#### Plan du cours

- 1. Rappel des notions de la mécanique statistique d'équilibre liens avec la réponse linéaire
  - états de Gibbs
  - Théorème de Fluctuation-Dissipation, relations de Kramers-Kronig
  - applications à la calibration de micro-systèmes (oscillateur harmonique, circuit électronique, pièges optiques, microscope à force atomique)
- 2. Modélisation de la dynamique hors d'équilibre
  - systèmes déterministes : forces conservatives et non conservatives, systèmes thermostatés
  - systèmes aléatoires : processus de Markov, dynamique de Langevin
  - Thermodynamique stochastique

#### 3. Relations de Fluctuation transitoires

- renversement temporaire
- égalités de Jarzynski et relations de Crooks
- lien avec la 2ème Loi de la Thermodynamique
- relations de Evans-Searles et de Hatano-Sasa
- application à l'oscillateur harmonique, mesure sur molécule unique et piège optique hors d'équilibre

#### 4. Relations de Fluctuations stationnaires

- états stationnaires hors d'équilibres (NESS)
- grandes déviations
- Théorème de Gallavotti-Cohen
- relations stationnaires pour la dynamique de Langevin
- exemples d'applications expérimentales dans des systèmes linéaires et non linéaires
- utilisation des relations de fluctuation pour mesurer la puissance d'un moteur moléculaire
- 5. La réponse linéaire hors d'équilibre théorie et expérience
  - généralisations autour des NESS
  - le cas de la dynamique de relaxation

## **Measuring out of equilibrium fluctuations**

Out of equilibrium fluctuations :

- 1. Chaotic dynamics
- 2. Stochastic systems

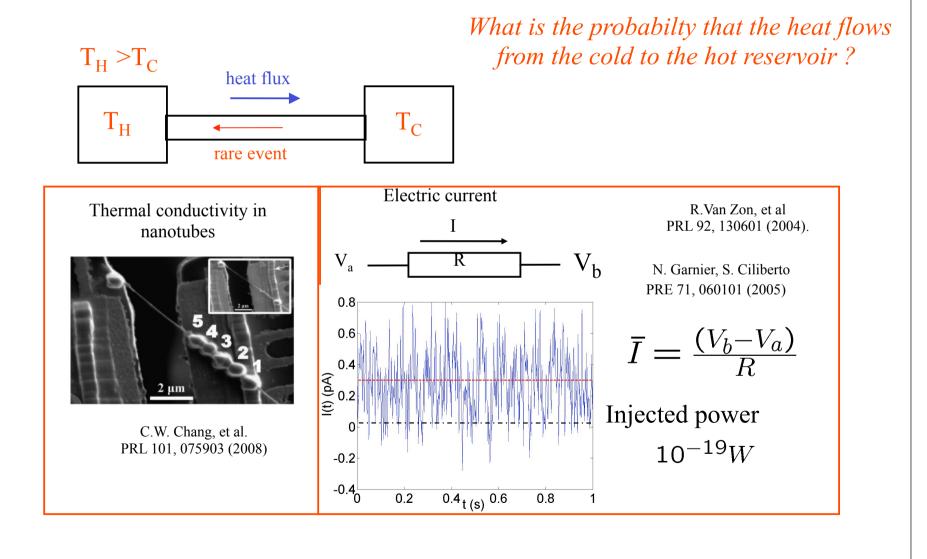
- a. System in contact with an out of equilibrium bath
- b. System in contact with several heat baths at different temperatures
- c. System driven by an external force

What can be measured in these systems?

- Fluctuation Dissipation Theorem
- Fluctuation Theorem for work, heat and entropy
- Jarzinsky equality
- Time reversal symmetry and entropy production

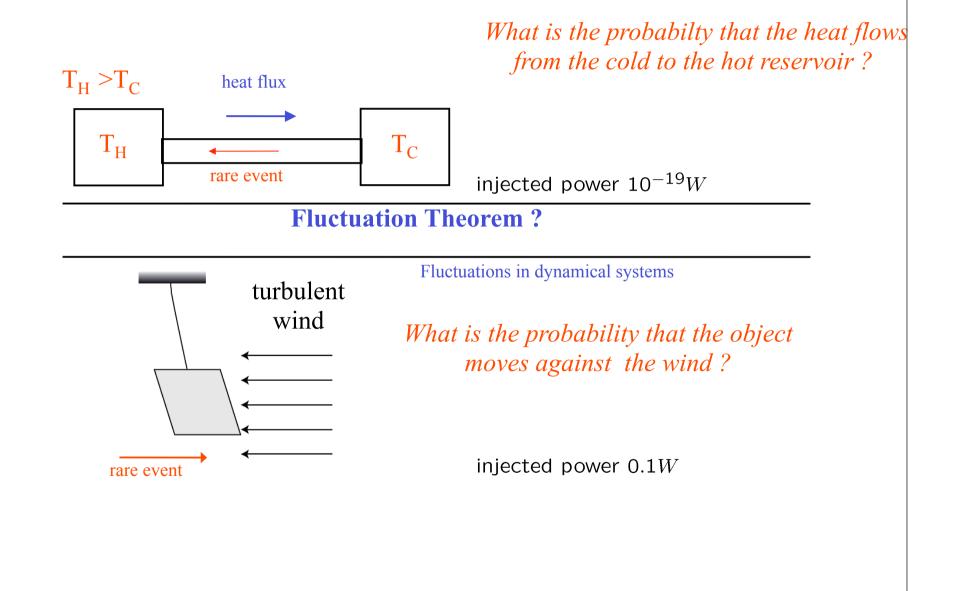
## Fluctuations in out of equilibrium systems

