Argmin}(f^* \circ (-L^*) + g^*)$.

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Sketch of the proof: ADMM can be shown to be equivalent to Douglas-Rachford applied to the dual problem.

Augmented Lagrangian method

- ▶ Extension: Splitting more than 2 functions

$$\underset{x \in \mathcal{H}}{\text{minimize}} \quad \sum_{i=1}^M f_i(x)$$

where \mathcal{H} a real Hilbert space and, for every $i \in \{1, \dots, m\}$, $f_i \in \Gamma_0(\mathcal{H})$.

- ▶ Idea: Reformulate the problem as a consensus one in the product space $\mathcal{H} = \mathcal{H}^m$

$$\underset{x=(x_1, \dots, x_m) \in \mathcal{H}}{\text{minimize}} \quad \sum_{i=1}^M f_i(x_i) + \iota_{\Lambda_m}(x)$$

where

$$\Lambda_m = \{(x_1, \dots, x_m) \in \mathcal{H} \mid x_1 = \dots = x_m\}.$$

Augmented Lagrangian method

- Use of ADMM: set

$$\begin{cases} (\forall x = (x_1, \dots, x_m) \in \mathcal{H}) & f(x) = \sum_{i=1}^M f_i(x_i) \\ g = \iota_{\Lambda_m}, \\ L = \text{Id}. \end{cases}$$

- Resulting SDMM (*Simultaneous Direction Method of Multipliers*):

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_n = \underset{x \in \mathcal{H}}{\operatorname{argmin}} \frac{1}{2} \|x - y_n + z_n\|^2 + \frac{1}{\gamma} f(x) \\ y_{n+1} = \operatorname{prox}_{\frac{g}{\gamma}}(z_n + x_n) \\ z_{n+1} = z_n + x_n - y_{n+1}. \end{cases}$$

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$$\Rightarrow P_{\Lambda_m} z_{n+1} = P_{\Lambda_m}(z_n + x_n) - P_{\Lambda_m} y_{n+1} = y_{n+1} - y_{n+1} = 0$$

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provided that $P_{\Lambda_m} z_0 = 0$.

Augmented Lagrangian method

- ▶ Projection onto Λ_m :

$$(\forall u = (u_1, \dots, u_m) \in \mathcal{H}) \quad P_{\Lambda_m}(u) = (\bar{u}, \dots, \bar{u})$$

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↪ Parallel computing of proximity operator, but centralized computation of average.

Distributed optimization

- ▶ $\mathbb{V} = \{1, \dots, m\}$ set of indices of the vertices of an undirected nonreflexive graph
 $x \in \mathcal{H}$ vector of node weights
 $E = \{e_{i,j} \mid (i,j) \in \mathbb{E}\}$ (with $i < j$) set of edges.

Distributed optimization

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- ▶ For every $(i,j) \in \mathbb{E}$, we define

- ▶ decimation operators: $L_{i,j}: \mathcal{H} \rightarrow \mathcal{H}^2: x \mapsto (x_i, x_j)$
- ▶ interpolation operators: $L_{i,j}^*: \mathcal{H}^2 \rightarrow \mathcal{H}: (y_1, y_2) \rightarrow x = (x_{i'})_{1 \leq i' \leq m}$
 where

$$(\forall i' \in \{1, \dots, m\}) \quad x_{i'} = \begin{cases} y_1 & \text{if } i' = i \\ y_2 & \text{if } i' = j \\ 0 & \text{otherwise.} \end{cases}$$

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The concatenated decimation operator $L = (L_{i,j})_{(i,j) \in \mathbb{E}}$ is such that

$$L^* L = \sum_{(i,j) \in \mathbb{E}} L_{i,j}^* L_{i,j} = \text{Diag}(d_1 \text{Id}, \dots, d_m \text{Id})$$

where, for every $i \in \{1, \dots, m\}$, d_i is the degree of vertex of index i .

