The Algebra of Signal Flow Graphs

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- an algebraic theory of matrices over a PID k (Hopf Algebras);
- an algebraic theory of subspaces over the field of fractions of k (Interacting Hopf Algebras).

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- an algebraic theory of subspaces over the field of fractions of k (Interacting Hopf Algebras).

Interacting Hopf Algebras provide a (graphical) syntax and a sound and complete axiomatization for subspaces.

For instance, we can express both *systems of equations* and *bases* as term of our syntax; we can check that they denote the same subspace via the axiomatization.

We show

- an algebraic theory of matrices over a PID k (Hopf Algebras);
- an algebraic theory of subspaces over the field of fractions of *k* (Interacting Hopf Algebras).

In this talk, we fix the PID to be the ring of polynomials k[x].

The terms of the corresponding syntax are well-known structures called *signal flow graphs*.

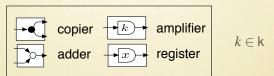
If you are interested in, you can

- have a look to the Ph.D thesis of Fabio Zanasi (ENS-Lyon),
- follow Pawel's blog http://graphicallinearalgebra.net,
- knock to my door.

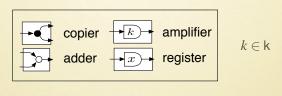
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- Signal Flow Graphs (SFGs) are stream processing circuits widely adopted in Control Theory since at least the 1950s.
- Constructed combining four kinds of gate

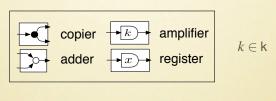


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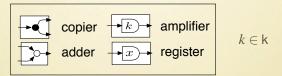




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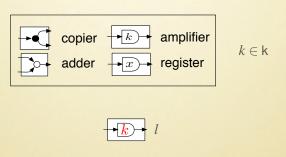


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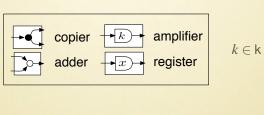




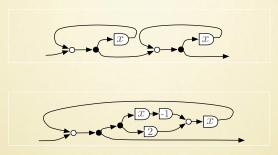
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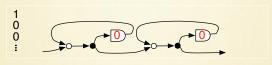


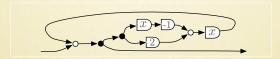
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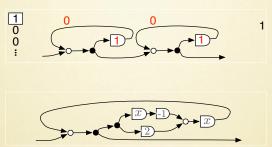


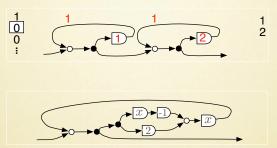


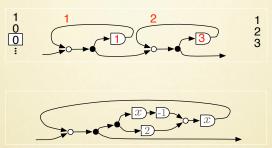


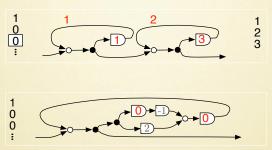


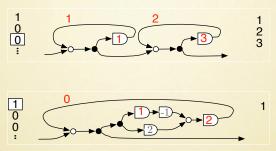


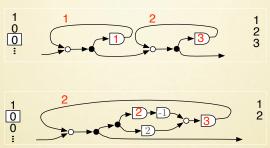


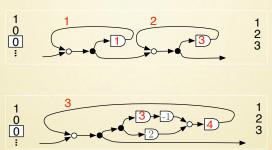




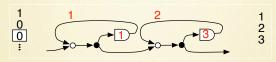


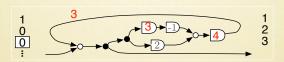






Two examples:

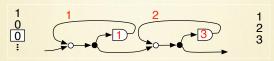


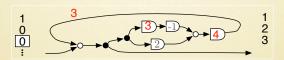


Both circuits implement the generating function

$$\frac{1}{(1-x)^2} = 1x + 2x^2 + 3x^3 + \dots$$

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Can we check this *statically*?

- In traditional approaches, SFGs are not treated as interesting mathematical structures per se.
 - ⇒ formal analysis typically mean translation into systems of linear equations.
- We study SFGs *directly* as graphical structures.

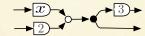
In this work

A graphical theory of Signal Flow Graphs

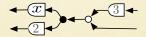
- String diagrammatic syntax for circuits.
- Compositional semantics.
- Sound and complete axiomatisation for semantic equivalence.
 - ⇒ Two circuits implement the same specification if they can be transformed one into the other using the equational theory.

Outline

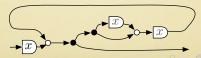
- Functional circuits
 - ⇒ the signal flows from left to right



- Reverse functional circuits
 - \Rightarrow the signal flows from right to left

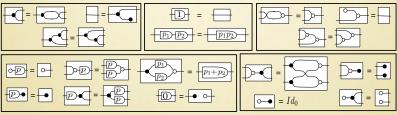


- Generalised circuits
 - ⇒ the signal can flow in both directions
 - ⇒ environment for modeling signal flow graphs

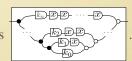


Functional circuits are the string diagrams generated by the grammar

subject to the following equations:



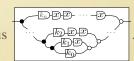
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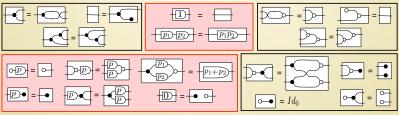
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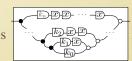