Steady current through a system in contact between two reservoirs



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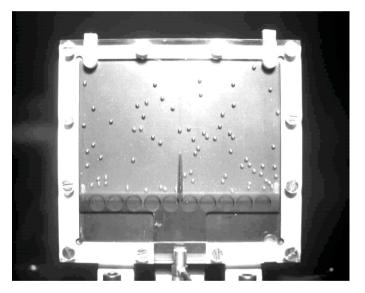


**Examples of Dynamical Systems** 

#### Vibrated granular media

#### Thermal convetion in a fluid

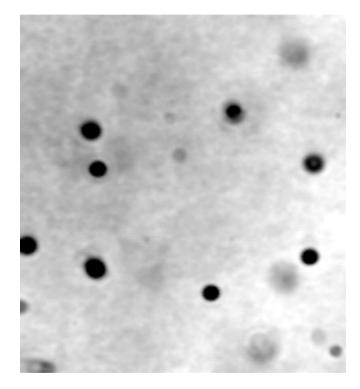
Cooled from above

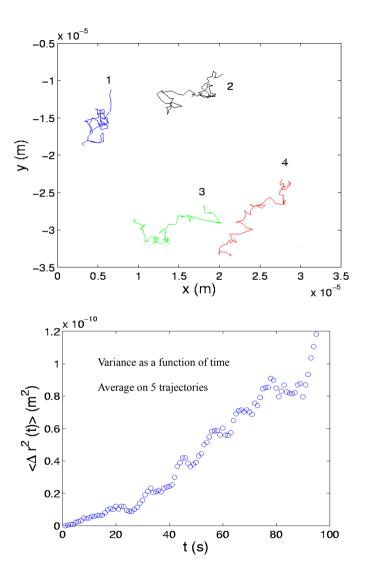




#### Heated from below

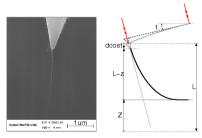
# Brownian motion EQUILIBRIUM



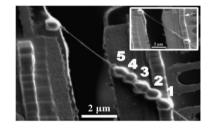


10 times faster than reality

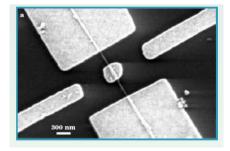
#### **Examples of stochastic systems**

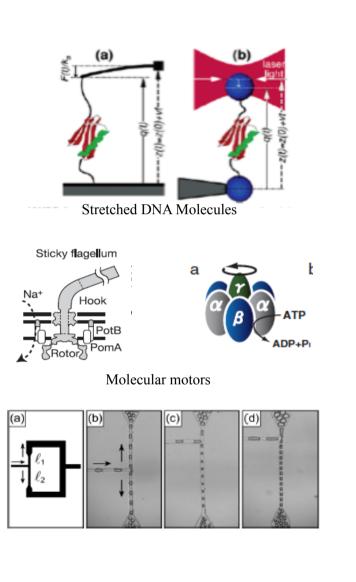


Mechanical properties of nanotubes



Thermal conduction in nanotubes

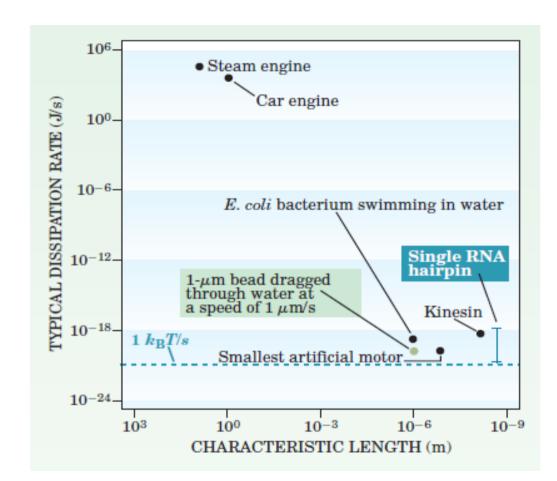




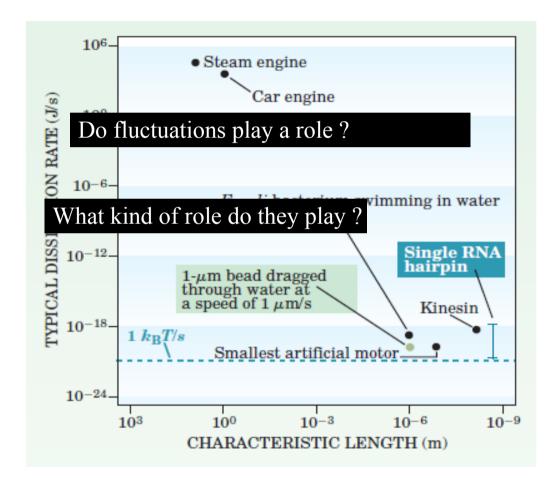
Micro Electro Mechanical Devices

Micro hydrodynamics

#### **Dissipation**



#### **Dissipation**



# **The Optical Tweezers**

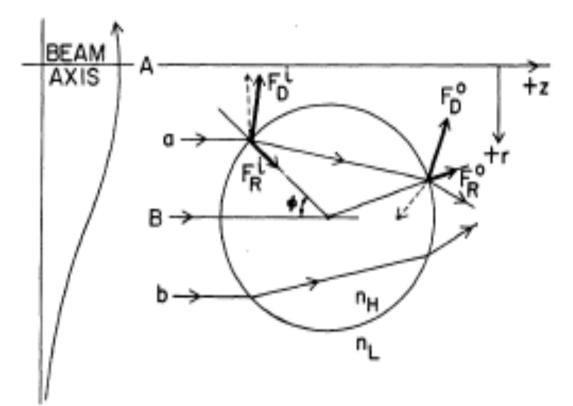