Distributed optimization

► Distributed consensus

$$\underset{x=(x_1, \dots, x_m) \in \mathcal{H}}{\text{minimize}} \quad \sum_{i=1}^M f_i(x_i) + \underbrace{\iota_{\Lambda_m}(x)}_{\sum_{(i,j) \in \mathbb{E}} \iota_{\Lambda_2}((x_i, x_j))}$$

Distributed optimization

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- ▶ Use of ADMM: Set

$$\begin{aligned} (\forall x = (x_1, \dots, x_m) \in \mathcal{H}) \quad & f(x) = \sum_{i=1}^M f_i(x_i) \\ (\forall y = (y_{i,j})_{(i,j) \in \mathbb{E}} \in \mathcal{H}^{|\mathbb{E}|}) \quad & g(y) = \sum_{(i,j) \in \mathbb{E}} \iota_{\Lambda_2}(y_{i,j}). \end{aligned}$$

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- ▶ Distributed ADMM (1):

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_n = \operatorname{argmin}_{x \in \mathcal{H}} \frac{1}{2} \|Lx - y_n + z_n\|^2 + \frac{1}{\gamma} f(x) \\ s_n = Lx_n \\ y_{n+1} = \operatorname{prox}_{\frac{g}{\gamma}}(z_n + s_n) \\ z_{n+1} = z_n + s_n - y_{n+1}. \end{cases}$$

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- ▶ Distributed ADMM (2): provided that $(\forall (i, j) \in \mathbb{E}) P_{\Lambda_2} z_{0,ij} = 0$,

$$(\forall n \in \mathbb{N}) \quad \begin{cases} 0 \in L^*(Lx_n - y_n + z_n) + \frac{1}{\gamma} \partial f(x_n) \\ s_{n,ij} = (x_{n,i}, x_{n,j}), \quad (i, j) \in \mathbb{E} \\ y_{n+1,ij} = P_{\Lambda_2}(z_{n,ij} + s_{n,ij}) = P_{\Lambda_2} s_{n,ij}, \quad (i, j) \in \mathbb{E} \\ z_{n+1,ij} = z_{n,ij} + s_{n,ij} - y_{n+1,ij}, \quad (i, j) \in \mathbb{E}. \end{cases}$$

Distributed optimization

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- ▶ Distributed ADMM (3):

$$(\forall n \in \mathbb{N}) \begin{cases} 0 \in d_i x_{n,i} - (L^*(y_n - z_n))_i + \frac{1}{\gamma} \partial f_i(x_{n,i}), \quad i \in \mathbb{V} \\ s_{n,i,j} = (x_{n,i}, x_{n,j}), \quad (i, j) \in \mathbb{E} \\ y_{n+1,i,j} = P_{\Lambda_2} s_{n,i,j}, \quad (i, j) \in \mathbb{E} \\ z_{n+1,i,j} = z_{n,i,j} + s_{n,i,j} - y_{n+1,i,j}, \quad (i, j) \in \mathbb{E}. \end{cases}$$

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- ▶ Distributed ADMM (4):

$$(\forall n \in \mathbb{N}) \begin{cases} x_{n,i} = \text{prox}_{\frac{f_i}{\gamma d_i}} (d_i^{-1} (L^*(y_n - z_n))_i) & i \in \mathbb{V} \\ \bar{y}_{n+1,i,j} = \frac{1}{2} (x_{n,i} + x_{n,j}), & (i,j) \in \mathbb{E} \\ y_{n+1,i,j} = (\bar{y}_{n+1,i,j}, \bar{y}_{n+1,i,j}) \\ z_{n+1,i,j,1} = z_{n,i,j,1} + x_{n,i} - \bar{y}_{n+1,i,j}, & (i,j) \in \mathbb{E} \\ z_{n+1,i,j,2} = z_{n,i,j,2} + x_{n,j} - \bar{y}_{n+1,i,j}, & (i,j) \in \mathbb{E}. \end{cases}$$

Distributed optimization

- Distributed ADMM (4):

$$(\forall n \in \mathbb{N}) \begin{cases} x_{n,i} = \text{prox}_{\frac{f_i}{\gamma d_i}}(d_i^{-1}(L^*(y_n - z_n))_i) & i \in \mathbb{V} \\ \bar{y}_{n+1,i,j} = \frac{1}{2}(x_{n,i} + x_{n,j}), & (i,j) \in \mathbb{E} \\ y_{n+1,i,j} = (\bar{y}_{n+1,i,j}, \bar{y}_{n+1,i,j}) \\ z_{n+1,i,j,1} = z_{n,i,j,1} + x_{n,i} - \bar{y}_{n+1,i,j}, & (i,j) \in \mathbb{E} \\ z_{n+1,i,j,2} = z_{n,i,j,2} + x_{n,j} - \bar{y}_{n+1,i,j}, & (i,j) \in \mathbb{E}. \end{cases}$$