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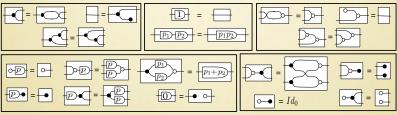


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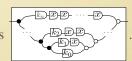


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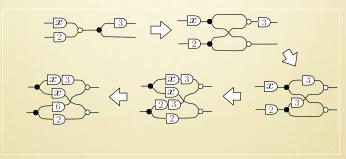
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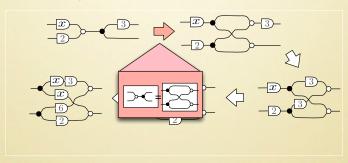
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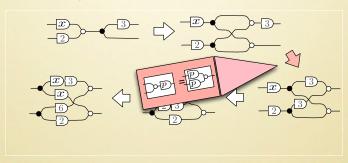
- Functional circuits modulo the equations are in 1-1 correspondence with matrices over the polynomial ring k[x].
- Example: check the semantics of busing the equational theory $\mathbb{H}\mathbb{A}$.



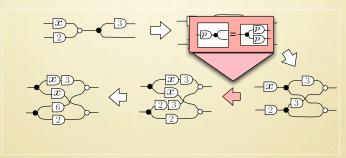
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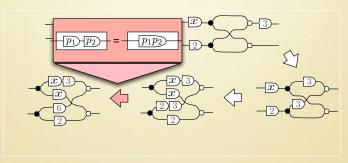
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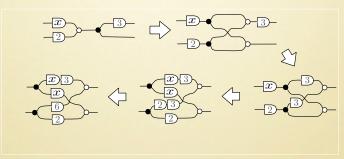
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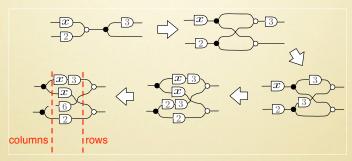
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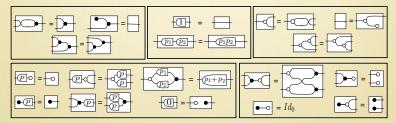
Its semantics is the matrix $\begin{pmatrix} 3x & 6 \\ x & 2 \end{pmatrix}$.

Reverse functional circuits

Reverse functional circuits are functional circuits "reflected about the y-axis". They are the diagrams generated by the grammar

$$c,d := lackbox{--} | lackbox{--}$$

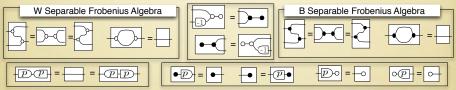
subject to equations dual to those of HA:



The theory III of generalised circuits

Generalised circuits are string diagrams generated by the grammar

subject to the equations of the theories of functional and reverse functional circuits, plus the following:



Semantics of Generalised Circuits

Circuits do not generally have a univocal flow direction — a *relational* model is required.

For instance, \bullet ; σ expresses the diagonal relation.

Semantics of Generalised Circuits

The semantics [] maps a circuit into a linear relation (subspace):

$$\sigma$$

$$\sigma = \sigma$$

$$\sigma$$
 $k \cdot \sigma$

$$\sigma \hspace{-0.1cm} \stackrel{\sigma}{\longleftarrow} \hspace{-0.1cm} \sigma \hspace{-0.1cm} \hspace{$$

$$\sigma \rightarrow \sigma + \tau$$

$$-\sigma$$

$$\sigma$$
 σ
 σ

$$x \cdot \sigma$$
 $x \cdot \sigma$

$$\sigma + \tau - \sigma \tau$$

$$\sigma \longrightarrow \sigma$$

The axiomatisation of IH is sound and complete

$$[c] = [d] \Leftrightarrow c \stackrel{\mathbb{IH}}{=} d$$

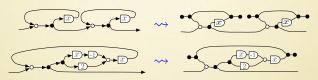
The key technical step in the proof consists in reducing a circuit in its Hermite Normal Form

Graphical reasoning in III

Check: and implement $\frac{1}{(1-x)^2}$.

Proof strategy:

• Represent the two SFGs as generalised circuits



• Represent the specification as a generalised circuit:

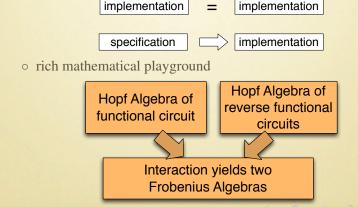
$$\sigma \quad \overbrace{(1-x)^2} \quad \sigma \cdot \frac{1}{(1-x)^2}$$

• Prove the three of them equal using the axioms of IH:

Conclusions

We proposed an algebraic environment for signal flow graphs

- compositional semantics in terms of linear relations
- sound and complete axiomatisation
 - graphical proof system



Future Work

What are the fundamental structures of concurrency? We still don't know! - Samson Abramsky 2014

- functional computations have a paradigmatic model: λ -calculus;
- concurrent computations do not: there are many different models like Petri nets, Process Calculi, Event Structures ...

A path toward an answer...

Systems of linear difference equations	IH
Diophantine Systems of linear difference equations	?