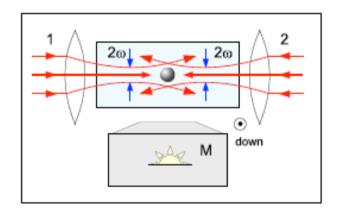
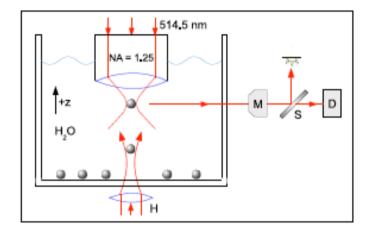


FIG. 2. A dielectric sphere situated off the axis A of a TEM<sub>00</sub>-mode beam and a pair of symmetric rays a and b. The forces due to a are shown for  $n_H > n_L$ . The sphere moves toward +z and -r.

# First trapping experiments





(a)

(b)

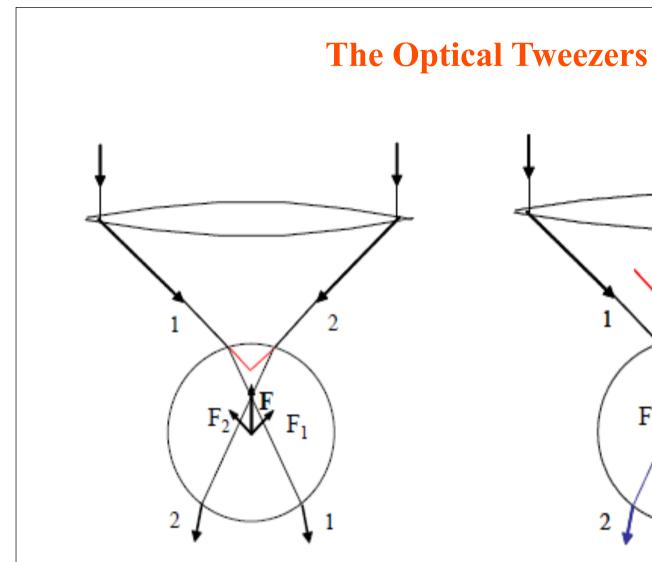
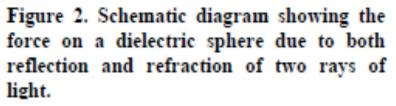


Figure 1. Schematic diagram showing the force on a dielectric sphere due to refraction of two rays of light, 1 and 2. The resultant force on the bead due to refraction is towards the focus.



refraction

F<sub>1</sub>

reflection

# **The Optical Tweezers**

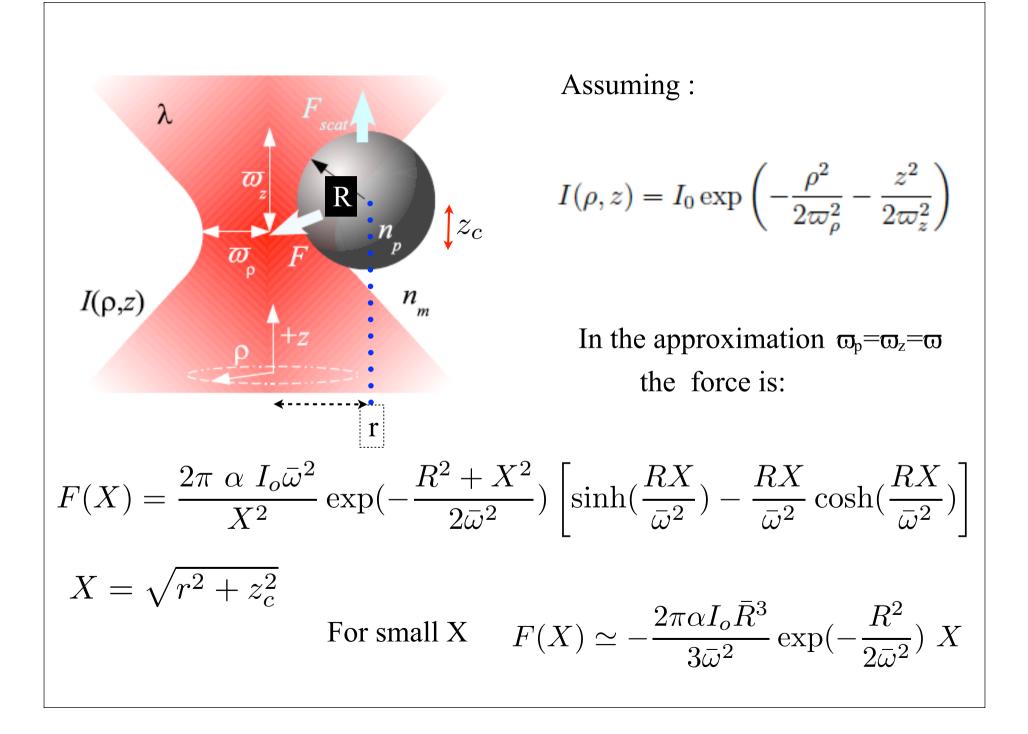
For dielectric particles in presence of a strongly focused beam the main contribution is coming from the electric field. Thus the total energy variation can be expressed as the dipole interaction:

$$U = -\int_V P_i E_{oi} \, dv$$

where  $P_i = \epsilon_0 \chi E_{oi}$ ,  $E_{oi}$  is the incident field and  $\chi = \epsilon - 1$ . This reduce the dipole interaction energy to

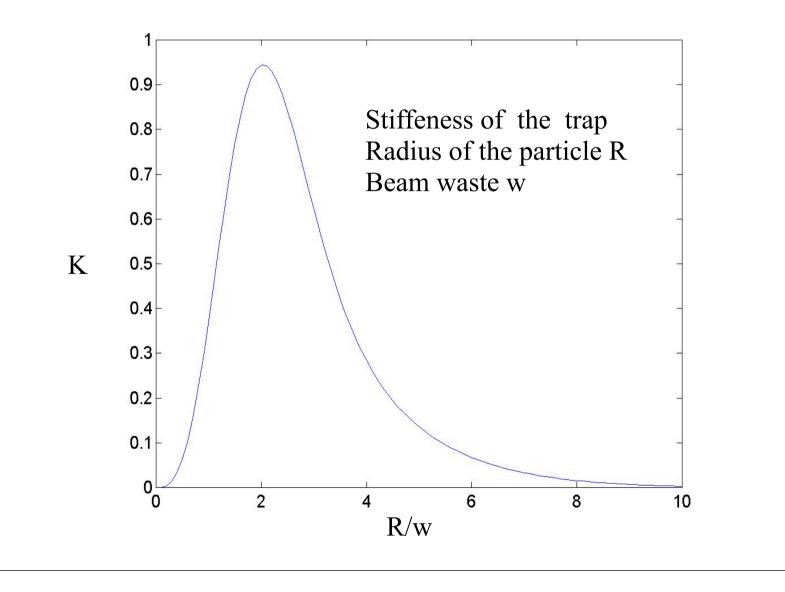
$$U = -\alpha \int_V I \, dv$$

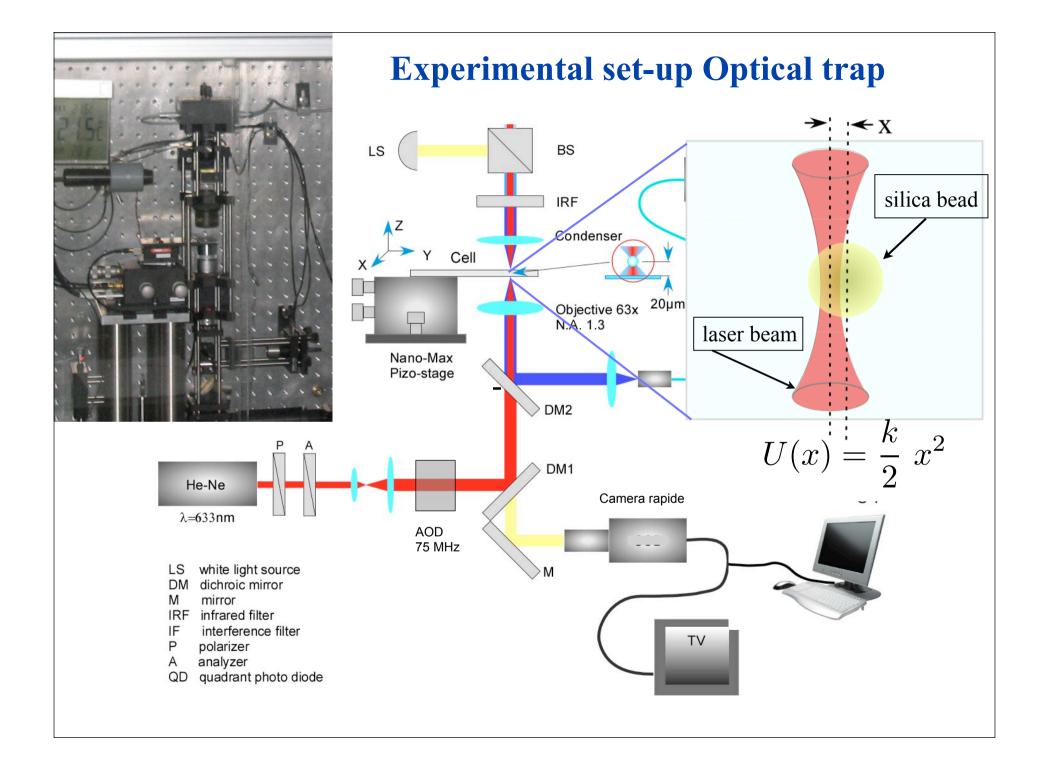
where  $I = \epsilon_f \epsilon_0 E_0^2$  is the intensity of the laser beam and  $\alpha = \frac{\epsilon_p}{\epsilon_f} - 1 = \frac{n_p^2}{n_f^2} - 1$  $\epsilon_f$  and  $\epsilon_p$  are the dielectric constant of the fluid and of the particle.