- Distributed ADMM (5):

$$(\forall n \in \mathbb{N}) \begin{cases} x_{n,i} = \text{prox}_{\frac{f_i}{\gamma d_i}}\left(d_i^{-1}\left(\sum_{j:(i,j) \in \mathbb{E}} (\bar{y}_{n,i,j} - z_{n,i,j,1}) + \sum_{j:(j,i) \in \mathbb{E}} (\bar{y}_{n,j,i} - z_{n,j,i,2})\right)\right), & i \in \mathbb{V} \\ \bar{y}_{n+1,i,j} = \frac{1}{2}(x_{n,i} + x_{n,j}), & (i,j) \in \mathbb{E} \\ z_{n+1,i,j,1} = z_{n,i,j,1} + x_{n,i} - \bar{y}_{n+1,i,j}, & (i,j) \in \mathbb{E} \\ z_{n+1,j,i,2} = z_{n,j,i,2} + x_{n,i} - \bar{y}_{n+1,j,i}, & (j,i) \in \mathbb{E}. \end{cases}$$

$$\Rightarrow \begin{cases} \bar{y}_{n+1,i,j} - z_{n+1,i,j,1} = 2\bar{y}_{n+1,i,j} - x_{n,i} - z_{n,i,j,1} = x_{n,j} - z_{n,i,j,1} \\ \bar{y}_{n+1,j,i} - z_{n+1,j,i,2} = x_{n,j} - z_{n,j,i,2} \end{cases}$$

Distributed optimization

- ▶ Distributed ADMM (5):

$$(\forall n \in \mathbb{N}) \begin{cases} x_{n,i} = \text{prox}_{\frac{f_i}{\gamma d_i}} \left(d_i^{-1} \left(\sum_{j:(i,j) \in \mathbb{E}} (\bar{y}_{n,i,j} - z_{n,i,j,1}) + \sum_{j:(j,i) \in \mathbb{E}} (\bar{y}_{n,j,i} - z_{n,j,i,2}) \right) \right), & i \in \mathbb{V} \\ \bar{y}_{n+1,i,j} = \frac{1}{2}(x_{n,i} + x_{n,j}), & (i,j) \in \mathbb{E} \\ z_{n+1,i,j,1} = z_{n,i,j,1} + x_{n,i} - \bar{y}_{n+1,i,j}, & (i,j) \in \mathbb{E} \\ z_{n+1,j,i,2} = z_{n,j,i,2} + x_{n,i} - \bar{y}_{n+1,j,i}, & (j,i) \in \mathbb{E}. \end{cases}$$

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- ▶ Distributed ADMM (6):

$$(\forall n \in \mathbb{N}) \begin{cases} z_{n+1,i,j,1} = z_{n,i,j,1} + \frac{1}{2}(x_{n,i} - x_{n,j}), & (i,j) \in \mathbb{E} \\ z_{n+1,j,i,2} = z_{n,j,i,2} + \frac{1}{2}(x_{n,i} - x_{n,j}), & (j,i) \in \mathbb{E} \\ \bar{x}_{n,i} = d_i^{-1} \left(\sum_{j:(i,j) \in \mathbb{E}} x_{n,j} + \sum_{j:(j,i) \in \mathbb{E}} x_{n,j} \right) & i \in \mathbb{V} \\ \bar{z}_{n,i} = d_i^{-1} \left(\sum_{j:(i,j) \in \mathbb{E}} z_{n,i,j,1} + \sum_{j:(j,i) \in \mathbb{E}} z_{n,j,i,2} \right) & i \in \mathbb{V} \\ x_{n+1,i} = \text{prox}_{\frac{f_i}{\gamma d_i}} \left(\bar{x}_{n,i} - \bar{z}_{n,i} \right), & i \in \mathbb{V} \end{cases}$$

Distributed optimization

- Distributed ADMM (6):

$$(\forall n \in \mathbb{N}) \begin{cases} z_{n+1,i,j,1} = z_{n,i,j,1} + \frac{1}{2}(x_{n,i} - x_{n,j}), & (i,j) \in \mathbb{E} \\ z_{n+1,j,i,2} = z_{n,j,i,2} + \frac{1}{2}(x_{n,i} - x_{n,j}), & (j,i) \in \mathbb{E} \\ \bar{x}_{n,i} = d_i^{-1} \left(\sum_{j:(i,j) \in \mathbb{E}} x_{n,j} + \sum_{j:(j,i) \in \mathbb{E}} x_{n,j} \right) & i \in \mathbb{V} \\ \bar{z}_{n,i} = d_i^{-1} \left(\sum_{j:(i,j) \in \mathbb{E}} z_{n,i,j,1} + \sum_{j:(j,i) \in \mathbb{E}} z_{n,j,i,2} \right) & i \in \mathbb{V} \\ x_{n+1,i} = \text{prox}_{\frac{f_i}{\gamma d_i}} \left(\bar{x}_{n,i} - \bar{z}_{n,i} \right), & i \in \mathbb{V} \end{cases}$$