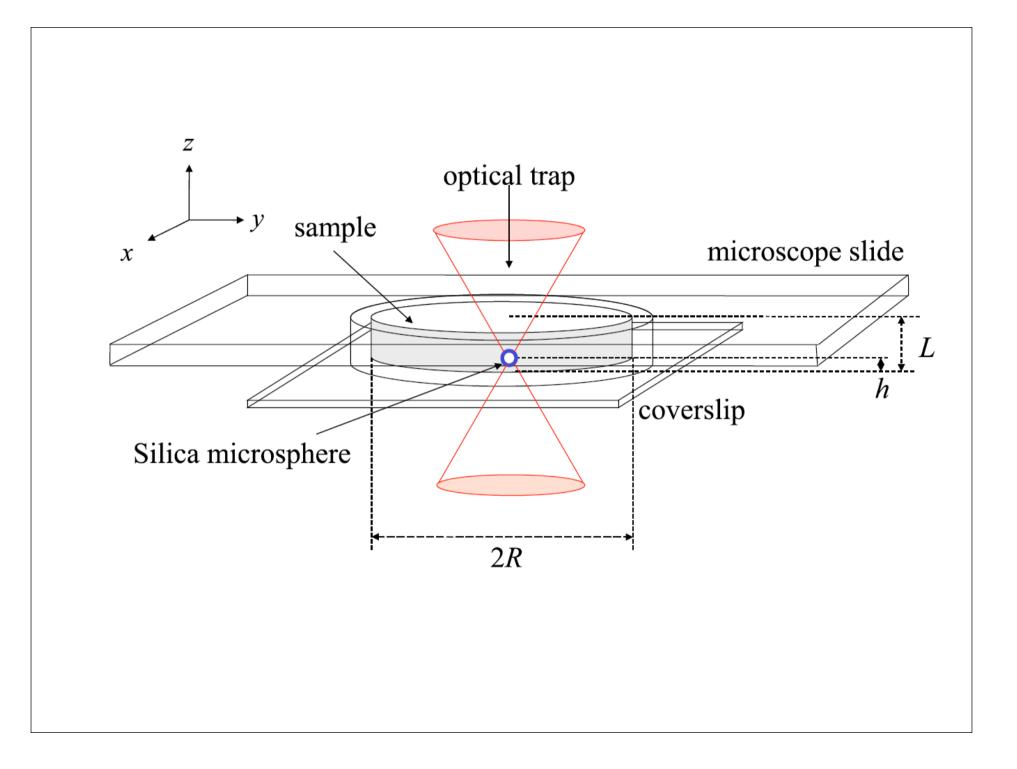


# **The Optical Tweezers**

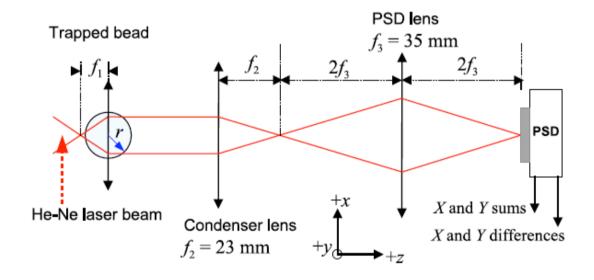
Then, the optical gradient force is simply given by the change of U in response to a change of the particles coordinates.

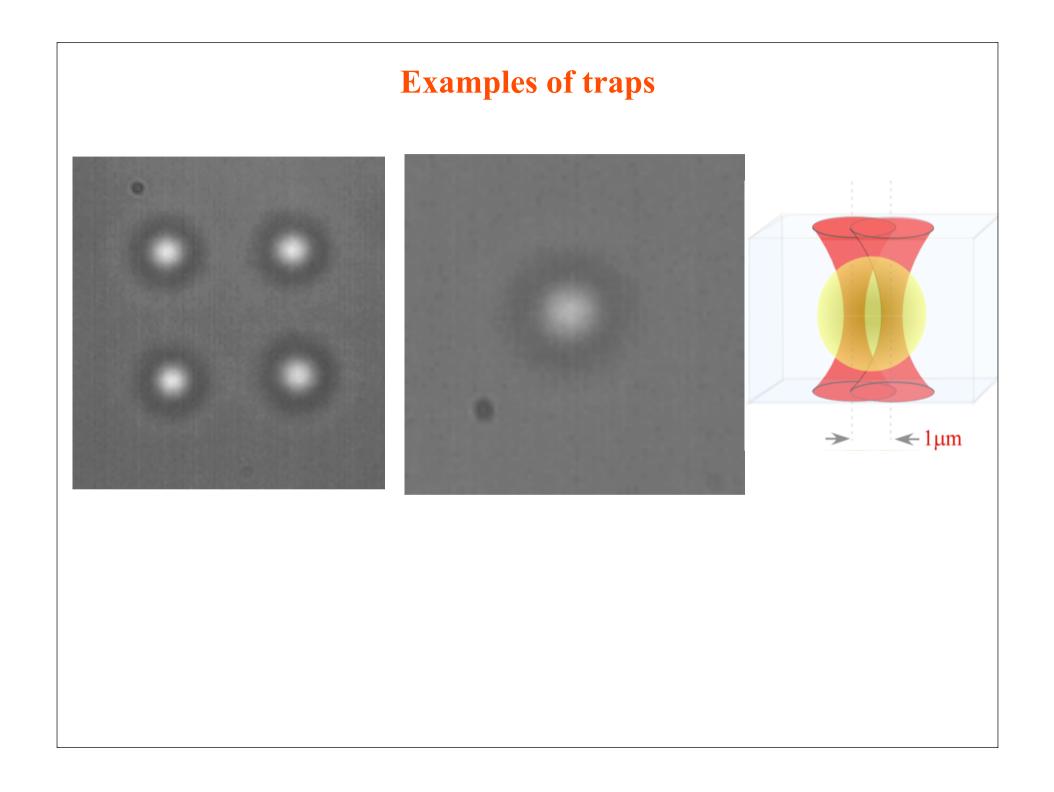


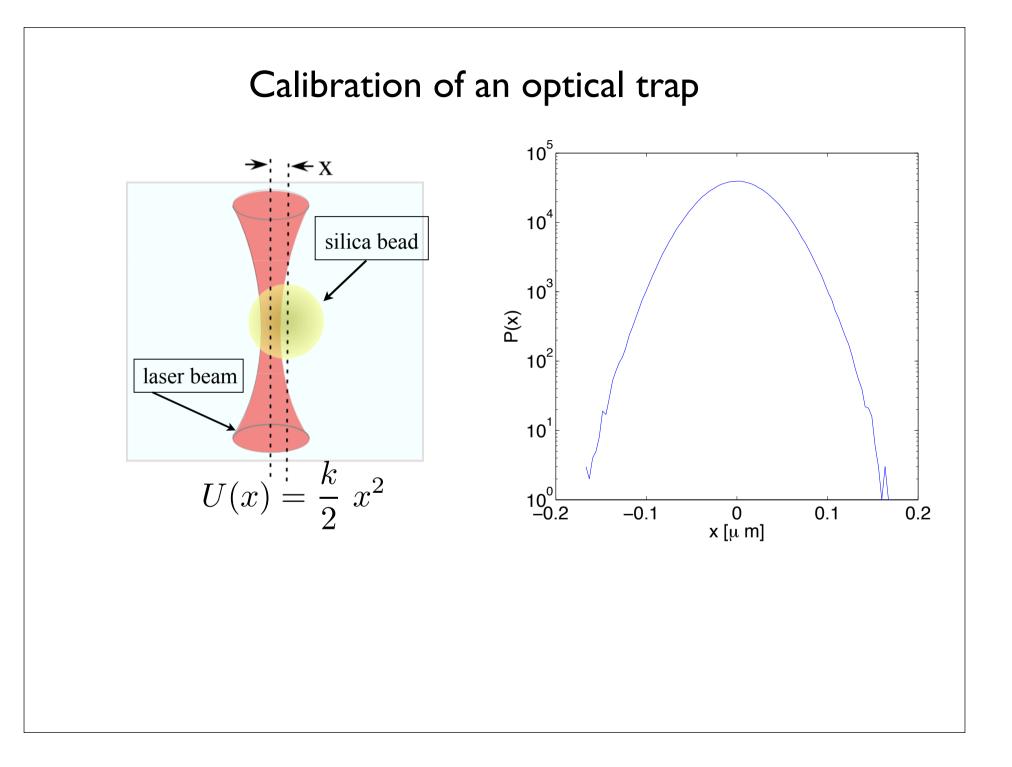




# Detecting the bead position







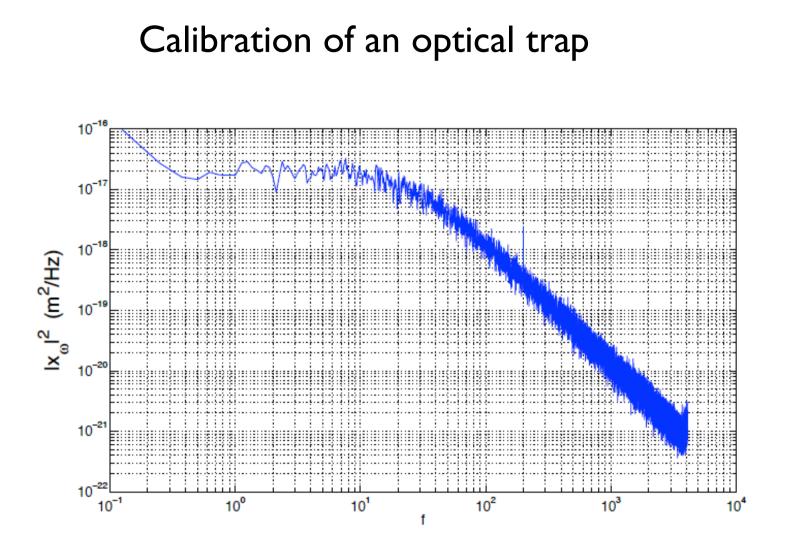
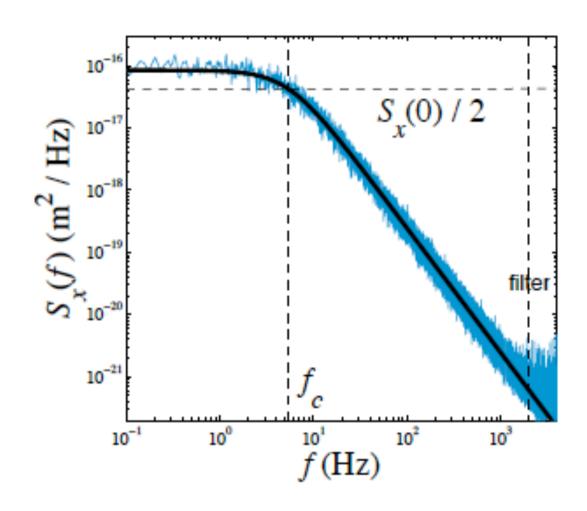


FIGURE 1 – Spectre de puissance de la position d'une