- Distributed ADMM (final form):

$$(\forall n \in \mathbb{N}) \begin{cases} \bar{x}_{n,i} = d_i^{-1} \left(\sum_{j:(i,j) \in \mathbb{E}} x_{n,j} + \sum_{j:(j,i) \in \mathbb{E}} x_{n,j} \right) & i \in \mathbb{V} \\ \bar{z}_{n+1,i} = \bar{z}_{n,i} + d_i x_{n,i} - \bar{x}_{n,i} \\ x_{n+1,i} = \text{prox}_{\frac{f_i}{\gamma d_i}} \left(\bar{x}_{n,i} - \bar{z}_{n,i} \right), & i \in \mathbb{V}. \end{cases}$$

Primal-dual methods

Problem

Let \mathcal{H} and \mathcal{G} be two real Hilbert spaces, $f \in \Gamma_0(\mathcal{H})$, $h \in \Gamma_0(\mathcal{H})$, $g \in \Gamma_0(\mathcal{G})$, and $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

It is assumed that h is differentiable and have a β -Lipschitzian gradient with $\beta \in]0, +\infty[$.

We want to

$$\underset{x \in \mathcal{H}}{\text{minimize}} \quad f(x) + g(Lx) + h(x).$$

Primal-dual methods

- ▶ ADMM algorithm: Let $\gamma \in]0, +\infty[$.

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_n = \operatorname{argmin}_{x \in \mathcal{H}} \frac{1}{2} \|Lx - y_n + z_n\|^2 + \frac{1}{\gamma} (f(x) + h(x)) \\ y_{n+1} = \operatorname{prox}_{\frac{g}{\gamma}} (z_n + Lx_n) \\ z_{n+1} = z_n + Lx_n - y_{n+1}. \end{cases}$$

- ▶ Limitations:
 - ▶ Computation of x_n at iteration $n \in \mathbb{N}$ may be complicated.
 - ▶ Convergence requires L^*L to be invertible.
 - ▶ The smoothness of h is not exploited.

Primal-dual methods

- ▶ Idea 1: the optimization problem is reformulated as finding

$$\inf_{x \in \mathcal{H}} \sup_{v \in \mathcal{G}} f(x) + h(x) + \langle v \mid Lx \rangle - g^*(v).$$

- ▶ Arrow-Hurwitz method: Let $(\tau_n)_{n \in \mathbb{N}}$ and $(\sigma_n)_{n \in \mathbb{N}}$ be sequences in $]0, +\infty[$.

$$(\forall n \in \mathbb{N}) \quad \begin{cases} t_n \in \partial f(x_n) \\ x_{n+1} = x_n - \tau_n(t_n + \nabla h(x_n) + L^* v_n) \\ s_n \in \partial g^*(v_n) \\ v_{n+1} = v_n - \sigma_n(s_n - Lx_{n+1}) \end{cases}$$

\rightsquigarrow requires stringent conditions on the choice of the step-size (e.g. decaying to zero)

Primal-dual methods

- ▶ Idea 2: Use implicit updates

$$\begin{aligned}
 (\forall n \in \mathbb{N}) \quad & \begin{cases} t_n \in \partial f(x_{n+1}) \\ x_{n+1} = x_n - \tau_n(t_n + \nabla h(x_n) + L^* v_n) \\ s_n \in \partial g^*(v_{n+1}) \\ v_{n+1} = v_n - \sigma_n(s_n - Lx_{n+1}) \end{cases} \\
 \Leftrightarrow & \begin{cases} 0 \in x_{n+1} - x_n + \tau_n(\nabla h(x_n) + L^* v_n) + \tau_n \partial f(x_{n+1}) \\ 0 \in v_{n+1} - v_n - \sigma_n Lx_{n+1} + \sigma_n \partial g^*(v_{n+1}) \end{cases} \\
 \Leftrightarrow & \begin{cases} x_{n+1} = \text{prox}_{\tau_n f}(x_n - \tau_n(\nabla h(x_n) + L^* v_n)) \\ v_{n+1} = \text{prox}_{\sigma_n g^*}(v_n + \sigma_n Lx_{n+1}) \end{cases}
 \end{aligned}$$

\rightsquigarrow still does not converge for constant values of the step-size.