particule piégée par un piège optique dans un fluide visqueux.



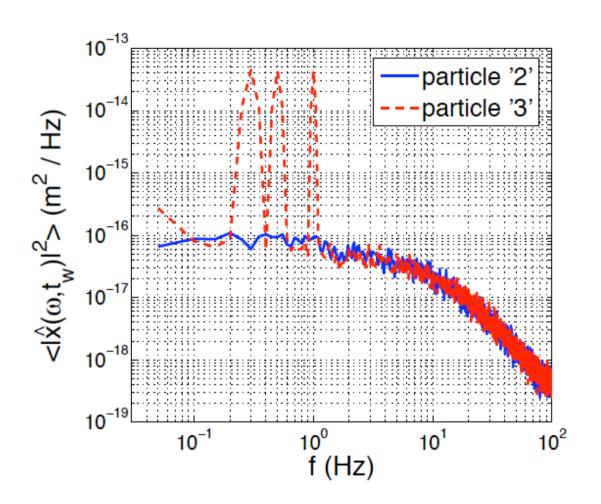
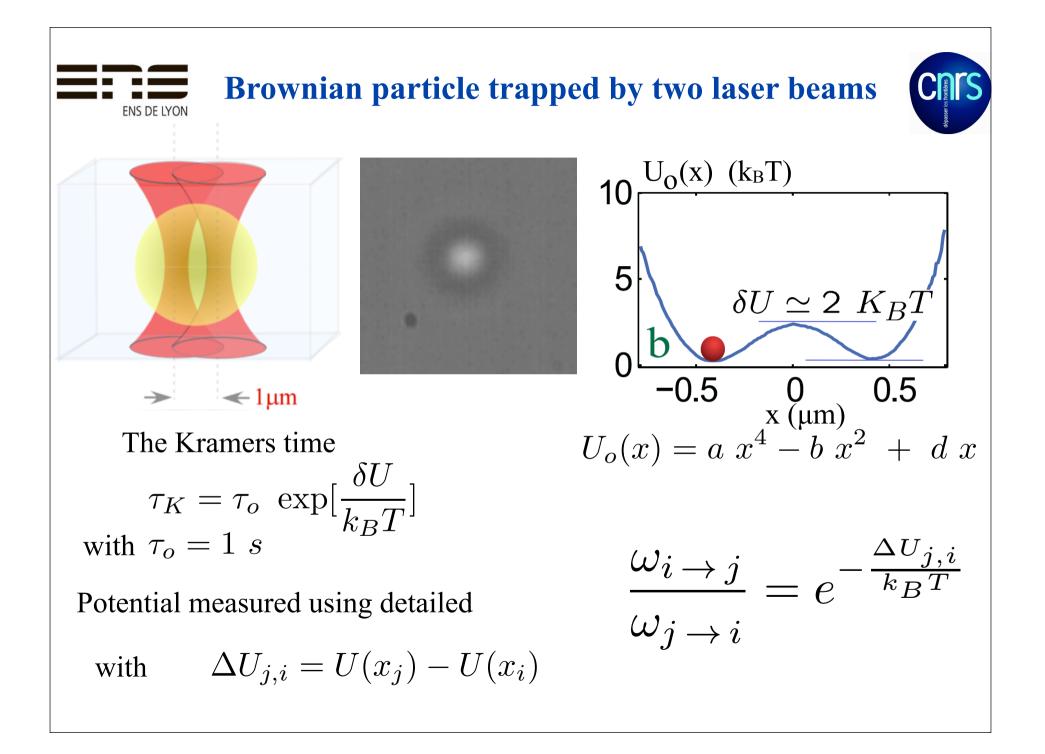


FIGURE 2 – Spectres de puissance de la position d'une particule piégée à l'équilibre et soumise à une force externe.



# Fluctuation Dissipation Theorem

Observable : O(t) conjugated variable : h

response function : 
$$R(t,s) = \frac{\delta O(t)}{\delta h}$$

correlation function :  $C(t,s) = \langle O(t)O(s) \rangle$ 

$$\partial_s C(t,s) = -k_B T R(t,s)$$
 FDT

$$C(t,t) - C(t,s) = k_B T \chi(t,s)$$
 Integral form

Integral response function :  $\chi(t,s)$ 

## FDT from time to frequency

From Wiener-Khinchin theorem

$$\langle x(\tau)x(0) \rangle = C(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S(\omega) \exp(-i\omega\tau) d\omega$$
 (1)

thus

$$\partial_{\tau} C(\tau) = -\frac{1}{2\pi} \int_{-\infty}^{\infty} i\omega \ S(\omega) \exp(-i\omega\tau) \ d\omega$$
<sup>(2)</sup>

and

$$\int_{-\infty}^{\infty} \partial_{\tau} C(\tau) \exp(i\omega\tau) \, d\tau = -i\omega \, S(\omega) \tag{3}$$

As a consequence we may write

$$S(\omega) = -\frac{1}{i\omega} \int_{-\infty}^{\infty} \partial_{\tau} C(\tau) \exp(i\omega\tau) d\tau$$
(4)

$$= \frac{i}{\omega} \left[ \int_{-\infty}^{0} \partial_{\tau} C(\tau) \exp(i\omega\tau) \, d\tau + \int_{0}^{\infty} \partial_{\tau} C(\tau) \exp(i\omega\tau) \, d\tau \right]$$
(5)

### FDT from time to frequency

Let us consider  $\int_{-\infty}^{0} \partial_{\tau} C(\tau) \exp(-i\omega\tau) d\tau$  and change  $\tau \to -\tau'$ 

$$\int_{-\infty}^{0} \partial_{\tau} C(\tau) \exp(i\omega\tau) d\tau = \int_{\infty}^{0} \partial_{\tau'} C(-\tau') \exp(-i\omega\tau') d\tau'$$
(6)

$$= -\int_0^\infty \partial_{\tau'} C(-\tau') \exp(-i\omega\tau') \, d\tau' \tag{7}$$

$$= -\int_0^\infty \partial_{\tau'} C(\tau') \exp(-i\omega\tau') \, d\tau' \tag{8}$$

$$= -\left[\int_0^\infty \partial_{\tau'} C(\tau') \exp(i\omega\tau') d\tau'\right]^*$$
(9)

where we used  $C(-\tau') = C(\tau')$  and  $[\cdot]^*$  stands for complex conjugate Thus replacing this result in eq.5

$$S(\omega) = \frac{i}{\omega} \left[ -\left( \int_0^\infty \partial_\tau C(\tau) \exp(i\omega\tau) \, d\tau \right)^* + \int_0^\infty \partial_\tau C(\tau) \exp(i\omega\tau) \, d\tau \right]$$
(10)  
$$= \frac{-2}{\omega} Imag \left[ \int_0^\infty \partial_\tau C(\tau) \exp(i\omega\tau) \, d\tau \right]$$
(11)

# FDT from time to frequency

Now we know that FDT imposes that for  $\tau > 0$ 

 $\partial_{\tau} C(\tau) = -K_B \ TR(\tau)$ 

thus

$$S(\omega) = \frac{2K_BT}{\omega} Imag\left[\int_0^\infty R(\tau) \exp(i\omega\tau) d\tau\right]$$
(12)

$$= \frac{2K_BT}{\omega} \ Imag\left[R(\omega)\right] \tag{13}$$

Furthermore as  $S(\omega) = S(-\omega)$  then

$$\langle x^2 \rangle = \frac{1}{2\pi} \int_{-\infty}^{\infty} S(\omega) d\omega$$
 (14)

$$= \frac{1}{2\pi} \int_0^\infty 2S(\omega) d\omega \tag{15}$$

$$= \int_0^\infty S_x(f)df \tag{16}$$

where we have defined  $S_x(f) = 2S(\omega)$  and  $2\pi f = \omega$ . Finally we get

$$S_x(f) = \frac{4K_BT}{\omega} \ Imag\left[R(\omega)\right] \tag{17}$$

## Kramer Kroening

$$S_j(\omega) = \frac{4 k_B T}{\omega} \chi_j''(\omega)$$

$$\tilde{\chi}'_{j}(\omega) = \frac{2}{\pi} P \int_{0}^{\infty} \frac{\xi \tilde{\chi}''_{j}(\xi)}{\xi^{2} - \omega^{2}} d\xi = \frac{1}{2\pi k_{B}T} P \int_{0}^{\infty} \frac{\xi^{2} S_{j}(\xi)}{\xi^{2} - \omega^{2}} d\xi$$

i.e. 
$$\tilde{\chi}_j''(\xi, t_w) = \omega S_j(\omega, t_w)/(4k_BT).$$

To compute  $\tilde{\chi}'_{j}$  we use a Fourier transform algorithm that is:

$$\tilde{\chi}_j'(\omega) = \frac{1}{2\pi k_B T} \int_0^{1/\omega_{min}} \cos(\omega t) dt \int_0^{\omega_{max}} \xi^2 S_j(\xi) \sin(\xi t) d\xi,$$

where  $\omega_{min}$ ,  $\omega_{max}$  are the minimum and maximum of the spectrum.