Primal-dual methods

- ▶ Idea 3: Use the approximation $x_{n+1} \simeq 2x_{n+1} - x_n$

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_{n+1} = \text{prox}_{\tau_n f}(x_n - \tau_n(\nabla h(x_n) + L^* v_n)) \\ v_{n+1} = \text{prox}_{\sigma_n g^*}(v_n + \sigma_n L(2x_{n+1} - x_n)). \end{cases}$$

Primal-dual optimization algorithm

Convergence of PD algorithm

Let \mathcal{H} and \mathcal{G} be two Hilbert spaces. Let $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

Let $f \in \Gamma_0(\mathcal{H})$ and $g \in \Gamma_0(\mathcal{G})$. Let $h \in \Gamma_0(\mathcal{H})$ have a β -Lipschitzian gradient.

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_{n+1} = \text{prox}_{\tau f}(x_n - \tau(\nabla h(x_n) + L^* v_n)) \\ v_{n+1} = \text{prox}_{\sigma g^*}(v_n + \sigma L(2x_{n+1} - x_n)). \end{cases}$$

Primal-dual optimization algorithm

Convergence of PD algorithm

Let \mathcal{H} and \mathcal{G} be two Hilbert spaces. Let $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

Let $f \in \Gamma_0(\mathcal{H})$ and $g \in \Gamma_0(\mathcal{G})$. Let $h \in \Gamma_0(\mathcal{H})$ have a β -Lipschitzian gradient.

Let $\tau \in]0, +\infty[$ and $\sigma \in]0, +\infty[$.

We assume that $\tau^{-1} - \sigma\|L\|^2 \geq \beta/2$ and $\text{zer}(\partial f + \nabla h + L^* \partial g L) \neq \emptyset$.

Let $x_0 \in \mathcal{H}$, $v_0 \in \mathcal{G}$, and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_{n+1} = \text{prox}_{\tau f}(x_n - \tau(\nabla h(x_n) + L^* v_n)) \\ v_{n+1} = \text{prox}_{\sigma g^*}(v_n + \sigma L(2x_{n+1} - x_n)). \end{cases}$$

We have:

- ▶ $x_n \rightharpoonup \hat{x} \in \text{Argmin}(f + h + g \circ L)$
- ▶ $v_n \rightharpoonup \hat{v} \in \text{Argmin}((f + g)^* \circ (-L^*) + g^*)$.

Primal-dual optimization algorithm

Convergence of PD algorithm

Let \mathcal{H} and \mathcal{G} be two Hilbert spaces. Let $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$.

Let $f \in \Gamma_0(\mathcal{H})$ and $g \in \Gamma_0(\mathcal{G})$. Let $h \in \Gamma_0(\mathcal{H})$ have a β -Lipschitzian gradient.

Let $\tau \in]0, +\infty[$ and $\sigma \in]0, +\infty[$.

We assume that $\tau^{-1} - \sigma\|L\|^2 \geq \beta/2$ and $\text{zer}(\partial f + \nabla h + L^* \partial g L) \neq \emptyset$.

Let $x_0 \in \mathcal{H}$, $v_0 \in \mathcal{G}$, and

$$(\forall n \in \mathbb{N}) \quad \begin{cases} x_{n+1} = \text{prox}_{\tau f}(x_n - \tau(\nabla h(x_n) + L^* v_n)) \\ v_{n+1} = \text{prox}_{\sigma g^*}(v_n + \sigma L(2x_{n+1} - x_n)). \end{cases}$$

We have:

- ▶ $x_n \rightharpoonup \hat{x} \in \text{Argmin}(f + h + g \circ L)$
- ▶ $v_n \rightharpoonup \hat{v} \in \text{Argmin}((f + g)^* \circ (-L^*) + g^*)$.

Sketch of the proof: rewrite the algorithm as a Forward-Backward iteration for solving a saddle point problem.

Exercise

Let \mathcal{H} and $(\mathcal{G}_i)_{1 \leq i \leq m}$ be real Hilbert spaces. Let $f \in \Gamma_0(\mathcal{H})$, let $h \in \Gamma_0(\mathcal{H})$, and, for every $i \in \{1, \dots, m\}$, let $g_i \in \Gamma_0(\mathcal{G})$ and $L_i \in \mathcal{B}(\mathcal{H}, \mathcal{G}_i)$.

It is assumed that h is differentiable and have a β -Lipschitzian gradient with $\beta \in]0, +\infty[$. Propose a primal-dual algorithm to solve

$$\underset{x \in \mathcal{H}}{\text{minimize}} \quad f(x) + \sum_{i=1}^m g_i(L_i x) + h(x).$$